

Final Sprint Presentation

Made By: Abigayle O'Connell

Group: Robot group - 2

Team introduction

Abby - I'm Abby, and I wrote for the ERD table, helped with the option 1 code on python with josh, wrote the code for room 3 of the robot and wrote this PowerPoint presentation.

Josh - I'm Josh, and I wrote for the ERD table and wrote the general code for option 1 on python and wrote the code for option 8 on python

Cole - I'm Cole and I wrote the general code for rooms 1,2 and 4 of the robot

Tre - I'm Tre and I wrote for the ERD's reports and receipts and wrote option 6 7 code on python

Tristan - I'm Tristan and I helped work on rooms 1,2 and 4 of the robot with cole and helped with the option 1 code on python.



Project management strategy

- The tools that we used to help us manage our project were the following:

Kanban Board

- A Kanban Board was used on the Trello website. The way it was organized was that everyone would have their own list, with each containing cards for each task that we would have to complete. Once finished, we would add our own card in the finished list and write down what we have completed.

How often did we have meetings?

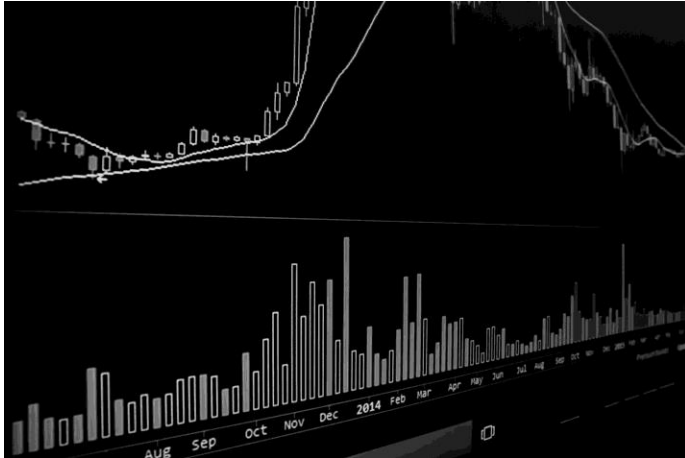
- Meetings from our group did vary from time to time, but still took place, give or take a couple days

How did the team co-ordinate work?

- We coordinated out our work by choosing where we thought our strongest points were, and then focusing on those parts so they can get done more effectively and efficiently

How did we host our code?

- Our group hosted our code through GitHub and personal team chats. The robot code being with GitHub and the Python code being through team chats.



Major Challenges

What were the biggest challenges we faced in this project?

- The biggest challenges we faced in this project were communication, mainly team meetings.

How will we mitigate this in future projects?

- For future projects, we will implement more of a strict schedule for meetings, conversations of progress and to check in more and see if every group member is doing a part.

