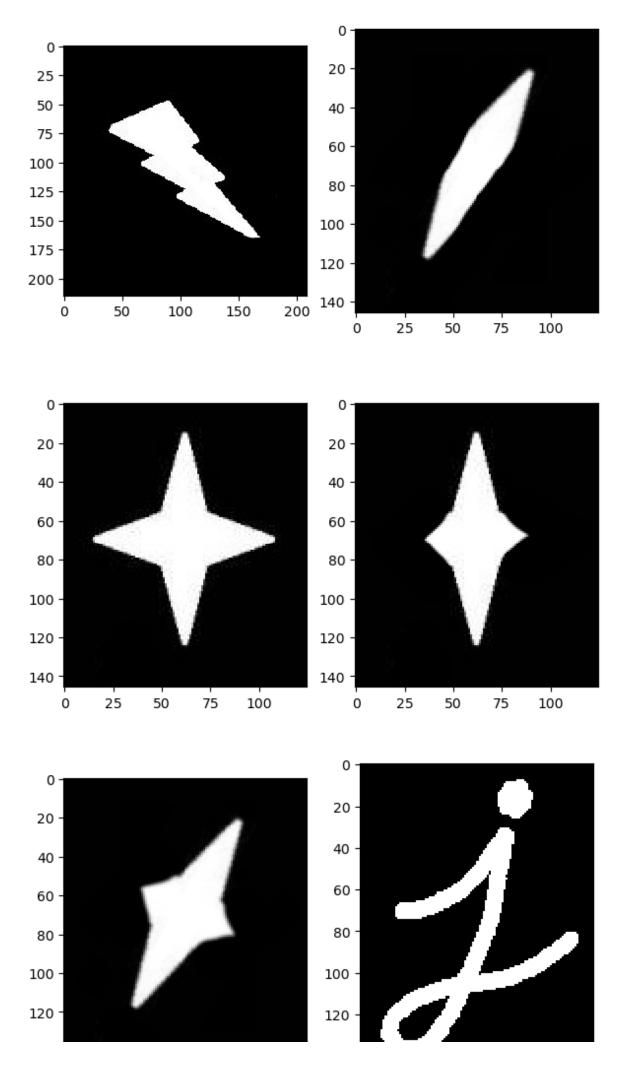
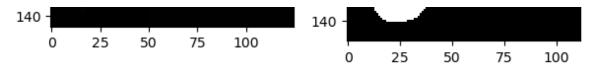
```
In [1]: %matplotlib inline
    from __future__ import print_function
    #import ganymede
    #ganymede.configure('uav.beaver.works')
    import matplotlib.pyplot as plt
    import numpy as np
    import cv2
    import os
In []: def check(p): pass
check(0)
```

Note

cv2.imshow() will not work in a notebook, even though the OpenCV tutorials use it. Instead, use plt.imshow and family to visualize your results.

```
In [17]: #Charlie Lai
         lightningbolt
                           = cv2.imread('shapes/lightningbolt.png', cv2.IMREAD GR
         blob
                           = cv2.imread('shapes/blob.png', cv2.IMREAD_GRAYSCALE)
                            = cv2.imread('shapes/star.png', cv2.IMREAD_GRAYSCALE)
         star
         squishedstar = cv2.imread('shapes/squishedstar.png', cv2.IMREAD_GRA
         squishedturnedstar = cv2.imread('shapes/squishedturnedstar.png', cv2.IMRE
                            = cv2.imread('shapes/letterj.png', cv2.IMREAD GRAYSCAL
         letterj
         images = [lightningbolt, blob, star, squishedstar, squishedturnedstar, le
         fig,ax = plt.subplots(nrows=3, ncols=2)
         for a,i in zip(ax.flatten(), images):
             a.imshow(i, cmap='gray', interpolation='none');
         fig.set size inches(7,14);
```





```
In [18]: intensity_values = set(lightningbolt.flatten())
print(len(intensity_values))
75
```

Question:

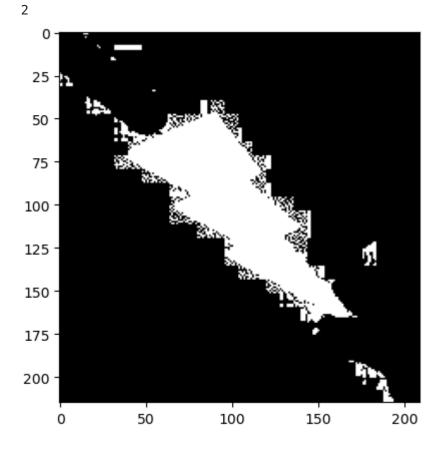
What would you expect the value to be, visually? What explains the actual value?

```
In [ ]: # TODO
# I would expect the value to be 2 because it seems like there are only 2
```

Thresholding

https://docs.opencv.org/3.4.1/d7/d4d/tutorial_py_thresholding.html

```
In [4]: _, lightningbolt = cv2.threshold(lightningbolt,0,255,cv2.THRESH_BINARY)
    intensity_values = set(lightningbolt.flatten())
    print(len(intensity_values))
    plt.imshow(lightningbolt, cmap='gray');
```



Question

What happens when the above values are used for thresholding? What is a "good" value for thresholding the above images? Why?

```
In [ ]: ## TODO
## It sets every value that isn't black to white. A more strict value, a
```

Exercises

Steps

- 1. Read each tutorial
 - Skim all parts of each tutorial to understand what each operation does
 - Focus on the part you will need for the requested transformation
- 2. Apply the transformation and visualize it

1. Blend lightningbolt and blob together

https://docs.opencv.org/3.4.1/d0/d86/tutorial_py_image_arithmetics.html

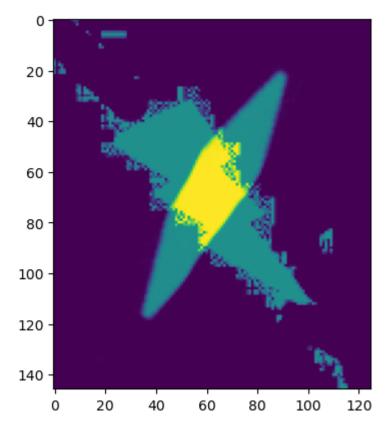
Remember: Don't use imshow from OpenCV, use imshow from matplotlib

```
In [5]: # 1. Blend
# TODO
#
height, width = blob.shape[:2]
bolt_resized = cv2.resize(lightningbolt, (width, height), interpolation=c
print(width)
print(height)

img = cv2.addWeighted(bolt_resized, .5, blob, .5, 0)
plt.imshow(img)

125
146
```

Out[5]: <matplotlib.image.AxesImage at 0xf1173583afe0>



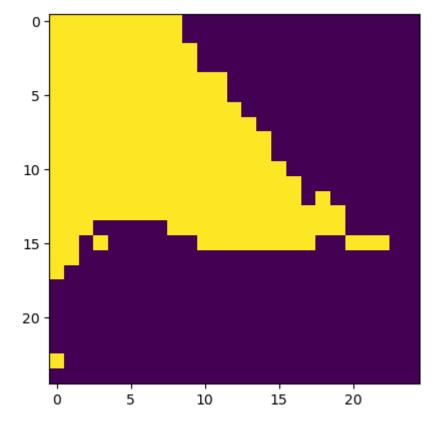
2. Find a ROI which contains the point of the lightning bolt

https://docs.opencv.org/3.4.1/d3/df2/tutorial_py_basic_ops.html

```
In [6]: # 2. R0I
# TODO

point = lightningbolt[150:175, 150:175]
plt.imshow(point)
```

Out[6]: <matplotlib.image.AxesImage at 0xf11735b85570>

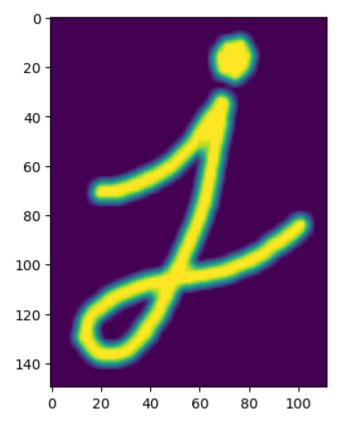


3. Use an averaging kernel on the letter j

https://docs.opencv.org/3.4.1/d4/d13/tutorial_py_filtering.html

```
In [7]: # 3.
# TODO
img = cv2.blur(letterj, (5,5))
plt.imshow(img)
```

Out[7]: <matplotlib.image.AxesImage at 0xf11735bcf5e0>



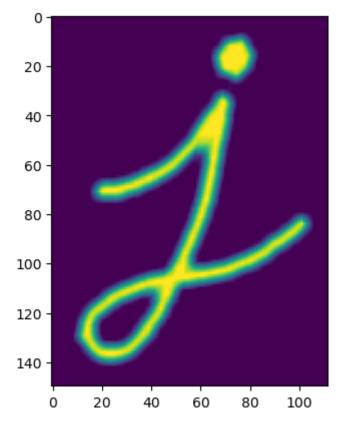
Morphology

https://docs.opencv.org/3.4.1/d9/d61/tutorial_py_morphological_ops.html

4. Perform erosion on j with a 3x3 kernel

```
In [8]: # 4
# TODO
kernel = np.ones((3, 3), np.uint8)
erodedJ = cv2.erode(img, kernel, iterations = 1)
plt.imshow(erodedJ)
```

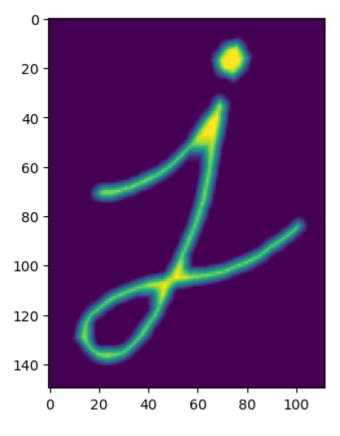
Out[8]: <matplotlib.image.AxesImage at 0xf11735c432b0>



5. Perform erosion on j with a 5x5 kernel

```
In [9]: # 5
# TODO
kernel = np.ones((5, 5), np.uint8)
erodedJ = cv2.erode(img, kernel, iterations = 1)
plt.imshow(erodedJ)
```

Out[9]: <matplotlib.image.AxesImage at 0xf11735aa5de0>



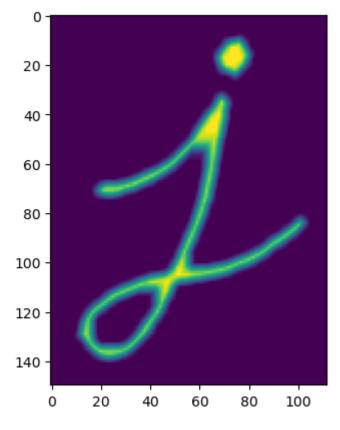
6. Perform erosion on j with **two** iterations, using a kernel size of your choice

Hint: look at the OpenCV API documentation. It is possible to perform two iterations of erosion in one line of Python!

https://docs.opencv.org/3.4.1/d4/d86/ group__imgproc__filter.html#gaeb1e0c1033e3f6b891a25d0511362aeb

```
In [10]: # 6
# TODO
kernel = np.ones((3, 3), np.uint8)
erodedJ = cv2.erode(img, kernel, iterations = 2)
plt.imshow(erodedJ)
```

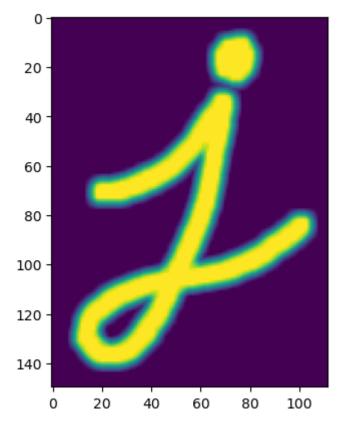
Out[10]: <matplotlib.image.AxesImage at 0xf11735b11720>



7. Perform dilation on j with a 3x3 kernel

```
In [11]: # 7
# TODO
kernel = np.ones((3, 3), np.uint8)
erodedJ = cv2.dilate(img, kernel, iterations = 1)
plt.imshow(erodedJ)
```

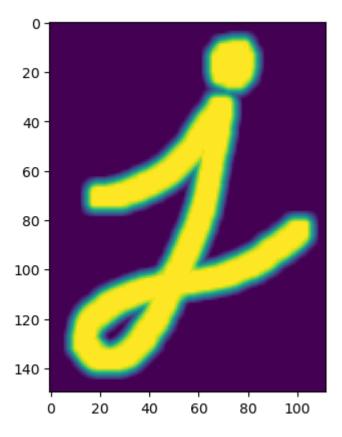
Out[11]: <matplotlib.image.AxesImage at 0xf1173597d150>



8. Perform dilation on j with a 5x5 kernel

```
In [12]: # 8
# TODO
kernel = np.ones((5, 5), np.uint8)
erodedJ = cv2.dilate(img, kernel, iterations = 1)
plt.imshow(erodedJ)
```

Out[12]: <matplotlib.image.AxesImage at 0xf117359f0a60>



9. What is the effect of kernel size on morphology operations?

```
In [13]: # 9
# TODO
# The larger the kernel size, the greater the effect of the morphology op
```

10. What is the difference betweeen repeated iterations of a morphology operation with a small kernel, versus a single iteration with a large kernel?

```
In [14]: # 10
     # TODO
     # Repeated iterations with a small kernel would tend to produce gradual a
```

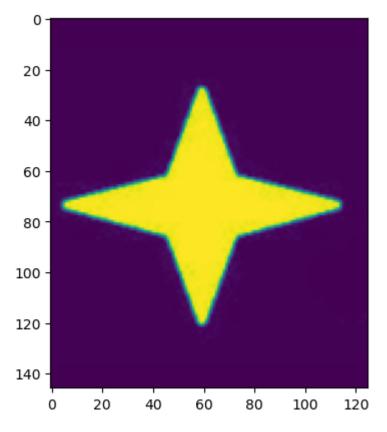
11. Rotate the lightningbolt and star by 90 degrees

https://docs.opencv.org/3.4.1/da/d6e/tutorial py geometric transformations.html

```
In [15]: # 11
# TODO
    rows2,cols2 = star.shape
    M2 = cv2.getRotationMatrix2D((cols2/2,rows2/2),90,1)
    rotatedstar = cv2.warpAffine(star,M2,(cols2,rows2))
```

plt.imshow(rotatedstar)

Out[15]: <matplotlib.image.AxesImage at 0xf11735a5d600>

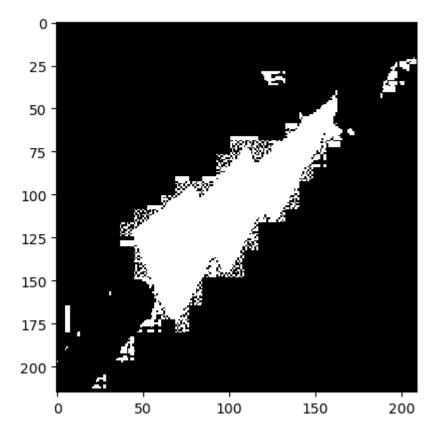


```
In [16]: rows, cols = lightningbolt.shape

# Create a rotation matrix
M = cv2.getRotationMatrix2D((cols / 2, rows / 2), 90, 1)

# Apply the affine transformation with cubic interpolation
rotatedbolt = cv2.warpAffine(lightningbolt, M, (cols, rows), flags=cv2.IN

# Display the rotated image
fig, ax = plt.subplots()
ax.imshow(rotatedbolt, cmap='gray', interpolation='none')
plt.show()
```



12. STRETCH GOAL:

Visualize the result of Laplacian, Sobel X, and Sobel Y on all of the images. Also, produce a combined image of both Sobel X and Sobel Y for each image. Is Exercise 1 the best way to do this? Are there other options?

You should have 4 outputs (Laplacian, SobelX, SobelY, and the combination) for each input image visualized at the end.

https://docs.opencv.org/3.4.1/d5/d0f/tutorial_py_gradients.html

When you are done:

You should have one or more images for each exercise.

- 1. Double-check that you filled in your name at the top of the notebook!
- 2. Click File -> Export Notebook As -> PDF
- 3. Email the PDF to YOURTEAMNAME@beaver.works