University of Missouri

MASTER'S PROJECT

A Survey on Character Tables for Representations of Finite Groups

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Abstract

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A Survey on Character Tables for Representations of Finite Groups

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The Thesis Abstract is written here (and usually kept to just this page). The page is kept centered vertically so can expand into the blank space above the title too...

Acknowledgements

The acknowledgements and the people to thank go here, don't forget to include your project advisor...

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For/Dedicated to/To my...

Chapter 1

Basics of Representation Theory

1.1 Group Actions

Definition 1.1. A *(left)* **group action** of a group G on a set X is a map $\varphi : G \times X \to X$ (written as $g \cdot a$, for all $g \in G$ and $a \in A$) that satisfies the following two axoims:

$$id_G \cdot x = x \qquad \forall x \in X \tag{1.1.1}$$

$$(gh) \cdot x = g \cdot (h \cdot x)$$
 $\forall g, h \in G, x \in X$ (1.1.2)

Note. We could likewise define the concept of a *right* group action, where the set elements would be multiplied by group elements on the right instead of on the left. Throughout we shall use the term *group action* to mean a *left* group action.

Proposition 1.2. Let G act on the set X. For any fixed $g \in G$, the map σ_g from X into X defined by $\sigma_g(x) = g \cdot x$ is a permutation of the set X, i.e. $\sigma_g \in S_X$.

Proof. We show that σ_g is a permutation of X by finding a two-sided inverse map, namely $\sigma_{g^{-1}}$. Observe that for any $x \in X$, we have

$$(\sigma_{g^{-1}} \circ \sigma_g)(x) = \sigma_{g^{-1}}(\sigma_g(x))$$
 (by definition of function composition)
$$= g^{-1} \cdot (g \cdot x)$$
 (by definition of σ_g and $\sigma_{g^{-1}}$)
$$= (g^{-1}g) \cdot x$$
 (by axiom 1.1.1 of an action)
$$= id_G \cdot x$$

$$= x$$
 (by axiom 1.1.2 of an action).

Thus $\sigma_{g^{-1}} \circ \sigma_g$ is the identity map on X. We can reverse the roles of g and g^{-1} to see that $\sigma_g \circ \sigma_{g^{-1}}$ is also the identity map on X. Having a two-sided inverse, we conslude that σ_g is a permutation of X.

Proposition 1.3. Let G act on the set X. The map from G to the symmetric group S_X defined by $g \mapsto \sigma_q(x) = g \cdot x$ is a group homomorphism.

Proof. Define the map $\varphi: G \to S_X$ by $\varphi(g) = \sigma_g$. We have seen from Proposition 1.2 that σ_g is indeed an element of S_X . It remains to show that $\varphi(g_1g_2) = \varphi(g_1) \circ \varphi(g_2)$ for any $g_1, g_2 \in G$. Observe that

$$\varphi(g_1g_2)(x) = \sigma_{g_1g_2}(x) \qquad \text{(by definition of } \varphi)$$

$$= (g_1g_2) \cdot x \qquad \text{(by definition of } \sigma_{g_1g_2})$$

$$= g_1 \cdot (g_2 \cdot x) \qquad \text{(by axiom 1.1.1 of an action)}$$

$$= \sigma_{g_1}(\sigma_{g_2}(x)) \qquad \text{(by definition of } \sigma_{g_1} \text{ and } \sigma g_2)$$

$$= \varphi(g_1)(\varphi(g_2)(x)) \qquad \text{(by definition of } \varphi)$$

$$= (\varphi(g_1) \circ \varphi(g_2))(x) \qquad \text{(by definition of function composition)}.$$

Since the values of $\varphi(g_1g_2)$ and $\varphi(g_1)\circ\varphi(g_2)$ agree on every element $x\in X$, these two permutations are equal. We conclude that φ is a homomorphism, since g_1 and g_2 were arbitrary elements of G.

Proposition 1.4. Any homomorphism ψ from the group G into the symmetric group on S_X on a set X gives rise to an action of G on X, defined by taking $g \cdot x = \psi(g)(x)$.

Proof. Suppose that we have a homomorphism ψ from G into S_X . We can define a map from $G \times X$ to X by $g \cdot x = \psi(g)(x)$. We verify that this map satisfies the definition of a group action of G on X:

(axiom 1.1.1)
$$id_G \cdot x = \psi(id_G)(x) = id_X(x) = x$$

(axiom 1.1.2) $(gh) \cdot x = \psi(gh)(x) = (\psi(g)\psi(h))(x) = \psi(g)(\psi(h)(x)) = g \cdot (h \cdot x)$

Proposition 1.5. The actions of G on the set X are in bijective correspondence with the homomorphisms from G into the symmetric group S_X .

Proof. By Proposition 1.3, any action of G on X yields a homomorphism from G into S_X . Conversely, any homomorphism from G into S_X establishes an action of G on X by Proposition 1.4.

1.2 Definition of a Representation

Definition 1.6. A **linear representation** of a group G on a vector space V is a group homomorphism from G to GL(V), the general linear group on V.

Definition 1.7. A **linear representation** of a group G on a vector space V over a field F is an action of G on V which preserves the linear structure of V, that is,

$$g \cdot (v_1 + v_2) = g \cdot v_1 + g \cdot v_2 \qquad \forall g \in G, v_1, v_2 \in V$$
 (1.7.1)

$$g \cdot (kv) = k(g \cdot v) \qquad \forall g \in G, v \in V, k \in F \qquad (1.7.2)$$

Proposition 1.8. The definitions of a linear representation given in 1.6 and 1.7 above are equivalent.

Proof. (\rightarrow) Suppose that we have a homomorphism $\varphi: G \to GL(V)$. Note that GL(V) is a subgroup of the symmetric group S_V on V, so we can apply Proposition 1.4 to obtain an action of G on V by $g \cdot v = \varphi(g)(v)$. We check that this action preserves the linear structure of V.

1.7.1 For any $g \in G$, $v_1, v_2 \in V$ we have $g \cdot (v_1 + v_2) = \varphi(g)(v_1 + v_2) = \varphi(g)(v_1) + \varphi(g)(v_2) = g \cdot v_1 + g \cdot v_2$.

1.7.2 For any $g \in G, v \in V, k \in F$ we have $g \cdot (kv) = \varphi(g)(kv) = k(\varphi(g)(v)) = k(g \cdot v)$.

(\leftarrow) Suppose that we have an action of G on V which preserves the linear structure of V in the sense of Definition 1.7. We can apply Proposition 1.3 to obtain a homorphism $\varphi:G\to S_V$ given by $\varphi(g)=\sigma_g$ where $\sigma_g(v)=g\cdot v$. It remains to show that the image $\varphi(G)$ of G under φ is actually contained in GL(V), i.e. that for each $g\in G$ the map σ_g is linear. Fix an element $g\in G$. For any $k\in F$ and $v\in V$ we have

$$\sigma_g(kv) = g \cdot (kv)$$
 (by definition of σ_g)
 $= k(g \cdot v)$ (by property 1.7.1)
 $= k(\sigma_g(v))$ (by definition of σ_g).

Also, for any $v_1, v_2 \in V$ we have

$$\begin{split} \sigma_g(v_1+v_2) &= g \cdot (v_1+v_2) & \text{(by definition of } \sigma_g) \\ &= g \cdot v_1 + g \cdot v_2 & \text{(by property 1.7.2)} \\ &= \sigma_g(v_1) + \sigma_g(v_2) & \text{(by definition of } \sigma_g). \end{split}$$

Thus σ_g is linear, and $\varphi(G) \subset GL(V)$ proves that we have a homomorphism $\varphi: G \to GL(V)$.

Chapter 2

Spaghetti

2.1 Definition of a Representation AGAIN

Definition 2.1. A **linear representation** of a group G on a vector space V is a group homomorphism from G to GL(V), the general linear group on V.

More explicitly, a representation is a map $\rho:G\to GL(V)$ such that

$$\rho(g_1g_2) = \rho(g_1)\rho(g_2) \quad \forall g_1, g_2 \in G.$$

Definition 2.2. A **linear representation** ρ of a group G on a vector space V over a field K is a group action of G on V which preserves the linear structure of V. That is,

1.
$$\rho(g)(v_1 + v_2) = \rho(g)(v_1) + \rho(g)(v_2) \quad \forall g \in G, v_1, v_2 \in V$$

2.
$$\rho(g)(kv) = k \cdot \rho(g)v \quad \forall g \in G, v \in V, k \in K$$

2.1.1 Subsection 1

Definition 2.3. Here is a new definition.

$$E = mc^2 (2.3.1)$$

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2.1.2 Subsection 2

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Definition 2.4. A **linear representation** ρ of a group G on a vector space V over a field K is a group action of G on V which preserves the linear structure of V. That is,

$$\rho(g)(v_1 + v_2) = \rho(g)(v_1) + \rho(g)(v_2) \quad \forall g \in G, \forall v_1, v_2 \in V$$
(2.4.1)

$$\rho(g)(kv) = k \cdot \rho(g)v \quad \forall g \in G, v \in V, k \in K$$

2.2 Main Section 2

Definition 2.5. Here is a new definition.

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Appendix A

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