

Week 1 : Advanced Statistics & Regression

Course 2 : Multivariate Linear Regression

Reminders :

- Random Vector :
 X is random vector if each coordinate X_i is random variable
So : $\mathbb{E}(X) = (\mathbb{E}(X_1), \dots, \mathbb{E}(X_d))$
- Affine transformation :
if : $Y = \alpha + AX$ so : $\mathbb{E}(Y) = \alpha + A \mathbb{E}(X)$
and $Cov(Y) = ACov(X)A^\top$
- Gaussian Vector (GV) :
 X is a GV if, and only if, its characteristic function is :
 $\Phi(t) = \exp(im - \frac{t^2 \sigma^2}{2})$
Or, for all $a \in R^d$, we have $a^\top X$ is a gaussian variable.
- Standard Gaussian Vector :
 X is standrad GV if $\mathbb{E}(X) = 0$ and $Cov(X) = I_d$
- if X is GV so all X_i are gaussian variable and X_i is independent of X_j if $Cov(X_i, X_j) = 0$
- Cochran's Theorem : c.f slides

Multivariate Regression :

Goal :

create a statistical framework for :

- Probabilistic model that describe the observations
- Construction of estimators
- Statistic optimality
- Statistic inference

Linear Model : $Y_i = \beta_0 + \sum_{j=1}^p \beta_j X_{ij} + \epsilon_i$ with $i = 1, \dots, n$

Simply : $Y = X\beta + \epsilon$

P.s : The model is lineary dependent to β not necessarily to X

- Model is identified if, and only if, $X\mathbf{X}^\top$ is invertible (X is of rank full).

Hypo

- $\mathbb{E}(\epsilon_i) = 0$: errors are centralized
- $Var(\epsilon_i) = \sigma^2$: errors with constant variance
- $Cov(\epsilon_i, \epsilon_j) = 0$: The errors are decorrelated from each other

But we can simply suppose that $\epsilon_i \sim \text{Norm}(0, \sigma^2)$

- **LSE**

$$\hat{\beta} = \underset{u \in \mathbb{R}^p}{\operatorname{argmin}} \|Y - Xu\|^2$$

with norm is the euclidian norm.

So, if $X\mathbf{X}^\top$ is invertible : $\hat{\beta} = (X\mathbf{X}^\top)^{-1}X^\top Y$

- Gauss-Markov's Theorem :

if $X\mathbf{X}^\top$ is invertible, the estimator $\hat{\beta}$ LSE is guaranting the minimal variance within all the linear estimators.

Plus, It's unbiased : $\mathbb{E}_\beta(\hat{\beta}) = \beta$

and $Var_\beta(\hat{\beta}) = \sigma^2(X\mathbf{X}^\top)^{-1}$

- We define empirical residuals as : $\hat{\epsilon} = Y - X\hat{\beta}$
so the estimation of σ with LSE is given by : $\hat{\sigma}^2 = \frac{\|\hat{\epsilon}\|^2}{n-p}$
- For gaussian model : LSE \sim MLE. However, MLE is biased given $\hat{\sigma}_{ML}^2 = \frac{\|\hat{\epsilon}\|^2}{n}$

Hypothesis Tests :

for this part, we will present only the results, and the slides give wider explanation yet no proof is presented.

- Distribution of LSE :

If all hypothesis above are met, with $X\mathbf{X}^\top$ is invertible,

we have, for all $c \in \mathbb{R}^p$: $\frac{c^\top \hat{\beta} - c^\top \beta}{\hat{\sigma} \sqrt{c^\top (X\mathbf{X}^\top)^{-1} c}} \sim t_{(n-p)}$

with $t_{(n-p)}$ is the student law with n-p degree of freedom

- Trust Region :

from the result above, we can define the trust interval with the level $1 - \alpha$

$$I_{c,\alpha} = [c^\top \hat{\beta} \pm t_{n-p, 1-\alpha/2} \hat{\sigma} \sqrt{c^\top (X\mathbf{X}^\top)^{-1} c}]$$

with $t_{n-p, 1-\alpha/2}$ is the $1 - \alpha/2$ quantile of $t_{(n-p)}$

- Tests :

we present here the test presented in the slides, yet the details to be checked there,

so the test admits an error: $\Phi(Y) = 1_{(|T| > t_{n-p, 1-\alpha/2})}$

Robust Extensions :

Problem : LSE and MLE do not perform well in the case of $p > n$ (more variables than observations) and in the presence of outliers.

- Huber Loss :

A solution of outliers, since this loss will be less sensitive to the outliers.

It's given by :

$$L_{\delta}(a) = \begin{cases} a^2/2 & \text{if } |a| < \delta \\ \delta(|a| - \delta/2) & \text{otherwise.} \end{cases}$$

- Ridge Regression :

The problem becomes : $\hat{\beta} \in \operatorname{argmin}_{u \in \mathbb{R}^p} \|Y - Xu\|^2 + \lambda \|u\|^2$

λ : term of regularisation

By tuning λ we control the regularisation

Generally, ridge regression gives better prediction errors

Also, it enhances the numeric stability of the model.