

2. Contact Manifolds

2.1 Hyperplane fields

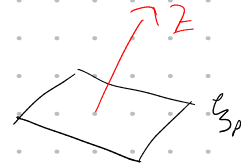
M^n = smooth manifold

$$(p) \mapsto \xi_p \subset T_p M^n$$

$\xi \in TM$ is called hyperplane field $\Leftrightarrow \forall p \in M \exists$ neighborhood U of p and linearly independent vector fields x_1, \dots, x_{n-1} on U s.t. $\forall q \in U$:

$$\xi_q := \xi \cap T_q M = \langle x_1(q), \dots, x_{n-1}(q) \rangle$$

ξ is called co-orientable $\Leftrightarrow TM/\xi$ is orientable



Def: Vector bundle over M^n

$$\begin{array}{ccc} E & \xrightarrow[\text{Fib isom}]{p^{-1}(u)} & U \times \mathbb{R}^k \\ \downarrow p & \searrow p & \downarrow \pi \\ M^n \ni p & & U \end{array}$$

Why is TM/ξ a bundle?

$$\xi_q = \langle x_1(q), \dots, x_{n-1}(q) \rangle$$

$$\mathcal{N}_q = \xi_q^\perp$$

$$p^{-1}(u) \cong U \times \mathbb{R}$$

$$p^{-1}(u) \cong U \times V_p$$

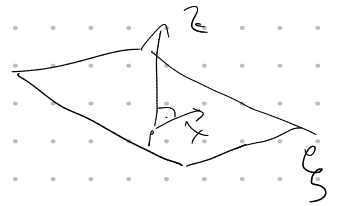
Lemma 1: $\xi \in TM$ is coorientable $\Leftrightarrow \exists$ 1-form α on M s.t. $\xi = \ker(\alpha)$ (18.10.23)
(i.e. $\alpha_p : T_p M \rightarrow \mathbb{R}$)

proof: Let g be a Riemannian metric.

" \Rightarrow " Choose a vector field Z on M with

$$\begin{cases} g(Z, x) = 0 & \forall x \in \xi \\ g(Z, Z) = 1 \end{cases}$$

$$\alpha := g(Z, \cdot)$$



" \Leftarrow " A vector field Z with $\begin{cases} g(Z, Z) = 1 \\ \alpha(Z) \neq 0 \end{cases}$ defines a coorientation of ξ

convention: we restrict to coorientable hyperplane fields (often this is secretly assumed)

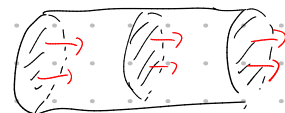
Example:

$$M^n := S^1 \times \mathbb{N}^{n-1}$$

$$\forall p = (\theta, x) \in M = \xi_p := T_x \mathbb{N} \subset T_p M$$

$\xi = \bigcup_{p \in M} \xi_p$ is a hyperplane field

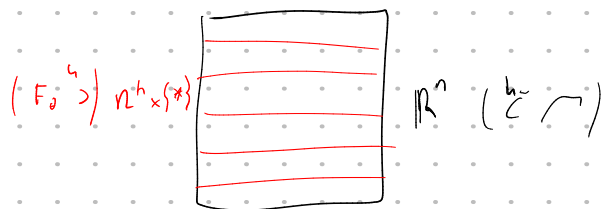
$\xi = \ker(d\theta)$ (odd - n foliation)



glue left and right side together

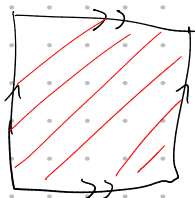
Foliation: $\mathcal{F} = \bigcup_{\theta \in \Lambda} F_\theta$ is called n -dim foliation

(6) \exists Atlas of \mathcal{F} (U_α, h_α) s.t. $\forall \theta \in \Lambda: h_\alpha(F_\theta \cap U_\alpha) = \emptyset$ or $\mathbb{R}^n \times p \cap h_\alpha(U_\alpha)$



Ex: Flow lines of a non-vanishing vector field are 1-dimensional foliations

$$M = T^2$$



If slope $\in \mathbb{Q} \Rightarrow$ Leaves are compact

If slope $\in \mathbb{R} \setminus \mathbb{Q} \Rightarrow$ "noncompact"

If $k = n-1 \Rightarrow \mathcal{F} = \bigcup_{p \in M} T_p F(p)$ is a hypersurface field

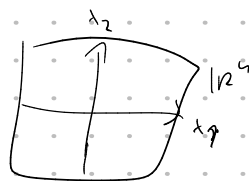
"every foliation of codim 1 induces a hypersurface field"

Q: When does a hypersurface come from a foliation?

Theorem 2 [Frobenius]

$\ker(\alpha) = \mathcal{F} \subset TM$ is induced by \mathcal{F} foliation $(\Leftrightarrow) \alpha \wedge d\alpha = 0$

digression: $\alpha_p: T_p M \xrightarrow{\text{1-form}} \mathbb{R}$ $\alpha_p \in (T_p M)^*$



Let x_1, \dots, x_n be coordinates on M

\Rightarrow coordinate vector fields $\partial_{x_1}, \dots, \partial_{x_n}$ form a basis of $T_p M$

Dual basis dx_1, \dots, dx_n , i.e. $dx_i(\partial_{x_j}) = \delta_{ij}$

$$\Rightarrow \alpha_p = \sum c_i(p) dx_i$$

n -form $\beta: \underbrace{(T_p M)^* \times \dots \times (T_p M)^*}_{n \text{ times}} \rightarrow \mathbb{R}$ multilinear, alternating

\wedge -product:

$$\begin{aligned} 1\text{-forms: } \alpha &= \sum c_i dx_i \\ \beta &= \sum b_j dx_j \end{aligned}$$

$$\begin{aligned} \alpha \wedge \beta &= \text{det. to be linear} \\ dx_i \wedge dx_j &= -dx_j \wedge dx_i \\ dx_i \wedge dx_i &= 0 \end{aligned}$$

Differential

$d: k\text{-form} \rightarrow (k+1)\text{-form}$

$$\begin{aligned} \sum c_i(p) dx_i &\mapsto d\alpha \\ &= \sum \frac{\partial c_i}{\partial x_j} dx_j \wedge dx_i \end{aligned}$$

Ex: $\gamma = \mathbb{R}^3_{(x,y,z)} \quad \alpha = dx \quad \Rightarrow \quad \alpha \wedge d\alpha$ comes from a foliation
 $d\alpha = d(dx) = 0$

(2) $\alpha = x dy + dz$

$$d\alpha = d(x dy + dz) = d(x dy) + d(dz) = \underbrace{\frac{\partial x}{\partial x}}_{=1} dx \wedge dy + \cancel{\frac{\partial x}{\partial y} dy \wedge dy}$$

$$\alpha \wedge d\alpha = (x dy + dz) \wedge (dx \wedge dy) = x dy \wedge (dx \wedge dy) + dz \wedge dx \wedge dy \\ = dx \wedge dy \wedge dz \neq 0$$

2.2 Contact structures Let M^{2n+1}

* $\gamma^{2n+1} = \ker(\alpha)$ is a contact structure $(\Leftrightarrow \alpha \wedge (d\alpha)^n \neq 0$ is a volume form
 { i.e. $\alpha \wedge (d\alpha)^n \neq 0$ at every point } $\alpha \wedge (d\alpha)^n = \alpha \wedge d\alpha \wedge \dots \wedge d\alpha$

* α is called contact form

* the reeb vector field R_α of α is defined

$$\begin{cases} d\alpha(R_\alpha, \cdot) \equiv 0 \\ \alpha(R_\alpha) \equiv 1 \end{cases}$$

remark: $\alpha \wedge (d\alpha)^n$ is a vol form $\Rightarrow M$ orientable

* $\gamma = \ker(\alpha) = \ker(\tilde{\alpha}) \Leftrightarrow \tilde{\alpha} = f\alpha$ for $f: M \rightarrow \mathbb{R} \setminus \{0\}$

$$\Rightarrow \tilde{\alpha} \wedge (d\tilde{\alpha})^n = (f\alpha) \wedge (d(f\alpha))^n = f\alpha \wedge (fd\alpha + d.f \wedge \alpha)^n$$

$$\alpha \wedge d\alpha = 0$$

$$= \underbrace{f^{n+1}}_{\neq 0} \underbrace{\alpha \wedge (d\alpha)^n}_{\neq 0}$$

* R_α is well-defined:

$$\alpha \wedge (d\alpha)^n \neq 0 \Rightarrow (d\alpha)^n \Big|_{\gamma} \neq 0 \Rightarrow d\alpha \text{ has rank } 2n \\ \nwarrow \text{2n-dimensional} \Rightarrow \ker(d\alpha) \text{ is 1-dim} \\ \text{simple} \quad \& \alpha \neq 0 \text{ on } \ker(d\alpha)$$

Warning (why: \cap closed \Rightarrow ?) \nexists contact form α on \mathbb{R}^n s.t. R_{α} is a periodic orbit

Ex) (1) Consider \mathbb{R}^{2n+1}
 $(x_1, y_1, \dots, x_n, y_n, z)$

$\xi_{st} = \ker(\alpha_{st})$ standard contact structure

$$\alpha_{st} = \left(\sum_{i=1}^n x_i dy_i \right) + dz$$

$$\begin{aligned} \alpha_{st} \wedge (d\alpha_{st})^n &= (\sum x_i dy_i + dz) \wedge (d(\sum x_i dy_i + dz))^n = (\sum x_i dy_i + dz) \wedge (\sum d x_i \wedge dy_i)^n \\ &= (\sum x_i dy_i + dz) \wedge (\sum d x_i \wedge dy_i) \wedge (\sum d x_i \wedge dy_i)^{n-2} \\ &= (\sum x_i dy_i + dz) \wedge \underbrace{(\sum_{i,j} d x_i \wedge dy_i \wedge d x_j \wedge dy_j)}_{\wedge (\sum d x_i \wedge dy_i)^{n-2}} \\ &= (\sum x_i dy_i + dz) \wedge n! (d x_1 \wedge d y_1 \wedge d x_2 \wedge d y_2 \wedge \dots \wedge d x_n \wedge d y_n) \\ &= dz \wedge n! (d x_1 \wedge d y_1 \wedge d x_2 \wedge d y_2 \wedge \dots \wedge d x_n \wedge d y_n) \\ &= n! d x_1 \wedge d y_1 \wedge d x_2 \wedge d y_2 \wedge \dots \wedge d x_n \wedge d y_n \wedge dz \neq 0 \end{aligned}$$

compute $R_{\alpha_{st}} = (\sum A_i \partial x_i + B_i \partial y_i) + C \partial z$

$$d\alpha_{st} (R_{st}, \cdot) = \sum A_i dy_i - B_i dx_i = 0$$

$$d\alpha_{st} (R_{st}) = C + \sum x_i B_i = 1$$

One solution: $R_{\alpha_{st}} = \partial_z$

$$(2) \xi_{syn} = \ker \left(\underbrace{\sum_{i=1}^n (x_i dy_i - y_i dx_i)}_{\alpha} + dz \right)$$

Homework: • This is a contact structure

- $R_{\alpha} = \partial_z$
- for $n=1$: draw plots
- read Milnor:
Topology from a
differential viewpoint
Jeffrey Lee