

# WSNSimulation API Usage

Zack Raven

**Classes** in the package:

1. **Complex** – Represents complex numbers (Note: this is a simplified version for use in WSNSimulation)
  - I. Constructors
    - i. `Complex()`  
⇒ Sets real and imaginary parts to 0
    - ii. `Complex(double real, double im)`  
⇒ Sets the real to real and the imaginary to im
  - II. Get Functions
    - i. `double : getReal`  
⇒ Returns the real portion of the Complex number
    - ii. `double : getImaginary`  
⇒ Returns the imaginary portion of the Complex number
    - iii. `double : getMagnitude`  
⇒ Returns the magnitude of the Complex number
    - iv. `double : getPhase`  
⇒ Returns the phase of the Complex number
  - III. Set Functions
    - i. `setReal(double)`  
⇒ Sets the real portion of the Complex number
    - ii. `setImaginary(double)`  
⇒ Sets the imaginary portion of the Complex number
    - iii. `setValues(double real, double im)`  
⇒ Sets the real to real and imaginary to im
  - IV. Others
    - i. `String : toString`  
⇒ Returns the String representation of the Complex number. Note: this does not include any formatting/rounding.
    - ii. `String : toFormattedString`  
⇒ Returns the String representation of the Complex number rounded to two digits past the decimal for each portion of real and imaginary.
2. **Sensor** – Represents sensors in the simulation. Each Sensor has an ID, which is auto incremented in this case, a Complex alpha value, a Complex H value and a Complex N value.
  - I. Constructors
    - i. `Sensor(int id, Complex alpha, Complex h, Complex n)`  
⇒ Sets the values for the sensor
  - II. Get Functions

- i. Int : getID
  - ii. Complex : getAlpha
  - iii. Complex : getHVal
  - iv. Complex : GetNVal
- III. Set Functions
  - i. setID(int)
  - ii. setAlpha(Complex)
  - iii. setHVal(Complex)
  - iv. setNVal(Complex)
- IV. Others
- 3. **SetupException** – Exception for the SimulationSetup inherits RuntimeException, only thrown when an error that would break the simulation occurs, so it is an unchecked exception (meaning you aren't required to use try catch block).
  - I. Constructors
    - i. SetupException(SetupException.ExceptionType)
      - ⇒ Allows for an easier way of checking exactly why there was an error.
  - II. Get Functions
    - i. SetupException.ExceptionType : getExceptionType
      - ⇒ Return the exception type so the user can correct the error
  - III. Set Functions
  - IV. Others
- 4. **Simulation** – Represents a single simulation
  - I. Constructors
    - i. Simulation(SimulationSetup)
      - ⇒ This constructor will automatically run the simulation based on the setup provided.
  - II. Get Functions
    - i. Complex : getVVal
    - ii. Complex : getYVal
    - iii. Complex : getThetaHat
    - iv. List<Sensor> : getSensorList
      - ⇒ Returns the list of sensors that is automatically generated upon calling the constructor
    - v. Sensor : getSensor(int)
      - ⇒ Shorthand for getSensorList().get(int)
    - vi. SimulationSetup : getSetup
  - III. Set Functions
  - IV. Others
    - i. sortSensorsByNumber(Boolean descending)
    - ii. sortSensorsByAlpha(Boolean descending)
    - iii. sortSensorsByH(Boolean descending)

- iv. sortSensorsByN(Boolean descending)

## 5. **SimulationSetup** – Represents the setup for the simulation

### I. Constructors

- i. SimulationSetup()  
⇒ Sets up the default settings
- ii. SimulationSetup(args[])  
⇒ Sets up the settings by name

### II. Get Functions

- i. double : getC
- ii. String : getObservation
- iii. double : getTheta
- iv. int : getSensorCount
- v. double : getPower
- vi. double : getVarianceN
- vii. double : getVarianceV
- viii. double : getK
- ix. Boolean : isUniform
- x. Boolean : isOptimum  
⇒ Shorthand for !isUniform()
- xi. Boolean : isRician
- xii. Boolean : isAWGN  
⇒ Shorthand for !isRician()
- xiii. double : getSensingSNR
- xiv. double : getChannelSNR

### III. Set Functions

- i. setObservation(String)
- ii. setTheta(double)
- iii. setSensorCount(int)  
⇒ Throws SensorException for negative numbers
- iv. setPower(double)  
⇒ Throws SensorException for negative numbers
- v. setVarianceN(double)  
⇒ Throws SensorException for negative numbers
- vi. setVarianceV(double)  
⇒ Throws SensorException for negative numbers
- vii. setK(double)  
⇒ Throws SensorException for negative numbers
- viii. setUniform(Boolean)  
⇒ Throws SensorException for if channels are set as Rician
- ix. setOptimum(Boolean)  
⇒ Shorthand for setUniform(!input)

- x. setRician(Boolean)
  - ⇒ Will automatically switch to Optimum alphas if Rician is chosen
- xi. setAWGN(Boolean)
  - ⇒ Shorthand for setRician(!input)

#### IV. Others

- i. addListener(SetupListener)
- ii. removeListener(SetupListener)

### 6. **SimulationManager** – Helps to manage all things in the simulation and setup

#### I. Constructors

#### II. Get Functions

- i. Simulation : getLastSimulation
- ii. SimulationSetup : getSimulationSetup
- iii. SetupListener : getListener

#### III. Set Functions

- i. setSetupListener(SetupListener)

#### IV. Others

- i. getInstance
  - ⇒ SimulationManager is a singleton
- ii. runSimulation
  - ⇒ This runs the Simulation and sorts the sensors based on the most recent way of sorting them
- iii. updateSimulation(SharedPreferences)
  - ⇒ This is only used in android, this will save the current setup to the shared preferences so it can be loaded in later
- iv. sortSensors
  - ⇒ Sorts the sensors the same way as previously done in case of shuffling etc.
- v. sortSensors(int)
  - ⇒ Sort by a specific field. 0 for ID, 1 for Alpha, 2 for H and 3 for N. This is very useful for swapping between ascending and descending because SimulationManager remembers what was done. For instance calling sortSensors(0) will sort the sensors by ID ascending. Calling sortSensors(0) again will sort the sensors by ID descending. This cycle repeats or starts over when a new field is used.
- vi. sortSensorsByNumber(Boolean descending)
- vii. sortSensorsByAlpha(Boolean descending)
- viii. sortSensorsByH(Boolean descending)
- ix. sortSensorsByN (Boolean descending)

**Interfaces** in the package:

1. **SetupListener** – Alerts the listener for a change in the simulation

## Use Cases:

### 1. Adjust the setup

- 1.1. Use `SimulationManager` to retrieve the current setup and then use the `set*` functions to adjust the setup.

```
SimulationManager.getSimulationSetup().setObservation(SimulationSetup.DEFAULT_OBSERVATION);
SimulationManager.getSimulationSetup().setSensorCount(SimulationSetup.DEFAULT_SENSOR_COUNT);
SimulationManager.getSimulationSetup().setTheta(SimulationSetup.DEFAULT_THETA);
SimulationManager.getSimulationSetup().setPower(SimulationSetup.DEFAULT_POWER);
SimulationManager.getSimulationSetup().setVarianceN(SimulationSetup.DEFAULT_N);
SimulationManager.getSimulationSetup().setVarianceV(SimulationSetup.DEFAULT_V);
SimulationManager.getSimulationSetup().setK(SimulationSetup.DEFAULT_K);
SimulationManager.getSimulationSetup().setRician(SimulationSetup.DEFAULT_RICIAN);
SimulationManager.getSimulationSetup().setUniform(SimulationSetup.DEFAULT_UNIFORM);
```

### 2. Get values from the setup

- 2.1. Use the `SimulationManager` to retrieve the current setup and then use the `get*` functions to get any desired value.

```
DecimalFormat two = new DecimalFormat("#.##");
System.out.println("Current Setup:"); System.out.println("");
System.out.println("Observation: "+SimulationManager.getSimulationSetup().getObservation());
System.out.println("Theta: "+two.format(SimulationManager.getSimulationSetup().getTheta()));
System.out.println("Number of sensors to use: "+SimulationManager.getSimulationSetup().getSensorCount());
System.out.println("Power Value: "+two.format(SimulationManager.getSimulationSetup().getPower()));
System.out.println("N-Variance: "+two.format(SimulationManager.getSimulationSetup().getVarianceN()));
System.out.println("V-Variance: "+two.format(SimulationManager.getSimulationSetup().getVarianceV()));
System.out.println("Alpha Type: "+(SimulationManager.getSimulationSetup().isUniform() ? "Uniform" :
"Optimum"));
System.out.println("Channel Type: "+(SimulationManager.getSimulationSetup().isRician() ? "Rician" :
"AWGN"));
System.out.println("K-Value: "+(SimulationManager.getSimulationSetup().isRician() ?
two.format(SimulationManager.getSimulationSetup().getK()) : "N/A"));
```

### 3. Run the simulation

- 3.1. Simply call `SimulationManager.runSimulation()`

### 4. Run the simulation multiple times

- 4.1. Call `SimulationManager.runSimulation()` multiple times

```
for (int i = 0; i < runCount; i++) {
    SimulationManager.runSimulation();
}
```

### 5. Get values from the simulation

- 5.1. Use `SimulationManager` to obtain the most recent Simulation and use the `get*` functions to get desired values

```
System.out.println("Current Simulation:"); System.out.println("");
System.out.println("Theta Hat: "+SimulationManager.getLastSimulation().getThetaHat().toFormattedString());
System.out.println("Y Value: "+SimulationManager.getLastSimulation().getYVal().toFormattedString());
System.out.println("V Value: "+SimulationManager.getLastSimulation().getVVal().toFormattedString());
```

6. Print out data from the sensors

6.1. Get the sensor list from the most recent simulation

```
System.out.println("Current Sensors:"); System.out.println("");
for (Sensor s : SimulationManager.getLastSimulation().getSensorList()) {
    System.out.println("Sensor Number: "+s.getID());
    System.out.println("Alpha: "+s.getAlpha().toFormattedString());
    System.out.println("H-Value: "+s.getHVal().toFormattedString());
    System.out.println("N-Value: "+s.getNVal().toFormattedString());
    System.out.println("");
}
```

7. Sort the sensors

7.1. Use the SimulationManager to adjust this

```
SimulationManager.sortSensors();
SimulationManager.sortSensors(0);
SimulationManager.sortSensorsByNumber(true);
SimulationManager.sortSensorsByAlpha(true);
SimulationManager.sortSensorsByH(true);
SimulationManager.sortSensorsByN(true);
```

8. Use the SetupListener

8.1. Implement SetupListener in your class, then call *SimulationManager.setSetupListener(this);*