

Induced voltage:  $\mathcal{E} = - \frac{d\Phi_B}{dt}$  ;  $\mathcal{E} = -N \frac{d\Phi_B}{dt}$

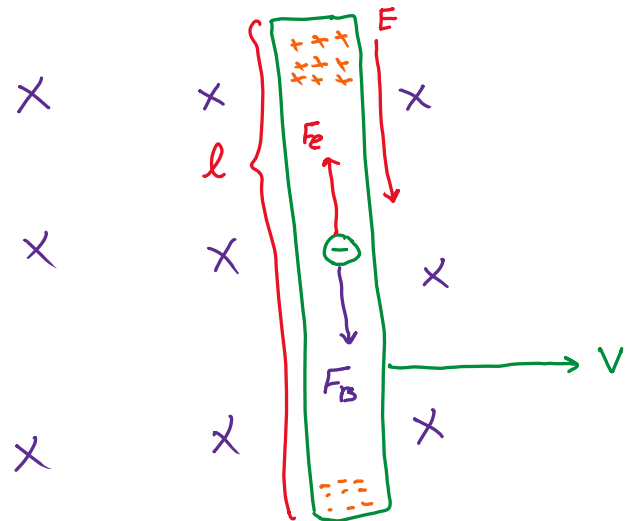
$$= - \frac{d[BA \cos \theta]}{dt}$$

$$F_B = q v B$$

$$F_e = q E$$

$$F_e = F_B \Rightarrow q E = q v B.$$

$$\Rightarrow \boxed{E = v B} \text{ equilibrium}$$



$$E = \frac{\Delta V}{l} \Rightarrow \Delta V = E l = v B l$$

$$I = \frac{\Delta V}{R} = \frac{v B l}{R}$$

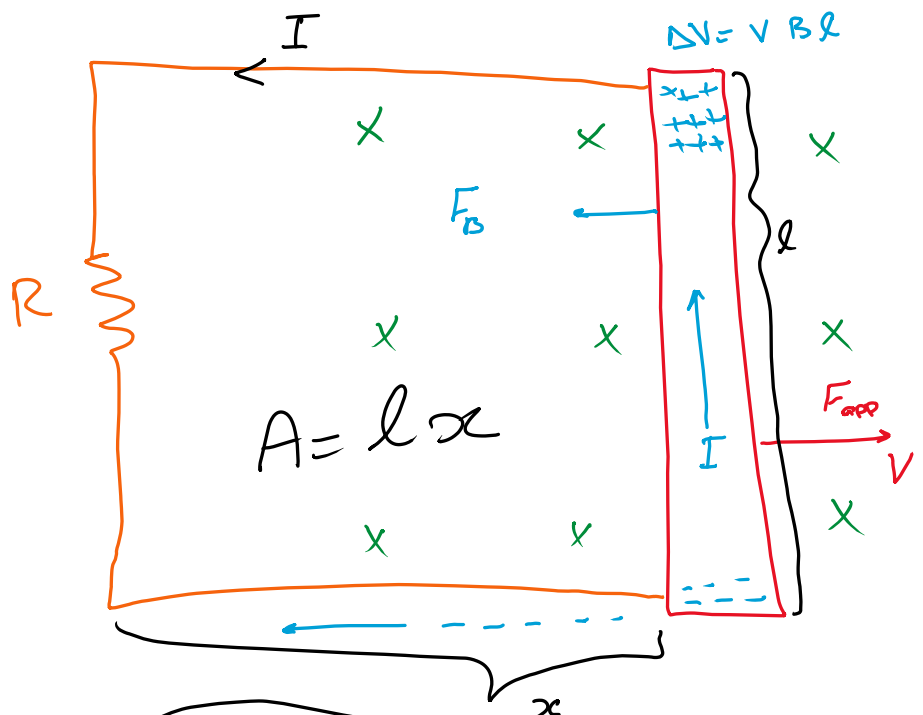
$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

$$= - \frac{d[BA \cos \theta]}{dt}$$

$$= - B \frac{dA}{dt} = - B l \frac{dx}{dt}$$

$$\boxed{\mathcal{E} = - B l v}$$

↓  
motional emf



$$\boxed{P = \frac{\mathcal{E}^2}{R} = F_{app} v}$$

$$F_{app} = F_B = I l B$$

$$\xi = -N \frac{d\Phi_B}{dt} = -NBA \frac{d[\cos \theta]}{dt} \quad \theta =$$

$$\omega = \text{rad/sec} = \frac{\theta}{t} \quad = -NBA \frac{d[\cos \omega t]}{dt}$$

$$\theta = \omega t$$

$$= -NBA [-\sin \omega t \cdot \omega]$$

$$\xi = NBA \omega \sin \omega t$$

$$\xi_{\max} = NBA \omega$$