view_frames Result

Recorded at time: 6720.983

map

Broadcaster: /slam_gmapping
Average rate: 20.202 Hz
Most recent transform: 6721.013 (-0.030 sec old)
Buffer length: 4.950 sec

odom

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 6720.945 (0.038 sec old)
Buffer length: 4.900 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 6720.946 (0.037 sec old)
Buffer length: 4.900 sec

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 6720.946 (0.037 sec old)
Buffer length: 4.900 sec

base_link_dummy

left_rear_wheel_link

right_rear_wheel_link

right_front_wheel_link

left_front_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

base_top

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

bottom_box

laser

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

back_bar

middle_bar

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

top_bar

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

back_xtion_link

head_stand_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 6720.974 (0.009 sec old)
Buffer length: 4.960 sec

back_rgb_optical_link

head_yaw_link

Broadcaster: /robot_state_publisher
Average rate: 50.202 Hz
Most recent transform: 6720.974 (0.009 sec old)
Buffer length: 4.960 sec

head_pitch_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

front_xtion_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (6720.983 sec old)
Buffer length: 0.000 sec

front_rgb_optical_link