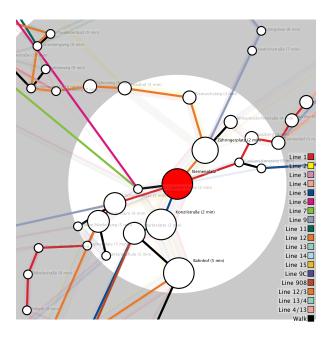
BusVis – Interactive Visualization of a Public Transport System

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Introduction

We present BusVis, a tool for explorative analysis that is capable of visualizing transportation systems, illustrated on the bus system of Konstanz. The focus on a specific station is chosen interactively by the user. The visualization adapts to the selection by transforming the overview into a locally correct projection w.r.t. distances to neighbours while preserving geographical context.



Dataset and Preprocessing

The data consists of 123 bus stations, 18 bus lines, schematic and geographic positions for each stop, walking distances, and 16,088 time-dependent directed edges. The following data pre-processing steps were applied:

Cleaning. Data files were converted from XLS to CSV and missing values in the time table were added.

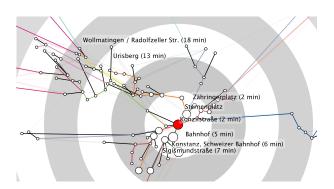
Walking distances. We then added walking distances between each station the enrich the data and allow the application to incorporate that users would probably walk small distances instead of waiting for a bus.

Schematic plan positions. We annotated each bus station with its corresponding position on the schematic map.

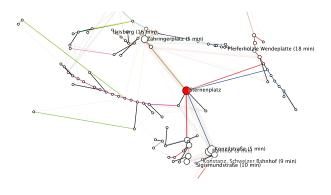
Visualization

We show the travel distances from a selected source to all destinations in one visualization. The stations are represented as nodes and their connections as edges in a node-link diagram. We encode travel times by visual distances. Two alternative layouts allow either local correctness or global stress minimization for the described distance mapping.

Radial Layout. The source is the center of the layout. Destinations are positioned in a way that the distance to the center is an exact mapping of the source-destination time distance. To preserve the mental map we chose the angle between two stations w.r.t. the source to align with geographic directions. Concentric rings represent five-minute intervals.



Stress-Majorization Layout. This layout projects travel times between adjacent bus stations to length of edges by minimizing a global stress function. We used the $SMACOF^1$ algorithm as an efficient solver. The geographic positions of the stations are chosen as initial layout in order to roughly preserve the shape of the bus network. This works well because travel time increases with geographical distance.



¹Scaling by Majorizing A COnvex Function

Tool

Our tool is implemented in Java and provides a GUI to interact with and configure the visualization. Initially the nodes are located at their geographic positions. The user can select a station as source. Then the shortest routes to all other stations are calculated and the layout changes accordingly. Transitions are smoothly animated to retain the mental map. Additionally one or more destinations can be selected and the visualization will then highlight the corresponding routes. The user can switch between radial and stress layout.

The tool includes a schematic overview which allows the user to select bus stations even when the main visualization has changed. The user interface allows to modify parameters of the routing algorithm, e.g. the current time, the maximal allowed walking time, or minimal stopover time. A real-time and fast-forward mode can be enabled to simulate bus tracking at different speed.

Use Cases

A bus plan is very difficult to read when source and destination are not connected by the same bus line. Normally a simple routing application can be used to find the fastest route to a given destination. However this only works with one source and one destination. Our visualization shows shortest routes to all bus stations in a network from a single source.

Comparing travel times. The bus stations *Universität* and *Egg* for example are very close. This raises the question when it is rewarding to chose one destination over the other. Our visualization gives a simple advice by just choosing the station that is nearer to the center (Figure 1).

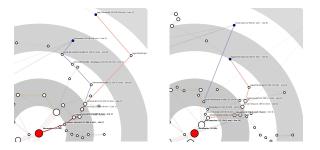


Figure 1: Routes from Sternenplatz (red) to $Universit\ddot{a}t$ and Egg (both blue) at different times. On the left $Universit\ddot{a}t$ is nearer than Egg and on the right vice versa.

Finding weakly connected stations. The possibility to change the starting time of a path helps to analyse the reachability of bus stations over time. For example frequent walk suggestions indicate a bad reachability of a bus station, as seen in Figure 2.

Challenges

Routing. Obligatory stopover times violate invariants of classical routing algorithms, as suboptimal intermediate steps can still lead to an optimal route.

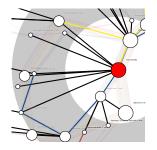


Figure 2: Black edges indicate walks. Sometimes it is better to walk from $Konzilstra\beta e$.

We adapted our algorithm accordingly. Resulting performance problems were solved by excluding suboptimal routes earlier.

Overlaps. We resolved overlaps in the radial layout by changing the angle of the nodes without compromising the correctness of the visualization. This is not possible in the stress-majorization layout.

Drawbacks of the layouts. In the radial layout, it is very easy to misinterpret the distance between two nodes: If they do not lie on a line from the center, their distance has no meaning, because only the difference between their distances to the center is meaningful. For this reason we introduced the additional stressmajorizing layout. Every edge tries to have the length which is proportional to the time it takes to traverse this edge. However, this is an optimization problem which does not result in a exact solution.

Conclusion

We provided a tool to visualize shortest routes in a transportation network which, in contrast to standard techniques like bus plans, allows the user to quickly explore transportation schedules. Real-time interaction enables the user to navigate in the visualization and modify parameters with instant feedback. The tool can be used to compare travel times to different stations at different times and find flaws in the schedule.

Authors' Contributions

Feeras Al-Masoudi Labels, fast-forward animations.

Josua Krause Radial layout, user interaction.

Marc Spicker Overview, edge drawing, GUI.

Leonard Wörteler Stress-majorization layout, routing.

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