HISTORY OF MICROPROCESSORS

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Introduction

- Fairchild Semiconductors (founded in 1957) invented the first IC in 1959.
- In 1968, Robert Noyce, Gordan Moore, Andrew Grove resigned from Fairchild Semiconductors.
- They founded their own company Intel (Integrated Electronics).
- Intel grown from 3 man start-up in 1968

4-BIT MICROPROCESSORS

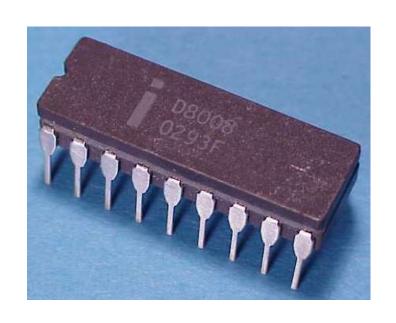


- Introduced in 1971.
- It was the first microprocessor by Intel.
- It was a 4-bit μP.
- Its clock speed was 740KHz.
- It had 2,300 transistors.
- It could execute around 60,000 instructions per second.



- ▶ Introduced in 1974.
- > It was also 4-bit μP.

8-BIT MICROPROCESSORS



- Introduced in 1972.
- It was first 8-bit μP.
- Its clock speed was 500 KHz.
- Could execute 50,000 instructions per second.

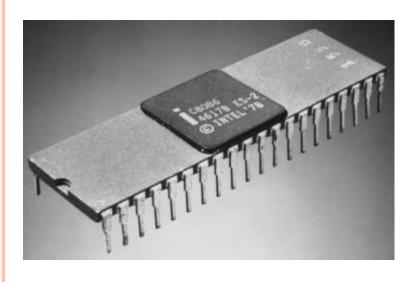


- Introduced in 1974.
- It was also 8-bit μP.
- Its clock speed was 2 MHz.
- It had 6,000 transistors.
- Was 10 times faster than 8008.
- Could execute 5,00,000 instructions per second.



- Introduced in 1976.
- It was also 8-bit μP.
- Its clock speed was 3 MHz.
- Its data bus is 8-bit and address bus is 16-bit.
- It had 6,500 transistors.
- Could execute 7,69,230 instructions per second.
- It could access 64 KB of memory.
- It had 246 instructions.

16-BIT MICROPROCESSORS



- Introduced in 1978.
- It was first 16-bit μP.
- Its clock speed is 4.77 MHz, 8 MHz and 10 MHz, depending on the version.
- Its data bus is 16-bit and address bus is 20-bit.
- It had 29,000 transistors.
- Could execute 2.5 million instructions per second.
- It could access 1 MB of memory.
- It had 22,000 instructions.
- It had *Multiply* and *Divide* instructions.



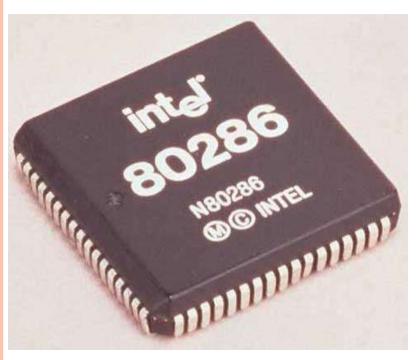
- Introduced in 1979.
- It was also 16-bit μP.
- It was created as a cheaper version of Intel's 8086.
- It was a 16-bit processor with an 8-bit external bus.

INTEL 80186 & 80188



- Introduced in 1982.
- They were 16-bit μPs.
- Clock speed was 6 MHz.





- Introduced in 1982.
- It was 16-bit μP.
- Its clock speed was 8 MHz.

32-BIT MICROPROCESSORS



- Introduced in 1986.
- It was first 32-bit μP.
- Its data bus is 32-bit and address bus is 32-bit.
- It could address 4 GB of memory.



- Introduced in 1989.
- It was also 32-bit μP.
- It had 1.2 million transistors.
- Its clock speed varied from 16 MHz to 100 MHz depending upon the various versions.

INTEL PENTIUM



- Introduced in 1993.
- It was also 32-bit μP.
- It was originally named 80586.
- Its clock speed was 66 MHz.

INTEL PENTIUM PRO



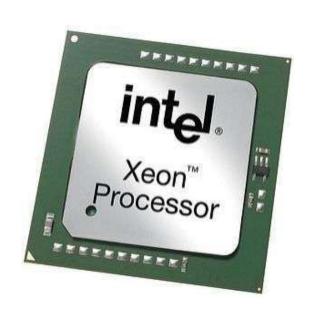
- > Introduced in 1995.
- It was also 32-bit μP.

INTEL PENTIUM II

- > Introduced in 1997.
- > It was also 32-bit μP.

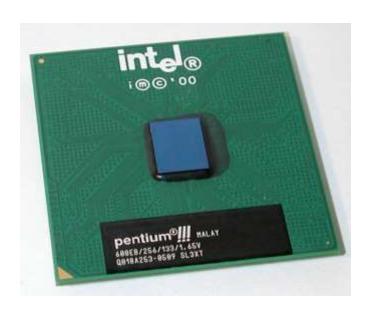


INTEL PENTIUM II XEON



- > Introduced in 1998.
- > It was also 32-bit μP.

INTEL PENTIUM III



- > Introduced in 1999.
- > It was also 32-bit μP.

INTEL PENTIUM IV



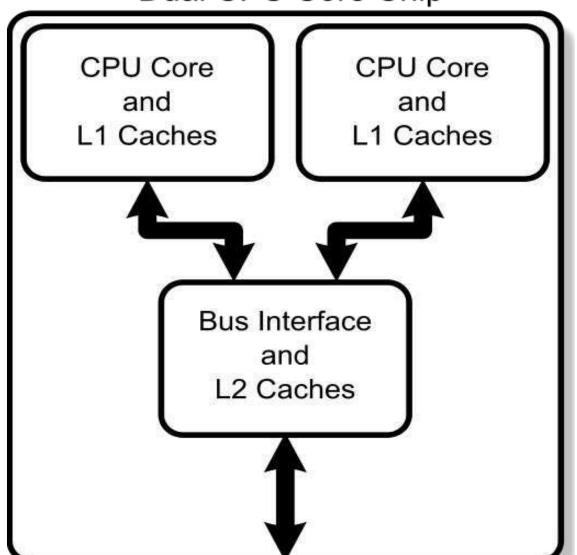
- Introduced in 2000.
- It was also 32-bit μP.

INTEL DUAL CORE



- Introduced in 2006.
- > It is 32-bit or 64-bit μ P.
- It has two cores.
- Both the cores have there own internal bus and L1 cache, but share the external bus and L2 cache

Dual CPU Core Chip



64-BIT MICROPROCESSORS



- > Introduced in 2006.
- \triangleright It is a 64-bit μ P.



- ▶ Introduced in 2008.
- \triangleright It is a 64-bit μ P.



- > Introduced in 2009.
- \triangleright It is a 64-bit μ P.



- Introduced in 2010.
- ▶ It is a 64-bit µP.

The salient features of 8085 microprocessor.

8085 Microprocessor

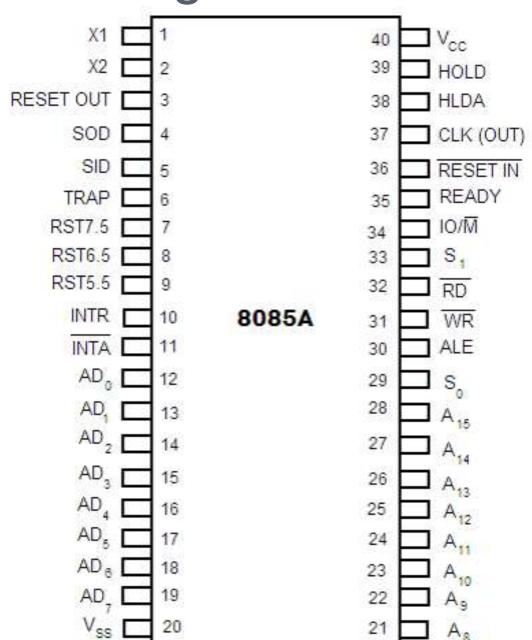
The salient features of 8085 µp are:

- 1. It is a 8 bit microprocessor.
- 2. It has 16 bit address bus and hence can address up to $2^{16} = 65536$ bytes (64KB) memory locations through A0-A15.
- 3. The first 8 lines of address bus and 8 lines of data bus are multiplexed AD0 AD7.
- 4. Data bus is a group of 8 lines D0 D7.
- 5. It supports 5 hardware interrupt and 8 software interrupt.

8085 Microprocessor

- 6. A 16 bit program counter (PC)
- 7. A 16 bit stack pointer (SP)
- 8. Six 8-bit general purpose register arranged in pairs: BC,DE, HL.
- 9. It requires a signal +5V power supply
- 10.Maximum Clock Frequency is 3MHz and Minimum Clock Frequency is 500kHz

Pin Diagram of 8085



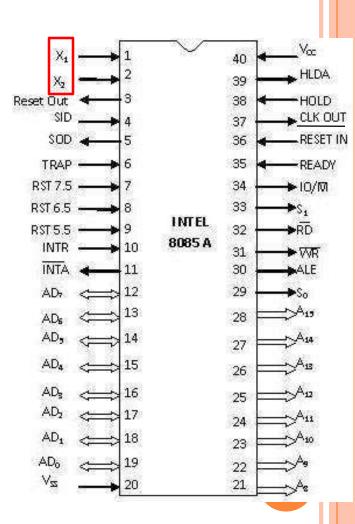
$X_1 \& X_2$

Pin 1 and Pin 2 (Input)

These are also called Crystal Input Pins.

≥ 8085 can generate clock signals internally.

To generate clock signals internally, 8085 requires external inputs from X₁ and X₂.

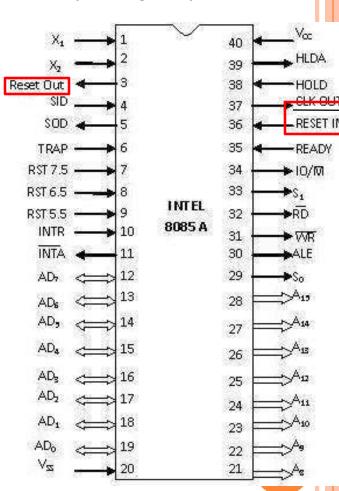


RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

EXERCITIN:

- It is used to reset the microprocessor.
- It is active low signal.
- When the signal on this pin is low for at least 3 clocking cycles, it forces the microprocessor to reset itself.

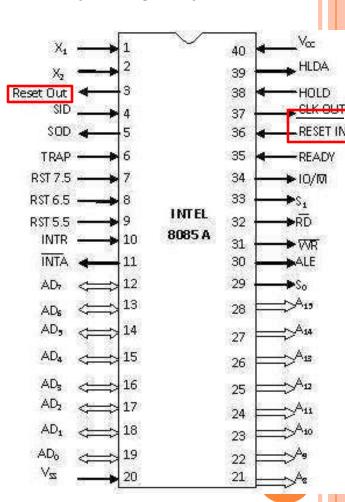


RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

Resetting the microprocessor means:

- Clearing the PC and IR.
- Disabling all interrupts (except TRAP).
- Disabling the SOD pin.
- All the buses (data, address, control) are *tri*stated.
- Gives HIGH output to RESET OUT pin.

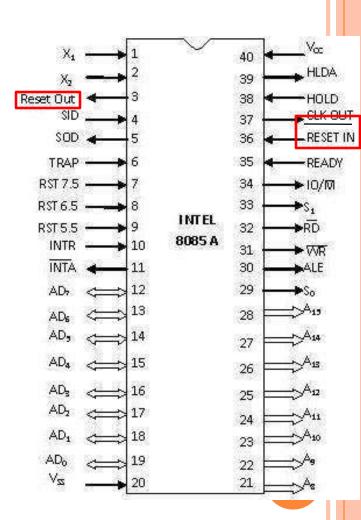


RESET IN and RESET OUT

Pin 36 (Input) and Pin 3 (Output)

RESET OUT:

- It is used to reset the peripheral devices and other ICs on the circuit.
- It is an output signal.
- It is an active high signal.
- The output on this pin goes high whenever RESET IN is given low signal.
- The output remains high as long as RESET IN is kept low.

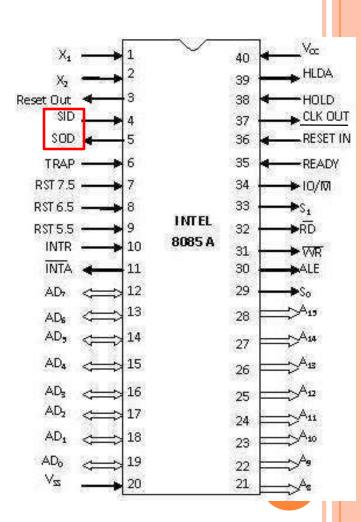


SID and SOD

Pin 4 (Input) and Pin 5 (Output)

SID (Serial Input Data):

- It takes 1 bit input from serial port of 8085.
- Stores the bit at the 8th position (MSB) of the Accumulator.
- RIM (Read Interrupt Mask) instruction is used to transfer the bit.



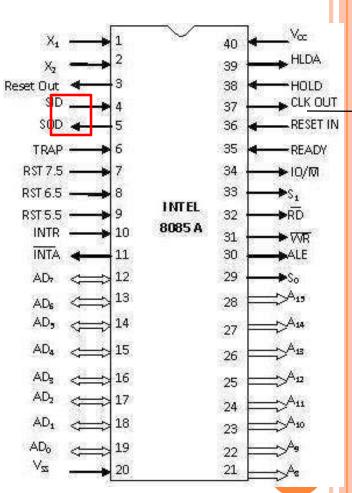
SID and SOD

Pin 4 (Input) and Pin 5 (Output)

SOD (Serial Output Data):

 It takes 1 bit from Accumulator to serial port of 8085.

- Takes the bit from the 8th position (MSB) of the Accumulator.
- SIM (Set Interrupt Mask) instruction is used to transfer the bit.



Interrupt Pins Interrupt Pins

∞ Interrupt:

- It means interrupting the normal execution of the microprocessor.
- When microprocessor receives interrupt signal, it discontinues whatever it was executing.
- It starts executing new program indicated by the interrupt signal.
- Interrupt signals are generated by external peripheral devices.
- After execution of the new program, microprocessor goes back to the previous program.

Sequence of Steps Whenever There Sequence of Steps Whenever There

- Microprocessoiscompletes respectation of current instruction of the program.
- » PC contents are stored in stack.
- >>> PC is loaded with address of the new program.
- After executing the new program, the microprocessor returns back to the previous program.
- It goes to the previous program by reading the top value of stack.

Five Hardware Interrupts in 8085

™TRAP

≈RST6.5