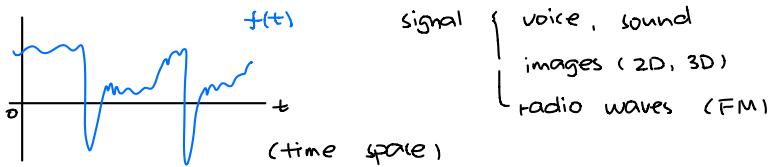


## Applied Harmonic Analysis

## Background :



## Fourier analysis :

Fourier series (periodic  $f$ )

$$f(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos(\omega_n t) + b_n \sin(\omega_n t)$$

amplitude                      frequency

$$\text{waveform} = N + \text{nr} + \text{nn} + \dots$$

Fourier transform (non-periodic  $f$ )

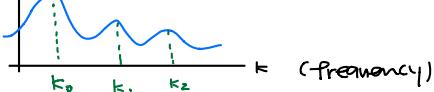
$$F(f) = \frac{1}{2\pi} \int_{\mathbb{R}} f(t) e^{-ikt} dt \quad \text{where } i = \sqrt{-1}$$

Function  $f \in V \leftarrow$  some vector space (say  $L^2(\mathbb{R})$  or  $\ell^2(\mathbb{R})$ ) $\downarrow$ Decompose  $f$  (into say sines/cosines or wavelets) $\downarrow$ In frequency space, can manipulate  $f$ : compression, denoising, apply other filters ..

amplitude

ex: low-pass filter

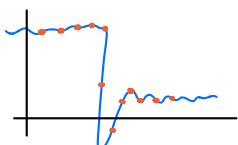
$$f(t) \approx \frac{a_0}{2} + \sum_{n=1}^N a_n \cos(\omega_n t) + b_n \sin(\omega_n t)$$



In practice, need to discretize!

- DFT (Discrete Fourier Transform)

- DWT (Discrete Wavelet Transform)

need to sample points of  $f$ .

## Number Systems.

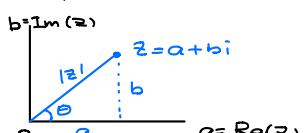
Countable

$\mathbb{N} = \{0, 1, 2, 3, \dots\}$	naturals
$\mathbb{Z} = \{\dots, -1, 0, 1, 2, \dots\}$	integers
$\mathbb{Q} = \{p/q \mid p, q \in \mathbb{Z}, q \neq 0\}$	rationals.

Uncountable

$\mathbb{R} = \{\text{real numbers}\}$	ex: $\pi, -\frac{1}{2}, 0, e, \dots$
$\mathbb{C} = \{a+bi \mid a, b \in \mathbb{R}\}$	complex.

## (Complex numbers)



$$|z| = z\bar{z} = \sqrt{a^2 + b^2} \quad (\text{modulus})$$

[conjugate  $\bar{z} = a - bi$ ]

Polar form:  $z = r e^{i\theta}$  where  $r = |z|$ ,  $\theta = \tan^{-1}(\frac{b}{a})$

$$e^{i\theta} = \cos\theta + i \sin\theta \quad (\text{Euler's Formula})$$

## Complex Fourier series:

$$f(t) = \sum_{n=-\infty}^{\infty} a_n e^{int} \quad \text{where } n = \text{frequency}$$

Roots of complex  $z \in \mathbb{C}$

if  $w^n = z$ , then  $w = n^{\text{th}}$  root of  $z$

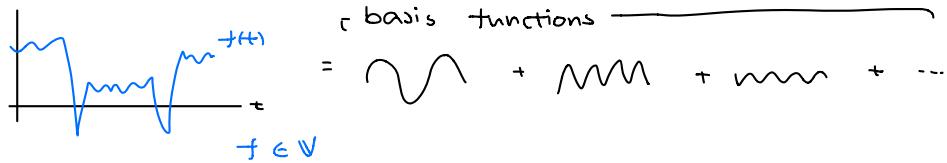
$$w = pe^{ia}, z = re^{i\theta}$$

$$w^n = p^n e^{ina}$$

$$\Rightarrow w = \sqrt[n]{r} \exp(i \frac{\theta + 2k\pi}{n}) \quad (k=0, 1, 2 \dots n-1)$$

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Vector (linear) spaces.



Examples of vector spaces :  $\mathbb{R}^n$  finite dimensional

$\mathbb{C}^n$   $2n$  dimensional

$P_n = \{ n^{\text{th}} \text{ degree polynomials} \} = \text{poly}$

infinite dimensional  $\begin{cases} C[0,1] = \{ u: [0,1] \rightarrow \mathbb{R} \mid u \text{ is continuous} \} \\ L^2(a,b) = \{ u: (a,b) \rightarrow \mathbb{R} \mid \int_a^b |u(t)|^2 dt < \infty \} \end{cases}$

Vector Space Axioms: let  $\underline{u, v, w \in V}$  = some set and let  $\underline{\alpha, \beta \in \mathbb{R} \text{ or } \mathbb{C}}$   
linearity vectors fields

- 1)  $u + (v + w) = (u + v) + w$
- 2)  $u + v = v + u$
- 3)  $\exists 0 \in V$  s.t.  $u + 0 = u$
- 4)  $\exists (-u) \in V$  s.t.  $u + (-u) = 0$
- 5)  $\alpha(\beta u) = (\alpha\beta)u$
- 6)  $(\alpha + \beta)u = \alpha u + \beta u$
- 7)  $\alpha(u + v) = \alpha u + \alpha v$

Defn: If  $\{v_1, \dots, v_n\} \subset V$  and  $\{\alpha_1, \dots, \alpha_n\} \subset \mathbb{R}$  (or  $\mathbb{C}$ )

then  $\sum_{i=1}^n \alpha_i v_i = \alpha_1 v_1 + \dots + \alpha_n v_n$  is a linear combination of the  $\{v_i\}_{i=1}^n$

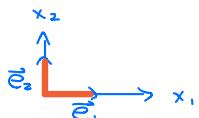
note:  $n$  has to be finite

ex:  $\sum_{k=1}^{10} \alpha_k \cos(kt)$  is a lin. comb. of  $\{\cos(kt)\}_{k=1}^{10}$

Defn: The span of  $\{v_1, \dots, v_n\} \subset V$  is the set

$$\text{span}\{v_1, \dots, v_n\} = \left\{ \sum_{i=1}^n \alpha_i v_i \mid v_i \in V, \alpha_i \in \mathbb{K} \right\} \quad \mathbb{K} = \mathbb{R} \text{ or } \mathbb{C}$$

ex:  $\mathbb{R}^2$ ,  $\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ ,  $\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$



$\text{span}(\vec{e}_1) = \text{entire } x_1 \text{ axis} = \{a\vec{e}_1 \mid a \in \mathbb{R}\}$

$$\text{span}(\vec{e}_1, \vec{e}_2) = \mathbb{R}^2 = \{a_1\vec{e}_1 + a_2\vec{e}_2 \mid a_1, a_2 \in \mathbb{R}\} = \left( \begin{matrix} a_1 \\ a_2 \end{matrix} \right)$$

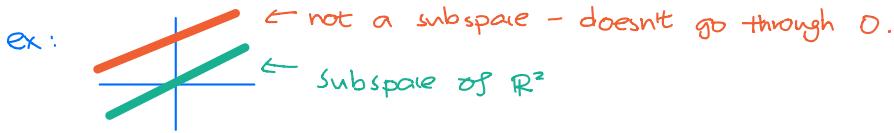
Subspaces :

ex:  $\text{span}\{v_i\}_{i=1}^n$  is a subspace of  $V$ .

A subspace of  $V$  is a set  $X \subset V$  s.t.  $u + v \in X \quad \forall u, v \in X$

- we say  $X \subset V$  is closed under scalar multiplication and addition.

- A subspace is itself a vector space.



ex:  $P_2$  is a subspace of  $C[0,1]$

**Defn:** A set  $\{v_1, \dots, v_n\} \subset V$  is linearly independent

if  $\sum_{i=1}^n c_i v_i = 0$ , then  $c_i = 0$  for  $i = 1, \dots, n$ . note:  $n$  is finite.

ex:  $(1, 0), (0, 1), (0, 0)$  are linearly independent.  
since  $(0, 0) = \frac{1}{2}(0, 1) + 0(1, 0)$

**Defn:** A basis  $B$  of  $V$  is a linearly independent set of vectors that span  $V$ .

ex:  $B = \{1, t, t^2\}$  form a basis of  $P_2$ .

**Defn:** The dimension of  $V$  is the number of vectors in any basis.

ex:  $\dim(R^2) = 2$ ,  $\dim(P_2) = 3$ ,  $\dim(C[0,1]) = \infty$

note: need to be careful in  $C[0,1]$

since  $\sum_{i=1}^{\infty} c_i v_i$  not allowed in vector space axiom.

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**Basis in  $\infty$ -dim spaces**

Hamel Basis (ignore) - uses finite # of vectors.

Schauder Basis:

$B$  is a schauder basis if

- Any finite set of vectors of  $B$  is linearly independent.
- $\forall \vec{v} \in V$ ,  $\vec{v} = \sum_{i=1}^{\infty} c_i \vec{v}_i$  where  $B = \{\vec{v}_i\}_{i=1}^{\infty}$  (completeness)  
interpreted as  $\lim_{n \rightarrow \infty} \|\vec{v} - \sum_{i=1}^n c_i \vec{v}_i\|_V = 0$
- The coefficients  $c_i$  are unique.

example of Schauder basis: Fourier series in  $L^2(0, 2\pi) = V$

$$f(t) = \sum_{n=-\infty}^{\infty} a_n e^{int}$$

form a Schauder basis  $\{1, e^{it}, e^{-it}, e^{2it}, e^{-2it}, \dots\}$

**Inner-Product Spaces**:  $\mathbb{R}^n = \mathbb{R}^n$  or  $\mathbb{C}^n$

Define inner-product  $\langle x, y \rangle = \sum_{i=1}^n x_i \bar{y}_i$   $x, y \in \mathbb{R}^n$  note  $z = x+iy$ ,  $\bar{z} = x-iy$

$$\text{i)} \quad \langle x, y \rangle = \overline{\langle y, x \rangle}$$

$$\text{ii)} \quad \langle ax + by, z \rangle = a\langle x, z \rangle + b\langle y, z \rangle \quad a, b \in \mathbb{R}$$

$$\text{iii)} \quad \langle x, x \rangle \geq 0 \text{ and } \langle x, x \rangle = 0 \text{ iff } x = 0$$

$$\text{note: } \langle x, ay \rangle = \overline{a\langle y, x \rangle} = \overline{a} \overline{\langle y, x \rangle} = \bar{a} \langle x, y \rangle$$

ex:  $\mathbb{R}^2$



$$\text{pf: law of cosines } \|\vec{x} - \vec{y}\|^2 = \|\vec{x}\|^2 + \|\vec{y}\|^2 - 2\|\vec{x}\|\|\vec{y}\| \cos \theta$$

$$\langle \vec{x} - \vec{y}, \vec{x} - \vec{y} \rangle = \|\vec{x}\|^2 + \|\vec{y}\|^2 - 2\|\vec{x}\|\|\vec{y}\| \cos \theta$$

$$\cancel{\|\vec{x}\|^2} - \langle \vec{x}, \vec{y} \rangle - \langle \vec{y}, -\vec{x} \rangle + \cancel{\|\vec{y}\|^2} = \|\vec{x}\|^2 + \|\vec{y}\|^2 - 2\|\vec{x}\|\|\vec{y}\| \cos \theta$$

**Normed spaces**  $(V, \|\cdot\|)$  is a normed space where  $\|\cdot\| : V \rightarrow \mathbb{R}$  and satisfies

- $\|u+v\| \leq \|u\| + \|v\| \quad \forall u, v \in V$ . (triangle inequality)
- $\|au\| = |a|\|u\| \quad a \in \mathbb{K}$
- $\|u\| \geq 0$  and  $\|u\| = 0 \iff u = 0$

All inner-products generate a norm:  $\|\mathbf{x}\| = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}$

Other norms on  $\mathbb{R}^n$ : let  $p \geq 1$ , and set  $\|\vec{x}\|_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$

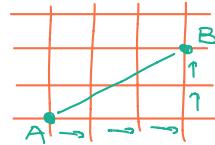
$$\|\vec{x}\|_1 = \sum_{i=1}^n |x_i| \quad (1\text{-norm, taxicab norm})$$

$$\Rightarrow \|\vec{x}\|_2 = (\sum_{i=1}^n |x_i|^2)^{1/2} \quad (2\text{-norm})$$

$$\hookrightarrow \text{generated by } \langle \mathbf{x}, \mathbf{y} \rangle = \sum_{i=1}^n x_i y_i$$

$$\Rightarrow \|\vec{x}\|_\infty = \max_{i=1,\dots,n} |x_i| \quad (\infty\text{-norm, max norm})$$

$$\hookrightarrow \text{note } \|\vec{x}\|_\infty = \lim_{p \rightarrow \infty} \|\vec{x}\|_p$$

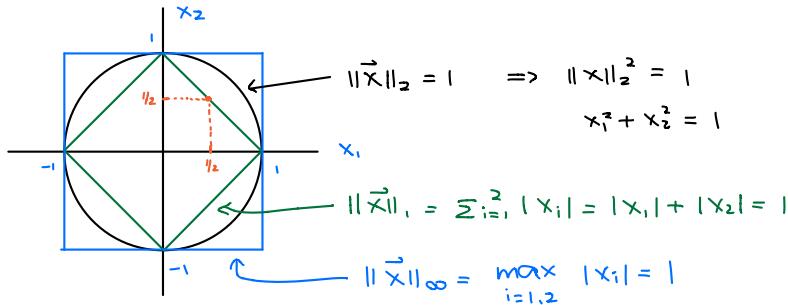


Dist btw. A, B  
in  $\|\vec{x}\|_1$  is 5

Ex:

$$\|\vec{x}\|_2 = \sqrt{x_1^2 + x_2^2} = (\sum_{i=1}^2 x_i^2)^{1/2} \quad (\text{Euclidean norm})$$

### Unit Spheres in various norms $\mathbb{R}^2$



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### Equivalent Norms

We say any two norms  $\|\cdot\|_\alpha, \|\cdot\|_\beta$  are equivalent

If  $\exists A, B > 0$  s.t.  $A\|\mathbf{x}\|_\alpha \leq \|\mathbf{x}\|_\beta \leq B\|\mathbf{x}\|_\alpha$  (norm are comparable)

Theorem: In finite dimensional spaces, All norms are equivalent.

### Cauchy-Schwarz Inequality

For any  $\mathbf{x}, \mathbf{y} \in V$  ( $V$  inner-product space)

We have  $|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \|\mathbf{y}\|$  recall  $\|\mathbf{x}\| = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}$

Pf: If  $\mathbf{x} = \mathbf{0}$  or  $\mathbf{y} = \mathbf{0}$ , done.

So, suppose  $\mathbf{x}, \mathbf{y} \neq \mathbf{0}$ . Suppose  $V = \mathbb{R}$

$$\begin{aligned} 0 \leq \|\mathbf{x} - t\mathbf{y}\|^2 &= \langle \mathbf{x} - t\mathbf{y}, \mathbf{x} - t\mathbf{y} \rangle = \|\mathbf{x}\|^2 - 2t\langle \mathbf{x}, \mathbf{y} \rangle + t^2\|\mathbf{y}\|^2 \\ &\quad \text{constant} \quad \text{"c"} \quad \text{"-2tb"} \quad \text{"t^2a"} \\ &= c - 2tb + at^2 \quad (\text{quadratic in } t) \end{aligned}$$

$$t = \frac{2b \pm \sqrt{(-2b)^2 - 4ac}}{2a} \quad \text{want } (-2b)^2 - 4ac \leq 0$$

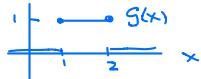
$$\begin{aligned} b^2 \leq ac &\quad \leftarrow \|\mathbf{x}\|^2 \quad \leftarrow \|\mathbf{y}\|^2 \\ |\langle \mathbf{x}, \mathbf{y} \rangle|^2 &\leq \|\mathbf{x}\|^2 \|\mathbf{y}\|^2 \quad \Rightarrow |\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \|\mathbf{y}\| \end{aligned}$$

## The vector space $L^2[a, b]$

$$L^2[a, b] := \{ f: [a, b] \rightarrow \mathbb{C} \mid \int_a^b |f(x)|^2 dx < \infty \}$$

this is an inner-product space with  $\langle f, g \rangle = \langle f, g \rangle_{L^2[a, b]} := \int_a^b f(x) \overline{g(x)} dx$   
 an norm  $\|f\|_{L^2[a, b]} = \|f\|_{L^2} = (\int_a^b |f(x)|^2 dx)^{1/2}$

ex:  $g \in L^2(\mathbb{R})$



$$\|g\|_{L^2(\mathbb{R})} = (\int_{\mathbb{R}} |g(x)|^2 dx)^{1/2} = (\int_1^2 1^2 dx)^{1/2} = 1$$

Cauchy-Schwarz in  $L^2$ :  $|\langle f, g \rangle| \leq \|f\| \|g\|$

$$|\int_a^b f(x) \overline{g(x)} dx| \leq (\int_a^b |f|^2 dx)^{1/2} (\int_a^b |g|^2 dx)^{1/2}$$

## Orthogonality

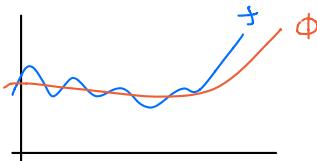
let  $u, v \in V$ , we say  $u, v$  are orthogonal if  $\langle u, v \rangle = 0$

ex:  $\vec{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\langle \vec{x}, \vec{y} \rangle = \langle \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \rangle = 1 - 1 = 0$$

$$\text{note } \langle \vec{x}, \vec{y} \rangle = \|\vec{x}\|_2 \|\vec{y}\|_2 \cos \theta = 0 \quad \theta = \frac{\pi}{2}$$

plus if  $\|u\|_2, \|v\|_2 = 1$ , then  $u, v$  are orthonormal.



- $\|f - \phi\|_2$  is the average distance btwn  $f, \phi$ .
- $\|f - \phi\|_\infty$  is a distance that tries to minimize the maximum dist.

note  $L^3[a, b] = \{ f: [a, b] \rightarrow \mathbb{R} \mid \int_a^b |f(x)|^3 dx < \infty \}$

$$\|f\|_{L^3} = (\int_a^b |f(x)|^3 dx)^{1/3}$$

$$\text{while } \|\vec{x}\|_3 = (\sum_{i=1}^n |x_i|^3)^{1/3}$$

## Orthonormal Bases

Suppose  $B = \{e_1, e_2, \dots, e_n\} \subset V$  is an orthonormal basis of  $V$ .

I have  $\langle e_i, e_j \rangle = 0$  unless  $i = j$  in which case  $\langle e_i, e_j \rangle = \|e_i\|^2 = 1$

$$\text{Kronecker Delta: } \langle e_i, e_j \rangle = \delta_{ij} = \delta(i-j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

and  $\forall u \in V, u = \sum_{i=1}^n c_i e_i$

$$\text{use orthogonality: } \langle u, e_j \rangle = \langle \sum_{i=1}^n c_i e_i, e_j \rangle = \sum_{i=1}^n c_i \underbrace{\langle e_i, e_j \rangle}_{=\delta_{ij}} = c_j$$

so  $u = \sum_{i=1}^n \langle u, e_i \rangle e_i$

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Recall:

Orthonormal basis  $\{e_k\}_{k=1}^n \subset V$ .

$$u \in V, u = \sum_{k=1}^n \langle u, e_k \rangle e_k$$

$$\langle u, u \rangle = \langle \sum_{k=1}^n \langle u, e_k \rangle e_k, u \rangle$$

$$\|u\|^2 = \sum_{k=1}^n \langle u, e_k \rangle \langle e_k, u \rangle = \sum_{k=1}^n |\langle u, e_k \rangle|^2 = \|u\|^2$$

$= \langle u, u \rangle$

Each  $\langle u, e_k \rangle e_k$  is an orthogonal projection of  $u$  onto  $e_k$

$$P_{e_k} u = \text{Proj}_{e_k} u = \langle u, e_k \rangle e_k$$

-  $\{e_k\}_{k=1}^n$  is orthonormal here

If  $M = \text{Span}\{e_1, \dots, e_m\}$  then  $P_M u = \text{Proj}_M u = \sum_{k=1}^m \langle u, e_k \rangle e_k$   
 ↳ set  $m \in \mathbb{Z}^+ = \mathbb{N}$  (index)

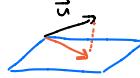
$$\begin{aligned} \vec{w} = \text{proj}_{\vec{v}} \vec{u} &\quad \text{have } \vec{w} = \pi \vec{v} \text{ for some } \pi \in \mathbb{R} \\ 0 = \langle \vec{u} - \vec{w}, \vec{v} \rangle &= \langle \vec{u} - \pi \vec{v}, \vec{v} \rangle = \langle \vec{u}, \vec{v} \rangle - \underbrace{\langle \pi \vec{v}, \vec{v} \rangle}_{\pi \|\vec{v}\|^2} \\ \pi &= \langle \vec{u}, \vec{v} \rangle / \|\vec{v}\|^2 \\ \vec{w} &= \pi \vec{v} = \frac{\langle \vec{u}, \vec{v} \rangle \vec{v}}{\|\vec{v}\|^2} \quad \text{when } \|\vec{v}\|=1, \quad \vec{w} = \langle \vec{u}, \vec{v} \rangle \vec{v} \end{aligned}$$

If  $\{e_k\}_{k=1}^n$  is an orthogonal basis then  $u = \sum_{k=1}^n \frac{\langle u, e_k \rangle}{\|e_k\|^2} e_k$

$P_m$  is a projection if  $P_m(P_m) = P_m^2 = P_m$

lets check for  $P_M u = \sum_{k=1}^m \langle u, e_k \rangle e_k \in \pi$

$$\begin{aligned}
 P_M(P_M u) &= \sum_{k=1}^m \langle P_M u, e_k \rangle e_k \\
 &= \sum_{k=1}^m \left\langle \sum_{j=1}^m \langle u, e_j \rangle e_j, e_k \right\rangle e_k \\
 &\quad \left| \quad \quad \quad = \sum_{j=1}^m \langle u, e_j \rangle \underbrace{\langle e_j, e_k \rangle}_{= \delta_{jk}} = \langle u, e_k \rangle \right. \\
 &= \sum_{k=1}^m \langle u, e_k \rangle e_k \\
 &= P_M u
 \end{aligned}$$

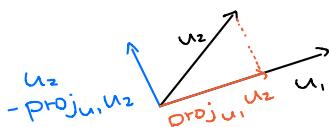


Consider  $\{1, t\} \subset L^2[0, 1] = \mathbb{V}$

$$\langle 1, t \rangle = \int_0^1 1 \cdot t \, dt = \frac{1}{2} \neq 0 \quad \Rightarrow \quad 1, t \text{ not orthogonal}$$

## How to orthogonalize?

$\{u_1, u_2, \dots, u_n\}$  non-orthogonal want to turn into  $\{v_1, v_2, \dots, v_n\}$  orthogonal.



Now  $\{U_1, U_2 - \text{proj}_{U_1} U_2\}$  is an orthogonal set spanning the same set as  $\{U_1, U_2\}$

## Gram - Schmidt Process

To turn  $\{u_i\}_{i=1}^n$  non-orthogonal set into  $\{v_i\}_{i=1}^n$  orthogonal.

$$V_1 = U_1$$

$$v_2 = u_2 - \text{proj}_{u_1} u_2$$

$$U_3 = U_3 - \text{Proj}_{\text{span}(U_1, U_2)}, U_3 = U_3 - \text{Proj}_{U_1} U_3 - \text{Proj}_{U_2} U_3$$

⋮

$$v_n = u_n - \text{proj}_{\text{span}\{v_1, \dots, v_{n-1}\}} u_n$$

we have  $\text{span}\{u_1, \dots, u_n\} = \text{span}\{v_1, \dots, v_n\}$ ,  $\{v_1, \dots, v_n\}$  is orthogonal,

We can normalize by  $\left\{ \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}, \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|}, \dots, \frac{\mathbf{v}_n}{\|\mathbf{v}_n\|} \right\}$

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## Linear Operators (map, function)

$T: V \rightarrow W$  is a linear map if  $\alpha \in \mathbb{K}$  ( $\mathbb{R}$  or  $\mathbb{C}$ ) and  $A, u, v \in V$ .

- $$\text{i) } T(u+v) = T(u) + T(v)$$

$$G_X: \mathbb{H} \rightarrow \mathcal{P}_n^{\mathbb{R}}$$

$$T(\vec{x}) = A\vec{x} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad A = \text{linear operator (Matrix)}$$

Ex:  $T: L^2(0,1) \rightarrow \mathbb{R}$

$$T(u) = \int_0^1 u(t)e^t dt$$

$$T(au+bu) = \int_0^1 (au+bu)(t)e^t dt = aT(u) + bT(v)$$

Ex:  $T: l^2(\mathbb{N}) \rightarrow l^2(\mathbb{N})$ ,  $x \in l^2(\mathbb{N})$ ,  $x = \{x_1, x_2, \dots\}$

$$T(x) = \{\frac{1}{2}x_1, \frac{1}{2^2}x_2, \frac{1}{2^3}x_3, \dots, \frac{1}{2^n}x_n, \dots\}$$

$$T(ax+by) = \{\frac{1}{2}(ax_1+bx_1), \frac{1}{2^2}(ax_2+bx_2), \dots\}$$

$$= a\{\frac{1}{2}x_1, \frac{1}{2^2}x_2, \dots\} + b\{\frac{1}{2}x_1, \frac{1}{2^2}x_2, \dots\}$$

$$= aT(x) + bT(y)$$

In finite dimensions, any linear map  $T: V \rightarrow W$  can be represented as matrix multiplication. where  $V, W$  are vector spaces.

Let  $\{v_1, \dots, v_n\}$  be a basis of  $V$  and let  $\{w_1, \dots, w_m\}$  be a basis of  $W$ .

Note  $T(v_j) \in W \quad \forall j=1, \dots, n$

$$\Rightarrow T(v_j) = \sum_{i=1}^m a_{ij} w_i$$

$$\text{let } v = \sum_{j=1}^n x_j v_j \in V$$

$$= c_i$$

$$\text{Then } T(v) = T\left(\sum_{j=1}^n x_j v_j\right) = \sum_{j=1}^n x_j T(v_j) = \sum_{j=1}^n x_j \left(\sum_{i=1}^m a_{ij} w_i\right) = \sum_{i=1}^m \sum_{j=1}^n a_{ij} x_j w_i = \sum_{i=1}^m c_i w_i$$

Here  $c_i = \sum_{j=1}^n a_{ij} x_j$  is precisely matrix-vector multiplication:  $\vec{z} = A\vec{x}$

$$\begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & \ddots & \ddots & \vdots \\ \vdots & & \ddots & \vdots \\ a_{m1} & \cdots & \cdots & a_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\text{think of } T(\vec{v}) = A\vec{v}$$

The column of  $A$  store the coefficients of  $T(v_j) \quad j=1 \dots n$

where  $\{v_j\}_{j=1}^n$  is a basis of  $V$ .

Ex: Find the matrix representation of  $T: V \rightarrow W$  where  $V = \mathbb{R}^2$ ,  $W = \text{span}\{\text{cost}, \text{sint}\}$ .  
and  $T(\vec{v}) = (v_1 + 2v_2)\text{cost}, v_2 \text{sint}$

basis for  $V$  let's use  $\{\vec{e}_1, \vec{e}_2\} = \{(1, 0), (0, 1)\}$

and for  $W$  let's use  $\{w_1, w_2\} = (\text{cost}, \text{sint})$

$$\text{Have } T(\vec{e}_1) = T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = 1 \cdot \text{cost} + 0 \cdot \text{sint} \Rightarrow A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$$
$$T(\vec{e}_2) = T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = 2 \cdot \text{cost} + 1 \cdot \text{sint}$$

$$\Rightarrow \vec{v} = x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \in V = \mathbb{R}^2, \vec{z} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}, \vec{z} = A\vec{x}.$$

$\underbrace{\text{basis of } \mathbb{R}^2}$

$$\text{so } T(\vec{v}) = c_1 w_1 + c_2 w_2 = c_1 \text{cost} + c_2 \text{sint}$$

And if used basis  $\{(1, 0), (0, 1)\}$  for  $V = \mathbb{R}^2$ .

$$T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = 1 \cdot \text{cost} + 0 \cdot \text{sint} \Rightarrow A = \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$$
$$T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = 3 \cdot \text{cost} + 1 \cdot \text{sint}$$

Ex: if basis  $\{(1, 0), (0, 1)\}$  of  $V = \mathbb{R}^2$ , basis  $\{w_1, w_2\} = (\text{cost} + \text{sint}, \text{sint})$  of  $W$ .

$$\text{then } A = \begin{pmatrix} 1 & 2 \\ -1 & -1 \end{pmatrix} \quad \vec{v} = x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}, T(\vec{v}) = c_1(\text{cost} + \text{sint}) + c_2 \text{sint}$$

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## Adjoint Operators

 $T: V \rightarrow W$  linear operator (map)inner-product spaces with  $\langle \cdot, \cdot \rangle_V$  and  $\langle \cdot, \cdot \rangle_W$ Can we write  $\langle Tv, w \rangle_W$  as  $\langle v, T^*w \rangle_V$  for some new operator  $T^*$  the adjoint of  $T$ .[  $Tv$  or  $T(v)$  denotes action of  $T$  on  $v$  ]i.e.  $T^*: W \rightarrow V$  s.t.  $\langle Tv, w \rangle_W = \langle v, T^*w \rangle_V$ Goal: Try to write  $\langle Tv, w \rangle_W = \langle v, z \rangle_V$  for some  $z \in V$  and define  $T^*w = z$ .Theorem: If  $V, W$  are finite-dimensional and  $T: V \rightarrow W$  is linear, then  $T^*: W \rightarrow V$  exists and is uniqueIf  $T = T^*$  we call  $T$  self-adjoint,  $\langle Tv, w \rangle = \langle v, T^*w \rangle = \langle v, Tw \rangle$ Ex: The Fourier transform  $F[f] = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{ix^2} dx$  is self-adjoint with the  $L^2(\mathbb{R})$  inner-product  $\langle f, g \rangle_{L^2(\mathbb{R})} = \int_{\mathbb{R}} f(x)g(x) dx$ 

$$\text{so } \langle Ff, g \rangle_{L^2} = \langle f, Fg \rangle_{L^2}$$

Ex:  $T = I$   $I: V \rightarrow V$  (identity map)  $Iv = v$ 

$$\langle Iv, w \rangle = \langle v, Iw \rangle$$

$$\text{so } I^*w = Iw \Rightarrow I^* = I \text{ by definition}$$

Ex: Let  $a(t)$  be bounded.  $\langle f, g \rangle_{L^2} = \int_a^b f(x)g(x) dx$ Define  $T: L^2(a, b) \rightarrow L^2(a, b)$  by  $(Tf)(t) = a(t)f(t)$ Find  $T^*$ 

$$\begin{aligned} \text{Have } \langle Tf, g \rangle &= \langle af, g \rangle = \int_a^b a(t)f(t)\overline{g(t)} dt = \int_a^b f(t) \cdot \underbrace{\overline{a(t)g(t)}}_{} dt \\ &= \int_a^b f(t)\overline{a(t)g(t)} dt \\ &= \langle f, \bar{a}g \rangle \quad \text{so } (T^*g)(t) = \overline{a(t)}g(t) \end{aligned}$$

If  $a(t)$  real-valued, then  $T^* = T$  and  $T$  self-adjoint.

Integration by Parts:

$$\int_a^b f(t)g'(t) dt = -f(t)g(t) \Big|_{t=a}^{t=b} + \int_a^b f'(t)g(t) dt$$

Ex:  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ ,  $T(x, y, z) = A\vec{x} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ 

$$\text{Fact: } A^* = \bar{A}^T \text{ so } A^* = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} \quad A^*: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\begin{aligned} \langle A \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} a \\ b \end{pmatrix} \rangle_2 &= \langle \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} a \\ b \end{pmatrix} \rangle_2 = \langle \begin{pmatrix} x+y \\ x+2z \end{pmatrix}, \begin{pmatrix} a \\ b \end{pmatrix} \rangle_2 = (x+y)a + (x+2z)b \\ &= x(a+b) + ya + za + zb = \langle \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} a+b \\ a \\ 2b \end{pmatrix} \rangle_3 \end{aligned}$$

$$\text{we define } A^* \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a+b \\ a \\ 2b \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \quad A: \mathbb{R}^3 \rightarrow \mathbb{R}^2, A^*: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\langle A\vec{x}, \vec{y} \rangle_2 = \langle \vec{x}, A^*\vec{y} \rangle_3$$

2/10/21

## Intro to Frames

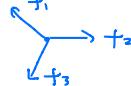
$\mathbb{V}$  with orthonormal basis  $\{v_1, v_2, v_3, \dots\}$  (ONB)

- can be restrictive in practice
- easy to compute  $c_i$  s.t.  $x = \sum c_i v_i$ ,  $c_i = \langle x, v_i \rangle$

$\{f_1, f_2, f_3, \dots\}$  is a frame of  $\mathbb{V}$  if the  $\{f_i\}_{i \in I}$  span  $\mathbb{V}$  and satisfy some other conditions.

- frame can be linearly dependent.

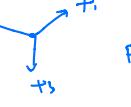
ex:  a basis of  $\mathbb{R}^2$  (orthonormal)

ex:  a frame for  $\mathbb{R}^2$  (contains redundancies)

ex:  another frame

ex: Reconstruction, orthonormal basis  $\{e_1, e_2\}$

 person A,  $\{1, 2\}$ ,  $x = 1 \cdot e_1 + 2 \cdot e_2$ .  
 ↓ "erasure" "information loss", lose all info. in the  $e_2$  dire.  
 person B,  $\{1, ?\}$ ,  $x = 1 \cdot e_1 + ?$

 person A,  $\{1, 2, 3\}$ ,  $x = 1 \cdot f_1 + 2 \cdot f_2 + 3 \cdot f_3$   
 ↓ retains more info. than with ONB and sometimes can get  
 person B,  $\{1, 2, ?\}$ ,  $x = 1 \cdot f_1 + 2 \cdot f_2 + ?$  "perfect reconstruction"

## Primer on Hilbert Spaces

A Hilbert space  $H$  is a complete inner-product space.

- also normed  $\|x\|_H = \sqrt{\langle x, x \rangle_H}$

Defn:  $\{x_n\}_{n=1}^{\infty} \subset H$  is a Cauchy-sequence if

$$\forall \epsilon > 0 \quad \exists N \in \mathbb{N} \text{ s.t. } \forall n, m \geq N, \quad \|x_n - x_m\|_H < \epsilon$$

Defn:  $H$  is complete if every Cauchy sequence  $\{x_n\}_{n=1}^{\infty}$  converges to a point  $x \in H$ .

$$\text{i.e. } \lim_{n \rightarrow \infty} x_n = x \in H, \quad \|x_n - x\|_H \rightarrow 0 \text{ as } n \rightarrow \infty$$

Hilbert spaces:  $\mathbb{R}, \mathbb{R}^n, \mathbb{C}^n, L^2(\mathbb{Z}), L^2(a, b), L^2(\mathbb{R})$

any finite dimensional inner-product space i.e.  $\mathbb{P}_n$

Non-Hilbert spaces:  $S = (0, 1) \subseteq \mathbb{R}$ ,  $x_n = 1/n$  for  $n \geq 2$  converges to  $0 \notin S$

Defn:  $H$  is separable if it contains a countable basis.

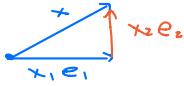
- All examples above are separable.

For ONB, of a Hilbert space  $H$ ,  $x = \sum_{i \in I} \langle x, e_i \rangle e_i \quad \forall x \in H$

Dotting with  $x$  we get

$$\|x\|^2 = \langle x, \sum_{i \in I} \langle x, e_i \rangle e_i \rangle = \sum_{i \in I} \overline{\langle x, e_i \rangle} \langle x, e_i \rangle = \sum_{i \in I} |\langle x, e_i \rangle|^2$$

↳ Parseval equality

ex:   $\|x\|^2$ -case:  $\|x\|^2 = x_1^2 + x_2^2 = |\langle x, e_1 \rangle|^2 + |\langle x, e_2 \rangle|^2 = \sum_{i \in I} |\langle x, e_i \rangle|^2$   
Pythagorean theorem

Frames generalize Parseval equality:

Defn:  $\{f_i\}_{i \in I}$  is a frame for  $H$  if  $I$  is countable and if  $\exists 0 < A \leq B < \infty$   
s.t.  $\forall x \in H$   $A \|x\|^2 \leq \sum_{i \in I} |\langle x, f_i \rangle|^2 \leq B \|x\|^2$   
frame bounds.

- largest  $A$  and smallest  $B$  that work are called optimal frame bounds.
- For  $A=B=1$ , equality holds and we call  $\{f_i\}_{i \in I}$  a Parseval frame  
i.e. an ONB is parseval
- $\{f_i\}_{i \in I}$  is a tight frame if  $A=B$

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