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# ENEL420 Formula Sheet

The bitchiest of all the exams

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October 31, 2020

# 1 Interpolation

Interpolation, convolution with a kernel function:

$$f(k_0) = \sum_k f(k) \frac{K(k_0 - k)}{\text{convolution kernel}} \quad (1)$$

Where  $f(k_0)$  is the interpolated signal and  $f(k)$  is the data

## 1.1 Kernels

Nearest Neighbour:

$$K(x) = \text{rect}(x) = \begin{cases} 1 & |x| \leq \frac{1}{2} \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

Linear:

$$K(x) = \text{tri}(x) = \begin{cases} 1 - |x| & |x| < 1 \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

Sinc:

$$K(x) = \text{sinc}(x) = \frac{\sin(\pi x)}{\pi x} \quad (4)$$

# 2 Aliasing

General Case to avoid aliasing:

$$\frac{2f_u}{n} < f_s < \frac{2f_l}{n-1} \quad (5)$$

Where,

$$1 \leq n \leq I_{MLT} \left( \frac{f_u}{B} \right) \quad (6)$$

$I_{MLT}$  is Maximum integer less than

### 3 Z-Transform

$$F(z) = \sum_{n=0}^{\infty} f(n)z^{-n} \quad (7)$$

Or,

$$F(s) = \sum_{n=0}^{\infty} f(nT)e^{-nTs} \quad (8)$$

### 4 Quantisation Noise

RMS quantisation noise:

$$\sigma = \frac{\Delta}{\sqrt{12}} = \frac{\Delta}{2\sqrt{3}} \quad (9)$$

Noise Power:

$$\text{NP} \propto \Delta^2 \quad (10)$$

Therefore noise power is decreased by  $\frac{1}{2}$ ,

$$10\log_{10}\left(\frac{1}{2}\right) = -6\text{dB} \quad (11)$$

### 5 Filters

Direct realisation:

$$H(z) = \frac{\sum_{k=0}^K b_k z^{-k}}{1 + \sum_{m=1}^M a_m z^{-m}} \quad (12)$$

Linear Phase, if a filter has linear phase it can be expressed in the form:

$$H(\omega) = |H(\omega)|e^{j\theta(\omega)} \quad (13)$$

Where,

$$\theta(\omega) = -(\alpha\omega + \beta) \quad (14)$$

Windowing the impulse response is defined by the inverse Fourier Transform,

$$h_D(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_D(\omega)e^{j\omega n} d\omega \quad (15)$$

non-recursive FIR Filters,

$$y(n) = b_0x(n) + b_1x(n-1) \quad (16)$$

Recursive,

$$y(n) = ay(n-1) + bx(n) \quad (17)$$

So,

$$H(z) = \sum_{n=0}^{N-1} \frac{1}{N} \sum_{k=0}^{N-1} H(k) e^{\frac{j2\pi kn}{N}} z^{-n} \quad (18)$$

## 6 Detection Theory

Likelihood Ratio,

$$\frac{p(\mathbf{x}|H_0)}{p(\mathbf{x}|H_1)} \quad (19)$$

### 6.1 Likelihood ratio test

Choose null hypothesis if,

$$\frac{p(\mathbf{x}|H_0)}{p(\mathbf{x}|H_1)} > \gamma \quad (20)$$

Choose alternative hypothesis if,

$$\frac{p(\mathbf{x}|H_0)}{p(\mathbf{x}|H_1)} \leq \gamma \quad (21)$$

### 6.2 Log Likelihood

Choose null hypothesis if,

$$-x[0] + \frac{1}{2} > 0 \leftrightarrow x[0] < \frac{1}{2} \quad (22)$$

Choose alternative hypothesis if,

$$-x[0] + \frac{1}{2} \leq 0 \leftrightarrow x[0] \geq \frac{1}{2} \quad (23)$$

Solve for  $\gamma$  using,

$$P_{FA} = \int_{\mathbf{x}: L(\mathbf{x}) < \gamma} p(\mathbf{x}|H_0) d\mathbf{x} \quad (24)$$

### 6.3 Missed Detection

The probability of missed detection is,

$$P_M = p(x[0] \leq \frac{1}{2} | H_1) = p(x[0] \leq \frac{1}{2} | u = 1) \quad (25)$$

### 6.4 Detection Error Rate

$$P_{FA}P(H_0) + P_MP(H_1) \quad (26)$$

Where  $P_{FA}$  is the probability of falsely selecting the alternative hypothesis and  $P_M$  is the probability of falsely selecting the null hypothesis.

### 6.5 Detection Threshold

To find the detection threshold use the following,

$$P_{FA} = \int_{\mathbf{x}} 1(\log(L(\mathbf{x})) - c < \gamma) \cdot p(\log(L(\mathbf{x})) - c | H_0) \, d\mathbf{x} \quad (27)$$

### 6.6 NP Detector of Known Signal in WGN

The signal likelihood under  $w[n] \sim N(0, \sigma^2)$  (Normal distribution) for the null hypothesis,

$$p(\mathbf{x} | H_0) = \prod_{n=0}^{N-1} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{x[n]^2}{2\sigma^2}\right) \quad (28)$$

For the alternative hypothesis,

$$p(x | H_1) = \prod_{n=0}^{N-1} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x[n] - s[n])^2}{2\sigma^2}\right) \quad (29)$$

Therefore the Log-Likelihood ratio test is,

$$\log(L(\mathbf{x})) = \log\left(\frac{p(\mathbf{x} | H_0)}{p(\mathbf{x} | H_1)}\right) = \frac{1}{2\sigma^2} \sum_{n=0}^{N-1} (s[n]^2 - 2s[n]x[n]) \quad (30)$$

## 6.7 Multivariate Gaussian PDF

Null Hypothesis,

$$P(\mathbf{x}|H_0) = \frac{1}{(\sqrt{2\pi}\sigma)^N} \exp\left(-\frac{1}{2\sigma^2} \mathbf{x}^T \mathbf{x}\right) (\delta = \sigma^2 \mathbf{I}) \quad (31)$$

Alternative Hypothesis,

$$P(\mathbf{x}|H_1) = \frac{1}{|2\pi(\mathbf{C} + \sigma^2 \mathbf{I})|} \exp\left(-\frac{1}{2} \mathbf{x}^T (\mathbf{C} + \sigma^2 \mathbf{I})^{-1} \mathbf{x}\right) (\Delta = \mathbf{C} + \sigma^2 \mathbf{I}) \quad (32)$$

LLR,

$$\log(L(\mathbf{x})) \propto -\mathbf{x}^T \mathbf{C} (\mathbf{C} + \sigma^2 \mathbf{I})^{-1} \mathbf{x} \quad (33)$$

Simplified,

$$\sum_{n=0}^{N=1} \frac{\delta_n}{\delta_n + \sigma^2} y[n]^2 \quad (34)$$

## 6.8 Mixture Model

$$p(\mathbf{x}|\theta) = \sum_{k=1}^K w_k p_k(\mathbf{x}|\theta) \quad (35)$$

Where,  $p_k(\mathbf{x}|\theta)$  is the  $k^{\text{th}}$  base distribution and  $w_k$  is the mixing weight of  $p_k(\mathbf{x}|\theta)$   
Where,

$$w_k \geq 0 \quad \text{and} \quad \sum_{k=1}^K w_k = 1 \quad (36)$$

## 7 Fourier Transform

### 7.1 Properties

Shift Theorem

$$x(t - t_0) \leftrightarrow X(f) \exp(-j2\pi f t_0) \quad (37)$$

Scaling

$$x(at) \leftrightarrow \frac{1}{|a|} X\left(\frac{f}{a}\right) \quad (38)$$

Convolution

$$x(t) \otimes y(t) \leftrightarrow X(f)Y(f) \quad (39)$$

For a real signal

$$X(-f) = X^*(f) \quad (40)$$

DFT

$$X(k) = \frac{1}{N} \sum_{n=0}^{N-1} x(n) \exp(-j2\pi nk/N) \quad (41)$$

IDFT

$$x(n) = \sum_{k=0}^{N-1} X(k) \exp(j2\pi nk/N) \quad (42)$$

Parseval's Theorem

$$\sum_{n=0}^{N-1} [f(n)]^2 = \sum_{k=0}^{N-1} |F(k)|^2 \quad (43)$$

2D Fourier Transform can be expressed as a weighted sum of harmonics,

$$\exp(j2\pi(ux + vy)) \quad (44)$$

## 7.2 2D FT

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp(-j2\pi(ux + vy)) dx dy \quad (45)$$

2D DFT,

$$F(p, q) = \frac{1}{N} \sum_{m=0}^{N-1} \left( \frac{1}{N} \sum_{n=0}^{N-1} f(m, n) \exp(-j2\pi qn/N) \right) \exp(-j2\pi pm/N) \quad (46)$$

Rotation of an image rotating by  $\alpha$ ,

$$F_{\alpha}(\rho; \phi) = \int_0^{2\pi} \int_0^{\infty} f(r; \theta) \exp(-j2\pi \rho r \cos(\theta - \phi)) r dr d\theta \quad (47)$$

So,

$$F_{\alpha}(\rho; \phi) = F(\rho; \phi - \alpha) \quad (48)$$

## 8 Projection

$$P(\theta, x') = \int_{-\infty}^{\infty} f(x', y') dy' \quad (49)$$

### 8.1 Wiener filtering

$$W(u, v) = \frac{H^*(u, v)}{|H(u, v)|^2 + \Phi(u, v)} \quad (50)$$

Where  $\Phi(u, v)$  is an estimate of the spatial frequency dependent noise-to-signal power

The estimate of the image spectrum is given by,

$$\hat{F}(u, v) = G(u, v)W(u, v) \quad (51)$$

If  $H(u, v)$  is large,

$$\hat{F}(u, v) \approx F(u, v) + \frac{N(u, v)}{H(u, v)} \approx F(u, v) \quad (52)$$

However when  $H(u, v)$  is small,

$$\hat{F}(u, v) = G(u, v) \left( \frac{H^*(u, v)}{|H(u, v)|^2 + \Phi} \right) \approx G(u, v) \frac{H^*(u, v)}{\Phi} \approx 0 \quad (53)$$

## 9 Diffraction

The phase difference is,

$$\phi = (d_1 - d_2) \left( \frac{2\pi}{\lambda} \right) = (\mathbf{x} \cdot \hat{\mathbf{k}}_0 - \mathbf{x} \cdot \hat{\mathbf{k}}) \left( \frac{2\pi}{\lambda} \right) \quad (54)$$

So,

$$\phi = -\mathbf{x} \cdot (\mathbf{k} - \mathbf{k}_0) \quad (55)$$

Therefore the total scattering is,

$$\psi(\mathbf{k}) = \int f(\mathbf{x}) \exp(i(\mathbf{k} - \mathbf{k}_0) \cdot \mathbf{x}) d\mathbf{x} \quad (56)$$



The scattering vector is defined as,

$$\mathbf{u} = (\hat{\mathbf{k}} - \hat{\mathbf{k}}_0)/\lambda \quad (57)$$

Therefore the scattered field in terms of  $\mathbf{u}$  is,

$$F(\mathbf{u}) = \int f(\mathbf{x}) \exp(i2\pi \mathbf{u} \cdot \mathbf{x}) d\mathbf{x} \quad (58)$$

Therefore by taking the inverse Fourier transform the object can be reconstructed,

$$f(\mathbf{x}) = \int F(\mathbf{u}) \exp(-i2\pi \mathbf{u} \cdot \mathbf{x}) d\mathbf{u} \quad (59)$$