



## Radboud University Nijmegen

 Iterative processes - (coupled) difference / differential equations that represent autocatalytic change processes, the time-evolution of a system observable



Timeseries - a record of values generated by an iterative / change process

 Solution - if available, actual iterations of the function are not necessary. Only available for a very limited set of (coupled) equations.

The return plot - a scatterplot of Y<sub>i</sub> vs. Y<sub>i+1..n</sub>

The state / phase space - A space spanned by M observable dimensions of the system.

Depending on parameter settings a system can be attracted to just a few states: Attractors

Not discussed: The cobweb method

• The phase / bifurcation diagram - diagram representing the parameter space of a system. Its dimensions represent the possible values of the control parameter(s) of the system. Stable regions are often labelled by an order parameter (solid, liquid, gas).

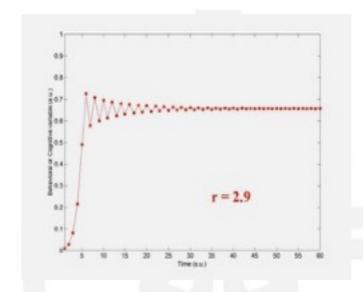
Today: Potential Functions - A functions describing the relative stability of the 'end-states' of

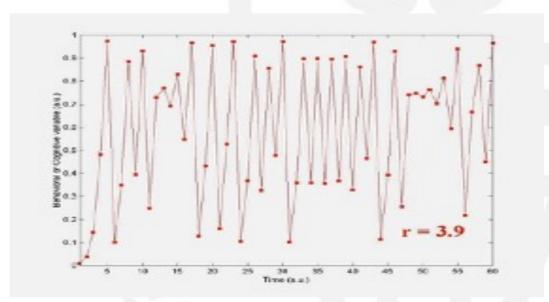
## Story so far - Assignments session 1: Different ways to represent characteristics of change processes

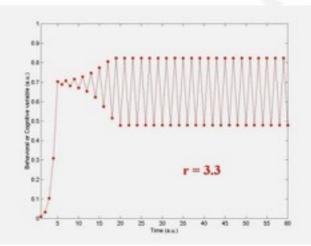
## Story so far - Assignments session 1: Different ways to represent characteristics of change processes

- Iterative processes (coupled) difference / differential equations that represent autocatalytic change processes, the time-evolution of a system observable
- Timeseries a record of values generated by an iterative / change process
- Solution if available, actual iterations of the function are not necessary. Only available for a very limited set of (coupled) equations.
- The return plot a scatterplot of Y<sub>i</sub> vs. Y<sub>i+1..n</sub>
- The state / phase space A space spanned by M observable dimensions of the system.
  - Depending on parameter settings a system can be attracted to just a few states: Attractors
  - Not discussed: The cobweb method

## Story so far - Assignments session 1: Return plot of the logistic map







$$L_{i+1} = rL_i(1-L_i)$$