Abstract Interpretation Idea. Lattices and Fixpoints

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## Basic idea of abstract interpretation

Abstract interpretation is a way to infer properties of program computations. Consider the assignment: z = x + y.

Interpreter:

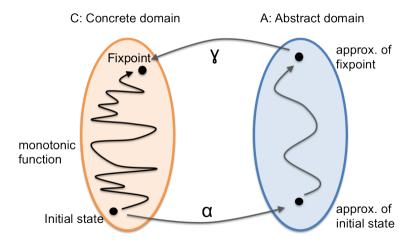
$$\begin{pmatrix} x:10 \\ y:-2 \\ z:3 \end{pmatrix} \xrightarrow{z=x+y} \begin{pmatrix} x:10 \\ y:-2 \\ z:8 \end{pmatrix}$$

Abstract interpreter:

$$\begin{pmatrix} x \in [0, 10] \\ y \in [-5, 5] \\ z \in [0, 10] \end{pmatrix} \xrightarrow{z = x + y} \begin{pmatrix} x \in [0, 10] \\ y \in [-5, 5] \\ z \in [-5, 15] \end{pmatrix}$$

Each abstract state represents a set of concrete states

# Program Meaning is a Fixpoint. We Approximate It.



 $\gamma$  maps abstract states to concrete states

# Programs as control-flow graphs

```
One possible corresponding control-flow graph is:
i = 0;
 //b
while (i < 10) {
  if (i > 1)
   i = i + 3:
  else
 i = i + 2;
```

# Programs as control-flow graphs

```
One possible corresponding control-flow graph is:
while (i < 10) {
  \mathbf{if} (i > 1)
                                                   [i \le 9]
    i = i + 3:
                                      [i \ge 2]
                                                       [i \leq 1]
  else
                                    i = i + 3
//c
```

# Sets of states at each program point Suppose that

- ightharpoonup program state is given by the value of the integer variable i
- initially, it is possible that i has any value

Compute the set of states at each vertex in the CFG.

```
i = 0:
while (i < 10) {
   //d
                                                        [i \le 9]
  if (i > 1)
     i = i + 3:
                                           [i ≥ 2]
                                                             [i \leq 1]
  else
                                         i = i + 3
                                                             i = i + 2
   //g
```

# Sets of states at each program point Suppose that

- ightharpoonup program state is given by the value of the integer variable i
- ▶ initially, it is possible that i has any value Compute the set of states at each vertex in the CFG.

```
i = 0:
while (i < 10) {
                                                           \{0, 2, 5, 8, 11\}
   //d
  if (i > 1)
     i = i + 3:
                                           [i ≥ 2]
  else
                                                  {2,5,8}
                                         i = i + 3
   //g
```

# Sets of states at each program point

#### **Running the Program**

One way to describe the set of states for each program point: for each initial state, run the CFG with this state and insert the modified states at appropriate points.

#### Reachable States as A Set of Recursive Equations

If c is the label on the edge of the graph, let  $\rho(c)$  denotes the relation between initial and final state that describes the meaning of statement. For example,

$$\begin{split} &\rho(i=0) = \{(i,i') \mid i'=0\} \\ &\rho(i=i+2) = \{(i,i') \mid i'=i+2\} \\ &\rho(i=i+3) = \{(i,i') \mid i'=i+3\} \\ &\rho([i<10]) = \{(i,i') \mid i'=i \land i < 10\} \end{split}$$

Sets of states at each program point

We will write T(S,c) (transfer function) for the image of set S under relation  $\rho(c)$ . For example,

$$T({10, 15, 20}, i = i + 2) = {12, 17, 22}$$

General definition can be given using the notion of strongest postcondition

$$T(S,c) = sp(S, \rho(c))$$

If [p] is a condition (assume(p), coming from 'if' or 'while') then

$$T(S,[p]) = \{x \in S \mid p\}$$

If an edge has no label, we denote it skip. So, T(S, skip) = S.

## Reachable States as A Set of Recursive Equations

Now we can describe the meaning of our program using recursive equations:

$$S(a) = \{\dots, -2, -1, 0, 1, 2, \dots\}$$

$$S(b) = T(S(a), i = 0) \cup T(S(g), skip)$$

$$S(c) = T(S(b), [\neg (i < 10)])$$

$$S(d) = T(S(b), [i < 10])$$

$$S(e) = T(S(d), [i > 1])$$

$$S(f) = T(S(d), [\neg (i > 1)])$$

$$S(g) = T(S(e), i = i + 3)$$

$$\cup T(S(f), i = i + 2)$$

$$i = 0$$

$$\{0, 2, 5, 8, 11\}$$

$$[i \ge 2]$$

$$\{0, 2, 5, 8, 11\}$$

$$[i \ge 2]$$

$$\{i \ge 2\}$$

$$\{i \ge 1\}$$

$$\{i \ge 1\}$$

$$\{i \ge 1\}$$

$$\{i \ge 1\}$$

$$\{i \le 1\}$$

Our solution is the unique **least** solution of these equations. Can be computed by iterating starting from empty sets as initial solution.

**The problem:** These exact equations are as difficult to compute as running the program on all possible input states. Instead, we consider **approximate** descriptions of these sets of states.

A Large Analysis Domain: All Intervals of Integers

For every  $L, U \in \mathbb{Z}$  interval:

$$\{x \mid L \leq x \land x \leq U\}$$

This domain has infinitely many elements, but is already an approximation of all possible sets of integers.

# Smaller Domain: Finitely Many Intervals

We continue with the same example but instead of allowing to denote all possible sets, we will allow sets represented by expressions

[L, U]

which denote the set  $\{x \mid L \leq x \land x \leq U\}$ .

**Example:** [0, 127] denotes integers between 0 and 127.

- ightharpoonup L is the lower bound and U is the upper bound, with  $L \leq U$ .
- to ensure that we have only a few elements, we let

$$L,U \in \{\mathsf{MININT}, -128, 1, 0, 1, 127, \mathsf{MAXINT}\}$$

- ► [MININT, MAXINT] denotes all possible integers, denote it ⊤
- ightharpoonup instead of writing [1,0] and other empty sets, we will always write  $\perp$

So, we only work with a finite number of sets  $1 + {7 \choose 2} = 22$ . Denote the family of these sets by D (domain).

## New Set of Recursive Equations

We want to write the same set of equations as before, but because we have only a finite number of sets, we must approximate. We approximate sets with possibly larger sets.

```
S^{\#}(a) = \top
S^{\#}(b) = T^{\#}(S^{\#}(a), i = 0)
\qquad \sqcup T^{\#}(S^{\#}(g), skip)
S^{\#}(c) = T^{\#}(S^{\#}(b), [\neg (i < 10)])
S^{\#}(d) = T^{\#}(S^{\#}(b), [i < 10])
S^{\#}(e) = T^{\#}(S^{\#}(d), [i > 1])
S^{\#}(f) = T^{\#}(S^{\#}(d), [\neg (i > 1)])
S^{\#}(g) = T^{\#}(S^{\#}(e), i = i + 3)
\qquad \sqcup T^{\#}(S^{\#}(f), i = i + 2)
```

- ▶  $S_1 \sqcup S_2$  denotes the approximation of  $S_1 \cup S_2$ : it is the set that contains both  $S_1$  and  $S_2$ , that belongs to D, and is otherwise as small as possible. Here  $[a,b] \sqcup [c,d] = [min(a,c), max(b,d)]$
- ▶ We use approximate functions  $T^{\#}(S,c)$  that give a result in D.

#### **Updating Sets**

We solve the equations by starting in the initial state and repeatedly applying them.

ightharpoonup in the 'entry' point, we put  $\top$ , in all others we put  $\bot$ .

```
S^{\#}(a) = \top
S^{\#}(b) = T^{\#}(S^{\#}(a), i = 0)
         \sqcup T^{\#}(S^{\#}(g), skip)
S^{\#}(c) = T^{\#}(S^{\#}(b), [\neg(i < 10)])
S^{\#}(d) = T^{\#}(S^{\#}(b), [i < 10])
S^{\#}(e) = T^{\#}(S^{\#}(d), [i > 1])
S^{\#}(f) = T^{\#}(S^{\#}(d), [\neg(i > 1)])
S^{\#}(g) = T^{\#}(S^{\#}(e), i = i + 3)
          \sqcup T^{\#}(S^{\#}(f), i = i + 2)
```

# **Updating Sets**

Sets after a few iterations:

```
S^{\#}(a) = \top
S^{\#}(b) = T^{\#}(S^{\#}(a), i = 0)
         \sqcup T^{\#}(S^{\#}(g), skip)
S^{\#}(c) = T^{\#}(S^{\#}(b), [\neg(i < 10)])
S^{\#}(d) = T^{\#}(S^{\#}(b), [i < 10])
                                                               [i ≥ 2]
S^{\#}(e) = T^{\#}(S^{\#}(d), [i > 1])
S^{\#}(f) = T^{\#}(S^{\#}(d), [\neg(i > 1)])
S^{\#}(g) = T^{\#}(S^{\#}(e), i = i + 3)
         \Box T^{\#}(S^{\#}(f), i = i + 2)
                                                            i = i + 3
```

## **Updating Sets**

Sets after a few more iterations:

```
S^{\#}(a) = \top
S^{\#}(b) = T^{\#}(S^{\#}(a), i = 0)
         \sqcup T^{\#}(S^{\#}(g), skip)
S^{\#}(c) = T^{\#}(S^{\#}(b), [\neg(i < 10)])
S^{\#}(d) = T^{\#}(S^{\#}(b), [i < 10])
S^{\#}(e) = T^{\#}(S^{\#}(d), [i > 1])
S^{\#}(f) = T^{\#}(S^{\#}(d), [\neg(i > 1)])
S^{\#}(g) = T^{\#}(S^{\#}(e), i = i + 3)
         \Box T^{\#}(S^{\#}(f), i = i + 2)
```

# Fixpoint Found

Final values of sets:

```
S^{\#}(a) = \top
S^{\#}(b) = T^{\#}(S^{\#}(a), i = 0)
          \sqcup T^{\#}(S^{\#}(g), skip)
S^{\#}(c) = T^{\#}(S^{\#}(b), [\neg(i < 10)])
S^{\#}(d) = T^{\#}(S^{\#}(b), [i < 10])
S^{\#}(e) = T^{\#}(S^{\#}(d), [i > 1])
S^{\#}(f) = T^{\#}(S^{\#}(d), [\neg(i > 1)])
S^{\#}(g) = T^{\#}(S^{\#}(e), i = i + 3)
          \sqcup T^{\#}(S^{\#}(f), i = i + 2)
```

If we map intervals to sets, this is also solution of the original constraints.

# Automatically Constructed Hoare Logic Proof

Final values of sets:

```
//a: true
i = 0:
     //b: 0 < i < 12
while (i < 10) {
                                                           [0, 12]
  //d: 0 < i < 9
  if (i > 1)
    //e: 2 < i < 9
    i = i + 3:
  else
    //f: 0 \le i \le 1
    i = i + 2:
  //g: 2 < i < 12
//c: 10 < i < 12
```

This method constructed a sufficiently annotated program and ensured that all Hoare triples that were constructed hold

# Proving through Fixpoints of Approximate Functions

Meaning of a program (e.g. a relation) is a least fixpoint of F.

Given specification s, the goal is to prove  $\mathbf{lfp}(\mathbf{F}) \subseteq \mathbf{s}$ 

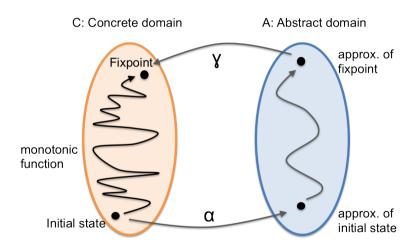
- ▶ if  $F(s) \subseteq s$  then  $Ifp(F) \subseteq s$  and we are done
- ▶  $lfp(F) = \bigcup_{k \ge 0} F^k(\emptyset)$ , but that is too hard to compute because it is infinite union unless, by some luck,  $F^{n+1}(\emptyset) = F^n$  for some n

Instead, we search for an inductive strengthening of s: find s' such that:

- ▶  $F(s') \subseteq s'$  (s' is inductive). If so, theorem says  $lfp(F) \subseteq s'$ ▶  $s' \subseteq s$  (s' implies the desired specification). Then  $lfp(F) \subseteq s' \subseteq s$
- How to find s'? Iterating F is hard, so we try some simpler function  $F_{\#}$ :
- ▶ suppose  $F_{\#}$  is approximation:  $F(r) \subseteq F_{\#}(r)$  for all r
  - ightharpoonup we can find s' such that:  $F_\#(s')\subseteq s'$  (e.g.  $s'=F_\#^{n+1}(\emptyset)=F_\#^n(\emptyset)$ )

Then:  $F(s') \subseteq F_{\#}(s') \subseteq s'$ . So, if  $s' \subseteq s$ , we have know  $lfp(F) \subseteq s'$ . Abstract interpretation: automatically construct  $F_{\#}$  using F and s

## Abstract Interpretation Big Picture



#### Abstract Domains are Partial Orders

Program semantics is given by certain sets (e.g. sets of reachable states).

- ▶ subset relation ⊆: used to compare sets
- union of states: used to combine sets coming from different executions (e.g. if statement)

Our goal is to approximate such sets. We introduce a domain of elements  $d \in D$  where each d represents a set.

- $ightharpoonup \gamma(d)$  is a set of states.  $\gamma$  is called **concretization function**
- ightharpoonup given  $d_1$  and  $d_2$ , it could happen that there is **no element** d representing union

$$\gamma(d_1) \cup \gamma(d_2) = \gamma(d)$$

Instead, we use a set d that approximates union, and denote it  $d_1 \sqcup d_2$ . This leads us to review the theory of **partial orders** and **(semi)lattices**.

#### Partial Orders

**Partial ordering relation** is a binary relation  $\leq$  that is reflexive, antisymmetric, and transitive, that is, the following properties hold for all x, y, z:

- $ightharpoonup x \le x$  (reflexivity)
- $ightharpoonup x \le y \land y \le x \rightarrow x = y$  (antisymmetry)
- ▶  $x \le y \land y \le z \rightarrow x \le z$  (transitivity)

If A is a set and  $\leq$  a binary relation on A, we call the pair  $(A, \leq)$  a **partial order**.

Given a partial ordering relation  $\leq$ , the corresponding **strict ordering relation** x < y is defined by  $x \leq y \land x \neq y$  and can be viewed as a shorthand for this conjunction.

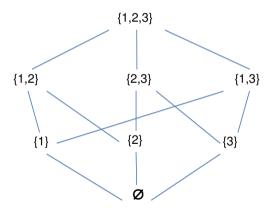
- Orders on integers, rationals, reals are all special cases of partial orders called linear orders.
- ▶ Given a set U, let A be any set of subsets of U, that is  $A \subseteq 2^U$ . Then  $(A, \subseteq)$  is a partial order.

**Example:** Let  $U = \{1, 2, 3\}$  and let  $A = \{\emptyset, \{1\}, \{2\}, \{3\}, \{2, 3\}, \{1, 2, 3\}\}$ . Then  $(A, \subseteq)$  is a partial order. We can draw it as a *Hasse diagram*.

### Hasse diagram

presents the relation as a directed graph in a plane, such that

- ▶ the direction of edge is given by which nodes is drawn above
- transitive and reflexive edges are not represented (they can be derived)



#### Extreme Elements in Partial Orders

Given a partial order  $(A, \leq)$  and a set  $S \subseteq A$ , we call an element  $a \in A$ 

- **• upper bound** of *S* if for all  $a' \in S$  we have  $a' \leq a$
- **lower bound** of S if for all  $a' \in S$  we have  $a \leq a'$
- **minimal element** of S if  $a \in S$  and there is no element  $a' \in S$  such that a' < a
- **maximal element** of S if  $a \in S$  and there is no element  $a' \in S$  such that a < a'
- **preatest element** of S if  $a \in S$  and for all  $a' \in S$  we have  $a' \leq a$
- ▶ **least element** of *S* if  $a \in S$  and for all  $a' \in S$  we have a < a'
- ▶ least upper bound (lub, supremum, join,  $\sqcup$ ) of S if a is the least element in the set of all upper bounds of S
- **greatest lower bound** (glb, infimum, meet,  $\sqcap$ ) of S if a is the greatest element in the set of all lower bounds of S

Taking S = A we obtain minimal, maximal, greatest, least elements for the entire partial order.

#### Extreme Elements in Partial Orders

#### Notes

- minimal element need not exist: (0,1) interval of rationals
- ▶ there may be multiple minimal elements:  $\{\{a\}, \{b\}, \{a, b\}\}$
- ▶ if minimal element exists, it need not be least: above example
- there are no two distinct least elements for the same set
- least element is always glb and minimal
- if glb belongs to the set, then it is always least and minimal
- on a family of relations closed under ∩ and ∪, glb is ∩ and lub is ∪ for the partial order ⊆; not all families of sets are closed; these are:
  - the set of all subsets
  - the family of open sets from topology

Least upper bound (lub, supremum, join,  $\sqcup$ )

Denoted lub(S), least upper bound of S is an element M, if it exists, such that M is the least element of the set

$$U = \{x \mid x \text{ is upper bound on } S\}$$

In other words:

- M is an upper bound on S
- ▶ for every other upper bound M' on S, we have that  $M \leq M'$

Note: this is the same definition as supremum in real analysis.

# Least upper bound (glb, infimum, meet, $\sqcap$ )

$$a_1 \sqcup a_2$$
 denotes  $lub(\{a_1, a_2\})$ 

$$(\ldots(a_1\sqcup a_2)\ldots)\sqcup a_n$$
 is in fact  $lub(\{a_1,\ldots,a_n\})$ 

So the operation is

- associative
- commutative
- idempotent

## Real Analysis

Take as S the open interval of reals  $(0,1) = \{x \mid 0 < x < 1\}$ Then

- S has no maximal element
- > S thus has no greatest element
- $\triangleright$  2, 2.5, 3,... are all upper bounds on S
- ightharpoonup lub(S) = 1

Execise: subsets of U

Consider

$$A = 2^U = \{S \mid S \subseteq U\}$$
 and  $(A, \subseteq)$ 

Do these exist, and if so, what are they?

$$lub(S) = ?$$

# Partial order for the domain of intervals

**Domain:**  $D = \{\bot\} \cup \{(L, U) \mid L \in \{-\infty\} \cup \mathbb{Z}, U \in \{+\infty\} \cup \mathbb{Z}\}$ such that L < U.

The associated set of elements is given by the function  $\gamma$ :

$$\gamma: D \to 2^{\mathbb{Z}}, \qquad \gamma((L, U)) = \{x \mid L \le x \land x \le U\}$$

$$\gamma:D o 2^{\mathbb{Z}}, \qquad \gamma((L,U))=\{x\mid L\leq x\wedge x\leq U\}$$
  
**Lub:** for  $d_1,d_2\in D,\ d_1\sqsubseteq d_2\quad \leftrightarrow\quad \gamma(d_1)\subseteq \gamma(d_2)$ 

hence 
$$(L_1,U_1)\sqsubseteq (L_2,U_2) \quad \leftrightarrow \quad L_2 \leq L_1 \wedge U_1 \leq U_2 \\ \perp \sqsubseteq d \quad \forall d \in D$$
 
$$(L_1,U_1)\sqcup (L_2,U_2) = (\textit{min}(L_1,L_2),\textit{max}(U_1,U_2))$$

# Remark on constructing orders using inverse images

Suppose  $\gamma:D\to C$  where C is some collection of sets.

If we define relation  $\sqsubseteq$  by:

$$d_1 \sqsubseteq d_2 \iff \gamma(d_1) \subseteq \gamma(d_2)$$

then

- 1.  $\sqsubseteq$  is reflexive
- 2.  $\sqsubseteq$  is transitive
- 3.  $\sqsubseteq$  is antisymmetric if and only iff  $\gamma$  is injective

If  $\sqsubseteq$  is not antisymmetric then we can define equivalence relation

$$d_1 \sim d_2 \iff \gamma(d_1) = \gamma(d_2)$$

and then take D' to be equivalence classes of such new set.

Example: suppose we defined intervals as all possible pairs of integers (L, U). Then there would be many representations of the empty set, all those intervals where L > U.

#### Lattices

**Definition:** A lattice is a partial order in which every two-element set has a least upper bound and a greatest lower bound.

**Lemma:** In a lattice every non-empty finite set has a lub ( $\sqcup$ ) and glb ( $\sqcap$ ).

#### Lattices

**Definition:** A lattice is a partial order in which every two-element set has a least upper bound and a greatest lower bound.

**Lemma:** In a lattice every non-empty finite set has a lub ( $\Box$ ) and glb ( $\Box$ ).

#### **Proof:** is by induction!

Case where the set S has three elements x,y and z:

Let 
$$a = (x \sqcup y) \sqcup z$$
.

By definition of  $\sqcup$  we have  $z \sqsubseteq a$  and  $x \sqcup y \sqsubseteq a$ .

Then we have again by definition of  $\Box$ ,  $x \sqsubseteq x \sqcup y$  and  $y \sqsubseteq x \sqcup y$ . Thus by transitivity we have  $x \sqsubseteq a$  and  $y \sqsubseteq a$ .

Thus we have  $S \sqsubseteq a$  and a is an upper bound.

Now suppose that there exists a' such that  $S \sqsubseteq a'$ . We want  $a \sqsubseteq a'$  (a least upper bound):

We have  $x \sqsubseteq a'$  and  $y \sqsubseteq a'$ , thus  $x \sqcup y \sqsubseteq a'$ . But  $z \sqsubseteq a'$ , thus  $((x \sqcup y) \sqcup z) \sqsubseteq a'$ .

Thus a is the lub of our 3 elements set.

### **Examples of Lattices**

**Lemma:** Every linear order is a lattice.

**Example:** Every bounded subset of the set of real numbers has a lub. This is an axiom of real numbers, the way they are defined (or constructed from rationals).

- ▶ If a lattice has least and greatest element, then every finite set (including empty set) has a lub and glb.
- ▶ This does not imply there are lub and glb for infinite sets.

**Example:** In the oder  $([0,1), \leq)$  with standard ordering on reals is a lattice, the entire set has no lub. The set of all rationals of interval [0,10] is a lattice, but the set  $\{x \mid 0 \leq x \land x^2 \leq 2\}$  has no lub.

#### **Exercises**

#### Prove the following:

- 1.  $(x \sqcup y) \sqcup z = x \sqcup (y \sqcup z)$
- 2.  $\Box A \Box \Box B \Leftrightarrow \forall x \in A. \forall y \in B. x \Box y$
- 3. Let  $(A, \sqsubseteq)$  be a partial order such that every set  $S \subseteq A$  has the greatest lower bound. Prove that then every set  $S \subseteq A$  has the least upper bound.

# Constructing Partial Orders using Maps

**Example:** Let A be the set of all propositional formulas containing only variables p, q. For a formula  $F \in A$  define

$$[F] = \{(u, v). \ u, v \in \{0, 1\} \land F \text{ is true for } p \mapsto u, q \mapsto v\}$$

i.e. [F] denotes the set of assignments for which F is true. Note that  $F \implies G$  is a tautology iff  $[F] \subseteq [G]$ . Define ordering on formulas A by

$$F \leq G \iff [F] \subseteq [G]$$

Is  $\leq$  a partial order? Which laws does  $\leq$  satisfy?

# Constructing Partial Orders using Maps

**Lemma:** Let  $(C, \leq)$  be an lattice and A a set. Let  $\gamma : A \to C$  be an injective function. Define oder  $x \sqsubseteq y$  on A by  $\gamma(x) \leq \gamma(y)$ . Then  $(A, \sqsubseteq)$  is a partial order.

**Note:** even if  $(C, \leq)$  had top and bottom element and was a lattice, the constructed order need not have top and bottom or be a lattice. For example, we take A to be a subset of A and define  $\gamma$  to be identity.

#### Lattices

**Definition:** A lattice is a partial order in which every two-element set has a least upper bound and a greatest lower bound (so, we have  $\Box$  and  $\Box$  as well-defined binary operations).

**Lemma:** In every lattice,  $x \sqcup (x \sqcap y) = x$ .

#### Lattices

**Definition:** A lattice is a partial order in which every two-element set has a least upper bound and a greatest lower bound (so, we have  $\sqcap$  and  $\sqcup$  as well-defined binary operations).

**Lemma:** In every lattice,  $x \sqcup (x \sqcap y) = x$ .

### **Proof:**

We trivially have  $x \sqsubseteq x \sqcup (x \sqcap y)$ .

Let's prove that  $x \sqcup (x \sqcap y) \sqsubseteq x$ :

x is an upper bound of x and  $x \sqcap y$ ,  $x \sqcup (x \sqcap y)$  is the least upper bound of x and  $x \sqcap y$ , thus  $x \sqcup (x \sqcap y) \sqsubseteq x$ .

**Definition:** A lattice is distributive iff

$$x \sqcap (y \sqcup z) = (x \sqcap y) \sqcup (x \sqcap z)$$
$$x \sqcup (y \sqcap z) = (x \sqcup y) \sqcap (x \sqcup z)$$

Lattice of all subsets of a set is distributive. Linear order is a distributive lattice.

### Products of Lattices

**Note:** for n=2 a function  $f:\{1,2\}\to (L_1\cup L_2)$  with  $f(1)\in L_1$ ,  $f(2)\in L_2$  is isomorphic to an ordered pair (f(1),f(2)). We denote the product by  $(L_1,\leq_1)\times (L_2,\leq_2)$ .

**Example:** Let  $R = \{a, b, c, d\}$  denote set of values. Let  $A_1 = A_2 = 2^R$ . Let

$$s_1 \leq_1 s_2 \iff s_1 \subseteq s_2$$

and let

$$t_1 \leq_2 t_2 \iff t_1 \supseteq t_2$$

Then we can define the product  $(A_1, \leq_1) \times (A_2, \leq_2)$ . In this product,  $(s_1, t_1) \leq (s_2, t_2)$  iff:  $s_1 \subseteq s_2$  and  $t_1 \supseteq t_2$ . The original partial orders were lattices, so the product is also a lattice. For example, we have

Tor example, we have

$$(\{a,b,c\},\{a,b,d\}) \sqcap (\{b,c,d\},\{c,d\}) = (\{b,c\},\{a,b,c,d\})$$

### **Products of Lattices**

Lattice elements can be combined into finite or infinite-dimensional vectors, and the result is again a lattice.

**Lemma:** Let  $(A_1, \leq_1), \ldots, (A_n, \leq_n)$  be partial orders. Define  $(L, \leq)$  by

$$A = \{f \mid f : \{1, \dots, n\} \rightarrow (A_1 \cup \dots \cup A_n) \text{ where } \forall i.f(i) \in A_i\}$$

For  $f, g \in A$  define

$$f \leq g \iff \forall i.f(i) \leq_i g(i)$$

Then  $(A, \leq)$  is a partial order. We denote  $(A, \leq)$  by

$$\prod_{i=1}^{n} (L_i, \leq_i)$$

Moreover, if for each i,  $(A_i, \leq_i)$  is a lattice, then  $(A, \leq)$  is also a lattice.

### Properties of $\sqcap S$ and $\sqcup S$

Consider a partial order  $(A, \sqsubseteq)$ .

- ▶ Suppose  $S_1 \subseteq S_2 \subseteq A$  and  $\sqcup S_1$  and  $\sqcup S_2$  exist. In what relationship are these two elements?
- ▶ Suppose  $S_1 \subseteq S_2 \subseteq A$  and  $\sqcap S_1$  and  $\sqcap S_2$  exist. In what relationship are these two elements?
- Suppose □∅ exists. Describe this element.
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- ▶ Suppose  $S_1 \subseteq S_2 \subseteq A$  and  $\sqcap S_1$  and  $\sqcap S_2$  exist. In what relationship are these two elements?
- ► Suppose ⊔∅ exists. Describe this element.
- ▶ Suppose  $\neg \emptyset$  exists. Describe this element.
- $\sqcup \emptyset = \bot$  and  $\square \emptyset = \top$ . This is because every element is an upper bound and a lower bound of  $\emptyset$
- :  $\forall x. \forall y \in \emptyset. y \sqsubseteq x$  is valid, as well as  $\forall x. \forall y \in \emptyset. y \supseteq x$ .

Complete Semilattice is a Complete Lattice

If we have all  $\square$ -s we then also have all  $\sqcup$ -s:

**Theorem:** Let  $(A, \sqsubseteq)$  be a partial order such that every set  $S \subseteq A$  has the greatest lower bound  $(\sqcap)$ . Prove that then every set  $S \subseteq A$  has the least upper bound  $(\sqcup)$ .

Example: Application of the Previous Theorem

Let U be a set and  $A \subseteq U \times U$  the set of all **equivalence relations** on this set. Consider the partial order  $(A, \subseteq)$ .

#### Lemma

If  $I \subseteq A$  is a set of equivalence relations, then  $\cap I$  is also an equivalence relation.

**Consequence:** Given  $I \subseteq A$  there exists the least equivalence relation containing every relation from I (equivalence closure of relations in I).

Note: **congruence** is equivalence relation that agrees with some operations. For example,  $x \sim x'$  and  $y \sim y'$  implies  $(x + y) \sim (x' + y')$ . The analogous properties hold for congruence relations.

| Com | plete | Lattice |
|-----|-------|---------|
| ••• |       |         |

**Definition:** A **complete** lattice is a lattice where for every set S (including empty set and infinite sets) there exist  $\Box S$  and  $\Box S$ .

### Monotonic functions

Given two partial orders  $(C, \leq)$  and  $(A, \sqsubseteq)$ , we call a function  $\alpha : C \to A$  monotonic iff for all  $x, y \in C$ ,  $x \leq y \to \alpha(x) \sqsubseteq \alpha(y)$ 

**Fixpoints** 

**Definition:** Given a set A and a function  $f: A \to A$  we say that  $x \in A$  is a fixed point (fixpoint) of f if f(x) = x.

**Definition:** Let  $(A, \leq)$  be a partial order, let  $f: A \to A$  be a monotonic function on  $(A, \leq)$ , and let the set of its fixpoints be  $S = \{x \mid f(x) = x\}$ . If the least element of S exists, it is called the **least fixpoint**, if the greatest element of S exists, it is called the **greatest fixpoint**.

# **Fixpoints**

Let  $(A, \sqsubseteq)$  be a complete lattice and  $G : A \to A$  a monotonic function.

#### **Definition:**

Post =  $\{x \mid G(x) \sqsubseteq x\}$  - the set of *postfix points* of G (e.g.  $\top$  is a postfix point) Pre =  $\{x \mid x \sqsubseteq G(x)\}$  - the set of *prefix points* of G

Fix =  $\{x \mid G(x) = x\}$  - the set of *fixed points* of G.

Note that  $Fix \subseteq Post$ .

# Tarski's fixed point theorem

**Theorem**: Let  $a = \sqcap \mathsf{Post}$ . Then a is the least element of Fix (dually,  $\sqcup \mathsf{Pre}$  is the largest element of Fix).

#### **Proof:**

Let x range over elements of Post.

- ▶ applying monotonic G from  $a \sqsubseteq x$  we get  $G(a) \sqsubseteq G(x) \sqsubseteq x$
- ightharpoonup so G(a) is a lower bound on Post, but a is the greatest lower bound, so  $G(a) \sqsubseteq a$
- ▶ therefore  $a \in Post$
- ▶ Post is closed under G, by monotonicity, so  $G(a) \in Post$
- ▶ a is a lower bound on Post, so  $a \sqsubseteq G(a)$
- ▶ from  $a \sqsubseteq G(a)$  and  $G(a) \sqsubseteq a$  we have a = G(a), so  $a \in Fix$
- ▶ a is a lower bound on Post so it is also a lower bound on a smaller set Fix

In fact, the set of all fixpoints Fix is a lattice itself.

## Tarski's fixed point theorem

Tarski's Fixed Point theorem shows that in a complete lattice with a monotonic function G on this lattice, there is at least one fixed point of G, namely the least fixed point  $\sqcap \mathsf{Post}$ .

- ► Tarski's theorem guarantees fixpoints in complete lattices, but the above proof does not say how to find them.
- How difficult it is to find fixpoints depends on the structure of the lattice.

Let G be a monotonic function on a lattice. Let  $a_0 = \bot$  and  $a_{n+1} = G(a_n)$ . We obtain a sequence  $\bot \sqsubseteq G(\bot) \sqsubseteq G^2(\bot) \sqsubseteq \cdots$ . Let  $a_* = \bigsqcup_{n>0} a_n$ .

**Lemma:** The value  $a_*$  is a prefix point.

Observation:  $a_*$  need not be a fixpoint (e.g. on lattice [0,1] of real numbers).

Omega continuity

**Definition:** A function G is  $\omega$ -continuous if for every chain  $x_0 \sqsubseteq x_1 \sqsubseteq \ldots \sqsubseteq x_n \sqsubseteq \ldots$  we have

$$G(\bigsqcup_{i>0} x_i) = \bigsqcup_{i>0} G(x_i)$$

**Lemma:** For an  $\omega$ -continuous function G, the value  $a_* = \bigsqcup_{n \geq 0} G^n(\bot)$  is the least fixpoint of G.

## Iterating sequences and omega continuity

**Lemma:** For an  $\omega$ -continuous function G, the value  $a_* = \bigsqcup_{n \geq 0} G^n(\bot)$  is the least fixpoint of G.

#### **Proof:**

- ▶ By definition of ω-continuous we have  $G(\bigsqcup_{n\geq 0} G^n(\bot)) = \bigsqcup_{n\geq 0} G^{n+1}(\bot) = \bigsqcup_{n\geq 1} G^n(\bot)$ .
- ▶ But  $\bigsqcup_{n\geq 0} G^n(\bot) = \bigsqcup_{n\geq 1} G^n(\bot) \sqcup \bot = \bigsqcup_{n\geq 1} G^n(\bot)$  because  $\bot$  is the least element of the lattice.
- ▶ Thus  $G(\bigsqcup_{n>0} G^n(\bot)) = \bigsqcup_{n>0} G^n(\bot)$  and  $a_*$  is a fixpoint.

Now let's prove it is the least. Let c be such that G(c) = c. We want  $\bigsqcup_{n \geq 0} G^n(\bot) \sqsubseteq c$ . This is equivalent to  $\forall n \in \mathbb{N}$ .  $G^n(\bot) \sqsubseteq c$ .

We can prove this by induction :  $\bot \sqsubseteq c$  and if  $G^n(\bot) \sqsubseteq c$ , then by monotonicity of G and by definition of c we have  $G^{n+1}(\bot) \sqsubseteq G(c) \sqsubseteq c$ .

Iterating sequences and omega continuity

**Lemma:** For an  $\omega$ -continuous function G, the value  $a_* = \bigsqcup_{n \geq 0} G^n(\bot)$  is the least fixpoint of G.

When the function is not  $\omega$ -continuous, then we obtain  $a_*$  as above (we jump over a discontinuity) and then continue iterating. We then take the limit of such sequence, and the limit of limits etc., ultimately we obtain the fixpoint.