# Character Tables for Representations of Finite Groups

Jared Stewart

April 3, 2016

## Table of contents

- Basics of Representation Theory
  - Motivation
  - Group Actions
  - The Definition of a Representation
  - Subrepresentations
- 2 Complete Reducibility

## Motivation

Groups arise naturally as sets of symmetries of some object which are closed under composition and taking inverses. For example,

- **1** The **symmetric group** of degree n,  $S_n$ , is the group of all symmetries of the set  $\{1, \ldots, n\}$ .
- ② The **dihedral group** of order 2n,  $D_n$ , is the group of all symmetries of the regular n-gon in the plane.

In these two examples,  $S_n$  acts on the set  $\{1,\ldots,n\}$  and  $D_n$  acts on the regular n-gon in a natural manner. One may wonder more generally: Given an abstract group G, which objects X does G act on? This is the basic question of representation theory, which attempts to classify all such X up to isomorphism.

# **Group Actions**

#### Definition

A **group** action of a group G on a set X is a map  $\rho \colon G \times X \to X$  (written as  $g \cdot x$ , for all  $g \in G$  and  $x \in X$ ) that satisfies the following two axoims:

$$1 \cdot x = x \qquad \forall x \in X \tag{1}$$

$$(gh) \cdot x = g \cdot (h \cdot x)$$
  $\forall g, h \in G, x \in X$  (2)

# The Definition of a Representation

#### Definition

Let G be a group, let F be a field, and let V be a vector space over F. A **linear representation** of G is an action of G on V that preserves the linear structure of V, i.e. an action of G on V such that

$$g \cdot (v_1 + v_2) = g \cdot v_1 + g \cdot v_2 \qquad \forall g \in G, v_1, v_2 \in V$$
 (3)

$$g \cdot (kv) = k(g \cdot v)$$
  $\forall g \in G, v \in V, k \in F$  (4)

## Definition (Alternative definition)

Let G be a group, let F be a field, and let V be a vector space over F. A **linear representation** of G is any group homomorphism

$$\rho \colon G \to GL(V)$$
.

## Proposition

The two definitions we have given of a linear representation are equivalent.

#### Proof.

- (
  ightarrow) Suppose that we have a homomorphism  $\rho\colon G o GL(V)$ . We can obtain a linear action of G on V by defining  $g\cdot v=\rho(g)(v)$ .
- $(\leftarrow)$  Suppose that we have a linear action of G on V. We obtain a homomorphism  $\rho\colon G\to GL(V)$  by defining  $\rho(g)(v)=g\cdot v$ .



# The Dimension of a Representation

#### Definition

Let  $\rho\colon G\to GL(V)$  be a representation of G. The **dimension** of the representation is the dimension of the vector space V.

#### Example

Let V be an n-dimensional vector space. The map  $\rho \colon G \to GL(V)$  defined by  $\rho(g) = \operatorname{Id}_V$  for all  $g \in G$  is a representation of G called the **trival representation** of dimension n.

## Example

If G is a finite group that acts on a finite set X, and F is any field, then there is an associated **permutation representation** on the vector space V over F with basis  $\{e_x\colon x\in X\}$ . We let G act on the basis elements by the permutation  $g\cdot e_x=e_{gx}$  for all  $x\in X$  and  $g\in G$ . This representation has dimension |X|.

## Example

A special case of a permutation representation is that when a finite group acts on itself by left multiplication. We take the vector space  $V_{\text{reg}}$  which has a basis given by the formal symbols  $\{e_g|g\in G\}$ , and let  $h\in G$  act by

$$\rho_{\mathsf{reg}}(h)(e_g) = e_{hg}.$$

This representation is called the **regular representation** of G, and has dimension |G|.

## Example

For any symmetric group  $S_n$ , the **alternating representation** on  $\mathbb C$  is given by the map

$$\rho \colon S_n \to GL(\mathbb{C}) = \mathbb{C}^{\times}$$
$$\sigma \mapsto \operatorname{sgn}(\sigma).$$

More generally, for any group G with a subgroup H of index 2, we can define an **alternating representation**  $\rho\colon G\to GL(\mathbb{C})$  by letting  $\rho(g)=1$  if  $g\in H$  and  $\rho(g)=-1$  if  $g\notin H$ . (We recover our original example by taking  $G=S_n$  and  $H=A_n$ .)

# G-linear maps

#### Definition

A **homomorphism** between two representations  $\rho_1 \colon G \to GL(V)$  and  $\rho_2 \colon G \to GL(W)$  is a linear map  $\psi \colon V \to W$  that interwines with the action of G, i.e. such that

$$\psi \circ \rho_1(g) = \rho_2(g) \circ \psi \quad \forall g \in G.$$

In this case, we also refer to  $\psi$  as a G-linear map.

#### Definition

An **isomorphism** of representations is a G-linear map that is also invertible.

# Representations as matrices

## Example

Given any representation  $(\rho,V)$ , where V is a vector space of dimension n over the field K, we can fix a basis for V to obtain an isomorphism of vector spaces  $\psi\colon V\to K^n$ . This yields a representation  $\phi$  of G on  $K^n$  by defining

$$\phi(g) = \psi \circ \rho(g) \circ \psi^{-1}$$

for all  $g \in G$ . This representation is isomorphic to our original representation  $(\rho,V)$ . In particular, we can always choose to view complex n-dimensional representations of G as representations on  $\mathbb{C}^n$ , where each  $\phi(g)$  is given by an  $n \times n$  matrix with entries in  $\mathbb{C}$ .

# Representations as matrices

## Example

Let  $G = \{(1), (123), (132)\} \subset S_3$ . Let  $V = \mathbb{C}^3$ . Then G acts on the standard basis by  $g \cdot e_i = e_{gi}$ . Thus, the permutation representation of G (with respect to the standard basis) is given by:

$$\rho((1)) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rho((123)) = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\rho((132)) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}.$$

Let  $G = C_2 \times C_2 = \langle \sigma, \tau | \sigma^2 = \tau^2 = e, \sigma\tau = \tau\sigma \rangle$  be the Klein four-group. Let V be the vector space with basis  $\{b_e, b_\sigma, b_\tau, b_{\sigma\tau}\}$ . Left multiplication by  $\sigma$  gives a permutation

$$b_{e} \mapsto b_{\sigma}$$

$$b_{\sigma} \mapsto b_{e}$$

$$b_{\tau} \mapsto b_{\sigma\tau}$$

$$b_{\sigma\tau} \mapsto b_{\tau}.$$

We can similarly compute  $\rho_{\rm reg}(\tau)$ . Thus, in our basis, the regular representation  $\rho_{\rm reg}\colon G\to GL(V)$  is given by the matrices

$$\rho_{\mathsf{reg}}(\sigma) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \rho_{\mathsf{reg}}(\tau) = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

Let  $G=D_4=\langle\sigma,\tau|\sigma^4=\tau^2=e,\tau\sigma\tau^{-1}=\sigma^{-1}\rangle$  be the symmetry group of the square.

Let  $G = D_4 = \langle \sigma, \tau | \sigma^4 = \tau^2 = e, \tau \sigma \tau^{-1} = \sigma^{-1} \rangle$  be the symmetry group of the square. Consider a square in the plane with vertices at (1,1), (1,-1), (-1,-1), and (-1,1).

Let  $G=D_4=\langle \sigma,\tau|\sigma^4=\tau^2=e,\tau\sigma\tau^{-1}=\sigma^{-1}\rangle$  be the symmetry group of the square. Consider a square in the plane with vertices at (1,1),(1,-1),(-1,-1), and (-1,1). We let  $\sigma$  act on the square as a rotation by  $\frac{\pi}{2}$ , and let  $\tau$  act by reflection over the x-axis. This naturally gives rise to a linear action of G on all of  $\mathbb{C}^2$ .

Let  $G=D_4=\langle \sigma,\tau|\sigma^4=\tau^2=e,\tau\sigma\tau^{-1}=\sigma^{-1}\rangle$  be the symmetry group of the square. Consider a square in the plane with vertices at (1,1),(1,-1),(-1,-1), and (-1,1). We let  $\sigma$  act on the square as a rotation by  $\frac{\pi}{2}$ , and let  $\tau$  act by reflection over the x-axis. This naturally gives rise to a linear action of G on all of  $\mathbb{C}^2$ . Under the standard basis, we get the matrices:

$$\rho(e) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \qquad \rho(\tau) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\rho(\sigma) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \qquad \qquad \rho(\sigma\tau) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\rho(\sigma^2) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \qquad \qquad \rho(\sigma^2\tau) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\rho(\sigma^3) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \qquad \qquad \rho(\sigma^3\tau) = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

# Subrepresentations

#### Definition

A subrepresentation of V is a G-invariant subspace  $W\subseteq V$ ; that is, a subspace  $W\subseteq V$  with the property that  $\rho(g)(w)\in W$  for all  $g\in G$  and  $w\in W$ . Note that W itself is a representation of G under the action  $\rho(g)\upharpoonright_W$ .

# Representations of $C^2$

#### Example

Let  $G=C_2=\langle \tau|\tau^2=e\rangle$  be the cyclic group of order 2. The regular representation of G written in the standard basis is given by

$$\rho_{\mathsf{reg}}(\tau) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

and  $\rho_{\rm reg}(e)={\rm Id}_2.$  Let  $\rho_{\rm sgn}$  be the alternating representation of G on  $\mathbb C$ , i.e.

$$\rho_{sgn} \colon G \to GL_1(\mathbb{C}) = \mathbb{C}^{\times}$$
$$\tau \mapsto -1$$
$$e \mapsto 1.$$

# Representations of $C^2$

## Example (Cont.)

Let  $f \colon \mathbb{C}^2 \to \mathbb{C}$  be the linear map represented by the matrix

$$\begin{bmatrix} 1 & -1 \end{bmatrix}$$
. Then for any  $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{C}^2$ , we have

$$f \circ \rho_{\mathsf{reg}}(\tau)(x) = \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
$$= \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
$$= \rho_{\mathsf{sgn}}(\tau) \circ f(x).$$

Also note that  $f\circ \rho_{\rm reg}(e)=\rho_{\rm sgn}(e)\circ f$ . Thus f is a G-linear map from  $\rho_{\rm reg}$  to  $\rho_{\rm sgn}$  (i.e. a homomorphism of representations).

# Representations of $C^2$

## Example (Cont.)

Now let W be the subspace of  $\mathbb{C}^2$  spanned by the vector  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

Then

$$\rho_{\mathsf{reg}}(\tau) \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

and  $\rho_{\text{reg}}(e) \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , so W is a G-invariant subpace, i.e. W is a subrepresentation of  $\rho_{\text{reg}}$ . Note that W is precisely equal to the kernel of the map f, and that W is isomorphic to the 1-dimensional trivial representation of G.

We can generalize the G-invariant subspace from the previous example. Suppose we have a representation  $\rho\colon G\to GL_n(\mathbb{C})$ . If we can find a vector  $x\in\mathbb{C}^n$  which is an eigenvector for every matrix  $\rho(g),g\in G$ , i.e. an  $x\in\mathbb{C}^n$  such that

$$\rho(g)(x) = \lambda_g(x) \quad \forall g \in G$$

for some eigenvalues  $\lambda_g \in \mathbb{C}$ , then the span of x is a 1-dimensional G-invariant subspace of  $\mathbb{C}^n$ . It is isomorphic to the 1-dimensional representation

$$\rho_2 \colon G \to GL_1(\mathbb{C})$$
$$g \mapsto \lambda_q.$$

## Proposition

Let  $f\colon V\to W$  be a homomorphism of representations of G. Then  $\operatorname{Ker}(f)$  is a subrepresentation of V and  $\operatorname{Im}(f)$  is a subrepresentation of W.

#### Proof.

- Let  $x \in \text{Ker}(f)$ . Then 0 = g0 = gf(x) = f(gx) for every  $g \in G$ . So  $gx \in \text{Ker}(f)$  and Ker(f) is G-invariant.
- Now let  $w \in \operatorname{Im}(f)$ . There exists  $v \in V$  such that w = f(v), so gw = gf(v) = f(gv) for every  $g \in G$ . Thus  $gw \in \operatorname{Im}(f)$ , and  $\operatorname{Im}(f)$  is G-invariant.

# The direct sum of representations

#### Note

We know from linear algebra that given two vector spaces V and W, we can form the **direct sum**  $V \oplus W$  consisting of ordered pairs (v,w) where  $v \in V, w \in W$ .

# The direct sum of representations

#### Note

We know from linear algebra that given two vector spaces V and W, we can form the **direct sum**  $V \oplus W$  consisting of ordered pairs (v,w) where  $v \in V, w \in W$ .

#### Definition

Let V and W be representations of G. Then  $V\oplus W$  admits a natural representation of G, called the **direct sum representation** of V and W, which we define by

$$\rho_{V \oplus W} \colon G \to GL(V \oplus W)$$
$$\rho_{V \oplus W}(g) \colon (x, y) \mapsto (\rho_V(g)(x), \rho_W(g)(y)).$$

# Irreducible representations and complete reducibility

#### Definition

A representation is said to be **irreducible** if it has no subrepresentations other than the trivial subrepresentations  $0 \subset V$  and  $V \subset V$ . A representation is called **completely reducible** if it decomposes into a direct sum of irreducible representations.

#### Note

- Any 1-dimensional representation V has no subspaces other than 0 and V itself, and is thus irreducible.
- ② Any irreducible representation is, in particular, completely reducible.

# Example (A 2-dimensional irreducible representation)

Let  $G=D_3=\langle \sigma,\tau|\sigma^3=\tau^2=e,\tau\sigma\tau^{-1}=\sigma^{-1}\rangle$ . (Note that  $D_3\cong S_3$ ). Consider the regular triangle centered at the origin with vertices

$$(1,0), (-\frac{1}{2}, \frac{\sqrt{3}}{2}), (-\frac{1}{2}, -\frac{\sqrt{3}}{2}).$$

We can let  $\sigma$  act as rotation by  $\frac{2\pi}{3}$  and let  $\tau$  act as reflection over the x-axis to obtain an action of G on  $\mathbb{C}^2$  given (under the standard basis) by the matrices

$$\rho(\sigma) = \begin{bmatrix} -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$$
$$\rho(\tau) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

# Example (A 2-dimensional irreducible representation cont.)

Suppose  $\rho$  has a non-trivial subrepresentation W. We must have dim W=1. Since W is invariant under the action of both  $\rho(\sigma)$  and  $\rho(\tau)$ , there must be some mutual eigenvector for  $\rho(\sigma)$  and  $\rho(\tau)$  that spans W. The eigenvectors of  $\rho(\sigma)$  are

$$\begin{bmatrix} 1 \\ -i \end{bmatrix} \quad (\lambda_1 = e^{\frac{2\pi i}{3}}) \quad \text{and} \quad \begin{bmatrix} 1 \\ i \end{bmatrix} \quad (\lambda_2 = e^{-\frac{2\pi i}{3}}).$$

The eigenvectors of  $\rho(\tau)$  are

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad (\lambda_1 = 1) \quad \text{and} \quad \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad (\lambda_2 = -1).$$

Thus we see that there is no such  ${\cal W}$ , and our representation is irreducible.

# Representations of finite abelian groups

#### Theorem

If  $A_1,A_2,\ldots,A_r$  are linear operators on V and each  $A_i$  is diagonalizable, then  $\{A_i\}$  are simultaneously diagonalizable if and only if they commute.

# Representations of finite abelian groups

#### Theorem

Every complex representation of a finite abelian group is completely reducible into irreducible representations of dimension 1.

#### Proof.

Take an arbitrary element  $q \in G$ . Since G is finite, we can find an integer n such that  $q^n = 1$  and  $\rho(q)^n = Id$ . The minimal polynomial of  $\rho(g)$  divides  $x^n-1$ , which has n distinct roots over  $\mathbb{C}$ . So the minimal polynomial of  $\rho(g)$  factors into linear factors only over  $\mathbb{C}$ , i.e.  $\rho(q)$  is diagonalizable. We conclude that each  $\rho(q)$  is (separately) diagonalizable since  $q \in G$  was arbitrary. Now, given any two elements  $g_1, g_2 \in G$  we have  $\rho(q_1)\rho(q_2)=\rho(q_2)\rho(q_1)$ . Since the matrices  $\{\rho(q)\}$  commute,  $\{\rho(q)\}\$  are simultaneously diagonalizable, say with basis  $\{e_1,...,e_k\}$ . Then we have  $V=\mathbb{C}e_1\oplus\mathbb{C}e_2\oplus\ldots\oplus\mathbb{C}e_n$ , with each subspace  $\mathbb{C}e_1$  invariant under the action of G.

#### Definition

Let W be a subspace of V. A **linear projection** V onto W is a linear map  $f\colon V\to W$  such that  $f\restriction_W=\operatorname{Id}_W$ . If W is a subrepresentation of V and the map f is G-invariant, then we say that f is a G-linear projection.

#### Lemma

Let  $\rho\colon G\to GL(V)$  be a representation, and  $W\subset V$  be a subrepresentation. Suppose we have a G-linear projection

$$f\colon V\to W$$
.

Then Ker(f) is a complementary subrepresentation to W, i.e. Ker(f) is a G-invariant subspace of V such that

$$V = \mathit{Ker}(f) \oplus W$$

## Theorem (Maschke's Theorem)

Let G be a finite group and let F be a field such that  $\operatorname{char}(F) \nmid |G|$ . If V is any finite dimensional representation of G over F, and  $W \subset V$  is a subrepresentation of V, then there exists a complementary subrepresentation  $U \subset V$  to W, i.e. there is a G-invariant subspace  $U \subset V$  such that

$$V = W \oplus U$$
.

#### Proof.

It will suffice to find a G-linear projection from V onto W. Fix a basis  $\{b_1,\ldots,b_m\}$  for W and extend it to a basis  $\{b_1,\ldots,b_m,b_{m+1},\ldots,b_n\}$  for V. Let  $U=\langle b_{m+1},\ldots,b_n\rangle$ . Then U is certainly a complementary subspace to W, and we have a natural projection  $f\colon W\oplus U\to W$  of V onto W with kernel U. There is no reason to think that f should be G-linear, but we can fix this by averaging over G. Define  $\widetilde{f}\colon V\to V$  by

$$\widetilde{f}(x) = \frac{1}{|G|} \sum_{g \in G} (\rho(g) \circ f \circ \rho(g^{-1}))(x).$$

We claim that  $\widetilde{f}$  is a G-linear projection from V onto W.

#### Proof.

First we check that  $\operatorname{Im}(\widetilde{f}) \subset W$ . If  $x \in V$  and  $g \in G$ , then

$$f(\rho(g^{-1})(x)) \in W$$

and so

$$\rho(g)(f(\rho(g^{-1})(x))) \in W$$

since W is G-invariant. Thus

$$\widetilde{f}(x) = \frac{1}{|G|} \sum_{g \in G} (\rho(g) \circ f \circ \rho(g^{-1}))(x) \in W.$$

#### Proof.

Next we check that  $\widetilde{f}\upharpoonright_W=\operatorname{Id}_W$ . Let  $y\in W$ . For any  $g\in G$ , we know that  $\rho(g^{-1})(y)$  is also in W, so  $f(\rho(g^{-1})(y))=\rho(g^{-1})(y)$ . Then

$$\widetilde{f}(y) = \frac{1}{|G|} \sum_{g \in G} \rho(g) (f(\rho(g^{-1})(y)))$$

$$= \frac{1}{|G|} \sum_{g \in G} \rho(g) (\rho(g^{-1})(y))$$

$$= \frac{1}{|G|} \sum_{g \in G} (y) = \frac{|G|y}{|G|} = y$$

so indeed  $\widetilde{f}$  is a linear projection of V onto W.

#### Proof.

Finally, we check that  $\widetilde{f}$  is G-linear. If  $x \in V$  and  $h \in G$ , then

$$(\widetilde{f} \circ \rho(h))(x) = \frac{1}{|G|} \sum_{g \in G} (\rho(g) \circ f \circ \rho(g^{-1}) \circ \rho(h))(x)$$

$$= \frac{1}{|G|} \sum_{g \in G} (\rho(g) \circ f \circ \rho(g^{-1}h))(x)$$

$$= \frac{1}{|G|} \sum_{g \in G} (\rho(hg) \circ f \circ \rho(g^{-1}))(x) \quad (g \mapsto hg)$$

$$= (\rho(h) \circ \widetilde{f})(x).$$

## Corollary

Let G be a finite group and let F be a field such that  $\operatorname{char}(F) \nmid |G|$ . then any finite-dimensional representation of G over F is completely reducible.

#### Proof.

Let V be a representation of G over F of dimension n. If V is irreducible, then V is, in particular, completely reducible. If not, then V contains a propositioner subrepresentation  $W \subset V$ . From Maschke's Theorem (??), we know there exists a subrepresentation  $U \subset V$  such that

$$V = W \oplus U. \tag{5}$$

Both W and U have dimension less than n, so by induction we know that W and U are completely reducible. We deduce from 5 that V is completely reducible.