

Cracking computational modelling with Stan: Using Rescorla-Wagner model as an example

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https://github.com/lei-zhang/RL_tutorial_webinar





Outline

- About me
- What is computational modeling?
- The idea of the simple Rescorla-Wagner (RW) model
- Implementing RW model for one subject in Stan
- Fitting multiple subjects with the hBayesDM package
- Summary

About me



Postdoc @univie



PhD + Postdoc @UKE



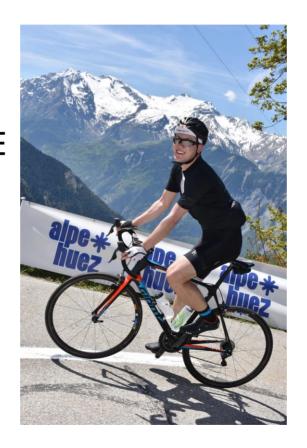
RiSE intern@Roche



MSc @BCBL



BSc @BNU



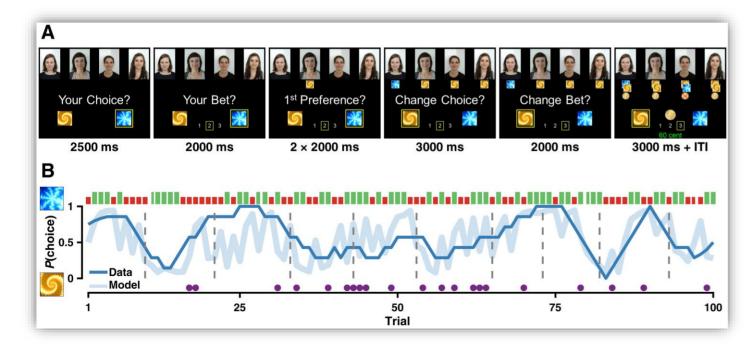


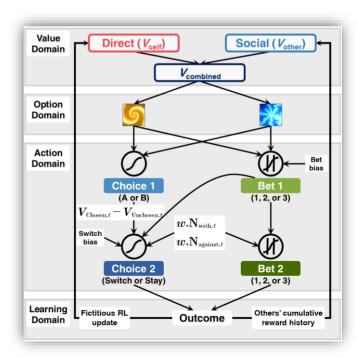
310km in one day!



My research

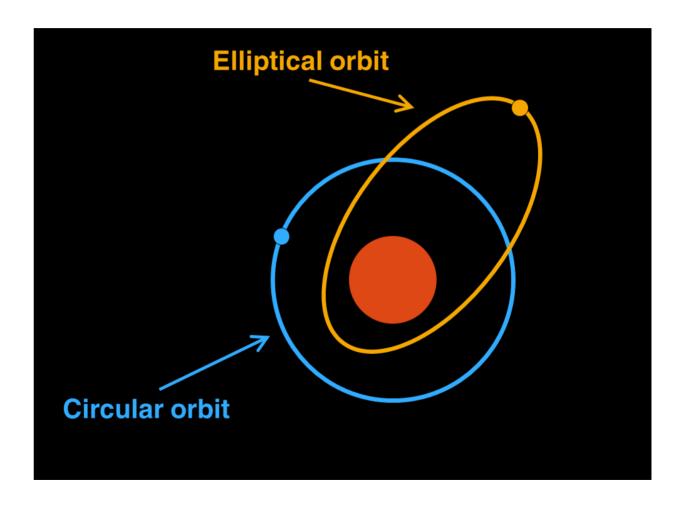
- Overarching goal: uncover the neuro-computational mechanisms underlying social decision-making
- Methods: behavioral/physiological measurement, cognitive modeling, fMRI
- Example work: A brain network supporting social influences in human decision-making (Zhang & Gläscher, bioRxiv)



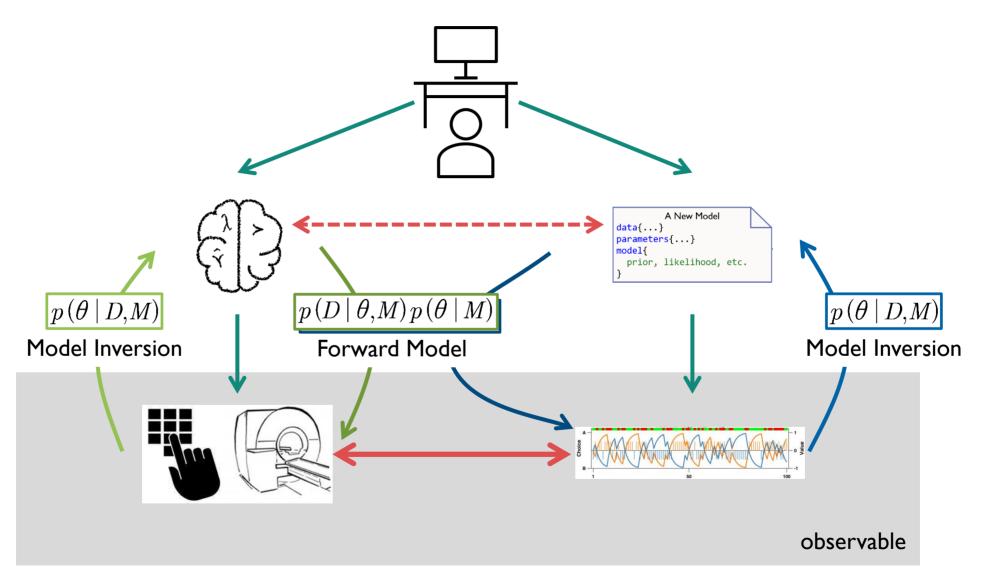


The idea of computational modeling is never new

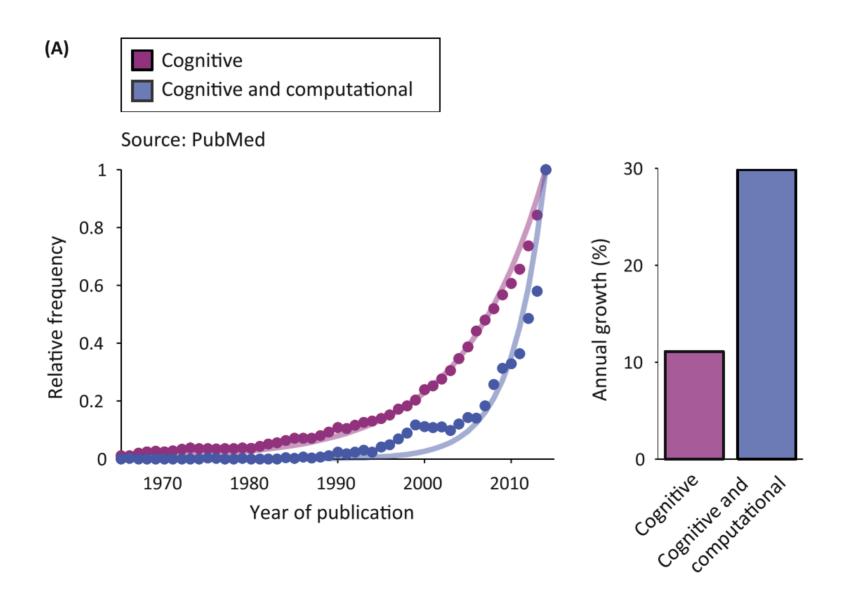
Scientists use mathematical models to approximate certain processes (physical or mental), in order to explain and to predict.



Computational modeling of Cognition



Boom in Computational Modeling



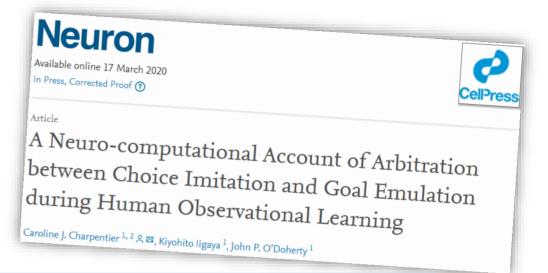
Very recent examples

Dopamine promotes cognitive effort by biasing the benefits versus costs of cognitive work

A. Westbrook^{1,2,3,*}, R. van den Bosch^{2,3}, J. I. Määttä^{2,3}, L. Hofmans^{2,3}, D. Papadopetraki^{2,3}, R. Cools^{2,3,†}, M. J. Frank^{1,4,†}

+ See all authors and affiliations

Science 20 Mar 2020: Vol. 367, Issue 6484, pp. 1362-1366 DOI: 10.1126/science.aaz5891



3 out of 4 focused on Reinforcement Learning models!

nature reviews neuroscience

Review Article | Published: 12 March 2020

The neural and computational systems of social learning

Andreas Olsson ≅, Ewelina Knapska & Björn Lindström

Nature Reviews Neuroscience 21, 197–212(2020) | Cite this article

Article Open Access Published: 17 March 2020

Neurocomputational mechanisms underpinning aberrant social learning in young adults with low self-esteem

Goodyer, Peter Fonagy, Peter B. Jones, NSPN Consortium, Robb B. Rutledge & Raymond J. Dolan

Simple reinforcement learning: 2-armed bandit task





a simple task often used in the laboratory:

- repeated choice between N options (N-armed bandit)
- ...whose properties (reward amounts, probabilities) are learned through trial-and-error
- ...with a goal in mind: maximize the overall reward

2-armed bandit task

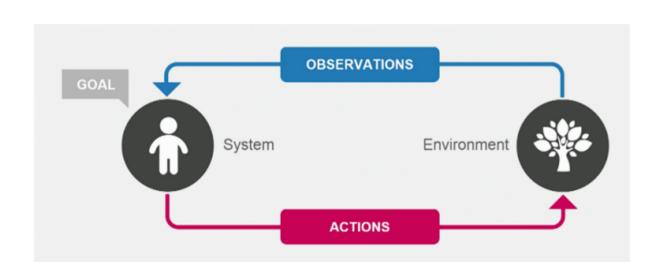


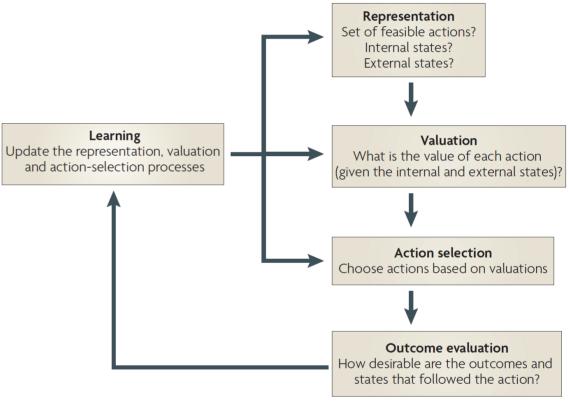


What can be your strategies:

- I. predict the value of each deck
- 2. choose the best
- 3. learn from outcome to update predictions (repeat)

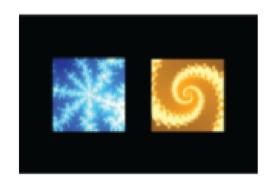
How prediction is shaped by learning?



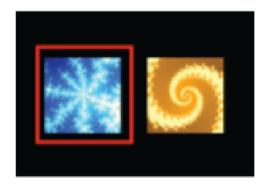




One simple experiment: two choice task







action selection



outcome

what do we know?

what can we measure?

what do we not know?

choice & outcome

choice accuracy

RL update

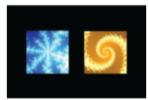
	subjID	trialID	choice	outcome
1	1	1	1	1
2	1	2	1	1
3	1	3	1	1

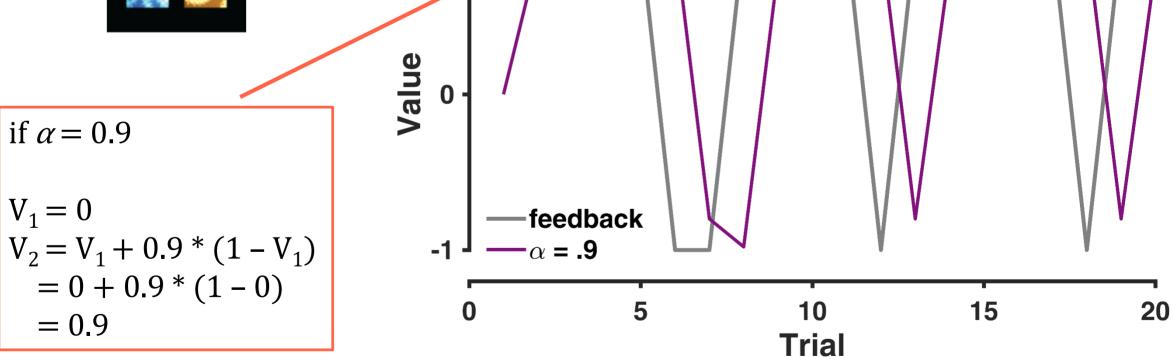
p(choosing the better option)

Understand the learning rate

Value update: $V_t = V_{t-1} + \alpha * PE_{t-1}$

Prediction error: $PE_{t-1} = R_{t-1} - V_{t-1}$

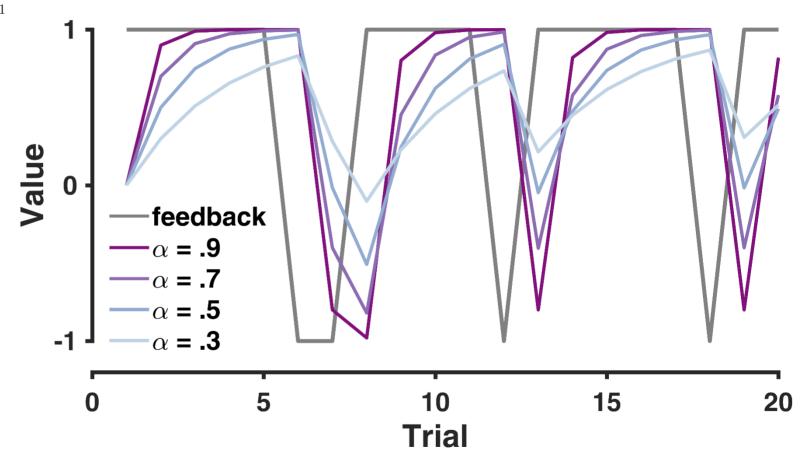




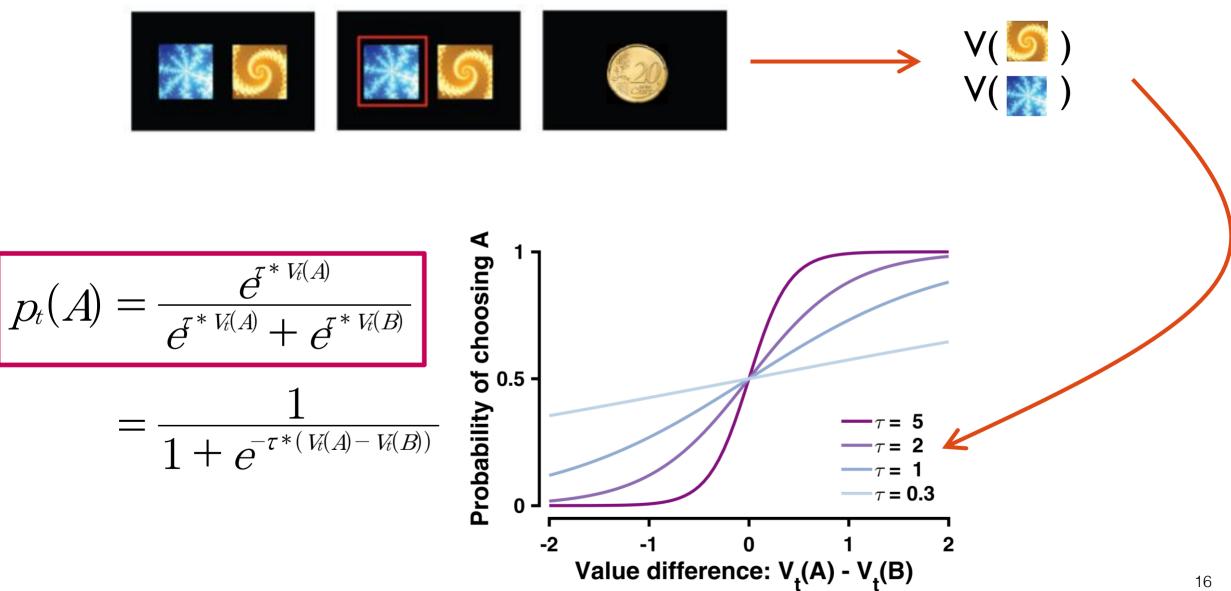
Understand the learning rate

Value update: $V_t = V_{t-1} + \alpha * PE_{t-1}$

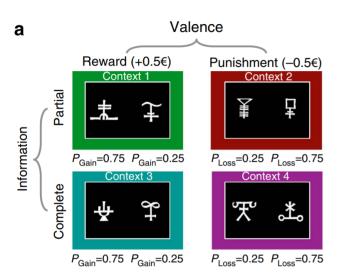
Prediction error: $PE_{t-1} = R_{t-1} - V_{t-1}$



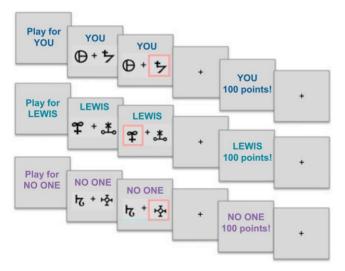
Choice rule: softmax



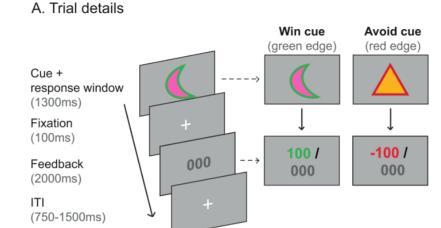
Generalizing RL framework



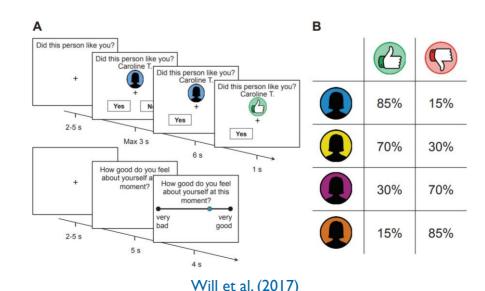
Palminteri et al. (2015)



Lockwood et al. (2016)



Swart et al. (2017)



Learning
Update the representation, valuation and action-selection processes

Valuation
What is the value of each action (given the internal and external states)?

Action selection
Choose actions based on valuations

Outcome evaluation
How desirable are the outcomes and states that followed the action?

Bayesian analysis in Stan

Likelihood

How plausible is the data given our parameter is true?

Prior

How plausible is our parameter before observing the data?

$$p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)}$$

Posterior

How plausible is our parameter given the observed data?

Evidence

How plausible is the data under all possible parameters?

Getting rid of the denominator

$$p\left(\theta\mid D\right) = \frac{p\left(D\mid\theta\right)p\left(\theta\right)}{\int p\left(D\mid\theta^*\right)p\left(\theta^*\right)d\theta^*}$$

$$p(data) = \int_{\text{All}\theta_1} \int_{\text{All}\theta_2} p(data,\theta_1,\theta_2)d\theta_1d\theta_2$$

$$p(data) = \int_{\mu_1} \int_{\sigma_1} \dots \int_{\mu_{100}} \int_{\sigma_{100}} \underbrace{p(data\mid\mu_1,\sigma_1,\dots,\mu_{100},\sigma_{100})}_{\text{likelihood}} \times \underbrace{p(\mu_1,\sigma_1,\dots,\mu_{100},\sigma_{100})}_{\text{prior}} \times \underbrace{p(\mu_1,\sigma_1,\dots,\mu_{100},\sigma_{100})}_{\text{prior}}$$

$$d\mu_1d\sigma_1...d\mu_{100}d\sigma_{100},$$

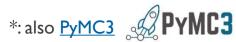
$$p\left(\theta\mid D\right) \propto p\left(D\mid\theta\right)p\left(\theta\right)$$

important property that can be made use of by algorithms, e.g., Markov Chain Monte Carlo (MCMC)

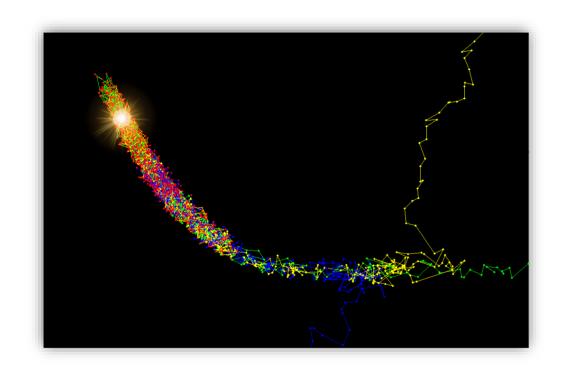
MCMC Sampling Algorithms

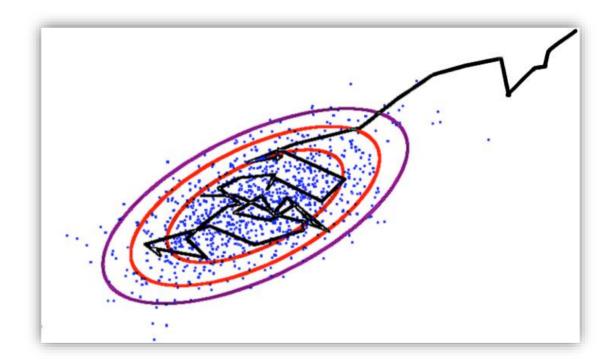
- Rejection sampling
- Importance sampling
- Metropolis algorithm
- Gibbs sampling → JAGS
- HMC sampling*



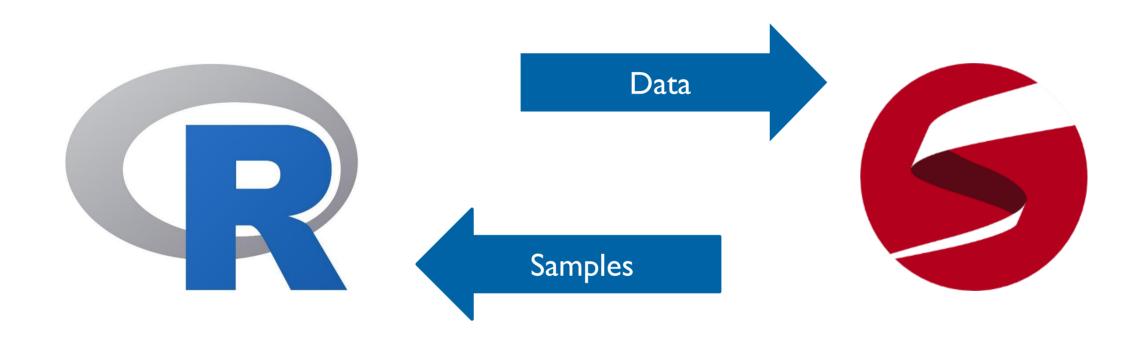


Visual Example





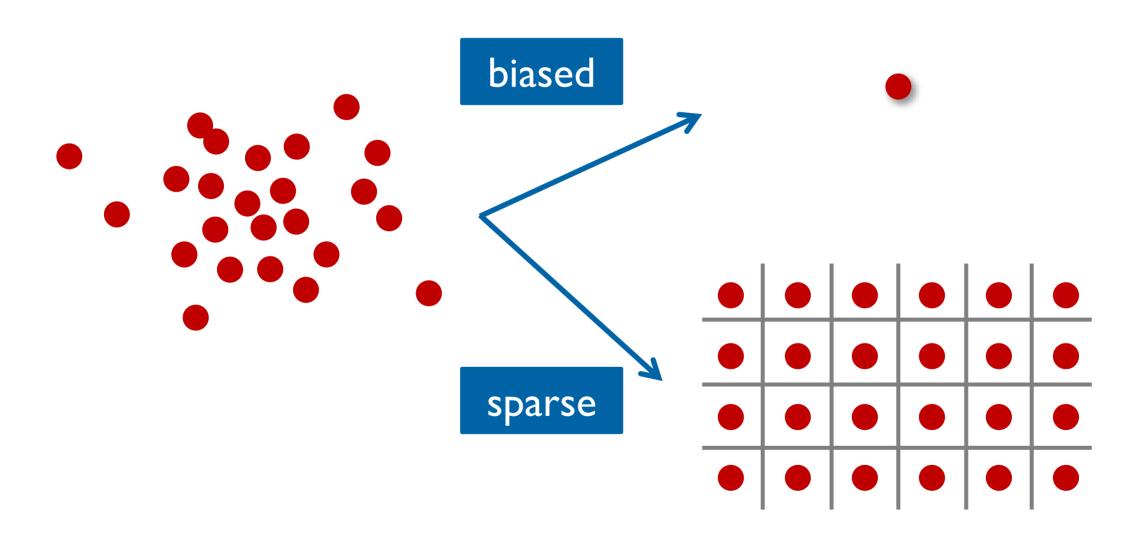
Stan and RStan



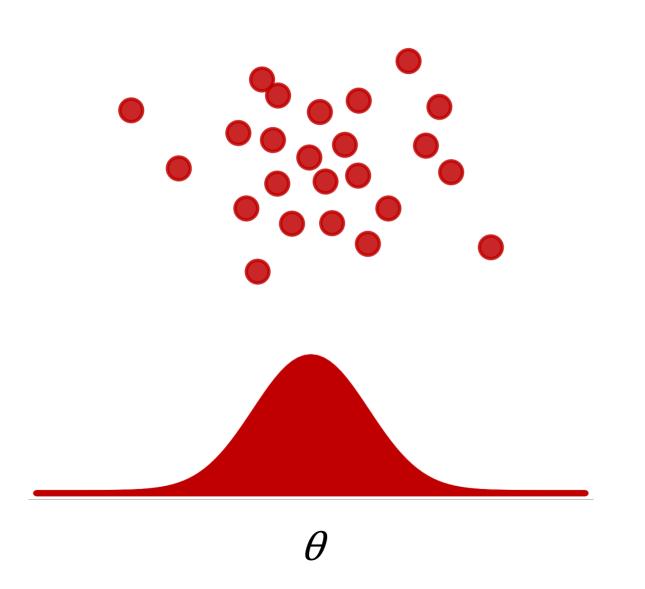
Stan Language

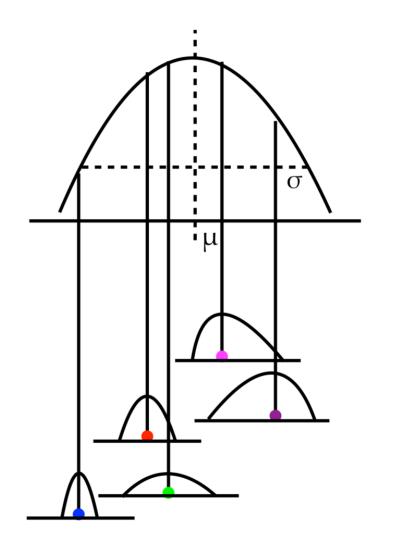
```
data {
//... read in external data...
transformed data {
//... pre-processing of data ...
parameters {
//... parameters to be sampled by HMC ...
transformed parameters {
//... pre-processing of parameters ...
model {
//... statistical/cognitive model ...
generated quantities {
//... post-processing of the model ...
```

Fitting Multiple Participants

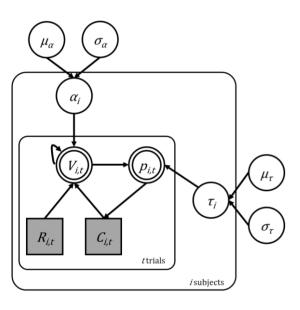


Fitting Multiple Participants with hierarchical Bayesian analysis (HBA)





HBA sounds good, but...



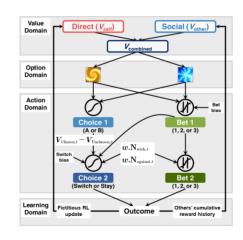
 $\mu_{\alpha} \sim Uniform(0,1)$ $\sigma_{\alpha} \sim halfCauchy(0,1)$ $\mu_{\tau} \sim Uniform(0,3)$ $\sigma_{\tau} \sim halfCauchy(0,3)$

 $\alpha_i \sim Normal(\mu_{\alpha}, \sigma_{\alpha})_{\mathcal{T}(0,1)}$

 $\tau_i \sim Normal(\mu_{\tau}, \sigma_{\tau})_{\tau(0,3)}$

$$p_{i,t}(C=A) = rac{1}{1 + e^{ au_{i}(V_{i,t}(B) - V_{i,t}(A))}}$$

$$V_{i,t+1}^c = V_{i,t}^C + lpha_i (R_{i,t} - V_{i,t}^C)$$



$$\begin{array}{lll} \mathbb{V}_{\text{other,I}} &= [V_{\text{self,I}}(A), V_{\text{self,I}}(B)] \\ \mathbb{V}_{\text{other,I}} &= [V_{\text{other,I}}(A), V_{\text{other,I}}(B)] \\ \mathbb{V}_{t} &= \beta_{\text{velf}} \mathbb{V}_{\text{wilf,I}} + \beta_{\text{vother}} \mathbb{V}_{\text{other,I}} \\ \mathbb{C}1_{t} &\sim Categorical(Softmax(\mathbb{V}_{t})) \\ \mathbb{U}_{\text{bet1,I}} &= \beta_{\text{bise,st}} + \beta_{\text{vidif,In}}(V_{\text{chosen,C1,I}} - V_{\text{unchosen,C1,I}}) \\ \mathbb{B}1_{t} &\sim CrderedLogistic(U_{\text{bet1,I}} \mid \theta) \\ \\ w.N_{\text{against,I}} &= \frac{\sum\limits_{s=1}^{K} w_{s,t}}{\sum\limits_{s=1}^{4} w_{s,t}}, K = 0, 1, ..., 4 \\ \\ w.N_{\text{with,t}} &= \frac{\sum\limits_{s=1}^{K} w_{s,t}}{\sum\limits_{s=1}^{4} w_{s,t}} \\ \mathbb{V}_{t}(\text{switch}) &= \beta_{\text{bisec,T}} + \beta_{\text{wiif,ET}}(V_{\text{chosen,C1,I}} - V_{\text{unchosen,C1,I}}) + \beta_{\text{against,W}}.N_{\text{against,I}} \\ \mathbb{C}2 &\sim Bernoulli(V_{t}(\text{switch})) \\ \mathbb{U}_{\text{be2,t}} &= \frac{U_{\text{bet1,t}} + \beta_{\text{with,eco,W}}.N_{\text{with,t}} + \beta_{\text{against,eco,W}}.N_{\text{against,I}}, \text{ if } C1 = C2 \\ \mathbb{U}_{\text{bet1,t}} + \beta_{\text{with,eco,W}}.N_{\text{with,t}} + \beta_{\text{against,eco,W}}.N_{\text{against,I}}, \text{ if } C1 \neq C2 \\ \mathbb{E}2_{t} &\sim CrderedLogistic(U_{\text{be2,I}} \mid \theta) \\ \mathbb{\Phi}(x) &= \frac{1}{1 + e^{-x}} \\ \mathcal{S}_{\text{self,chosen,C2,I}} &= R_{\text{self,t}} - V_{\text{self,chosen,C2,I}} \\ \mathcal{V}_{\text{self,chosen,C2,I}} &= V_{\text{self,chosen,C2,I}} + \alpha \mathcal{S}_{\text{self,unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha \mathcal{S}_{\text{self, unchosen,C2,I}} \\ \mathbb{V}_{\text{self, unchosen,C2,I}} &= V_{\text{self, unchosen,C2,I}} + \alpha$$



RESEARCH

Revealing Neurocomputational Mechanisms of Reinforcement Learning and Decision-Making With the hBayesDM Package

Woo-Young Ahn¹, Nathaniel Haines¹, and Lei Zhang²

¹Department of Psychology, The Ohio State University, Columbus, OH

²Institute for Systems Neuroscience, University Medical Center Hamburg-Eppendorf, Hamburg, Germany

Keywords: reinforcement learning, decision-making, hierarchical Bayesian modeling, model-based fMRI

https://ccs-lab.github.io/hBayesDM/articles/getting_started.html



Getting Started

Source: vignettes/getting_started.Rmd

hBayesDM (hierarchical Bayesian modeling of Decision-Making tasks) is a user-friendly R package that offers hierarchical Bayesian analysis of various computational models on an array of decision-making tasks. Click here to download its help file (reference manual). Click here to read our paper published in Computational Psychiatry. Click here to download a poster we presented at several conferences/meetings. You can find hBayesDM on CRAN and GitHub.

Recommended reading: tutorial

Using reinforcement learning models in social neuroscience: frameworks, pitfalls, and suggestions of best practices

AUTHORS

Lei Zhang, Lukas Lengersdorff, Nace Mikus, Jan Gläscher, Claus Lamm

CREATED ON November 06, 2019 LAST EDITED
March 19, 2020

https://psyarxiv.com/uthw2

ACCEPTED MANUSCRIPT

Computational modelling of social cognition and behaviour—a reinforcement learning primer 3

Patricia L Lockwood ™, Miriam Klein-Flügge ™

Social Cognitive and Affective Neuroscience, nsaa040, https://doi.org/10.1093/scan/nsaa040

Published: 30 March 2020 Article history ▼

https://academic.oup.com/scan/advance-article/doi/10.1093/scan/nsaa040/5813717

Ten simple rules for the computational modeling of behavioral data

f y 🗷

Robert C Wilson [™], Anne GE Collins [™]

University of Arizona, United States; University of California, Berkeley, United States

https://elifesciences.org/articles/49547

The Importance of Falsification in Computational Cognitive Modeling

Stefano Palminteri, 1,2,*,‡ Valentin Wyart, 1,2,*,‡ and Etienne Koechlin 1,2,*

https://doi.org/10.1016/j.tics.2017 .03.011

Recommended reading: empirical work

Catecholaminergic challenge uncovers distinct Pavlovian and instrumental mechanisms of motivated (in)action



Jennifer C Swart M., Monja I Froböse, Jennifer L Cook, Dirk EM Geurts, Michael J Frank, Roshan Cools, Hanneke EM den Ouden Radboud University, The Netherlands; University of Birmingham, United Kingdom; Radboud University Medical Center, The Netherlands; Linguistic and Psychological Sciences, Brown University, United States; Brown University, United States

https://elifesciences.org/articles/22169

New Results

Comment on this paper

A brain network supporting social influences in human decision-making

Lei Zhang, Jan P. Gläscher

doi: https://doi.org/10.1101/551614

https://www.biorxiv.org/content/10.1101/551614v3

Social threat learning transfers to decision making in humans

Björn Lindström^{a,b,c,1}, Armita Golkar^{c,d}, Simon Jangard^c, Philippe N. Tobler^b, and Andreas Olsson^c

^aDepartment of Social Psychology, University of Amsterdam, 1018 WT Amsterdam, The Netherlands; ^bLaboratory for Social and Neural Systems Research, Department of Economics, University of Zürich, 8001 Zürich, Switzerland; ^cSection for Psychology, Department of Clinical Neuroscience, Karolinska Institutet, 171 77 Stockholm, Sweden; and ^dDepartment of Clinical Psychology, University of Amsterdam, 1018 WT Amsterdam, The Netherlands

https://www.pnas.org/content/116/10/4732.abstract

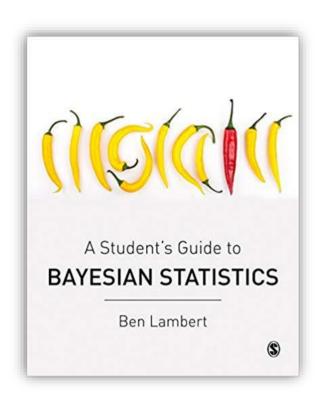
Article

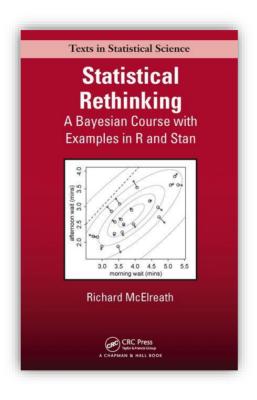
Primate Amygdala Neurons Simulate Decision Processes of Social Partners

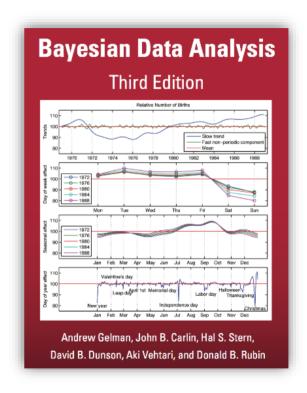
Fabian Grabenhorst ^{1, 5} A ☑, Raymundo Báez-Mendoza ^{1, 4}, Wilfried Genest ¹, Gustavo Deco ^{2, 3}, Wolfram Schultz ¹

https://www.sciencedirect.com/science/article/pii/S0092 867419302259

Recommended reading: book

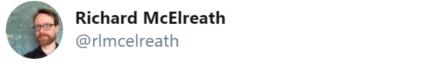






Summary

- Computational modeling is never new → don't let it fear you!
- Learn some statistics (e.g., different statistical distributions)
- Learn some math (e.g., linear algebra)
- Learn some programing (e.g., R/Python/Julia/Matlab)
- Learn to seek external help (e.g., existing packages)
- Learn in pairs; practice makes perfect!



I say this a lot, bc I am also confused quite often.



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AN JEST 10N

Happy Computing!