Introduction of Pytorch

2021/09/27

Frameworks

- **C++**
  - ✓Caffe
- **Python**
  - ✓PyTorch, TensorFlow, Keras, Caffe2, MXNet, Theano
- Matlab
  - ✓MatConvNet
- Lua
  - ✓Torch7

Frameworks

Google:
TensorFlow

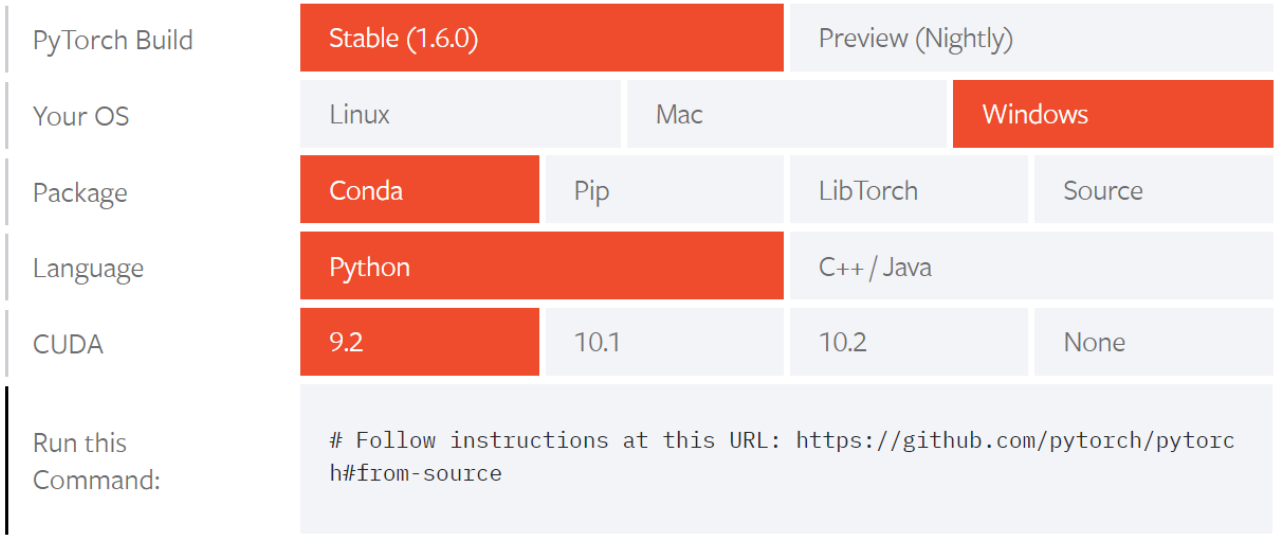
Facebook:
PyTorch + Caffe2

Future Homework

- Do your homework using PyTorch
- Other frameworks are not available:
  - Keras (backend = tensorflow)
  - TensorFlow

Install PyTorch

- https://pytorch.org/get-started/locally/



Python

Currently, PyTorch on Windows only supports Python 3.x; Python 2.x is not supported.

As it is not installed by default on Windows, there are multiple ways to install Python:

- Chocolatey
- Python website
- Anaconda

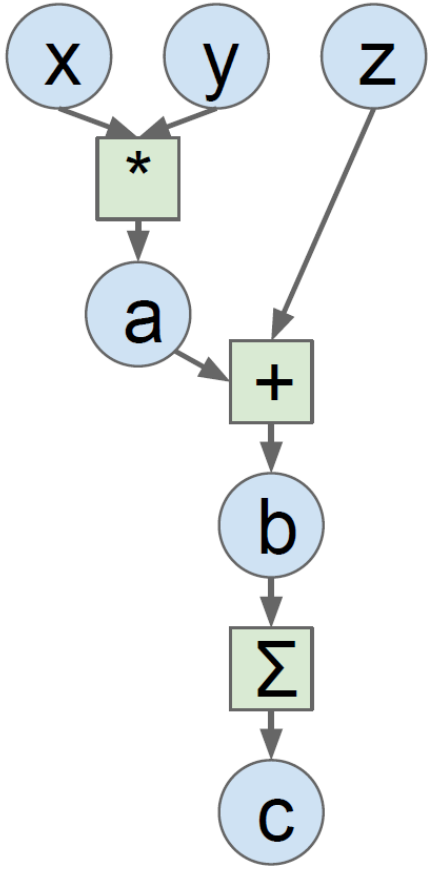
Package Manager

To install the PyTorch binaries, you will need to use at least one of two supported package managers: Anaconda and pip. Anaconda is the recommended package manager as it will provide you all of the PyTorch dependencies in one, sandboxed install, including Python and `pip.`

Computational Graphs

Numpy

```
import numpy as np
np.random.seed(0)

N, D = 3, 4

x = np.random.randn(N, D)
y = np.random.randn(N, D)
z = np.random.randn(N, D)

a = x * y
b = a + z
c = np.sum(b)
```

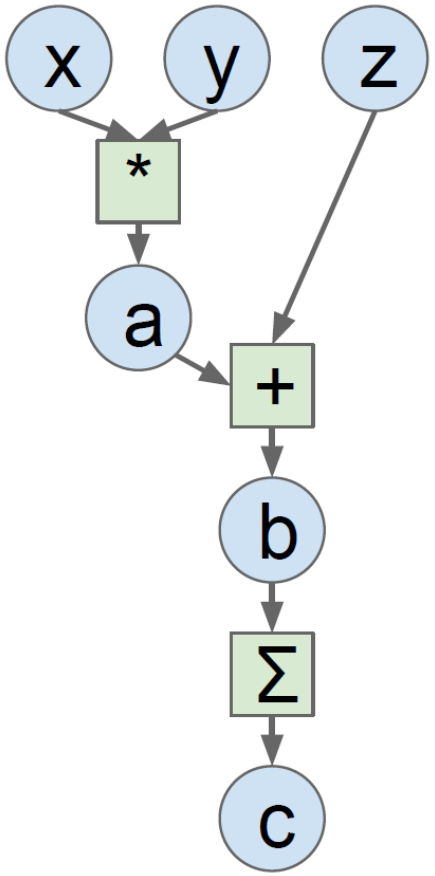


Neural network can be denoted as a directed acyclic graph

Computational Graphs

Numpy

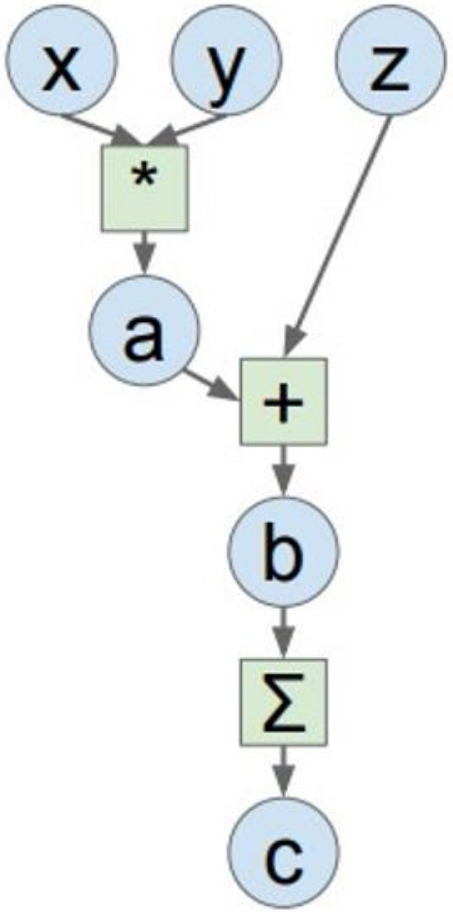
```
import numpy as np
np.random.seed(0)

N, D = 3, 4

x = np.random.randn(N, D)
y = np.random.randn(N, D)
z = np.random.randn(N, D)

a = x * y
b = a + z
c = np.sum(b)

grad_c = 1.0
grad_b = grad_c * np.ones((N, D))
grad_a = grad_b.copy()
grad_z = grad_b.copy()
grad_x = grad_a * y
grad_y = grad_a * x
```



Problems:

- Can't run on GPU
- Have to compute our gradients

Computational Graphs



Define Variable to start building graph

Forward Pass

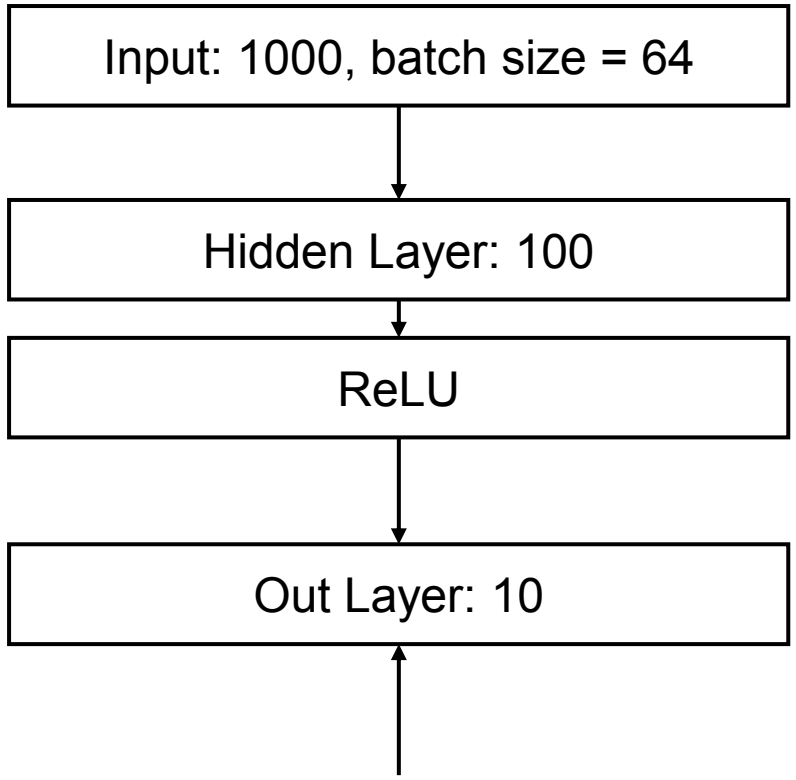
Compute gradient

PyTorch

```
import torch
from torch.autograd import Variable

N, D = 3, 4

x = Variable(torch.randn(N, D),
             requires_grad=True)
y = Variable(torch.randn(N, D),
             requires_grad=True)
z = Variable(torch.randn(N, D),
             requires_grad=True)

a = x * y
b = a + z
c = torch.sum(b)

c.backward()

print(x.grad.data)
print(y.grad.data)
print(z.grad.data)
```

Example

- A 2-layer ReLU network



x: 64×1000

w1: 1000×100

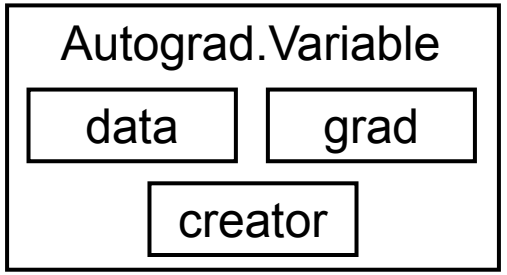
$$ReLU(x) = \begin{cases} x, & if\ x > 0 \\ 0, & if\ x \leq 0 \end{cases}$$

w2: 100×10

y: 64×10

PyTorch: Autograd

A PyTorch Variable is a node in a computational graph



x.data is tensor

x.grad is a Variable of gradients

x.grad.data is a Tensor of gradients

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)

learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()

    if w1.grad: w1.grad.data.zero_()
    if w2.grad: w2.grad.data.zero_()
    loss.backward()  compute gradient

    w1.data -= learning_rate * w1.grad.data  apply gradient
    w2.data -= learning_rate * w2.grad.data
```

PyTorch: Autograd

We will not want gradients with respect to data

Do want gradients with respect to weights

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)

learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()

    if w1.grad: w1.grad.data.zero_()
    if w2.grad: w2.grad.data.zero_()
    loss.backward()

    w1.data -= learning_rate * w1.grad.data
    w2.data -= learning_rate * w2.grad.data
```

PyTorch: Autograd

Forward pass looks exactly the same as the Tensor version, but everything is a variable now

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)

learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()

    if w1.grad: w1.grad.data.zero_()
    if w2.grad: w2.grad.data.zero_()
    loss.backward()

    w1.data -= learning_rate * w1.grad.data
    w2.data -= learning_rate * w2.grad.data
```

PyTorch: nn

Higher-level wrapper for working with neural nets

Similar to Keras and friends … but only one, and it's good

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)

    model.zero_grad()
    loss.backward()

    for param in model.parameters():
        param.data -= learning_rate * param.grad.data
```

PyTorch: nn

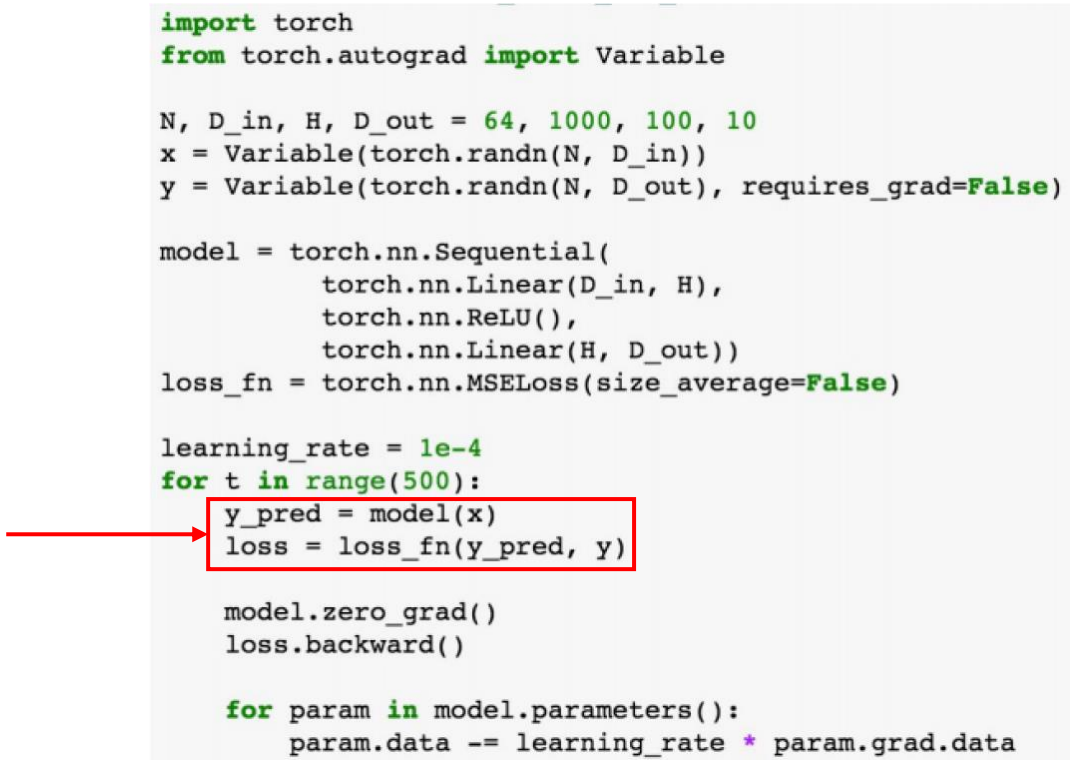
Define our model as a sequence of layers

nn also defines common loss functions

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)

    model.zero_grad()
    loss.backward()

    for param in model.parameters():
        param.data -= learning_rate * param.grad.data
```

PyTorch: nn

Forward pass:
feed data to model, and
prediction to loss function



```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)

    model.zero_grad()
    loss.backward()

    for param in model.parameters():
        param.data -= learning_rate * param.grad.data
```

PyTorch: nn

Backward pass:
compute all gradients

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
    model.zero_grad()
    loss.backward()

    for param in model.parameters():
        param.data -= learning_rate * param.grad.data
```

optimizer

PyTorch: optim

Use an optimizer for different update rules

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
optimizer = torch.optim.Adam(model.parameters(),
                             lr=learning_rate)
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)

    optimizer.zero_grad()
    loss.backward()

    optimizer.step()
```

PyTorch: optim

```
import torch
from torch.autograd import Variable

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = torch.nn.Sequential(
          torch.nn.Linear(D_in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
optimizer = torch.optim.Adam(model.parameters(),
                             lr=learning_rate)
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)

    optimizer.zero_grad()
    loss.backward()

    optimizer.step()
```

Update all parameters after computing gradients

PyTorch: nn Define new Modules

A PyTorch Module is a neural net layer: it inputs and outputs Variables

Modules can contain weights (as Variables) or other Modules

You can define your own Modules using autograd

Define our whole model as a single Module

```
import torch
from torch.autograd import Variable

class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)

    def forward(self, x):
        h_relu = self.linear1(x).clamp(min=0)
        y_pred = self.linear2(h_relu)
        return y_pred

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = TwoLayerNet(D_in, H, D_out)

criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)

    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

PyTorch: nn Define new Modules

Initializer sets up two children
(Modules can contain modules)

```
import torch
from torch.autograd import Variable

class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)

    def forward(self, x):
        h_relu = self.linear1(x).clamp(min=0)
        y_pred = self.linear2(h_relu)
        return y_pred

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = TwoLayerNet(D_in, H, D_out)

criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)

    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

PyTorch: nn Define new Modules

Define forward pass using child modules and autograd ops on Variables

No need to define backward – autograd will handle it

```
import torch
from torch.autograd import Variable

class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)

    def forward(self, x):
        h_relu = self.linear1(x).clamp(min=0)
        y_pred = self.linear2(h_relu)
        return y_pred

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = TwoLayerNet(D_in, H, D_out)

criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)

    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

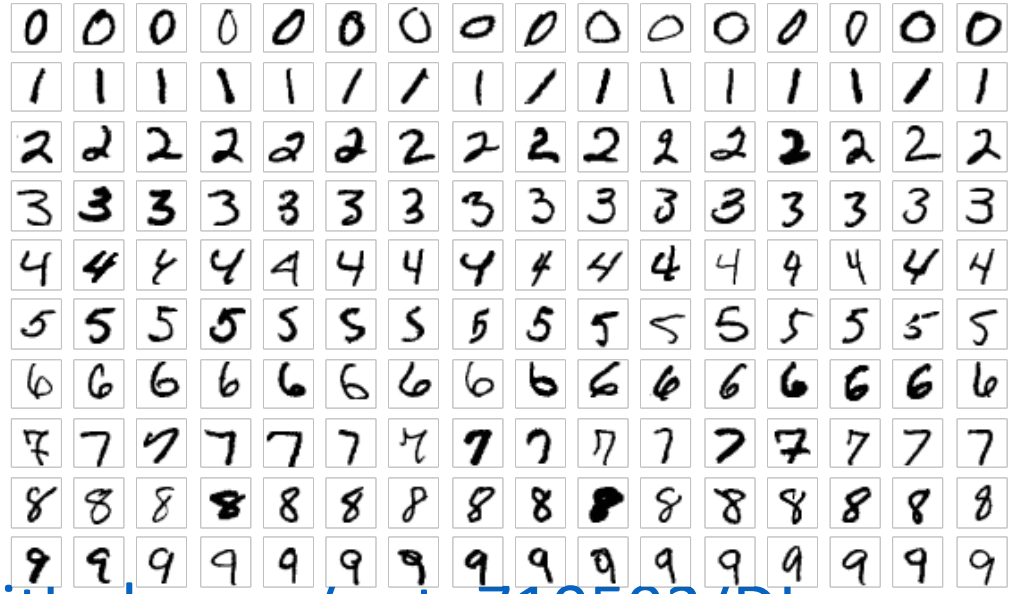
PyTorch: nn Define new Modules

Construct and train an instance of our model

```
import torch
from torch.autograd import Variable

class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)

    def forward(self, x):
        h_relu = self.linear1(x).clamp(min=0)
        y_pred = self.linear2(h_relu)
        return y_pred

N, D_in, H, D_out = 64, 1000, 100, 10

x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

model = TwoLayerNet(D_in, H, D_out)

criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)

    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

Application

- MNIST example for PyTorch



- git clone https://github.com/pete710592/DLcourse_NCTU.git
- CNN_MNIST_pytorch.py

Build and train a CNN classifier

- Data Loader
- Define Network
- Define Optimizer/Loss function
- Learning rate scheduling
- Training
- Testing
- Run and Save model

Data Loader

- PyTorch offers data loaders for popular dataset

The following datasets are available:

Datasets

- MNIST
- COCO
  - Captions
  - Detection
- LSUN
- ImageFolder
- Imagenet-12
- CIFAR
- STL10
- SVHN
- PhotoTour

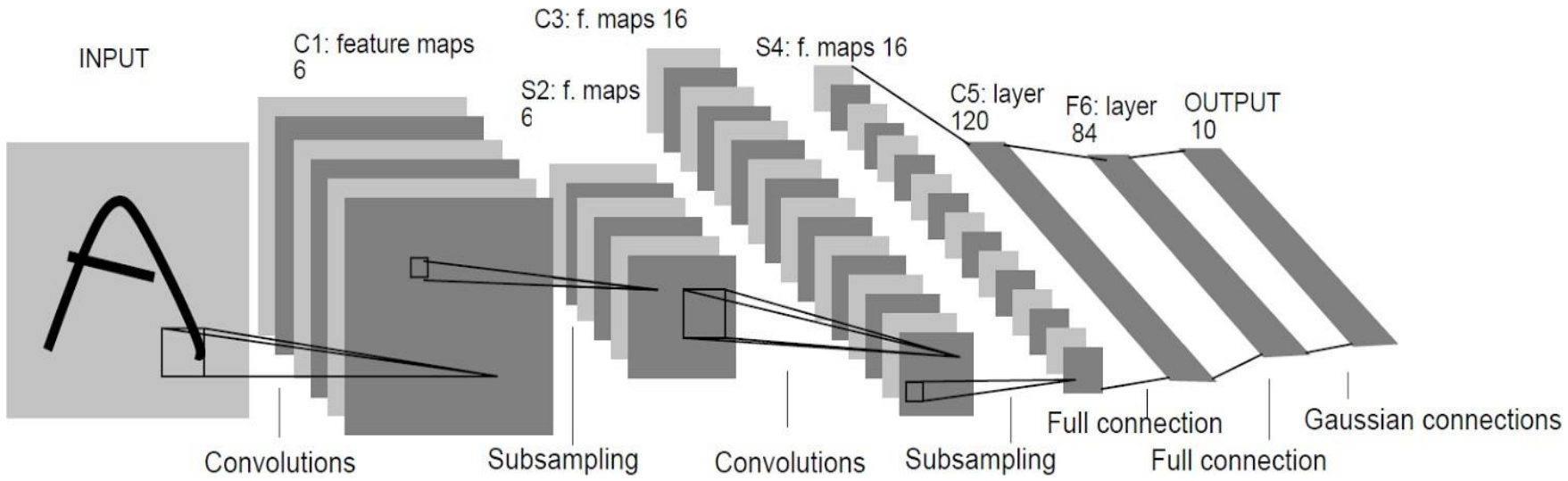
Data Loader

```
import torch
from torchvision import datasets, transforms

# Dataloader
train_loader = torch.utils.data.DataLoader(
    datasets.MNIST('../data', train=True, download=True,
                   transform=transforms.Compose([
                       transforms.ToTensor(),
                       transforms.Normalize((0.1307,), (0.3081,))
                   ])),
    batch_size=args.batch_size, shuffle=True,num_workers = 2)

test_loader = torch.utils.data.DataLoader(
    datasets.MNIST('../data', train=False, transform=transforms.Compose([
                       transforms.ToTensor(),
                       transforms.Normalize((0.1307,), (0.3081,))
                   ])),
    batch_size=args.batch_size, shuffle=True,num_workers = 2)
```

https://pytorch.org/docs/stable/torchvision/transforms.html

Define Network

- LeNet



Define Network

```
#Define Network, we implement LeNet here
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 6, kernel_size=(5,5),stride=1, padding=0)
        self.conv2 = nn.Conv2d(6, 16, kernel_size=(5,5),stride=1, padding=0)
        self.fc1 = nn.Linear(16*4*4, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)

    def forward(self, x):
        out = F.relu(self.conv1(x))
        out = F.max_pool2d(out, 2)
        out = F.relu(self.conv2(out))
        out = F.max_pool2d(out, 2)
        out = out.view(out.size(0), -1) #flatten
        out = F.relu(self.fc1(out))
        out = F.relu(self.fc2(out))
        out = self.fc3(out)
        return out

model = Net()
if args.cuda:
    model.cuda()
```

Define Optimizer/Loss function

- Cross Entropy Loss
- Stochastic Gradient Descent

```
#define optimizer/loss function
Loss = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), lr=args.lr, momentum=args.momentum)
```

Learning rate scheduling

- 20 epochs
- LR decay at 10 and 15 epoch

```
#learning rate scheduling
def adjust_learning_rate(optimizer, epoch):

    if epoch < 10:
        lr = 0.01
    elif epoch < 15:
        lr = 0.001
    else:
        lr = 0.0001

    for param_group in optimizer.param_groups:
        param_group['lr'] = lr
```

Training

```
#training function
def train(epoch):
    model.train()
    adjust_learning_rate(optimizer, epoch)

    for batch_idx, (data, target) in enumerate(train_loader):
        if args.cuda:
            data, target = data.cuda(), target.cuda()
        data, target = Variable(data), Variable(target)
        optimizer.zero_grad()
        output = model(data)
        loss = Loss(output, target)
        loss.backward()
        optimizer.step()
        print('Train Epoch: {} [{}/{} ({:.0f}%)]\tLoss: {:.6f}'.format(
                epoch, batch_idx * len(data), len(train_loader.dataset),
                100. * batch_idx / len(train_loader), loss.data[0]))
```

Set model to training mode

Clean gradient

Backward gradient Update weight

Testing

```
#Testing function
def test(epoch):
    model.eval()
    test_loss = 0
    correct = 0
    for batch_idx, (data, target) in enumerate(test_loader):
        if args.cuda:
            data, target = data.cuda(), target.cuda()
        data, target = Variable(data, volatile=True), Variable(target)
        output = model(data)
        test_loss += Loss(output, target).data[0]
        pred = output.data.max(1)[1] # get the index of the max log-probability
        correct += pred.eq(target.data).cpu().sum()

    test_loss = test_loss
    test_loss /= len(test_loader) # loss function already averages over batch size
    print('\nTest set: Average loss: {:.4f}, Accuracy: {}/{} ({:.0f}%)\n'.format(
        test_loss, correct, len(test_loader.dataset),
        100. * correct / len(test_loader.dataset)))
```

Run and Save model

```
#run and save model
for epoch in range(1, args.epochs + 1):
    train(epoch)
    test(epoch)
    savefilename = 'LeNet_'+str(epoch)+'.tar'
    torch.save({
            'epoch': epoch,
            'state_dict': model.state_dict(),
        }, savefilename)
```

Exercise

- Deeper: add more convolution layer
  - insert two 3x3 conv layer between conv1 and conv2 (stride=1,pad=1)
  - Hint: define new conv layer, and forward
  - Notice the *spatial* dimension
- Wider: add more neuron
  - Make your net 2x wider
  - Notice the *in/out* dimension
- Other Optimizer
  - Try Adam/RMSprop
- More epochs, New learning rate schedule, ...

- 在 Jupyter notebook 中寫下註解，會透過註解進行評分。

Rules

- 請勿抄作業，抄襲一律 0 分計算。
- 將 Jupyter notebook 打包成 zip 檔上傳至 到 e3 數位教學平台，檔名為學號。
- 繳交期限: 2021/10/11 (一) 23:59。
- 作業格式、檔案未依照規定分數 x 0.5。
- 如有任何問題可使用 e3 或者 mail 助教，連假不受理。
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