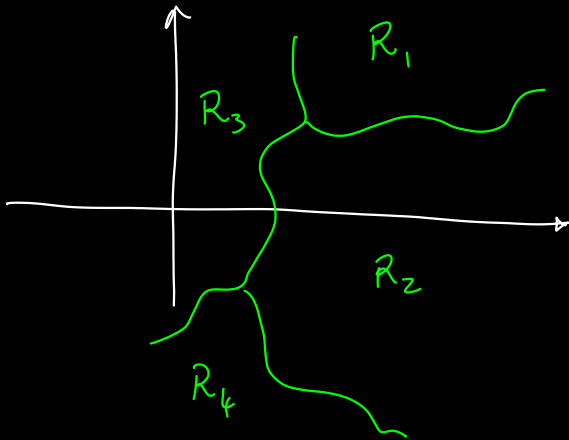


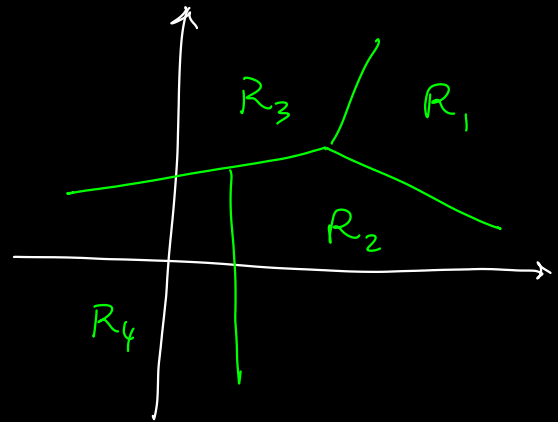
2022-09-16

# Linear and Probabilistic Models for Classification

Decision regions



Decision regions (linear models)



Example: 2 classes

$$\begin{cases} y(x) = w^T x + w_0 \\ x \in R_1 \text{ iff } y(x) \geq 0 \\ x \in R_2 \text{ iff } y(x) < 0 \end{cases} \quad (\text{sign}[y(x)])$$

Example  $w$

$$w_0 = -12, w_1 = 3, w_2 = 4$$

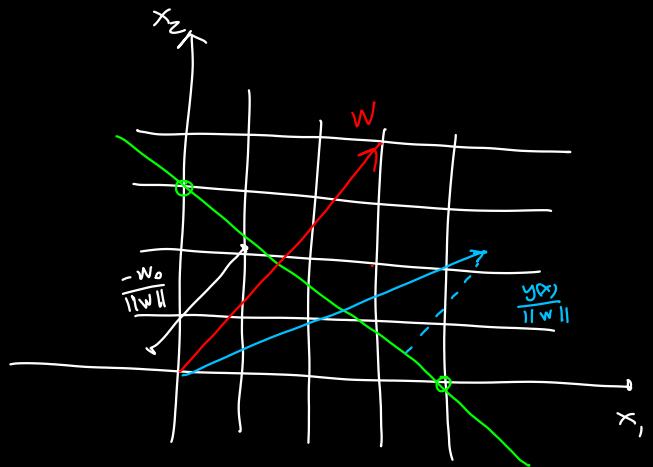
decision boundary:  $(x_1, x_2)$  s.t.  $y(x) = 0$

$$3x_1 + 4x_2 - 12 = 0$$

$$\|w\| = \sqrt{3^2 + 4^2} = \sqrt{25} = 5$$

$$\frac{-w_0}{\|w\|} = \frac{12}{5}$$

$$\frac{y(x)}{\|w\|}$$



Least squares

check derivations on the book

# Fisher's linear discriminant

linear classification viewed as dimensionality reduction

$$y = w^T X \quad \text{from } D \text{ to } 1 \text{ dimension}$$

we can select the projection that maximizes class separation

Example 2-class

$$C_1, N_1, C_2, N_2$$

$$\underline{m}_1 = \frac{1}{N_1} \sum_{n \in C_1} x_n \quad \underline{m}_2 = \frac{1}{N_2} \sum_{n \in C_2} x_n$$

simple measure of separation:

$$m_2 - m_1 = w^T (\underline{m}_2 - \underline{m}_1)$$

but this can be arbitrarily large (increasing  $\|w\|$ )

we can constrain  $\sum_i w_i = 1$

Problem:

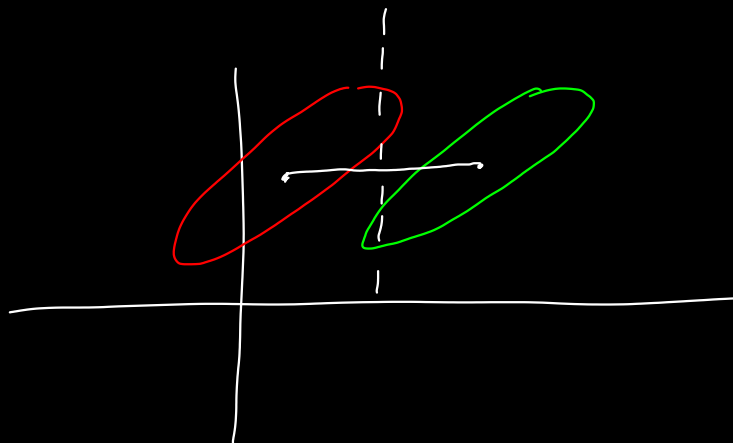


Fig 4.6

Idea: 1) maximize distance of projected means

2) minimize within-class projected variance

$$s_k^2 = \sum_{n \in C_k} (y_n - m_k)^2$$

$\uparrow$   
 $y(x_n) = w^T x_n$

total within-class variance:  $s_1^2 + s_2^2$

$$J(w) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2} \quad \text{Fisher's criterion}$$

$$= \frac{(w^T \underline{m}_2 - w^T \underline{m}_1)^2}{\sum_{n \in C_1} (w^T x_n - w^T \underline{m}_1)^2 + \sum_{n \in C_2} (w^T x_n - w^T \underline{m}_2)^2}$$

$$w^T (x_n - \underline{m}_1) [w^T (x_n - \underline{m}_1)]^T$$

$$w^T (x_n - \underline{m}_1) (x_n - \underline{m}_1)^T w$$

$$= \frac{w^T (\underline{m}_2 - \underline{m}_1) (\underline{m}_2 - \underline{m}_1)^T w}{w^T \left[ \sum_{n \in C_1} (x_n - \underline{m}_1) (x_n - \underline{m}_1)^T + \sum_{n \in C_2} (x_n - \underline{m}_2) (x_n - \underline{m}_2)^T \right] w}$$

$$= \frac{w^T S_B w}{w^T S_W w}$$

$S_B \leftarrow$  between-class covariance

$S_W \leftarrow$  within-class covariance

differentiating  $\Rightarrow w \propto S_W^{-1} (\underline{m}_2 - \underline{m}_1)$

$y = w^T x$  is roughly gaussian because of the central limit theorem.

least-squares  $\rightarrow$  minimize error w.r.t.  $t$

fisher  $\rightarrow$  maximize class separation in output space

If the target for class  $C_1$  is  $\frac{N}{N_1}$  (macro of prior)

$$C_2 \text{ is } -\frac{N}{N_2}$$

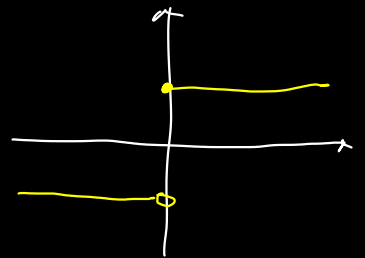
$\Rightarrow$  least squares  $\equiv$  fisher

## Perceptron

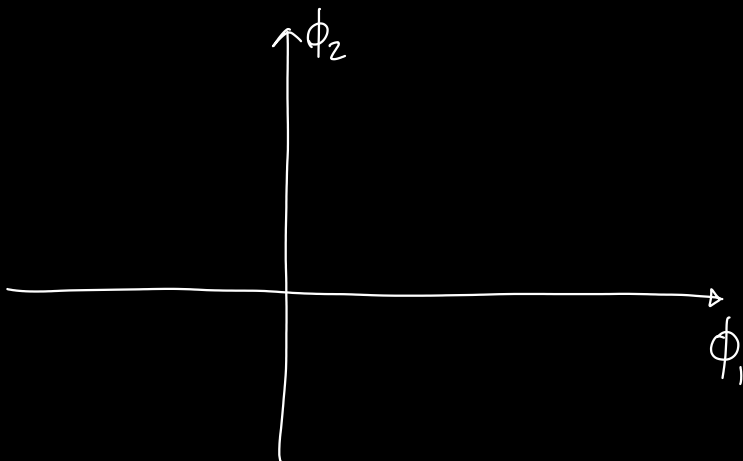
Rosenblatt 1962

$$y(x) = f(w^T \phi(x))$$

$$f(a) = \begin{cases} +1, & a \geq 0 \\ -1, & a < 0 \end{cases}$$



optimization of  $w$  through error minimization



$$t \in \{-1, +1\}$$

$$w^T \phi(x_n) > 0 \rightarrow C_1$$

$$w^T \phi(x_n) < 0 \rightarrow C_2$$

we would like  $w^T \phi(x_n) t_n > 0$  for all patterns

$$E_P(w) = - \sum_{n \in \mathcal{M}} w^T \phi(x_n) t_n$$

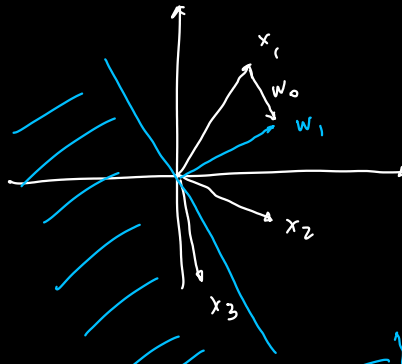
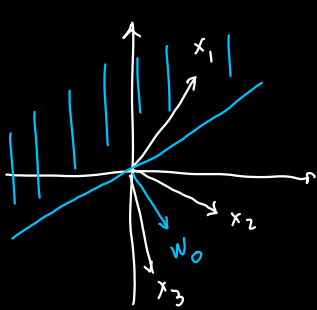
$\mathcal{M}$  = misclassified

# Stochastic gradient descent

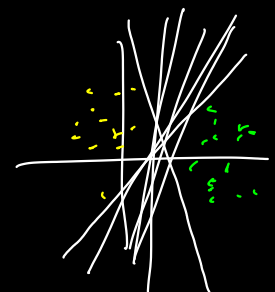
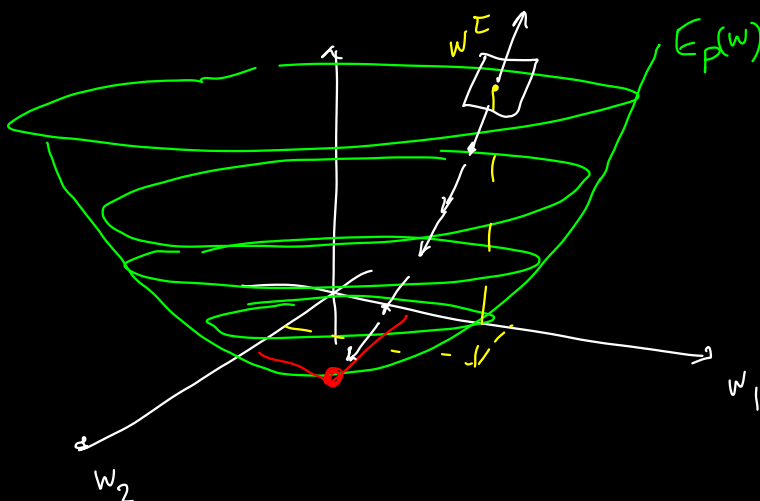
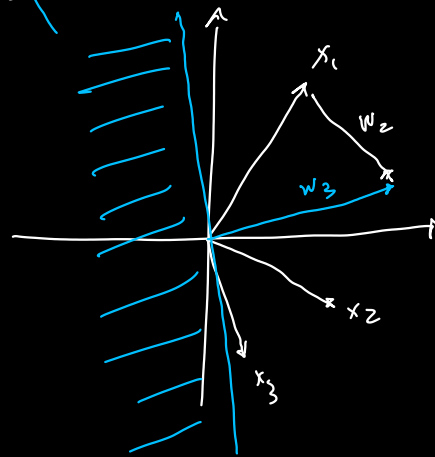
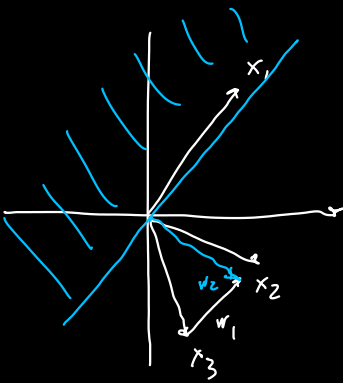
$$w^{(\tau+1)} = w^{(\tau)} - \underset{\substack{\uparrow \\ \text{learning rate}}}{\eta} \nabla E_p(w) = w^{(\tau)} + \eta \phi(x_n) t_n$$

because  $w \times \text{constant}$  does not change the solution, we can set  $\eta = 1$

not guaranteed to reduce error at each step



Fig



# Probabilistic models

## Maximum likelihood

In general we would like to maximize

(Duda makes class independence an assumption)

$$\begin{aligned} \ln \mathcal{L} &= \sum_{n=1}^N \ln p(x_n, t_n | \theta) \dots \left[ p(x_n, t_n | \theta) = p(x_n | t_n, \theta) p(t_n | \theta) \right] \\ &= \sum_{n=1}^N \left[ \ln p(x_n | t_n, \theta) + \ln p(t_n | \theta) \right] \dots \\ &= \sum_{k=1}^K \sum_{n: \{t_n=k\}} \left[ \ln p(x_n | C_k, \theta_k) + \ln p(C_k | \theta_k) \right] \end{aligned}$$

When we differentiate w.r.t. the parameters for class  $k$ , only data points belonging to that class influence the derivative.

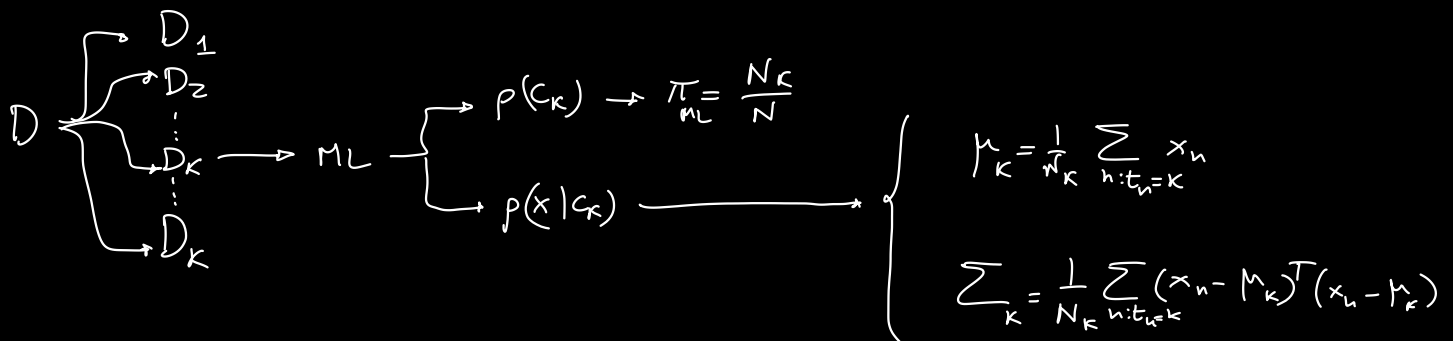
Example: Gaussian class-conditional likelihoods

$$p(C_k) = \pi_k$$

$$p(x | C_k) = \mathcal{N}(x | \mu_k, \Sigma_k)$$

$$\theta = \{ \pi_1, \dots, \pi_K, \mu_1, \dots, \mu_K, \Sigma_1, \dots, \Sigma_K \}$$

$$D \rightarrow p(x, C_k) \equiv$$



Special Case: equal  $\Sigma$

### Example Gaussian distributions

$$p(x|C_k) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma_k|^{1/2}} \exp \left\{ -\frac{1}{2} (x - \mu_k)^T \Sigma_k^{-1} (x - \mu_k) \right\}$$

if 2-class, decision boundary:

$$p(C_1|x) = 0.5 \Leftrightarrow \ln p(C_1|x) = c \Leftrightarrow \underbrace{\quad}_{c} \quad \text{quadratic}$$

if 2-classes and  $\Sigma_1 = \Sigma_2 = \Sigma \Rightarrow$

$$p(C_1|x) = \sigma(a)$$

$$a = \ln \frac{N(x|\mu_1, \Sigma) p(C_1)}{N(x|\mu_2, \Sigma) p(C_2)} = \cancel{\ln c} - \frac{1}{2} (x - \mu_1)^T \Sigma^{-1} (x - \mu_1) + \ln p(C_1) \\ - \cancel{\ln c} + \frac{1}{2} (x - \mu_2)^T \Sigma^{-1} (x - \mu_2) - \ln p(C_2)$$

$$= \cancel{-\frac{1}{2} x^T \Sigma^{-1} x} + \cancel{\frac{1}{2} x^T \Sigma^{-1} x} - \frac{1}{2} \mu_1^T \Sigma^{-1} \mu_1 + \frac{1}{2} \mu_2^T \Sigma^{-1} \mu_2$$

$$+ \mu_1^T \Sigma^{-1} x - \mu_2^T \Sigma^{-1} x + \ln \frac{p(C_1)}{p(C_2)}$$

$$= \underbrace{(\mu_1 - \mu_2)^T \Sigma^{-1} x}_{w^T} - \underbrace{\frac{1}{2} \mu_1^T \Sigma^{-1} \mu_1 + \frac{1}{2} \mu_2^T \Sigma^{-1} \mu_2 + \ln \frac{p(C_1)}{p(C_2)}}_{w_0}$$

$$= w^T x + w_0 \quad \text{linear!}$$