# **CS3223** AY22/23 SEM 2

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- 1.  $k^*$  is an actual **data record** (with search key k)
- 2. k\* is of the form (k. RID) fixed length (k. •)
- 3. k\* is of the form (k, RID-list) e.g. (k, {RID11, RID12})

Notation	Meaning
r	relational algebra expression
	number of tuples in output of r
r	number of pages in output of r
b <sub>d</sub>	number of data records that can fit on a page
bi	number of data entries that can fit on a page
F	average fanout of B <sup>+</sup> -tree index (i.e., number of pointers to child nodes)
h	height of B+-tree index (i.e., number of levels of internal nodes)
	$h = \lceil \log_F(\lceil \frac{  R  }{b_i} \rceil) \rceil$ if format-2 index on table $R$
В	number of available buffer pages

# 04.1 Sorting and Selection

# External Merge Sort

- sorted run → sorted data records written to a file on disk
- · divide and conquer
  - 1. create temporary file  $R_i$  for each B pages of R sorted 2. merge: use B-1 pages for input, 1 page for output
- total I/O =  $2N(\lceil \log_{B-1}(N_0) \rceil + 1)$ 
  - 2N to create  $\lceil N/B \rceil$  sorted runs of B pages each
  - merging sorted runs:  $2N imes \lceil \log_{B-1} N_0 \rceil$

# optimisation with blocked I/O

- sequential I/O read/write in buffer blocks of b pages
- one block (b pages) for output, remaining blocks for input
- number of runs merged per pass, \*  $F = \lfloor \frac{B}{L} \rfloor 1$
- number of passes =  $\lceil \log_F(N_0) \rceil + 1$

# Sorting with B+-trees

- when sort key is a prefix of the index key of the B+-tree
- sequentially scan leaf pages of B<sup>+</sup>-tree
- · for Format-2/3, use RID to retrieve data records

# 04.2 SELECTION: $\sigma_p(R)$

- $\sigma_n(R)$ : selects rows from relation R satisfying predicate p
- access path: a way of accessing data records/entries
  - table scan 
    → scan all data pages
  - index scan
     ⇒ scan index pages
  - index intersection → combine results from index scans
- selectivity of an access path → number of index & data pages retrieved to access data records/entries
  - · more selective = fewer pages retrieved
- index I is a **covering index** for query  $Q \rightarrow$  if all attributes referenced in Qare part of the key of I
- Q can be evaluated using I without any RID lookup (index-only plan)

### Matching Predicates

- term  $\rightarrow$  of form R.A op c or  $R.A_i$  op  $R.A_i$
- conjunct → one or more terms connected by ∨
- CNF predicate → comprises one or more conjuncts connected by ∧

# B<sup>+</sup>-tree matching predicates

- for index  $I=(K_1,K_2,\ldots,K_n)$  and non-disjunctive CNF predicate p· at most one non-equality comparison operator which must be on the last attribute of the prefix  $(K_i)$
- matching index: matching records are in contiguous pages
- non-matching index: not contiguous ⇒ less efficient

## Hash index matching predicates

- for hash index  $I = (K_1, K_2, \dots, K_n)$  and non-disjunctive CNF predicate p, all attributes must be present and all ops must be equality. Primary/Covered Conjuncts
- primary conjuncts 
  → subset of conjuncts that I matches
- e.g.  $p = (age \ge 18) \land (age \le 20) \land (weight=65)$
- for I = (age, weight, height)
- covered conjuncts 
   → subset of conjuncts covered by I
  - each attribute in covered conjuncts appears in key of I
- primary conjuncts ⊂ covered conjuncts

## Cost of Evaluation

let p' = primary conjuncts of p,  $p_c$  = covered conjuncts of p

## B<sup>+</sup>-tree index evaluation of p

1. navigate internal nodes to find first leaf page

$$\operatorname{cost}_{\mathsf{internal}} = \begin{cases} \lceil \log_F(\lceil \frac{||R||}{bd} \rceil) \rceil & \text{if I is a format-1 index} \\ \lceil \log_F(\lceil \frac{||R||}{bd} \rceil) \rceil & \text{otherwise} \end{cases}$$

2. scan leaf pages to access all qualifying data entries

2. Scan lear pages to access an qualifying data entiries 
$$\cosh_{\text{leaf}} = \begin{cases} \lceil \frac{|\sigma_{p'}(R)|}{b_{b}} \rceil & \text{if I is a format-1 index} \\ \lceil \frac{|\sigma_{p'}(R)|}{b_{b}} \rceil & \text{otherwise} \end{cases}$$
 3. retrieve qualified data records via RID lookups

$$\begin{aligned} & \operatorname{cost}_{\mathsf{RID}} = \begin{cases} 0 & \text{if I is a covering format-1 index,} \\ & ||\sigma_{p_{c}}(R)|| & \text{otherwise} \end{cases} \\ & \cdot \text{ reduce cost with } \mathbf{clustered} \text{ data records (sort RIDs):} \end{aligned}$$

 $\lceil \frac{||\sigma_{P_C}(R)||}{b_d} \rceil \leq \operatorname{cost}_{RID} \leq \min\{||\sigma_{P_C}(R)||, |R|\}$  hash index evaluation of p

- $\begin{array}{ll} \textbf{-format-1:} & \text{cost to retrieve data records} \geq \lceil \frac{||\sigma_{p'}(R)||}{b_d} \rceil \\ \textbf{-format-2:} & \text{cost to retrieve data entries} \geq \lceil \frac{||\sigma_{p'}(R)||}{b_i} \rceil \\ \text{cost to retrieve data records} = \begin{cases} 0 & \text{if I is a covering index,} \\ ||\sigma_{p'}(R)|| & \text{otherwise} \end{cases}$

# 05. PROJECTION $\pi_{A_1,...,A_m}(R)$ AND JOIN

•  $\pi_L(R)$  eliminates duplicates,  $\pi_L^*(R)$  preserves duplicates Sort-based approach cost analysis

- 1. extract attributes:  $|R| \operatorname{scan} + |\pi_L^*(R)|$  output temp result
- 2. sort records:  $2|\pi_L^*(R)|(\log_m(N_0)+1)$
- 3. remove duplicates:  $|\pi_L^*(R)|$  to scan records

### optimised sort-based approach

- if  $B > \sqrt{|\pi_L^*(R)|}$ , same I/O cost as hash-based approach
  - +  $N_0 = \lfloor \frac{|R|}{B} \rfloor pprox \sqrt{|\pi_L^*(R)|}$  initial sorted runs
  - $\log_{B-1}(N_0) \approx 1$  merge passes

# Hash-based approach

- 1. **partitioning phase**: hash each tuple  $t \in R$ 
  - $R = R_1 \cup R_2 \cup \cdots \cup R_{B-1}$ • for each  $R_i \& R_j$ ,  $i \neq j$ ,  $\pi_L^*(R_i) \cap \pi_L^*(R_j) = \emptyset$
  - for each t: project attributes to form t', hash h(t') to one output buffer, flush output buffer to disk when full
- one buffer for input, (B-1) buffers for output
- 2. duplicate elimination from each  $\pi_I^*(R_i)$ 
  - for each  $R_i$ : initialise in-mem hash table, hash each  $t \in R_i$  to bucket  $B_i$  with  $h' \neq h$ , insert if  $t \notin B_i$
  - write tuples in hash table to results
- I/O cost (no partition overflow):  $|R| + 2|\pi_L^*(R)|$ 
  - partitioning cost:  $|R| + |\pi_L^*(R)|$
  - duplicate elimination cost:  $|\tilde{\pi}_L^*(R)|$
- partition overflow: recursively apply partitioning + to avoid, B> size of hash table for  $R_i=\frac{|\pi_L^*(R)|}{B_1}\times f$ 
  - approximately  $B > \sqrt{f \times |\pi_L^*(R)|}$

## **Projection using Indexes**

- if index search key contains all wanted attributes as a prefix
- · index scan data entries in order & eliminate duplicates 05.2 JOIN  $R\bowtie_{ heta} S$

R = outer relation (smaller relation); S = inner relation

! for format-2 index, add cost of retrieving record

## nested loop joins

- tuple-based nested loop join:  $|R| + |R|| \times |S|$
- page-based nested loop join:  $|R| + |R| \times |S|$
- block nested loop join:  $|R| + (\lceil \frac{|R|}{B-2} \rceil \times |S|), \quad |R| \leq |S|$ 
  - 1 page output, 1 page input, (B-2) pages to read R
  - for each (B-2) pages of R: for each  $P_S$  of S: check r,s
- · index nested loop join:

$$|R| + ||R|| \times \left(\log_F(\lceil\frac{||S||}{b_d}\rceil) + \lceil\frac{||S||}{b_d||\pi_{B_j}(S)||}\rceil\right)$$

- joining  $R(A,B)\bowtie_A S(A,C)$  with B+tree index on S.A
- for each tuple  $r \in R$ , use r to probe S's index for match

- sort R & S:  $2|R|(\log_m(N_R)+1)+2|S|(\log_m(N_S)+1)$
- merge cost: |R| + |S| (worst case  $|R| + |R| \times |S|$ )

# optimised sort-merge join

- merge sorted runs until B > N(R, i) + N(S, j); then do merge and join at the same time
- I/O cost:  $3 \times (|R| + |S|)$ 
  - if  $B > \sqrt{2|S|}$ , one pass to merge initial sorted runs
  - 2(|R| + |S|) for initial sorted runs, |R| + |S| for merging
- 1. partition R and S into k partitions on join column •  $\pi_A(R_i) \cap \pi_B(S_i) = \emptyset \quad \forall R_i, S_i, i \neq j$

- $R = R_1 \cup R_2 \cup \cdots \cup R_k$ ,  $t \in R_i \iff h(t.A) = i$ •  $S = S_1 \cup S_2 \cup \cdots \cup S_k$ ,  $t \in S_i \iff h(t.B) = i$
- 2. join corresponding partitions:  $R\bowtie_{R.A=S.B} S = (R_1\bowtie S_1)\cup\cdots\cup(R_k\bowtie S_k)$

## Grace hash join

for build relation R and probe relation S.

- 1. **partition** R and S into k partitions each, k = B 1
- 2. **probing phase**: hash  $r \in R_i$  with h'(r.A) to table T
- 2.1.  $\forall s \in S_i, r \in \text{bucket } h'(s.B)$ : output (r, s) if match
- I/O cost: 3(|R| + |S|) (no partition overflow)
- $B > \frac{f \times |R|}{B-1} + 2$  (input & output buffer)  $\approx B > \sqrt{f \times |R|}$ 
  - during probing, B > size of each partition +2
- partition overflow if R<sub>i</sub> cannot fit in memory
- · recursively apply partitioning to overflow partition

# General join conditions

- multiple equality-join conditions:  $(R.A = S.A) \land (R.B = S.B)$ 
  - index nested loop join: use index on some/all join attribs
  - · sort-merge join; sort on combination of attributes
- · other algos: no change • inequality-join conditions: (R.A < S.A)
- index nested loop join: requires B<sup>+</sup>-tree index
- not applicable: sort-merge join (too much rewinding), hash-based joins
- · other algos: no change

# 06. Query Evaluation & Optimization

- · Set operations can be implemented with joins and sort/hash
  - $R(A,B)\cap S(A,B)=\pi_{R.A,R.B}R\bowtie_p S$  where p = (R.A = S.A)  $\wedge$  (R.B = S.B)
- Sorting for  $R \cup S$
- · Sort R and S using all attributes. Merge the sorted operands.
- Hashing for  $R \cup S$
- · Same as grace hash join, k partitions, when probing, discard if in, else add. Write to disk.
- · Aggregation: maintain running info while scanning table.
- Use index scan on covering index whenever possible. · Group by: Partition by grp attr and run normal aggregation.

# Materialized evaluation

- · Evaluate operator only when all operands are evaluated or materialized.
- · Intermediate results are written to disk which can be costly.

# Pipelined evaluation

- Execution of operators is interleaved. Pipelining may not always be
- Temporary relations are not stored on disk. · Output produced by operator is passed directly to parent.
- . Blocking operator O cannot start until all receive all input tuples from children operators
- · Examples are external merge sort, smi, grace hash.
- · Use partial materialization cheaper to read from temp output relation (due to very selective p)
- · Iterator interface.
  - open: initialize iterator state: resources, args.

  - · getNext: gen next tuple, return null when done · close: Deallocate state information
- · A SQL query has many equiv logical plans, which have many equiv physical
- Query optimization is about avoiding the worst plans, not picking the best
- · Relational Algebra Equiv rules
- 1. Commutativity of binary ops
  - 1.1.  $R \times S \equiv S \times R$
  - 1.2.  $R \bowtie S \equiv S \bowtie R$
- 2. Associativity of binary ops 2.1.  $(R \times S) \times T \equiv R \times (S \times T)$
- 2.2.  $(R \bowtie S) \bowtie T \equiv R \bowtie (S \bowtie T)$ 3. Idempotence of unary op
- 3.1.  $\pi_{L'}(\pi_L(R)) \equiv \pi_{L'}(R)$  if  $L' \subseteq L \subseteq attr(R)$ 3.2.  $\sigma_{p1}^{L}(\sigma_{p2}(R)) \equiv \sigma_{p1 \wedge p2}^{L}(R)$ 4. Commutating selection with projection
  - 4.1.  $\pi_L(\sigma_p(R)) \equiv \pi_L(\sigma_p(\pi_{L\cup attr(p)}(R)))$
- 5. Commutating selection with binary ops 5.1.  $\sigma_p(R \times S) \equiv \sigma_p(R) \times S$ 
  - 5.2.  $\sigma_p(R \bowtie_{n'} S) \equiv \sigma_p(R) \bowtie_{n'} S$
  - 5.3. assuming  $attr(p) \subseteq attr(R)$
- 5.4.  $\sigma_p(R \cup S) \equiv \sigma_p(R) \cup \sigma_p(S)$ 6. Commutating proj with binary ops
- Let  $L = L_R \cup L_S$  where  $L_R \subseteq attr(R), L_S \subseteq attr(S)$ 6.1.  $\pi_L(R \times S) \equiv \pi_{L_R}(R) \times \pi_{L_S}(S)$
- 6.2.  $\pi_L(R\bowtie_p S) \equiv \pi_{L_R}^{L_R}(R)\bowtie_p \pi_{L_S}(S)$ if attr(p)  $\cap$  attr(R)  $\subseteq L_R$  and attr(p)  $\cap$  attr(S)  $\subseteq L_S$ 6.3.  $\pi_L(R \cup S) \equiv \pi_L(R) \cup \pi_L(S)$
- · Summary of RA optimization
- 1. Perform selection as early as possible, ideally before joins.

- 2. Replace Cartesian Product by join whenever possible
- 3. Project out useless attributes early
- 4. If there are several joins, perform most restrictive join first.
- · Types of Query Plan Trees
  - . A guery plan is linear if at least one operand for each join op is a base

- · DP algorithm for query enumeration: Calculate optimal plan for all single relations. Calculate optimal plan involving 2, 3 and so on relations by finding best way to join each smaller relation.
- - Uses  $dp(S_i,o_i)$  where  $o_i$  is null if unordered or a sequence of attrs
  - · May be cheaper if a SMJ is sorted on some sequence even if by itself is suboptimal.
- · Cost estimation
  - · Uniformity assumption: uniform distribution
  - Independence assumption: diff attrs are independent
  - Inclusion assumption: For  $R\bowtie_{R.A=S.B}S$ , if
- $\|\pi_A(R)\| \leq \|\pi_B(S)\| \text{ then } \pi_A(R) \subseteq \pi_B(S)$  Size estimation:  $\|q\| \approx \|e\| \times \prod_{i=1}^n rf(t_i)$
- Join selectivity:  $rf(R.A=S.B) = \frac{\|R \bowtie_{R.A=S.B}\|}{\|R\| \times \|S\|}$  Inclusion assumption: Assume that  $\|\pi_A(R)\| \le \|\pi_B(S)\|$  By uniformity assumption, every R-tuple joins with  $\frac{\|S\|}{\|\pi_B(S)\|}$
- :  $rf(R.A = S.B) \approx \frac{1}{\max(\|\pi_A(R)\|, \|\pi_B(S)\|)}$  Using histograms. Partition domain into sub-ranges (buckets) and assume

# MCV: Keep track of exact top-k common values and exclude from buckets.

- within each Xact is preserved • Serial Schedule = A schedule where the actions of Xacts are not interleaved
- We say that  $T_i$  reads 0 from  $T_i$  in a schedule S if the last write on 0 before
- We say that  $T_i$  reads  $T_i$  if  $T_i$  has read some object from  $T_i$
- on O is  $W_i(O)$ An interleaved Xact schedule is correct if it is "equivalent" to some serial
- Two schedules S and S' (over the same set of Xacts) are view equivalent
- denoted by  $S \equiv_v S'$  if they satisfy: 1. If  $T_i$  reads A from  $T_i$  in S, then  $T_i$  must also read A from  $T_i$  in S'

in S must also perform the final write on A in S'A schedule S is a view serializable schedule (VS) if S is view equivalent to

some serial schedule over the same set of Xacts. We can also construct a directed VSG(S) to capture read-from and final-write

- relations among Txn. Each node in VSG repr a Txn with the following edges 1.  $(T_i, T_i)$  if  $T_i$  reads from  $T_i$
- 2.  $(T_j, T_i)$  if both  $T_i$  and  $T_j$  update the same O and  $T_i$  does final write 3.  $(T_i, T_i)$  if  $T_i$  read O from initial db and  $T_i$  update O

equivalent to S. Two actions on the same O conflict if at least one is a W and both are from diff

- 1. Dirty read (due to WR conflicts)
  - $T_2$  reads O modified by  $T_1$  and  $T_1$  has not yet committed.
  - T<sub>2</sub> can see an inconsistent DB state
- 2. Unrepeatable read (due to RW conflicts) ullet  $T_2$  updates O that  $T_1$  reads and  $T_2$  commits while  $T_1$  is still in
- $R_1(x), W_2(x), Commit_2, R_1(x)$

- relation, else it is bushy
- · A linear plan is left-deep if every right operand is a base relation
- · A linear plan is right-deep if every left operand is a base relation
- · Query plan enumeration, assume that optimal sol to smaller set is optimal sol to larger set may not be true
- System R optimizer
- Enumerate only left-deep query plans. (too much to search o/w)
- · Avoid cross-product query plans.
- · Consider early selections and projections.

- $\begin{aligned} & \cdot \ rf(t_i) = \frac{\|\sigma_i(e)\|}{\|e\|}, \text{ reduction/selectivity factor} \\ & \cdot \ rf(R=c) = \frac{\|c\|}{\|R\|} \text{ uniformity assumption} \end{aligned}$
- uniform value distribution within each bucket. · Equiwidth: Each bucket has almost equal num values
- · Equidepth: Each bucket has almost equal num tuples, sub-range of adj buckets can overlap
- 07. Transaction
- · An active Xact is a Xact still in progress Schedule = A list of actions from a set of Xacts where the order of the actions
- $R_i(O)$  in S is  $W_i(O)$
- We say that  $T_i$  performs the final write on O in a schedule S if the last write

schedule over the set of Xacts

- 2. For each data object A, the Xact (if any) that performs the final write on A

If VSG(S) is cyclic, then S is not VSS. If VSG(S) is acylic, then S is VSS iff there exists a serial schedule produced from a topo ordering of VSG(S) that is view

- **Xacts** 
  - $W_1(x), R_2(x)$
- progress
- T<sub>1</sub> can get a different value if it reads O again
- 3. Lost update (due to WW conflicts)

- ullet  $T_2$  overwrites O that was modified by  $T_1$  while  $T_1$  is still in progress
- $R_1(x), R_2(x), W_1(x), W_2(x)$
- T<sub>1</sub> 's update is lost
- 4. Phantom read
  - · T re-executes a query on a predicate and gets a different set of results due to a recently committed T
- · Can be prevented by predicate locking: Grant T an S on p, another T' request for X on p is blocked. Also see index locking
- conflict equivalent denoted by  $S \equiv_{c} S'$  if they order every pair of conflicting actions of two committed Xacts in the same way.
- · conflict serializable schedule (CS) if it is conflict equivalent to a serial schedule over the same set of Xacts.
- Conflict serializability graph denoted as CSG(S) = (V, E) s.t
  - ullet V contains a node for each committed Xact in S
  - E contains  $T_i$ ,  $T_j$  if an action in  $T_i$  precedes and conflicts with one of T: 's action
- . Theorem: A schedule is CS iff its CSG is acyclic.
- Theorem:  $CSS \subseteq VSS \subseteq MVSS$ .
- Note: CS3223 uses serializable to mean CS
- A write on O by  $T_i$  is a **blind write** if  $T_i$  did not read O prior to the write
- . Theorem: If S is VS and S has no blind writes, then S is also CS.
- Cascading abort: For correctness, if  $T_i$  read from  $T_i$  then  $T_i$  must abort if  $T_{i}$  aborts. We say that  $T_{i}$ 's abort is cascaded to  $T_{i}$ .
- Recoverable schedule: For every Xact T that commits in S, T must commit after T' if T reads from T'.
- · Recoverable schedules guarantee that committed Xacts will not be aborted but cascading aborts of active Xacts are possible.
- Cascadeless schedule: If whenever  $T_i$  reads from  $T_i$  in S, Commit, must precede this read action.
- Theorem: A cascadeless schedule is recoverable.
- · Before-images: Log the before-images of writes to undo the aborted Xacts. See Chap 10. But this does not always work.
  - $W_1(A), W_2(A), \text{Abort}_1$ . Undoing  $W_1(A)$  is incorrect.
- Strict: For every  $W_i(O)$  in S, O is not read or written by another Xact until T<sub>i</sub> either aborts or commits.
- · Recovery using before-images is more efficient.
- · Concurrent executions are more restrictive.
- Theorem: Strict ⊆ Cascadeless ⊆ Recoverable.

## 08. Concurrency Control

Transaction Scheduler: For each input action (R, W, C, A) to the scheduler, either output action to S, postpone(block Xact) or reject (abort Xact)

Loc	k compa	tability	matri	x	
Lock		Lock Held			
Requested	- k	IS	IX	S	X
IS	- V	V	V	V	×
IX	V	V	V	×	×
S	V	1	×	V	×
. X	1/	×	×	×	×

# Lock-Based concurrency control

- 1. If lock request not granted, T becomes **blocked**, execution is suspended and T is added to O's request queue.
- 2. When a lock on O is released, lock manager checks request of first T in request queue for O. If can be granted, T acquires lock on O and resumes after popped from queue
- 3. When an Xact commits/aborts, all locks are released and T is removed from any request queue it's in.
- 4. S<sub>i</sub>(O): Xact T<sub>i</sub> requests S on O
- 5.  $X_i(O)$ : Xact  $T_i$  requests X on O
- 6.  $U_i(O)$ : Xact  $T_i$  releases lock on O
- Two Phase Locking (2PL) Protocol

# 1. To read O, T must hold S or X on O.

- 2 To write O T must hold X on O
- 3. Once T releases a lock, T cannot request anymore.
- 4. 2PL = growing and shrinking phase.
- 5. Theorem: 2PL S are CS.
- Strict 2PI

- · Same as 2PL points 1 and 2.
- . T must hold onto locks until T commits or aborts. . Theorem: Strict 2PL S are strict and CS.
- · Deadlock Detection: Waits-for graph (WFG)
- · Nodes represent active T.
- Add edge  $T_i \to T_j$  if  $T_i$  waiting for  $T_j$  to release lock.
- Remove edge when lock request is granted.
- · Deadlock detected if WFG has a cycle
- · Break deadlock by aborting a T in the cycle.
- · Alternative: timeout
- · Deadlock Prevention: Older T have higher priority than younger T
- . Each T is assigned to when started. Older T has a smaller to.
- Suppose  $T_i$  requests for a lock that conflicts with a lock held by  $T_i$

Prevention Policy	I <sub>i</sub> has higher priority	I <sub>i</sub> has lower priority
Wait-die	$T_i$ waits for $T_i$	T <sub>i</sub> aborts
Wound-wait	T <sub>j</sub> aborts	$T_i$ waits for $T_j$
	•	

· Wait-die policy

- · non-preemptive: only requesting T can be aborted
- · younger T may abort repeatedly
- · T that has all locks is never aborted
- Wound-wait policy is preemptive
- . To avoid starvation, a restarted T must use original timestamp

Lock Conversion Increases concurrency by allowing lock conversions, previously serial only schedules can become interleaved.

- $UG_i(A): T_i$  upgrades S on A to X.
  - · Blocked if another T is holding S on A.
  - Allowed if T<sub>i</sub> has not released any lock.
- DG<sub>i</sub>(A): T<sub>i</sub> downgrades X on A to S.
  - Allowed if  $T_i$  has not modified A and  $T_i$  has not released any lock.

## Lock-based Isolation levels

	Dirty	Unrepeatable	Phantom		Isolation	Write	Read	Predicate
Isolation Level	Read	Read	Read	Degree	level	Locks	Locks	Locking
READ UNCOMMITTED	possible	possible	possible	0	Read Uncommitted	long duration	none	none
READ COMMITTED	not possible	possible	possible	1	Read Committed	long duration	short duration	none
REPEATABLE READ	not possible	not possible	possible	2	Repeatable Read	long duration	long duration	none
SERIALIZABLE	not possible	not possible	not possible	3	Serializable	long duration	long duration	yes

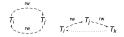
- Short duration lock acquired for an operation can be released after operation ends before T commits/abort
- · Long duration lock acquired for an operation is held until T commits/abort
- · Lock Granularity: Highest(coarsest) to lowest(finest): db, relation, page,
- If T holds M on D, T implicitly holds M on granules finer than D.
- Protocol: Before acquiring S/X on G, acquire IS/IX on granules coarser than G top-down. Release locks bottom-up.

## 09. MVCC

- $W_i(O_i)$  : create new version of O denoted by  $O_i$ .  $O_0$  is initial version
- $R_i(O_i)$ : read an appropriate version of O
- · Read-only T not blocked by update T and vice versa
- · Read-only T never aborted
- Multiversion view equivalent (MVE) denoted by  $S \equiv_{mv} S'$  if they have the same set of reads-from.
- $R_i(x_i)$  occurs in S iff  $R_i(x_i)$  also occurs in S'
- · Monoversion schedule: each read in S returns most recently created version. Also can be serial.
- · Multiversion view serializable s (MVSS): a S where there exists a serial monoversion S' that is MVE to S.
- To show not MVSS, suppose there exists a S' and show that there is a cycle in the precede graph.
- · MVCC Protocol: Snapshot Isolation (SI)
- Each T has two timestamps start(T) and commit(T)
- Each T sees a snapshot of DB that consists of updates by T' that committed before T starts
- . T and T' are concurrent if they overlap
- $O_i$  is a **newer version** compared to  $O_i$  if commit $(T_i) > \text{commit}(T_i)$
- If  $R_i(O)$  returns  $O_i$  then (either own update or latest version of O created by T that committed before T starts)
  - j = i if  $W_i(O)$  precedes  $R_i(O)$  OR
  - commit $(T_i) < \text{start}(T_i)$
  - For every  $T_k$ ,  $k \neq j$ , that has created a version  $O_k$  of O if  $\operatorname{commit}(T_k) < \operatorname{start}(T_i) \operatorname{thencommit}(T_k) < \operatorname{commit}(T_i)$
- Concurrent update property: If multiple concurrent T updated same O, only one T allowed to commit. If not, S may not be serializable.
- · First Committer Wins (FCW): Before committing T, if another committed concurrent T' that has updated some O that T has updated exists, abort T. Else commit T.
- · First Updater Wins (FUW): When T needs to update O, T requests for X. If X is not held by another concurrent T'
  - T is granted X on O. If O has been updated by any concurrent T", T aborts. Otherwise T proceeds.
- Else if X is held by some concurrent T', T waits until T' aborts or commits. • If T' aborts, then assume T is granted X on O. If O has been updated by any concurrent T", T aborts. Otherwise T proceeds.
  - · If T' commits, then T is aborted.
- · (FUW): When T commits/aborts, releases its X-lock(s).
- Garbage collection A version  $O_i$  may be deleted if there exists a newer version  $O_i$  commit $(T_i) < \text{commit}(T_i)$  s.t for every **active**  $T_k$  that started after  $T_i$  committed, we have commit $(T_i) < \text{start}(T_k)$
- SI has similar performance to Read Committed but SI does not suffer from lost update or unrepeatable reads.
- · But SI is vulnerable to non-serializable executions such as write-skew anomaly (left pic) and read-only txn anomaly (middle pic). Both pics are SI S that isnt MVSS
- · SI also does not guarantee serializability. The rightmost picture shows the DSG for both anomalies (S1 = write-skew, S2 = read-only)

- $R_1(y_0)$  $W_1(x_1)$ Commit  $DSG(S_1)$  $DSG(S_2)$
- · Serializable Snapshot Isolation (SSI): Guarantees serializable SI schedules.
- · Transactional dependencies •  $T_1 \xrightarrow[ww]{} T_2$ :  $T_1$  writes a version of x.  $T_2$  later writes **immediate** 
  - successor of x •  $T_1 \longrightarrow_{wr} T_2$ :  $T_1$  writes a version of x.  $T_2$  later reads this version of

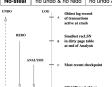
  - $T_1 \longrightarrow_{rw} T_2$ :  $T_1$  reads a version of x.  $T_2$  later writes **immediate** successor of x. •  $x_i$  is the **immediate successor** of  $x_i$  if  $T_i$  commits before  $T_i$  and no
- txn that commits between  $T_i$ 's and  $T_i$ 's commits produces x. · Maintain a Dependency Serializable Graph (DSG) to keep track of rw
- dependencies among concurrent T
- DSG(S) = (V, E), V = {T<sub>1</sub>, ..., T<sub>k</sub>} and E
- --→ concurrent txn
- → non-concurrent txn
- If there exists a  $T_i$  is involved in two rw concurrent dependencies, abort one of  $T_i, T_j, T_k$ .
- May result in unnecessary rollbacks due to false positives of SI anomalies.
- Theorem Non-MVSS SI Schedules: If S is a SI schedule that is not MVSS.
  - · There is at least one cycle in DSG(S), and
  - For each cycle in DSG(S), there exists three txns  $T_i, T_i, T_k$  where



# 10. Crash Recovery

- · Types of failure
  - Transaction failure: T aborts
  - · System crash: loss of volatile memory contents
  - Media failure: data is lost on non-volatile storage
- Recovery manager: Supports Commit. Abort and Restart (abort all losers. and install updates from committed T not written to disk)
- desiderata: little overhead and recover quickly
- · Steal policy: allow dirty pages updated by T to be replaced from buffer pool before T commits.
  - · No steal: poor throughput. Steal: how atomic?
- Force policy: force dirty pages updated by T to written to disk when T commits
  - · poor response time but provide durability

	Force	No-force
Steal	undo & no redo	undo & redo
No-steal	no undo & no redo	no undo & redo



- Log Sequential file of records in non-volatile/stable storage (multi copies) LSN: unique identifier, LSN of an earlier log record < later log record</li>
  - · type of log record (update, commit, abort)
  - identifier of Xact
  - · pageID: what page is modified
  - prevLSN: LSN of the previous log record for same Xact
- undoNextLSN: See CLR
- Update log record
  - · id of page being updated, byte offset within page indicating when updated portion start, length: number of byes for updated portion of page
  - · before-image and after-image of update
- Compensation Log Record (CLR)
  - · When an update (described by a log record) is undone, create a CLR. Track action taken to undo update.
  - undoNextLSN = LSN of next log record to be undone (this skips over the undone action in the LL)
- · Abort log record: When Xact is to be aborted, start undoing this Xact.
- · End log record: When the extra processing for aborted/committed Xact is · Checkpoint log record: See checkpointing
- Transaction Table (TT)
- One entry for each active Txn which contains

- · lastLSN: LSN of most recent log record for this Xact
- Xact status (C = committed or U = has not committed)
- . One entry for each dirty page in buffer pool which contains

  - · recLSN: LSN of the earliest log record for an update that dirtied page
- describes update to the page. Before flushing db page p to disk, ensure that
- Force-at-commit protocol
- storage (db or log). Enforced by writing a commit log record r for Xact and
- An Xact is considered committed if its commit log is written to stable storage
- · Stop accepting any new update, commit and abort ops.

- · Analysis phase finds latest checkpoint log and resumes from there, init Xact to checkpoint and DPT to empty.
- · Write end checkpoint log record (ECPLR) containing current DPT and TT.
- · We assume there are no log records between BCPLR and ECPLR.

# **ARIES: Analysis**

- 2. Retrieve end checkpoint log record (ECPLR) corresponding to BCPLR
- 4. Scan log record in forward direction to process each record r

- · Add an entry in TT for T if T is not in TT

- Create entry for P in DPT with pageID = P's pageID, recLSN = r's LSN
- 2. Let r be the log record with LSN = RedoLSN

  - · Reapply logged action in r to P
- Update P's entry in DPT: recLSN = P's pageLSN + 1 5. At the end of Redo Phase, 1) Create end log records for Xacts with status = C in TT and remove them from TT. 2) System is restored to state
- at time of crash. (Still have losers)
- 1. Abort losers (active Xacts at time of crash) by undoing action in reverse
- 2. Initialize L = set of lastLSNs (with status = U) from TT
- 3. Repeat until L becomes empty
  - - i. Create a CLR  $r_2$  for T:  $r_2$ 's undoNextLSN = r's prevLSN and
    - ii. Update T's entry in TT: lastLSN =  $r_2$ 's LSN

  - 3.4. else if r is a CLR for T then
    - i. Update L and TT(r's undoNextLSN)
  - 3.6. **def** Update L and TT(Isn)

- · Do not commit a Xact until after-images of all its updated records are in stable
- · Simple checkpointing

- · Resume accepting new update, commit and abort.
- · Fuzzy checkpointing: Used by ARIES in analysis start up.
- 1. Retrieve begin checkpoint log record (BCPLR) identified by master record
- · We assume there are no log records between BCPLR and ECPLR
- · Remove T from TT
- · Update lastLSN of entry T to be r's LSN
- 7. If (r is a redoable log record for page P) and (P is not in DPT) then

- 4. If (r is a redoable (update or CLR) log record) and (condition C is false)

  - update P's pageLSN = r's LSN
- 6. Condition C: (P is not in DPT) or (P's recLSN in DPT > r's LSN)

- 3.2. Let r be the corresponding log record
  - prevLSN = T's lastLSN in TT
  - iii. Undo logged action on page P (WAL principle)

- · Uncommitted update to db not flushed til log with before-image is flushed.
- all log r' up to log r corresponding to p's pageLSN has been flushed.

- · Wait till all active update, commit and abort ops are done.
- Write a checkpoint log record containing Xact table.

- 3. Initialize DPT and TT using ECPLR's contents
- 6 Fise
- 8. At the end of Analysis, 1) TT = list of all active Txn at time of crash, 2) DPT
- 1. Set RedoLSN = smallest recLSN among all dirty pages in DPT
- 3. Scan the log in forward dir starting from r
  - If (P's pageLSN < r's LSN) then

- 3.1. Delete largest lastLSN from L
- iv. update P's pageLSN =  $r_2$ 's LSN
- 3.5. else if r is an **abort log record** 
  - i. if Isn is not null then add Isn to L
  - ii. else create an end log record for T and remove T from TT

- · Dirty Page Table (DPT)
- · pageID: page ID of dirty page
- · Write-ahead logging (WAL) protocol
- · Each db page contains LSN of most recent log record (pageLSN) that

- flushing all log records (up to and including r) for Xact to disk.

- · Flush all dirty pages in buffer
- Write begin checkpoint log record (BCPLR).
- Write a master record containing LSN of begin checkpoint to stable storage.
- 5. If r is an end log record
- . Update status of entry T to C if r is a commit log record
- = superset of dirty pages at time of crash ARIES: Redo

  - Fetch page P associated with r (this requires a page access!!!)
- - 3.3. If r is an update log record for T on page P
  - v.  $Update \tilde{L} and TT$ (r's prevLSN)
  - i. Update L and TT (r's prevLSN)