MTK: Mimetic Methods Toolkit

Generated by Doxygen 1.8.8

Mon Nov 23 2015 17:21:09

Contents

1	Intro	duction	1
	1.1	MTK Concerns	1
	1.2	MTK Flavors	1
	1.3	Contact, Support and Credits	2
	1.4	Acknowledgements and Contributions	2
2	Prog	gramming Tools	3
3	Lice	nsing and Modifications	5
4	Read	d Me File and Installation Instructions	7
5	Test	s and Test Architectures	11
6	Exar	nples	13
7	User	Manual, References and Theory	15
8	Todo	D List	17
9	Bug	List	19
10	Mod	ule Index	21
	10.1	Modules	21
11	Nam	espace Index	23
	11.1	Namespace List	23
12		s Index	25
	12.1	Class List	25
13	File	Index	27
	13.1	File List	27

iv CONTENTS

14	Mod	ule Doc	umentation	31
	14.1	Roots.		31
		14.1.1	Detailed Description	31
		14.1.2	Typedef Documentation	32
			14.1.2.1 Real	32
		14.1.3	Variable Documentation	32
			14.1.3.1 kCriticalOrderAccuracyDiv	32
			14.1.3.2 kCriticalOrderAccuracyGrad	32
			14.1.3.3 kDefaultMimeticThreshold	32
			14.1.3.4 kDefaultOrderAccuracy	32
			14.1.3.5 kDefaultTolerance	32
			14.1.3.6 kOne	32
			14.1.3.7 kTwo	32
			14.1.3.8 kZero	33
	14.2	Enume	erations	34
		14.2.1	Detailed Description	34
		14.2.2	Enumeration Type Documentation	34
			14.2.2.1 DirInterp	34
			14.2.2.2 FieldNature	34
			14.2.2.3 MatrixOrdering	
			14.2.2.4 MatrixStorage	35
	14.3		ion tools.	
		14.3.1	Detailed Description	36
	14.4	Data st	tructures	37
		14.4.1	Detailed Description	37
	14.5		ical methods	
		14.5.1	Detailed Description	38
	14.6			
			Detailed Description	
	14.7		c operators	
			Detailed Description	
		14.7.2	Typedef Documentation	
			14.7.2.1 CoefficientFunction2D	40
15	Nam	espace	Documentation	41
	15.1	mtk Na	mespace Reference	41
		15.1.1	Function Documentation	43

CONTENTS

			15.1.1.1	operator<<	43
			15.1.1.2	operator<<	43
			15.1.1.3	operator<<	44
			15.1.1.4	operator<<	44
			15.1.1.5	operator<<	44
			15.1.1.6	operator<<	44
			15.1.1.7	operator<<	45
			15.1.1.8	saxpy	45
			15.1.1.9	sgels	45
			15.1.1.10	sgemm	46
			15.1.1.11	sgemv	47
			15.1.1.12	sgeqrf	47
			15.1.1.13	sgesv	47
			15.1.1.14	snrm2	48
			15.1.1.15	$sormqr_\ \dots$	48
16	Close	o Doour	nentation		51
10				r1D Class Reference	
	10.1			Description	
				Function Documentation	
		10.1.2		ImposeOnGrid	
				ImposeOnLaplacianMatrix	
	16.2	mtk··B0		r2D Class Reference	
			•	Description	
				tor & Destructor Documentation	
				BCDescriptor2D	
				BCDescriptor2D	
				~BCDescriptor2D	
		16.2.3		- Function Documentation	
			16.2.3.1	highest_order_diff_east	57
			16.2.3.2	highest_order_diff_north	57
			16.2.3.3	highest_order_diff_south	58
			16.2.3.4	highest_order_diff_west	
			16.2.3.5	ImposeOnEastBoundaryNoSpace	
			16.2.3.6	ImposeOnEastBoundaryWithSpace	
			16.2.3.7	ImposeOnGrid	60
			16.2.3.8	ImposeOnLaplacianMatrix	62

vi CONTENTS

		16.2.3.9	ImposeOnNorthBoundaryNoSpace	 	63
		16.2.3.10	ImposeOnNorthBoundaryWithSpace	 	64
		16.2.3.11	ImposeOnSouthBoundaryNoSpace	 	65
		16.2.3.12	2 ImposeOnSouthBoundaryWithSpace	 	66
		16.2.3.13	B ImposeOnWestBoundaryNoSpace	 	67
		16.2.3.14	ImposeOnWestBoundaryWithSpace	 	68
		16.2.3.15	PushBackEastCoeff	 	69
		16.2.3.16	B PushBackNorthCoeff	 	69
		16.2.3.17	7 PushBackSouthCoeff	 	70
		16.2.3.18	B PushBackWestCoeff	 	70
		16.2.3.19	est_east_condition	 	71
		16.2.3.20	set_north_condition	 	71
		16.2.3.21	set_south_condition	 	72
		16.2.3.22	2 set_west_condition	 	72
	16.2.4	Member [Data Documentation	 	73
		16.2.4.1	east_coefficients	 	73
		16.2.4.2	east_condition	 	73
		16.2.4.3	generate_space	 	73
		16.2.4.4	highest_order_diff_east	 	73
		16.2.4.5	highest_order_diff_north	 	73
		16.2.4.6	highest_order_diff_south	 	73
		16.2.4.7	highest_order_diff_west	 	73
		16.2.4.8	north_coefficients	 	73
		16.2.4.9	north_condition	 	74
		16.2.4.10	osouth_coefficients	 	74
		16.2.4.11	south_condition	 	74
			2 west_coefficients		
		16.2.4.13	B west_condition	 	74
16.3	mtk::Bl	ASAdapte	er Class Reference	 	74
	16.3.1	Detailed [Description	 	75
	16.3.2	Member F	Function Documentation	 	75
		16.3.2.1	RealAXPY	 	75
		16.3.2.2	RealDenseMM	 	76
		16.3.2.3	RealDenseMV	 	77
		16.3.2.4	RealNRM2	 	79
		16.3.2.5	RelNorm2Error	 	80
16.4	mtk::De	enseMatrix	x Class Reference	 	80

CONTENTS vii

16.4.1	Detailed Description
16.4.2	Constructor & Destructor Documentation
	16.4.2.1 DenseMatrix
	16.4.2.2 DenseMatrix
	16.4.2.3 DenseMatrix
	16.4.2.4 DenseMatrix
	16.4.2.5 DenseMatrix
	16.4.2.6 ~DenseMatrix
16.4.3	Member Function Documentation
	16.4.3.1 data
	16.4.3.2 GetValue
	16.4.3.3 Kron
	16.4.3.4 matrix_properties
	16.4.3.5 num_cols
	16.4.3.6 num_rows
	16.4.3.7 operator=
	16.4.3.8 operator==
	16.4.3.9 OrderColMajor
	16.4.3.10 OrderRowMajor
	16.4.3.11 SetOrdering
	16.4.3.12 SetValue
	16.4.3.13 Transpose
	16.4.3.14 WriteToFile
16.4.4	Friends And Related Function Documentation
	16.4.4.1 operator <<
16.4.5	Member Data Documentation
	16.4.5.1 data
	16.4.5.2 matrix_properties
mtk::Div	v1D Class Reference
16.5.1	Detailed Description
16.5.2	Constructor & Destructor Documentation
	16.5.2.1 Div1D
	16.5.2.2 Div1D
	16.5.2.3 ~Div1D
16.5.3	Member Function Documentation
	16.5.3.1 AssembleOperator
	16.5.3.2 coeffs_interior
	16.4.2 16.4.3 16.4.3 mtk::Di [*] 16.5.1 16.5.2

viii CONTENTS

		16.5.3.3	ComputePreliminaryApproximations	12
		16.5.3.4	ComputeRationalBasisNullSpace)3
		16.5.3.5	ComputeStencilBoundaryGrid)4
		16.5.3.6	ComputeStencilInteriorGrid)4
		16.5.3.7	ComputeWeights)5
		16.5.3.8	ConstructDiv1D)6
		16.5.3.9	mim_bndy)6
		16.5.3.10	num_bndy_coeffs)7
		16.5.3.11	ReturnAsDenseMatrix)7
		16.5.3.12	weights_cbs	8(
		16.5.3.13	weights_crs	8(
	16.5.4	Friends A	nd Related Function Documentation	8(
		16.5.4.1	operator <<	8(
	16.5.5	Member I	Data Documentation	8(
		16.5.5.1	coeffs_interior	8(
		16.5.5.2	dim_null	8(
		16.5.5.3	divergence)9
		16.5.5.4	divergence_length)9
		16.5.5.5	mim_bndy)9
		16.5.5.6	mimetic_threshold)9
		16.5.5.7	minrow)9
		16.5.5.8	num_bndy_coeffs)9
		16.5.5.9	order_accuracy)9
		16.5.5.10	prem_apps)9
		16.5.5.11	rat_basis_null_space)9
		16.5.5.12	row)9
		16.5.5.13	weights_cbs)9
		16.5.5.14	weights_crs	0
16.6	mtk::Di	v2D Class	Reference	0
	16.6.1	Detailed [Description	2
	16.6.2	Construct	tor & Destructor Documentation	2
		16.6.2.1	Div2D	2
		16.6.2.2	Div2D	2
		16.6.2.3	~Div2D	2
	16.6.3	Member F	Function Documentation	3
		16.6.3.1	ConstructDiv2D	3
		16.6.3.2	ReturnAsDenseMatrix	3

CONTENTS ix

	16.6.4	Member Data Documentation
		16.6.4.1 divergence
		16.6.4.2 mimetic_threshold
		16.6.4.3 order_accuracy
16.7	mtk::Gl	LPKAdapter Class Reference
	16.7.1	Detailed Description
	16.7.2	Member Function Documentation
		16.7.2.1 SolveSimplexAndCompare
16.8	mtk::Gr	rad1D Class Reference
	16.8.1	Detailed Description
	16.8.2	Constructor & Destructor Documentation
		16.8.2.1 Grad1D
		16.8.2.2 Grad1D
		16.8.2.3 ~Grad1D121
	16.8.3	Member Function Documentation
		16.8.3.1 AssembleOperator
		16.8.3.2 coeffs_interior
		16.8.3.3 ComputePreliminaryApproximations
		16.8.3.4 ComputeRationalBasisNullSpace
		16.8.3.5 ComputeStencilBoundaryGrid
		16.8.3.6 ComputeStencilInteriorGrid
		16.8.3.7 ComputeWeights
		16.8.3.8 ConstructGrad1D
		16.8.3.9 mim_bndy
		16.8.3.10 num_bndy_coeffs
		16.8.3.11 ReturnAsDenseMatrix
		16.8.3.12 ReturnAsDenseMatrix
		16.8.3.13 ReturnAsDimensionlessDenseMatrix
		16.8.3.14 weights_cbs
		16.8.3.15 weights_crs
	16.8.4	Friends And Related Function Documentation
		16.8.4.1 operator <<
	16.8.5	Member Data Documentation
		16.8.5.1 coeffs_interior
		16.8.5.2 dim_null
		16.8.5.3 gradient
		16.8.5.4 gradient_length

CONTENTS

	16.8.5.5 mim_bndy
	16.8.5.6 mimetic_threshold
	16.8.5.7 minrow
	16.8.5.8 num_bndy_approxs
	16.8.5.9 num_bndy_coeffs
	16.8.5.10 order_accuracy
	16.8.5.11 prem_apps
	16.8.5.12 rat_basis_null_space
	16.8.5.13 row
	16.8.5.14 weights_cbs
	16.8.5.15 weights_crs
16.9 mtk:	Grad2D Class Reference
16.9	.1 Detailed Description
16.9	2 Constructor & Destructor Documentation
	16.9.2.1 Grad2D
	16.9.2.2 Grad2D
	16.9.2.3 ∼Grad2D
16.9	.3 Member Function Documentation
	16.9.3.1 ConstructGrad2D
	16.9.3.2 ReturnAsDenseMatrix
16.9	4 Member Data Documentation
	16.9.4.1 gradient
	16.9.4.2 mimetic_threshold
	16.9.4.3 order_accuracy
16.10mtk:	Interp1D Class Reference
16.1	0.1 Detailed Description
16.1	0.2 Constructor & Destructor Documentation
	16.10.2.1 Interp1D
	16.10.2.2 Interp1D
	16.10.2.3 ~Interp1D
16.1	0.3 Member Function Documentation
	16.10.3.1 coeffs_interior
	16.10.3.2 ConstructInterp1D
	16.10.3.3 ReturnAsDenseMatrix
16.1	0.4 Friends And Related Function Documentation
	16.10.4.1 operator <<
16.1	0.5 Member Data Documentation

CONTENTS xi

16.10.5.1 coeffs_interior
16.10.5.2 dir_interp
16.10.5.3 order_accuracy
16.11 mtk::Interp2D Class Reference
16.11.1 Detailed Description
16.11.2 Constructor & Destructor Documentation
16.11.2.1 Interp2D
16.11.2.2 Interp2D
16.11.2.3 ~Interp2D
16.11.3 Member Function Documentation
16.11.3.1 ConstructInterp2D
16.11.3.2 ReturnAsDenseMatrix
16.11.4 Member Data Documentation
16.11.4.1 interpolator
16.11.4.2 mimetic_threshold
16.11.4.3 order_accuracy
16.12mtk::Lap1D Class Reference
16.12.1 Detailed Description
16.12.2 Constructor & Destructor Documentation
16.12.2.1 Lap1D
16.12.2.2 Lap1D
16.12.2.3 ∼Lap1D
16.12.3 Member Function Documentation
16.12.3.1 ConstructLap1D
16.12.3.2 data
16.12.3.3 ReturnAsDenseMatrix
16.12.4 Friends And Related Function Documentation
16.12.4.1 operator<<
16.12.5 Member Data Documentation
16.12.5.1 laplacian
16.12.5.2 laplacian_length
16.12.5.3 mimetic_threshold
16.12.5.4 order_accuracy
16.13mtk::Lap2D Class Reference
16.13.1 Detailed Description
16.13.2 Constructor & Destructor Documentation
16.13.2.1 Lap2D

xii CONTENTS

CONTENTS xiii

16.15.3.13num_rows	162
16.15.3.14num_values	163
16.15.3.15num_zero	163
16.15.3.16ordering	163
16.15.3.17rel_density	164
16.15.3.18rel_sparsity	164
16.15.3.19set_num_cols	164
16.15.3.20set_num_null	165
16.15.3.21set_num_rows	166
16.15.3.22set_num_zero	166
16.15.3.23set_ordering	167
16.15.3.24set_storage	168
16.15.3.25storage	168
16.15.4 Member Data Documentation	169
16.15.4.1 abs_density	169
16.15.4.2 abs_sparsity	169
16.15.4.3 bandwidth	169
16.15.4.4 kl	169
16.15.4.5 ku	169
16.15.4.6 ld	169
16.15.4.7 num_cols	169
16.15.4.8 num_non_null	170
16.15.4.9 num_non_zero	
16.15.4.10num_null	170
16.15.4.11num_rows	170
16.15.4.12hum_values	170
16.15.4.13num_zero	170
16.15.4.14ordering	170
16.15.4.15rel_density	170
16.15.4.16rel_sparsity	170
16.15.4.17storage	170
16.16mtk::Quad1D Class Reference	
16.16.1 Detailed Description	172
16.16.2 Constructor & Destructor Documentation	172
16.16.2.1 Quad1D	
16.16.2.2 Quad1D	
16.16.2.3 ~Quad1D	173

xiv CONTENTS

16.16.3 Member Function Documentation
16.16.3.1 degree_approximation
16.16.3.2 Integrate
16.16.3.3 weights
16.16.4 Friends And Related Function Documentation
16.16.4.1 operator <<
16.16.5 Member Data Documentation
16.16.5.1 degree_approximation
16.16.5.2 weights
16.17mtk::Tools Class Reference
16.17.1 Detailed Description
16.17.2 Member Function Documentation
16.17.2.1 Assert
16.17.2.2 BeginUnitTestNo
16.17.2.3 EndUnitTestNo
16.17.2.4 Prevent
16.17.3 Member Data Documentation
16.17.3.1 begin_time
16.17.3.2 duration
16.17.3.3 test_number
16.18mtk::UniStgGrid1D Class Reference
16.18.1 Detailed Description
16.18.2 Constructor & Destructor Documentation
16.18.2.1 UniStgGrid1D
16.18.2.2 UniStgGrid1D
16.18.2.3 UniStgGrid1D
16.18.2.4 ~UniStgGrid1D
16.18.3 Member Function Documentation
16.18.3.1 BindScalarField
16.18.3.2 BindVectorField
16.18.3.3 delta_x
16.18.3.4 discrete_domain_x
16.18.3.5 discrete_field_u
16.18.3.6 east_bndy_x
16.18.3.7 num_cells_x
16.18.3.8 west_bndy_x
16.18.3.9 WriteToFile

CONTENTS xv

16.18.4 Friends And Related Function Documentation	. 185
16.18.4.1 operator<<	. 185
16.18.5 Member Data Documentation	. 185
16.18.5.1 delta_x	. 185
16.18.5.2 discrete_domain_x	. 185
16.18.5.3 discrete_field_u	. 185
16.18.5.4 east_bndy_x	. 186
16.18.5.5 nature	. 186
16.18.5.6 num_cells_x	. 186
16.18.5.7 west_bndy_x	. 186
16.19mtk::UniStgGrid2D Class Reference	. 186
16.19.1 Detailed Description	. 189
16.19.2 Constructor & Destructor Documentation	. 190
16.19.2.1 UniStgGrid2D	. 190
16.19.2.2 UniStgGrid2D	. 190
16.19.2.3 UniStgGrid2D	. 190
16.19.2.4 ~UniStgGrid2D	. 190
16.19.3 Member Function Documentation	. 191
16.19.3.1 BindScalarField	. 191
16.19.3.2 BindVectorField	. 191
16.19.3.3 BindVectorFieldPComponent	. 192
16.19.3.4 BindVectorFieldQComponent	. 192
16.19.3.5 Bound	. 193
16.19.3.6 delta_x	. 193
16.19.3.7 delta_y	193
16.19.3.8 discrete_domain_x	. 194
16.19.3.9 discrete_domain_y	. 195
16.19.3.10discrete_field	. 195
16.19.3.11east_bndy	. 195
16.19.3.12nature	196
16.19.3.13north_bndy	. 197
16.19.3.14num_cells_x	. 197
16.19.3.15num_cells_y	. 198
16.19.3.16south_bndy	. 199
16.19.3.17west_bndy	200
16.19.3.18WriteToFile	201
16.19.4 Friends And Related Function Documentation	201

xvi CONTENTS

			16.19.4.1 operator <<	01
		16.19.5	Member Data Documentation	02
			16.19.5.1 delta_x	02
			16.19.5.2 delta_y	02
			16.19.5.3 discrete_domain_x	02
			16.19.5.4 discrete_domain_y	02
			16.19.5.5 discrete_field	02
			16.19.5.6 east_bndy	02
			16.19.5.7 nature	02
			16.19.5.8 north_bndy	02
			16.19.5.9 num_cells_x	02
			16.19.5.10num_cells_y	02
			16.19.5.11south_bndy	03
			16.19.5.12west_bndy	03
	En .	.		^-
17				05
	17.1		es/minimalistic_poisson_1d/minimalistic_poisson_1d.cc File Reference	
			Detailed Description	
		17.1.2	17.1.2.1 main	
	17.0	minima	listic_poisson_1d.cc	
			es/poisson_1d/poisson_1d.cc File Reference	
	17.3	•	Detailed Description	
			Function Documentation	
		17.3.2	17.3.2.1 main	
	17.4	poissor	1_1d.cc	
			/mtk.h File Reference	
	17.5		Detailed Description	
	17.6			
			/mtk_bc_descriptor_1d.h File Reference	
	17.7		Detailed Description	
	170		_descriptor_1d.h	
			/mtk_bc_descriptor_2d.h File Reference	
	17.9			
	47.44		Detailed Description	
			descriptor_2d.h	
	17.1		/mtk_blas_adapter.h File Reference	
		17.11.1	Detailed Description	22

CONTENTS xvii

17.12mtk_blas_adapter.h
17.13include/mtk_dense_matrix.h File Reference
17.13.1 Detailed Description
17.14mtk_dense_matrix.h
17.15include/mtk_div_1d.h File Reference
17.15.1 Detailed Description
17.16mtk_div_1d.h
17.17include/mtk_div_2d.h File Reference
17.17.1 Detailed Description
17.18mtk_div_2d.h
17.19include/mtk_enums.h File Reference
17.19.1 Detailed Description
17.20mtk_enums.h
17.21 include/mtk_glpk_adapter.h File Reference
17.21.1 Detailed Description
17.22mtk_glpk_adapter.h
17.23include/mtk_grad_1d.h File Reference
17.23.1 Detailed Description
17.24mtk_grad_1d.h
17.25include/mtk_grad_2d.h File Reference
17.25.1 Detailed Description
17.26mtk_grad_2d.h
17.27include/mtk_interp_1d.h File Reference
17.27.1 Detailed Description
17.28mtk_interp_1d.h
17.29include/mtk_interp_2d.h File Reference
17.29.1 Detailed Description
17.30mtk_interp_2d.h
17.31include/mtk_lap_1d.h File Reference
17.31.1 Detailed Description
17.32mtk_lap_1d.h
17.33include/mtk_lap_2d.h File Reference
17.33.1 Detailed Description
17.34mtk_lap_2d.h
17.35include/mtk_lapack_adapter.h File Reference
17.35.1 Detailed Description
17.36mtk_lapack_adapter.h

xviii CONTENTS

17.37include/mtk_matrix.h File Reference
17.37.1 Detailed Description
17.38mtk_matrix.h
17.39include/mtk_quad_1d.h File Reference
17.39.1 Detailed Description
17.40mtk_quad_1d.h
17.41 include/mtk_roots.h File Reference
17.41.1 Detailed Description
17.42mtk_roots.h
17.43include/mtk_tools.h File Reference
17.43.1 Detailed Description
17.44mtk_tools.h
17.45include/mtk_uni_stg_grid_1d.h File Reference
17.45.1 Detailed Description
17.46mtk_uni_stg_grid_1d.h
17.47include/mtk_uni_stg_grid_2d.h File Reference
17.47.1 Detailed Description
17.48mtk_uni_stg_grid_2d.h
17.49Makefile.inc File Reference
17.50Makefile.inc
17.51README.md File Reference
17.52README.md
17.53src/mtk_bc_descriptor_1d.cc File Reference
17.53.1 Detailed Description
17.54mtk_bc_descriptor_1d.cc
17.55src/mtk_bc_descriptor_2d.cc File Reference
17.55.1 Detailed Description
17.56mtk_bc_descriptor_2d.cc
17.57src/mtk_blas_adapter.cc File Reference
17.57.1 Detailed Description
17.58mtk_blas_adapter.cc
17.59src/mtk_dense_matrix.cc File Reference
17.60mtk_dense_matrix.cc
17.61src/mtk_div_1d.cc File Reference
17.61.1 Detailed Description
17.62mtk_div_1d.cc
17.63src/mtk_div_2d.cc File Reference

CONTENTS xix

17.63.1 Detailed Description
17.64mtk_div_2d.cc
17.65src/mtk_glpk_adapter.cc File Reference
17.65.1 Detailed Description
17.66mtk_glpk_adapter.cc
17.67src/mtk_grad_1d.cc File Reference
17.67.1 Detailed Description
17.68mtk_grad_1d.cc
17.69src/mtk_grad_2d.cc File Reference
17.69.1 Detailed Description
17.70mtk_grad_2d.cc
17.71src/mtk_interp_1d.cc File Reference
17.71.1 Detailed Description
17.72mtk_interp_1d.cc
17.73src/mtk_lap_1d.cc File Reference
17.73.1 Detailed Description
17.74mtk_lap_1d.cc
17.75src/mtk_lap_2d.cc File Reference
17.75.1 Detailed Description
17.76mtk_lap_2d.cc
17.77src/mtk_lapack_adapter.cc File Reference
17.77.1 Detailed Description
17.78mtk_lapack_adapter.cc
17.79src/mtk_matrix.cc File Reference
17.79.1 Detailed Description
17.80mtk_matrix.cc
17.81src/mtk_tools.cc File Reference
17.81.1 Detailed Description
17.82mtk_tools.cc
17.83src/mtk_uni_stg_grid_1d.cc File Reference
17.83.1 Detailed Description
17.84mtk_uni_stg_grid_1d.cc
17.85src/mtk_uni_stg_grid_2d.cc File Reference
17.85.1 Detailed Description
17.86mtk_uni_stg_grid_2d.cc
17.87tests/mtk_bc_descriptor_2d_test.cc File Reference
17.87.1 Detailed Description

XX CONTENTS

17.87.2 Function Documentation
17.87.2.1 main
17.88mtk_bc_descriptor_2d_test.cc
17.89tests/mtk_blas_adapter_test.cc File Reference
17.89.1 Detailed Description
17.89.2 Function Documentation
17.89.2.1 main
17.90mtk_blas_adapter_test.cc
17.91tests/mtk_dense_matrix_test.cc File Reference
17.91.1 Detailed Description
17.91.2 Function Documentation
17.91.2.1 main
17.92mtk_dense_matrix_test.cc
17.93tests/mtk_div_1d_test.cc File Reference
17.93.1 Detailed Description
17.93.2 Function Documentation
17.93.2.1 main
17.94mtk_div_1d_test.cc
17.95tests/mtk_div_2d_test.cc File Reference
17.95.1 Detailed Description
17.95.2 Function Documentation
17.95.2.1 main
17.96mtk_div_2d_test.cc
17.97tests/mtk_glpk_adapter_test.cc File Reference
17.97.1 Detailed Description
17.97.2 Function Documentation
17.97.2.1 main
17.98mtk_glpk_adapter_test.cc
17.99tests/mtk_grad_1d_test.cc File Reference
17.99.1 Detailed Description
17.99.2 Function Documentation
17.99.2.1 main
17.10@ntk_grad_1d_test.cc
17.101ests/mtk_grad_2d_test.cc File Reference
17.101. Detailed Description
17.101. Function Documentation
17.101.2.1main

CONTENTS xxi

17.102htk_grad_2d_test.cc	8
17.108ests/mtk_interp_1d_test.cc File Reference	0
17.103. Detailed Description	0
17.103. Function Documentation	0
17.103.2.1main	0
17.104ntk_interp_1d_test.cc	0
17.10 Sests/mtk_lap_1d_test.cc File Reference	2
17.105. Detailed Description	2
17.105. Function Documentation	2
17.105.2.1main	3
17.10@ntk_lap_1d_test.cc	3
17.10 Tests/mtk_lap_2d_test.cc File Reference	5
17.107. Detailed Description	6
17.107. Function Documentation	6
17.107.2.1main	6
17.108htk_lap_2d_test.cc	6
17.10% ests/mtk_lapack_adapter_test.cc File Reference	8
17.109. Detailed Description	8
17.109. Function Documentation	8
17.109.2.1main	8
17.11@ntk_lapack_adapter_test.cc41	8
17.111ests/mtk_uni_stg_grid_1d_test.cc File Reference	0
17.111. Detailed Description	0
17.111. Function Documentation	0
17.111.2.1main	0
17.112htk_uni_stg_grid_1d_test.cc	0
17.118ests/mtk_uni_stg_grid_2d_test.cc File Reference	3
17.113. Detailed Description	3
17.113. Function Documentation	3
17.113.2.1main	3
17.114ntk_uni_stg_grid_2d_test.cc	3
Index 42	7

Introduction

We define numerical methods that are based on discretizations preserving the properties of their continuum counterparts to be **mimetic**.

The **Mimetic Methods Toolkit (MTK)** is a C++ library for mimetic numerical methods. It is arranged as a set of classes for **mimetic quadratures**, mimetic interpolation**, and **mimetic finite differences** methods for the numerical solution of ordinary and partial differential equations.

An older version of this library is available outside of GitHub... just email me about it, and you can have it... it is ugly, yet functional and more complete.

1.1 MTK Concerns

Since collaborative development efforts are definitely important in achieving the level of generality we intend the library to possess, we have divided the library's source code according to the designated purpose the classes possess within the library. These divisions (or concerns) are grouped by layers, and are hierarchically related by the dependence they have among them.

One concern is said to depend on another one, if the classes the first concern includes, rely on the classes the second concern includes.

In order of dependence these are:

- 1. Roots.
- 2. Enumerations.
- 3. Tools.
- 4. Data Structures.
- 5. Numerical Methods.
- 6. Grids.
- 7. Mimetic Operators.

1.2 MTK Flavors

The MTK collection of wrappers is:

2 Introduction

1. MMTK: MATLAB wrappers collection for MTK; intended for sequential computations.

Others are being designed and developed.

1.3 Contact, Support and Credits

The MTK is developed by researchers and adjuncts to the Computational Science Research Center (CSRC) at San Diego State University (SDSU).

Developers are members of:

- 1. Mimetic Numerical Methods Research and Development Group.
- 2. Computational Geoscience Research and Development Group.
- 3. Ocean Modeling Research and Development Group.

Currently the developers are:

- 1. Eduardo J. Sanchez, Ph.D. esanchez at mail dot sdsu dot edu ejspeiro
- 2. Jose E. Castillo, Ph.D. jcastillo at mail dot sdsu dot edu
- 3. Guillermo F. Miranda, Ph.D. unigrav at hotmail dot com
- 4. Christopher P. Paolini, Ph.D. paolini at engineering dot sdsu dot edu
- 5. Angel Boada.
- 6. Johnny Corbino.
- 7. Raul Vargas-Navarro.

1.4 Acknowledgements and Contributions

The authors would like to acknowledge valuable advising, contributions and feedback, from research personnel at the Computational Science Research Center at San Diego State University, which were vital to the fruition of this work. Specifically, our thanks go to (alphabetical order):

- 1. Mohammad Abouali, Ph.D.
- 2. Dany De Cecchis, Ph.D.
- 3. Julia Rossi.

Programming Tools

The development of MTK has been made possible through the use of the following applications:

- 1. Editor: Kate KDE Advanced Text Editor. Version 3.13.3. Using KDE Development Platform 4.13.3 (C) 2000-2005. The Kate Authors.
- 2. Compiler: gcc version 4.4.5 (Ubuntu/Linaro 4.4.4-14ubuntu5). Copyright (C) 2013 Free Software Foundation, Inc.
- 3. Debugger: GNU gdb (Ubuntu 7.7.1-0ubuntu5~14.04.2) 7.7.1. Copyright (C) 2014 Free Software Foundation, Inc.
- 4. Memory Profiler: valgrind-3.10.0.SVN.

4	Programming Tools

Licensing and Modifications

Copyright (C) 2015, Computational Science Research Center, San Diego State University. All rights reserved.

Redistribution and use in source and binary forms, with or without modification, are permitted provided that the following conditions are met:

- 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu and a copy of the modified files should be reported once modifications are completed, unless these modifications are made through the project's GitHub page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications should be developed and included in any deliverable.
- 2. Redistributions of source code must be done through direct downloads from the project's GitHub page: http←://www.csrc.sdsu.edu/mtk
- 3. Redistributions in binary form must reproduce the above copyright notice, this list of conditions and the following disclaimer in the documentation and/or other materials provided with the distribution.
- 4. Usage of the binary form on proprietary applications shall require explicit prior written permission from the the copyright holders, and due credit should be given to the copyright holders.
- 5. Neither the name of the copyright holder nor the names of its contributors may be used to endorse or promote products derived from this software without specific prior written permission.

The copyright holders provide no reassurances that the source code provided does not infringe any patent, copyright, or any other intellectual property rights of third parties. The copyright holders disclaim any liability to any recipient for claims brought against recipient by any third party for infringement of that parties intellectual property rights.

THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND ANY EARPESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MARCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EARMPLARY, OR CONSEQUENTIAL DAMAGES (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSACTITUTE GOODS OR SERVICES; LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.

Licensing and	Modifications
---------------	---------------

Read Me File and Installation Instructions

README File for the Mimetic Methods Toolkit (MTK)

By: Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu

1. Description

We define numerical methods that are based on discretizations preserving the properties of their continuum counterparts to be **mimetic**.

The Mimetic Methods Toolkit (MTK) is a C++ library for mimetic numerical methods. It is arranged as a set of classes for mimetic quadratures, mimetic interpolation, and mimetic finite differences methods for the numerical solution of ordinary and partial differential equations.

An older version of this library is available outside of GitHub... just email me about it, and you can have it... it is ugly, yet functional and more complete.

2. Dependencies

This README assumes all of these dependencies are installed in the following folder:

```
$(HOME)/Libraries/
```

In this version, the MTK optionally uses ATLAS-optimized BLAS and LAPACK routines for the internal computation on some of the layers. However, ATLAS requires both BLAS and LAPACK in order to create their optimized distributions. Therefore, the following dependencies tree arises:

For Linux:

```
    LAPACK - Available from: http://www.netlib.org/lapack/
        1. BLAS - Available from: http://www.netlib.org/blas/
    GLPK - Available from: https://www.gnu.org/software/glpk/
    (Optional) ATLAS - Available from: http://math-atlas.sourceforge.net/
        1. LAPACK - Available from: http://www.netlib.org/lapack/
        1. BLAS - Available from: http://www.netlib.org/blas
    (Optional) Valgrind - Available from: http://valgrind.org/
    (Optional) Doxygen - Available from http://www.stack.nl/~dimitri/doxygen/
```

For OS X:

```
1. GLPK - Available from: https://www.gnu.org/software/glpk/
```

3. Installation

PART 1. CONFIGURATION OF THE MAKEFILE.

The following steps are required the build and test the MTK. Please use the accompanying Makefile.inc file, which should provide a solid template to start with. The following command provides help on the options for make:

```
$ make help
----
Makefile for the MTK.

Options are:
- all: builds the library, the tests, and examples.
- mtklib: builds the library.
- test: builds the test files.
- example: builds the examples.

- testall: runs all the tests.

- gendoc: generates the documentation for the library.

- clean: cleans all the generated files.
- cleanlib: cleans the generated archive and object files.
- cleantest: cleans the generated tests executables.
- cleanexample: cleans the generated examples executables.
- ----
```

PART 2. BUILD THE LIBRARY.

```
$ make

If successful you'll read (before building the examples):
---- Library created! Check in /home/ejspeiro/Dropbox/MTK/lib

Examples and tests will also be built.
```

4. Frequently Asked Questions

```
Q: Why haven't you guys implemented GBS to build the library?
A: I'm on it as we speak!;)

Q: Is there any main reference when it comes to the theory on Mimetic Methods?
A: Yes! Check: http://www.csrc.sdsu.edu/mimetic-book

Q: Do I need to generate the documentation myself?
A: You can if you want to... but if you DO NOT want to, just go to our website.
```

5. Contact, Support, and Credits

The MTK is developed by researchers and adjuncts to the Computational Science Research Center (CSRC) at San Diego State University (SDSU).

Developers are members of:

- 1. Mimetic Numerical Methods Research and Development Group.
- 2. Computational Geoscience Research and Development Group.
- 3. Ocean Modeling Research and Development Group.

Currently the developers are:

Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu - ejspeiro

- 2. Jose E. Castillo, Ph.D. jcastillo at mail dot sdsu dot edu
- 3. Guillermo F. Miranda, Ph.D. unigrav at hotmail dot com
- 4. Christopher P. Paolini, Ph.D. paolini at engineering dot sdsu dot edu
- 5. Angel Boada.
- 6. Johnny Corbino.
- 7. Raul Vargas-Navarro.

Finally, please feel free to contact me with suggestions or corrections:

Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu - ejspeiro

Thanks and happy coding!

Tests and Test Architectures

Tests are given in the files list section. They are provided in the /tests/ folder within the distributed software.

In this page we intend to make a summary of all of the architectures in where the MTK has been tested. The MTK is intended to be as portable as possible throughout architectures. The following architectures have provided flawless installations of the API and correct execution of the examples:

```
1. Linux 3.2.0-23-generic-pae #36-Ubuntu SMP i386 GNU/Linux.
   Intel(R) Pentium(R) M CPU 1.73 GHz 2048 KB of cache and stepping of 8.
   gcc version 4.6.3 (Ubuntu/Linaro 4.6.3-lubuntu5).
```

```
2. Linux 3.13.0-67-generic #110-Ubuntu SMP x86_64 GNU/Linux. Intel(R) Core(TM) i7-4700MQ CPU 2.40 GHz 6144 KB of cache and stepping of 3. gcc version 4.8.4 (Ubuntu 4.4.4-2ubuntu1\sim14.04).
```

3. Linux 3.16.7-29-desktop #1 SMP PREEMPT (6be6a97) x86_64 GNU/Linux Intel(R) Core(TM) i7-4600U CPU 2.10 GHz 4096 KB of cache and a stepping of 1. gcc (SUSE Linux) 4.8.3 20140627 [gcc-4_8-branch revision 212064].

Further architectures will be tested!

Tests	and	Teet	Arch	nited	tures

Examples

Examples are given in the files list section. They are provided in the /examples/ folder within the distributed software.

14	Examples

User Manual, References and Theory

The main source of references for this work can be found in:

http://www.csrc.sdsu.edu/mimetic-book/

However, a .PDF copy of this manual can be found here.

User Manual,	References	and Theory

16

Todo List

Member mtk::BCDescriptor2D::ImposeOnGrid (UniStgGrid2D &grid) const

Implement imposition for vector-valued grids.

Member mtk::BCDescriptor2D::ImposeOnSouthBoundaryNoSpace (const mtk::UniStgGrid2D &grid, mtk::← DenseMatrix &matrix, const int &order_accuracy) const

Impose the Neumann conditions on every pole, for every scenario.

Member mtk::BCDescriptor2D::ImposeOnSouthBoundaryWithSpace (const mtk::UniStgGrid2D &grid, mtk::← DenseMatrix &matrix, const int &order_accuracy) const

Impose Harmonic mean on the corners for the case when the generated space is available, for all poles.

Member mtk::DenseMatrix::Kron (const DenseMatrix &aa, const DenseMatrix &bb)

Implement Kronecker product using the BLAS.

Member mtk::DenseMatrix::OrderColMajor ()

Improve this so that no new arrays have to be created.

Member mtk::DenseMatrix::OrderRowMajor ()

Improve this so that no new arrays have to be created.

Member mtk::DenseMatrix::Transpose ()

Improve this so that no extra arrays have to be created.

Class mtk::GLPKAdapter

Rescind from the GLPK as the numerical core for CLO problems.

Member mtk::Matrix::IncreaseNumNull () noexcept

Review the definition of sparse matrices properties.

Member mtk::Matrix::IncreaseNumZero () noexcept

Review the definition of sparse matrices properties.

Member mtk::Tools::Prevent (const bool complement, const char *const fname, int lineno, const char *const fxname) noexcept

Check if this is the best way of stalling execution.

Member mtk::Tools::test_number_

Check usage of static methods and private members.

Member mtk::UniStgGrid1D::discrete_domain_x () const

Review const-correctness of the pointer we return.

18 Todo List

Member mtk::UniStgGrid1D::discrete_field_u ()

Review const-correctness of the pointer we return. Look at the STL!

Member mtk::UniStgGrid2D::discrete_domain_x () const

Review const-correctness of the pointer we return.

Member mtk::UniStgGrid2D::discrete domain y () const

Review const-correctness of the pointer we return.

File mtk div 1d.cc

Overload ostream operator as in mtk::Lap1D.

Implement creation of ■ w. mtk::BLASAdapter.

File mtk glpk adapter test.cc

Test the mtk::GLPKAdapter class.

File mtk grad 1d.cc

Overload ostream operator as in mtk::Lap1D.

Implement creation of ■ w. mtk::BLASAdapter.

File mtk lapack adapter.cc

Write documentation using LaTeX.

File mtk_lapack_adapter_test.cc

Test the mtk::LAPACKAdapter class.

File mtk_quad_1d.h

Implement this class.

File mtk_roots.h

Documentation should (better?) capture effects from selective compilation.

Test selective precision mechanisms.

File mtk_uni_stg_grid_1d.h

Create overloaded binding routines that read data from files.

File mtk_uni_stg_grid_2d.h

Create overloaded binding routines that read data from files.

Bug List

Member mtk::Matrix::set_num_null (const int &in) noexcept
-nan assigned on construction time due to num_values_ being 0.

Member mtk::Matrix::set_num_zero (const int &in) noexcept
-nan assigned on construction time due to num_values_ being 0.

20	Bug List

Module Index

10.1 Modules

Here is a list of all modules:

ots	31
umerations	34
ecution tools	36
a structures	37
merical methods	38
ds	39
netic operators	40

22	Module Index

Namespace Index

1	1		1	Na	am	esp	oac	e l	_ist
---	---	--	---	----	----	-----	-----	-----	------

Here is a list	t of all namespaces with brief descriptions:
mtk	
	Mimetic Methods Toolkit namespace

24	Namespace Index

Class Index

12.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

26	Class Index
20	Olass III

mtk::UniStgGrid1D																	
Uniform 1D Staggered Grid	 															10	78
mtk::UniStgGrid2D																	
Uniform 2D Staggered Grid	 															18	86

File Index

13.1 File List

Here is a list of all files with brid	ef descriptions
---------------------------------------	-----------------

Makefile.inc
examples/minimalistic_poisson_1d/minimalistic_poisson_1d.cc
Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs
examples/poisson_1d/poisson_1d.cc
Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs
include/mtk.h
Includes the entire API
include/mtk_bc_descriptor_1d.h
Enforces boundary conditions in either the operator or the grid
include/mtk_bc_descriptor_2d.h
Imposes boundary conditions in either the operator or the grid
include/mtk_blas_adapter.h
Adapter class for the BLAS API
include/mtk_dense_matrix.h
Defines a common dense matrix, using a 1D array
include/mtk_div_1d.h
Includes the definition of the class Div1D
include/mtk_div_2d.h
Includes the definition of the class Div2D
include/mtk_enums.h
Considered enumeration types in the MTK
include/mtk_glpk_adapter.h
Adapter class for the GLPK API
include/mtk_grad_1d.h
Includes the definition of the class Grad1D
include/mtk_grad_2d.h
Includes the definition of the class Grad2D
include/mtk_interp_1d.h
Includes the definition of the class Interp1D
include/mtk_interp_2d.h
Includes the definition of the class Interp2D
include/mtk_lap_1d.h
Includes the definition of the class Lap1D

28 File Index

include/mtk_lap_2d.h
Includes the implementation of the class Lap2D
include/mtk_lapack_adapter.h Adapter class for the LAPACK API
include/mtk matrix.h
Definition of the representation of a matrix in the MTK
include/mtk guad 1d.h
Includes the definition of the class Quad1D
include/mtk roots.h
Fundamental definitions to be used across all classes of the MTK
include/mtk tools.h
Tool manager class
include/mtk_uni_stg_grid_1d.h
Definition of an 1D uniform staggered grid
include/mtk_uni_stg_grid_2d.h
Definition of an 2D uniform staggered grid
src/mtk_bc_descriptor_1d.cc
Enforces boundary conditions in either the operator or the grid
src/mtk_bc_descriptor_2d.cc
Enforces boundary conditions in either the operator or the grid
src/mtk_blas_adapter.cc
Adapter class for the BLAS API
src/mtk_dense_matrix.cc
src/mtk_div_1d.cc
Implements the class Div1D
src/mtk_div_2d.cc
Implements the class Div2D
src/mtk_glpk_adapter.cc
Adapter class for the GLPK API
src/mtk_grad_1d.cc
Implements the class Grad1D
src/mtk_grad_2d.cc
Implements the class Grad2D
src/mtk_interp_1d.cc
Includes the implementation of the class Interp1D
src/mtk_lap_1d.cc
Includes the implementation of the class Lap1D
src/mtk_lap_2d.cc
Includes the implementation of the class Lap2D
src/mtk_lapack_adapter.cc
Adapter class for the LAPACK API
src/mtk_matrix.cc
Implementing the representation of a matrix in the MTK
src/mtk_tools.cc
Implements a execution tool manager class
src/mtk_uni_stg_grid_1d.cc
Implementation of an 1D uniform staggered grid
src/mtk_uni_stg_grid_2d.cc
Implementation of a 2D uniform staggered grid
tests/mtk_bc_descriptor_2d_test.cc
Test file for the mtk::BCDescriptor2D class
tests/mtk_blas_adapter_test.cc
Test file for the mtk::BLASAdapter class

13.1 File List 29

tests/mtk_dense_matrix_test.cc
Test file for the mtk::DenseMatrix class
tests/mtk_div_1d_test.cc
Testing the mimetic 1D divergence, constructed with the CBS algorithm
tests/mtk_div_2d_test.cc
Test file for the mtk::Div2D class
tests/mtk_glpk_adapter_test.cc
Test file for the mtk::GLPKAdapter class
tests/mtk_grad_1d_test.cc
Testing the mimetic 1D gradient, constructed with the CBS algorithm
tests/mtk_grad_2d_test.cc
Test file for the mtk::Grad2D class
tests/mtk_interp_1d_test.cc
Testing the 1D interpolation
tests/mtk_lap_1d_test.cc
Testing the 1D Laplacian operator
tests/mtk_lap_2d_test.cc
Test file for the mtk::Lap2D class
tests/mtk_lapack_adapter_test.cc
Test file for the mtk::LAPACKAdapter class
tests/mtk_uni_stg_grid_1d_test.cc
Test file for the mtk::UniStgGrid1D class
tests/mtk_uni_stg_grid_2d_test.cc
Test file for the mtk::UniStgGrid2D class

30	File Index

Module Documentation

14.1 Roots.

Fundamental execution parameters and defined types.

Typedefs

typedef float mtk::Real

Users can simply change this to build a double- or single-precision MTK.

Variables

const float mtk::kZero {0.0f}

MTK's zero defined according to selective compilation.

const float mtk::kOne {1.0f}

MTK's one defined according to selective compilation.

const float mtk::kTwo {2.0f}

MTK's two defined according to selective compilation.

• const float mtk::kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

• const int mtk::kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

• const float mtk::kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

const int mtk::kCriticalOrderAccuracyDiv {8}

At this order (and higher) we must use the CBSA to construct.

const int mtk::kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

14.1.1 Detailed Description

Fundamental execution parameters and defined types.

32 Module Documentation

```
14.1.2 Typedef Documentation
14.1.2.1 mtk::Real
Definition at line 83 of file mtk_roots.h.
14.1.3 Variable Documentation
14.1.3.1 mtk::kCriticalOrderAccuracyDiv {8}
Definition at line 167 of file mtk roots.h.
14.1.3.2 mtk::kCriticalOrderAccuracyGrad {10}
Definition at line 176 of file mtk_roots.h.
14.1.3.3 mtk::kDefaultMimeticThreshold {1e-6f}
Warning
     Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 157 of file mtk_roots.h.
14.1.3.4 mtk::kDefaultOrderAccuracy {2}
Warning
      Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 143 of file mtk roots.h.
14.1.3.5 mtk::kDefaultTolerance {1e-7f}
Definition at line 131 of file mtk_roots.h.
14.1.3.6 mtk::kOne {1.0f}
Warning
     Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 117 of file mtk_roots.h.
14.1.3.7 mtk::kTwo {2.0f}
Warning
      Declared as double if MTK_PRECISION_DOUBLE is defined.
```

Definition at line 118 of file mtk roots.h.

14.1 Roots. 33

14.1.3.8 mtk::kZero {0.0f}

Warning

Declared as double if MTK_PRECISION_DOUBLE is defined.

Definition at line 116 of file mtk_roots.h.

34 Module Documentation

14.2 Enumerations.

Enumerations.

Enumerations

```
• enum mtk::MatrixStorage { mtk::DENSE, mtk::BANDED, mtk::CRS }
```

Considered matrix storage schemes to implement sparse matrices.

enum mtk::MatrixOrdering { mtk::ROW_MAJOR, mtk::COL_MAJOR }

Considered matrix ordering (for Fortran purposes).

enum mtk::FieldNature { mtk::SCALAR, mtk::VECTOR }

Nature of the field discretized in a given grid.

enum mtk::DirInterp { mtk::SCALAR_TO_VECTOR, mtk::VECTOR_TO_SCALAR }
 Interpolation operator.

14.2.1 Detailed Description

Enumerations.

14.2.2 Enumeration Type Documentation

```
14.2.2.1 enum mtk::DirInterp
```

Used to tag different directions of interpolation supported.

Enumerator

```
SCALAR_TO_VECTOR Interpolations places scalar on vectors' location.

VECTOR_TO_SCALAR Interpolations places vectors on scalars' location.
```

Definition at line 127 of file mtk_enums.h.

```
14.2.2.2 enum mtk::FieldNature
```

Fields can be scalar or vector in nature.

See also

```
https://en.wikipedia.org/wiki/Scalar_field
https://en.wikipedia.org/wiki/Vector_field
```

Enumerator

```
SCALAR Scalar-valued field.
```

VECTOR Vector-valued field.

Definition at line 113 of file mtk enums.h.

14.2 Enumerations. 35

14.2.2.3 enum mtk::MatrixOrdering

Row-major ordering is used for most application in C/C++. For Fortran purposes, the matrices must be listed in a column-major ordering.

See also

```
https://en.wikipedia.org/wiki/Row-major_order
```

Enumerator

```
ROW_MAJOR Row-major ordering (C/C++). COL_MAJOR Column-major ordering (Fortran).
```

Definition at line 95 of file mtk_enums.h.

14.2.2.4 enum mtk::MatrixStorage

The considered sparse storage schemes are selected so that these are compatible with some of the most used mathematical APIs, as follows: DENSE and BANDED for BLAS, LAPACK, and Scalapack. Finally, CRS for Superlu.

Enumerator

DENSE Dense matrices, implemented as a 1D array: DenseMatrix.

BANDED Banded matrices ala LAPACK and ScaLAPACK: Must be implemented.

CRS Compressed-Rows Storage: Must be implemented.

Definition at line 77 of file mtk_enums.h.

36 Module Documentation

14.3 Execution tools.

Tools to ensure execution correctness.

Classes

class mtk::Tools

Tool manager class.

14.3.1 Detailed Description

Tools to ensure execution correctness.

14.4 Data structures. 37

14.4 Data structures.

Fundamental data structures.

Classes

• class mtk::DenseMatrix

Defines a common dense matrix, using a 1D array.

class mtk::Matrix

Definition of the representation of a matrix in the MTK.

14.4.1 Detailed Description

Fundamental data structures.

38 Module Documentation

14.5 Numerical methods.

Adapter classes and auxiliary numerical methods.

Classes

· class mtk::BLASAdapter

Adapter class for the BLAS API.

• class mtk::GLPKAdapter

Adapter class for the GLPK API.

• class mtk::LAPACKAdapter

Adapter class for the LAPACK API.

14.5.1 Detailed Description

Adapter classes and auxiliary numerical methods.

14.6 Grids. 39

14.6 Grids.

Uniform rectangular staggered grids.

Classes

• class mtk::UniStgGrid1D

Uniform 1D Staggered Grid.

• class mtk::UniStgGrid2D

Uniform 2D Staggered Grid.

14.6.1 Detailed Description

Uniform rectangular staggered grids.

40 Module Documentation

14.7 Mimetic operators.

Mimetic operators.

Classes

• class mtk::BCDescriptor1D

Enforces boundary conditions in either the operator or the grid.

• class mtk::BCDescriptor2D

Enforces boundary conditions in either the operator or the grid.

class mtk::Div1D

Implements a 1D mimetic divergence operator.

class mtk::Div2D

Implements a 2D mimetic divergence operator.

· class mtk::Grad1D

Implements a 1D mimetic gradient operator.

class mtk::Grad2D

Implements a 2D mimetic gradient operator.

· class mtk::Interp1D

Implements a 1D interpolation operator.

· class mtk::Interp2D

Implements a 2D interpolation operator.

class mtk::Lap1D

Implements a 1D mimetic Laplacian operator.

class mtk::Lap2D

Implements a 2D mimetic Laplacian operator.

class mtk::Quad1D

Implements a 1D mimetic quadrature.

Typedefs

• typedef Real(* mtk::CoefficientFunction2D)(const Real &, const Real &)

A function of a BC coefficient evaluated on a 2D domain.

14.7.1 Detailed Description

Mimetic operators.

14.7.2 Typedef Documentation

14.7.2.1 mtk::CoefficientFunction2D

Definition at line 92 of file mtk_bc_descriptor_2d.h.

Namespace Documentation

15.1 mtk Namespace Reference

Mimetic Methods Toolkit namespace.

Classes

class BCDescriptor1D

Enforces boundary conditions in either the operator or the grid.

• class BCDescriptor2D

Enforces boundary conditions in either the operator or the grid.

· class BLASAdapter

Adapter class for the BLAS API.

class DenseMatrix

Defines a common dense matrix, using a 1D array.

class Div1D

Implements a 1D mimetic divergence operator.

class Div2D

Implements a 2D mimetic divergence operator.

· class GLPKAdapter

Adapter class for the GLPK API.

• class Grad1D

Implements a 1D mimetic gradient operator.

· class Grad2D

Implements a 2D mimetic gradient operator.

class Interp1D

Implements a 1D interpolation operator.

class Interp2D

Implements a 2D interpolation operator.

• class Lap1D

Implements a 1D mimetic Laplacian operator.

class Lap2D

Implements a 2D mimetic Laplacian operator.

class LAPACKAdapter

Adapter class for the LAPACK API.

class Matrix

Definition of the representation of a matrix in the MTK.

class Quad1D

Implements a 1D mimetic quadrature.

class Tools

Tool manager class.

class UniStgGrid1D

Uniform 1D Staggered Grid.

· class UniStgGrid2D

Uniform 2D Staggered Grid.

Typedefs

typedef Real(* CoefficientFunction2D)(const Real &, const Real &)

A function of a BC coefficient evaluated on a 2D domain.

· typedef float Real

Users can simply change this to build a double- or single-precision MTK.

Enumerations

enum MatrixStorage { DENSE, BANDED, CRS }

Considered matrix storage schemes to implement sparse matrices.

enum MatrixOrdering { ROW MAJOR, COL MAJOR }

Considered matrix ordering (for Fortran purposes).

• enum FieldNature { SCALAR, VECTOR }

Nature of the field discretized in a given grid.

enum DirInterp { SCALAR_TO_VECTOR, VECTOR_TO_SCALAR }

Interpolation operator.

Functions

- float snrm2 (int *n, float *x, int *incx)
- void saxpy_ (int *n, float *sa, float *sx, int *incx, float *sy, int *incy)
- void sgemv_ (char *trans, int *m, int *n, float *alpha, float *a, int *lda, float *x, int *incx, float *beta, float *y, int *incy)
- void sgemm_ (char *transa, char *transb, int *m, int *n, int *k, double *alpha, double *a, int *lda, double *b, aamm int *ldb, double *beta, double *c, int *ldc)
- std::ostream & operator<< (std::ostream &stream, mtk::DenseMatrix &in)
- std::ostream & operator<< (std::ostream &stream, mtk::Div1D &in)
- std::ostream & operator<< (std::ostream &stream, mtk::Grad1D &in)
- std::ostream & operator<< (std::ostream &stream, mtk::Interp1D &in)
- std::ostream & operator<< (std::ostream &stream, mtk::Lap1D &in)
- void sgesv_ (int *n, int *nrhs, Real *a, int *Ida, int *ipiv, Real *b, int *Idb, int *info)
- void sgels_ (char *trans, int *m, int *n, int *nrhs, Real *a, int *Ida, Real *b, int *Idb, Real *work, int *Iwork, int *info)

Single-precision GEneral matrix Least Squares solver.

• void sgeqrf_ (int *m, int *n, Real *a, int *lda, Real *tau, Real *work, int *lwork, int *info)

Single-precision GEneral matrix QR Factorization.

• void sormqr_ (char *side, char *trans, int *m, int *n, int *k, Real *a, int *lda, Real *tau, Real *c, int *ldc, Real *work, int *lwork, int *info)

Single-precision Orthogonal Matrix from QR factorization.

- std::ostream & operator<< (std::ostream &stream, mtk::UniStgGrid1D &in)
- std::ostream & operator<< (std::ostream &stream, mtk::UniStgGrid2D &in)

Variables

• const float kZero {0.0f}

MTK's zero defined according to selective compilation.

• const float kOne {1.0f}

MTK's one defined according to selective compilation.

const float kTwo {2.0f}

MTK's two defined according to selective compilation.

const float kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

const int kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

const float kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

• const int kCriticalOrderAccuracyDiv {8}

At this order (and higher) we must use the CBSA to construct.

• const int kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

15.1.1 Function Documentation

- 15.1.1.1 std::ostream& mtk::operator<< (std::ostream & stream, mtk::Interp1D & in)
 - 1. Print approximating coefficients for the interior.

Definition at line 66 of file mtk_interp_1d.cc.

- 15.1.1.2 std::ostream& mtk::operator<< (std::ostream & stream, mtk::UniStgGrid2D & in)
 - 1. Print spatial coordinates.
 - 2. Print scalar field.

Definition at line 67 of file mtk uni stg grid 2d.cc.

- 15.1.1.3 std::ostream& mtk::operator<< (std::ostream & stream, mtk::UniStgGrid1D & in)
 - 1. Print spatial coordinates.
 - 2. Print scalar field.

Definition at line 68 of file mtk_uni_stg_grid_1d.cc.

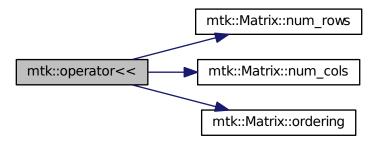
- 15.1.1.4 std::ostream& mtk::operator<< (std::ostream & stream, mtk::Lap1D & in)
 - 1. Print order of accuracy.
 - 2. Print approximating coefficients for the interior.
 - 3. No weights, thus print the mimetic boundary coefficients.

Definition at line 73 of file mtk_lap_1d.cc.

15.1.1.5 std::ostream& mtk::operator<< (std::ostream & stream, mtk::DenseMatrix & in)

Definition at line 77 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



- 15.1.1.6 std::ostream& mtk::operator<< (std::ostream & stream, mtk::Grad1D & in)
 - 1. Print order of accuracy.
 - 2. Print approximating coefficients for the interior.
 - 3. Print mimetic weights.
 - 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk_grad_1d.cc.

15.1.1.7 std::ostream& mtk::operator<< (std::ostream & stream, mtk::Div1D & in)

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk div 1d.cc.

```
15.1.1.8 void mtk::saxpy_( int * n, float * sa, float * sx, int * incx, float * sy, int * incy)
```

Here is the caller graph for this function:



```
15.1.1.9 void mtk::sgels_( char * trans, int * m, int * n, int * nrhs, Real * a, int * lda, Real * b, int * ldb, Real * work, int * lwork, int * info )
```

SGELS solves overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and m >= n: find the least squares solution of an overdetermined system, i.e., solve the least squares problem

```
minimize || B - A*X ||.
```

- 2. If TRANS = 'N' and m < n: find the minimum norm solution of an underdetermined system A \times X = B.
- 3. If TRANS = 'T' and m >= n: find the minimum norm solution of an undetermined system A**T*X = B.
- 4. If TRANS = 'T' and m < n: find the least squares solution of an overdetermined system, i.e., solve the least squares problem

```
minimize || B - A**T * X ||.
```

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

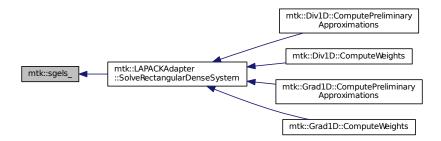
See also

http://www.math.utah.edu/software/lapack/lapack-s/sgels.html

Parameters

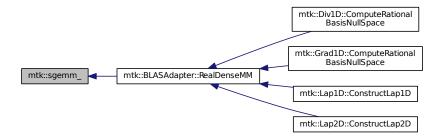
in	trans	Am I giving the transpose of the matrix?
in	m	The number of rows of the matrix $a. m \ge 0$.
in	n	The number of columns of the matrix a. $n \ge 0$.
in	nrhs	The number of right-hand sides.
in,out	а	On entry, the m-by-n matrix a.
in	lda	The leading dimension of a. $da \ge max(1,m)$.
in,out	b	On entry, matrix b of right-hand side vectors.
in	ldb	The leading dimension of b. $ldb \ge max(1,m,n)$.
in,out	work	On exit, if info = 0, work(1) is optimal lwork.
in,out	lwork	The dimension of the array work.
in,out	info	If info = 0, then successful exit.

Here is the caller graph for this function:



15.1.1.10 void mtk::sgemm_ (char * transa, char * transb, int * m, int * n, int * k, double * alpha, double * a, int * lda, double * b, aamm int * ldb, double * b, double * b, alpha, int * ldc)

Here is the caller graph for this function:



15.1.1.11 void mtk::sgemv_(char * trans, int * m, int * n, float * alpha, float * a, int * lda, float * x, int * incx, float * beta, float * y, int * incy)

Here is the caller graph for this function:



15.1.1.12 void mtk::sgeqrf_(int * m, int * n, Real * a, int * Ida, Real * tau, Real * work, int * Iwork, int * info)

Single-Precision Orthogonal Make Q from QR: dormqr_ overwrites the general real M-by-N matrix C with (Table 1):

TRANS = 'N': Q * C C * Q TRANS = 'T': Q**T * C C * Q**T

where Q is a real orthogonal matrix defined as the product of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of order N if SIDE = 'R'.

See also

http://www.netlib.org/lapack/explore-html/df/d97/sgeqrf_8f.html

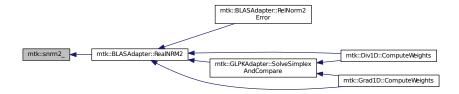
Parameters

in	m	The number of columns of the matrix $a. n \ge 0$.
in	n	The number of columns of the matrix a. $n \ge 0$.
in,out	а	On entry, the n-by-n matrix a.
in	lda	Leading dimension matrix. LDA >= max(1,M).
in,out	tau	Scalars from elementary reflectors. min(M,N).
in,out	work	Workspace. info = 0, work(1) is optimal lwork.
in	lwork	The dimension of work. $ work>= max(1,n)$.
in	info	info = 0: successful exit.

15.1.1.13 void mtk::sgesv_(int * n, int * nrhs, Real * a, int * lda, int * ipiv, Real * b, int * ldb, int * info)

15.1.1.14 float mtk::snrm2_(int * n, float * x, int * incx)

Here is the caller graph for this function:



15.1.1.15 void mtk::sormqr_(char * side, char * trans, int * m, int * n, int * k, Real * a, int * lda, Real * tau, Real * tau,

Single-Precision Orthogonal Make Q from QR: sormqr_ overwrites the general real M-by-N matrix C with (Table 1):

TRANS = 'N': Q * C C * Q TRANS = 'T': Q**T * C C * Q**T

where Q is a real orthogonal matrix defined as the product of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of order N if SIDE = 'R'.

See also

http://www.netlib.org/lapack/explore-html/d0/d98/sormqr_8f_source.html

Parameters

in	side	See Table 1 above.
in	trans	See Table 1 above.
in	т	Number of rows of the C matrix.
in	n	Number of columns of the C matrix.
in	k	Number of reflectors.
in,out	а	The matrix containing the reflectors.
in	lda	The dimension of work. Iwork $\geq \max(1,n)$.
in	tau	Scalar factors of the elementary reflectors.
in	С	Output matrix.
in	ldc	Leading dimension of the output matrix.
in,out	work	Workspace. info = 0, work(1) optimal lwork.
in	lwork	The dimension of work.

in,out	info	info = 0: successful exit.

Chapter 16

Class Documentation

16.1 mtk::BCDescriptor1D Class Reference

Enforces boundary conditions in either the operator or the grid.

#include <mtk_bc_descriptor_1d.h>

Collaboration diagram for mtk::BCDescriptor1D:

mtk::BCDescriptor1D

- + ImposeOnLaplacianMatrix()
- + ImposeOnGrid()

Static Public Member Functions

static void ImposeOnLaplacianMatrix (DenseMatrix &matrix, const std::vector < Real > &west, const std::vector < Real > &east)

Enforces the condition on the Laplacian represented as matrix.

• static void ImposeOnGrid (UniStgGrid1D &grid, const Real &epsilon, const Real &omega)

Enforces the condition on the grid.

16.1.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 1D mimetic operators and the grids they are acting on.

Definition at line 78 of file mtk_bc_descriptor_1d.h.

16.1.2 Member Function Documentation

16.1.2.1 void mtk::BCDescriptor1D::ImposeOnGrid (mtk::UniStgGrid1D & grid, const Real & epsilon, const Real & omega) [static]

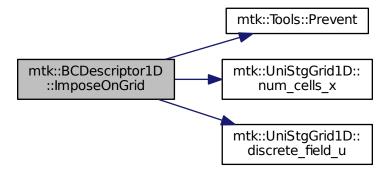
Parameters

in,out	grid	Input grid.
in	epsilon	Actual BC for the east.
in	omega	Actual BC for the west.

- 1. Assign the west condition.
- 2. Assign the east condition.

Definition at line 89 of file mtk_bc_descriptor_1d.cc.

Here is the call graph for this function:



16.1.2.2 void mtk::BCDescriptor1D::ImposeOnLaplacianMatrix (mtk::DenseMatrix & matrix, const std::vector < Real > & west, const std::vector < Real > & east) [static]

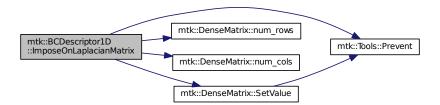
Parameters

in,out	matrix	Input operator.
in	west	Array of values for the west boundary.
in	east	Array of values for the east boundary.

- 1. Assign the west array.
- 2. Assign the east array.

Definition at line 61 of file mtk_bc_descriptor_1d.cc.

Here is the call graph for this function:



The documentation for this class was generated from the following files:

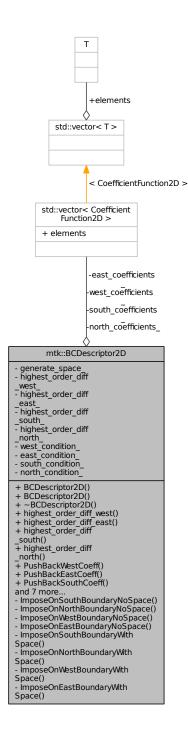
- include/mtk_bc_descriptor_1d.h
- src/mtk_bc_descriptor_1d.cc

16.2 mtk::BCDescriptor2D Class Reference

Enforces boundary conditions in either the operator or the grid.

#include <mtk_bc_descriptor_2d.h>

Collaboration diagram for mtk::BCDescriptor2D:



Public Member Functions

• BCDescriptor2D ()

Default constructor.

BCDescriptor2D (const BCDescriptor2D &desc)

Copy constructor.

∼BCDescriptor2D () noexcept

Destructor.

int highest order diff west () const noexcept

Getter for the highest order of differentiation in the west boundary.

int highest_order_diff_east () const noexcept

Getter for the highest order of differentiation in the east boundary.

int highest_order_diff_south () const noexcept

Getter for the highest order of differentiation in the south boundary.

int highest_order_diff_north () const noexcept

Getter for the highest order of differentiation in the north boundary.

void PushBackWestCoeff (CoefficientFunction2D cw)

Push back coefficient function at west of lowest order diff. available.

void PushBackEastCoeff (CoefficientFunction2D ce)

Push back coefficient function at east of lowest order diff. available.

void PushBackSouthCoeff (CoefficientFunction2D cs)

Push back coefficient function south of lowest order diff. available.

void PushBackNorthCoeff (CoefficientFunction2D cn)

Push back coefficient function north of lowest order diff. available.

void set_west_condition (Real(*west_condition)(Real xx, Real yy)) noexcept

Set boundary condition at west.

void set east condition (Real(*east condition)(Real xx, Real yy)) noexcept

Set boundary condition at east.

void set south condition (Real(*south condition)(Real xx, Real yy)) noexcept

Set boundary condition at south.

void set north condition (Real(*north condition)(Real xx, Real yy)) noexcept

Set boundary condition at north.

void ImposeOnLaplacianMatrix (const UniStgGrid2D &grid, DenseMatrix &matrix, const int &order_accuracy=2)
 const

Imposes the condition on the operator represented as matrix.

void ImposeOnGrid (UniStgGrid2D &grid) const

Imposes the condition on the grid.

Private Member Functions

 void ImposeOnSouthBoundaryNoSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order_accuracy) const

Imposes the condition on the south boundary.

 void ImposeOnNorthBoundaryNoSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order_accuracy) const

Imposes the condition on the north boundary.

 void ImposeOnWestBoundaryNoSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order accuracy) const

Imposes the condition on the west boundary.

 void ImposeOnEastBoundaryNoSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order accuracy) const

Imposes the condition on the east boundary.

 void ImposeOnSouthBoundaryWithSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order_accuracy) const

Imposes the condition on the south boundary.

 void ImposeOnNorthBoundaryWithSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order_accuracy) const

Imposes the condition on the north boundary.

 void ImposeOnWestBoundaryWithSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order_accuracy) const

Imposes the condition on the west boundary.

 void ImposeOnEastBoundaryWithSpace (const mtk::UniStgGrid2D &grid, mtk::DenseMatrix &matrix, const int &order accuracy) const

Imposes the condition on the east boundary.

Private Attributes

bool generate space

Should I generate coordinates as evaluate?

int highest order diff west

Highest order of differentiation for west.

int highest_order_diff_east_

Highest order of differentiation for east.

int highest_order_diff_south_

Highest order differentiation for south.

int highest_order_diff_north_

Highest order differentiation for north.

- std::vector
 - < CoefficientFunction2D > west coefficients

Coeffs. west.

- std::vector
 - < CoefficientFunction2D > east coefficients

Coeffs. east.

- · std::vector
 - < CoefficientFunction2D > south_coefficients_

Coeffs. south.

- · std::vector
 - < CoefficientFunction2D > north coefficients

Coeffs. south.

Real(* west_condition_)(Real xx, Real yy)

Condition for west.

Real(* east_condition_)(Real xx, Real yy)

Condition for east.

• Real(* south_condition_)(Real xx, Real yy)

Condition for south.

Real(* north_condition_)(Real xx, Real yy)

Condition for north.

16.2.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 2D mimetic operators and the grids they are acting on.

Def. Let f be any scalar or vector field defined over a domain Ω . We can specify any linear combination of f and its n derivatives to fulfill a condition, which we define as a **boundary condition**:

$$\forall \mathbf{x} \in \partial \Omega : \sum_{i=0}^{n} c_i(\mathbf{x}) < \hat{\mathbf{n}}, \frac{\partial^i f}{\partial x^i}(\mathbf{x}) > = \beta(\mathbf{x}).$$

This class receives information about the highest-order of differentiation, n, all possible coefficient functions, $c_i(\mathbf{x})$ for any subset of the boundary (south, north, west and east), and each condition for any subset of the boundary, and takes care of assigning them to both, the differentiation matrices and the grids.

Definition at line 123 of file mtk bc descriptor 2d.h.

16.2.2 Constructor & Destructor Documentation

16.2.2.1 mtk::BCDescriptor2D::BCDescriptor2D ()

Definition at line 80 of file mtk bc descriptor 2d.cc.

16.2.2.2 mtk::BCDescriptor2D::BCDescriptor2D (const BCDescriptor2D & desc)

Parameters

in	desc	Given 2D descriptor.
----	------	----------------------

Definition at line 91 of file mtk_bc_descriptor_2d.cc.

16.2.2.3 mtk::BCDescriptor2D::~BCDescriptor2D() [noexcept]

Definition at line 93 of file mtk_bc_descriptor_2d.cc.

16.2.3 Member Function Documentation

16.2.3.1 int mtk::BCDescriptor2D::highest_order_diff_east() const [noexcept]

Returns

Integer highest order of differentiation in the east boundary.

Definition at line 100 of file mtk_bc_descriptor_2d.cc.

16.2.3.2 int mtk::BCDescriptor2D::highest_order_diff_north() const [noexcept]

Returns

Integer highest order of differentiation in the north boundary.

Definition at line 110 of file mtk bc descriptor 2d.cc.

16.2.3.3	int mtk::BCDescri	ptor2D::highest o	order diff	south () const	[noexcept]
----------	-------------------	-------------------	------------	---------	---------	------------

Returns

Integer highest order of differentiation in the south boundary.

Definition at line 105 of file mtk_bc_descriptor_2d.cc.

Returns

Integer highest order of differentiation in the west boundary.

Definition at line 95 of file mtk_bc_descriptor_2d.cc.

16.2.3.5 void mtk::BCDescriptor2D::ImposeOnEastBoundaryNoSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

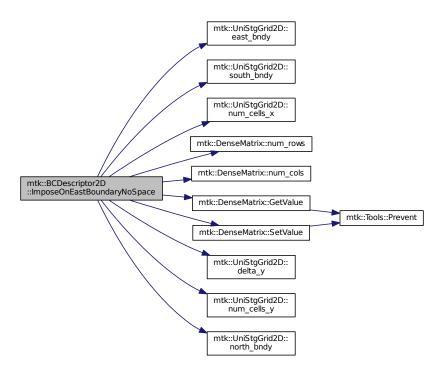
Parameters

in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

- 1. Impose the Dirichlet condition first.
- 2. Impose the Neumann condition second.

Definition at line 467 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.6 void mtk::BCDescriptor2D::ImposeOnEastBoundaryWithSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

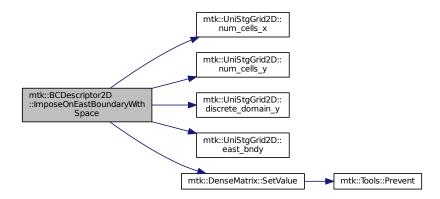
Parameters

in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

- 1. Impose the Dirichlet condition first.
- 2. Impose the Neumann condition second.

Definition at line 537 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.7 void mtk::BCDescriptor2D::ImposeOnGrid (mtk::UniStgGrid2D & grid) const

Parameters

in,out	grid Grid upon which impose the desired boundary condition.	
--------	---	--

- 1. Impose assuming an scalar grid.
- 1.1. Impose south condition.
- 1.1.1. Impose south-west corner.
- 1.1.2. Impose south border.
- 1.1.3. Impose south-east corner.
- 1.2. Impose north condition.
- 1.2.1. Impose north-west corner.
- 1.2.2. Impose north border.
- 1.2.3. Impose north-east corner.
- 1.3. Impose west condition.
- 1.3.1. Impose south-west corner.

Note

As per discussion with Otilio, we will take the arithmetic mean of the values of the BCs at the corners.

- 1.3.2. Impose west border.
- 1.3.3. Impose north-west corner.
- 1.4. Impose east condition.
- 1.4.1. Impose south-east corner.

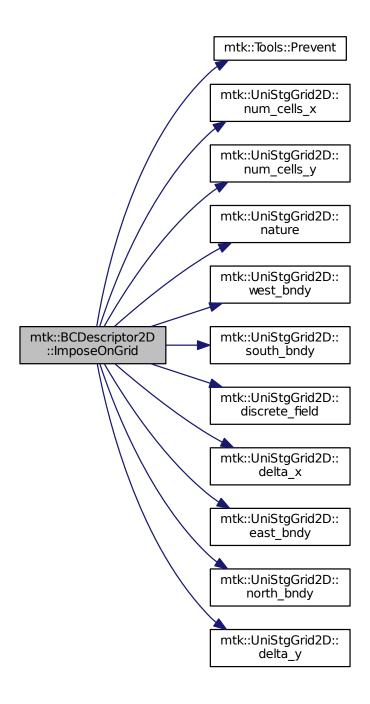
1.4.2. Impose east border.1.4.3. Impose north-east corner.

1. Impose assuming a vector grid.

Todo Implement imposition for vector-valued grids.

Definition at line 596 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.8 void mtk::BCDescriptor2D::ImposeOnLaplacianMatrix (const UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy = 2) const

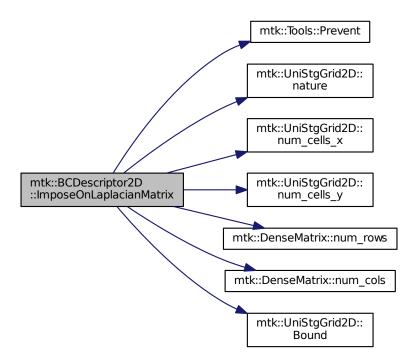
Parameters

in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

If we have not bound anything to the grid, then we have to generate our collection of spatial coordinates, as we evaluate the coefficients.

Definition at line 558 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.9 void mtk::BCDescriptor2D::ImposeOnNorthBoundaryNoSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

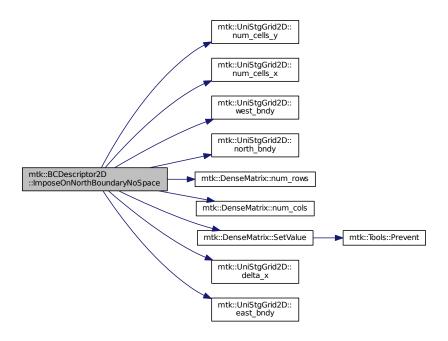
Parameters

in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

- 1. Impose the Dirichlet condition first.
- 2. Impose the Neumann condition second.

Definition at line 291 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.10 void mtk::BCDescriptor2D::ImposeOnNorthBoundaryWithSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

Parameters

in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

1. Impose Dirichlet condition.

For each entry on the diagonal:

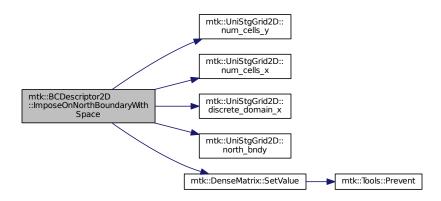
Evaluate next set spatial coordinates to evaluate the coefficient.

Evaluate and assign the Dirichlet coefficient.

1. Impose the Neumann condition.

Definition at line 355 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.11 void mtk::BCDescriptor2D::ImposeOnSouthBoundaryNoSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

Parameters

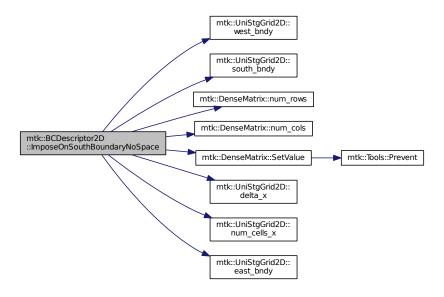
in	grid	Grid upon which impose the desired boundary condition.
in,out	matrix	Input Laplacian operator.
in	order_accuracy	Order of accuracy of the operator in the Matrix.

- 1. Impose the Dirichlet condition first.
- 2. Impose the Neumann condition second.

Todo Impose the Neumann conditions on every pole, for every scenario.

Definition at line 209 of file $mtk_bc_descriptor_2d.cc$.

Here is the call graph for this function:



16.2.3.12 void mtk::BCDescriptor2D::ImposeOnSouthBoundaryWithSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

Parameters

	in	grid	Grid upon which impose the desired boundary condition.
in	,out	matrix	Input Laplacian operator.
	in	order_accuracy	Order of accuracy of the operator in the Matrix.

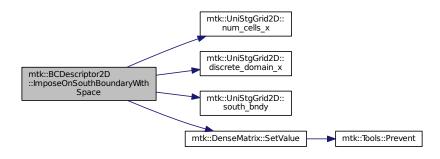
1. Impose the Dirichlet condition first.

Todo Impose Harmonic mean on the corners for the case when the generated space is available, for all poles.

1. Impose the Neumann condition second.

Definition at line 269 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.13 void mtk::BCDescriptor2D::ImposeOnWestBoundaryNoSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

Parameters

in	grid	Grid upon which impose the desired boundary condition.	
in,out	matrix	Input Laplacian operator.	
in	order_accuracy	Order of accuracy of the operator in the Matrix.	

1. Impose the Dirichlet condition first.

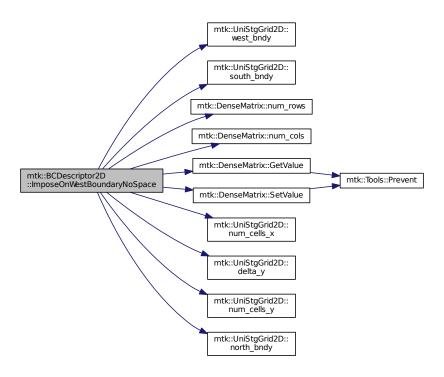
Note

As it can be seen, we must adopt a convention about how to treat the corners. Based on a reasoning with Otilio, we will take the **harmonic mean**.

1. Impose the Neumann condition second.

Definition at line 376 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.14 void mtk::BCDescriptor2D::ImposeOnWestBoundaryWithSpace (const mtk::UniStgGrid2D & grid, mtk::DenseMatrix & matrix, const int & order_accuracy) const [private]

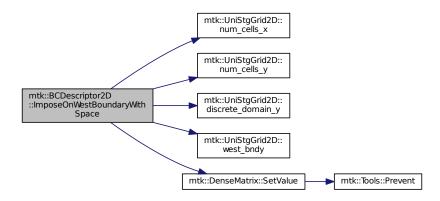
Parameters

in	grid	Grid upon which impose the desired boundary condition.	
in,out	matrix	Input Laplacian operator.	
in	order_accuracy	Order of accuracy of the operator in the Matrix.	

- 1. Impose the Dirichlet condition first.
- 2. Impose the Neumann condition second.

Definition at line 446 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



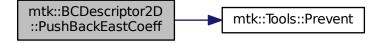
16.2.3.15 void mtk::BCDescriptor2D::PushBackEastCoeff (mtk::CoefficientFunction2D ce)

Parameters

in	се	Function $c_e(x,y): \Omega \mapsto \mathbb{R}$.

Definition at line 128 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.16 void mtk::BCDescriptor2D::PushBackNorthCoeff (mtk::CoefficientFunction2D cn)

Parameters

in	cn	Function $c_n(x,y): \Omega \mapsto \mathbb{R}$.

Definition at line 154 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



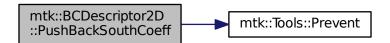
16.2.3.17 void mtk::BCDescriptor2D::PushBackSouthCoeff (mtk::CoefficientFunction2D cs)

Parameters

in	CS	Function $c_s(x,y): \Omega \mapsto \mathbb{R}$.

Definition at line 141 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



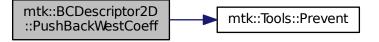
16.2.3.18 void mtk::BCDescriptor2D::PushBackWestCoeff (mtk::CoefficientFunction2D cw)

Parameters

in	CW	Function $c_w(x,y): \Omega \mapsto \mathbb{R}$.

Definition at line 115 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.19 void mtk::BCDescriptor2D::set_east_condition (Real(*)(Real xx, Real yy) east_condition) [noexcept]

Parameters

in	east_condition	$eta_e(x,y):\Omega\mapsto\mathbb{R}.$

Definition at line 177 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



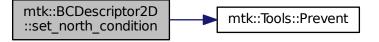
16.2.3.20 void mtk::BCDescriptor2D::set_north_condition (Real(*)(Real xx, Real yy) north_condition) [noexcept]

Parameters

in	north_condition	$\beta_n(x,y): \Omega \mapsto \mathbb{R}.$	

Definition at line 198 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.21 void mtk::BCDescriptor2D::set_south_condition (Real(*)(Real xx, Real yy) south_condition) [noexcept]

Parameters

in	south condition	$\beta_{\rm s}(x,{ m v}):\Omega\mapsto \mathbb{R}.$
		P3 (41,5) 1 = 1 1 = 1

Definition at line 187 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.3.22 void mtk::BCDescriptor2D::set_west_condition (Real(*)(Real xx, Real yy) west_condition) [noexcept]

Parameters

in	west_condition	$\beta_w(x,y): \Omega \mapsto \mathbb{R}.$	

Definition at line 167 of file mtk_bc_descriptor_2d.cc.

Here is the call graph for this function:



16.2.4 Member Data Documentation

16.2.4.1 std::vector < CoefficientFunction2D > mtk::BCDescriptor2D::east_coefficients_ [private]

Definition at line 330 of file mtk_bc_descriptor_2d.h.

16.2.4.2 Real(* mtk::BCDescriptor2D::east_condition_)(Real xx, Real yy) [private]

Definition at line 335 of file mtk_bc_descriptor_2d.h.

16.2.4.3 bool mtk::BCDescriptor2D::generate_space_ [mutable], [private]

Definition at line 322 of file mtk_bc_descriptor_2d.h.

16.2.4.4 int mtk::BCDescriptor2D::highest_order_diff_east_ [private]

Definition at line 325 of file mtk bc descriptor 2d.h.

16.2.4.5 int mtk::BCDescriptor2D::highest_order_diff_north_ [private]

Definition at line 327 of file mtk_bc_descriptor_2d.h.

16.2.4.6 int mtk::BCDescriptor2D::highest_order_diff_south_ [private]

Definition at line 326 of file mtk_bc_descriptor_2d.h.

16.2.4.7 int mtk::BCDescriptor2D::highest_order_diff_west_ [private]

Definition at line 324 of file mtk_bc_descriptor_2d.h.

16.2.4.8 std::vector < CoefficientFunction2D > mtk::BCDescriptor2D::north_coefficients_ [private]

Definition at line 332 of file mtk_bc_descriptor_2d.h.

16.2.4.9 Real(* mtk::BCDescriptor2D::north_condition_)(Real xx, Real yy) [private]

Definition at line 337 of file mtk_bc_descriptor_2d.h.

16.2.4.10 std::vector<CoefficientFunction2D> mtk::BCDescriptor2D::south_coefficients_ [private]

Definition at line 331 of file mtk_bc_descriptor_2d.h.

16.2.4.11 Real(* mtk::BCDescriptor2D::south_condition_)(Real xx, Real yy) [private]

Definition at line 336 of file mtk_bc_descriptor_2d.h.

16.2.4.12 std::vector<CoefficientFunction2D> mtk::BCDescriptor2D::west_coefficients_ [private]

Definition at line 329 of file mtk_bc_descriptor_2d.h.

16.2.4.13 Real(* mtk::BCDescriptor2D::west_condition_)(Real xx, Real yy) [private]

Definition at line 334 of file mtk_bc_descriptor_2d.h.

The documentation for this class was generated from the following files:

- include/mtk_bc_descriptor_2d.h
- src/mtk bc descriptor 2d.cc

16.3 mtk::BLASAdapter Class Reference

Adapter class for the BLAS API.

#include <mtk_blas_adapter.h>

Collaboration diagram for mtk::BLASAdapter:

mtk::BLASAdapter

- + RealNRM2()
- + RealAXPY()
- + RelNorm2Error()
- + RealDenseMV()
- + RealDenseMM()

Static Public Member Functions

• static Real RealNRM2 (Real *in, int &in length)

Compute the $||\mathbf{x}||_2$ of given array \mathbf{x} .

static void RealAXPY (Real alpha, Real *xx, Real *yy, int &in_length)

Real-Arithmetic Scalar-Vector plus a Vector.

static Real RelNorm2Error (Real *computed, Real *known, int length)

Computes the relative norm-2 of the error.

static void RealDenseMV (Real &alpha, DenseMatrix &aa, Real *xx, Real &beta, Real *yy)

Real-Arithmetic General (Dense matrices) Matrix-Vector Multiplier.

• static DenseMatrix RealDenseMM (DenseMatrix &aa, DenseMatrix &bb)

Real-Arithmetic General (Dense matrices) Matrix-Matrix multiplier.

16.3.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the BLAS.

The **BLAS** (**Basic Linear Algebra Subprograms**) are routines that provide standard building blocks for performing basic vector and matrix operations. The Level 1 BLAS perform scalar, vector and vector-vector operations, the Level 2 BLAS perform matrix-vector operations, and the Level 3 BLAS perform matrix operations.

See also

```
http://www.netlib.org/blas/
```

Definition at line 96 of file mtk_blas_adapter.h.

16.3.2 Member Function Documentation

Performs

$$\mathbf{y} := \alpha \mathbf{A} mathbf x + \mathbf{y}$$

Parameters

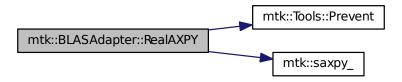
in	alpha	Scalar of the first array.	
in	XX	First array.	
in	уу	Second array.	
in	in_length	Lengths of the given arrays.	

Returns

Norm-2 of the given array.

Definition at line 339 of file mtk_blas_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.2.2 mtk::DenseMatrix mtk::BLASAdapter::RealDenseMM (mtk::DenseMatrix & aa, mtk::DenseMatrix & bb) [static]

Performs:

$$C := AB$$

Parameters

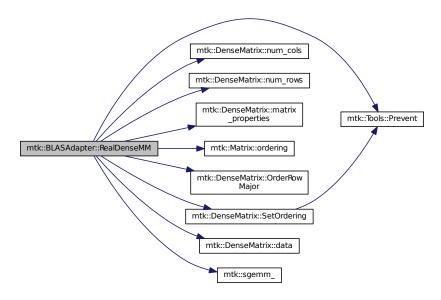
in	aa	First matrix.
in	bb	Second matrix.

See also

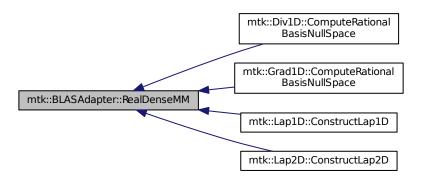
http://ejspeiro.github.io/Netlib-and-CPP/

Definition at line 409 of file mtk_blas_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.2.3 void mtk::BLASAdapter::RealDenseMV (mtk::Real & alpha, mtk::DenseMatrix & aa, mtk::Real * xx, mtk::Real & beta, mtk::Real * yy) [static]

Performs

$$\mathbf{y} := \alpha \mathbf{A} \mathbf{x} + \beta \mathbf{y}$$

Parameters

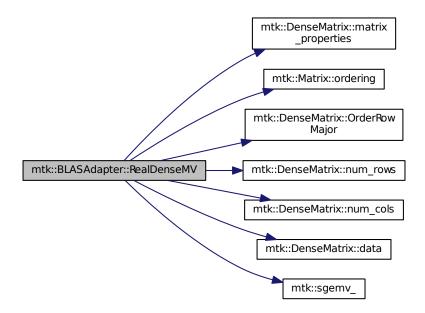
in	alpha	First scalar.
in	aa	Given matrix.
in	XX	First vector.
in	beta	Second scalar.
in,out	уу	Second vector (output).

See also

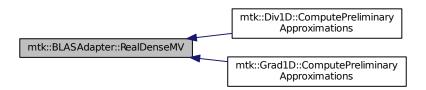
http://ejspeiro.github.io/Netlib-and-CPP/

Definition at line 378 of file mtk_blas_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.2.4 mtk::Real mtk::BLASAdapter::RealNRM2 (Real * in, int & in_length) [static]

Parameters

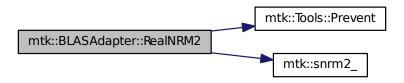
ſ	in	in	Input array.
	in	in_length	Length of the array.

Returns

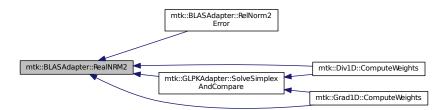
Norm-2 of the given array.

Definition at line 324 of file mtk_blas_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.2.5 mtk::Real mtk::BLASAdapter::RelNorm2Error (mtk::Real * computed, mtk::Real * known, int length) [static]

We compute

$$\frac{||\mathbf{\tilde{x}}-\mathbf{x}||_2}{||\mathbf{x}||_2}.$$

Parameters

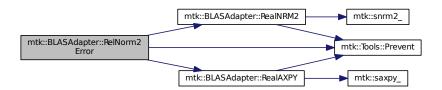
in	known	Array containing the computed solution.
in	computed	Array containing the known solution (ref. solution).

Returns

Relative norm-2 of the error, aka, the difference between the arrays.

Definition at line 358 of file mtk_blas_adapter.cc.

Here is the call graph for this function:



The documentation for this class was generated from the following files:

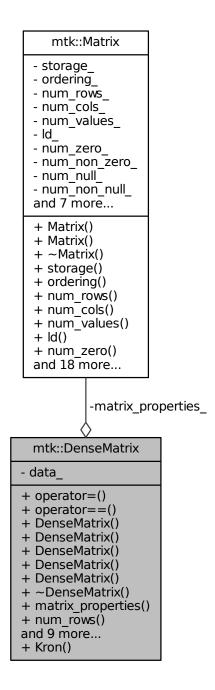
- include/mtk_blas_adapter.h
- src/mtk_blas_adapter.cc

16.4 mtk::DenseMatrix Class Reference

Defines a common dense matrix, using a 1D array.

#include <mtk_dense_matrix.h>

Collaboration diagram for mtk::DenseMatrix:



Public Member Functions

DenseMatrix & operator= (const DenseMatrix &in)

Overloaded assignment operator.

bool operator== (const DenseMatrix &in)

Am I equal to the in matrix?

• DenseMatrix ()

Default constructor.

DenseMatrix (const DenseMatrix &in)

Copy constructor.

• DenseMatrix (const int &num_rows, const int &num_cols)

Construct a dense matrix based on the given dimensions.

DenseMatrix (const int &rank, const bool &padded, const bool &transpose)

Construct a zero-rows-padded identity matrix.

DenseMatrix (const Real *const gen, const int &gen_length, const int &pro_length, const bool &transpose)

Construct a dense Vandermonde matrix.

∼DenseMatrix ()

Destructor.

· Matrix matrix properties () const noexcept

Provides access to the matrix data.

• int num_rows () const noexcept

Gets the number of rows.

• int num cols () const noexcept

Gets the number of columns.

Real * data () const noexcept

Provides access to the matrix value array.

void SetOrdering (mtk::MatrixOrdering oo) noexcept

Sets the ordering of the matrix.

Real GetValue (const int &row_coord, const int &col_coord) const noexcept

Gets a value on the given coordinates.

• void SetValue (const int &row coord, const int &col coord, const Real &val) noexcept

Sets a value on the given coordinates.

void Transpose ()

Transpose this matrix.

void OrderRowMajor ()

Make the matrix row-wise ordered.

void OrderColMajor ()

Make the matrix column-wise ordered.

bool WriteToFile (const std::string &filename) const

Writes matrix to a file compatible with Gnuplot 4.6.

Static Public Member Functions

static DenseMatrix Kron (const DenseMatrix &aa, const DenseMatrix &bb)

Construct a dense matrix based on the Kronecker product of arguments.

Private Attributes

Matrix matrix_properties_

Data related to the matrix nature.

Real * data

Array holding the data in contiguous position in memory.

Friends

std::ostream & operator<< (std::ostream &stream, DenseMatrix &in)

Prints the matrix as a block of numbers (standard way).

16.4.1 Detailed Description

For developing purposes, it is better to have a not-so-intrincated data structure implementing matrices. This is the purpose of this class: to be used for prototypes of new code for small test cases. In every other instance, this should be replaced by the most appropriate sparse matrix.

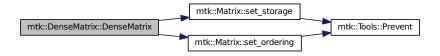
Definition at line 92 of file mtk dense matrix.h.

16.4.2 Constructor & Destructor Documentation

16.4.2.1 mtk::DenseMatrix::DenseMatrix ()

Definition at line 162 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



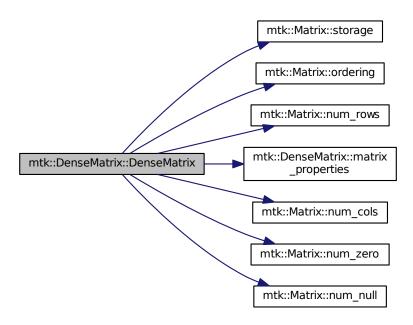
16.4.2.2 mtk::DenseMatrix::DenseMatrix (const DenseMatrix & in)

Parameters

in	in	Given matrix.

Definition at line 168 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



16.4.2.3 mtk::DenseMatrix::DenseMatrix (const int & num_rows, const int & num_cols)

Parameters

in	num_rows	Number of rows of the required matrix.
in	num_cols	Number of rows of the required matrix.

Exceptions

std::bad_alloc	

Definition at line 201 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



16.4.2.4 mtk::DenseMatrix::DenseMatrix (const int & rank, const bool & padded, const bool & transpose)

Used in the construction of the mimetic operators.

Def**. A padded matrix is a matrix with its first and last rows initialized to only zero values:

$$\bar{\mathbf{I}} = \begin{pmatrix} 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix}$$

Parameters

in	rank	Rank or number of rows/cols in square matrix.
in	padded	Should it be padded?
in	transpose	Should I return the transpose of the requested matrix?

Exceptions

std::bad_	alloc

Definition at line 223 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



16.4.2.5 mtk::DenseMatrix::DenseMatrix (const Real *const gen, const int & gen_length, const int & pro_length, const bool & transpose)

Def**. In linear algebra, a **Vandermonde matrix** is a matrix with terms of a geometric progression in each row. This progression uses the terms of a given **generator vector**:

$$\mathbf{V} = \left(egin{array}{ccccc} 1 & lpha_1 & lpha_1^2 & \dots & lpha_1^{n-1} \ 1 & lpha_2 & lpha_2^2 & \dots & lpha_2^{n-1} \ 1 & lpha_3 & lpha_3^2 & \dots & lpha_3^{n-1} \ dots & dots & dots & dots \ 1 & lpha_m & lpha_m^2 & \dots & lpha_m^{n-1} \end{array}
ight)$$

This constructor generates a Vandermonde matrix, as defined above.

Obs**. It in important to understand that the generator vectors to be used are nothing but a very particular instance of a grid. These are little chunks, little samples, if you will, of a grid which is rectangular and uniform. So the selected samples, on the mtk::Div1D and mtk::Grad1D, basically represent the entire space, the entire grid. This is why nor the CRS nor the CBS algorithms may work for irregular geometries, such as curvilinear grids.

Parameters

in	gen	Given generator vector.
in	gen_length	Length generator vector.
in	pro_length	Length the progression.
in	transpose	Should the transpose be created instead?

Exceptions

std::bad_alloc	

Definition at line 264 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



16.4.2.6 mtk::DenseMatrix::~DenseMatrix ()

Definition at line 312 of file mtk_dense_matrix.cc.

16.4.3 Member Function Documentation

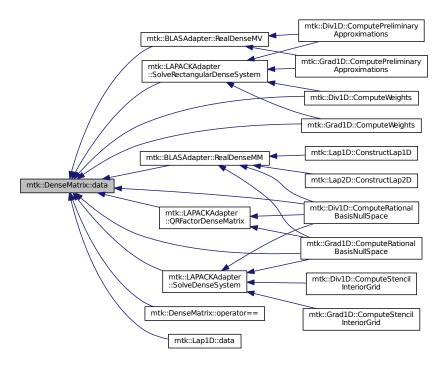
16.4.3.1 mtk::Real * mtk::DenseMatrix::data () const [noexcept]

Returns

Pointer to an array of mtk::Real.

Definition at line 343 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:



16.4.3.2 mtk::Real mtk::DenseMatrix::GetValue (const int & row_coord, const int & col_coord) const [noexcept]

Parameters

in	row_coord	Row coordinate.
in	col_coord	Column coordinate.

Returns

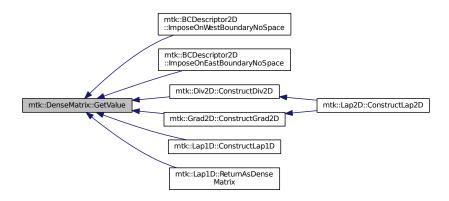
The required value at the specified coordinates.

Definition at line 348 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.4.3.3 mtk::DenseMatrix mtk::DenseMatrix::Kron (const DenseMatrix & aa, const DenseMatrix & bb) [static]

Parameters

ſ	in	aa	First matrix.
	in	bb	Second matrix.

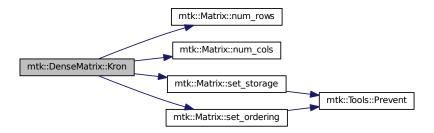
Exceptions

std::bad_alloc	

Todo Implement Kronecker product using the BLAS.

Definition at line 490 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



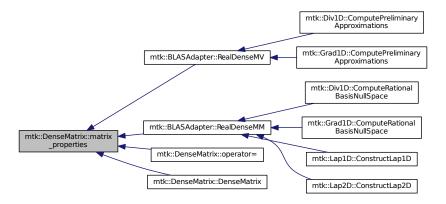
16.4.3.4 mtk::Matrix mtk::DenseMatrix::matrix_properties () const [noexcept]

Returns

Pointer to a Matrix.

Definition at line 318 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:



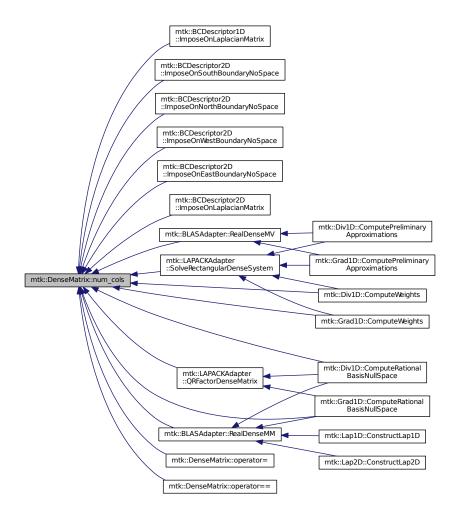
16.4.3.5 int mtk::DenseMatrix::num_cols() const [noexcept]

Returns

Number of columns of the matrix.

Definition at line 338 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:



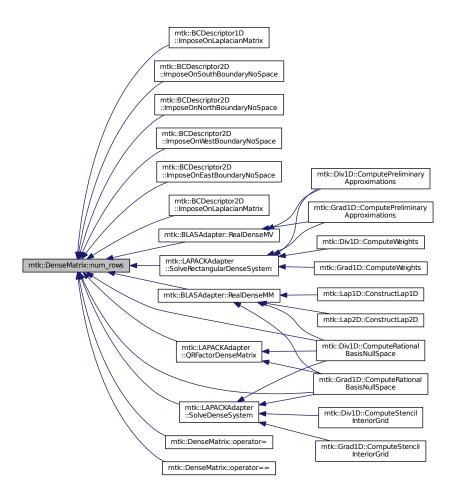
16.4.3.6 int mtk::DenseMatrix::num_rows() const [noexcept]

Returns

Number of rows of the matrix.

Definition at line 333 of file mtk_dense_matrix.cc.

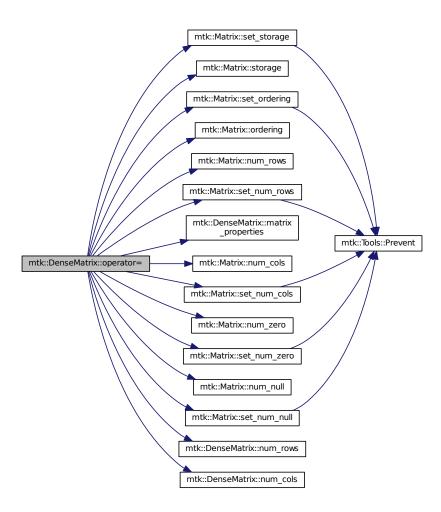
Here is the caller graph for this function:



16.4.3.7 mtk::DenseMatrix & mtk::DenseMatrix::operator= (const DenseMatrix & in)

Definition at line 100 of file mtk_dense_matrix.cc.

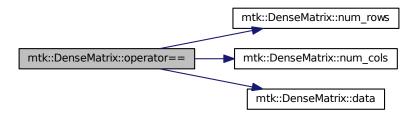
Here is the call graph for this function:



16.4.3.8 bool mtk::DenseMatrix::operator== (const DenseMatrix & in)

Definition at line 141 of file mtk_dense_matrix.cc.

Here is the call graph for this function:

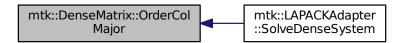


16.4.3.9 void mtk::DenseMatrix::OrderColMajor ()

Todo Improve this so that no new arrays have to be created.

Definition at line 451 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:

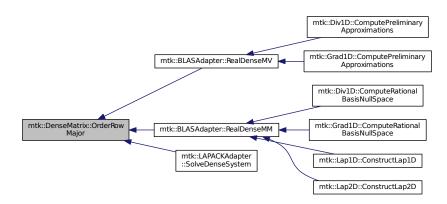


16.4.3.10 void mtk::DenseMatrix::OrderRowMajor ()

Todo Improve this so that no new arrays have to be created.

Definition at line 410 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:



16.4.3.11 void mtk::DenseMatrix::SetOrdering (mtk::MatrixOrdering oo) [noexcept]

Parameters

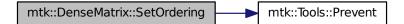
in	00	Ordering.
----	----	-----------

Returns

The required value at the specified coordinates.

Definition at line 323 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.4.3.12 void mtk::DenseMatrix::SetValue (const int & row_coord, const int & col_coord, const Real & val) [noexcept]

Parameters

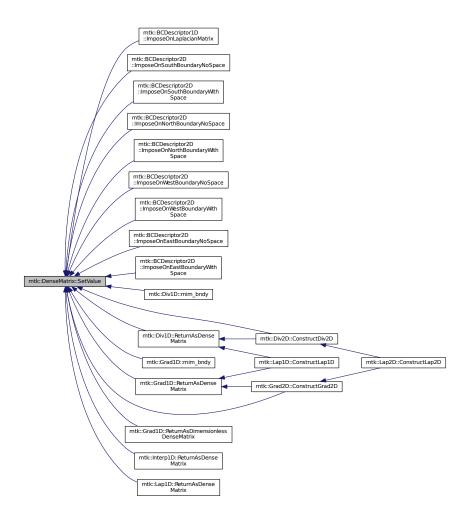
in	row_coord	Row coordinate.
in	col_coord	Column coordinate.
in	val	Row Actual value to be inserted.

Definition at line 360 of file mtk_dense_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:

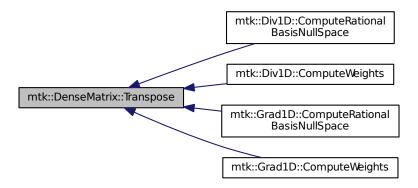


16.4.3.13 void mtk::DenseMatrix::Transpose ()

Todo Improve this so that no extra arrays have to be created.

Definition at line 373 of file mtk_dense_matrix.cc.

Here is the caller graph for this function:



16.4.3.14 bool mtk::DenseMatrix::WriteToFile (const std::string & filename) const

Parameters

in	filename	Name of the output file.

Returns

Success of the file writing process.

See also

http://www.gnuplot.info/

Definition at line 531 of file mtk_dense_matrix.cc.

16.4.4 Friends And Related Function Documentation

16.4.4.1 std::ostream& operator<< (std::ostream & stream, mtk::DenseMatrix & in) [friend]

Definition at line 77 of file mtk_dense_matrix.cc.

16.4.5 Member Data Documentation

16.4.5.1 Real* mtk::DenseMatrix::data_ [private]

Definition at line 285 of file mtk_dense_matrix.h.

16.4.5.2 Matrix mtk::DenseMatrix::matrix_properties_ [private]

Definition at line 283 of file mtk_dense_matrix.h.

The documentation for this class was generated from the following files:

• include/mtk_dense_matrix.h

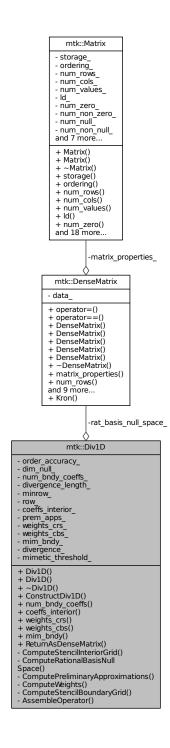
• src/mtk_dense_matrix.cc

16.5 mtk::Div1D Class Reference

Implements a 1D mimetic divergence operator.

#include <mtk_div_1d.h>

Collaboration diagram for mtk::Div1D:



Public Member Functions

• Div1D ()

Default constructor.

• Div1D (const Div1D &div)

Copy constructor.

• ~Div1D ()

Destructor.

bool ConstructDiv1D (int order_accuracy=kDefaultOrderAccuracy, Real mimetic_threshold=kDefaultMimetic
 —
 Threshold)

Factory method implementing the CBS Algorithm to build operator.

• int num_bndy_coeffs () const

Returns how many coefficients are approximating at the boundary.

Real * coeffs interior () const

Returns coefficients for the interior of the grid.

• Real * weights_crs (void) const

Return collection of weights as computed by the CRSA.

Real * weights_cbs (void) const

Return collection of weights as computed by the CBSA.

• DenseMatrix mim_bndy () const

Return collection of mimetic approximations at the boundary.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid) const

Return the operator as a dense matrix.

Private Member Functions

bool ComputeStencilInteriorGrid (void)

Stage 1 of the CBS Algorithm.

bool ComputeRationalBasisNullSpace (void)

Stage 2.1 of the CBS Algorithm.

bool ComputePreliminaryApproximations (void)

Stage 2.2 of the CBS Algorithm.

bool ComputeWeights (void)

Stage 2.3 of the CBS Algorithm.

bool ComputeStencilBoundaryGrid (void)

Stage 2.4 of the CBS Algorithm.

bool AssembleOperator (void)

Stage 3 of the CBS Algorithm.

Private Attributes

int order_accuracy_

Order of numerical accuracy of the operator.

int dim_null_

Dim. null-space for boundary approximations.

int num bndy coeffs

Req. coeffs. per bndy pt. uni. order accuracy.

int divergence_length_

Length of the output array.

int minrow

Row from the optimizer with the minimum rel. nor.

int row

Row currently processed by the optimizer.

DenseMatrix rat_basis_null_space_

Rational b. null-space w. bndy.

Real * coeffs interior

Interior stencil.

Real * prem_apps_

2D array of boundary preliminary approximations.

Real * weights_crs_

Array containing weights from CRSA.

• Real * weights_cbs_

Array containing weights from CBSA.

• Real * mim_bndy_

Array containing mimetic boundary approximations.

• Real * divergence_

Output array containing the operator and weights.

Real mimetic_threshold_

< Mimetic threshold.

Friends

std::ostream & operator<< (std::ostream &stream, Div1D &in)
 Output stream operator for printing.

16.5.1 Detailed Description

This class implements a 1D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 81 of file mtk div 1d.h.

16.5.2 Constructor & Destructor Documentation

```
16.5.2.1 mtk::Div1D::Div1D()
```

Definition at line 125 of file mtk_div_1d.cc.

16.5.2.2 mtk::Div1D::Div1D (const Div1D & div)

Parameters

in	div	Given divergence.

Definition at line 140 of file mtk_div_1d.cc.

```
16.5.2.3 mtk::Div1D::∼Div1D ( )
```

Definition at line 155 of file mtk div 1d.cc.

16.5.3 Member Function Documentation

```
16.5.3.1 bool mtk::Div1D::AssembleOperator(void) [private]
```

Construct the output array with the operator and its weights.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry the collection of coefficients for interior of grid.
- 3. If order accuracy > 2, then third entry is the collection of weights.
- 4. If order accuracy > 2, next dim null entries is approximating coefficients for the west boundary of the grid.

Definition at line 1334 of file mtk_div_1d.cc.

```
16.5.3.2 mtk::Real * mtk::Div1D::coeffs_interior( ) const
```

Returns

Coefficients for the interior of the grid.

Definition at line 320 of file mtk div 1d.cc.

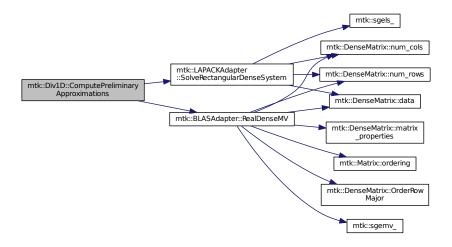
```
16.5.3.3 bool mtk::Div1D::ComputePreliminaryApproximations ( void ) [private]
```

Compute the set of preliminary approximations on the boundary neighborhood.

- 1. Create generator vector for the first approximation.
- 2. Compute the dim null near-the-boundary columns of the pi matrix.
- 3. Create the Vandermonde matrix for this iteration.
- 4. New order-selector vector (gets re-written with LAPACK solutions).
- 5. Solving TT*rr = ob yields the columns rr of the KK matrix.
- 6. Scale the KK matrix to make it a rational basis for null-space.
- 7. Extract the last dim_null values of the pre-scaled ob.
- 8. Once we posses the bottom elements, we proceed with the scaling.

Definition at line 689 of file mtk div 1d.cc.

Here is the call graph for this function:



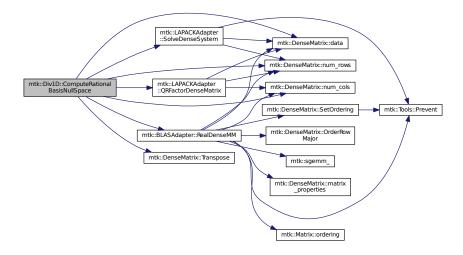
16.5.3.4 bool mtk::Div1D::ComputeRationalBasisNullSpace (void) [private]

Compute a rational basis for the null-space of the Vandermonde matrix approximating at the west boundary.

- 1. Create generator vector for the first approximation.
- 2. Create Vandermonde matrix.
- 3. QR-factorize the Vandermonde matrix.
- 4. Extract the basis for the null-space from Q matrix.
- 5. Scale null-space to make it rational.

Definition at line 513 of file mtk_div_1d.cc.

Here is the call graph for this function:



16.5.3.5 bool mtk::Div1D::ComputeStencilBoundaryGrid (void) [private]

Compute mimetic stencil approximating at boundary.

- 1. Collect lambda values.
- 2. Compute alpha values.
- 3. Compute the mimetic boundary approximations.

Definition at line 1235 of file mtk_div_1d.cc.

16.5.3.6 bool mtk::Div1D::ComputeStencilInteriorGrid (void) [private]

Compute the stencil approximating the interior of the staggered grid.

- 1. Create vector for interior spatial coordinates.
- 2. Create Vandermonde matrix (using interior coordinates as generator).
- 3. Create order-selector vector.
- 4. Solve dense Vandermonde system to attain the interior coefficients.

Definition at line 414 of file mtk_div_1d.cc.

Here is the call graph for this function:



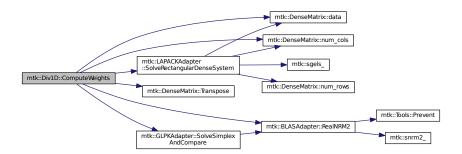
16.5.3.7 bool mtk::Div1D::ComputeWeights (void) [private]

Compute the set of mimetic weights to impose the mimetic condition.

- 1. Construct the matrix.
- 2. Use interior stencil to build proper RHS vector h.
- 3. Get weights (as **CRSA**): $\blacksquare q = h$.
- 4. If required order is greater than critical order, start the CBSA.
- 5. Create matrix from ■.
- 6. Prepare constraint vector as in the CBSA: ■.
- 7. Brute force search through all the rows of the Φ matrix.
- 8. Apply solution found from brute force search.

Definition at line 909 of file mtk div 1d.cc.

Here is the call graph for this function:



16.5.3.8 bool mtk::Div1D::ConstructDiv1D (int order_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the construction.

- 1. Compute stencil for the interior cells.
- 2. Compute a rational basis for the null-space for the first matrix.
- 3. Compute preliminary approximation (non-mimetic) on the boundaries.
- 4. Compute quadrature weights to impose the mimetic conditions.
- 5. Compute real approximation (mimetic) on the boundaries.
- 6. Assemble operator.

Definition at line 176 of file mtk_div_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.5.3.9 mtk::DenseMatrix mtk::Div1D::mim_bndy () const

Returns

Collection of mimetic approximations at the boundary.

Definition at line 336 of file mtk_div_1d.cc.

Here is the call graph for this function:



16.5.3.10 int mtk::Div1D::num_bndy_coeffs () const

Returns

How many coefficients are approximating at the boundary.

Definition at line 315 of file mtk_div_1d.cc.

16.5.3.11 mtk::DenseMatrix mtk::Div1D::ReturnAsDenseMatrix (const UniStgGrid1D & grid) const

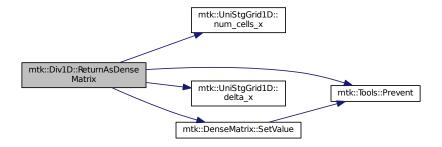
Returns

The operator as a dense matrix.

- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 351 of file mtk_div_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.5.3.12 mtk::Real * mtk::Div1D::weights_cbs (void) const

Returns

Collection of weights as computed by the CBSA.

Definition at line 330 of file mtk_div_1d.cc.

16.5.3.13 mtk::Real * mtk::Div1D::weights_crs (void) const

Returns

Collection of weights as computed by the CRSA.

Definition at line 325 of file mtk_div_1d.cc.

16.5.4 Friends And Related Function Documentation

16.5.4.1 std::ostream& operator<< (std::ostream & stream, mtk::Div1D & in) [friend]

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk_div_1d.cc.

16.5.5 Member Data Documentation

16.5.5.1 Real* mtk::Div1D::coeffs_interior_ [private]

Definition at line 202 of file mtk_div_1d.h.

16.5.5.2 int mtk::Div1D::dim_null_ [private]

Definition at line 194 of file mtk div 1d.h.

```
16.5.5.3 Real* mtk::Div1D::divergence_ [private]
Definition at line 207 of file mtk_div_1d.h.
16.5.5.4 int mtk::Div1D::divergence_length_ [private]
Definition at line 196 of file mtk_div_1d.h.
16.5.5.5 Real* mtk::Div1D::mim_bndy_ [private]
Definition at line 206 of file mtk div 1d.h.
16.5.5.6 Real mtk::Div1D::mimetic_threshold [private]
Definition at line 209 of file mtk div 1d.h.
16.5.5.7 int mtk::Div1D::minrow_ [private]
Definition at line 197 of file mtk_div_1d.h.
16.5.5.8 int mtk::Div1D::num_bndy_coeffs_ [private]
Definition at line 195 of file mtk_div_1d.h.
16.5.5.9 int mtk::Div1D::order_accuracy_ [private]
Definition at line 193 of file mtk_div_1d.h.
16.5.5.10 Real* mtk::Div1D::prem_apps_ [private]
Definition at line 203 of file mtk_div_1d.h.
16.5.5.11 DenseMatrix mtk::Div1D::rat_basis_null_space_ [private]
Definition at line 200 of file mtk div 1d.h.
16.5.5.12 int mtk::Div1D::row_ [private]
Definition at line 198 of file mtk div 1d.h.
16.5.5.13 Real* mtk::Div1D::weights_cbs_ [private]
Definition at line 205 of file mtk_div_1d.h.
```

16.5.5.14 Real* mtk::Div1D::weights_crs_ [private]

Definition at line 204 of file mtk_div_1d.h.

The documentation for this class was generated from the following files:

• include/mtk_div_1d.h

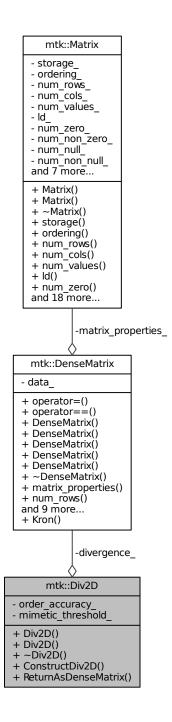
• src/mtk_div_1d.cc

16.6 mtk::Div2D Class Reference

Implements a 2D mimetic divergence operator.

#include <mtk_div_2d.h>

Collaboration diagram for mtk::Div2D:



Public Member Functions

• Div2D ()

Default constructor.

• Div2D (const Div2D &div)

Copy constructor.

• ~Div2D ()

Destructor.

bool ConstructDiv2D (const UniStgGrid2D &grid, int order_accuracy=kDefaultOrderAccuracy, Real mimetic_
 threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix () const

Return the operator as a dense matrix.

Private Attributes

• DenseMatrix divergence_

Actual operator.

int order_accuracy_

Order of accuracy.

Real mimetic threshold

Mimetic Threshold.

16.6.1 Detailed Description

This class implements a 2D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 76 of file mtk_div_2d.h.

16.6.2 Constructor & Destructor Documentation

```
16.6.2.1 mtk::Div2D::Div2D()
```

Definition at line 69 of file mtk div 2d.cc.

16.6.2.2 mtk::Div2D::Div2D (const Div2D & div)

Parameters

in	div	Given divergence.
----	-----	-------------------

Definition at line 73 of file mtk_div_2d.cc.

16.6.2.3 mtk::Div2D::∼Div2D ()

Definition at line 77 of file mtk div 2d.cc.

16.6.3 Member Function Documentation

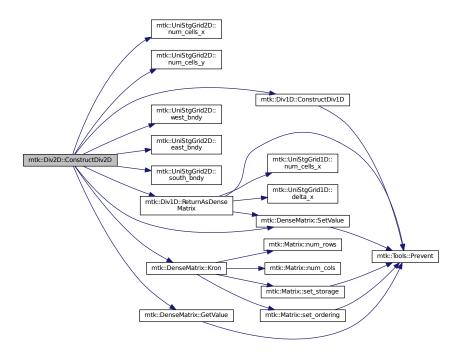
16.6.3.1 bool mtk::Div2D::ConstructDiv2D (const UniStgGrid2D & grid, int order_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the construction.

Definition at line 79 of file mtk_div_2d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



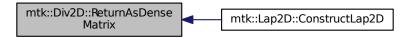
16.6.3.2 mtk::DenseMatrix mtk::Div2D::ReturnAsDenseMatrix () const

Returns

The operator as a dense matrix.

Definition at line 145 of file mtk_div_2d.cc.

Here is the caller graph for this function:



16.6.4 Member Data Documentation

16.6.4.1 DenseMatrix mtk::Div2D::divergence [private]

Definition at line 108 of file mtk_div_2d.h.

16.6.4.2 Real mtk::Div2D::mimetic_threshold [private]

Definition at line 112 of file mtk_div_2d.h.

16.6.4.3 int mtk::Div2D::order_accuracy_ [private]

Definition at line 110 of file mtk_div_2d.h.

The documentation for this class was generated from the following files:

- include/mtk_div_2d.h
- src/mtk_div_2d.cc

16.7 mtk::GLPKAdapter Class Reference

Adapter class for the GLPK API.

#include <mtk_glpk_adapter.h>

Collaboration diagram for mtk::GLPKAdapter:

mtk::GLPKAdapter

+ SolveSimplexAndCompare()

Static Public Member Functions

• static mtk::Real SolveSimplexAndCompare (mtk::Real *A, int nrows, int ncols, int kk, mtk::Real *hh, mtk::Real *qq, int robjective, mtk::Real mimetic tol, int copy)

Solves a CLO problem and compares the solution to a reference solution.

16.7.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

Warning

We use the GLPK temporarily in order to test the CBSA, but it will be removed due to potential licensing issues.

See also

```
http://www.gnu.org/software/glpk/
```

Todo Rescind from the GLPK as the numerical core for CLO problems.

Definition at line 101 of file mtk glpk adapter.h.

16.7.2 Member Function Documentation

16.7.2.1 mtk::Real mtk::GLPKAdapter::SolveSimplexAndCompare (mtk::Real * A, int nrows, int ncols, int kk, mtk::Real * hh, mtk::Real * qq, int robjective, mtk::Real mimetic_tol, int copy) [static]

This routine is the pivot of the CBSA. It solves a Constrained Linear Optimization (CLO) problem, and it compares the attained solution to a given reference solution. This comparison is done computing the norm-2 relative error.

Parameters

in	alpha	First scalar.
in	AA	Given matrix.
in	XX	First vector.
in	beta	Second scalar.
in	beta	Second scalar.
in,out	уу	Second vector (output).
in	XX	First vector.
in	beta	Second scalar.
in	beta	Second scalar.

Returns

Relative error computed between attained solution and provided ref.

Warning

GLPK indexes in [1,n], so we must get the extra space needed.

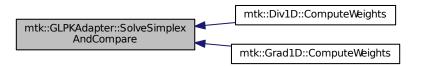
- 1. Memory allocation.
- 2. Fill the problem.
- 3. Copy the row to the vector objective.
- 4. Forming the RHS.
- 5. Setting up the objective function.
- 6. Setting up constraints.
- 7. Copy the matrix minus the row objective to the glpk problem.
- 8. Solve problem.

Definition at line 76 of file mtk_glpk_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



The documentation for this class was generated from the following files:

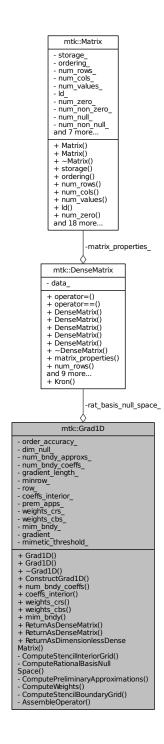
- include/mtk_glpk_adapter.h
- src/mtk_glpk_adapter.cc

16.8 mtk::Grad1D Class Reference

Implements a 1D mimetic gradient operator.

#include <mtk_grad_1d.h>

Collaboration diagram for mtk::Grad1D:



Public Member Functions

• Grad1D ()

Default constructor.

Grad1D (const Grad1D &grad)

Copy constructor.

∼Grad1D ()

Destructor.

bool ConstructGrad1D (int order_accuracy=kDefaultOrderAccuracy, Real mimetic_threshold=kDefaultMimetic
 —
 Threshold)

Factory method implementing the CBS Algorithm to build operator.

• int num_bndy_coeffs () const

Returns how many coefficients are approximating at the boundary.

Real * coeffs interior () const

Returns coefficients for the interior of the grid.

• Real * weights_crs (void) const

Returns collection of weights as computed by the CRSA.

Real * weights_cbs (void) const

Returns collection of weights as computed by the CBSA.

• DenseMatrix mim_bndy () const

Return collection of mimetic approximations at the boundary.

• DenseMatrix ReturnAsDenseMatrix (Real west, Real east, int num_cells_x) const

Returns the operator as a dense matrix.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid) const

Returns the operator as a dense matrix.

DenseMatrix ReturnAsDimensionlessDenseMatrix (int num_cells_x) const

Returns the operator as a dimensionless dense matrix.

Private Member Functions

bool ComputeStencilInteriorGrid (void)

Stage 1 of the CBS Algorithm.

bool ComputeRationalBasisNullSpace (void)

Stage 2.1 of the CBS Algorithm.

bool ComputePreliminaryApproximations (void)

Stage 2.2 of the CBS Algorithm.

bool ComputeWeights (void)

Stage 2.3 of the CBS Algorithm.

bool ComputeStencilBoundaryGrid (void)

Stage 2.4 of the CBS Algorithm.

• bool AssembleOperator (void)

Stage 3 of the CBS Algorithm.

Private Attributes

int order accuracy

Order of numerical accuracy of the operator.

int dim null

Dim. null-space for boundary approximations.

• int num_bndy_approxs_

Req. approximations at and near the boundary.

int num_bndy_coeffs_

Req. coeffs. per bndy pt. uni. order accuracy.

int gradient_length_

Length of the output array.

int minrow

Row from the optimizer with the minimum rel. nor.

int row

Row currently processed by the optimizer.

DenseMatrix rat_basis_null_space_

Rational b. null-space w. bndy.

• Real * coeffs_interior_

Interior stencil.

• Real * prem_apps_

2D array of boundary preliminary approximations.

• Real * weights_crs_

Array containing weights from CRSA.

Real * weights_cbs_

Array containing weights from CBSA.

Real * mim_bndy_

Array containing mimetic boundary approximations.

Real * gradient

Output array containing the operator and weights.

- Real mimetic_threshold_
 - < Mimetic threshold.

Friends

std::ostream & operator<< (std::ostream &stream, Grad1D &in)
 Output stream operator for printing.

16.8.1 Detailed Description

This class implements a 1D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (C← BSA).

Definition at line 81 of file mtk_grad_1d.h.

16.8.2 Constructor & Destructor Documentation

16.8.2.1 mtk::Grad1D::Grad1D()

Definition at line 129 of file mtk_grad_1d.cc.

16.8.2.2 mtk::Grad1D::Grad1D (const Grad1D & grad)

Parameters

in	div	Given divergence.
----	-----	-------------------

Definition at line 145 of file mtk_grad_1d.cc.

```
16.8.2.3 mtk::Grad1D::∼Grad1D ( )
```

Definition at line 161 of file mtk_grad_1d.cc.

16.8.3 Member Function Documentation

```
16.8.3.1 bool mtk::Grad1D::AssembleOperator(void) [private]
```

Construct the output array with the operator and its weights.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry of the array will contain the collection of approximating coefficients for the interior of the grid.
- 3. The third entry will contain the collection of weights.
- 4. The next dim_null + 1 entries will contain the collections of approximating coefficients for the west boundary of the grid.

Definition at line 1499 of file mtk_grad_1d.cc.

```
16.8.3.2 mtk::Real * mtk::Grad1D::coeffs_interior ( ) const
```

Returns

Coefficients for the interior of the grid.

Definition at line 330 of file mtk_grad_1d.cc.

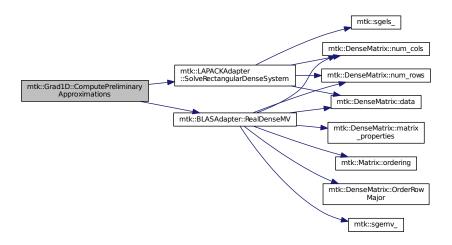
```
16.8.3.3 bool mtk::Grad1D::ComputePreliminaryApproximations (void ) [private]
```

Compute the set of preliminary approximations on the boundary neighborhood.

- 1. Create generator vector for the first approximation.
- 2. Compute the dim_null near-the-boundary columns of the pi matrix.
- 3. Create the Vandermonde matrix for this iteration.
- 4. New order-selector vector (gets re-written with LAPACK solutions).
- 5. Solving TT*rr = ob yields the columns rr of the kk matrix.
- 6. Scale the kk matrix to make it a rational basis for null-space.
- 7. Extract the last dim_null values of the pre-scaled ob.
- 8. Once we posses the bottom elements, we proceed with the scaling.

Definition at line 833 of file mtk_grad_1d.cc.

Here is the call graph for this function:



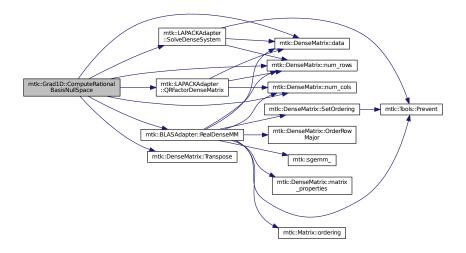
16.8.3.4 bool mtk::Grad1D::ComputeRationalBasisNullSpace(void) [private]

Compute a rational basis for the null-space of the Vandermonde matrix approximating at the west boundary.

- 1. Create generator vector for the first approximation.
- 2. Create Vandermonde matrix.
- 3. QR-factorize the Vandermonde matrix.
- 4. Extract the basis for the null-space from Q matrix.
- 5. Scale null-space to make it rational.

Definition at line 650 of file mtk_grad_1d.cc.

Here is the call graph for this function:



16.8.3.5 bool mtk::Grad1D::ComputeStencilBoundaryGrid (void) [private]

Compute mimetic stencil approximating at boundary.

- 1. Collect lambda values.
- 2. Compute alpha values.
- 3. Compute the mimetic boundary approximations.

Definition at line 1393 of file mtk_grad_1d.cc.

16.8.3.6 bool mtk::Grad1D::ComputeStencilInteriorGrid (void) [private]

Compute the stencil approximating the interior of the staggered grid.

- 1. Create vector for interior spatial coordinates.
- 2. Create Vandermonde matrix (using interior coordinates as generator).
- 3. Create order-selector vector.
- 4. Solve dense Vandermonde system to attain the interior coefficients.

Definition at line 554 of file mtk_grad_1d.cc.

Here is the call graph for this function:



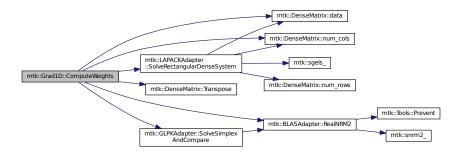
16.8.3.7 bool mtk::Grad1D::ComputeWeights (void) [private]

Compute the set of mimetic weights to impose the mimetic condition.

- 1. Construct the matrix.
- 2. Use interior stencil to build proper RHS vector h.
- 3. Get weights (as **CRSA**): $\blacksquare q = h$.
- 4. If required order is greater than critical order, start the CBSA.
- 5. Create matrix from ■.
- 6. Prepare constraint vector as in the CBSA: ■.
- 7. Brute force search through all the rows of the Φ matrix.
- 8. Apply solution found from brute force search.

Definition at line 1053 of file mtk_grad_1d.cc.

Here is the call graph for this function:



16.8.3.8 bool mtk::Grad1D::ConstructGrad1D (int order_accuracy = kDefaultOrderAccuracy, Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the solution.

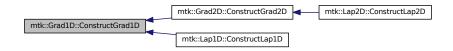
- 1. Compute stencil for the interior cells.
- 2. Compute a rational null-space from the first matrix transposed.
- 3. Compute preliminary approximation (non-mimetic) on the boundaries.
- 4. Compute quadrature weights to impose the mimetic conditions.
- 5. Compute real approximation (mimetic) on the boundaries.
- 6. Assemble operator.

Definition at line 182 of file mtk_grad_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.8.3.9 mtk::DenseMatrix mtk::Grad1D::mim_bndy() const

Returns

Collection of mimetic approximations at the boundary.

Definition at line 345 of file mtk_grad_1d.cc.

Here is the call graph for this function:



16.8.3.10 int mtk::Grad1D::num_bndy_coeffs () const

Returns

How many coefficients are approximating at the boundary.

Definition at line 325 of file mtk_grad_1d.cc.

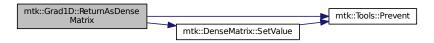
16.8.3.11 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix (mtk::Real west, mtk::Real east, int num_cells_x) const Returns

The operator as a dense matrix.

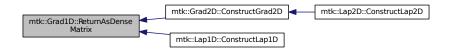
- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 360 of file mtk_grad_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.8.3.12 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix (const UniStgGrid1D & grid) const

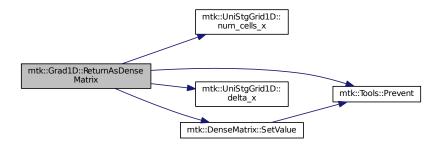
Returns

The operator as a dense matrix.

- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 428 of file mtk_grad_1d.cc.

Here is the call graph for this function:



16.8.3.13 mtk::DenseMatrix mtk::Grad1D::ReturnAsDimensionlessDenseMatrix (int num_cells_x) const

Returns

The operator as a dimensionless dense matrix.

- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 492 of file mtk_grad_1d.cc.

Here is the call graph for this function:



16.8.3.14 mtk::Real * mtk::Grad1D::weights_cbs (void) const

Returns

Collection of weights as computed by the CBSA.

Definition at line 340 of file mtk_grad_1d.cc.

```
16.8.3.15 mtk::Real * mtk::Grad1D::weights_crs ( void ) const
```

Returns

Success of the solution.

Definition at line 335 of file mtk grad 1d.cc.

16.8.4 Friends And Related Function Documentation

16.8.4.1 std::ostream& operator<< (std::ostream & stream, mtk::Grad1D & in) [friend]

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk_grad_1d.cc.

16.8.5 Member Data Documentation

```
16.8.5.1 Real* mtk::Grad1D::coeffs_interior_ [private]
```

Definition at line 217 of file mtk_grad_1d.h.

```
16.8.5.2 int mtk::Grad1D::dim_null_ [private]
```

Definition at line 208 of file mtk_grad_1d.h.

```
16.8.5.3 Real* mtk::Grad1D::gradient_ [private]
```

Definition at line 222 of file mtk_grad_1d.h.

```
16.8.5.4 int mtk::Grad1D::gradient_length_ [private]
```

Definition at line 211 of file mtk_grad_1d.h.

```
16.8.5.5 Real* mtk::Grad1D::mim_bndy_ [private]
```

Definition at line 221 of file mtk_grad_1d.h.

16.8.5.6 Real mtk::Grad1D::mimetic_threshold [private]

Definition at line 224 of file mtk grad 1d.h.

```
16.8.5.7 int mtk::Grad1D::minrow_ [private]
Definition at line 212 of file mtk_grad_1d.h.
16.8.5.8 int mtk::Grad1D::num_bndy_approxs_ [private]
Definition at line 209 of file mtk_grad_1d.h.
16.8.5.9 int mtk::Grad1D::num_bndy_coeffs_ [private]
Definition at line 210 of file mtk_grad_1d.h.
16.8.5.10 int mtk::Grad1D::order_accuracy_ [private]
Definition at line 207 of file mtk grad 1d.h.
16.8.5.11 Real* mtk::Grad1D::prem_apps_ [private]
Definition at line 218 of file mtk_grad_1d.h.
16.8.5.12 DenseMatrix mtk::Grad1D::rat_basis_null_space_ [private]
Definition at line 215 of file mtk grad 1d.h.
16.8.5.13 int mtk::Grad1D::row_ [private]
Definition at line 213 of file mtk_grad_1d.h.
16.8.5.14 Real* mtk::Grad1D::weights_cbs_ [private]
Definition at line 220 of file mtk_grad_1d.h.
16.8.5.15 Real* mtk::Grad1D::weights_crs_ [private]
Definition at line 219 of file mtk_grad_1d.h.
The documentation for this class was generated from the following files:
    • include/mtk grad 1d.h
```

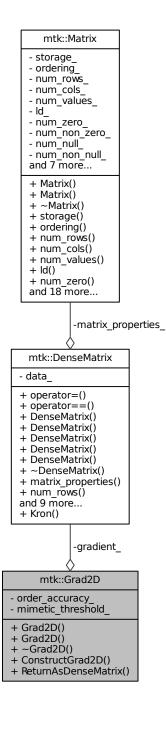
- src/mtk_grad_1d.cc

16.9 mtk::Grad2D Class Reference

Implements a 2D mimetic gradient operator.

```
#include <mtk_grad_2d.h>
```

Collaboration diagram for mtk::Grad2D:



Public Member Functions

• Grad2D ()

Default constructor.

• Grad2D (const Grad2D &grad)

Copy constructor.

• ~Grad2D ()

Destructor.

bool ConstructGrad2D (const UniStgGrid2D &grid, int order_accuracy=kDefaultOrderAccuracy, Real mimetic_
 threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix () const

Return the operator as a dense matrix.

Private Attributes

DenseMatrix gradient_

Actual operator.

int order_accuracy_

Order of accuracy.

Real mimetic threshold

Mimetic Threshold.

16.9.1 Detailed Description

This class implements a 2D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm ($C \leftarrow BSA$).

Definition at line 76 of file mtk_grad_2d.h.

16.9.2 Constructor & Destructor Documentation

```
16.9.2.1 mtk::Grad2D::Grad2D()
```

Definition at line 67 of file mtk grad 2d.cc.

16.9.2.2 mtk::Grad2D::Grad2D (const Grad2D & grad)

Parameters

in	div	Given divergence.
----	-----	-------------------

Definition at line 71 of file mtk_grad_2d.cc.

```
16.9.2.3 mtk::Grad2D::∼Grad2D ( )
```

Definition at line 75 of file mtk_grad_2d.cc.

16.9.3 Member Function Documentation

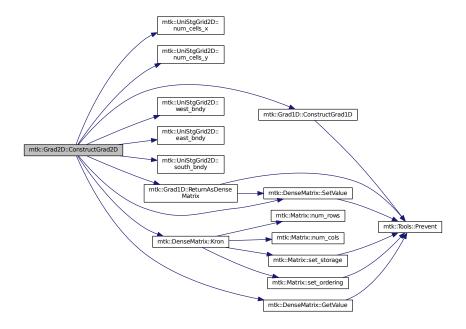
16.9.3.1 bool mtk::Grad2D::ConstructGrad2D (const UniStgGrid2D & grid, int order_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the construction.

Definition at line 77 of file mtk_grad_2d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.9.3.2 mtk::DenseMatrix mtk::Grad2D::ReturnAsDenseMatrix () const

Returns

The operator as a dense matrix.

Definition at line 143 of file mtk_grad_2d.cc.

Here is the caller graph for this function:



16.9.4 Member Data Documentation

16.9.4.1 DenseMatrix mtk::Grad2D::gradient_ [private]

Definition at line 108 of file mtk_grad_2d.h.

16.9.4.2 Real mtk::Grad2D::mimetic_threshold [private]

Definition at line 112 of file mtk_grad_2d.h.

16.9.4.3 int mtk::Grad2D::order_accuracy_ [private]

Definition at line 110 of file mtk_grad_2d.h.

The documentation for this class was generated from the following files:

- include/mtk_grad_2d.h
- src/mtk_grad_2d.cc

16.10 mtk::Interp1D Class Reference

Implements a 1D interpolation operator.

#include <mtk_interp_1d.h>

Collaboration diagram for mtk::Interp1D:

mtk::Interp1D

- dir interp
- order_accuracy_ coeffs_interior_
- + Interp1D()
- + Interp1D()
- + ~Interp1D()
- + ConstructInterp1D()
- + coeffs interior()
- + ReturnAsDenseMatrix()

Public Member Functions

• Interp1D ()

Default constructor.

Interp1D (const Interp1D &interp)

Copy constructor.

• ~Interp1D ()

bool ConstructInterp1D (int order accuracy=kDefaultOrderAccuracy, mtk::DirInterp dir=SCALAR TO VECTOR)

Factory method to build operator.

• Real * coeffs interior () const

Returns coefficients for the interior of the grid.

• DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid) const

Returns the operator as a dense matrix.

Private Attributes

· DirInterp dir_interp_

Direction of interpolation.

int order_accuracy_

Order of numerical accuracy of the operator.

• Real * coeffs_interior_

Interior stencil.

Friends

• std::ostream & operator<< (std::ostream &stream, Interp1D &in)

Output stream operator for printing.

16.10.1 Detailed Description

This class implements a 1D interpolation operator.

Definition at line 82 of file mtk_interp_1d.h.

16.10.2 Constructor & Destructor Documentation

```
16.10.2.1 mtk::Interp1D::Interp1D()
```

Definition at line 80 of file mtk_interp_1d.cc.

16.10.2.2 mtk::Interp1D::Interp1D (const Interp1D & interp)

Parameters

in	interp	Given interpolation operator.
----	--------	-------------------------------

Definition at line 85 of file mtk_interp_1d.cc.

```
16.10.2.3 mtk::Interp1D::\simInterp1D ( )
```

Definition at line 90 of file mtk_interp_1d.cc.

16.10.3 Member Function Documentation

16.10.3.1 mtk::Real * mtk::Interp1D::coeffs_interior() const

Returns

Coefficients for the interior of the grid.

Definition at line 130 of file mtk_interp_1d.cc.

16.10.3.2 bool mtk::Interp1D::ConstructInterp1D (int *order_accuracy* = kDefaultOrderAccuracy, mtk::DirInterp *dir* = SCALAR_TO_VECTOR)

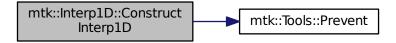
Returns

Success of the solution.

1. Compute stencil for the interior cells.

Definition at line 96 of file mtk interp 1d.cc.

Here is the call graph for this function:



16.10.3.3 mtk::DenseMatrix mtk::Interp1D::ReturnAsDenseMatrix (const UniStgGrid1D & grid) const

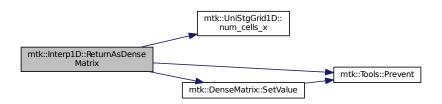
Returns

The operator as a dense matrix.

- 1. Preserve values at the boundary.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the boundaries.

Definition at line 135 of file mtk_interp_1d.cc.

Here is the call graph for this function:



16.10.4 Friends And Related Function Documentation

16.10.4.1 std::ostream& operator<< (std::ostream & stream, mtk::Interp1D & in) [friend]

1. Print approximating coefficients for the interior.

Definition at line 66 of file mtk_interp_1d.cc.

16.10.5 Member Data Documentation

16.10.5.1 Real* mtk::Interp1D::coeffs_interior_ [private]

Definition at line 127 of file mtk_interp_1d.h.

16.10.5.2 DirInterp mtk::Interp1D::dir_interp [private]

Definition at line 123 of file mtk_interp_1d.h.

16.10.5.3 int mtk::Interp1D::order_accuracy_ [private]

Definition at line 125 of file mtk_interp_1d.h.

The documentation for this class was generated from the following files:

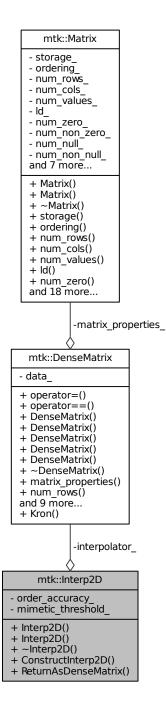
- include/mtk_interp_1d.h
- src/mtk_interp_1d.cc

16.11 mtk::Interp2D Class Reference

Implements a 2D interpolation operator.

#include <mtk_interp_2d.h>

Collaboration diagram for mtk::Interp2D:



Public Member Functions

• Interp2D ()

Default constructor.

• Interp2D (const Interp2D &interp)

Copy constructor.

• ~Interp2D ()

Destructor.

DenseMatrix ConstructInterp2D (const UniStgGrid2D &grid, int order_accuracy=kDefaultOrderAccuracy, Real mimetic_threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix ()

Return the operator as a dense matrix.

Private Attributes

• DenseMatrix interpolator_

Actual operator.

int order_accuracy_

Order of accuracy.

· Real mimetic_threshold_

Mimetic Threshold.

16.11.1 Detailed Description

This class implements a 2D interpolation operator.

Definition at line 76 of file mtk_interp_2d.h.

16.11.2 Constructor & Destructor Documentation

```
16.11.2.1 mtk::Interp2D::Interp2D()
```

16.11.2.2 mtk::Interp2D::Interp2D (const Interp2D & interp)

Parameters

in	lap	Given Laplacian.

16.11.2.3 mtk::Interp2D:: \sim Interp2D ()

16.11.3 Member Function Documentation

16.11.3.1 DenseMatrix mtk::Interp2D::ConstructInterp2D (const UniStgGrid2D & grid, int order_accuracy = kDefaultOrderAccuracy, Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the construction.

16.11.3.2 DenseMatrix mtk::Interp2D::ReturnAsDenseMatrix ()

Returns

The operator as a dense matrix.

16.11.4 Member Data Documentation

16.11.4.1 DenseMatrix mtk::Interp2D::interpolator_ [private]

Definition at line 108 of file mtk_interp_2d.h.

16.11.4.2 Real mtk::Interp2D::mimetic_threshold [private]

Definition at line 112 of file mtk_interp_2d.h.

16.11.4.3 int mtk::Interp2D::order_accuracy_ [private]

Definition at line 110 of file mtk interp 2d.h.

The documentation for this class was generated from the following file:

include/mtk_interp_2d.h

16.12 mtk::Lap1D Class Reference

Implements a 1D mimetic Laplacian operator.

#include <mtk_lap_1d.h>

Collaboration diagram for mtk::Lap1D:

mtk::Lap1D

- order_accuracy_
- laplacian_length_
- laplacian
- mimetic threshold
- + Lap1D()
- + Lap1D()
- + ~Lap1D()
- + ConstructLap1D()
- + ReturnAsDenseMatrix()
- + data()

Public Member Functions

Lap1D ()

Default constructor.

• Lap1D (const Lap1D &lap)

Copy constructor.

• ~Lap1D ()

Destructor.

bool ConstructLap1D (int order_accuracy=kDefaultOrderAccuracy, Real mimetic_threshold=kDefaultMimetic
 — Threshold)

Factory method implementing the CBS Algorithm to build operator.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid) const

Return the operator as a dense matrix.

• const mtk::Real * data (const UniStgGrid1D &grid) const

Return the operator as a dense array.

Private Attributes

· int order_accuracy_

Order of numerical accuracy of the operator.

int laplacian length

Length of the output array.

Real * laplacian

Output array containing the operator and weights.

- Real mimetic threshold
 - < Mimetic threshold.

Friends

std::ostream & operator << (std::ostream & stream, Lap1D &in)
 Output stream operator for printing.

16.12.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 76 of file mtk lap 1d.h.

16.12.2 Constructor & Destructor Documentation

```
16.12.2.1 mtk::Lap1D::Lap1D()
```

Definition at line 108 of file mtk_lap_1d.cc.

16.12.2.2 mtk::Lap1D::Lap1D (const Lap1D & lap)

Parameters

in	lap	Given Laplacian.
----	-----	------------------

16.12.2.3 mtk::Lap1D::~Lap1D()

Definition at line 113 of file mtk_lap_1d.cc.

16.12.3 Member Function Documentation

16.12.3.1 bool mtk::Lap1D::ConstructLap1D (int order_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the solution.

- 1. Create gradient operator using specific values for the Laplacian.
- 2. Create gradient operator using specific values for the Laplacian.
- 3. Create both operators as matrices.
- 4. Multiply both operators: $\breve{\mathbf{L}}_{x}^{k} = \breve{\mathbf{D}}_{x}^{k} \breve{\mathbf{G}}_{x}^{k}$
- 5. Extract the coefficients from the matrix and store them in the array.

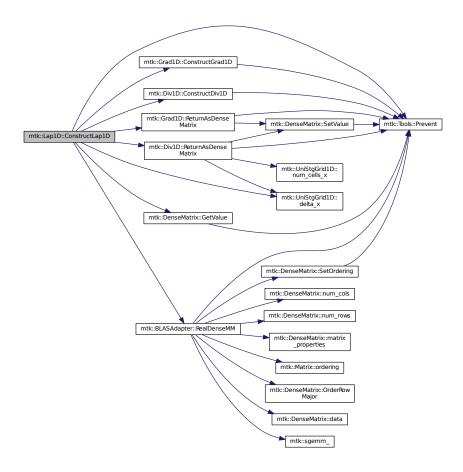
Warning

We do not compute weights for this operator.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry of the array will contain the collection of approximating coefficients for the interior of the grid.
- 3. We DO NOT have weights in this operator. Copy mimetic bndy coeffs.

Definition at line 119 of file mtk lap 1d.cc.

Here is the call graph for this function:



16.12.3.2 const mtk::Real * mtk::Lap1D::data (const UniStgGrid1D & grid) const

Returns

The operator as a dense array.

Definition at line 333 of file mtk_lap_1d.cc.

Here is the call graph for this function:



16.12.3.3 mtk::DenseMatrix mtk::Lap1D::ReturnAsDenseMatrix (const UniStgGrid1D & grid) const

Returns

The operator as a dense matrix.

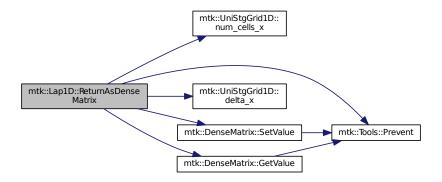
- Extract mimetic coefficients from the west boundary.
- 2. Extract interior coefficients.
- 3. Extract mimetic coefficients from the west boundary to go east.

Note

We could create two matrices of the requested size and multiply them, but that would be inefficient, since we already have the computed coefficients stored. We just have to set them in place, in a matrix of an adequate size, and multiply them times the inverse of the square of the step size, in order for the matrix to actually represent a differential operator.

Definition at line 265 of file mtk_lap_1d.cc.

Here is the call graph for this function:



16.12.4 Friends And Related Function Documentation

16.12.4.1 std::ostream& operator << (std::ostream & stream, mtk::Lap1D & in) [friend]

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. No weights, thus print the mimetic boundary coefficients.

Definition at line 73 of file mtk lap 1d.cc.

16.12.5 Member Data Documentation

16.12.5.1 Real* mtk::Lap1D::laplacian_ [private]

Definition at line 120 of file mtk lap 1d.h.

16.12.5.2 int mtk::Lap1D::laplacian_length_ [private]

Definition at line 118 of file mtk_lap_1d.h.

16.12.5.3 Real mtk::Lap1D::mimetic_threshold_ [private]

Definition at line 122 of file mtk_lap_1d.h.

16.12.5.4 int mtk::Lap1D::order_accuracy_ [private]

Definition at line 117 of file mtk_lap_1d.h.

The documentation for this class was generated from the following files:

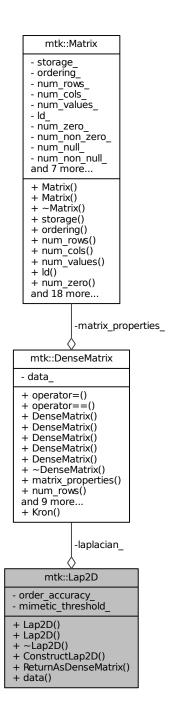
- include/mtk_lap_1d.h
- src/mtk_lap_1d.cc

16.13 mtk::Lap2D Class Reference

Implements a 2D mimetic Laplacian operator.

#include <mtk_lap_2d.h>

Collaboration diagram for mtk::Lap2D:



Public Member Functions

• Lap2D ()

Default constructor.

Lap2D (const Lap2D &lap)

Copy constructor.

• ~Lap2D ()

Destructor.

bool ConstructLap2D (const UniStgGrid2D &grid, int order_accuracy=kDefaultOrderAccuracy, Real mimetic_
 threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix () const

Return the operator as a dense matrix.

• Real * data () const

Return the operator as a dense array.

Private Attributes

• DenseMatrix laplacian_

Actual operator.

int order_accuracy_

Order of accuracy.

· Real mimetic_threshold_

Mimetic Threshold.

16.13.1 Detailed Description

This class implements a 2D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 76 of file mtk lap 2d.h.

16.13.2 Constructor & Destructor Documentation

```
16.13.2.1 mtk::Lap2D::Lap2D()
```

Definition at line 69 of file mtk_lap_2d.cc.

16.13.2.2 mtk::Lap2D::Lap2D (const Lap2D & lap)

Parameters

in	lap	Given Laplacian.
----	-----	------------------

Definition at line 71 of file mtk_lap_2d.cc.

```
16.13.2.3 mtk::Lap2D::\simLap2D ( )
```

Definition at line 75 of file mtk_lap_2d.cc.

16.13.3 Member Function Documentation

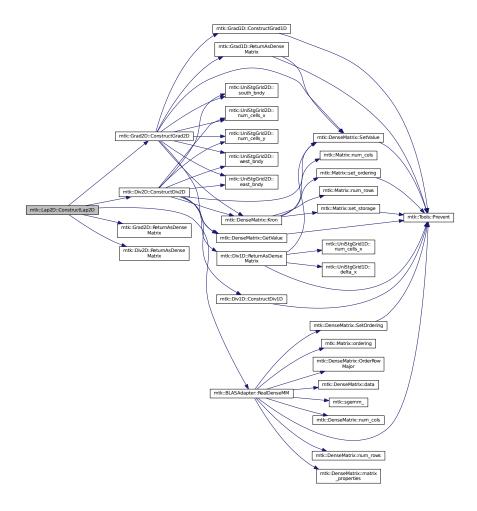
16.13.3.1 bool mtk::Lap2D::ConstructLap2D (const UniStgGrid2D & grid, int order_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic_threshold = kDefaultMimeticThreshold)

Returns

Success of the construction.

Definition at line 77 of file mtk_lap_2d.cc.

Here is the call graph for this function:



16.13.3.2 mtk::Real * mtk::Lap2D::data () const

Returns

The operator as a dense array.

Definition at line 111 of file mtk_lap_2d.cc.

16.13.3.3 mtk::DenseMatrix mtk::Lap2D::ReturnAsDenseMatrix () const

Returns

The operator as a dense matrix.

Definition at line 106 of file mtk_lap_2d.cc.

16.13.4 Member Data Documentation

16.13.4.1 DenseMatrix mtk::Lap2D::laplacian [private]

Definition at line 115 of file mtk_lap_2d.h.

16.13.4.2 Real mtk::Lap2D::mimetic_threshold [private]

Definition at line 119 of file mtk_lap_2d.h.

16.13.4.3 int mtk::Lap2D::order_accuracy_ [private]

Definition at line 117 of file mtk_lap_2d.h.

The documentation for this class was generated from the following files:

- include/mtk lap 2d.h
- · src/mtk_lap_2d.cc

16.14 mtk::LAPACKAdapter Class Reference

Adapter class for the LAPACK API.

#include <mtk_lapack_adapter.h>

Collaboration diagram for mtk::LAPACKAdapter:

mtk::LAPACKAdapter

- + SolveDenseSystem()
- + SolveDenseSystem()
- + SolveDenseSystem()
- + SolveRectangularDenseSystem()
- + QRFactorDenseMatrix()

Static Public Member Functions

static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::Real *rhs)

Solves a dense system of linear equations.

static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::DenseMatrix &rr)

Solves a dense system of linear equations.

static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::UniStgGrid1D &rhs)

Solves a dense system of linear equations.

static int SolveRectangularDenseSystem (const mtk::DenseMatrix &aa, mtk::Real *ob_, int ob_ld_)

Solves overdetermined or underdetermined real linear systems.

static mtk::DenseMatrix QRFactorDenseMatrix (DenseMatrix &matrix)

Performs a QR factorization on a dense matrix.

16.14.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

See also

```
http://www.netlib.org/lapack/
```

Definition at line 92 of file mtk lapack adapter.h.

16.14.2 Member Function Documentation

16.14.2.1 mtk::DenseMatrix mtk::LAPACKAdapter::QRFactorDenseMatrix (mtk::DenseMatrix & aa) [static]

Adapts the MTK to LAPACK's routine.

Parameters

in,out	matrix	Input matrix.
--------	--------	---------------

Returns

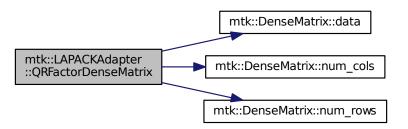
Matrix Q.

Exceptions

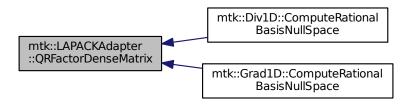
std::bad_alloc	

Definition at line 555 of file mtk lapack adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.2.2 int mtk::LAPACKAdapter::SolveDenseSystem (mtk::DenseMatrix & mm, mtk::Real * rhs) [static]

Adapts the MTK to LAPACK's dgesv_routine.

Parameters

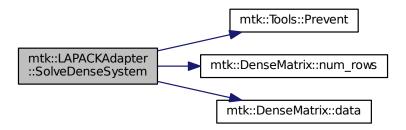
	in	matrix	Input matrix.
Ì	in	rhs	Input right-hand sides vector.

Exceptions

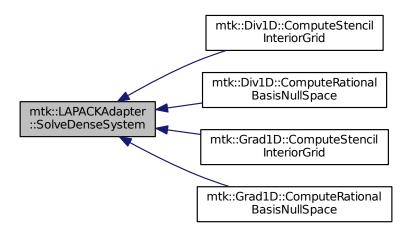
std::bad_alloc	

Definition at line 430 of file mtk_lapack_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.2.3 int mtk::LAPACKAdapter::SolveDenseSystem (mtk::DenseMatrix & mm, mtk::DenseMatrix & rr) [static]

Adapts the MTK to LAPACK's dgesv_routine.

Parameters

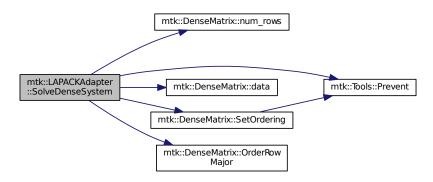
in	matrix	Input matrix.
in	rr	Input right-hand sides matrix.

Exceptions

std::bad alloc	

Definition at line 465 of file mtk_lapack_adapter.cc.

Here is the call graph for this function:



16.14.2.4 int mtk::LAPACKAdapter::SolveDenseSystem (mtk::DenseMatrix & mm, mtk::UniStgGrid1D & rhs) [static]

Adapts the MTK to LAPACK's dgesv_routine.

Parameters

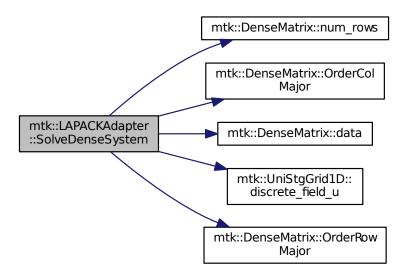
	in	matrix	Input matrix.
Ì	in	rr	Input right-hand side from info on a grid.

Exceptions

std::bad_alloc	

Definition at line 517 of file mtk_lapack_adapter.cc.

Here is the call graph for this function:



16.14.2.5 int mtk::LAPACKAdapter::SolveRectangularDenseSystem (const mtk::DenseMatrix & aa, mtk::Real * ob_, int ob_ld_) [static]

Adapts the MTK to LAPACK's routine.

Parameters

in,out	matrix	Input matrix.

Returns

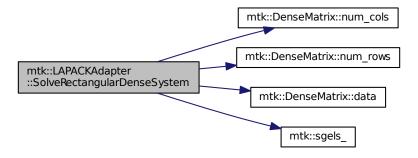
Success of the solution.

Exceptions

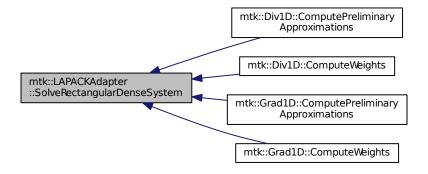
```
std::bad_alloc
```

Definition at line 756 of file mtk_lapack_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



The documentation for this class was generated from the following files:

- include/mtk_lapack_adapter.h
- src/mtk_lapack_adapter.cc

16.15 mtk::Matrix Class Reference

Definition of the representation of a matrix in the MTK.

#include <mtk_matrix.h>

Collaboration diagram for mtk::Matrix:

mtk::Matrix - storage - ordering - num_rows_ - num_cols_ - num_values_ - Id - num zero - num_non_zero_ - num_null_ num_non_null_ and 7 more... + Matrix() + Matrix() + ~Matrix() + storage() + ordering() + num_rows() + num_cols() + num_values() + Id()

+ num_zero() and 18 more...

Public Member Functions

• Matrix ()

Default constructor.

• Matrix (const Matrix &in)

Copy constructor.

∼Matrix () noexcept

Destructor.

MatrixStorage storage () const noexcept

Gets the type of storage of this matrix.

MatrixOrdering ordering () const noexcept

Gets the type of ordering of this matrix.

• int num_rows () const noexcept

Gets the number of rows.

• int num_cols () const noexcept

Gets the number of rows.

• int num_values () const noexcept

Gets the number of values.

• int ld () const noexcept

Gets the matrix' leading dimension.

• int num_zero () const noexcept

Gets the number of zeros.

• int num non zero () const noexcept

Gets the number of non-zero values.

• int num_null () const noexcept

Gets the number of null values.

int num_non_null () const noexcept

Gets the number of non-null values.

int kl () const noexcept

Gets the number of lower diagonals.

• int ku () const noexcept

Gets the number of upper diagonals.

• int bandwidth () const noexcept

Gets the bandwidth.

· Real abs_density () const noexcept

Gets the absolute density.

Real rel_density () const noexcept

Gets the relative density.

· Real abs_sparsity () const noexcept

Gets the Absolute sparsity.

Real rel_sparsity () const noexcept

Gets the Relative sparsity.

void set_storage (const MatrixStorage &tt) noexcept

Sets the storage type of the matrix.

void set_ordering (const MatrixOrdering &oo) noexcept

Sets the ordering of the matrix.

· void set num rows (const int &num rows) noexcept

Sets the number of rows of the matrix.

· void set_num_cols (const int &num_cols) noexcept

Sets the number of columns of the matrix.

void set_num_zero (const int &in) noexcept

Sets the number of zero values of the matrix that matter.

void set_num_null (const int &in) noexcept

Sets the number of zero values of the matrix that DO NOT matter.

· void IncreaseNumZero () noexcept

Increases the number of values that equal zero but with meaning.

void IncreaseNumNull () noexcept

Increases the number of values that equal zero but with no meaning.

Private Attributes

MatrixStorage storage_

What type of matrix is this?

MatrixOrdering ordering_

What kind of ordering is it following?

int num rows

Number of rows.

int num_cols_

Number of columns.

int num_values_

Number of total values in matrix.

int Id

Elements between successive rows when row-major.

int num zero

Number of zeros.

· int num_non_zero_

Number of non-zero values.

int num null

Number of null (insignificant) values.

• int num_non_null_

Number of null (significant) values.

int kl

Number of lower diagonals on a banded matrix.

• int ku_

Number of upper diagonals on a banded matrix.

· int bandwidth_

Bandwidth of the matrix.

Real abs_density_

Absolute density of matrix.

· Real rel_density_

Relative density of matrix.

· Real abs_sparsity_

Absolute sparsity of matrix.

· Real rel_sparsity_

Relative sparsity of matrix.

16.15.1 Detailed Description

Definition of the representation for the matrices implemented in the MTK.

Definition at line 75 of file mtk_matrix.h.

16.15.2 Constructor & Destructor Documentation

16.15.2.1 mtk::Matrix::Matrix ()

Definition at line 67 of file mtk matrix.cc.

16.15.2.2 mtk::Matrix::Matrix (const Matrix & in)

Parameters

in	in	Given matrix.
----	----	---------------

Definition at line 86 of file mtk_matrix.cc.

```
16.15.2.3 mtk::Matrix::~Matrix() [noexcept]
```

Definition at line 105 of file mtk matrix.cc.

16.15.3 Member Function Documentation

```
16.15.3.1 Real mtk::Matrix::abs_density() const [noexcept]
```

See also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

Returns

Absolute density of the matrix.

```
16.15.3.2 mtk::Real mtk::Matrix::abs_sparsity() const [noexcept]
```

See also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

Returns

Absolute sparsity of the matrix.

Definition at line 177 of file mtk_matrix.cc.

```
16.15.3.3 int mtk::Matrix::bandwidth ( ) const [noexcept]
```

Returns

Bandwidth of the matrix.

Definition at line 167 of file mtk_matrix.cc.

```
16.15.3.4 void mtk::Matrix::IncreaseNumNull() [noexcept]
```

Todo Review the definition of sparse matrices properties.

Definition at line 274 of file mtk_matrix.cc.

16.15.3.5 void mtk::Matrix::IncreaseNumZero() [noexcept]

Todo Review the definition of sparse matrices properties.

Definition at line 264 of file mtk matrix.cc.

16.15.3.6 int mtk::Matrix::kl() const [noexcept]

Returns

Number of lower diagonals.

Definition at line 157 of file mtk matrix.cc.

16.15.3.7 int mtk::Matrix::ku () const [noexcept]

Returns

Number of upper diagonals.

Definition at line 162 of file mtk matrix.cc.

16.15.3.8 int mtk::Matrix::ld() const [noexcept]

Leading dimension of the data array is the number of elements between successive rows (for row major storage) in memory. Most of the cases, the leading dimension is the same as the number of columns.

Returns

Leading dimension of the matrix.

Definition at line 132 of file mtk matrix.cc.

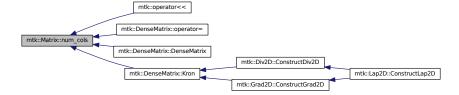
16.15.3.9 int mtk::Matrix::num_cols() const [noexcept]

Returns

Number of rows of the matrix.

Definition at line 122 of file mtk matrix.cc.

Here is the caller graph for this function:



```
16.15.3.10 int mtk::Matrix::num_non_null() const [noexcept]
```

See also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

Returns

Number of non-null values of the matrix.

Definition at line 152 of file mtk_matrix.cc.

```
16.15.3.11 int mtk::Matrix::num_non_zero() const [noexcept]
```

Returns

Number of non-zero values of the matrix.

Definition at line 142 of file mtk_matrix.cc.

```
16.15.3.12 int mtk::Matrix::num_null() const [noexcept]
```

See also

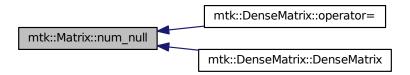
```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

Returns

Number of null values of the matrix.

Definition at line 147 of file mtk_matrix.cc.

Here is the caller graph for this function:



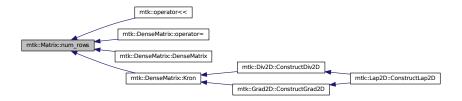
16.15.3.13 int mtk::Matrix::num_rows() const [noexcept]

Returns

Number of rows of the matrix.

Definition at line 117 of file mtk_matrix.cc.

Here is the caller graph for this function:



16.15.3.14 int mtk::Matrix::num_values() const [noexcept]

Returns

Number of values of the matrix.

Definition at line 127 of file mtk_matrix.cc.

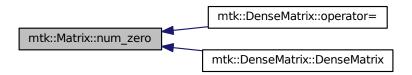
16.15.3.15 int mtk::Matrix::num_zero () const [noexcept]

Returns

Number of zeros of the matrix.

Definition at line 137 of file mtk_matrix.cc.

Here is the caller graph for this function:



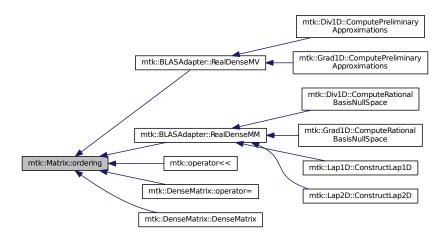
16.15.3.16 mtk::MatrixOrdering mtk::Matrix::ordering () const [noexcept]

Returns

Type of ordering of this matrix.

Definition at line 112 of file mtk matrix.cc.

Here is the caller graph for this function:



16.15.3.17 mtk::Real mtk::Matrix::rel_density() const [noexcept]

See also

http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf

Returns

Relative density of the matrix.

Definition at line 172 of file mtk_matrix.cc.

16.15.3.18 mtk::Real mtk::Matrix::rel_sparsity() const [noexcept]

See also

http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf

Returns

Relative sparsity of the matrix.

Definition at line 182 of file mtk_matrix.cc.

16.15.3.19 void mtk::Matrix::set_num_cols (const int & num_cols) [noexcept]

Parameters

in	num_cols	Number of columns.		
----	----------	--------------------	--	--

Definition at line 224 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.15.3.20 void mtk::Matrix::set_num_null(const int & in) [noexcept]

Parameters

in	in	Number of zero values.

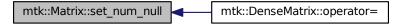
Bug -nan assigned on construction time due to num_values_ being 0.

Definition at line 250 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.15.3.21 void mtk::Matrix::set_num_rows (const int & num_rows) [noexcept]

Parameters

- 1			
	in	num_rows	Number of rows.

Definition at line 212 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.15.3.22 void mtk::Matrix::set_num_zero (const int & in) [noexcept]

Parameters

in	in	Number of zero values.

Bug -nan assigned on construction time due to num_values_ being 0.

Definition at line 236 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:

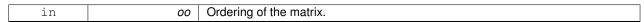


16.15.3.23 void mtk::Matrix::set_ordering (const MatrixOrdering & oo) [noexcept]

See also

MatrixOrdering

Parameters

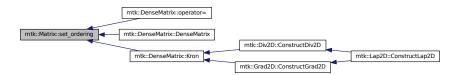


Definition at line 199 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.15.3.24 void mtk::Matrix::set_storage (const MatrixStorage & tt) [noexcept]

See also

MatrixStorage

Parameters

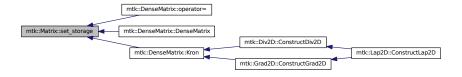
in	tt	Type of the matrix storage.

Definition at line 187 of file mtk_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



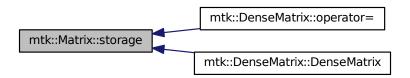
16.15.3.25 mtk::MatrixStorage mtk::Matrix::storage() const [noexcept]

Returns

Type of storage of this matrix.

Definition at line 107 of file mtk_matrix.cc.

Here is the caller graph for this function:



16.15.4 Member Data Documentation

16.15.4.1 Real mtk::Matrix::abs_density_ [private]

Definition at line 296 of file mtk matrix.h.

16.15.4.2 Real mtk::Matrix::abs_sparsity_ [private]

Definition at line 298 of file mtk_matrix.h.

16.15.4.3 int mtk::Matrix::bandwidth_ [private]

Definition at line 294 of file mtk matrix.h.

16.15.4.4 int mtk::Matrix::kl_ [private]

Definition at line 292 of file mtk_matrix.h.

16.15.4.5 int mtk::Matrix::ku_ [private]

Definition at line 293 of file mtk matrix.h.

16.15.4.6 int mtk::Matrix::Id_ [private]

Definition at line 285 of file mtk_matrix.h.

16.15.4.7 int mtk::Matrix::num_cols_ [private]

Definition at line 283 of file mtk_matrix.h.

```
16.15.4.8 int mtk::Matrix::num_non_null_ [private]
Definition at line 290 of file mtk_matrix.h.
16.15.4.9 int mtk::Matrix::num_non_zero_ [private]
Definition at line 288 of file mtk_matrix.h.
16.15.4.10 int mtk::Matrix::num_null_ [private]
Definition at line 289 of file mtk matrix.h.
16.15.4.11 int mtk::Matrix::num_rows_ [private]
Definition at line 282 of file mtk_matrix.h.
16.15.4.12 int mtk::Matrix::num_values_ [private]
Definition at line 284 of file mtk_matrix.h.
16.15.4.13 int mtk::Matrix::num_zero_ [private]
Definition at line 287 of file mtk_matrix.h.
16.15.4.14 MatrixOrdering mtk::Matrix::ordering_ [private]
Definition at line 280 of file mtk_matrix.h.
16.15.4.15 Real mtk::Matrix::rel_density_ [private]
Definition at line 297 of file mtk matrix.h.
16.15.4.16 Real mtk::Matrix::rel_sparsity_ [private]
Definition at line 299 of file mtk_matrix.h.
16.15.4.17 MatrixStorage mtk::Matrix::storage [private]
Definition at line 278 of file mtk_matrix.h.
The documentation for this class was generated from the following files:
```

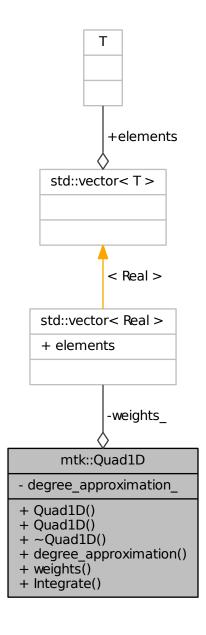
- include/mtk_matrix.h
- src/mtk_matrix.cc

16.16 mtk::Quad1D Class Reference

Implements a 1D mimetic quadrature.

#include <mtk_quad_1d.h>

Collaboration diagram for mtk::Quad1D:



Public Member Functions

• Quad1D ()

Default constructor.

• Quad1D (const Quad1D &quad)

Copy constructor.

• ~Quad1D ()

Destructor.

int degree_approximation () const

Get the degree of interpolating polynomial per sub-interval of domain.

• Real * weights () const

Return collection of weights.

• Real Integrate (Real(*Integrand)(Real xx), UniStgGrid1D grid) const

Mimetic integration routine.

Private Attributes

int degree approximation

Degree of the interpolating polynomial.

• std::vector< Real > weights_

Collection of weights.

Friends

std::ostream & operator<< (std::ostream &stream, Quad1D &in)

Output stream operator for printing.

16.16.1 Detailed Description

This class implements a 1D quadrature solver based on the mimetic discretization of the gradient operator.

Definition at line 81 of file mtk_quad_1d.h.

16.16.2 Constructor & Destructor Documentation

16.16.2.1 mtk::Quad1D::Quad1D()

16.16.2.2 mtk::Quad1D::Quad1D (const Quad1D & quad)

Parameters

	in	div	Given quadrature.
--	----	-----	-------------------

```
16.16.2.3 mtk::Quad1D::~Quad1D( )
```

16.16.3 Member Function Documentation

16.16.3.1 int mtk::Quad1D::degree_approximation () const

Returns

Degree of the interpolating polynomial per sub-interval of the domain.

16.16.3.2 Real mtk::Quad1D::Integrate (Real(*)(Real xx) Integrand, UniStgGrid1D grid) const

Parameters

in	Integrand	Real-valued function to integrate.
in	grid	Given integration domain.

Returns

Result of the integration.

16.16.3.3 Real* mtk::Quad1D::weights () const

Returns

Collection of weights.

16.16.4 Friends And Related Function Documentation

16.16.4.1 std::ostream& operator<<(std::ostream & stream, Quad1D & in) [friend]

16.16.5 Member Data Documentation

16.16.5.1 int mtk::Quad1D::degree_approximation_ [private]

Definition at line 124 of file mtk_quad_1d.h.

16.16.5.2 std::vector<Real> mtk::Quad1D::weights_ [private]

Definition at line 126 of file mtk_quad_1d.h.

The documentation for this class was generated from the following file:

• include/mtk_quad_1d.h

16.17 mtk::Tools Class Reference

Tool manager class.

#include <mtk_tools.h>

Collaboration diagram for mtk::Tools:

mtk::Tools

- test number
- duration
- begin time
- + Prevent()
- + BeginUnitTestNo()
- + EndUnitTestNo()
- + Assert()

Static Public Member Functions

static void Prevent (const bool complement, const char *const fname, int lineno, const char *const fxname)
 noexcept

Enforces preconditions by preventing their complements from occur.

static void BeginUnitTestNo (const int &nn) noexcept

Begins the execution of a unit test. Starts a timer.

• static void EndUnitTestNo (const int &nn) noexcept

Ends the execution of a unit test. Stops and reports wall-clock time.

· static void Assert (const bool &condition) noexcept

Asserts if the condition required to pass the unit test occurs.

Static Private Attributes

• static int test_number_

Current test being executed.

static Real duration_

Duration of the current test.

static clock_t begin_time_

Elapsed time on current test.

16.17.1 Detailed Description

Basic tools to ensure execution correctness.

Definition at line 78 of file mtk_tools.h.

16.17.2 Member Function Documentation

16.17.2.1 void mtk::Tools::Assert (const bool & condition) [static], [noexcept]

Parameters

in	condition	Condition to be asserted.
	00	

Definition at line 114 of file mtk_tools.cc.

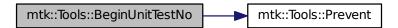
16.17.2.2 void mtk::Tools::BeginUnitTestNo (const int & nn) [static], [noexcept]

Parameters

in	nn	Number of the test.
----	----	---------------------

Definition at line 91 of file mtk_tools.cc.

Here is the call graph for this function:



16.17.2.3 void mtk::Tools::EndUnitTestNo(const int & nn) [static], [noexcept]

Parameters

	I	Ni walang dalan ang
ın	nn	Number of the test.

Definition at line 105 of file mtk_tools.cc.

Here is the call graph for this function:



16.17.2.4 void mtk::Tools::Prevent (const bool *complement*, const char *const *fname*, int *lineno*, const char *const *fxname*) [static], [noexcept]

See also

http://stackoverflow.com/questions/8884335/print-the-file-name-line-number-and-function

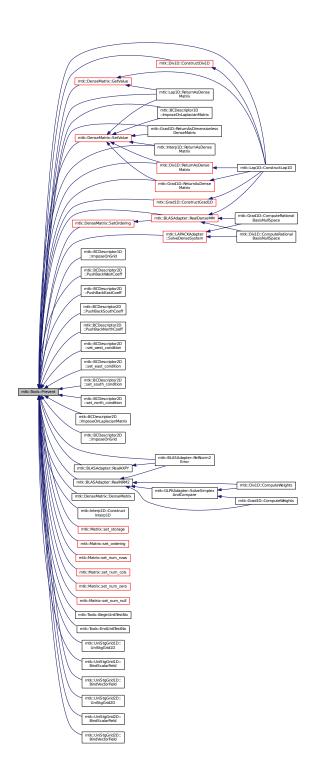
Parameters

in	complement	Complement of desired pre-condition.
in	fname	Name of the file being checked.
in	lineno	Number of the line where the check is executed.
in	fxname	Name of the module containing the check.

Todo Check if this is the best way of stalling execution.

Definition at line 61 of file mtk_tools.cc.

Here is the caller graph for this function:



16.17.3 Member Data Documentation

```
16.17.3.1 clock_t mtk::Tools::begin_time_ [static], [private]
```

Definition at line 121 of file mtk_tools.h.

```
16.17.3.2 mtk::Real mtk::Tools::duration_ [static], [private]
```

Definition at line 119 of file mtk_tools.h.

```
16.17.3.3 int mtk::Tools::test_number_ [static], [private]
```

Todo Check usage of static methods and private members.

Definition at line 117 of file mtk_tools.h.

The documentation for this class was generated from the following files:

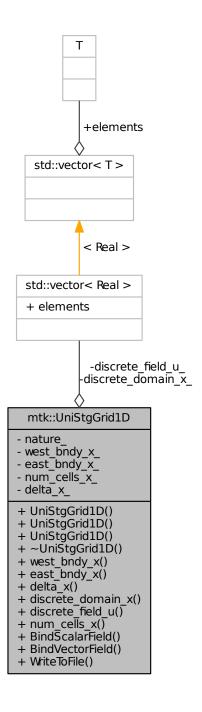
- include/mtk_tools.h
- src/mtk_tools.cc

16.18 mtk::UniStgGrid1D Class Reference

Uniform 1D Staggered Grid.

```
#include <mtk_uni_stg_grid_ld.h>
```

Collaboration diagram for mtk::UniStgGrid1D:



Public Member Functions

• UniStgGrid1D ()

Default constructor.

• UniStgGrid1D (const UniStgGrid1D &grid)

Copy constructor.

UniStgGrid1D (const Real &west_bndy_x, const Real &east_bndy_x, const int &num_cells_x, const mtk::Field
 Nature &nature=mtk::SCALAR)

Construct a grid based on spatial discretization parameters.

∼UniStgGrid1D ()

Destructor.

Real west_bndy_x () const

Provides access to west boundary spatial coordinate.

Real east_bndy_x () const

Provides access to east boundary spatial coordinate.

Real delta_x () const

Provides access to the computed \$ x \$.

• const Real * discrete_domain_x () const

Provides access to the grid spatial data.

Real * discrete_field_u ()

Provides access to the grid field data.

int num_cells_x () const

Provides access to the number of cells of the grid.

void BindScalarField (Real(*ScalarField)(Real xx))

Binds a given scalar field to the grid.

void BindVectorField (Real(*VectorField)(Real xx))

Binds a given vector field to the grid.

bool WriteToFile (std::string filename, std::string space_name, std::string field_name) const

Writes grid to a file compatible with gnuplot 4.6.

Private Attributes

FieldNature nature

Nature of the discrete field.

std::vector< Real > discrete_domain_x_

Array of spatial data.

std::vector< Real > discrete_field_u_

Array of field's data.

Real west bndy x

West boundary spatial coordinate.

• Real east_bndy_x_

East boundary spatial coordinate.

Real num_cells_x_

Number of cells discretizing the domain.

· Real delta_x_

Produced Δx .

Friends

std::ostream & operator<< (std::ostream &stream, UniStgGrid1D &in)

Prints the grid as a tuple of arrays.

16.18.1 Detailed Description

Uniform 1D Staggered Grid.

Definition at line 77 of file mtk_uni_stg_grid_1d.h.

16.18.2 Constructor & Destructor Documentation

16.18.2.1 mtk::UniStgGrid1D::UniStgGrid1D()

Definition at line 99 of file mtk_uni_stg_grid_1d.cc.

16.18.2.2 mtk::UniStgGrid1D::UniStgGrid1D (const UniStgGrid1D & grid)

Parameters

in	grid	Given grid.

Definition at line 108 of file mtk_uni_stg_grid_1d.cc.

16.18.2.3 mtk::UniStgGrid1D::UniStgGrid1D (const Real & west_bndy_x, const Real & east_bndy_x, const int & num_cells_x, const mtk::FieldNature & nature = mtk::SCALAR)

Parameters

in	west_bndy_x	Coordinate for the west boundary.
in	east_bndy_x	Coordinate for the east boundary.
in	num_cells_x	Number of cells of the required grid.
in	nature	Nature of the discrete field to hold.

See also

mtk::FieldNature

Definition at line 124 of file mtk_uni_stg_grid_1d.cc.

Here is the call graph for this function:



16.18.2.4 mtk::UniStgGrid1D::~UniStgGrid1D()

Definition at line 144 of file mtk_uni_stg_grid_1d.cc.

16.18.3 Member Function Documentation

16.18.3.1 void mtk::UniStgGrid1D::BindScalarField (Real(*)(Real xx) ScalarField)

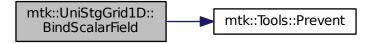
Parameters

	0 / 5: //	
ın	ScalarField	Pointer to the function implementing the scalar field.

- 1. Create collection of spatial coordinates.
- 2. Create collection of field samples.

Definition at line 176 of file mtk_uni_stg_grid_1d.cc.

Here is the call graph for this function:



16.18.3.2 void mtk::UniStgGrid1D::BindVectorField (Real(*)(Real xx) VectorField)

We assume the field to be of the form:

$$\mathbf{v}(x) = v(x)\hat{\mathbf{i}}$$

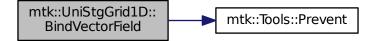
Parameters

in	VectorField	Pointer to the function implementing the vector field.

- 1. Create collection of spatial coordinates.
- 2. Create collection of field samples.

Definition at line 212 of file mtk_uni_stg_grid_1d.cc.

Here is the call graph for this function:



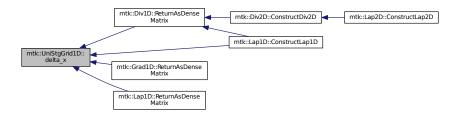
16.18.3.3 mtk::Real mtk::UniStgGrid1D::delta_x () const

Returns

Computed \$ x \$.

Definition at line 156 of file mtk_uni_stg_grid_1d.cc.

Here is the caller graph for this function:



16.18.3.4 const mtk::Real * mtk::UniStgGrid1D::discrete_domain_x () const

Returns

Pointer to the spatial data.

Todo Review const-correctness of the pointer we return.

Definition at line 161 of file mtk_uni_stg_grid_1d.cc.

16.18.3.5 mtk::Real * mtk::UniStgGrid1D::discrete_field_u ()

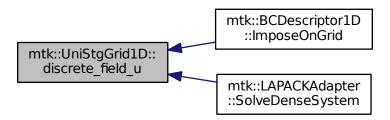
Returns

Pointer to the field data.

Todo Review const-correctness of the pointer we return. Look at the STL!

Definition at line 166 of file mtk_uni_stg_grid_1d.cc.

Here is the caller graph for this function:



16.18.3.6 mtk::Real mtk::UniStgGrid1D::east_bndy_x () const

Returns

East boundary spatial coordinate.

Definition at line 151 of file mtk_uni_stg_grid_1d.cc.

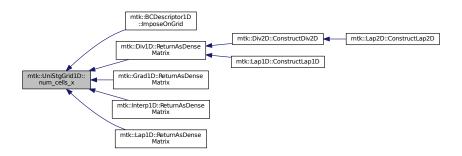
16.18.3.7 int mtk::UniStgGrid1D::num_cells_x () const

Returns

Number of cells of the grid.

Definition at line 171 of file mtk_uni_stg_grid_1d.cc.

Here is the caller graph for this function:



16.18.3.8 mtk::Real mtk::UniStgGrid1D::west_bndy_x () const

Returns

West boundary spatial coordinate.

Definition at line 146 of file mtk_uni_stg_grid_1d.cc.

16.18.3.9 bool mtk::UniStgGrid1D::WriteToFile (std::string filename, std::string space_name, std::string field_name) const

Parameters

in	filename	Name of the output file.
in	space_name	Name for the first column of the data.
in	field_name	Name for the second column of the data.

Returns

Success of the file writing process.

See also

http://www.gnuplot.info/

Definition at line 240 of file mtk_uni_stg_grid_1d.cc.

16.18.4 Friends And Related Function Documentation

16.18.4.1 std::ostream & operator << (std::ostream & stream, mtk::UniStgGrid1D & in) [friend]

- 1. Print spatial coordinates.
- 2. Print scalar field.

Definition at line 68 of file mtk_uni_stg_grid_1d.cc.

16.18.5 Member Data Documentation

16.18.5.1 Real mtk::UniStgGrid1D::delta_x [private]

Definition at line 200 of file mtk_uni_stg_grid_1d.h.

16.18.5.2 std::vector<Real> mtk::UniStgGrid1D::discrete_domain_x_ [private]

Definition at line 194 of file mtk_uni_stg_grid_1d.h.

16.18.5.3 std::vector<Real> mtk::UniStgGrid1D::discrete_field_u_ [private]

Definition at line 195 of file mtk_uni_stg_grid_1d.h.

```
16.18.5.4 Real mtk::UniStgGrid1D::east_bndy_x_ [private]
```

Definition at line 198 of file mtk_uni_stg_grid_1d.h.

```
16.18.5.5 FieldNature mtk::UniStgGrid1D::nature [private]
```

Definition at line 192 of file mtk_uni_stg_grid_1d.h.

```
16.18.5.6 Real mtk::UniStgGrid1D::num_cells_x_ [private]
```

Definition at line 199 of file mtk_uni_stg_grid_1d.h.

```
16.18.5.7 Real mtk::UniStgGrid1D::west_bndy_x_ [private]
```

Definition at line 197 of file mtk_uni_stg_grid_1d.h.

The documentation for this class was generated from the following files:

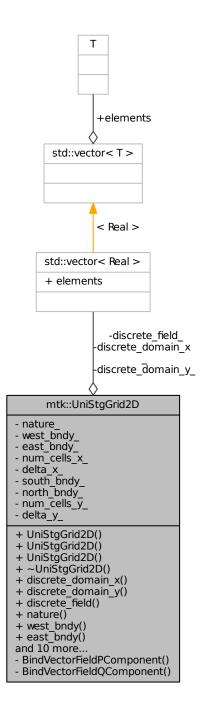
- include/mtk_uni_stg_grid_1d.h
- src/mtk_uni_stg_grid_1d.cc

16.19 mtk::UniStgGrid2D Class Reference

Uniform 2D Staggered Grid.

#include <mtk_uni_stg_grid_2d.h>

Collaboration diagram for mtk::UniStgGrid2D:



Public Member Functions

• UniStgGrid2D ()

Default constructor.

UniStgGrid2D (const UniStgGrid2D &grid)

Copy constructor.

UniStgGrid2D (const Real &west_bndy_x, const Real &east_bndy_x, const int &num_cells_x, const Real &south_bndy_y, const Real &north_bndy_y, const int &num_cells_y, const mtk::FieldNature &nature=mtk::S

CALAR)

Construct a grid based on spatial discretization parameters.

∼UniStgGrid2D ()

Destructor.

const Real * discrete_domain_x () const

Provides access to the grid spatial data.

const Real * discrete_domain_y () const

Provides access to the grid spatial data.

Real * discrete_field ()

Provides access to the grid field data.

• FieldNature nature () const

Physical nature of the data bound to the grid.

Real west_bndy () const

Provides access to west boundary spatial coordinate.

Real east_bndy () const

Provides access to east boundary spatial coordinate.

• int num cells x () const

Provides access to the number of cells of the grid.

• Real delta_x () const

Provides access to the computed \$ x \$.

Real south_bndy () const

Provides access to south boundary spatial coordinate.

Real north_bndy () const

Provides access to north boundary spatial coordinate.

int num_cells_y () const

Provides access to the number of cells of the grid.

Real delta_y () const

Provides access to the computed \$ y \$.

• bool Bound () const

Have any field been bound to the grid?

void BindScalarField (Real(*ScalarField)(Real xx, Real yy))

Binds a given scalar field to the grid.

void BindVectorField (Real(*VectorFieldPComponent)(Real xx, Real yy), Real(*VectorFieldQComponent)(Real xx, Real yy))

Binds a given vector field to the grid.

bool WriteToFile (std::string filename, std::string space_name_x, std::string space_name_y, std::string field_
 name) const

Writes grid to a file compatible with Gnuplot 4.6.

Private Member Functions

void BindVectorFieldPComponent (Real(*VectorFieldPComponent)(Real xx, Real yy))

Binds a given component of a vector field to the grid.

void BindVectorFieldQComponent (Real(*VectorFieldQComponent)(Real xx, Real yy))

Binds a given component of a vector field to the grid.

Private Attributes

std::vector< Real > discrete_domain_x_

Array of spatial data.

std::vector< Real > discrete_domain_y_

Array of spatial data.

std::vector< Real > discrete_field_

Array of field's data.

FieldNature nature_

Nature of the discrete field.

Real west_bndy_

West boundary spatial coordinate.

Real east_bndy_

East boundary spatial coordinate.

int num_cells_x_

Number of cells discretizing the domain.

• Real delta_x_

Computed Δx .

· Real south_bndy_

West boundary spatial coordinate.

· Real north_bndy_

East boundary spatial coordinate.

int num_cells_y_

Number of cells discretizing the domain.

• Real delta_y_

Computed Δy .

Friends

std::ostream & operator<< (std::ostream &stream, UniStgGrid2D &in)

Prints the grid as a tuple of arrays.

16.19.1 Detailed Description

Uniform 2D Staggered Grid.

Definition at line 79 of file mtk_uni_stg_grid_2d.h.

16.19.2 Constructor & Destructor Documentation

16.19.2.1 mtk::UniStgGrid2D::UniStgGrid2D()

Definition at line 131 of file mtk_uni_stg_grid_2d.cc.

16.19.2.2 mtk::UniStgGrid2D::UniStgGrid2D (const UniStgGrid2D & grid)

Parameters

in	grid	Given grid.
----	------	-------------

Definition at line 145 of file mtk_uni_stg_grid_2d.cc.

16.19.2.3 mtk::UniStgGrid2D::UniStgGrid2D (const Real & west_bndy_x, const Real & east_bndy_x, const int & num_cells_x, const Real & south_bndy_y, const Real & north_bndy_y, const int & num_cells_y, const mtk::FieldNature & nature = mtk::SCALAR)

Parameters

in	west_bndy_x	Coordinate for the west boundary.
in	east_bndy_x	Coordinate for the east boundary.
in	num_cells_x	Number of cells of the required grid.
in	south_bndy_y	Coordinate for the west boundary.
in	north_bndy_y	Coordinate for the east boundary.
in	num_cells_y	Number of cells of the required grid.
in	nature	Nature of the discrete field to hold.

See also

mtk::FieldNature

Definition at line 169 of file mtk_uni_stg_grid_2d.cc.

Here is the call graph for this function:



16.19.2.4 mtk::UniStgGrid2D:: \sim UniStgGrid2D ()

Definition at line 203 of file mtk_uni_stg_grid_2d.cc.

16.19.3 Member Function Documentation

16.19.3.1 void mtk::UniStgGrid2D::BindScalarField (Real(*)(Real xx, Real yy) ScalarField)

Parameters

in	ScalarField	Pointer to the function implementing the scalar field.

- 1. Create collection of spatial coordinates for x.
- 2. Create collection of spatial coordinates for *y*.
- 3. Create collection of field samples.

Definition at line 270 of file mtk_uni_stg_grid_2d.cc.

Here is the call graph for this function:



16.19.3.2 void mtk::UniStgGrid2D::BindVectorField (Real(*)(Real xx, Real yy) VectorFieldPComponent, Real(*)(Real xx, Real yy) VectorFieldQComponent)

We assume the field to be of the form:

$$\mathbf{v}(x) = p(x, y)\mathbf{\hat{i}} + q(x, y)\mathbf{\hat{j}}$$

Parameters

in	VectorFieldP⊷	Pointer to the function implementing the \$ p \$ component of the vector field.
	Component	
in	VectorFieldP⇔	Pointer to the function implementing the \$ q \$ component of the vector field.
	Component	

Definition at line 417 of file mtk_uni_stg_grid_2d.cc.

Here is the call graph for this function:



16.19.3.3 void mtk::UniStgGrid2D::BindVectorFieldPComponent (Real(*)(Real xx, Real yy) VectorFieldPComponent)

[private]

We assume the field to be of the form:

$$\mathbf{v}(x) = p(x, y)\hat{\mathbf{i}} + q(x, y)\hat{\mathbf{j}}$$

Parameters

in	BindVectorField↔	Pointer to the function implementing the \$ p \$ component of the vector field.
	PComponent	

- 1. Create collection of spatial coordinates for x.
- 2. Create collection of spatial coordinates for y.
- 3. Allocate space for discrete vector field and bind \$ p \$ component.

Definition at line 324 of file mtk_uni_stg_grid_2d.cc.

16.19.3.4 void mtk::UniStgGrid2D::BindVectorFieldQComponent (Real(*)(Real xx, Real yy) VectorFieldQComponent)

[private]

We assume the field to be of the form:

$$\mathbf{v}(x) = p(x, y)\mathbf{\hat{i}} + q(x, y)\mathbf{\hat{j}}$$

Parameters

in	BindVectorField⊷	Pointer to the function implementing the \$ q \$ component of the vector field.
	QComponent	

1. Bind \$ q \$ component, since \$ p \$ component has already been bound.

Definition at line 389 of file mtk_uni_stg_grid_2d.cc.

16.19.3.5 bool mtk::UniStgGrid2D::Bound () const

Returns

True is a field has been bound.

Definition at line 255 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



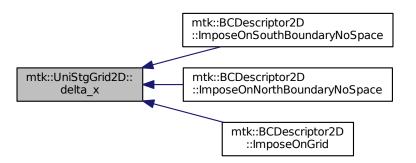
16.19.3.6 mtk::Real mtk::UniStgGrid2D::delta_x () const

Returns

Computed \$ x \$.

Definition at line 225 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



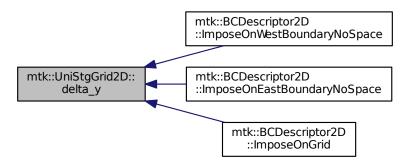
16.19.3.7 mtk::Real mtk::UniStgGrid2D::delta_y () const

Returns

Computed \$ y \$.

Definition at line 250 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.8 const mtk::Real * mtk::UniStgGrid2D::discrete_domain_x () const

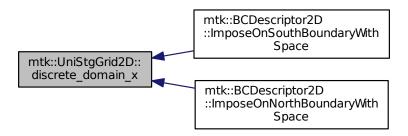
Returns

Pointer to the spatial data.

Todo Review const-correctness of the pointer we return.

Definition at line 230 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.9 const mtk::Real * mtk::UniStgGrid2D::discrete_domain_y () const

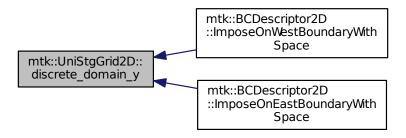
Returns

Pointer to the spatial data.

Todo Review const-correctness of the pointer we return.

Definition at line 260 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



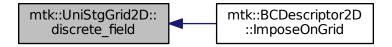
16.19.3.10 mtk::Real * mtk::UniStgGrid2D::discrete_field ()

Returns

Pointer to the field data.

Definition at line 265 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.11 mtk::Real mtk::UniStgGrid2D::east_bndy() const

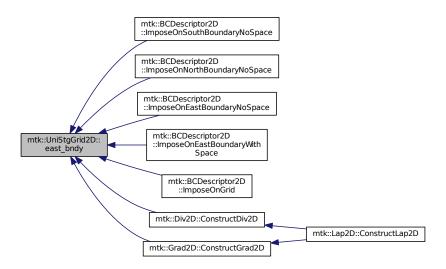
196 Class Documentation

Returns

East boundary spatial coordinate.

Definition at line 215 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.12 mtk::FieldNature mtk::UniStgGrid2D::nature () const

Returns

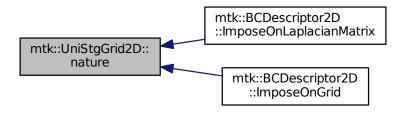
Value of an enumeration.

See also

mtk::FieldNature

Definition at line 205 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



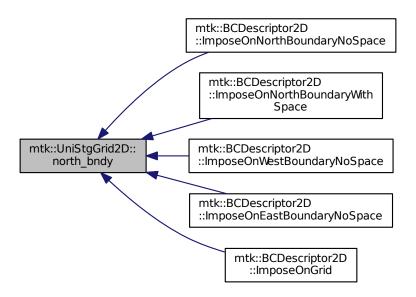
16.19.3.13 mtk::Real mtk::UniStgGrid2D::north_bndy () const

Returns

North boundary spatial coordinate.

Definition at line 240 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.14 int mtk::UniStgGrid2D::num_cells_x () const

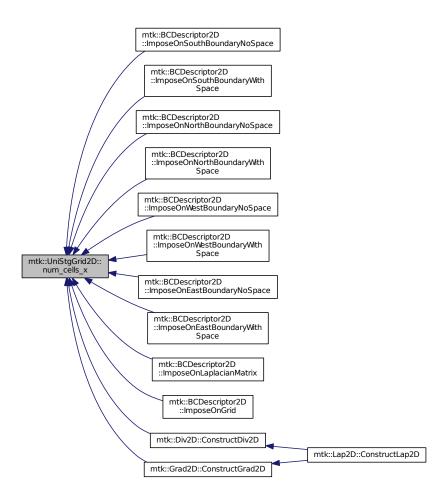
198 Class Documentation

Returns

Number of cells of the grid.

Definition at line 220 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



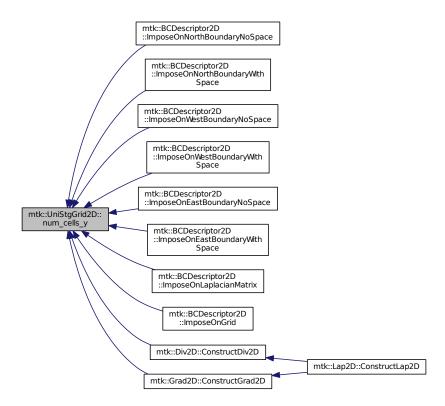
16.19.3.15 int mtk::UniStgGrid2D::num_cells_y () const

Returns

Number of cells of the grid.

Definition at line 245 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



16.19.3.16 mtk::Real mtk::UniStgGrid2D::south_bndy () const

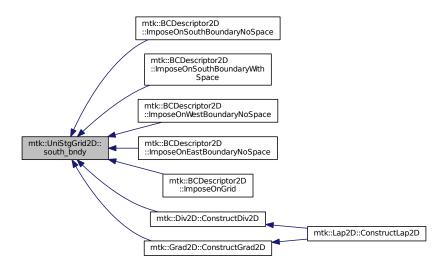
200 Class Documentation

Returns

South boundary spatial coordinate.

Definition at line 235 of file mtk_uni_stg_grid_2d.cc.

Here is the caller graph for this function:



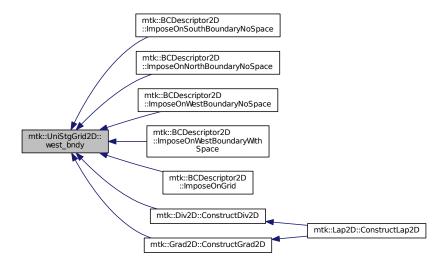
16.19.3.17 mtk::Real mtk::UniStgGrid2D::west_bndy () const

Returns

West boundary spatial coordinate.

Definition at line 210 of file $mtk_uni_stg_grid_2d.cc$.

Here is the caller graph for this function:



16.19.3.18 bool mtk::UniStgGrid2D::WriteToFile (std::string filename, std::string space_name_x, std::string field_name) const

Parameters

in	filename	Name of the output file.
in	space_name_x	Name for the first column of the (spatial) data.
in	space_name_y	Name for the second column of the (spatial) data.
in	field_name	Name for the second column of the (physical field) data.

Returns

Success of the file writing process.

See also

Write the values of the p component, with a null q component.

Write the values of the q component, with a null p component.

Definition at line 429 of file mtk_uni_stg_grid_2d.cc.

16.19.4 Friends And Related Function Documentation

16.19.4.1 std::ostream& operator<<(std::ostream & stream, mtk::UniStgGrid2D & in) [friend]

1. Print spatial coordinates.

202 Class Documentation

2. Print scalar field.

```
Definition at line 67 of file mtk_uni_stg_grid_2d.cc.
```

```
16.19.5 Member Data Documentation
```

```
16.19.5.1 Real mtk::UniStgGrid2D::delta_x_ [private]
```

Definition at line 296 of file mtk_uni_stg_grid_2d.h.

16.19.5.2 Real mtk::UniStgGrid2D::delta_y_ [private]

Definition at line 301 of file mtk_uni_stg_grid_2d.h.

16.19.5.3 std::vector<Real> mtk::UniStgGrid2D::discrete_domain_x_ [private]

Definition at line 287 of file mtk_uni_stg_grid_2d.h.

16.19.5.4 std::vector<Real> mtk::UniStgGrid2D::discrete_domain_y_ [private]

Definition at line 288 of file mtk_uni_stg_grid_2d.h.

16.19.5.5 std::vector<Real> mtk::UniStgGrid2D::discrete_field_ [private]

Definition at line 289 of file mtk_uni_stg_grid_2d.h.

16.19.5.6 Real mtk::UniStgGrid2D::east_bndy_ [private]

Definition at line 294 of file mtk_uni_stg_grid_2d.h.

16.19.5.7 FieldNature mtk::UniStgGrid2D::nature [private]

Definition at line 291 of file mtk_uni_stg_grid_2d.h.

16.19.5.8 Real mtk::UniStgGrid2D::north_bndy_ [private]

Definition at line 299 of file mtk uni stg grid 2d.h.

16.19.5.9 int mtk::UniStgGrid2D::num_cells_x_ [private]

Definition at line 295 of file mtk_uni_stg_grid_2d.h.

16.19.5.10 int mtk::UniStgGrid2D::num_cells_y_ [private]

Definition at line 300 of file mtk uni stg grid 2d.h.

16.19.5.11 Real mtk::UniStgGrid2D::south_bndy [private]

Definition at line 298 of file mtk_uni_stg_grid_2d.h.

16.19.5.12 Real mtk::UniStgGrid2D::west_bndy_ [private]

Definition at line 293 of file mtk_uni_stg_grid_2d.h.

The documentation for this class was generated from the following files:

- include/mtk_uni_stg_grid_2d.h
- src/mtk_uni_stg_grid_2d.cc

204	Class Documentation

Chapter 17

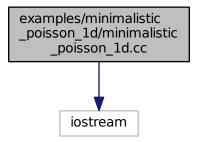
File Documentation

17.1 examples/minimalistic_poisson_1d/minimalistic_poisson_1d.cc File Reference

Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs.

#include <iostream>

Include dependency graph for minimalistic_poisson_1d.cc:



Functions

• int main ()

17.1.1 Detailed Description

We solve:

$$\nabla^2 p(x) = -s(x),$$

for
$$x \in \Omega = [a, b] = [0, 1]$$
.

The source term function is defined as

$$s(x) = \frac{\lambda^2 \exp(\lambda x)}{\exp(\lambda) - 1}$$

where $\lambda = -1$ is a parameter.

We consider Robin's boundary conditions of the form:

$$\alpha p(a) - \beta p'(a) = \omega$$

$$\alpha p(b) + \beta p'(b) = \varepsilon$$
.

The analytical solution for this problem is given by

$$p(x) = \frac{\exp(\lambda x) - 1}{\exp(\lambda) - 1}.$$

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Raul Vargas-Navarro - vargasna at rohan dot sdsu dot edu

Definition in file minimalistic poisson 1d.cc.

17.1.2 Function Documentation

17.1.2.1 int main ()

Definition at line 167 of file minimalistic poisson 1d.cc.

17.2 minimalistic_poisson_1d.cc

```
00001
00042 /*
00043 Copyright (C) 2015, Computational Science Research Center, San Diego State
00044 University. All rights reserved.
00046 Redistribution and use in source and binary forms, with or without modification,
00047 are permitted provided that the following conditions are met:
00049 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00050 and a copy of the modified files should be reported once modifications are
00051 completed, unless these modifications are made through the project's GitHub
00052 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00053 should be developed and included in any deliverable.
00055 2. Redistributions of source code must be done through direct
00056 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00058 3. Redistributions in binary form must reproduce the above copyright notice, 00059 this list of conditions and the following disclaimer in the documentation and/or
{\tt 00060} other materials provided with the distribution.
00061
00062 4. Usage of the binary form on proprietary applications shall require explicit
00063 prior written permission from the the copyright holders, and due credit should
00064 be given to the copyright holders.
```

```
00065
00066 5. Neither the name of the copyright holder nor the names of its contributors
00067 may be used to endorse or promote products derived from this software without
00068 specific prior written permission.
00070 The copyright holders provide no reassurances that the source code provided does
00071 not infringe any patent, copyright, or any other intellectual property rights of
00072 third parties. The copyright holders disclaim any liability to any recipient for
00073 claims brought against recipient by any third party for infringement of that
00074 parties intellectual property rights.
00075
00076 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00077 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00078 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00079 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00080 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00081 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00082 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00083 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00084 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00085 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00087
00088 #if __cplusplus == 201103L
00089
00090 #include <iostream>
00091 #include <fstream>
00092 #include <cmath>
00093 #include <vector>
00094
00095 #include "mtk.h"
00096
00097 mtk::Real Source(mtk::Real xx) {
00098 mtk::Real lambda = -1.0;
00099
       return lambda*lambda*exp(lambda*xx)/(exp(lambda) - 1.0);
00100 }
00101
00102 mtk::Real KnownSolution(mtk::Real xx) {
00103 mtk::Real lambda = -1.0;
       return (exp(lambda*xx) - 1.0)/(exp(lambda) - 1.0);
00104
00105 }
00106
00107 int main () {
00108
00109
       mtk::Real west_bndy_x = 0.0;
00110
       mtk::Real east_bndy_x = 1.0;
00111
       mtk::Real relative_norm_2_error{};
00112
       int num_cells_x = 5;
00113
       mtk::Grad1D grad;
00114
       mtk::Lap1D lap;
00115
        std::vector<mtk::Real> west_coeffs;
00116
        std::vector<mtk::Real> east_coeffs;
       mtk::UniStgGrid1D source(west_bndy_x, east_bndy_x, num_cells_x);
00117
00118
        mtk::UniStgGrid1D comp_sol(west_bndy_x, east_bndy_x, num_cells_x);
00119
       mtk::UniStgGrid1D known_sol(west_bndy_x, east_bndy_x, num_cells_x);
00120
00121
        if (!lap.ConstructLap1D()) {
00122
         std::cerr << "Mimetic lap could not be built." << std::endl;
00123
         return EXIT_FAILURE;
00124
00125
       mtk::DenseMatrix lapm(lap.ReturnAsDenseMatrix(comp_sol));
00126
        if (!grad.ConstructGrad1D()) {
00127
          std::cerr << "Mimetic grad could not be built." << std::endl;</pre>
00128
         return EXIT_FAILURE;
00129
00130
        mtk::DenseMatrix gradm(grad.ReturnAsDenseMatrix(comp_sol));
00131
00132
        source.BindScalarField(Source);
00133
00134
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00135
         west_coeffs.push_back(-((exp(-1.0) - 1.0)/-1.0)*gradm.GetValue(0, ii));
00136
00137
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00138
          east coeffs.push back(
00139
            ((\exp(-1.0) - 1.0)/-1.0)*gradm.GetValue(gradm.num_rows() - 1,
00140
                                                    gradm.num_cols() - 1 - ii));
00141
00142
       west coeffs[0] += -\exp(-1.0);
       east_coeffs[0] += -\exp(-1.0);
00143
       mtk::BCDescriptor1D::ImposeOnLaplacianMatrix(lapm,
00144
      west_coeffs, east_coeffs);
```

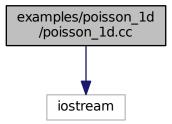
```
00145
        mtk::BCDescriptor1D::ImposeOnGrid(source, -1.0, 0.0);
00146
00147
        int info{mtk::LAPACKAdapter::SolveDenseSystem(lapm, source)};
00148
        if (info != 0) {
00149
         std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
00150
         return EXIT_FAILURE;
00151
00152
00153
        source.WriteToFile("minimalistic_poisson_1d_comp_sol.dat", "x", "~u(x)");
00154
        known_sol.BindScalarField(KnownSolution);
        relative_norm_2_error =
00156
         mtk::BLASAdapter::RelNorm2Error(source.discrete_field_u(),
00157
                                           known_sol.discrete_field_u(),
00158
                                           known_sol.num_cells_x());
00159
        std::cout << "relative_norm_2_error = ";
00160
       std::cout << relative_norm_2_error << std::endl;
00161 }
00162
00163 #else
00164 #include <iostream>
00165 using std::cout;
00166 using std::endl;
00167 int main () {
00168 cout << "This code HAS to be compiled with support for C++11." << endl;
00170
       return EXIT_SUCCESS;
00171 }
00172 #endif
```

17.3 examples/poisson_1d/poisson_1d.cc File Reference

Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs.

#include <iostream>

Include dependency graph for poisson 1d.cc:



Functions

• int main ()

17.3.1 Detailed Description

We solve:

$$\nabla^2 p(x) = -s(x),$$

17.4 poisson_ld.cc 209

for
$$x \in \Omega = [a, b] = [0, 1]$$
.

The source term function is defined as

$$s(x) = \frac{\lambda^2 \exp(\lambda x)}{\exp(\lambda) - 1}$$

where $\lambda = -1$ is a parameter.

We consider Robin's boundary conditions of the form:

$$\alpha p(a) - \beta p'(a) = \omega$$
,

$$\alpha p(b) + \beta p'(b) = \varepsilon$$
.

The analytical solution for this problem is given by

$$p(x) = \frac{\exp(\lambda x) - 1}{\exp(\lambda) - 1}.$$

Author

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Raul Vargas-Navarro vargasna at rohan dot sdsu dot edu

Definition in file poisson 1d.cc.

17.3.2 Function Documentation

```
17.3.2.1 int main ( )
```

Definition at line 261 of file poisson 1d.cc.

17.4 poisson 1d.cc

```
00001
00042 /*
00043 Copyright (C) 2015, Computational Science Research Center, San Diego State
00044 University. All rights reserved.
00046 Redistribution and use in source and binary forms, with or without modification,
00047 are permitted provided that the following conditions are met:
00049 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00050 and a copy of the modified files should be reported once modifications are
00051 completed, unless these modifications are made through the project's GitHub
00052 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00053 should be developed and included in any deliverable.
00054
00055 2. Redistributions of source code must be done through direct
00056 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00057
00058 3. Redistributions in binary form must reproduce the above copyright notice, 00059 this list of conditions and the following disclaimer in the documentation and/or
00060 other materials provided with the distribution.
00061
00062 4. Usage of the binary form on proprietary applications shall require explicit
```

```
00063 prior written permission from the the copyright holders, and due credit should
00064 be given to the copyright holders.
00065
00066 5. Neither the name of the copyright holder nor the names of its contributors
00067 may be used to endorse or promote products derived from this software without
00068 specific prior written permission.
00070 The copyright holders provide no reassurances that the source code provided does
00071 not infringe any patent, copyright, or any other intellectual property rights of
00072 third parties. The copyright holders disclaim any liability to any recipient for
00073 claims brought against recipient by any third party for infringement of that
00074 parties intellectual property rights.
00076 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00077 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00078 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00079 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00080 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00081 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00082 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00083 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00084 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00085 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00086 */
00087
00088 #if __cplusplus == 201103L
00089
00090 #include <iostream>
00091 #include <fstream>
00092 #include <cmath>
00093
00094 #include <vector>
00095
00096 #include "mtk.h"
00097
00098 mtk::Real Source(mtk::Real xx) {
00099
00100
       mtk::Real lambda = -1.0;
00101
00102
        return lambda*lambda*exp(lambda*xx)/(exp(lambda) - 1.0);
00103 }
00104
00105 mtk::Real KnownSolution(mtk::Real xx) {
00106
00107
        mtk::Real lambda = -1.0;
00108
00109
        return (exp(lambda*xx) - 1.0)/(exp(lambda) - 1.0);
00110 }
00111
00112 int main () {
00113
00114
        std::cout << "Example: Poisson Equation on a 1D Uniform Staggered Grid ";
00115
        std::cout << "with Robin BCs." << std::endl;
00116
00118
00119
       mtk::Real lambda = -1.0;
00120
       mtk::Real alpha = -exp(lambda);
       mtk::Real beta = (exp(lambda) - 1.0)/lambda;
00121
00122
       mtk::Real omega = -1.0;
00123
       mtk::Real epsilon = 0.0;
00124
00126
00127
       mtk::Real west_bndy_x = 0.0;
00128
        mtk::Real east_bndy_x = 1.0;
00129
        int num_cells_x = 5;
00130
00131
        mtk::UniStgGrid1D comp_sol(west_bndy_x, east_bndy_x, num_cells_x);
00132
00134
00135
        int order_of_accuracy{2}; // Desired order of accuracy for approximation.
00136
00137
       mtk::Grad1D grad; // Mimetic gradient operator.
00138
        mtk::Lap1D lap; // Mimetic Laplacian operator.
00139
00140
00141
        if (!lap.ConstructLap1D(order of accuracy)) {
         std::cerr << "Mimetic lap could not be built." << std::endl;
00142
          return EXIT_FAILURE;
00143
00144
00145
00146
       mtk::DenseMatrix lapm(lap.ReturnAsDenseMatrix(comp sol));
```

17.4 poisson 1d.cc 211

```
00147
00148
        std::cout << "Mimetic Laplacian operator: " << std::endl;</pre>
00149
        std::cout << lapm << std::endl;
00150
00151
        if (!grad.ConstructGrad1D(order_of_accuracy)) {
00152
         std::cerr << "Mimetic grad could not be built." << std::endl;
00153
          return EXIT_FAILURE;
00154
00155
00156
        mtk::DenseMatrix gradm(grad.ReturnAsDenseMatrix(comp_sol));
00157
00158
        std::cout << "Mimetic gradient operator: " << std::endl;</pre>
00159
        std::cout << gradm << std::endl;
00160
00162
00163
        mtk::UniStgGrid1D source(west_bndy_x, east_bndy_x, num_cells_x);
00164
00165
        source.BindScalarField(Source);
00166
00167
        std::cout << source << std::endl;
00168
00170
00171
        // Since we need to approximate the first derivative times beta, we must use
00172
        // the approximation of the gradient at the boundary. We could extract them
00173
        // from the gradient operator as packed in the grad object. BUT, since we have
00174
        \ensuremath{//} generated at matrix containing this operator, we can extract these from the
00175
        // matrix.
00176
        \ensuremath{//} Array containing the coefficients for the west boundary condition.
00177
00178
        std::vector<mtk::Real> west_coeffs;
00179
00180
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00181
         west_coeffs.push_back(-beta*gradm.GetValue(0, ii));
00182
00183
00184
        // Array containing the coefficients for the east boundary condition.
00185
        std::vector<mtk::Real> east_coeffs;
00186
00187
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00188
          east_coeffs.push_back(beta*gradm.GetValue(gradm.num_rows() - 1,
00189
                                                      gradm.num_cols() - 1 - ii));
00190
00191
00192
        // To impose the Dirichlet condition, we simple add its coefficient to the
00193
        \ensuremath{//} first entry of the west, and the last entry of the east array.
00194
00195
        west_coeffs[0] += alpha;
00196
00197
        east_coeffs[0] += alpha;
00198
00199
        // Now that we have the coefficients that should be in the operator, we create
00200
        // a boundary condition descriptor object, which will encapsulate the
00201
        // complexity of assigning them in the matrix, to complete the construction of
00202
        // the mimetic operator.
00203
00204
        mtk::BCDescriptor1D::ImposeOnLaplacianMatrix(lapm,
     west_coeffs, east_coeffs);
00205
00206
        std::cout << "Mimetic Laplacian with Robin conditions:" << std::endl;
00207
        std::cout << lapm << std::endl;</pre>
00208
00209
        mtk::BCDescriptor1D::ImposeOnGrid(source, omega, epsilon);
00210
00211
        std::cout << "Source term with imposed BCs:" << std::endl;</pre>
00212
        std::cout << source << std::endl;
00213
00214
        source.WriteToFile("poisson_1d_source.dat", "x", "s(x)");
00215
00217
00218
        int info{mtk::LAPACKAdapter::SolveDenseSystem(lapm, source)};
00219
00220
        if (!info) {
00221
         std::cout << "System solved! Problem solved!" << std::endl;</pre>
00222
          std::cout << std::endl;
00223
00224
       else {
         std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
00225
          std::cerr << "Exiting..." << std::endl;
00226
00227
          return EXIT_FAILURE;
        }
00228
00229
```

```
00230
        std::cout << "Computed solution:" << std::endl;</pre>
00231
        std::cout << source << std::endl;
00232
00233
        source.WriteToFile("poisson_ld_comp_sol.dat", "x", "~u(x)");
00234
00236
00237
        mtk::UniStgGrid1D known_sol(west_bndy_x, east_bndy_x, num_cells_x);
00238
00239
        known_sol.BindScalarField(KnownSolution);
00240
00241
        std::cout << "known_sol =" << std::endl;
00242
        std::cout << known_sol << std::endl;
00243
00244
        known_sol.WriteToFile("poisson_ld_known_sol.dat", "x", "u(x)");
00245
00246
       mtk::Real relative_norm_2_error{}; // Relative norm 2 of the error.
00247
00248
       relative norm 2 error =
00249
          mtk::BLASAdapter::RelNorm2Error(source.discrete_field_u(),
00250
                                            known sol.discrete field u(),
00251
                                            known_sol.num_cells_x());
00252
00253
        std::cout << "relative norm 2 error = ";
00254
       std::cout << relative_norm_2_error << std::endl;</pre>
00255 }
00256
00257 #else
00258 #include <iostream>
00259 using std::cout;
00260 using std::endl;
00261 int main () { 00262 \, cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;</pre>
00263
00264
       return EXIT_SUCCESS;
00265 }
00266 #endif
```

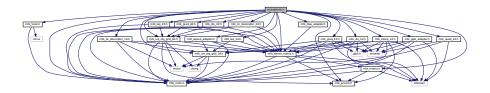
17.5 include/mtk.h File Reference

Includes the entire API.

```
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_tools.h"
#include "mtk_matrix.h"
#include "mtk_dense_matrix.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_uni_stg_grid_1d.h"
#include "mtk_uni_stg_grid_2d.h"
#include "mtk_grad_1d.h"
#include "mtk_div_1d.h"
#include "mtk_lap_1d.h"
#include "mtk_bc_descriptor_1d.h"
#include "mtk_quad_1d.h"
#include "mtk_interp_1d.h"
#include "mtk_grad_2d.h"
#include "mtk_div_2d.h"
#include "mtk_lap_2d.h"
#include "mtk_bc_descriptor_2d.h"
```

17.6 mtk.h 213

Include dependency graph for mtk.h:



17.5.1 Detailed Description

This file contains every required header file, thus containing the entire API. In this way, client codes only have to instruct #include "mtk.h".

Warning

IT IS EXTREMELY IMPORTANT THAT THE HEADERS ARE ADDED TO THIS FILE IN A SPECIFIC ORDER; THAT IS, CONSIDERING THE DEPENDENCE BETWEEN THE CLASSES THESE CONTAIN!

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk.h.

17.6 mtk.h

```
00001
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00018
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed, unless these modifications are made through the project's GitHub
00025 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00026 should be developed and included in any deliverable.
00028 2. Redistributions of source code must be done through direct
00029 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00031 3. Redistributions in binary form must reproduce the above copyright notice,
00032 this list of conditions and the following disclaimer in the documentation and/or
00033 other materials provided with the distribution.
00035 4. Usage of the binary form on proprietary applications shall require explicit
00036 prior written permission from the the copyright holders, and due credit should
00037 be given to the copyright holders.
00038
00039 5. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
```

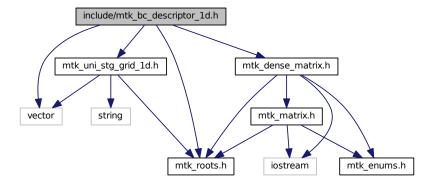
```
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00379 #ifndef MTK_INCLUDE_MTK_H_
00380 #define MTK_INCLUDE_MTK_H_
00389 #include "mtk_roots.h"
00390
00398 #include "mtk_enums.h"
00399
00407 #include "mtk_tools.h"
00408
00416 #include "mtk matrix.h"
00417 #include "mtk_dense_matrix.h"
00418
00426 #include "mtk_blas_adapter.h"
00427 #include "mtk_lapack_adapter.h"
00428 #include "mtk_glpk_adapter.h"
00429
00437 #include "mtk_uni_stg_grid_1d.h"
00438 #include "mtk_uni_stg_grid_2d.h"
00439
00447 #include "mtk_grad_1d.h"
00448 #include "mtk_div_ld.h"
00449 #include "mtk_lap_1d.h"
00450 #include "mtk_bc_descriptor_1d.h"
00451 #include "mtk_quad_1d.h'
00452 #include "mtk_interp_1d.h"
00453
00454 #include "mtk_grad_2d.h"
00455 #include "mtk_div_2d.h"
00456 #include "mtk_lap_2d.h"
00457 #include "mtk_bc_descriptor_2d.h"
00458
00459 #endif // End of: MTK_INCLUDE_MTK_H_
```

17.7 include/mtk_bc_descriptor_1d.h File Reference

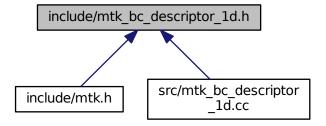
Enforces boundary conditions in either the operator or the grid.

```
#include <vector>
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
```

Include dependency graph for mtk_bc_descriptor_1d.h:



This graph shows which files directly or indirectly include this file:



Classes

• class mtk::BCDescriptor1D

Enforces boundary conditions in either the operator or the grid.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.7.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 1D mimetic operators and the grids they are acting on.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_bc_descriptor_1d.h.

17.8 mtk_bc_descriptor_1d.h

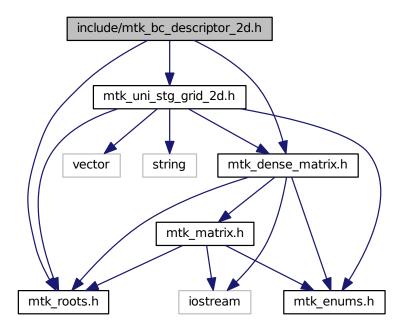
```
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <vector>
00059 #include "mtk_roots.h"
00060 #include "mtk_dense_matrix.h"
00061 #include "mtk_uni_stg_grid_ld.h"
00063 #ifndef MTK_INCLUDE_BC_DESCRIPTOR_1D_H_
00064 #define MTK_INCLUDE_BC_DESCRIPTOR_1D_H_
00065
00066 namespace mtk {
00067
00078 class BCDescriptor1D {
00079 public:
00087
       static void ImposeOnLaplacianMatrix(DenseMatrix &matrix,
00088
                                            const std::vector<Real> &west,
00089
                                            const std::vector<Real> &east);
00090
00098
       static void ImposeOnGrid(UniStgGrid1D &grid,
00099
                                 const Real &epsilon,
00100
                                 const Real & omega);
00101 };
```

```
00102 } 00103 #endif // End of: MTK_INCLUDE_BC_DESCRIPTOR_1D_H_
```

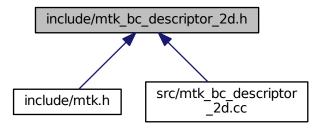
17.9 include/mtk_bc_descriptor_2d.h File Reference

Imposes boundary conditions in either the operator or the grid.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
Include dependency graph for mtk_bc_descriptor_2d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::BCDescriptor2D

Enforces boundary conditions in either the operator or the grid.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Typedefs

• typedef Real(* mtk::CoefficientFunction2D)(const Real &, const Real &)

A function of a BC coefficient evaluated on a 2D domain.

17.9.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 2D mimetic operators and the grids they are acting on.

Def. Let f be any scalar or vector field defined over a domain Ω . We can specify any linear combination of f and its n derivatives to fulfill a condition, which we define as a **boundary condition**:

$$\forall \mathbf{x} \in \partial \Omega : \sum_{i=0}^{n} c_i(\mathbf{x}) < \hat{\mathbf{n}}, \frac{\partial^i f}{\partial x^i}(\mathbf{x}) >= \beta(\mathbf{x}).$$

This class receives information about the highest-order of differentiation, n, all possible coefficient functions, $c_i(\mathbf{x})$ for any subset of the boundary (south, north, west and east), and each condition for any subset of the boundary, and takes care of assigning them to both, the differentiation matrices and the grids.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_bc_descriptor_2d.h.

17.10 mtk_bc_descriptor_2d.h

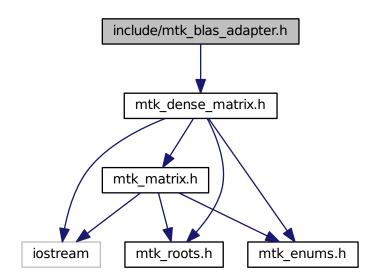
```
00031 Copyright (C) 2015, Computational Science Research Center, San Diego State
00032 University. All rights reserved.
00034 Redistribution and use in source and binary forms, with or without modification,
00035 are permitted provided that the following conditions are met:
00036
00037 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00038 and a copy of the modified files should be reported once modifications are
00039 completed, unless these modifications are made through the project's GitHub
00040 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00041 should be developed and included in any deliverable.
00043 2. Redistributions of source code must be done through direct
00044 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00045
00046 3. Redistributions in binary form must reproduce the above copyright notice,
00047 this list of conditions and the following disclaimer in the documentation and/or
00048 other materials provided with the distribution.
00049
00050 4. Usage of the binary form on proprietary applications shall require explicit
00051 prior written permission from the the copyright holders, and due credit should
00052 be given to the copyright holders.
00053
00054 5. Neither the name of the copyright holder nor the names of its contributors
00055 may be used to endorse or promote products derived from this software without
00056 specific prior written permission.
00057
00058 The copyright holders provide no reassurances that the source code provided does
00059 not infringe any patent, copyright, or any other intellectual property rights of
00060 third parties. The copyright holders disclaim any liability to any recipient for
00061 claims brought against recipient by any third party for infringement of that
00062 parties intellectual property rights.
00064 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00065 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00066 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00067 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00068 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00069 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00070 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00071 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00072 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00073 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00074 */
00075
00076 #ifndef MTK_INCLUDE_BC_DESCRIPTOR_2D_H_
00077 #define MTK_INCLUDE_BC_DESCRIPTOR_2D_H_
00078
00079 #include "mtk_roots.h"
00080 #include "mtk_dense_matrix.h"
00081 #include "mtk_uni_stg_grid_2d.h"
00083 namespace mtk{
00084
00092 typedef Real (*CoefficientFunction2D) (const Real &, const Real &);
00093
00123 class BCDescriptor2D {
00124 public:
00126
       BCDescriptor2D():
00127
       BCDescriptor2D(const BCDescriptor2D &desc);
00133
00134
00136
       ~BCDescriptor2D() noexcept;
00137
00143
        int highest_order_diff_west() const noexcept;
00144
```

```
00150
        int highest_order_diff_east() const noexcept;
00151
00157
        int highest_order_diff_south() const noexcept;
00158
00164
        int highest_order_diff_north() const noexcept;
00165
        void PushBackWestCoeff(CoefficientFunction2D cw);
00171
00172
00178
        void PushBackEastCoeff(CoefficientFunction2D ce);
00179
00185
        void PushBackSouthCoeff(CoefficientFunction2D cs);
00186
00192
        void PushBackNorthCoeff(CoefficientFunction2D cn);
00193
00199
        void set_west_condition(Real (*west_condition)(Real xx, Real yy)) noexcept;
00200
00206
        void set_east_condition(Real (*east_condition)(Real xx, Real yy)) noexcept;
00207
00213
        void set_south_condition(Real (*south_condition)(Real xx, Real yy)) noexcept;
00214
00220
        void set north condition (Real (*north condition) (Real xx, Real yy)) noexcept;
00221
00229
        void ImposeOnLaplacianMatrix(const UniStgGrid2D &grid,
00230
                                     DenseMatrix &matrix,
00231
                                     const int &order_accuracy = 2) const;
00232
00238
        void ImposeOnGrid(UniStaGrid2D &arid) const;
00239
00240 private:
       void ImposeOnSouthBoundaryNoSpace(const
00248
     mtk::UniStgGrid2D &grid,
00249
                                          mtk::DenseMatrix &matrix.
00250
                                          const int &order_accuracy) const;
       void ImposeOnNorthBoundaryNoSpace(const
00258
     mtk::UniStgGrid2D &grid,
00259
                                          mtk::DenseMatrix &matrix.
00260
                                          const int &order_accuracy) const;
00268
       void ImposeOnWestBoundaryNoSpace(const
     mtk::UniStgGrid2D &grid,
00269
                                         mtk::DenseMatrix &matrix,
00270
                                         const int &order_accuracy) const;
00278
       void ImposeOnEastBoundaryNoSpace(const
     mtk::UniStgGrid2D &grid,
00279
                                  mtk::DenseMatrix &matrix,
00280
                                  const int &order_accuracy) const;
00288
       void ImposeOnSouthBoundaryWithSpace(const
     mtk::UniStgGrid2D &grid,
00289
                                             mtk::DenseMatrix &matrix,
00290
                                             const int &order_accuracy) const;
00298
       void ImposeOnNorthBoundaryWithSpace(const
     mtk::UniStgGrid2D &grid,
00299
                                             mtk::DenseMatrix &matrix,
00300
                                             const int &order_accuracy) const;
00308
       void ImposeOnWestBoundaryWithSpace(const
      mtk::UniStgGrid2D &grid,
00309
                                           mtk::DenseMatrix &matrix,
00310
                                            const int &order_accuracy) const;
       void ImposeOnEastBoundaryWithSpace(const
00318
     mtk::UniStgGrid2D &grid,
00319
                                           mtk::DenseMatrix &matrix,
00320
                                           const int &order_accuracy) const;
00321
00322
       mutable bool generate_space_;
00323
00324
        int highest_order_diff_west_;
00325
        int highest_order_diff_east_;
00326
        int highest_order_diff_south_;
00327
        int highest_order_diff_north_;
00328
00329
        std::vector<CoefficientFunction2D> west_coefficients_;
00330
        std::vector<CoefficientFunction2D> east_coefficients_;
        std::vector<CoefficientFunction2D> south_coefficients_;
00331
00332
        std::vector<CoefficientFunction2D> north_coefficients_;
00333
00334
        Real (*west_condition_) (Real xx, Real yy);
        Real (*east_condition_) (Real xx, Real yy);
00335
00336
        Real (*south condition ) (Real xx, Real vy);
00337
        Real (*north_condition_) (Real xx, Real yy);
00338 };
00339 1
00340 #endif // End of: MTK INCLUDE BC DESCRIPTOR 2D H
```

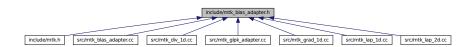
17.11 include/mtk_blas_adapter.h File Reference

Adapter class for the BLAS API.

#include "mtk_dense_matrix.h"
Include dependency graph for mtk_blas_adapter.h:



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::BLASAdapter

Adapter class for the BLAS API.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.11.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the BLAS.

The **BLAS** (**Basic Linear Algebra Subprograms**) are routines that provide standard building blocks for performing basic vector and matrix operations. The Level 1 BLAS perform scalar, vector and vector-vector operations, the Level 2 BLAS perform matrix-vector operations, and the Level 3 BLAS perform matrix operations.

The BLAS can be installed from links given in the See Also section of this page.

See also

```
http://www.netlib.org/blas/
https://software.intel.com/en-us/non-commercial-software-development
```

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk blas adapter.h.

17.12 mtk_blas_adapter.h

```
00024 /*
00025 Copyright (C) 2015, Computational Science Research Center, San Diego State
00026 University. All rights reserved.
00027
00028 Redistribution and use in source and binary forms, with or without modification,
00029 are permitted provided that the following conditions are met:
00030
00031 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00032 and a copy of the modified files should be reported once modifications are
00033 completed, unless these modifications are made through the project's GitHub
00034 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00035 should be developed and included in any deliverable.
00036
00037 2. Redistributions of source code must be done through direct
00038 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00040 3. Redistributions in binary form must reproduce the above copyright notice,
00041 this list of conditions and the following disclaimer in the documentation and/or
00042 other materials provided with the distribution.
00043
00044 4. Usage of the binary form on proprietary applications shall require explicit
00045 prior written permission from the the copyright holders, and due credit should
00046 be given to the copyright holders.
00048 5. Neither the name of the copyright holder nor the names of its contributors
00049 may be used to endorse or promote products derived from this software without
00050 specific prior written permission.
00052 The copyright holders provide no reassurances that the source code provided does
00053 not infringe any patent, copyright, or any other intellectual property rights of
00054 third parties. The copyright holders disclaim any liability to any recipient for
00055 claims brought against recipient by any third party for infringement of that
00056 parties intellectual property rights.
00058 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00059 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00060 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00061 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00062 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00063 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00064 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00065 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00066 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
```

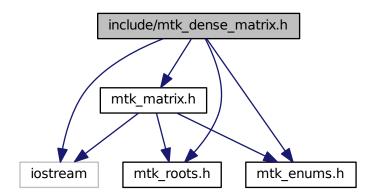
```
00067 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00068 */
00069
00070 #ifndef MTK_INCLUDE_BLAS_ADAPTER_H_
00071 #define MTK_INCLUDE_BLAS_ADAPTER_H_
00072
00073 #include "mtk_dense_matrix.h"
00074
00075 namespace mtk {
00076
00096 class BLASAdapter {
00097 public:
00106
       static Real RealNRM2 (Real *in, int &in_length);
00124
       static void RealAXPY(Real alpha, Real *xx, Real *yy, int &in_length);
00125
00140
       static Real RelNorm2Error (Real *computed, Real *known, int length);
00141
       static void RealDenseMV(Real &alpha,
00159
00160
                                DenseMatrix &aa,
00161
                                Real *xx,
00162
                                Real &beta,
00163
                                Real *yy);
00164
       static DenseMatrix RealDenseMM(DenseMatrix &aa,
00179
     DenseMatrix &bb);
00180 };
00181 }
00182 #endif // End of: MTK_INCLUDE_BLAS_ADAPTER_H_
```

17.13 include/mtk_dense_matrix.h File Reference

Defines a common dense matrix, using a 1D array.

```
#include <iostream>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_matrix.h"
```

Include dependency graph for mtk_dense_matrix.h:



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::DenseMatrix

Defines a common dense matrix, using a 1D array.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.13.1 Detailed Description

For developing purposes, it is better to have a not-so-intrincated data structure implementing matrices. This is the purpose of this class: to be used for prototypes of new code for small test cases. In every other instance, this should be replaced by the most appropriate sparse matrix.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Note

We prefer composition to inheritance [Reedy, 2011]. The main reason for this preference is that inheritance produces a more tightly coupled design. When a class inherits from another type be it public, protected, or private inheritance the subclass gains access to all public and protected members of the base class, whereas with composition, the class is only coupled to the public members of the other class. Furthermore, if you only hold a pointer to the other object, then your interface can use a forward declaration of the class rather than #include its full definition. This results in greater compile-time insulation and improves the time it takes to compile your code.

Definition in file mtk_dense_matrix.h.

17.14 mtk_dense_matrix.h

```
00001 00023 /*
00024 Copyright (C) 2015, Computational Science Research Center, San Diego State 00025 University. All rights reserved.
00026 00027 Redistribution and use in source and binary forms, with or without modification, 00028 are permitted provided that the following conditions are met:
00029 00030 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu 00031 and a copy of the modified files should be reported once modifications are 00032 completed, unless these modifications are made through the project's GitHub 00033 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications 00034 should be developed and included in any deliverable.
```

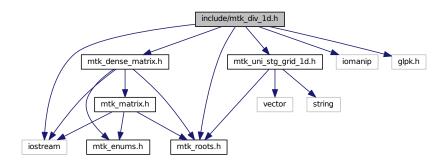
```
00035
00036 2. Redistributions of source code must be done through direct
00037 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00039 3. Redistributions in binary form must reproduce the above copyright notice,
00040 this list of conditions and the following disclaimer in the documentation and/or
00041 other materials provided with the distribution.
00042
00043 4. Usage of the binary form on proprietary applications shall require explicit
00044 prior written permission from the the copyright holders, and due credit should
00045 be given to the copyright holders.
00047 5. Neither the name of the copyright holder nor the names of its contributors
00048 may be used to endorse or promote products derived from this software without
00049 specific prior written permission.
00051 The copyright holders provide no reassurances that the source code provided does
00052 not infringe any patent, copyright, or any other intellectual property rights of
00053 third parties. The copyright holders disclaim any liability to any recipient for
00054 claims brought against recipient by any third party for infringement of that
00055 parties intellectual property rights.
00056
00057 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00058 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00059 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00060 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00061 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00062 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00063 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00064 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00065 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00066 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00067 */
00068
00069 #ifndef MTK_INCLUDE_DENSE_MATRIX_H_
00070 #define MTK_INCLUDE_DENSE_MATRIX_H_
00071
00072 #include <iostream>
00073
00074 #include "mtk_roots.h"
00075 #include "mtk_enums.h"
00076 #include "mtk_matrix.h"
00077
00078 namespace mtk {
00079
00092 class DenseMatrix {
00093 public:
00095
        friend std::ostream& operator <<(std::ostream &stream, DenseMatrix &in);</pre>
00096
00098
        DenseMatrix& operator = (const DenseMatrix &in);
00099
00101
       bool operator ==(const DenseMatrix &in);
00102
00104
        DenseMatrix();
00105
00111
        DenseMatrix(const DenseMatrix &in);
00112
00121
        DenseMatrix(const int &num_rows, const int &num_cols);
00122
00148
        DenseMatrix(const int &rank, const bool &padded, const bool &transpose);
00149
00183
        DenseMatrix(const Real *const gen,
00184
                   const int &gen_length,
00185
                    const int &pro_length,
00186
                    const bool &transpose);
00187
00189
        ~DenseMatrix();
00190
00196
        Matrix matrix_properties() const noexcept;
00197
00203
        int num rows() const noexcept;
00204
00210
        int num cols() const noexcept;
00211
00217
        Real* data() const noexcept;
00218
00226
        void SetOrdering(mtk::MatrixOrdering oo) noexcept;
00227
00236
        Real GetValue (const int &row coord, const int &col coord) const noexcept;
00237
00245
       void SetValue(const int &row coord,
```

```
00246
                      const int &col_coord,
00247
                      const Real &val) noexcept;
00248
00250
       void Transpose();
00251
00253
       void OrderRowMajor();
00254
00256
       void OrderColMajor();
00257
00268
       static DenseMatrix Kron(const DenseMatrix &aa,
00269
                                const DenseMatrix &bb);
00270
00280
       bool WriteToFile(const std::string &filename) const;
00281
00282 private:
       Matrix matrix_properties_;
00284
00285
       Real *data_;
00286 };
00287 }
00288 #endif // End of: MTK_INCLUDE_MTK_DENSE_MATRIX_H_
```

17.15 include/mtk_div_1d.h File Reference

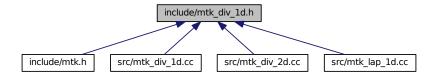
Includes the definition of the class Div1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_div_ld.h:
```



17.16 mtk div 1d.h 227

This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Div1D

Implements a 1D mimetic divergence operator.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.15.1 Detailed Description

This class implements a 1D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_div_1d.h.

17.16 mtk_div_1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
```

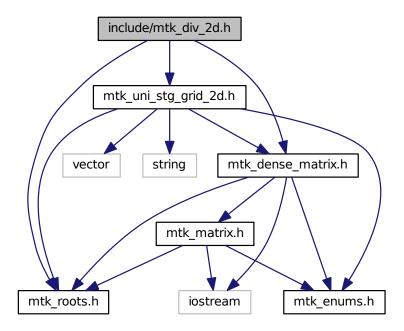
```
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_DIV_1D_H_
00058 #define MTK_INCLUDE_DIV_1D_H_
00059
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "glpk.h"
00064
00065 #include "mtk_roots.h"
00066 #include "mtk_dense_matrix.h"
00067 #include "mtk_uni_stg_grid_1d.h"
00068
00069 namespace mtk {
00070
00081 class Div1D {
      public:
00082
00084
        friend std::ostream& operator <<(std::ostream& stream, Div1D &in);</pre>
00085
00087
        Div1D();
00088
00094
       Div1D(const Div1D &div);
00095
00097
        ~Div1D();
00098
00104
        bool ConstructDiv1D(int order_accuracy = kDefaultOrderAccuracy,
00105
                            Real mimetic_threshold = kDefaultMimeticThreshold);
00106
00112
        int num_bndy_coeffs() const;
00113
00119
        Real *coeffs_interior() const;
00120
00126
        Real *weights_crs(void) const;
00127
00133
        Real *weights_cbs(void) const;
00134
00140
        DenseMatrix mim_bndy() const;
00141
00147
        DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid) const;
00148
00149 private:
00155
        bool ComputeStencilInteriorGrid(void);
00156
00163
        bool ComputeRationalBasisNullSpace(void);
00164
00170
        bool ComputePreliminaryApproximations (void);
00171
00177
        bool ComputeWeights (void);
00178
00184
        bool ComputeStencilBoundaryGrid(void);
00185
00191
        bool AssembleOperator(void);
00192
00193
        int order accuracy ;
00194
        int dim_null_;
```

```
00195
        int num_bndy_coeffs_;
00196
       int divergence_length_;
00197
        int minrow_;
00198
       int row_;
00199
00200
       DenseMatrix rat_basis_null_space_;
00201
00202
       Real *coeffs_interior_;
00203
       Real *prem_apps_;
00204
      Real *weights_crs_;
00205
       Real *weights_cbs_;
00206
      Real *mim_bndy_;
       Real *divergence_;
00209
       Real mimetic_threshold_;
00210 };
00211 }
00212 #endif // End of: MTK_INCLUDE_DIV_1D_H_
```

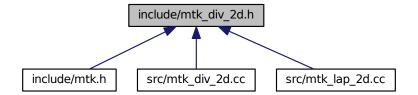
17.17 include/mtk_div_2d.h File Reference

Includes the definition of the class Div2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
Include dependency graph for mtk_div_2d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Div2D

Implements a 2D mimetic divergence operator.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.17.1 Detailed Description

This class implements a 2D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_div_2d.h.

17.18 mtk_div_2d.h

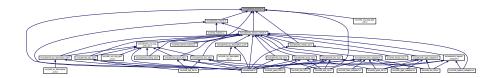
```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
{\tt 00024} 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
```

```
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_MTK_DIV_2D_H_
00058 #define MTK_INCLUDE_MTK_DIV_2D_H_
00059
00060 #include "mtk_roots.h"
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
00065
00076 class Div2D {
00077
      public:
00079
        Div2D();
00080
00086
       Div2D (const Div2D &div);
00087
00089
        ~Div2D();
00090
00096
       bool ConstructDiv2D(const UniStgGrid2D &grid,
00097
                            int order_accuracy = kDefaultOrderAccuracy,
00098
                            Real mimetic_threshold = kDefaultMimeticThreshold);
00099
00105
       DenseMatrix ReturnAsDenseMatrix() const;
00106
00107
00108
       DenseMatrix divergence_;
00109
00110
       int order_accuracy_;
00111
00112
        Real mimetic_threshold_;
00113 };
00114 }
00115 #endif // End of: MTK_INCLUDE_MTK_DIV_2D_H_
```

17.19 include/mtk_enums.h File Reference

Considered enumeration types in the MTK.

This graph shows which files directly or indirectly include this file:



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Enumerations

enum mtk::MatrixStorage { mtk::DENSE, mtk::BANDED, mtk::CRS }

Considered matrix storage schemes to implement sparse matrices.

enum mtk::MatrixOrdering { mtk::ROW_MAJOR, mtk::COL_MAJOR }

Considered matrix ordering (for Fortran purposes).

enum mtk::FieldNature { mtk::SCALAR, mtk::VECTOR }

Nature of the field discretized in a given grid.

enum mtk::DirInterp { mtk::SCALAR_TO_VECTOR, mtk::VECTOR_TO_SCALAR }
 Interpolation operator.

17.19.1 Detailed Description

Enumeration types are used throughout the MTK to differentiate instances of derived classes, as well as for mnemonic purposes. In this file, the enumeration types are listed alphabetically.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_enums.h.

17.20 mtk_enums.h

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00015
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00024
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
```

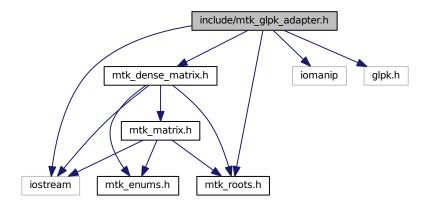
```
00027
00028 3. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 4. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED 00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; 00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_ENUMS_H_
00059 #define MTK_INCLUDE_ENUMS_H_
00060
00061 namespace mtk {
00062
00077 enum MatrixStorage {
00078
       DENSE.
00079
        BANDED,
08000
       CRS
00081 };
00082
00095 enum MatrixOrdering {
00096 ROW MAJOR,
00097
       COL_MAJOR
00098 };
00099
00113 enum FieldNature {
00114 SCALAR,
00115
        VECTOR
00116 };
00117
00127 enum DirInterp {
00128
        SCALAR_TO_VECTOR,
00129
       VECTOR_TO_SCALAR
00130 };
00132 #endif // End of: MTK_INCLUDE_ENUMS_H_
```

17.21 include/mtk_glpk_adapter.h File Reference

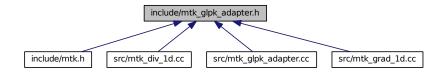
Adapter class for the GLPK API.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
```

Include dependency graph for mtk_glpk_adapter.h:



This graph shows which files directly or indirectly include this file:



Classes

class mtk::GLPKAdapter

Adapter class for the GLPK API.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.21.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

See also

```
http://www.gnu.org/software/glpk/
```

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk glpk adapter.h.

17.22 mtk_glpk_adapter.h

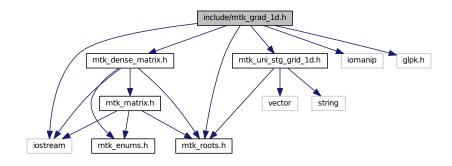
```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00025
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed, unless these modifications are made through the project's GitHub
00029 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00030 should be developed and included in any deliverable.
00031
00032 2. Redistributions of source code must be done through direct
00033 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00034
00035 3. Redistributions in binary form must reproduce the above copyright notice,
00036 this list of conditions and the following disclaimer in the documentation and/or
00037 other materials provided with the distribution.
00038
00039 4. Usage of the binary form on proprietary applications shall require explicit
00040 prior written permission from the the copyright holders, and due credit should
00041 be given to the copyright holders.
00042
00043 5. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00046
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00052
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00065 #ifndef MTK_INCLUDE_GLPK_ADAPTER_H_
00066 #define MTK_INCLUDE_GLPK_ADAPTER_H_
00068 #include <iostream>
00069 #include <iomanip>
00070
00071 #include "glpk.h"
00072
00073 #include "mtk roots.h"
00074 #include "mtk_dense_matrix.h"
00075
00076 namespace mtk {
00077
00101 class GLPKAdapter {
```

```
00102 public:
       static mtk::Real SolveSimplexAndCompare(
     mtk::Real *A,
                                                 int nrows,
00124
00125
                                                 int ncols,
00126
                                                 int kk,
00127
                                                 mtk::Real *hh,
00128
                                                 mtk::Real *qq,
00129
                                                 int robjective,
00130
                                                 mtk::Real mimetic_tol,
00131
                                                 int copy);
00132 };
00133 }
00134 #endif // End of: MTK_INCLUDE_MTK_GLPK_ADAPTER_H_
```

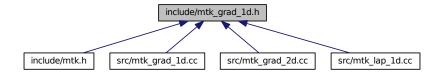
17.23 include/mtk_grad_1d.h File Reference

Includes the definition of the class Grad1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_grad_ld.h:
```



This graph shows which files directly or indirectly include this file:



17.24 mtk grad 1d.h 237

Classes

class mtk::Grad1D

Implements a 1D mimetic gradient operator.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.23.1 Detailed Description

This class implements a 1D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (C←BSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk grad 1d.h.

17.24 mtk_grad_1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
```

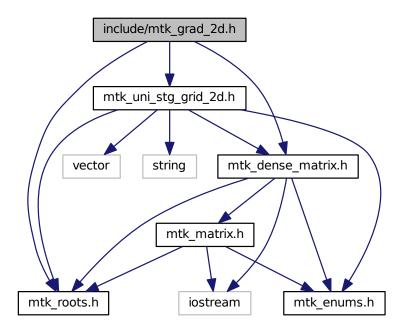
```
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_GRAD_1D_H_
00058 #define MTK_INCLUDE_GRAD_1D_H_
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "glpk.h"
00064
00065 #include "mtk_roots.h"
00066 #include "mtk_dense_matrix.h"
00067 #include "mtk_uni_stg_grid_ld.h"
00068
00069 namespace mtk {
00070
00081 class Grad1D {
00082 public:
00084
        friend std::ostream& operator <<(std::ostream& stream, Grad1D &in);</pre>
00085
00087
       Grad1D();
00088
00094
       Grad1D(const Grad1D &grad);
00095
00097
        ~Grad1D();
00098
00104
        bool ConstructGrad1D(int order_accuracy = kDefaultOrderAccuracy,
00105
                              Real mimetic_threshold = kDefaultMimeticThreshold);
00106
00112
        int num_bndy_coeffs() const;
00113
00119
        Real *coeffs_interior() const;
00120
00126
        Real *weights_crs(void) const;
00127
        Real *weights_cbs(void) const;
00133
00134
00140
        DenseMatrix mim_bndy() const;
00141
00147
        DenseMatrix ReturnAsDenseMatrix (Real west,
      Real east, int num_cells_x) const;
00148
00154
        DenseMatrix ReturnAsDenseMatrix(const
      UniStgGrid1D &grid) const;
00155
00161
        DenseMatrix ReturnAsDimensionlessDenseMatrix(int num_cells_x)
00162
00163
      private:
00169
        bool ComputeStencilInteriorGrid(void);
00170
00177
        bool ComputeRationalBasisNullSpace(void);
00178
00184
        bool ComputePreliminaryApproximations(void);
00185
00191
        bool ComputeWeights(void);
00192
00198
        bool ComputeStencilBoundaryGrid(void);
00199
00205
        bool AssembleOperator(void);
00206
00207
        int order_accuracy_;
00208
        int dim_null_;
        int num_bndy_approxs_;
00209
00210
        int num_bndy_coeffs_;
00211
        int gradient_length_;
00212
        int minrow_;
00213
        int row ;
00214
00215
        DenseMatrix rat basis null space ;
00216
00217
        Real *coeffs_interior_;
00218
        Real *prem_apps_;
00219
        Real *weights crs :
00220
        Real *weights_cbs_;
        Real *mim_bndy_;
00221
00222
        Real *gradient_;
```

```
00223
00224    Real mimetic_threshold_;
00225 };
00226 }
00227 #endif  // End of: MTK_INCLUDE_GRAD_1D_H_
```

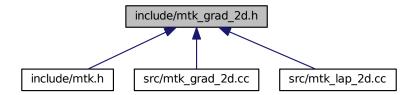
17.25 include/mtk_grad_2d.h File Reference

Includes the definition of the class Grad2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
Include dependency graph for mtk grad 2d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Grad2D

Implements a 2D mimetic gradient operator.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.25.1 Detailed Description

This class implements a 2D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (C← BSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_grad_2d.h.

17.26 mtk_grad_2d.h

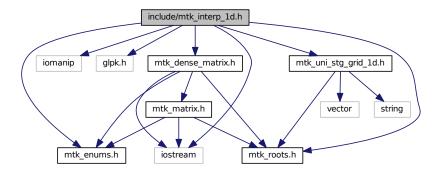
```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
```

```
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_MTK_GRAD_2D_H_
00058 #define MTK_INCLUDE_MTK_GRAD_2D_H_
00059
00060 #include "mtk_roots.h"
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
00065
00076 class Grad2D {
00077
      public:
00079
        Grad2D();
00080
00086
       Grad2D(const Grad2D &grad);
00087
00089
        ~Grad2D();
00090
00096
       bool ConstructGrad2D (const UniStgGrid2D &grid,
00097
                             int order_accuracy = kDefaultOrderAccuracy,
00098
                             Real mimetic_threshold = kDefaultMimeticThreshold);
00099
00105
       DenseMatrix ReturnAsDenseMatrix() const;
00106
00107
00108
       DenseMatrix gradient_;
00109
00110
       int order_accuracy_;
00111
00112
        Real mimetic_threshold_;
00113 };
00114 }
00115 #endif // End of: MTK_INCLUDE_MTK_GRAD_2D_H_
```

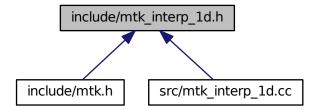
17.27 include/mtk_interp_1d.h File Reference

Includes the definition of the class Interp1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_interp_1d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

class mtk::Interp1D

Implements a 1D interpolation operator.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.28 mtk_interp_1d.h 243

17.27.1 Detailed Description

This class implements a 1D interpolation operator.

Author

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Johnny Corbino jcorbino at mail dot sdsu dot edu

Definition in file mtk interp 1d.h.

17.28 mtk_interp_1d.h

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00015
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00024
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027
00028 3. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 4. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00035
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00057
00058 #ifndef MTK_INCLUDE_INTERP_1D_H_
00059 #define MTK_INCLUDE_INTERP_1D_H_
00061 #include <iostream>
00062 #include <iomanip>
00063
00064 #include "glpk.h"
00065
00066 #include "mtk roots.h"
00067 #include "mtk_enums.h"
00068 #include "mtk_dense_matrix.h"
00069 #include "mtk_uni_stg_grid_1d.h"
00070
```

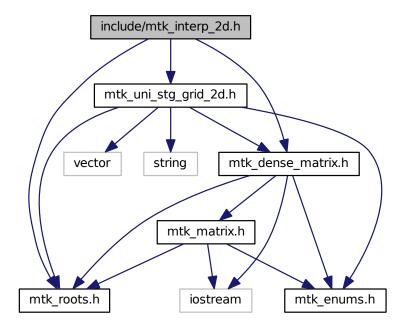
```
00071 namespace mtk {
00072
00082 class Interp1D {
00083 public:
00085
       friend std::ostream& operator <<(std::ostream& stream, InterplD &in);
00086
00088
       Interp1D();
00089
00095
       InterplD(const InterplD &interp);
00096
00098
00099
00105
       bool ConstructInterp1D(int order_accuracy =
     kDefaultOrderAccuracy,
00106
                               mtk::DirInterp dir = SCALAR_TO_VECTOR);
00107
00113
       Real *coeffs_interior() const;
00114
00120
       DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid) const;
00121
00122 private:
       DirInterp dir_interp_;
00123
00124
00125
       int order_accuracy_;
00126
       Real *coeffs_interior_;
00127
00128 };
00129 }
00130 #endif // End of: MTK_INCLUDE_INTERP_1D_H_
```

17.29 include/mtk_interp_2d.h File Reference

Includes the definition of the class Interp2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk_interp_2d.h:



Classes

· class mtk::Interp2D

Implements a 2D interpolation operator.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.29.1 Detailed Description

This class implements a 2D interpolation operator.

Author

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Johnny Corbino jcorbino at mail dot sdsu dot edu

Definition in file mtk_interp_2d.h.

17.30 mtk_interp_2d.h

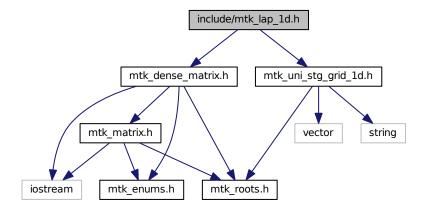
```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027
00028 3. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 4. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00035
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_MTK_INTERP_2D_H_
00059 #define MTK_INCLUDE_MTK_INTERP_2D_H_
00061 #include "mtk_roots.h"
00062 #include "mtk_dense_matrix.h"
00063 #include "mtk_uni_stg_grid_2d.h"
00064
00065 namespace mtk{
00066
00076 class Interp2D {
00077 public:
00079
       Interp2D();
00080
       Interp2D(const Interp2D &interp);
00087
       ~Interp2D();
00090
00096
       DenseMatrix ConstructInterp2D(const UniStgGrid2D &grid,
00097
                                      int order_accuracy = kDefaultOrderAccuracy,
00098
                                   Real mimetic_threshold =
     kDefaultMimeticThreshold);
00099
00105
       DenseMatrix ReturnAsDenseMatrix();
00106
00107
      private:
00108
       DenseMatrix interpolator ;
00109
00110
       int order accuracy;
00111
00112
       Real mimetic_threshold_;
00113 }:
```

```
00114 }
00115 #endif // End of: MTK_INCLUDE_MTK_INTERP_2D_H_
```

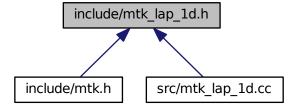
17.31 include/mtk_lap_1d.h File Reference

Includes the definition of the class Lap1D.

```
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_lap_1d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

class mtk::Lap1D

Implements a 1D mimetic Laplacian operator.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.31.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk lap 1d.h.

17.32 mtk_lap_1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are \text{met}:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK INCLUDE LAP 1D H
00058 #define MTK_INCLUDE_LAP_1D_H_
00059
00060 #include "mtk dense matrix.h"
```

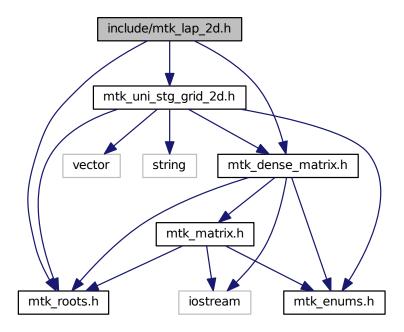
```
00061
00062 #include "mtk_uni_stg_grid_1d.h"
00064 namespace mtk {
00065
00076 class Lap1D {
00077 public:
00079
       friend std::ostream& operator <<(std::ostream& stream, Lap1D &in);
08000
       Lap1D();
00083
00089
       Lap1D (const Lap1D &lap);
00090
00092
       ~Lap1D();
00093
00099
       bool ConstructLap1D(int order_accuracy = kDefaultOrderAccuracy,
00100
                            Real mimetic_threshold = kDefaultMimeticThreshold);
00101
00107
        DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid) const;
00108
       const mtk::Real* data(const UniStgGrid1D &grid) const;
00114
00115
00116 private:
00117
        int order_accuracy_;
       int laplacian_length_;
00118
00119
00120
      Real *laplacian_;
00121
00122
       Real mimetic_threshold_;
00123 };
00124 }
00125 #endif // End of: MTK_INCLUDE_LAP_1D_H_
```

17.33 include/mtk_lap_2d.h File Reference

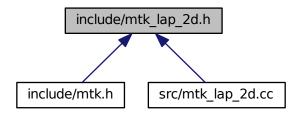
Includes the implementation of the class Lap2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk_lap_2d.h:



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Lap2D

Implements a 2D mimetic Laplacian operator.

17.34 mtk lap 2d.h 251

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.33.1 Detailed Description

This class implements a 2D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk lap 2d.h.

17.34 mtk_lap_2d.h

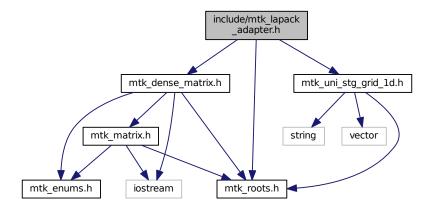
```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are \text{met}:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK INCLUDE MTK LAP 2D H
00058 #define MTK_INCLUDE_MTK_LAP_2D_H_
00059
00060 #include "mtk roots.h"
```

```
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
00065
00076 class Lap2D {
00077 public:
00079
       Lap2D();
08000
       Lap2D (const Lap2D &lap);
00087
00089
       ~Lap2D();
00090
       bool ConstructLap2D(const UniStgGrid2D &grid,
00096
00097
                            int order_accuracy = kDefaultOrderAccuracy,
00098
                            Real mimetic_threshold = kDefaultMimeticThreshold);
00099
00105
       DenseMatrix ReturnAsDenseMatrix() const;
00106
00112
       Real *data() const;
00113
00114 private:
00115
        DenseMatrix laplacian_;
00116
00117
        int order_accuracy_;
00118
00119
       Real mimetic_threshold_;
00120 };
00121 }
00122 #endif // End of: MTK_INCLUDE_MTK_LAP_2D_H_
```

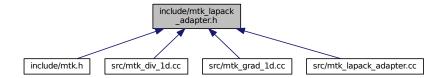
17.35 include/mtk_lapack_adapter.h File Reference

Adapter class for the LAPACK API.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_lapack_adapter.h:
```



This graph shows which files directly or indirectly include this file:



Classes

class mtk::LAPACKAdapter
 Adapter class for the LAPACK API.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.35.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

See also

```
http://www.netlib.org/lapack/
```

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_lapack_adapter.h.

17.36 mtk_lapack_adapter.h

```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00022
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00025
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
```

```
00028 completed, unless these modifications are made through the project's GitHub
00029 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00030 should be developed and included in any deliverable.
00032 2. Redistributions of source code must be done through direct
00033 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00035 3. Redistributions in binary form must reproduce the above copyright notice,
00036 this list of conditions and the following disclaimer in the documentation and/or
00037 other materials provided with the distribution.
00039 4. Usage of the binary form on proprietary applications shall require explicit
00040 prior written permission from the the copyright holders, and due credit should
00041 be given to the copyright holders.
00043 5. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00052
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00064
00065 #ifndef MTK INCLUDE LAPACK ADAPTER H
00066 #define MTK_INCLUDE_LAPACK_ADAPTER_H_
00067
00068 #include "mtk_roots.h"
00069 #include "mtk dense matrix.h"
00070 #include "mtk_uni_stg_grid_ld.h"
00071
00072 namespace mtk {
00073
00092 class LAPACKAdapter {
00093 public:
00104
      static int SolveDenseSystem(mtk::DenseMatrix &mm,
00105
                                    mtk::Real *rhs);
00106
00117
       static int SolveDenseSystem(mtk::DenseMatrix &mm,
00118
                                    mtk::DenseMatrix &rr);
00119
00130
      static int SolveDenseSystem(mtk::DenseMatrix &mm,
00131
                                    mtk::UniStgGrid1D &rhs);
00132
       static int SolveRectangularDenseSystem(const
     mtk::DenseMatrix &aa,
00145
                                               mtk::Real *ob .
00146
                                               int ob_ld_);
00147
       static mtk::DenseMatrix QRFactorDenseMatrix(
     DenseMatrix &matrix);
00160 };
00161
00162 #endif // End of: MTK_INCLUDE_LAPACK_ADAPTER_H_
```

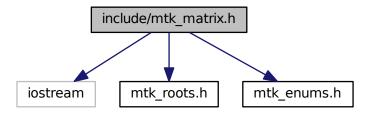
17.37 include/mtk matrix.h File Reference

Definition of the representation of a matrix in the MTK.

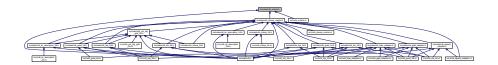
```
#include <iostream>
#include "mtk_roots.h"
#include "mtk_enums.h"
```

17.38 mtk_matrix.h 255

Include dependency graph for mtk_matrix.h:



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Matrix

Definition of the representation of a matrix in the MTK.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.37.1 Detailed Description

Definition of the representation for the matrices implemented in the MTK.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_matrix.h.

17.38 mtk_matrix.h

```
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #ifndef MTK_INCLUDE_MATRIX_H_
00057 #define MTK_INCLUDE_MATRIX_H_
00058
00059 #include <iostream>
00060
00061 #include "mtk_roots.h"
00062 #include "mtk_enums.h"
00063
00064 namespace mtk {
00065
00075 class Matrix {
00076 public:
00078
       Matrix();
00079
00085
       Matrix(const Matrix &in);
00086
00088
        ~Matrix() noexcept ;
00089
00095
       MatrixStorage storage() const noexcept;
00096
00102
        MatrixOrdering ordering() const noexcept;
00103
00109
        int num_rows() const noexcept;
00110
00116
        int num cols() const noexcept;
00117
00123
        int num_values() const noexcept;
00124
00134
        int 1d() const noexcept;
00135
00141
        int num zero() const noexcept;
00142
00148
        int num non zero() const noexcept;
00149
00157
        int num null() const noexcept;
00158
00166
        int num non null() const noexcept;
```

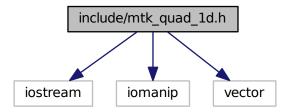
```
00167
00173
        int kl() const noexcept;
00174
00180
        int ku() const noexcept;
00181
00187
        int bandwidth() const noexcept;
00188
00196
        Real abs_density() const noexcept;
00197
00205
       Real rel_density() const noexcept;
00206
00214
       Real abs_sparsity() const noexcept;
00215
00223
        Real rel_sparsity() const noexcept;
00224
00232
        void set_storage(const MatrixStorage &tt) noexcept;
00233
00241
        void set_ordering(const MatrixOrdering &oo) noexcept;
00242
00248
        void set_num_rows(const int &num_rows) noexcept;
00249
00255
        void set_num_cols(const int &num_cols) noexcept;
00256
00262
       void set_num_zero(const int &in) noexcept;
00263
00269
       void set_num_null(const int &in) noexcept;
00270
00272
       void IncreaseNumZero() noexcept;
00273
00275
       void IncreaseNumNull() noexcept;
00276
00277 private:
00278
       MatrixStorage storage_;
00279
       MatrixOrdering ordering_;
00280
00281
00282
        int num_rows_;
00283
        int num_cols_;
00284
        int num_values_;
00285
        int ld_;
00286
00287
        int num_zero_;
00288
        int num_non_zero_;
00289
        int num_null_;
00290
       int num_non_null_;
00291
00292
        int kl_;
00293
        int ku_;
00294
       int bandwidth_;
00295
00296
       Real abs_density_;
00297
        Real rel_density_;
00298
       Real abs_sparsity_;
00299
        Real rel_sparsity_;
00300 };
00301
00302 #endif // End of: MTK_INCLUDE_MATRIX_H_
```

17.39 include/mtk_quad_1d.h File Reference

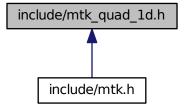
Includes the definition of the class Quad1D.

```
#include <iostream>
#include <iomanip>
#include <vector>
```

Include dependency graph for mtk_quad_1d.h:



This graph shows which files directly or indirectly include this file:



Classes

· class mtk::Quad1D

Implements a 1D mimetic quadrature.

Namespaces

• mtk

Mimetic Methods Toolkit namespace.

17.39.1 Detailed Description

This class implements a 1D quadrature solver based on the mimetic discretization of the gradient operator.

See also

mtk::Grad1D

17.40 mtk_quad_1d.h 259

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Implement this class.

Definition in file mtk_quad_1d.h.

17.40 mtk quad 1d.h

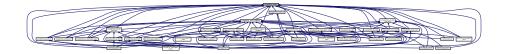
```
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00021
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed, unless these modifications are made through the project's GitHub
00025 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00026 should be developed and included in any deliverable.
00027
00028 2. Redistributions of source code must be done through direct
00029 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00031 3. Redistributions in binary form must reproduce the above copyright notice,
00032 this list of conditions and the following disclaimer in the documentation and/or
00033 other materials provided with the distribution.
00034
00035 4. Usage of the binary form on proprietary applications shall require explicit
00036 prior written permission from the the copyright holders, and due credit should
00037 be given to the copyright holders.
00038
00039 5. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00060
00061 #ifndef MTK_INCLUDE_QUAD_1D_H_
00062 #define MTK_INCLUDE_QUAD_1D_H_
00064 #include <iostream>
00065 #include <iomanip>
00066
00067 #include <vector>
00068
00069 namespace mtk {
00070
00081 class Quad1D {
00082
      public:
00084
        friend std::ostream& operator <<(std::ostream& stream, Quad1D &in);
00085
00087
       Quad1D();
00088
00094
        Quad1D (const Quad1D &quad);
00095
```

```
00097
        ~Quad1D();
00098
00104
        int degree_approximation() const;
00105
00111
        Real *weights() const;
00112
00121
        Real Integrate (Real (*Integrand) (Real xx), UniStgGrid1D grid) const;
00122
00123
00124
        int degree_approximation_;
00125
00126
        std::vector<Real> weights_;
00127 };
00129 #endif // End of: MTK_INCLUDE_QUAD_1D_H_
```

17.41 include/mtk_roots.h File Reference

Fundamental definitions to be used across all classes of the MTK.

This graph shows which files directly or indirectly include this file:



Namespaces

mtk

Mimetic Methods Toolkit namespace.

Typedefs

typedef float mtk::Real

Users can simply change this to build a double- or single-precision MTK.

Variables

• const float mtk::kZero {0.0f}

MTK's zero defined according to selective compilation.

const float mtk::kOne {1.0f}

MTK's one defined according to selective compilation.

• const float mtk::kTwo {2.0f}

MTK's two defined according to selective compilation.

const float mtk::kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

const int mtk::kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

const float mtk::kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

const int mtk::kCriticalOrderAccuracyDiv {8}

17.42 mtk roots.h 261

At this order (and higher) we must use the CBSA to construct.

const int mtk::kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

17.41.1 Detailed Description

This file contains the fundamental definitions that classes of the MTK rely on to be implemented. Examples of these definitions are the definition of fundamental data types, and global variables affecting the construction of mimetic operators, among others.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at sciences dot sdsu dot edu

Todo Documentation should (better?) capture effects from selective compilation.

Todo Test selective precision mechanisms.

Definition in file mtk roots.h.

17.42 mtk roots.h

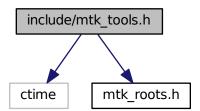
```
00017 /*
00018 Copyright (C) 2015, Computational Science Research Center, San Diego State
00019 University. All rights reserved.
00020
00021 Redistribution and use in source and binary forms, with or without modification,
00022 are permitted provided that the following conditions are met:
00023
00024 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00025 and a copy of the modified files should be reported once modifications are
00026 completed, unless these modifications are made through the project's GitHub
00027 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00028 should be developed and included in any deliverable.
00030 2. Redistributions of source code must be done through direct
00031 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00033 3. Redistributions in binary form must reproduce the above copyright notice,
00034 this list of conditions and the following disclaimer in the documentation and/or
00035 other materials provided with the distribution.
00036
00037 4. Usage of the binary form on proprietary applications shall require explicit
00038 prior written permission from the the copyright holders, and due credit should
00039 be given to the copyright holders.
00041 5. Neither the name of the copyright holder nor the names of its contributors
00042 may be used to endorse or promote products derived from this software without
00043 specific prior written permission.
00045 The copyright holders provide no reassurances that the source code provided does
00046 not infringe any patent, copyright, or any other intellectual property rights of
00047 third parties. The copyright holders disclaim any liability to any recipient for
00048 claims brought against recipient by any third party for infringement of that
00049 parties intellectual property rights.
00051 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00052 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00053 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00054 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00055 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00056 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00057 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00058 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00059 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
```

```
00060 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00062
00063 #ifndef MTK_INCLUDE_ROOTS_H_
00064 #define MTK_INCLUDE_ROOTS_H_
00071 namespace mtk {
00072
00080 #ifdef MTK_PRECISION_DOUBLE
00081 typedef double Real;
00082 #else
00083 typedef float Real;
00084 #endif
00111 #ifdef MTK_PRECISION_DOUBLE
00112 const double kZero{0.0};
00113 const double kOne{1.0};
00114 const double kTwo{2.0};
00115 #else
00116 const float kZero{0.0f};
00117 const float kOne{1.0f};
00118 const float kTwo{2.0f};
00119 #endif
00120
00128 #ifdef MTK_PRECISION_DOUBLE
00129 const double kDefaultTolerance{1e-7};
00130 #else
00131 const float kDefaultTolerance{1e-7f};
00132 #endif
00133
00143 const int kDefaultOrderAccuracy{2};
00144
00154 #ifdef MTK PRECISION DOUBLE
00155 const double kDefaultMimeticThreshold{1e-6};
00156 #else
00157 const float kDefaultMimeticThreshold{1e-6f};
00158 #endif
00159
00167 const int kCriticalOrderAccuracyDiv{8};
00168
00176 const int kCriticalOrderAccuracyGrad{10};
00177 }
00178 #endif // End of: MTK_INCLUDE_ROOTS_H_
```

17.43 include/mtk tools.h File Reference

Tool manager class.

```
#include <ctime>
#include "mtk_roots.h"
Include dependency graph for mtk_tools.h:
```



17.44 mtk_tools.h 263

This graph shows which files directly or indirectly include this file:



Classes

class mtk::Tools

Tool manager class.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.43.1 Detailed Description

Basic utilities.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Note

Performance Tip 8.1. If they do not need to be modified by the called function, pass large objects using pointers to constant data or references to constant data, to obtain the performance benefits of pass-by-reference.

Definition in file mtk tools.h.

17.44 mtk_tools.h

```
00001
00014 /*
00015 Copyright (C) 2015, Computational Science Research Center, San Diego State
00016 University. All rights reserved.
00018 Redistribution and use in source and binary forms, with or without modification,
00019 are permitted provided that the following conditions are met:
00021 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00022 and a copy of the modified files should be reported once modifications are
00023 completed, unless these modifications are made through the project's GitHub
00024 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00025 should be developed and included in any deliverable.
00027 2. Redistributions of source code must be done through direct
00028 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00029
00030 3. Redistributions in binary form must reproduce the above copyright notice, 00031 this list of conditions and the following disclaimer in the documentation and/or
00032 other materials provided with the distribution.
00033
00034 4. Usage of the binary form on proprietary applications shall require explicit
00035 prior written permission from the the copyright holders, and due credit should
00036 be given to the copyright holders.
```

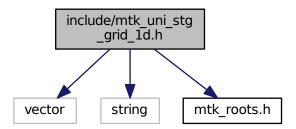
```
00038 5. Neither the name of the copyright holder nor the names of its contributors
00039 may be used to endorse or promote products derived from this software without
00040 specific prior written permission.
00042 The copyright holders provide no reassurances that the source code provided does
00043 not infringe any patent, copyright, or any other intellectual property rights of
00044 third parties. The copyright holders disclaim any liability to any recipient for
00045 claims brought against recipient by any third party for infringement of that
00046 parties intellectual property rights.
00048 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00049 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00050 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00051 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00052 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00053 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00054 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00055 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00056 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00057 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00058 */
00059
00060 #ifndef MTK_INCLUDE_TOOLS_H_
00061 #define MTK_INCLUDE_TOOLS_H_
00062
00063 #include <ctime>
00064
00065 #include "mtk roots.h"
00066
00067 namespace mtk {
00068
00078 class Tools {
00079 public:
00090
        static void Prevent (const bool complement,
00091
                            const char *const fname,
00092
                            int lineno,
00093
                            const char *const fxname) noexcept;
00094
00100
       static void BeginUnitTestNo(const int &nn) noexcept;
00101
00107
        static void EndUnitTestNo(const int &nn) noexcept;
00108
00114
       static void Assert (const bool &condition) noexcept;
00115
00116 private:
00117
       static int test_number_;
00118
00119
       static Real duration_;
00120
00121
        static clock_t begin_time_;
00122 };
00123 }
00124 #endif // End of: MTK_INCLUDE_TOOLS_H_
```

17.45 include/mtk_uni_stg_grid_1d.h File Reference

Definition of an 1D uniform staggered grid.

```
#include <vector>
#include <string>
#include "mtk_roots.h"
```

Include dependency graph for mtk_uni_stg_grid_1d.h:



This graph shows which files directly or indirectly include this file:



Classes

class mtk::UniStgGrid1D
 Uniform 1D Staggered Grid.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.45.1 Detailed Description

Definition of an 1D uniform staggered grid.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Create overloaded binding routines that read data from files.

Definition in file mtk_uni_stg_grid_1d.h.

17.46 mtk_uni_stg_grid_1d.h

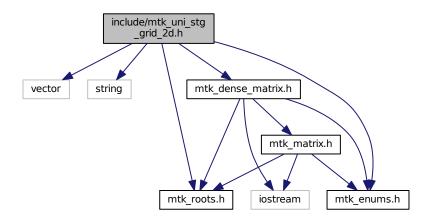
```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027
00028 3. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 4. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00035
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_UNI_STG_GRID_1D_H_
00059 #define MTK_INCLUDE_UNI_STG_GRID_1D_H_
00061 #include <vector>
00062 #include <string>
00063
00064 #include "mtk roots.h"
00065
00066 namespace mtk {
00077 class UniStgGrid1D {
00078 public:
00080
        friend std::ostream& operator << (std::ostream& stream, UniStgGrid1D &in);
00083
       UniStgGrid1D();
00084
        UniStgGrid1D(const UniStgGrid1D &grid);
00090
00091
00102
        UniStgGrid1D(const Real &west_bndy_x,
00103
                    const Real &east_bndy_x,
00104
                     const int &num_cells_x,
00105
                     const mtk::FieldNature &nature = mtk::SCALAR);
00106
00108
        ~UniStgGrid1D();
00109
        Real west bndy x() const;
00115
00116
00122
        Real east bndy x() const;
00123
00129
        Real delta_x() const;
00130
```

```
00138
        const Real *discrete_domain_x() const;
00139
00147
        Real *discrete_field_u();
00148
00154
        int num_cells_x() const;
00155
00161
        void BindScalarField(Real (*ScalarField)(Real xx));
00162
00174
        void BindVectorField(Real (*VectorField)(Real xx));
00175
00187
        bool WriteToFile(std::string filename,
00188
                         std::string space_name,
00189
                         std::string field_name) const;
00190
00191 private:
00192
        FieldNature nature_;
00193
00194
       std::vector<Real> discrete_domain_x_;
       std::vector<Real> discrete_field_u_;
00196
00197
        Real west_bndy_x_;
       Real east_bndy_x_;
00198
00199
       Real num_cells_x_;
00200
       Real delta_x_;
00201 };
00202 }
00203 #endif // End of: MTK_INCLUDE_UNI_STG_GRID_1D_H_
```

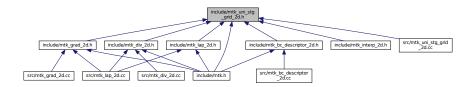
17.47 include/mtk_uni_stg_grid_2d.h File Reference

Definition of an 2D uniform staggered grid.

```
#include <vector>
#include <string>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_dense_matrix.h"
Include dependency graph for mtk_uni_stg_grid_2d.h:
```



This graph shows which files directly or indirectly include this file:



Classes

class mtk::UniStgGrid2D
 Uniform 2D Staggered Grid.

Namespaces

mtk

Mimetic Methods Toolkit namespace.

17.47.1 Detailed Description

Definition of an 2D uniform staggered grid.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Create overloaded binding routines that read data from files.

Definition in file mtk uni stg grid 2d.h.

17.48 mtk_uni_stg_grid_2d.h

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00024
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027
00028 3. Redistributions in binary form must reproduce the above copyright notice, 00029 this list of conditions and the following disclaimer in the documentation and/or
{\tt 00030} other materials provided with the distribution.
00031
00032 4. Usage of the binary form on proprietary applications shall require explicit
```

```
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK INCLUDE UNI STG GRID 2D H
00059 #define MTK_INCLUDE_UNI_STG_GRID_2D_H_
00060
00061 #include <vector>
00062 #include <string>
00063
00064 #include "mtk roots.h"
00065 #include "mtk_enums.h"
00066 #include "mtk_dense_matrix.h"
00067
00068 namespace mtk {
00069
00079 class UniStgGrid2D {
00080 public:
00082
        friend std::ostream& operator <<(std::ostream& stream, UniStgGrid2D &in);</pre>
00083
00085
       UniStgGrid2D();
00086
00092
       UniStgGrid2D(const UniStgGrid2D &grid);
00093
00107
        UniStgGrid2D(const Real &west_bndy_x,
00108
                    const Real &east_bndy_x,
00109
                     const int &num_cells_x,
00110
                     const Real &south_bndy_y,
00111
                     const Real &north_bndy_y,
00112
                     const int &num_cells_y,
00113
                     const mtk::FieldNature &nature =
     mtk::SCALAR);
00114
00116
        ~UniStgGrid2D();
00117
00125
        const Real *discrete_domain_x() const;
00126
00134
        const Real *discrete_domain_y() const;
00135
00141
        Real *discrete_field();
00142
00150
       FieldNature nature() const;
00151
00157
        Real west_bndy() const;
00158
00164
        Real east_bndy() const;
00165
00171
        int num_cells_x() const;
00172
00178
        Real delta_x() const;
00179
00185
        Real south bndv() const:
00186
00192
        Real north bndv() const:
00193
00199
        int num cells v() const;
00200
00206
        Real delta v() const;
00207
00213
       bool Bound() const;
```

```
00214
00220
        void BindScalarField(Real (*ScalarField)(Real xx, Real yy));
00221
00236
       void BindVectorField(Real (*VectorFieldPComponent)(Real xx,
     Real yy),
00237
                             Real (*VectorFieldQComponent) (Real xx,Real yy));
00238
00251
       bool WriteToFile(std::string filename,
00252
                         std::string space_name_x,
00253
                         std::string space_name_y,
00254
                         std::string field_name) const;
00255
00256 private:
       void BindVectorFieldPComponent(
00269
00270
         Real (*VectorFieldPComponent) (Real xx, Real yy));
00271
00284
       void BindVectorFieldQComponent(
00285
         Real (*VectorFieldQComponent) (Real xx, Real yy));
00286
00287
       std::vector<Real> discrete_domain_x_;
        std::vector<Real> discrete_domain_y_;
00288
00289
       std::vector<Real> discrete_field_;
00290
00291
       FieldNature nature_;
00292
00293
        Real west_bndy_;
00294
        Real east_bndy_;
00295
        int num_cells_x_;
00296
       Real delta_x_;
00297
00298
        Real south bndy ;
00299
       Real north_bndy_;
00300
        int num_cells_y_;
00301
        Real delta_y_;
00302 };
00303 }
00304 #endif // End of: MTK_INCLUDE_UNI_STG_GRID_2D_H_
```

17.49 Makefile.inc File Reference

17.50 Makefile.inc

```
00001 # Makefile setup file for MTK.
00002
00003 SHELL := /bin/bash
00004
00005 # Please set the following variables up:
00006
00007 #
         1. Absolute path to base directory of the MTK.
00008 #
00009
00010 BASE = /home/esanchez/Dropbox/MTK
00011
00012 #
         2. The machine (platform) identifier and required machine precision.
00013 #
00014
00015 # Options are:
00016 # - LINUX: A LINUX box installation.
00017 # - OSX: Uses OS X optimized solvers.
00018
00019 PLAT = LINUX
00020
00021 # Options are:
00022 # - SINGLE: Use 4 B floating point numbers.
00023 # - DOUBLE: Use 8 B floating point numbers.
00024
00025 PRECISION = DOUBLE
00026
00027 #
          3. Optimized solvers and operations by means of ATLAS in Linux?
00028 #
00029
00030 # If you have selected OSX in step 1, then you don't need to worry about this.
00031
00032 # Options are ON xor OFF:
00033
```

17.50 Makefile.inc 271

```
00034 ATL_OPT = OFF
00035
00036 #
          4. Paths to dependencies (header files for compiling).
00037 #
00038
00039 # GLPK include path (soon to go):
00040
00041 GLPK_INC = $(HOME)/Libraries/glpk-4.35/include
00042
00043 # Linux: If ATLAS optimization is ON, users should only provide the path to
00044 # ATLAS:
00045
00046 ATLAS_INC = $(HOME)/Libraries/ATLAS_3.8.4-CORE/include
00047
00048 # OS X: Do nothing.
00049
00050 #
         5. Paths to dependencies (archive files for (static) linking).
00051 #
00052
00053 # GLPK linking path (soon to go):
00054
00055 GLPK_LIB = $(HOME)/Libraries/qlpk-4.35/lib/lib64/libqlpk.a
00056
00057 # If optimization is OFF, then provide the paths for:
00058
00059 BLAS LIB = $(HOME)/Libraries/BLAS-3.5.0/libblas.a
00060 LAPACK_LIB = $(HOME)/Libraries/lapack-3.5.0/liblapack.a
00061
00062 # WARNING: Vendor libraries should be used whenever they are available.
00063
00064 # However, if optimization is ON, please provide the path the ATLAS' archive:
00065
00066 ATLAS LIB = $(HOME)/Libraries/ATLAS 3.8.4-CORE/ATLAS 3.8.4-BUILD-Citadel/lib
00067
00068 #
          6. Compiler and its flags.
00069 #
00070
00071 CC = g++
00073 # Debug Level. Options are:
00074 # 0. NO debug at all NOR any run-time checks... be cautious!
00075 # 1. Verbose (execution messages) AND run-time checks.
00076 \# 2. Level 1 plus intermediate scalar-valued results.
00077 # 3. Level 2 plus intermediate array-valued results.
00078
00079 DEBUG_LEVEL = 3
08000
00081 # Flags recommended for release code:
00082
00083 CCFLAGS = -Wall -Werror -03
00084
00085 # Flags recommended for debugging code:
00086
00087 CCFLAGS = -Wall -Werror -g
88000
00089 #
          7. Archiver, its flags, and ranlib:
00090 #
00091
00092 ARCH
00093 ARCHFLAGS = cr
00094
00095 # If your system does not have "ranlib" then set: "RANLIB = echo":
00096
00097 RANLIB = echo
00098
00099 # But, if possible:
00100
00101 RANLIB = ranlib
00102
00103 #
         8. Valgrind's memcheck options (optional):
00104 #
00105
00106 MEMCHECK_OPTS = -v --tool=memcheck --leak-check=full --show-leak-kinds=all \
00107 --track-origins=yes --freelist-vol=20000000
00108
00109 # Done! User, please, do not mess with the definitions from this point on.
00110
00111 #
00112 #
00113 #
00114
```

```
00115 # MTK-related.
00116 #
00117
00118 SRC
               = $(BASE)/src
00119 INCLUDE
              = $(BASE)/include
00120 LIB
               = $(BASE)/lib
00121 MTK_LIB
             = $(LIB)/libmtk.a
00122 TESTS
               = $(BASE)/tests
00123 EXAMPLES = $(BASE)/examples
00125 #
         Compiling-related.
00126 #
00127
00128 CCFLAGS += -std=c++11 -fPIC -DMTK_DEBUG_LEVEL=$ (DEBUG_LEVEL) -I$ (INCLUDE) -c
00129
00130 ifeq ($(PRECISION), DOUBLE)
00131 CCFLAGS += -DMTK_PRECISION_DOUBLE
00132 else
      CCFLAGS += -DMTK_PRECISION_SINGLE
00133
00134 endif
00135
00136 # Only the GLPK is included because the other dependencies are coded in Fortran.
00137
00138 ifeq ($(ATL_OPT),ON)
00139 CCFLAGS += -I$(GLPK_INC) $(ATLAS_INC)
00140 else
00141 CCFLAGS += -I$ (GLPK_INC)
00142 endif
00143
00144 #
         Linking-related.
0.0145 #
00146
00147 NOOPT_LIBS = $(LAPACK_LIB) $(BLAS_LIB) -lm $(GLPK_LIB) -lstdc++
00148
00149 OPT_LIBS
                = -LS(ATLAS LIB) -latlas -llapack -lblas -lm -latlas -lstdc++
00150
00151 ifeq ($(PLAT),OSX)
      LINKER = g++
00152
       LINKER += -framework Accelerate $(GLPK_LIB) $(MTK_LIB)
00153
00154 else
00155 ifeq ($(ATL_OPT),ON)
        LINKER = g++
00156
         LIBS = $ (MTK_LIB)
00157
00158
         LIBS += $(OPT_LIBS)
00159
      else
00160
        LINKER = gfortran
         LIBS = $ (MTK_LIB)
00161
00162
        LIBS += $(NOOPT_LIBS)
00163 endif
00164 endif
00165
00166 #
         Documentation-related.
00167 #
00168
                = doxygen
00169 DOCGEN
00170 DOCFILENAME = doc_config.dxcf
00171 DOC
               = $(BASE)/doc
00172 DOCFILE
                 = $ (BASE) /$ (DOCFILENAME)
```

17.51 README.md File Reference

17.52 README.md

```
00001 # The Mimetic Methods Toolkit (MTK)
00002
00003 By: **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu**
00004
00005
00006 ## 1. Description
00007
00008 We define numerical methods that are based on discretizations preserving the
00009 properties of their continuum counterparts to be **mimetic**.
00010
00011 The **Mimetic Methods Toolkit (MTK)** is a C++ library for mimetic numerical
00012 methods. It is arranged as a set of classes for **mimetic quadratures**,
```

17.52 README.md 273

```
00013 **mimetic interpolation**, and **mimetic finite differences** methods for the
00014 numerical solution of ordinary and partial differential equations.
00015
00016 An older version of this library is available outside of GitHub... just email me
00017 about it, and you can have it... it is ugly, yet it is functional and more
00018 complete.
00019
00020
00021 ## 2. Dependencies
00023 This README assumes all of these dependencies are installed in the following
00024 folder:
00025
00026 '''
00027 $(HOME)/Libraries/
00029
00030 In this version, the MTK optionally uses ATLAS-optimized BLAS and LAPACK
00031 routines for the internal computation on some of the layers. However, ATLAS
00032 requires both BLAS and LAPACK in order to create their optimized distributions.
00033 Therefore, the following dependencies tree arises:
00034
00035 ### For Linux:
00036
00037 1. LAPACK - Available from: http://www.netlib.org/lapack/
       1. BLAS - Available from: http://www.netlib.org/blas/
00038
00039
00040 2. GLPK - Available from: https://www.gnu.org/software/glpk/
00041
00042 3. (Optional) ATLAS - Available from: http://math-atlas.sourceforge.net/
       1. LAPACK - Available from: http://www.netlib.org/lapack/
1. BLAS - Available from: http://www.netlib.org/blas
00043
00044
00045
00046 4. (Optional) Valgrind - Available from: http://valgrind.org/
00047
00048 5. (Optional) Doxygen - Available from http://www.stack.nl/~dimitri/doxygen/
00049
00050 ### For OS X:
00051
00052 1. GLPK - Available from: https://www.gnu.org/software/glpk/
00053
00054
00055 ## 3. Installation
00056
00057 ### PART 1. CONFIGURATION OF THE MAKEFILE.
00058
00059 The following steps are required to build and test the MTK. Please use the 00060 accompanying 'Makefile.inc' file, which should provide a solid template to
00061 start with. The following command provides help on the options for make:
00062
00063 '''
00064 $ make help
00065 -
00066 Makefile for the MTK.
00067
00068 Options are:
00069 - all: builds the library, the tests, and examples.
00070 - mtklib: builds the library.
00071 - test: builds the test files.
00072 - example: builds the examples.
00073
00074 - testall: runs all the tests.
00075
00076 - gendoc: generates the documentation for the library.
00077
00078 - clean: cleans all the generated files.
00079 - cleanlib: cleans the generated archive and object files.
00080 - cleantest: cleans the generated tests executables.
00081 - cleanexample: cleans the generated examples executables.
00082 --
00083 '''
00084
00085 ### PART 2. BUILD THE LIBRARY.
00086
00087 ***
00088 $ make
00089 ...
00090
00091 If successful you'll read (before building the tests and examples):
00092
00093 '''
```

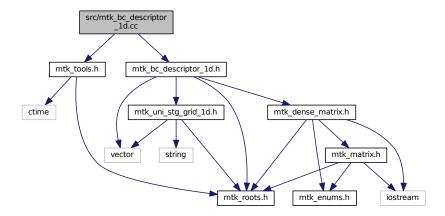
```
00094 ---- Library created! Check in /home/ejspeiro/Dropbox/MTK/lib
00095 '''
00096
00097 Examples and tests will also be built.
00098
00099
00100 ## 4. Frequently Asked Questions
00101
00102 Q: Why haven't you guys implemented GBS to build the library?
00103 A: I'm on it as we speak! ;)
00105 Q: Is there any main reference when it comes to the theory on Mimetic Methods?
00106 A: Yes! Check: http://www.csrc.sdsu.edu/mimetic-book
00108 Q: Do I need to generate the documentation myself?
00109 A: You can if you want to... but if you DO NOT want to, just go to our website.
00110
00111
00112 ## 5. Contact, Support, and Credits
00113
00114 The MTK is developed by researchers and adjuncts to the 00115 [Computational Science Research Center (CSRC)](http://www.csrc.sdsu.edu/)
00116 at [San Diego State University (SDSU)](http://www.sdsu.edu/).
00117
00118 Developers are members of:
00119
00120 1. Mimetic Numerical Methods Research and Development Group.
00121 2. Computational Geoscience Research and Development Group.
00122 3. Ocean Modeling Research and Development Group.
00123
00124 Currently the developers are:
00125
00126 - **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu** - @ejspeiro
00127 - Jose E. Castillo, Ph.D. - jcastillo at mail dot sdsu dot edu
00128 - Guillermo F. Miranda, Ph.D. - unigrav at hotmail dot com
00129 - Christopher P. Paolini, Ph.D. - paolini at engineering dot sdsu dot edu
00130 - Angel Boada.
00131 - Johnny Corbino.
00132 - Raul Vargas-Navarro.
00133
00134 Finally, please feel free to contact me with suggestions or corrections:
00135
00136 **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu** - @ejspeiro
00137
00138 Thanks and happy coding!
```

17.53 src/mtk_bc_descriptor_1d.cc File Reference

Enforces boundary conditions in either the operator or the grid.

```
#include "mtk_tools.h"
#include "mtk_bc_descriptor_1d.h"
```

Include dependency graph for mtk_bc_descriptor_1d.cc:



17.53.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 1D mimetic operators and the grids they are acting on.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_bc_descriptor_1d.cc.

17.54 mtk_bc_descriptor_1d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
```

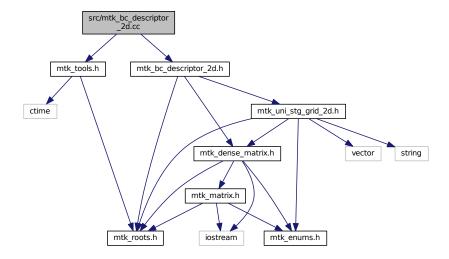
```
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include "mtk_tools.h"
00058
00059 #include "mtk_bc_descriptor_1d.h"
00060
00061 void mtk::BCDescriptor1D::ImposeOnLaplacianMatrix(
00062
         mtk::DenseMatrix &matrix,
00063
          const std::vector<mtk::Real> &west,
00064
          const std::vector<mtk::Real> &east) {
00065
00066
        #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(matrix.num_rows() == 0, __FILE__, __LINE__, __func__);
00067
00068
       mtk::Tools::Prevent(west.size() > (unsigned int) matrix.
     num_cols(),
       __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(east.size() > (unsigned int) matrix.
00069
00070
      num_cols(),
00071
                              _FILE__, __LINE__, __func__);
00072
        #endif
00073
00075
00076
        for (unsigned int ii = 0; ii < west.size(); ++ii) {</pre>
00077
         matrix.SetValue(0, ii, west[ii]);
00078
00079
00081
00082
       for (unsigned int ii = 0; ii < east.size(); ++ii) {</pre>
00083
          matrix.SetValue(matrix.num_rows() - 1,
00084
                          matrix.num_cols() - 1 - ii,
00085
                           east[ii]);
00086
00087 }
00088
00089 void mtk::BCDescriptor1D::ImposeOnGrid(
     mtk::UniStgGrid1D &grid,
00090
                                              const mtk::Real &omega,
00091
                                              const mtk::Real &epsilon) {
00092
00093
        #if MTK_DEBUG_LEVEL > 0
00094
        mtk::Tools::Prevent(grid.num_cells_x() == 0, __FILE__, __LINE__, __func__);
00095
00096
00098
00099
        grid.discrete_field_u()[0] = omega;
00100
00102
       grid.discrete_field_u()[grid.num_cells_x() + 2 - 1] = epsilon;
00104 }
```

17.55 src/mtk_bc_descriptor_2d.cc File Reference

Enforces boundary conditions in either the operator or the grid.

```
#include "mtk_tools.h"
#include "mtk_bc_descriptor_2d.h"
```

Include dependency graph for mtk_bc_descriptor_2d.cc:



17.55.1 Detailed Description

This class presents an interface for the user to specify boundary conditions on 2D mimetic operators and the grids they are acting on.

Def. Let f be any scalar or vector field defined over a domain Ω . We can specify any linear combination of f and its n derivatives to fulfill a condition, which we define as a **boundary condition**:

$$\forall \mathbf{x} \in \partial \Omega : \sum_{i=0}^{n} c_i(\mathbf{x}) < \hat{\mathbf{n}}, \frac{\partial^i f}{\partial x^i}(\mathbf{x}) > = \beta(\mathbf{x}).$$

This class receives information about the highest-order of differentiation, n, all possible coefficient functions, $c_i(\mathbf{x})$ for any subset of the boundary (south, north, west and east), and each condition for any subset of the boundary, and takes care of assigning them to both, the differentiation matrices and the grids.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_bc_descriptor_2d.cc.

17.56 mtk bc descriptor 2d.cc

```
00001 00030 /* 00031 Copyright (C) 2015, Computational Science Research Center, San Diego State 00032 University. All rights reserved. 00033 00034 Redistribution and use in source and binary forms, with or without modification, 00035 are permitted provided that the following conditions are met: 00036 00037 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
```

```
00038 and a copy of the modified files should be reported once modifications are
00039 completed, unless these modifications are made through the project's GitHub
00040 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00041 should be developed and included in any deliverable.
00043 2. Redistributions of source code must be done through direct
00044 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00045
00046 3. Redistributions in binary form must reproduce the above copyright notice,
00047 this list of conditions and the following disclaimer in the documentation and/or
00048 other materials provided with the distribution.
00050 4. Usage of the binary form on proprietary applications shall require explicit
00051 prior written permission from the the copyright holders, and due credit should
00052 be given to the copyright holders.
00054 5. Neither the name of the copyright holder nor the names of its contributors
00055 may be used to endorse or promote products derived from this software without
00056 specific prior written permission.
00058 The copyright holders provide no reassurances that the source code provided does
00059 not infringe any patent, copyright, or any other intellectual property rights of
00060 third parties. The copyright holders disclaim any liability to any recipient for
00061 claims brought against recipient by any third party for infringement of that
00062 parties intellectual property rights.
00063
00064 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00065 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00066 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE 00067 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00068 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00069 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00070 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00071 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00072 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00073 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00074 */
00075
00076 #include "mtk_tools.h"
00077
00078 #include "mtk_bc_descriptor_2d.h"
00079
00080 mtk::BCDescriptor2D::BCDescriptor2D():
00081
       generate_space_(false),
00082
        highest_order_diff_west_(-1),
00083
        highest_order_diff_east_(-1),
00084
        highest_order_diff_south_(-1),
00085
        highest_order_diff_north_(-1),
00086
        west_condition_(),
00087
        east_condition_(),
00088
        south_condition_(),
00089
        north_condition_() {}
00090
00091 mtk::BCDescriptor2D::BCDescriptor2D(const
      mtk::BCDescriptor2D &desc) {}
00092
00093 mtk::BCDescriptor2D::~BCDescriptor2D() noexcept {}
00094
00095 int mtk::BCDescriptor2D::highest_order_diff_west() const
      noexcept {
00096
00097
        return highest_order_diff_west_;
00098 }
00099
00100 int mtk::BCDescriptor2D::highest_order_diff_east() const
     noexcept {
00101
00102
        return highest_order_diff_east_;
00103 }
00104
00105 int mtk::BCDescriptor2D::highest_order_diff_south() const
      noexcept {
00106
00107
        return highest order diff south ;
00108 }
00109
00110 int mtk::BCDescriptor2D::highest_order_diff_north() const
     noexcept {
00111
00112
        return highest_order_diff_north_;
00113 }
```

```
00114
00115 void mtk::BCDescriptor2D::PushBackWestCoeff(
      mtk::CoefficientFunction2D cw) {
00116
00117
         #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(cw == nullptr, __FILE_, __LINE_, __func_);
mtk::Tools::Prevent(highest_order_diff_west_ > 1,
00118
00119
00120
                              __FILE__, __LINE__, __func__);
00121
00122
00123
        west_coefficients_.push_back(cw);
00124
00125
        highest order diff west ++;
00126 }
00127
00128 void mtk::BCDescriptor2D::PushBackEastCoeff(
      mtk::CoefficientFunction2D ce) {
00129
00130
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(ce == nullptr, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(highest_order_diff_east__ > 1,
00131
00132
00133
                              __FILE__, __LINE__, __func__);
00134
        #endif
00135
        east_coefficients_.push_back(ce);
00136
00137
00138
        highest_order_diff_east_++;
00139 }
00140
00141 void mtk::BCDescriptor2D::PushBackSouthCoeff(
      mtk::CoefficientFunction2D cs) {
00142
00143
        #if MTK DEBUG LEVEL > 0
        mtk::Tools::Prevent(cs == nullptr, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(highest_order_diff_south_ > 1,
00144
00145
00146
                                _FILE__, __LINE__, __func__);
00147
        #endif
00148
00149
        south_coefficients_.push_back(cs);
00150
00151
        highest_order_diff_south_++;
00152 }
00153
00154 void mtk::BCDescriptor2D::PushBackNorthCoeff(
      mtk::CoefficientFunction2D cn) {
00155
00156
        \#if MTK_DEBUG_LEVEL > 0
00157
        mtk::Tools::Prevent(cn == nullptr, _
                                                _FILE__, __LINE__, __func__);
00158
        mtk::Tools::Prevent(highest_order_diff_north_ > 1,
00159
                              __FILE__, __LINE__, __func__);
00160
00161
00162
        north_coefficients_.push_back(cn);
00163
00164
        highest_order_diff_north_++;
00165 }
00166
00167 void mtk::BCDescriptor2D::set_west_condition(
00168
          mtk::Real (*west_condition)(mtk::Real xx, mtk::Real yy)) noexcept {
00169
00170
        #if MTK_DEBUG_LEVEL > 0
00171
        mtk::Tools::Prevent(west_condition == nullptr, __FILE__, __LINE__, __func__);
00172
        #endif
00173
00174
        west_condition_ = west_condition;
00175 }
00176
00177 void mtk::BCDescriptor2D::set_east_condition(
00178
         mtk::Real (*east_condition) (mtk::Real xx, mtk::Real yy)) noexcept {
00179
00180
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(east_condition == nullptr, __FILE__, __LINE__, __func__);
00181
00182
        #endif
00183
00184
        east condition = east condition;
00185 }
00186
00187 void mtk::BCDescriptor2D::set south condition(
00188
          mtk::Real (*south_condition) (mtk::Real xx, mtk::Real yy)) noexcept {
00189
        #if MTK DEBUG LEVEL > 0
00190
```

```
00191
        mtk::Tools::Prevent(south_condition == nullptr,
00192
                             __FILE__, __LINE__, __func__);
00193
        #endif
00194
00195
        south_condition_ = south_condition;
00196 }
00197
00198 void mtk::BCDescriptor2D::set_north_condition(
00199
          mtk::Real (*north_condition) (mtk::Real xx, mtk::Real yy)) noexcept {
00200
00201
        #if MTK DEBUG LEVEL > 0
        mtk::Tools::Prevent(north_condition == nullptr,
00202
00203
                             __FILE__, __LINE__, __func__);
00204
00205
00206
        north_condition_ = north_condition;
00207 }
00208
00209 void mtk::BCDescriptor2D::ImposeOnSouthBoundaryNoSpace(
00210
        const mtk::UniStgGrid2D &grid,
          mtk::DenseMatrix &matrix,
00211
00212
          const int &order_accuracy) const {
00213
00214
        // At this point we have all of the information we need to fully impose the
00215
        // south boundary condition:
00216
        // 1. We have the collection of coefficients. The size of this collection
00217
        // tells us the type of BC for this boundary.
00218
        // 2. We have the grid that we can use to evaluate the coefficients at.
00219
        // 3. We have the matrix where to place them.
00220
00221
        // For now, we are sure that we will NOT have more than 2 coefficients per
00222
        \ensuremath{//} boundary. That is, we only support Robin type FOR NOW.
00223
00225
        // For the south-west corner:
00226
        auto cc = (south_coefficients_[0])(grid.west_bndy(), grid.south_bndy());
00227
00228
00229
        #if MTK DEBUG LEVEL > 0
        std::cout << "Matrix has " << matrix.num_rows() << " rows and " <<
    matrix.num_cols() << " columns." << std::endl;
std::cout << "Setting at " << 0 << ' ' << 0 << std::endl;</pre>
00230
00231
00232
00233
        #endif
00234
00235
        matrix.SetValue(0, 0, cc);
00236
00237
        // Compute first centers per dimension.
00238
        auto first_center_x = grid.west_bndy() + grid.delta_x()/
     mtk::kTwo;
00239
00240
        // For each entry on the diagonal (south boundary):
00241
        for (int ii = 0; ii < grid.num_cells_x(); ++ii) {</pre>
00242
          // Evaluate next set spatial coordinates to evaluate the coefficient.
00243
          mtk::Real xx = first_center_x + ii*grid.delta_x();
00244
          // Evaluate and assign the Dirichlet coefficient.
00245
          cc = (south_coefficients_[0])(xx, grid.south_bndy());
00246
00247
          #if MTK_DEBUG_LEVEL > 0
00248
          std::cout << "Setting at " << ii + 1 << ' ' << ii + 1 << std::endl;
00249
00250
00251
          matrix.SetValue(ii + 1, ii + 1, cc);
00252
00253
00254
        // For the south-east corner:
00255
        cc = (south_coefficients_[0]) (grid.east_bndy(), grid.south_bndy());
00256
00257
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Setting at " << grid.num_cells_x() + 1 << ' ' <<
00258
00259
          grid.num_cells_x() + 1 << std::endl;</pre>
00260
00261
00262
        matrix.SetValue(grid.num_cells_x() + 1, grid.num_cells_x() + 1, cc);
00263
00265
00267 }
00268
00269 void mtk::BCDescriptor2D::ImposeOnSouthBoundaryWithSpace
00270
          const mtk::UniStgGrid2D &grid,
00271
          mtk::DenseMatrix &matrix,
00272
          const int &order_accuracy) const {
```

```
00273
00275
00278
        \ensuremath{//} For each entry on the diagonal:
00279
        for (int ii = 0; ii < grid.num_cells_x() + 2; ++ii) {</pre>
00280
         // Evaluate next set spatial coordinates to evaluate the coefficient.
00281
00282
          mtk::Real xx{(grid.discrete_domain_x())[ii]};
00283
          // Evaluate and assign the Dirichlet coefficient.
00284
          mtk::Real cc = (south_coefficients_[0])(xx,grid.south_bndy());
00285
          matrix.SetValue(ii, ii, cc);
00286
00287
00289 }
00290
00291 void mtk::BCDescriptor2D::ImposeOnNorthBoundaryNoSpace(
         const mtk::UniStgGrid2D &grid,
00293
          mtk::DenseMatrix &matrix,
00294
          const int &order accuracy) const {
00295
00296
        // At this point we have all of the information we need to fully impose the
00297
        // north boundary condition:
00298
        // 1. We have the collection of coefficients. The size of this collection
00299
        // tells us the type of BC for this boundary.
00300
        // 2. We have the grid that we can use to evaluate the coefficients at.
00301
        \ensuremath{//} 3. We have the matrix where to place them.
00302
00303
        // For now, we are sure that we will NOT have more than 2 coefficients per
00304
        // boundary. That is, we only support Robin type FOR NOW.
00305
00306
        int north_offset{(grid.num_cells_y() + 1)*(grid.num_cells_x() + 2)};
00307
00309
00310
        // For the north-west corner:
        mtk::Real cc =
00311
00312
          (north_coefficients_[0]) (grid.west_bndy(), grid.north_bndy());
00313
        #if MTK_DEBUG_LEVEL > 0 std::cout << "Matrix has " << matrix.num_rows() << " rows and " <<
00314
00315
        matrix.num_cols() << " columns." << std::endl;
std::cout << "Setting at " << north_offset << ' ' << north_offset <<</pre>
00316
00317
00318
          std::endl;
00319
        #endif
00320
00321
        matrix.SetValue(north_offset, north_offset, cc);
00322
00323
        // Compute first centers per dimension.
00324
        auto first_center_x = grid.west_bndy() + grid.delta_x()/
     mtk::kTwo;
00325
00326
        // For each entry on the diagonal (north boundary):
00327
        for (int ii = 0; ii < grid.num_cells_x(); ++ii) {</pre>
00328
          // Evaluate next set spatial coordinates to evaluate the coefficient.
00329
          mtk::Real xx = first_center_x + ii*grid.delta_x();
          // Evaluate and assign the Dirichlet coefficient.
00330
00331
          cc = (north_coefficients_[0])(xx, grid.north_bndy());
00332
00333
          #if MTK_DEBUG_LEVEL > 0
00334
          std::cout << "Setting at " << north_offset + ii + 1 << ' ' <<
00335
           north_offset + ii + 1 << std::endl;
00336
00337
00338
          matrix.SetValue(north_offset + ii + 1, north_offset + ii + 1, cc);
00339
        }
00340
00341
        // For the north-east corner:
00342
        cc = (north_coefficients_[0]) (grid.east_bndy(), grid.north_bndy());
00343
00344
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Setting at " << north_offset + grid.num_cells_x() + 1 <<
00345
00346
              << north_offset + grid.num_cells_x() + 1 << std::endl;
00347
        #endif
00348
00349
        matrix.SetValue(north_offset + grid.num_cells_x() + 1,
00350
                         north_offset + grid.num_cells_x() + 1, cc);
00351
00353 }
00354
00355 void mtk::BCDescriptor2D::ImposeOnNorthBoundaryWithSpace
00356
          const mtk::UniStaGrid2D &arid.
00357
          mtk::DenseMatrix &matrix,
```

```
00358
          const int &order_accuracy) const {
00359
00361
00362
       int north_offset{(grid.num_cells_y() + 1)*(grid.num_cells_x() + 2));
00363
00365
        for (int ii = 0; ii < grid.num_cells_x() + 2; ++ii) {</pre>
00367
         mtk::Real xx{(grid.discrete_domain_x())[ii]};
00369
          mtk::Real cc = (north_coefficients_[0]) (xx, grid.north_bndy());
00370
          matrix.SetValue(north_offset + ii, north_offset + ii, cc);
00371
00372
00374 }
00375
00376 void mtk::BCDescriptor2D::ImposeOnWestBoundaryNoSpace(
          const mtk::UniStgGrid2D &grid,
00378
          mtk::DenseMatrix &matrix,
00379
          const int &order_accuracy) const {
00380
00381
        // At this point we have all of the information we need to fully impose the
00382
       // west boundary condition:
00383
        // 1. We have the collection of coefficients. The size of this collection
00384
        // tells us the type of BC for this boundary.
00385
        // 2. We have the grid that we can use to evaluate the coefficients at.
00386
        // 3. We have the matrix where to place them.
00387
00389
00390
        // For the south-west corner:
00391
        auto cc = (west_coefficients_[0]) (grid.west_bndy(), grid.south_bndy());
00392
00393
        #if MTK DEBUG LEVEL > 0
        matrix.num_cols() << " columns." << std::endl;
std::cout << "Setting at " << 0 << ' ' << 0 << std::endl;</pre>
00394
00395
00396
00397
        #endif
00398
00402
00403
       mtk::Real harmonic mean = mtk::kOne/matrix.GetValue(0, 0) +
     mtk::kOne/cc:
00404
       harmonic_mean = mtk::kTwo/harmonic_mean;
00405
00406
       matrix.SetValue(0, 0, harmonic_mean);
00407
00408
       int west_offset{grid.num_cells_x() + 1};
00409
00410
       auto first_center_y = grid.south_bndy() + grid.delta_y()/
     mtk::kTwo;
00411
00412
        // For each west entry on the diagonal (west boundary):
00413
        for (int ii = 0; ii < grid.num_cells_y(); ++ii) {</pre>
00414
          // Evaluate next set spatial coordinates to evaluate the coefficient.
00415
          mtk::Real yy = first_center_y + ii*grid.delta_y();
00416
          \ensuremath{//} Evaluate and assign the Dirichlet coefficient
00417
          cc = (west_coefficients_[0]) (grid.west_bndy(), yy);
00418
00419
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "Setting at " << west_offset + ii + 1 << ' ' <<
00420
            west_offset + ii + 1 << std::endl;</pre>
00421
00422
          #endif
00423
00424
          matrix.SetValue(west_offset + ii + 1, west_offset + ii + 1, cc);
00425
00426
          west_offset += grid.num_cells_x() + 1;
00427
       }
00428
00429
        // For the north-west corner:
00430
        cc = (west_coefficients_[0]) (grid.west_bndy(), grid.north_bndy());
00431
00432
        west_offset += grid.num_cells_x() + 1;
00433
        int aux{west_offset};
00434
        #if MTK_DEBUG_LEVEL > 0
00435
        std::cout << "Setting at " << aux << ' ' << aux << std::endl;
00436
        #endif
00437
00438
       harmonic mean = mtk::kOne/matrix.GetValue(aux, aux) +
     mtk::kOne/cc;
00439
       harmonic mean = mtk::kTwo/harmonic mean;
00440
00441
        matrix.SetValue(aux, aux, harmonic mean);
00442
00444 }
00445
```

```
00446 void mtk::BCDescriptor2D::ImposeOnWestBoundaryWithSpace(
          const mtk::UniStgGrid2D &grid,
00448
          mtk::DenseMatrix &matrix,
00449
          const int &order_accuracy) const {
00450
00452
00453
        int west_offset{grid.num_cells_x() + 1};
00454
        // For each west entry on the diagonal:
00455
        for (int ii = 0; ii < grid.num_cells_y() + 2; ++ii) {</pre>
         // Evaluate next set spatial coordinates to evaluate the coefficient.
00456
00457
          mtk::Real yy{(grid.discrete_domain_y())[ii]};
          // Evaluate and assign the Dirichlet coefficient.
00458
00459
          mtk::Real cc = (west_coefficients_[0])(grid.west_bndy(), yy);
00460
          matrix.SetValue(west_offset + ii, west_offset + ii, cc);
00461
          west_offset += grid.num_cells_x() + 1;
00462
00463
00465 }
00466
00467 void mtk::BCDescriptor2D::ImposeOnEastBoundaryNoSpace(
00468
          const mtk::UniStgGrid2D &grid,
00469
          mtk::DenseMatrix &matrix.
00470
          const int &order_accuracy) const {
00471
00472
        // At this point we have all of the information we need to fully impose the
00473
        // east boundary condition:
00474
        // 1. We have the collection of coefficients. The size of this collection
00475
        // tells us the type of BC for this boundary.
00476
        // 2. We have the grid that we can use to evaluate the coefficients at.
00477
        // 3. We have the matrix where to place them.
00478
00480
00481
        // For the south-east corner:
        auto cc = (east_coefficients_[0])(grid.east_bndy(), grid.south_bndy());
00482
00483
00484
        int east_offset{grid.num_cells_x() + 1};
00485
        #if MTK_DEBUG_LEVEL > 0
std::cout << "Matrix has " << matrix.num_rows() << " rows and " <<</pre>
00486
        matrix.num_cols() << " columns." << std::endl;
std::cout << "Setting at " << east_offset << ' ' << east_offset <<</pre>
00487
00488
00489
         std::endl;
00490
        #endif
00491
00492
        mtk::Real harmonic_mean =
00493
         mtk::kOne/matrix.GetValue(east_offset,east_offset) +
     mtk::kOne/cc:
00494
       harmonic_mean = mtk::kTwo/harmonic_mean;
00495
00496
        matrix.SetValue(east_offset, east_offset, harmonic_mean);
00497
00498
        auto first_center_y = grid.south_bndy() + grid.delta_y()/
00499
00500
        // For each east entry on the diagonal (east boundary):
00501
        for (int ii = 0; ii < grid.num_cells_y(); ++ii) {</pre>
00502
00503
          east_offset += grid.num_cells_x() + 1;
00504
00505
          // Evaluate next set spatial coordinates to evaluate the coefficient.
00506
          mtk::Real yy = first_center_y + ii*grid.delta_y();
          // Evaluate and assign the Dirichlet coefficient.
00507
00508
          cc = (east_coefficients_[0]) (grid.east_bndy(), yy);
00509
00510
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "Setting at " << east_offset + ii + 1 << ' ' <<
00511
00512
            east_offset + ii + 1 << std::endl;</pre>
00513
00514
00515
          matrix.SetValue(east_offset + ii + 1, east_offset + ii + 1, cc);
00516
00517
00518
        // For the north-east corner:
00519
        cc = (east_coefficients_[0]) (grid.east_bndy(), grid.north_bndy());
00520
00521
        east_offset += grid.num_cells_x() + 1;
00522
        east_offset += grid.num_cells_x() + 1;
        int aux{east_offset};
00523
        #if MTK_DEBUG_LEVEL > 0
00524
        std::cout << "Setting at " << aux << ' ' << aux << std::endl;
00525
00526
        #endif
00527
```

```
00528
        harmonic_mean =
00529
         mtk::kOne/matrix.GetValue(aux, aux) + mtk::kOne/cc;
00530
        harmonic_mean = mtk::kTwo/harmonic_mean;
00531
00532
        matrix.SetValue(aux, aux, harmonic_mean);
00533
00535 }
00536
00537 void mtk::BCDescriptor2D::ImposeOnEastBoundaryWithSpace(
        const mtk::UniStgGrid2D &grid,
00539
          mtk::DenseMatrix &matrix,
00540
          const int &order_accuracy) const {
00541
00543
00544
        int east_offset{grid.num_cells_x() + 1};
00545
        // For each west entry on the diagonal:
00546
        for (int ii = 0; ii < grid.num_cells_y() + 2; ++ii) {</pre>
00547
          east_offset += grid.num_cells_x() + 1;
00548
          // Evaluate next set spatial coordinates to evaluate the coefficient.
00549
          mtk::Real yy{(grid.discrete_domain_y())[ii]};
00550
          // Evaluate and assign the arithmetic mean of Dirichlet coefficients.
00551
          mtk::Real cc = (east_coefficients_[0])(grid.east_bndy(), yy);
00552
          matrix.SetValue(east_offset + ii, east_offset + ii, cc);
00553
00554
00556 }
00557
00558 void mtk::BCDescriptor2D::ImposeOnLaplacianMatrix(
00559
          const mtk::UniStqGrid2D &grid,
00560
          mtk::DenseMatrix &matrix.
00561
          const int &order_accuracy) const {
00562
00563
        #if MTK DEBUG LEVEL > 0
00564
        mtk::Tools::Prevent(highest_order_diff_south_ == -1,
00565
                               _FILE__, __LINE__, __func__);
        mtk::Tools::Prevent(highest_order_diff_north_ == -1,
00566
00567
                               _FILE__, __LINE__, __func__);
00568
        mtk::Tools::Prevent(highest_order_diff_west_ == -1,
00569
                               _FILE__, __LINE__, __func__);
00570
        mtk::Tools::Prevent(highest_order_diff_east_ == -1,
00571
                               _FILE__, __LINE__, __func__);
00572
        mtk::Tools::Prevent(grid.nature() != mtk::SCALAR,
                              __FILE__, __LINE__, __func__);
00573
        mtk::Tools::Prevent(grid.num_cells_x() == 0, __FILE_
00574
                                                                _, __LINE__, __func__);
        mtk::Tools::Prevent(grid.num_cells_y() == 0, __FILE__, __LINE__, __func__);
00575
00576
        mtk::Tools::Prevent(matrix.num_rows() == 0, __FILE__, __LINE__, __func__);
00577
        mtk::Tools::Prevent(matrix.num_cols() == 0, __FILE__, __LINE__, __func__);
00578
00579
00582
00583
        if (!grid.Bound()) {
00584
          ImposeOnSouthBoundaryNoSpace(grid, matrix, order_accuracy);
00585
          ImposeOnNorthBoundaryNoSpace(grid, matrix, order_accuracy);
00586
          ImposeOnWestBoundaryNoSpace(grid, matrix, order_accuracy);
00587
          ImposeOnEastBoundaryNoSpace(grid, matrix, order_accuracy);
00588
00589
          ImposeOnSouthBoundaryWithSpace(grid, matrix, order_accuracy);
00590
          ImposeOnNorthBoundaryWithSpace(grid, matrix, order_accuracy);
00591
          ImposeOnWestBoundaryWithSpace(grid, matrix, order_accuracy);
00592
          ImposeOnEastBoundaryWithSpace(grid, matrix, order_accuracy);
00593
00594 }
00596 void mtk::BCDescriptor2D::ImposeOnGrid(
     mtk::UniStgGrid2D &grid) const {
00597
00598
        #if MTK_DEBUG_LEVEL > 0
00599
        mtk::Tools::Prevent(grid.num_cells_x() == 0, __FILE__, __LINE__, __func__);
       mtk::Tools::Prevent(grid.num_cells_v() == 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(west_condition_ == nullptr, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(east_condition_ == nullptr, __FILE__, __LINE__, __func__);
00600
00601
00602
00603
        mtk::Tools::Prevent(south_condition_ == nullptr,
                              __FILE__, __LINE__, __func__);
00604
        00605
00606
00607
        #endif
00608
00610
        if (grid.nature() == mtk::SCALAR) {
00611
00613
          mtk::Real xx = grid.west bndv();
00615
```

```
00616
          mtk::Real yy = grid.south_bndy();
00617
          (grid.discrete_field())[0] = south_condition_(xx, yy);
00618
00620
          xx = xx + grid.delta_x()/mtk::kTwo;
00621
          // For every point on the south boundary:
00622
          for (int ii = 0; ii < grid.num_cells_x(); ++ii) {</pre>
00623
            (grid.discrete_field())[ii + 1] =
00624
              south_condition_(xx + ii*grid.delta_x(), yy);
00625
00626
00628
          xx = grid.east_bndy();
00629
          (grid.discrete_field())[grid.num_cells_x() + 1] = south_condition_(xx, yy);
00630
00632
00634
          xx = grid.west bndy();
00635
          yy = grid.north_bndy();
00636
          int north_offset{(grid.num_cells_y() + 1) * (grid.num_cells_x() + 2));
00637
          (grid.discrete_field())[north_offset] = north_condition_(xx, yy);
00638
00640
          xx = xx + grid.delta_x()/mtk::kTwo;
00641
          for (int ii = 0; ii < grid.num_cells_x(); ++ii) {
   (grid.discrete_field())[north_offset + ii + 1] =</pre>
00642
00643
              north_condition_(xx + ii*grid.delta_x(), yy);
00644
00645
          xx = grid.east_bndy();
00647
00648
          yy = grid.north_bndy();
          (grid.discrete_field())[north_offset + grid.num_cells_x() + 1] =
00649
00650
              north_condition_(xx, yy);
00651
00653
00657
          xx = grid.west_bndy();
00658
          yy = grid.south_bndy();
00659
           (grid.discrete_field())[0] =
            ((grid.discrete_field())[0] + west_condition_(xx,yy))/
00660
     mtk::kTwo;
00661
00663
          int west_offset{grid.num_cells_x() + 1 + 1};
00664
          yy = yy + grid.delta_y()/mtk::kTwo;
          for (int ii = 0; ii < grid.num_cells_y(); ++ii) {</pre>
00665
            \#if MTK_DEBUG_LEVEL > 0
00666
            std::cout << "Adding on " << west_offset << "-th position." << std::endl;</pre>
00667
00668
            #endif
00669
             (grid.discrete_field())[west_offset] =
00670
              west_condition_(xx, yy + ii*grid.delta_y());
00671
            west_offset += grid.num_cells_x() + 1 + 1;
00672
          }
00673
00675
          xx = grid.west_bndy();
00676
          yy = grid.north_bndy();
00677
          north_offset = (grid.num_cells_y() + 1)*(grid.num_cells_x() + 2);
00678
          (grid.discrete_field())[north_offset] =
00679
            ((grid.discrete_field())[north_offset] + west_condition_(xx, yy))/
00680
              mtk::kTwo;
00681
00683
00685
          xx = grid.east_bndy();
00686
          yy = grid.south_bndy();
00687
          int east_offset{grid.num_cells_x() + 1};
00688
          (grid.discrete_field())[east_offset] =
00689
            ((grid.discrete_field())[east_offset] + east_condition_(xx, yy))/
00690
              mtk::kTwo:
00691
00693
          yy = yy + grid.delta_y()/mtk::kTwo;
          for (int ii = 0; ii < grid.num_cells_y(); ++ii) {</pre>
00694
00695
            east_offset += grid.num_cells_x() + 1 + 1;
            #if MTK_DEBUG_LEVEL > 0
00696
00697
            std::cout << "Adding on " << east_offset << "-th position." << std::endl;</pre>
00698
            #endif
00699
            (grid.discrete_field())[east_offset] =
00700
              east_condition_(xx, yy + ii*grid.delta_y());
00701
00702
00704
          xx = grid.east bndy();
          yy = grid.north_bndy();
00705
00706
          (grid.discrete_field())[north_offset + grid.num_cells_x() + 1] =
            ((grid.discrete_field())[north_offset + grid.num_cells_x() + 1] +
00707
00708
            east_condition_(xx, yy))/mtk::kTwo;
00709
00710
        } else {
00711
```

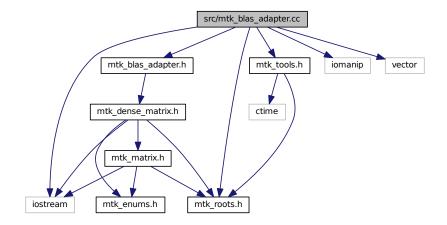
```
00713
00715 }
00716 }
```

17.57 src/mtk_blas_adapter.cc File Reference

Adapter class for the BLAS API.

```
#include <iostream>
#include <iomanip>
#include <vector>
#include "mtk_roots.h"
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
```

Include dependency graph for mtk_blas_adapter.cc:



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Functions

- float mtk::snrm2_ (int *n, float *x, int *incx)
- void mtk::saxpy_ (int *n, float *sa, float *sx, int *incx, float *sy, int *incy)
- void mtk::sgemv_ (char *trans, int *m, int *n, float *alpha, float *a, int *lda, float *x, int *incx, float *beta, float *y, int *incy)
- void mtk::sgemm_ (char *transa, char *transb, int *m, int *n, int *k, double *alpha, double *a, int *lda, double *b, aamm int *ldb, double *beta, double *c, int *ldc)

17.57.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the BLAS.

The **BLAS** (**Basic Linear Algebra Subprograms**) are routines that provide standard building blocks for performing basic vector and matrix operations. The Level 1 BLAS perform scalar, vector and vector-vector operations, the Level 2 BLAS perform matrix-vector operations, and the Level 3 BLAS perform matrix operations.

The BLAS can be installed from links given in the See Also section of this page.

See also

```
http://www.netlib.org/blas/
https://software.intel.com/en-us/non-commercial-software-development
```

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk blas adapter.cc.

17.58 mtk_blas_adapter.cc

```
00001
00024 /*
00025 Copyright (C) 2015, Computational Science Research Center, San Diego State
00026 University. All rights reserved.
00027
00028 Redistribution and use in source and binary forms, with or without modification,
00029 are permitted provided that the following conditions are met:
00030
00031 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00032 and a copy of the modified files should be reported once modifications are
00033 completed, unless these modifications are made through the project's GitHub
00034 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00035 should be developed and included in any deliverable.
00036
00037 2. Redistributions of source code must be done through direct
00038 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00040 3. Redistributions in binary form must reproduce the above copyright notice,
00041 this list of conditions and the following disclaimer in the documentation and/or
00042 other materials provided with the distribution.
00043
00044 4. Usage of the binary form on proprietary applications shall require explicit
00045 prior written permission from the the copyright holders, and due credit should
00046 be given to the copyright holders.
00048 5. Neither the name of the copyright holder nor the names of its contributors
00049 may be used to endorse or promote products derived from this software without
00050 specific prior written permission.
00052 The copyright holders provide no reassurances that the source code provided does
00053 not infringe any patent, copyright, or any other intellectual property rights of
00054 third parties. The copyright holders disclaim any liability to any recipient for
00055 claims brought against recipient by any third party for infringement of that
00056 parties intellectual property rights.
00058 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00059 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00060 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00061 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00062 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00063 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00064 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00065 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00066 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
```

```
00067 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00068 */
00069
00070 #include <iostream>
00071 #include <iomanip>
00072
00073 #include <vector>
00074
00075 #include "mtk_roots.h"
00076 #include "mtk_tools.h"
00077 #include "mtk_blas_adapter.h"
00078
00079 namespace mtk {
08000
00081 extern "C" {
00083 #ifdef MTK_PRECISION_DOUBLE
00084
00097 double dnrm2_(int *n, double *x, int *incx);
00098 #else
00099
00112 float snrm2_(int *n, float *x, int *incx);
00113 #endif
00114
00115 #ifdef MTK_PRECISION_DOUBLE
00116
00135 void daxpy_(int *n, double *da, double *dx, int *incx, double *dy, int *incy);
00136 #else
00137
00156 void saxpy_(int *n, float *sa, float *sx, int *incx, float *sy, int *incy);
00157 #endif
00158
00159 #ifdef MTK_PRECISION_DOUBLE
00160
00188 void dgemv_(char *trans,
                  int *m,
00189
00190
                  int *n,
00191
                  double *alpha,
00192
                  double *a,
00193
                  int *lda.
00194
                  double *x,
00195
                  int *incx,
00196
                  double *beta,
00197
                  double *y,
00198
                  int *incy);
00199 #else
00200
00228 void sgemv_(char *trans,
00229
                  int *m,
00230
                  int *n,
00231
                  float *alpha,
00232
                  float *a,
00233
                  int *lda,
00234
                  float *x,
00235
                  int *incx,
00236
                  float *beta,
00237
                  float *y,
00238
                  int *incy);
00239 #endif
00240
00241 #ifdef MTK_PRECISION_DOUBLE
00242
00267 void dgemm_(char *transa,
                  char* transb,
00268
00269
                  int *m,
00270
                  int *n,
00271
                  int *k,
00272
                  double *alpha,
00273
                  double *a,
00274
                  int *lda,
00275
                  double *b,
00276
                  int *ldb,
00277
                  double *beta,
00278
                  double *c,
00279
                  int *ldc);
00280 }
00281 #else
00282
00307 void sgemm_(char *transa,
00308
                  char* transb,
00309
                  int *m,
```

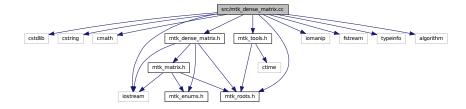
```
00310
                  int *n,
00311
                  int *k,
00312
                  double *alpha,
00313
                  double *a,
00314
                  int *lda,
                  double *b, aamm
00315
00316
                  int *ldb,
00317
                  double *beta,
00318
                  double *c,
00319
                  int *ldc);
00320 }
00321 #endif
00322 }
00323
00324 mtk::Real mtk::BLASAdapter::RealNRM2(Real *in, int &in_length) {
00326
        #if MTK_DEBUG_LEVEL > 0
00327
       mtk::Tools::Prevent(in_length <= 0, __FILE__, __LINE__, __func__);</pre>
00328
        #endif
00329
00330
        int incx{1}; // Increment for the elements of xx. ix \geq 0.
00331
00332
        #ifdef MTK_PRECISION_DOUBLE
00333
        return dnrm2_(&in_length, in, &incx);
00334
        #else
00335
        return snrm2 (&in length, in, &incx);
00336
        #endif
00337 }
00338
00339 void mtk::BLASAdapter::RealAXPY(mtk::Real alpha,
00340
                                           mtk::Real *xx,
00341
                                            mtk::Real *yy,
00342
                                           int &in_length) {
00343
00344
        #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(xx == nullptr, __FILE__, __LINE__, __func__);
00345
       mtk::Tools::Prevent(yy == nullptr, __FILE__, __LINE__, __func__);
00346
00347
        #endif
00348
        int incx{1}: // Increment for the elements of xx. ix >= 0.
00349
00350
00351
        #ifdef MTK_PRECISION_DOUBLE
00352
        daxpy_(&in_length, &alpha, xx, &incx, yy, &incx);
00353
00354
        saxpy_(&in_length, &alpha, xx, &incx, yy, &incx);
00355
        #endif
00356 }
00357
00358 mtk::Real mtk::BLASAdapter::RelNorm2Error(
     mtk::Real *computed,
00359
                                                 mtk::Real *known,
00360
                                                 int length) {
00361
00362
        #if MTK_DEBUG_LEVEL > 0
00363
        mtk::Tools::Prevent(computed == nullptr, __FILE__, __LINE__, __func__);
00364
        mtk::Tools::Prevent(known == nullptr, __FILE__, __LINE__, __func__);
00365
00366
00367
       mtk::Real norm_2_computed{mtk::BLASAdapter::RealNRM2(known, length)};
00368
00369
       mtk::Real alpha{-mtk::kOne};
00370
00371
       mtk::BLASAdapter::RealAXPY(alpha, known, computed, length);
00372
00373
       mtk::Real norm_2_difference{mtk::BLASAdapter::RealNRM2(computed,
      length) };
00374
00375
        return norm_2_difference/norm_2_computed;
00376 }
00377
00378 void mtk::BLASAdapter::RealDenseMV(mtk::Real &alpha,
00379
                                          mtk::DenseMatrix &aa,
00380
                                          mtk::Real *xx.
00381
                                          mtk::Real &beta,
00382
                                          mtk::Real *yy) {
00383
00384
        // Make sure input matrices are row-major ordered.
00385
       if (aa.matrix_properties().ordering() ==
00386
     mtk::COL MAJOR) {
00387
         aa.OrderRowMajor();
```

```
00388
00389
00390
        char transa{'T'}; // State that now, the input WILL be in row-major ordering.
00391
00392
         int mm{aa.num_rows()};
                                                     // Rows of aa.
                                                     // Columns of aa.
00393
        int nn{aa.num_cols()};
00394
         int lda{(aa.matrix_properties()).ld()); // Leading dimension.
00395
                                                     // Increment of values in \boldsymbol{x}.
         int incx{1};
00396
        int incy{1};
                                                     // Increment of values in y.
00397
00398
        std::swap(mm,nn);
00399
         #ifdef MTK_PRECISION_DOUBLE
00400
        dgemv_(&transa, &mm, &nn, &alpha, aa.data(), &lda,
00401
               xx, &incx, &beta, yy, &incy);
00402
00403
        sgemv_(&transa, &mm, &nn, &alpha, aa.data(), &lda,
00404
              xx, &incx, &beta, yy, &incy);
         #endif
00405
00406
        std::swap(mm,nn);
00407 }
00408
00409 mtk::DenseMatrix mtk::BLASAdapter::RealDenseMM(
      mtk::DenseMatrix &aa,
00410
                                                          mtk::DenseMatrix &bb) {
00411
        #if MTK DEBUG LEVEL > 0
00412
        mtk::Tools::Prevent(aa.num_cols() != bb.num_rows(),
00413
                              __FILE__, __LINE__, __func__);
00414
00415
        #endif
00416
00417
        // Make sure input matrices are row-major ordered.
00418
00419
        if (aa.matrix_properties().ordering() ==
     mtk::COL MAJOR) {
00420
          aa.OrderRowMajor();
00421
00422
        if (bb.matrix_properties().ordering() ==
      mtk::COL MAJOR) {
00423
          bb.OrderRowMajor();
00424
00425
        char ta{'T'}; // State that input matrix aa is in row-wise ordering.
00426
        char \mathsf{tb}\{'\mathsf{T}'\}; // State that input matrix bb is in row-wise ordering.
00427
00428
        int mm{aa.num_rows()};  // Rows of aa and rows of cc.
int nn{bb.num_cols()};  // Cols of bb and cols of cc.
int kk{aa.num_cols()};  // Cols of aa and rows of bb.
00429
00430
00431
00432
        int cc_num_rows{mm}; // Rows of cc.
int cc_num_cols{nn}; // Columns of cc.
00433
00434
00435
00436
         int lda{std::max(1,kk)}; // Leading dimension of the aa matrix.
        int ldb{std::max(1,nn)}; // Leading dimension of the bb matrix.
int ldc{std::max(1,mm)}; // Leading dimension of the cc matrix.
00437
00438
00439
00440
        mtk::Real alpha{1.0}; // First scalar coefficient.
00441
        mtk::Real beta{0.0}; // Second scalar coefficient.
00442
00443
        mtk::DenseMatrix cc_col_maj_ord(cc_num_rows,cc_num_cols); // Output matrix.
00444
00445
        cc_col_maj_ord.SetOrdering(mtk::COL_MAJOR);
00446
00447
         #ifdef MTK_PRECISION_DOUBLE
00448
        dgemm_(&ta, &tb, &mm, &nn, &kk, &alpha, aa.data(), &lda,
00449
                bb.data(), &ldb, &beta, cc_col_maj_ord.data(), &ldc);
00450
00451
         sgemm_(&ta, &tb, &mm, &nn, &kk, &alpha, aa.data(), &lda,
00452
                bb.data(), &ldb, &beta, cc_col_maj_ord.data(), &ldc);
00453
00454
00455
         #if MTK_DEBUG_LEVEL > 0
00456
         std::cout << "cc_col_maj_ord =" << std::endl;</pre>
00457
         std::cout << cc_col_maj_ord << std::endl;
00458
         #endif
00459
00460
        cc_col_maj_ord.OrderRowMajor();
00461
00462
        return cc_col_maj_ord;
00463 }
```

#include <cstdlib>

17.59 src/mtk dense matrix.cc File Reference

```
#include <cstring>
#include <cmath>
#include <iostream>
#include <iomanip>
#include <fstream>
#include <typeinfo>
#include <algorithm>
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_tools.h"
Include dependency graph for mtk dense matrix.cc:
```



Namespaces

mtk

Mimetic Methods Toolkit namespace.

Functions

std::ostream & mtk::operator<< (std::ostream &stream, mtk::DenseMatrix &in)

17.60 mtk dense matrix.cc

```
00013 /*
00014 Copyright (C) 2015, Computational Science Research Center, San Diego State
00015 University. All rights reserved.
00017 Redistribution and use in source and binary forms, with or without modification,
00018 are permitted provided that the following conditions are met:
00020 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00021 and a copy of the modified files should be reported once modifications are
00022 completed, unless these modifications are made through the project's GitHub
00023 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00024 should be developed and included in any deliverable.
00025
00026 2. Redistributions of source code must be done through direct
00027 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00028
00029 3. Redistributions in binary form must reproduce the above copyright notice, 00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
```

```
00033 4. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders, and due credit should
00035 be given to the copyright holders.
00037 5. Neither the name of the copyright holder nor the names of its contributors
00038 may be used to endorse or promote products derived from this software without
00039 specific prior written permission.
00041 The copyright holders provide no reassurances that the source code provided does
00042 not infringe any patent, copyright, or any other intellectual property rights of
00043 third parties. The copyright holders disclaim any liability to any recipient for
00044 claims brought against recipient by any third party for infringement of that
00045 parties intellectual property rights.
00047 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00048 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00049 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00050 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00051 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00052 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00053 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00054 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00055 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00056 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00057 */
00058
00059 #include <cstdlib>
00060 #include <cstring>
00061 #include <cmath>
00062
00063 #include <iostream>
00064 #include <iomanip>
00065 #include <fstream>
00066
00067 #include <typeinfo>
00068
00069 #include <algorithm>
00070
00071 #include "mtk_roots.h"
00072 #include "mtk_dense_matrix.h"
00073 #include "mtk_tools.h"
00074
00075 namespace mtk {
00076
00077 std::ostream& operator <<(std::ostream &stream, mtk::DenseMatrix &in) {
00078
00079
        int mm{in.matrix_properties_.num_rows()}; // Auxiliary.
00080
       int nn{in.matrix_properties_.num_cols()}; // Auxiliary.
00081
00082
        if (in.matrix_properties_.ordering() ==
     mtk::COL_MAJOR) {
00083
         std::swap(mm, nn);
00084
00085
       for (int ii = 0; ii < mm; ii++) {</pre>
00086
          int offset{ii*nn};
00087
          for (int jj = 0; jj < nn; jj++) {</pre>
00088
            mtk::Real value = in.data_[offset + jj];
00089
           stream << std::setw(9) << value;
00090
00091
         stream << std::endl;
00092
       if (in.matrix_properties_.ordering() ==
     mtk::COL_MAJOR) {
00094
         std::swap(mm, nn);
00095
00096
        return stream;
00097 }
00098 }
00099
00100 mtk::DenseMatrix& mtk::DenseMatrix::operator = (const
     mtk::DenseMatrix &in) {
00101
00102
        if(this == \&in) {
00103
         return *this;
00104
00105
00106
       matrix_properties_.set_storage(in.
     matrix_properties_.storage());
00107
00108
       matrix_properties_.set_ordering(in.
```

```
matrix_properties_.ordering());
00109
00110
        auto aux = in.matrix_properties_.num_rows();
00111
        matrix_properties_.set_num_rows(aux);
00112
00113
        aux = in.matrix_properties().num_cols();
00114
       matrix_properties_.set_num_cols(aux);
00115
00116
       aux = in.matrix_properties().num_zero();
00117
       matrix_properties_.set_num_zero(aux);
00118
00119
        aux = in.matrix_properties().num_null();
00120
       matrix properties .set num null(aux);
00121
00122
        auto num_rows = matrix_properties_.num_rows();
00123
        auto num_cols = matrix_properties_.num_cols();
00124
00125
        delete [] data ;
00126
00127
        trv {
        data_ = new mtk::Real[num_rows*num_cols];
} catch (std::bad_alloc &memory_allocation_exception) {
00128
00129
00130
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00131
           std::endl;
00132
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00133
00134
       memset(data_, mtk::kZero, sizeof(data_[0])*num_rows*
      num_cols);
00135
00136
        std::copy(in.data_, in.data_ + num_rows*num_cols, data_);
00137
00138
        return *this:
00139 }
00140
00141 bool mtk::DenseMatrix::operator == (const
     DenseMatrix &in) {
00142
00143
        bool ans{true};
00144
00145
       auto mm = in.num_rows();
00146
       auto nn = in.num_cols();
00147
00148
        if (mm != matrix_properties_.num_rows() ||
00149
            nn != matrix_properties_.num_cols()) {
00150
         return false;
00151
00152
00153
        for (int ii = 0; ii < mm && ans; ++ii) {</pre>
00154
        for (int jj = 0; jj < nn && ans; ++jj) {</pre>
00155
           ans = ans &&
00156
              abs(data_[ii*nn + jj] - in.data()[ii*nn + jj]) <
     mtk::kDefaultTolerance;
00157
         }
00158
00159
        return ans;
00160 }
00161
00162 mtk::DenseMatrix::DenseMatrix(): data_(nullptr) {
00163
00164
        matrix_properties_.set_storage(mtk::DENSE);
00165
       matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00166 }
00168 mtk::DenseMatrix::DenseMatrix(const
     mtk::DenseMatrix &in) {
00169
00170
        matrix_properties_.set_storage(in.matrix_properties_.storage());
00171
00172
       matrix_properties_.set_ordering(in.matrix_properties_.
     ordering());
00173
00174
        auto aux = in.matrix properties .num rows();
00175
       matrix properties .set num rows(aux);
00176
00177
       aux = in.matrix properties().num cols();
00178
       matrix_properties_.set_num_cols(aux);
00179
00180
        aux = in.matrix_properties().num_zero();
00181
        matrix_properties_.set_num_zero(aux);
00182
00183
        aux = in.matrix_properties().num_null();
```

```
00184
        matrix_properties_.set_num_null(aux);
00185
00186
        auto num_rows = in.matrix_properties_.num_rows();
        auto num_cols = in.matrix_properties_.num_cols();
00187
00188
00189
00190
          data_ = new mtk::Real[num_rows*num_cols];
00191
        } catch (std::bad_alloc &memory_allocation_exception) {
00192
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00193
00194
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00195
00196
        memset(data , mtk::kZero, sizeof(data [0])*num rows*num cols);
00198
        std::copy(in.data_,in.data_ + num_rows*num_cols,data_);
00199 }
00200
00201 mtk::DenseMatrix::DenseMatrix(const int &num_rows, const int &num_cols) {
00202
00203
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(num_rows < 1, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(num_cols < 1, __FILE__, __LINE__, __func__);</pre>
00204
00205
00206
        #endif
00207
00208
        matrix_properties_.set_storage(mtk::DENSE);
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00209
00210
        matrix_properties_.set_num_rows(num_rows);
00211
        matrix_properties_.set_num_cols(num_cols);
00212
00213
00214
          data_ = new mtk::Real[num_rows*num_cols];
00215
        } catch (std::bad_alloc &memory_allocation_exception) {
00216
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00217
            std::endl:
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00218
00219
00220
       memset(data_, mtk::kZero, sizeof(data_[0])*num_rows*num_cols);
00221 }
00222
00223 mtk::DenseMatrix::DenseMatrix(const int &rank,
00224
                                      const bool &padded,
00225
                                      const bool &transpose) {
00226
00227
        #if MTK DEBUG LEVEL > 0
00228
        mtk::Tools::Prevent(rank < 1, __FILE__, __LINE__, __func__);</pre>
00229
        #endif
00230
00231
        int aux{}; // Used to control the padding.
00232
00233
        if (padded) {
00234
         aux = 1;
00235
00236
00237
        matrix_properties_.set_storage(mtk::DENSE);
00238
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00239
        matrix_properties_.set_num_rows(aux + rank + aux);
00240
        matrix_properties_.set_num_cols(rank);
00241
00242
00243
          data_ = new mtk::Real[matrix_properties_.num_values()];
00244
        } catch (std::bad_alloc &memory_allocation_exception) {
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00245
00246
00247
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00248
00249
        memset (data_,
               mtk::kZero,
00250
00251
               sizeof(data_[0]) * (matrix_properties_.num_values()));
00252
00253
        for (auto ii =0; ii < matrix_properties_.num_rows(); ++ii) {</pre>
00254
         for (auto jj = 0; jj < matrix_properties_.num_cols(); ++jj) {</pre>
00255
            data_[ii*matrix_properties_.num_cols() + jj] =
              (ii == jj + aux)? mtk::kOne: mtk::kZero;
00256
00257
00258
00259
        if (transpose) {
00260
          Transpose();
00261
00262 }
00263
00264 mtk::DenseMatrix::DenseMatrix(const mtk::Real *const gen.
```

```
00265
                                       const int &gen_length,
00266
                                       const int &pro_length,
00267
                                       const bool &transpose)
00268
00269
        \#if MTK_DEBUG_LEVEL > 0
00270
        mtk::Tools::Prevent(gen == nullptr, __FILE__, __LINE__, __func__);
        mtk::Tools::Prevent(gen_length < 1, __FILE__, _LINE__, _func__);
mtk::Tools::Prevent(pro_length < 1, __FILE__, _LINE__, _func__);</pre>
00271
00272
00273
00274
00275
        matrix_properties_.set_storage(mtk::DENSE);
00276
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00277
        if (!transpose) {
00278
         matrix_properties_.set_num_rows(gen_length);
00279
          matrix properties .set num cols(pro length);
00280
        } else {
00281
          matrix properties .set num rows(pro length);
00282
          matrix_properties_.set_num_cols(gen_length);
00283
00284
        int mm = matrix_properties_.num_rows(); // Used to construct this matrix.
00285
00286
        int nn = matrix_properties_.num_cols(); // Used to construct this matrix.
00287
00288
        trv {
00289
        data_ = new mtk::Real[mm*nn];
} catch (std::bad_alloc &memory_allocation_exception) {
00290
00291
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00292
            std::endl;
00293
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00294
00295
        memset(data_, mtk::kZero, sizeof(data_[0])*mm*nn);
00296
        if (!transpose) {
  for (auto ii = 0; ii < mm; ii++) {</pre>
00297
00298
            for (auto jj = 0; jj < nn; jj++) {
  data_[ii*nn + jj] = pow(gen[ii], (double) jj);</pre>
00299
00300
00301
             }
00302
00303
        } else {
          for (auto ii = 0; ii < mm; ii++) {</pre>
00304
00305
           for (auto jj = 0; jj < nn; jj++) {</pre>
00306
              data_[ii*nn + jj] = pow(gen[jj], (double) ii);
00307
00308
00309
       }
00310 }
00311
00312 mtk::DenseMatrix::~DenseMatrix() {
00313
00314
        delete [] data_;
        data_ = nullptr;
00315
00316 }
00317
00318 mtk::Matrix mtk::DenseMatrix::matrix_properties() const
      noexcept {
00319
00320
        return matrix_properties_;
00321 }
00322
00323 void mtk::DenseMatrix::SetOrdering(
     mtk::MatrixOrdering oo) noexcept {
00324
00325
        #if MTK_DEBUG_LEVEL > 0
00326
        mtk::Tools::Prevent(!(oo == mtk::ROW_MAJOR || oo ==
      mtk::COL_MAJOR),
00327
                              __FILE__, __LINE__, __func__);
00328
00329
00330
        matrix_properties_.set_ordering(oo);
00331 }
00332
00333 int mtk::DenseMatrix::num_rows() const noexcept {
00334
00335
        return matrix_properties_.num_rows();
00336 }
00337
00338 int mtk::DenseMatrix::num_cols() const noexcept {
00339
00340
        return matrix_properties_.num_cols();
00341 }
00342
```

```
00343 mtk::Real* mtk::DenseMatrix::data() const noexcept {
00345
        return data_;
00346 }
00347
00348 mtk::Real mtk::DenseMatrix::GetValue(
00349
          const int &mm,
00350
          const int &nn) const noexcept {
00351
       #if MTK_DEBUG_LEVEL > 0
       mtk::Tools::Prevent(mm < 0, _FILE_, _LINE_, _func_);
mtk::Tools::Prevent(nn < 0, _FILE_, _LINE_, _func_);</pre>
00353
00354
00355
        #endif
00356
00357
        return data_[mm*matrix_properties_.num_cols() + nn];
00358 }
00359
00360 void mtk::DenseMatrix::SetValue(
00361
          const int &mm,
00362
          const int &nn,
00363
          const mtk::Real &val) noexcept {
00364
00365
        #if MTK DEBUG LEVEL > 0
00366
       mtk::Tools::Prevent(mm < 0, __FILE__, __LINE__, __func__);</pre>
00367
        mtk::Tools::Prevent(nn < 0, __FILE__, __LINE__, __func__);</pre>
00368
        #endif
00369
00370
        data_[mm*matrix_properties_.num_cols() + nn] = val;
00371 }
00372
00373 void mtk::DenseMatrix::Transpose() {
00374
00376
00377
        mtk::Real *data_transposed{}; // Buffer.
00378
        int mm = matrix_properties_.num_rows(); // Used to construct this matrix.
00379
00380
        int nn = matrix_properties_.num_cols(); // Used to construct this matrix.
00381
00382
          data_transposed = new mtk::Real[mm*nn];
00383
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<</pre>
00384
00385
00386
             std::endl;
00387
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00388
00389
        memset (data_transposed,
00390
               mtk::kZero,
00391
                sizeof(data_transposed[0])*mm*nn);
00392
00393
        // Assign the values to their transposed position.
00394
        for (auto ii = 0; ii < mm; ++ii) {</pre>
00395
         for (auto jj = 0; jj < nn; ++jj) {</pre>
00396
            data_transposed[jj*mm + ii] = data_[ii*nn + jj];
00397
00398
        }
00399
00400
        // Swap pointers.
00401
        auto tmp = data_; // Temporal holder.
00402
        data_ = data_transposed;
00403
        delete [] tmp;
00404
        tmp = nullptr;
00405
00406
        matrix_properties_.set_num_rows(nn);
00407
       matrix properties .set num cols(mm);
00408 }
00409
00410 void mtk::DenseMatrix::OrderRowMajor() {
00411
00412
        if (matrix_properties_.ordering() == mtk::COL_MAJOR) {
00413
00415
00416
          mtk::Real *data transposed{}; // Buffer.
00417
          int mm = matrix_properties_.num_rows(); // Used to construct this matrix.
00418
          int nn = matrix_properties_.num_cols(); // Used to construct this matrix.
00419
00420
00421
00422
            data transposed = new mtk::Real[mm*nn];
00423
          } catch (std::bad alloc &memory allocation exception) {
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00424
00425
              std::endl:
```

```
00426
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00427
00428
          memset (data_transposed,
00429
                mtk::kZero,
00430
                sizeof(data_transposed[0])*mm*nn);
00431
00432
          \ensuremath{//} Assign the values to their transposed position.
00433
          std::swap(mm, nn);
00434
          for (auto ii = 0; ii < mm; ++ii) {</pre>
            for (auto jj = 0; jj < nn; ++jj) {</pre>
00435
              data_transposed[jj*mm + ii] = data_[ii*nn + jj];
00436
00437
00438
00439
          std::swap(mm, nn);
00440
00441
          // Swap pointers.
          auto tmp = data_; // Temporal holder.
00442
          data_ = data_transposed;
00443
00444
          delete [] tmp;
00445
          tmp = nullptr;
00446
00447
          matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00448
00449 }
00450
00451 void mtk::DenseMatrix::OrderColMajor() {
00452
        if (matrix_properties_.ordering() == ROW_MAJOR) {
00453
00454
00456
00457
          mtk::Real *data transposed{}; // Buffer.
00458
          int mm = matrix_properties_.num_rows(); // Used to construct this matrix.
00459
          int nn = matrix_properties_.num_cols(); // Used to construct this matrix.
00460
00461
00462
00463
           data_transposed = new mtk::Real[mm*nn];
00464
          } catch (std::bad_alloc &memory_allocation_exception) {
00465
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00466
              std::endl;
00467
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00468
00469
          memset(data_transposed,
00470
                mtk::kZero,
00471
                sizeof(data_transposed[0])*mm*nn);
00472
00473
          \ensuremath{//} Assign the values to their transposed position.
00474
          for (auto ii = 0; ii < mm; ++ii) {</pre>
00475
           for (auto jj = 0; jj < nn; ++jj) {</pre>
00476
              data_transposed[jj*mm + ii] = data_[ii*nn + jj];
00477
00478
00479
00480
          // Swap pointers.
00481
          auto tmp = data_; // Temporal holder.
00482
          data_ = data_transposed;
          delete [] tmp;
00483
00484
          tmp = nullptr;
00485
00486
          matrix_properties_.set_ordering(mtk::COL_MAJOR);
00487
00488 }
00490 mtk::DenseMatrix mtk::DenseMatrix::Kron(const
     mtk::DenseMatrix &aa,
00491
                                               const mtk::DenseMatrix &bb) {
00492
00493
        int row_offset{}; // Offset for rows.
00494
       int col_offset{}; // Offset for rows.
00495
00496
       mtk::Real aa_factor{}; // Used in computation.
00497
        // Auxiliary variables:
00498
00499
        auto aux1 = aa.matrix properties .num rows()*bb.
     matrix_properties_.num_rows();
00500
       auto aux2 = aa.matrix_properties_.num_cols()*bb.
     matrix properties .num cols();
00501
00502
        mtk::DenseMatrix output(aux1,aux2); // Output matrix.
00503
00504
        int kk_num_cols{output.matrix_properties_.num_cols()}; // Aux.
```

```
00505
00506
        auto mm = aa.matrix_properties_.num_rows(); // Rows of aa.
        auto nn = aa.matrix_properties_.num_cols(); // Cols of aa.
00508
       auto pp = bb.matrix_properties_.num_rows(); // Rows of bb.
00509
        auto qq = bb.matrix_properties_.num_cols(); // Cols of bb.
00510
00511
       for (auto ii = 0; ii < mm; ++ii) {</pre>
00512
         row_offset = ii*pp;
00513
         for (auto jj = 0; jj < nn; ++jj) {</pre>
           col_offset = jj*qq;
00514
            aa_factor = aa.data_[ii*nn + jj];
00515
            for (auto 11 = 0; 11 < pp; ++11) {
00516
00517
             for (auto oo = 0; oo < qq; ++oo) {
               auto index = (ll + row_offset)*kk_num_cols + (oo + col_offset);
00519
                output.data_[index] = aa_factor*bb.data_[ll*qq + oo];
00521
            }
00522
         }
00523
       }
00524
00525
        output.matrix_properties_.set_storage(mtk::DENSE);
00526
       output.matrix_properties_.set_ordering(
     mtk::ROW MAJOR);
00527
00528
       return output;
00529 }
00530
00531 bool mtk::DenseMatrix::WriteToFile(const std::string &filename) const {
00532
00533
        std::ofstream output_dat_file; // Output file.
00534
00535
       output_dat_file.open(filename);
00536
00537
       return false;
}
        if (!output_dat_file.is_open()) {
00538
00539
00540
00541
        int mm{matrix_properties_.num_rows());
00542
       int nn{matrix_properties_.num_cols()};
00543
00544
        for (int ii = 0; ii < mm; ++ii) {</pre>
00545
         int offset{ii*nn};
         for (int jj = 0; jj < nn; ++jj) {
  output_dat_file << ii << ' ' << jj << ' ' << data_[offset + jj] <</pre>
00546
00547
00548
00549
00550
       }
00551
00552
       output_dat_file.close();
00553
00554
       return true;
00555 }
```

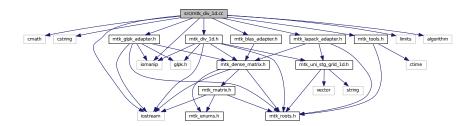
17.61 src/mtk_div_1d.cc File Reference

Implements the class Div1D.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_div_ld.h"
```

17.62 mtk div 1d.cc 299

Include dependency graph for mtk_div_1d.cc:



Namespaces

mtk

Mimetic Methods Toolkit namespace.

Functions

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Div1D &in)

17.61.1 Detailed Description

This class implements a 1D divergence matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Overload ostream operator as in mtk::Lap1D.

Todo Implement creation of ■ w. mtk::BLASAdapter.

Definition in file mtk_div_1d.cc.

17.62 mtk_div_1d.cc

```
00001
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00018
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00021
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed, unless these modifications are made through the project's GitHub
00025 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00026 should be developed and included in any deliverable.
00027
00028 2. Redistributions of source code must be done through direct
```

```
00029 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00031 3. Redistributions in binary form must reproduce the above copyright notice,
00032 this list of conditions and the following disclaimer in the documentation and/or
00033 other materials provided with the distribution.
00035 4. Usage of the binary form on proprietary applications shall require explicit
00036 prior written permission from the the copyright holders, and due credit should
00037 be given to the copyright holders.
00039 5. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00060
00061 #include <cmath>
00062 #include <cstring>
00063
00064 #include <iostream>
00065 #include <iomanip>
00066 #include <limits>
00067 #include <algorithm>
00068
00069 #include "mtk_tools.h"
00070
00071 #include "mtk_blas_adapter.h" 00072 #include "mtk_lapack_adapter.h"
00073 #include "mtk_glpk_adapter.h"
00074
00075 #include "mtk_div_1d.h"
00076
00077 namespace mtk {
00078
00079 std::ostream& operator <<(std::ostream &stream, mtk::Div1D &in) {
08000
00082
00083
       stream << "divergence_[0] = " << std::setw(9) << in.divergence_[0] <<</pre>
00084
         std::endl;
00085
00087
00088
        stream << "divergence_[1:" << in.order_accuracy_ << "] = ";</pre>
00089
        for (auto ii = 1; ii <= in.order_accuracy_; ++ii) {</pre>
00090
         stream << std::setw(9) << in.divergence_[ii] << " ";
00091
00092
        stream << std::endl;
00093
00094
        if (in.order_accuracy_ > 2) {
00095
00097
00098
          stream << "divergence_[" << in.order_accuracy_ + 1 << ":" <<
00099
           2*in.order_accuracy_ << "] = ";</pre>
          for (auto ii = in.order_accuracy_ + 1; ii <= 2*in.</pre>
00100
     order_accuracy_; ++ii) {
00101
           stream << std::setw(9) << in.divergence_[ii] << " ";
00102
00103
          stream << std::endl;
00104
00106
00107
          auto offset = (2*in.order accuracy + 1);
00108
          int mm{};
          for (auto ii = 0; ii < in.dim_null_; ++ii) {</pre>
00109
00110
            stream << "divergence_[" << offset + mm << ":" <<
            offset + mm + in.num_bndy_coeffs_ - 1 << "] = ";
for (auto jj = 0; jj < in.num_bndy_coeffs_; ++jj) {</pre>
00111
00112
```

17.62 mtk_div_1d.cc 301

```
auto value = in.divergence_[offset + mm];
stream << std::setw(9) << value << " ";</pre>
00113
00114
00115
00116
00117
            stream << std::endl;</pre>
00118
00119
00120
00121
        return stream;
00122 }
00124
00125 mtk::Div1D::Div1D():
00126 order_accuracy_(mtk::kDefaultOrderAccuracy),
00127
        dim_null_(),
       num_bndy_coeffs_(),
00129
       divergence_length_(),
00130
       minrow (),
00131
        row_(),
00132
       coeffs_interior_(),
00133
        prem_apps_(),
00134
        weights_crs_(),
00135
        weights_cbs_(),
00136
       mim_bndy_(),
00137
        divergence ().
       mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00138
00139
00140 mtk::Div1D::Div1D(const Div1D &div):
00141
        order_accuracy_(div.order_accuracy_),
00142
        dim_null_(div.dim_null_),
00143
        num_bndy_coeffs_(div.num_bndy_coeffs_),
00144
        divergence_length_(div.divergence_length_),
00145
        minrow_(div.minrow_),
00146
        row_(div.row_),
        coeffs_interior_(div.coeffs_interior_),
00147
00148
        prem_apps_(div.prem_apps_),
00149
        weights_crs_(div.weights_crs_),
00150
        weights_cbs_(div.weights_cbs_),
00151
        mim_bndy_(div.mim_bndy_),
00152
        divergence_(div.divergence_),
00153
        mimetic_threshold_(div.mimetic_threshold_) {}
00154
00155 mtk::Div1D::~Div1D() {
00156
00157
        delete[] coeffs_interior_;
00158
        coeffs_interior_ = nullptr;
00159
00160
        delete[] prem_apps_;
00161
       prem_apps_ = nullptr;
00162
00163
        delete[] weights_crs_;
00164
        weights_crs_ = nullptr;
00165
00166
        delete[] weights_cbs_;
00167
        weights_cbs_ = nullptr;
00168
00169
        delete[] mim_bndy_;
00170
        mim_bndy_ = nullptr;
00171
00172
        delete[] divergence_;
00173
       divergence_ = nullptr;
00174 }
00175
00176 bool mtk::Div1D::ConstructDiv1D(int order_accuracy,
00177
                                       mtk::Real mimetic_threshold) {
00178
00179
       #if MTK_DEBUG_LEVEL > 0
       00180
00181
00182
00183
00184
00185
        if (order_accuracy >= mtk::kCriticalOrderAccuracyDiv) {
00186
         std::cout << "WARNING: Numerical accuracy is critical." << std::endl;</pre>
00187
00188
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;
std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;</pre>
00189
00190
00191
        #endif
00192
00193
        order_accuracy_ = order_accuracy;
```

```
00194
        mimetic_threshold_ = mimetic_threshold;
00195
00197
00198
       bool abort_construction = ComputeStencilInteriorGrid();
00199
00200
        #if MTK_DEBUG_LEVEL > 0
00201
        if (!abort_construction) {
00202
         std::cerr << "Could NOT complete stage 1." << std::endl;
00203
          std::cerr << "Exiting..." << std::endl;
00204
         return false;
00205
00206
00207
00208
        // At this point, we already have the values for the interior stencil stored
00209
        // in the coeffs_interior_ array.
00210
00211
        // It is noteworthy, that the 2nd-order-accurate divergence operator has NO
00212
        // approximation at the boundary, thus it has no weights. For this case, the
        // dimension of the null-space of the Vandermonde matrices used to compute the
00213
00214
        // approximating coefficients at the boundary is 0. Ergo, we compute this
00215
        // number first and then decide if we must compute anything at the boundary.
00216
00217
        dim_null_ = order_accuracy_/2 - 1;
00218
00219
        if (dim null > 0) {
00220
00221
          #ifdef MTK PRECISION DOUBLE
          num_bndy_coeffs_ = (int) (3.0*((mtk::Real) order_accuracy_)/2.0);
00222
00223
          num_bndy_coeffs_ = (int) (3.0f*((mtk::Real) order_accuracy_)/2.0f);
00224
00225
          #endif
00226
00228
00229
          \ensuremath{//} For this we will follow recommendations given in:
00230
          // http://icl.cs.utk.edu/lapack-forum/viewtopic.php?f=5&t=4506
00231
00232
          // We will compute the QR Factorization of the transpose, as in the
00233
00234
          // following (MATLAB) pseudo-code:
00235
          11
          // [Q,R] = qr(V'); % Full QR as defined in
00236
          // % http://www.stanford.edu/class/ee263/notes/qr_matlab.pdf
00237
00238
00239
          // null-space = Q(:, last (order_accuracy_/2 - 1) columns of Q );
00240
00241
          // However, given the nature of the Vandermonde matrices we've just
00242
          \ensuremath{//} computed, they all posses the same null-space. Therefore, we impose the
00243
          // convention of computing the null-space of the first Vandermonde matrix
00244
          // (west boundary).
00245
00246
          abort_construction = ComputeRationalBasisNullSpace();
00247
00248
          #if MTK_DEBUG_LEVEL > 0
00249
          if (!abort_construction) {
00250
            std::cerr << "Could NOT complete stage 2.1." << std::endl;</pre>
00251
            std::cerr << "Exiting..." << std::endl;</pre>
00252
            return false;
00253
00254
          #endif
00255
00257
00258
          abort_construction = ComputePreliminaryApproximations();
00259
00260
          #if MTK_DEBUG_LEVEL > 0
00261
          if (!abort_construction) {
00262
            std::cerr << "Could NOT complete stage 2.2." << std::endl;
            std::cerr << "Exiting..." << std::endl;
00263
00264
            return false;
00265
00266
          #endif
00267
00269
00270
          abort construction = ComputeWeights();
00271
00272
          #if MTK_DEBUG_LEVEL > 0
00273
          if (!abort construction) {
00274
           std::cerr << "Could NOT complete stage 2.3." << std::endl;
            std::cerr << "Exiting..." << std::endl;
00275
00276
            return false;
00277
00278
          #endif
```

17.62 mtk_div_1d.cc 303

```
00279
00281
          abort_construction = ComputeStencilBoundaryGrid();
00282
00283
00284
          #if MTK_DEBUG_LEVEL > 0
00285
          if (!abort_construction) {
00286
            std::cerr << "Could NOT complete stage 2.4." << std::endl;
            std::cerr << "Exiting..." << std::endl;
00287
00288
            return false;
00289
00290
          #endif
00291
00292
        } // End of: if (dim_null_ > 0);
00293
00295
00296
        // Once we have the following three collections of data:
        // (a) the coefficients for the interior, // (b) the coefficients for the boundary
00297
            (b) the coefficients for the boundary (if it applies),
00298
00299
             (c) and the weights (if it applies),
00300
        // we will store everything in the output array:
00301
00302
        abort construction = AssembleOperator();
00303
00304
       #if MTK_DEBUG_LEVEL > 0
00305
        if (!abort_construction) {
         std::cerr << "Could NOT complete stage 3." << std::endl;
00306
          std::cerr << "Exiting..." << std::endl;
00307
00308
         return false;
00309
00310
        #endif
00311
00312
       return true;
00313 }
00314
00315 int mtk::Div1D::num_bndy_coeffs() const {
00316
00317
       return num_bndy_coeffs_;
00318 }
00319
00320 mtk::Real *mtk::Div1D::coeffs_interior() const {
00321
00322
        return coeffs_interior_;
00323 }
00324
00325 mtk::Real *mtk::Div1D::weights_crs() const {
00326
00327
        return weights_crs_;
00328 }
00329
00330 mtk::Real *mtk::Div1D::weights_cbs() const {
00331
00332
00333
        return weights_cbs_;
00334 }
00335
00336 mtk::DenseMatrix mtk::Div1D::mim_bndy() const {
00337
00338
       mtk::DenseMatrix xx(dim_null_, 3*order_accuracy_/2);
00339
00340
        auto counter = 0;
00341
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00342
         for(auto jj = 0; jj < 3*order_accuracy_/2; ++jj) {</pre>
00343
           xx.SetValue(ii, jj, divergence_[2*order_accuracy_ + 1 + counter]);
00344
            counter++;
00345
00346
        }
00347
00348
        return xx;
00349 }
00350
00351 mtk::DenseMatrix mtk::Div1D::ReturnAsDenseMatrix(
00352
        const UniStgGrid1D &grid) const {
00353
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00354
00355
00356
        #if MTK DEBUG LEVEL > 0
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);
00357
        mtk::Tools::Prevent(nn < 3*order_accuracy_ - 1, __FILE__, __LINE__, __func__);</pre>
00358
00359
        #endif
00360
00361
        mtk::Real inv delta x{mtk::kOne/grid.delta x()};
```

```
00362
00363
        int dd_num_rows = nn + 2;
00364
        int dd_num_cols = nn + 1;
        int elements_per_row = num_bndy_coeffs_;
00365
00366
        int num_extra_rows = dim_null_;
00367
00368
        // Output matrix featuring sizes for divergence operators.
00369
        mtk::DenseMatrix out(dd_num_rows, dd_num_cols);
00370
00372
00373
        auto ee_index = 0;
00374
        for (auto ii = 1; ii < num_extra_rows + 1; ii++) {</pre>
00375
          auto cc = 0;
          for(auto jj = 0; jj < dd_num_rows; jj++) {
  if( cc >= elements_per_row) {
00376
00377
00378
              out.SetValue(ii, jj, mtk::kZero);
00379
            } else {
00380
              out.SetValue(ii, jj, mim_bndy_[ee_index++]*inv_delta_x);
00381
              cc++;
00382
00383
          }
00384
        }
00385
00387
00388
        for (auto ii = num_extra_rows + 1;
             ii < dd_num_rows - num_extra_rows - 1; ii++) {</pre>
00389
          auto jj = ii - num_extra_rows - 1;
for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {</pre>
00390
00391
00392
            out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00393
00394
        }
00395
00397
00398
        ee_index = 0;
00399
        for (auto ii = dd_num_rows - 2; ii >= dd_num_rows - num_extra_rows - 1; ii--) {
00400
          auto cc = 0;
00401
          for (auto jj = dd_num_cols - 1; jj >= 0; jj--) {
00402
            if( cc >= elements_per_row) {
              out.SetValue(ii,jj,0.0);
00403
            } else {
00404
00405
               out.SetValue(ii, jj, -mim_bndy_[ee_index++] *inv_delta_x);
00406
               cc++;
00407
            }
00408
           }
00409
        }
00410
00411
        return out;
00412 }
00413
00414 bool mtk::Div1D::ComputeStencilInteriorGrid() {
00415
00417
00418
        mtk::Real* pp{}; // Spatial coordinates to create interior stencil.
00419
00420
00421
          pp = new mtk::Real[order_accuracy_];
00422
        } catch (std::bad_alloc &memory_allocation_exception) {
00423
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00424
            std::endl;
00425
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00426
00427
        memset(pp, mtk::kZero, sizeof(pp[0])*order_accuracy_);
00428
00429
        #ifdef MTK_PRECISION_DOUBLE
        pp[0] = 1.0/2.0 - ((mtk::Real) order_accuracy_)/2.0;
00430
00431
        #else
00432
        pp[0] = 1.0f/2.0f - ((mtk::Real) order_accuracy_)/2.0f;
00433
        #endif
00434
00435
        for (auto ii = 1; ii < order_accuracy_; ++ii) {</pre>
00436
         pp[ii] = pp[ii - 1] + mtk::kOne;
00437
00438
00439
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "pp =" << std::endl;
00440
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00441
          std::cout << std::setw(12) << pp[ii];
00442
00443
00444
        std::cout << std::endl << std::endl;
00445
        #endif
00446
```

17.62 mtk_div_1d.cc 305

```
00448
00449
        bool transpose{false};
00450
00451
        mtk::DenseMatrix vander_matrix(pp,
00452
                                         order_accuracy_,
00453
                                         order_accuracy_,
00454
                                         transpose);
00455
00456
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "vander_matrix = " << std::endl;</pre>
00457
00458
        std::cout << vander_matrix << std::endl;</pre>
00459
        #endif
00460
00462
00463
        trv {
00464
         coeffs_interior_ = new mtk::Real[order_accuracy_];
00465
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00466
00467
            std::endl;
00468
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00469
00470
        memset(coeffs interior, mtk::kZero, sizeof(coeffs interior [0])*order accuracy);
00471
00472
        coeffs_interior_[1] = mtk::kOne;
00473
00474
        #if MTK DEBUG LEVEL > 0
00475
        std::cout << "oo =" << std::endl;
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00476
00477
         std::cout << std::setw(12) << coeffs_interior_[ii] << std::endl;</pre>
00478
00479
        std::cout << std::endl:
00480
        #endif
00481
00483
        int info{mtk::LAPACKAdapter::SolveDenseSystem(vander_matrix,
00484
00485
                                                         coeffs_interior_) };
00486
        #if MTK_DEBUG_LEVEL > 0
00487
00488
        if (!info) {
         std::cout << "System solved! Interior stencil attained!" << std::endl;</pre>
00489
00490
          std::cout << std::endl;</pre>
00491
00492
        else {
00493
          std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
          std::cerr << "Exiting..." << std::endl;</pre>
00494
00495
          return false;
00496
00497
        #endif
00498
00499
        #if MTK_DEBUG_LEVEL > 0
00500
        std::cout << "coeffs_interior_ =" << std::endl;</pre>
00501
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00502
         std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
00503
00504
        std::cout << std::endl << std::endl;
00505
00506
00507
        delete [] pp;
        pp = nullptr;
00508
00509
00510
        return true;
00511 }
00512
00513 bool mtk::Div1D::ComputeRationalBasisNullSpace(void) {
00514
00515
        mtk::Real* gg{}; // Generator vector for the first Vandermonde matrix.
00516
00518
00519
        try {
          gg = new mtk::Real[num_bndy_coeffs_];
00520
00521
        } catch (std::bad_alloc &memory_allocation_exception) {
00522
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00523
            std::endl;
00524
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00525
00526
        memset(gg, \ mtk::kZero, \ sizeof(gg[0])*num\_bndy\_coeffs\_);
00527
        #ifdef MTK_PRECISION_DOUBLE
00528
00529
        qq[0] = -1.0/2.0;
00530
        #else
        gg[0] = -1.0f/2.0f;
00531
```

```
00532
00533
        for (auto ii = 1; ii < num_bndy_coeffs_; ++ii) {</pre>
00534
         gg[ii] = gg[ii - 1] + mtk::kOne;
00535
00536
00537
        #if MTK_DEBUG_LEVEL > 0
00538
        std::cout << "gg =" << std::endl;
00539
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00540
         std::cout << std::setw(12) << gg[ii];
00541
00542
        std::cout << std::endl << std::endl;</pre>
00543
        #endif
00544
00546
00547
        bool tran{true}; // Should I transpose the Vandermonde matrix.
00548
00549
       mtk::DenseMatrix vv west t(gg, num bndv coeffs, order accuracy + 1, tran);
00550
00551
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "vv_west_t =" << std::endl;
00552
        std::cout << vv_west_t << std::endl;</pre>
00553
00554
        #endif
00555
00557
       mtk::DenseMatrix qq_t(mtk::LAPACKAdapter::QRFactorDenseMatrix
00558
      (vv_west_t));
00559
00560
       #if MTK DEBUG LEVEL > 0
        std::cout << "QQ^T = " << std::endl;
00561
00562
        std::cout << qq_t << std::endl;
00563
        #endif
00564
00566
00567
        int KK_num_rows_{num_bndy_coeffs_};
00568
        int KK_num_cols_{dim_null_};
00569
00570
        mtk::DenseMatrix KK(KK_num_rows_, KK_num_cols_);
00571
00572
        for (auto ii = num_bndy_coeffs_ - dim_null_; ii < num_bndy_coeffs_; ++ii) {</pre>
00573
          for (auto jj = 0; jj < num_bndy_coeffs_; ++jj) {</pre>
            KK.data()[jj*dim_null_ + (ii - (num_bndy_coeffs_ - dim_null_))] =
00574
00575
                qq_t.data()[ii*num_bndy_coeffs_ + jj];
00576
00577
00578
00579
        #if MTK_DEBUG_LEVEL > 0
00580
        std::cout << "KK =" << std::endl;
00581
        std::cout << KK << std::endl;
        std::cout << "KK.num_rows() = " << KK.num_rows() << std::endl;
00582
        std::cout << "KK.num_cols() = " << KK.num_cols() << std::endl;
00583
00584
        std::cout << std::endl;</pre>
00585
        #endif
00586
00588
00589
        // Scale thus requesting that the last entries of the attained basis for the
00590
        // null-space, adopt the pattern we require.
00591
        // Essentially we will implement the following MATLAB pseudo-code:
00592
        // scalers = KK(num_bndy_approxs - (dim_null - 1):num_bndy_approxs,:)\B
00593
       // SK = KK*scalers
00594
        // where SK is the scaled null-space.
00595
00596
        // In this point, we almost have all the data we need correctly allocated
00597
        // in memory. We will create the matrix II_, and elements we wish to scale in
00598
        // the KK array. Using the concept of the leading dimension, we could just
00599
        // use KK, with the correct leading dimension and that is it. BUT I DO NOT
00600
        // GET how does it work. So I will just create a matrix with the content of
        // this array that we need, solve for the scalers and then scale the
00602
        // whole KK:
00603
00604
        // We will then create memory for that sub-matrix of KK (SUBK).
00605
00606
       mtk::DenseMatrix SUBK(dim null , dim null );
00607
00608
        for (auto ii = num_bndy_coeffs_ - dim_null_; ii < num_bndy_coeffs_; ++ii) {</pre>
         for (auto jj = 0; jj < dim_null_; ++jj) {
   SUBK.data()[(ii - (num_bndy_coeffs_ - dim_null_))*dim_null_ + jj] =
00609
00610
                KK.data()[ii*dim_null_ + jj];
00611
00612
00613
        }
00614
       #if MTK DEBUG LEVEL > 0
00615
```

17.62 mtk_div_1d.cc 307

```
00616
        std::cout << "SUBK =" << std::endl;
00617
        std::cout << SUBK << std::endl;
00618
00619
00620
        SUBK.Transpose();
00621
00622
        #if MTK_DEBUG_LEVEL > 0
00623
        std::cout << "SUBK^T =" << std::endl;</pre>
00624
        std::cout << SUBK << std::endl;
00625
        #endif
00626
00627
        bool padded{false};
00628
        tran = false;
00629
00630
        mtk::DenseMatrix II(dim_null_, padded, tran);
00631
00632
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "II =" << std::endl;
00633
00634
        std::cout << II << std::endl;
00635
        #endif
00636
00637
        // Solve the system to compute the scalers.
00638
        // An example of the system to solve, for k = 8, is:
00639
        11
00640
        // SUBK*scalers = II_ or
00641
        11
        // | 0.386018 -0.0339244 -0.129478 | | 1 0 0 |
// | -0.119774 0.0199423 0.0558632 |*scalers = | 0 1 0 |
00642
00643
00644
        // | 0.0155708 -0.00349546 -0.00853182 |
00645
00646
        // Notice this is a nrhs = 3 system.
        // Noteworthy: we do NOT ACTUALLY ALLOCATE space for the scalers... they
00647
00648
        \ensuremath{//} will be stored in the created identity matrix.
00649
        // Let us first transpose SUBK (because of LAPACK):
00650
00651
        int info{mtk::LAPACKAdapter::SolveDenseSystem(SUBK, II)};
00652
00653
        #if MTK_DEBUG_LEVEL > 0
00654
        if (!info) {
         std::cout << "System successfully solved!" <<
00655
00656
            std::endl;
00657
        } else {
          std::cerr << "Something went wrong solving system! info = " << info <<</pre>
00658
00659
            std::endl;
          std::cerr << "Exiting..." << std::endl;
00660
00661
          return false;
00662
00663
        std::cout << std::endl;</pre>
00664
       #endif
00665
00666
        \#if MTK_DEBUG_LEVEL > 0
00667
        std::cout << "Computed scalers:" << std::endl;</pre>
00668
        std::cout << II << std::endl;
00669
00670
00671
        // Multiply the two matrices to attain a scaled basis for null-space.
00672
00673
        rat_basis_null_space_ = mtk::BLASAdapter::RealDenseMM(KK, II);
00674
00675
        #if MTK_DEBUG_LEVEL > 0
00676
        std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00677
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00678
        #endif
00679
00680
        // At this point, we have a rational basis for the null-space, with the
00681
        // pattern we need! :)
00682
00683
        delete [] qq;
00684
        gg = nullptr;
00685
00686
        return true;
00687 }
00688
00689 bool mtk::Div1D::ComputePreliminaryApproximations(void) {
00690
00692
00693
        mtk::Real *gg{}; // Generator vector for the first approximation.
00694
00695
          gg = new mtk::Real[num_bndy_coeffs_];
00696
00697
        } catch (std::bad_alloc &memory_allocation_exception) {
```

```
00698
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00699 std::endl;
00700
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00701
00702
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00703
00704
        #ifdef MTK_PRECISION_DOUBLE
00705
        gg[0] = -1.0/2.0;
00706
00707
        gg[0] = -1.0f/2.0f;
00708
        #endif
00709
        for (auto ii = 1; ii < num_bndy_coeffs_; ++ii) {</pre>
00710
         gg[ii] = gg[ii - 1] + mtk::kOne;
00711
00712
00713
        #if MTK_DEBUG_LEVEL > 0
00714
        std::cout << "gg0 =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00715
00716
         std::cout << std::setw(12) << gg[ii];
00717
00718
        std::cout << std::endl << std::endl;
00719
        #endif
00720
00721
        // Allocate 2D array to store the collection of preliminary approximations.
00722
00723
          prem_apps_ = new mtk::Real[num_bndy_coeffs_*dim_null_];
        } catch (std::bad_alloc &memory_allocation_exception) {
00724
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00725
00726 std::endl:
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00727
00728
00729
       memset (prem_apps_,
00730
               mtk::kZero.
00731
               sizeof(prem_apps_[0])*num_bndy_coeffs_*dim_null_);
00732
00734
00735
        for (auto 11 = 0; 11 < dim null; ++11) {</pre>
00736
00737
          // Re-check new generator vector for every iteration except for the first.
00738
          #if MTK_DEBUG_LEVEL > 0
00739
          if (11 > 0) {
            std::cout << "gg" << 11 << " =" << std::endl;
00740
            for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00741
00742
              std::cout << std::setw(12) << gg[ii];
00743
00744
            std::cout << std::endl << std::endl;
00745
00746
          #endif
00747
00749
00750
          bool transpose(false);
00751
00752
          mtk::DenseMatrix AA_(gg,
00753
                                num_bndy_coeffs_, order_accuracy_ + 1,
00754
                                transpose);
00755
00756
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "AA_" << 11 << " =" << std::endl;
00757
00758
          std::cout << AA_ << std::endl;
00759
          #endif
00760
00762
00763
          mtk::Real *ob{};
00764
00765
          auto ob_ld = num_bndy_coeffs_;
00766
00767
00768
           ob = new mtk::Real[ob_ld];
00769
          } catch (std::bad_alloc &memory_allocation_exception) {
00770
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00771
              std::endl:
00772
            std::cerr << memory allocation exception.what() << std::endl;</pre>
00773
00774
          memset(ob, mtk::kZero, sizeof(ob[0])*ob_ld);
00775
00776
          ob[1] = mtk::kOne;
00777
00778
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "ob = " << std::endl << std::endl;
00779
          for (auto ii = 0; ii < ob_ld; ++ii) {
   std::cout << std::setw(12) << ob[ii] << std::endl;</pre>
00780
00781
```

17.62 mtk_div_1d.cc 309

```
00782
00783
          std::cout << std::endl;
00784
00785
00787
00788
          // However, this is an under-determined system of equations. So we can not
00789
          // use the same LAPACK routine (dgesv_). We will instead use dgels_, through
00790
          // our LAPACKAdapter class.
00791
00792
          int info_{
00793
            mtk::LAPACKAdapter::SolveRectangularDenseSystem(AA_,
     ob, ob_ld)};
00794
00795
          #if MTK_DEBUG_LEVEL > 0
00796
          if (!info_) {
00797
           std::cout << "System successfully solved!" << std::endl << std::endl;
00798
          } else {
00799
           std::cerr << "Error solving system! info = " << info_ << std::endl;</pre>
00800
00801
          #endif
00802
00803
          #if MTK_DEBUG_LEVEL > 0
00804
          std::cout << "ob =" << std::endl;
00805
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
00806
            std::cout << std::setw(12) << ob[ii] << std::endl;
00807
00808
          std::cout << std::endl;
00809
          #endif
00810
00812
00813
          // This implies a DAXPY operation. However, we must construct the arguments
00814
          // for this operation.
00815
00817
          // Save them into the ob bottom array:
00818
00819
          Real *ob_bottom{}; // Bottom part of the attained kernel used to scale it.
00820
00821
00822
            ob_bottom = new mtk::Real[dim_null_];
          } catch (std::bad_alloc &memory_allocation_exception) {
00823
00824
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00825
              std::endl:
00826
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00827
00828
          memset(ob_bottom, mtk::kZero, sizeof(ob_bottom[0])*dim_null_);
00829
00830
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00831
            ob_bottom[(dim_null_ - 1) - ii] = ob[num_bndy_coeffs_ - ii - 1];
00832
00833
00834
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "ob_bottom =" << std::endl;
00835
00836
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00837
            std::cout << std::setw(12) << ob_bottom[ii] << std::endl;</pre>
00838
00839
          std::cout << std::endl;</pre>
00840
          #endif
00841
00843
00844
          // We must computed an scaled ob, sob, using the scaled null-space in
00845
          // rat_basis_null_space_.
00846
          // Such operation is: sob = ob - rat_basis_null_space_*ob_bottom
          // or:
00847
                                 ob = -1.0*rat_basis_null_space_*ob_bottom + 1.0*ob
00848
          // thus:
                                          a*A
                                                 * X
00849
00850
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00851
00852
          std::cout << rat_basis_null_space_ << std::endl;</pre>
00853
00854
00855
          mtk::Real alpha{-mtk::kOne};
00856
          mtk::Real beta{mtk::kOne};
00857
00858
          mtk::BLASAdapter::RealDenseMV(alpha, rat_basis_null_space_,
00859
                                         ob bottom, beta, ob);
00860
00861
          #if MTK DEBUG LEVEL > 0
          std::cout << "scaled ob:" << std::endl;
00862
00863
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00864
            std::cout << std::setw(12) << ob[ii] << std::endl;
00865
```

```
00866
           std::cout << std::endl;
00867
00868
00869
           // We save the recently scaled solution, into an array containing these.
00870
           // We can NOT start building the pi matrix, simply because I want that part
00871
           // to be separated since its construction depends on the algorithm we want
00872
           // to implement.
00873
00874
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00875
            prem_apps_[ii*dim_null_ + ll] = ob[ii];
00876
00877
00878
           // After the first iteration, simply shift the entries of the last
00879
           // generator vector used:
00880
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00881
            gg[ii]--;
00882
00883
00884
           // Garbage collection for this loop:
00885
           delete[] ob;
00886
           ob = nullptr;
00887
00888
           delete[] ob bottom;
00889
           ob bottom = nullptr:
00890
         } // End of: for (ll = 0; ll < dim_null; ll++);
00891
00892
         #if MTK DEBUG LEVEL > 0
         std::cout << "Matrix post-scaled preliminary apps: " << std::endl;</pre>
00893
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00894
00895
           for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
00896
            std::cout << std::setw(12) << prem_apps_[ii*dim_null_ + jj];</pre>
00897
00898
           std::cout << std::endl;
00899
00900
         std::cout << std::endl;
00901
         #endif
00902
00903
        delete[] gg;
00904
        gg = nullptr;
00905
00906
        return true;
00907 }
00908
00909 bool mtk::Div1D::ComputeWeights(void) {
00910
00911
         // Matrix to copmpute the weights as in the CRSA.
00912
        mtk::DenseMatrix pi(num_bndy_coeffs_, num_bndy_coeffs_ - 1);
00913
00915
00916
         // Assemble the pi matrix using:
00917
         \ensuremath{//} 1. The collection of scaled preliminary approximations.
00918
         \ensuremath{//} 2. The collection of coefficients approximating at the interior.
00919
        // 3. The scaled basis for the null-space.
00920
00921
        // 1.1. Process array of scaled preliminary approximations.
00922
00923
        // These are queued in scaled_solutions. Each one of these, will be a column
00924
         // of the pi matrix:
00925
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
          for (auto jj = 0; jj < dim_null_; ++jj) {
   pi.data()[ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj] =
        prem_apps_[ii*dim_null_ + jj];</pre>
00926
00927
00928
00929
          }
00930
        }
00931
00932
         // 1.2. Add columns from known stencil approximating at the interior.
00933
00934
         // However, these must be padded by zeros, according to their position in the
00935
         // final pi matrix:
00936
         auto mm = 0;
         for (auto jj = dim_null_; jj < order_accuracy_; ++jj) {
  for (auto ii = 0; ii < order_accuracy_; ++ii) {
    pi.data()[(ii + mm)*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj] =</pre>
00937
00938
00939
00940
               coeffs_interior_[ii];
00941
00942
           ++mm;
        }
00943
00944
00945
         rat_basis_null_space_.OrderColMajor();
00946
        #if MTK DEBUG LEVEL > 0
00947
```

17.62 mtk div 1d.cc 311

```
std::cout << "Rational basis for the null-space (col. major):" << std::endl;</pre>
00948
00949
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00950
00951
00952
        // 1.3. Add final set of columns: rational basis for null-space.
00953
        for (auto jj = dim_null_ + (order_accuracy_/2 + 1); jj < num_bndy_coeffs_ - 1; ++jj) {</pre>
00954
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00955
            auto og =
00956
              (jj - (dim_null_ + (order_accuracy_/2 + 1)))*num_bndy_coeffs_ + ii;
            auto de = ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj;
00957
            pi.data()[de] = rat_basis_null_space_.data()[og];
00958
00959
00960
        }
00961
00962
        #if MTK_DEBUG_LEVEL >0
        std::cout << "coeffs_interior_ =" << std::endl;</pre>
00964
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
          std::cout << std::setw(12) << coeffs_interior_[ii];
00965
00966
00967
        std::cout << std::endl << std::endl;
00968
        #endif
00969
00970
        #if MTK_DEBUG_LEVEL >0
00971
        std::cout << "Constructed pi matrix for CRS Algorithm: " << std::endl;</pre>
00972
        std::cout << pi << std::endl;</pre>
00973
        #endif
00974
00976
00977
        // This imposes the mimetic condition.
00978
00979
        mtk::Real *hh{}; // Right-hand side to compute weights in the C{R,B}SA.
00980
00981
         hh = new mtk::Real[num_bndy_coeffs_];
00982
        } catch (std::bad_alloc &memory_allocation_exception) {
00983
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00984
00985
            std::endl;
00986
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00987
00988
        memset(hh, mtk::kZero, sizeof(hh[0])*num_bndy_coeffs_);
00989
00990
        hh[0] = -mtk::kOne;
00991
        for (auto ii = (order_accuracy_/2 + 2 - 1); ii < num_bndy_coeffs_; ++ii) {</pre>
00992
          auto aux_xx = mtk::kZero;
          for (auto jj = 0; jj < ((ii - (order_accuracy_/2 - 1)) - 1); ++jj) {</pre>
00993
00994
            aux_xx += coeffs_interior_[jj];
00995
00996
          hh[ii] = -mtk::kOne*aux_xx;
00997
        }
00998
01000
01001
        // That is, we construct a system, to solve for the weights.
01002
01003
        \ensuremath{//} Once again we face the challenge of solving with LAPACK. However, for the
01004
        // CRSA, this matrix PI is over-determined, since it has more rows than
01005
        // unknowns. However, according to the theory, the solution to this system is
01006
        // unique. We will use dgels_.
01007
01008
01009
          weights_cbs_ = new mtk::Real[num_bndy_coeffs_];
01010
        } catch (std::bad_alloc &memory_allocation_exception) {
01011
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01012
            std::endl;
01013
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01014
01015
        memset(weights_cbs_, mtk::kZero, sizeof(weights_cbs_[0])*num_bndy_coeffs_);
01016
01017
        int weights_ld{pi.num_cols() + 1};
01018
01019
        // Preserve hh.
01020
        std::copy(hh, hh + weights_ld, weights_cbs_);
01021
01022
        pi.Transpose();
01023
        int info{mtk::LAPACKAdapter::SolveRectangularDenseSystem(
01024
     pi, weights_cbs_, weights_ld)};
01025
01026
        #if MTK DEBUG LEVEL > 0
01027
        if (!info) {
          std::cout << "System successfully solved!" << std::endl << std::endl;</pre>
01028
        } else {
01029
```

```
01030
          std::cerr << "Error solving system! info = " << info << std::endl;</pre>
01031
         #endif
01032
01033
         #if MTK_DEBUG_LEVEL > 0
01034
01035
         std::cout << "hh =" << std::endl;
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01036
01037
          std::cout << std::setw(11) << hh[ii] << std::endl;
01038
01039
         std::cout << std::endl;
01040
01041
01042
         // Preserve the original weights for research.
01043
01044
01045
          weights_crs_ = new mtk::Real[num_bndy_coeffs_];
01046
         } catch (std::bad_alloc &memory_allocation_exception) {
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01047
01048
             std::endl;
01049
           std::cerr << memory allocation exception.what() << std::endl;</pre>
01050
01051
        memset (weights crs , mtk::kZero, sizeof (weights crs [0]) *num bndy coeffs );
01052
01053
         std::copy(weights cbs , weights cbs + (weights ld - 1), weights crs );
01054
01055
         #if MTK DEBUG LEVEL > 0
         std::cout << "weights_CRSA + lambda =" << std::endl;
01056
         for (auto ii = 0; ii < weights_ld - 1; ++ii) {</pre>
01057
01058
          std::cout << std::setw(12) << weights_crs_[ii] << std::endl;</pre>
01059
01060
         std::cout << std::endl:
01061
         #endif
01062
01064
         if (order_accuracy_ >= mtk::kCriticalOrderAccuracyDiv) {
01065
01066
01067
           int minrow {std::numeric limits<int>::infinity()};
01068
01069
          mtk::Real norm_{mtk::BLASAdapter::RealNRM2(weights_cbs_,
      order_accuracy_) };
01070
           mtk::Real minnorm_{std::numeric_limits<mtk::Real>::infinity()};
01071
01073
01074
           mtk::DenseMatrix phi(order_accuracy_ + 1, order_accuracy_);
01075
01076
           for (auto ii = 0; ii < order_accuracy_ + 1; ++ii) {</pre>
01077
             for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01078
               phi.data()[ii*(order_accuracy_) + jj] = prem_apps_[ii*dim_null_ + jj];
01079
01080
01081
01082
           int aux{}; // Auxiliary variable.
01083
           for (auto jj = dim_null_; jj < dim_null_ + 2; ++jj) {</pre>
01084
             for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01085
               phi.data()[(ii + aux)*order_accuracy_ + jj] = coeffs_interior_[ii];
01086
01087
             ++aux;
01088
01089
01090
           for(auto jj=order_accuracy_ - 1; jj >=order_accuracy_ - dim_null_; jj--) {
            for(auto ii=0; ii<order_accuracy_ + 1; ++ii) {</pre>
01091
01092
               phi.data()[ii*order_accuracy_+jj] = mtk::kZero;
01093
01094
           }
01095
           for (auto jj = 0; jj < order_accuracy_ + 1; ++jj) {
   for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01096
01097
               phi.data()[(ii + order_accuracy_ - dim_null_ + jj*order_accuracy_)] =
    -prem_apps_[(dim_null_ - ii - 1 + jj*dim_null_)];
01098
01099
01100
             }
01101
01102
01103
           for(auto ii = 0; ii < order_accuracy_/2; ++ii) {</pre>
             for (auto jj = dim_null_ + 2; jj < order_accuracy_; ++jj) {
  auto swap = phi.data()[ii*order_accuracy_+jj];</pre>
01104
01105
               phi.data()[ii*order_accuracy_ + jj] =
   phi.data()[(order_accuracy_-ii)*order_accuracy_+jj];
01106
01107
01108
               phi.data()[(order_accuracy_-ii)*order_accuracy_+jj] = swap;
01109
           1
01110
01111
```

17.62 mtk div_1d.cc 313

```
01112
          #if MTK_DEBUG_LEVEL > 0
01113
          std::cout << "Constructed PHI matrix for CBS Algorithm: " << std::endl;</pre>
01114
          std::cout << phi << std::endl;
01115
01116
01118
01119
          mtk::Real *lamed{}; // Used to build big lambda.
01120
01121
01122
            lamed = new mtk::Real[dim_null_];
          } catch (std::bad_alloc &memory_allocation_exception) {
01123
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01124
01125
              std::endl;
01126
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01127
01128
          memset(lamed, mtk::kZero, sizeof(lamed[0])*dim_null_);
01129
01130
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
            lamed[ii] = hh[ii + order_accuracy_ + 1];
01131
01132
01133
01134
          #if MTK_DEBUG_LEVEL > 0
01135
          std::cout << "lamed =" << std::endl;
01136
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01137
            std::cout << std::setw(12) << lamed[ii] << std::endl;
01138
01139
          std::cout << std::endl;
01140
          #endif
01141
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01142
            mtk::Real temp = mtk::kZero;
01143
             for(auto jj = 0; jj < dim_null_; ++jj) {</pre>
01144
01145
               temp = temp +
                lamed[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01146
01147
01148
            hh[ii] = hh[ii] - temp;
01149
01150
          #if MTK_DEBUG_LEVEL > 0
std::cout << "big_lambda =" << std::endl;</pre>
01151
01152
01153
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01154
            std::cout << std::setw(12) << hh[ii] << std::endl;
01155
01156
          std::cout << std::endl;
01157
          #endif
01158
01159
          int copy_result{};
01160
01161
          mtk::Real normerr_; // Norm of the error for the solution on each row.
01162
01164
01165
          for(auto row_= 0; row_ < order_accuracy_ + 1; ++row_) {</pre>
            normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
01166
      data(),
01167
                                                                    order_accuracy_ + 1,
01168
                                                                    order_accuracy_,
01169
                                                                    order_accuracy_,
01170
                                                                    weights_cbs_,
01171
01172
                                                                    row_,
01173
                                                                    mimetic_threshold_,
01174
                                                                    copy_result);
01175
            mtk::Real aux{normerr_/norm_};
01176
01177
             #if MTK_DEBUG_LEVEL>0
             std::cout << "Relative norm: " << aux << " " << std::endl;
01178
01179
            std::cout << std::endl;
01180
            #endif
01181
01182
             if (aux < minnorm_) {</pre>
01183
             minnorm_ = aux;
01184
              minrow_= row_;
01185
01186
          }
01187
          #if MTK_DEBUG_LEVEL > 0
01188
          std::cout << "weights_CBSA + lambda (after brute force search):" <<
01189
01190
            std::endl:
          for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01191
            std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01192
01193
```

```
01194
          std::cout << std::endl;</pre>
01195
          #endif
01196
01198
01199
          // After we know which row yields the smallest relative norm that row is
01200
          // chosen to be the objective function and the result of the optimizer is
01201
          // chosen to be the new weights_.
01202
01203
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "Minimum Relative Norm " << minnorm_ << " found at row " <<
01204
            minrow_ + 1 << std::endl;
01205
01206
          std::cout << std::endl;
01207
          #endif
01208
01209
          copy_result = 1;
01210
          normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
      data().
01211
                                                                  order_accuracy_ + 1,
01212
                                                                  order_accuracy_,
01213
                                                                  order accuracy ,
01214
                                                                  hh,
01215
                                                                  weights_cbs_,
01216
                                                                  minrow,
01217
                                                                  mimetic_threshold_,
01218
                                                                  copy_result);
          mtk::Real aux_{normerr_/norm_};
01219
          #if MTK_DEBUG_LEVEL > 0
01220
          std::cout << "Relative norm: " << aux_ << std::endl;
01221
          std::cout << std::endl;</pre>
01222
01223
          #endif
01224
01225
         delete [] lamed;
01226
         lamed = nullptr;
01227
01228
01229
        delete [] hh;
01230
        hh = nullptr;
01231
01232
        return true;
01233 }
01234
01235 bool mtk::Div1D::ComputeStencilBoundaryGrid(void) {
01236
01237
        #if MTK DEBUG LEVEL > 0
        std::cout << "weights_CBSA + lambda =" << std::endl;</pre>
01238
01239
        for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01240
          std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01241
01242
        std::cout << std::endl;
01243
        #endif
01244
01246
01247
        mtk::Real *lambda{}; // Collection of bottom values from weights_.
01248
01249
01250
          lambda = new mtk::Real[dim_null_];
01251
        } catch (std::bad_alloc &memory_allocation_exception) {
01252
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01253
            std::endl;
01254
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01255
01256
        memset(lambda, mtk::kZero, sizeof(lambda[0])*dim_null_);
01257
01258
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01259
          lambda[ii] = weights_cbs_[order_accuracy_ + ii];
01260
01261
01262
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "lambda =" << std::endl;
01263
        for (auto ii = 0; ii < dim_null_; ++ii) {
   std::cout << std::setw(12) << lambda[ii] << std::endl;</pre>
01264
01265
01266
01267
        std::cout << std::endl;
01268
        #endif
01269
01271
01272
        mtk::Real *alpha{}; // Collection of alpha values.
01273
01274
        try {
01275
          alpha = new mtk::Real[dim null ];
01276
        } catch (std::bad_alloc &memory_allocation_exception) {
```

17.62 mtk div 1d.cc 315

```
01277
           std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01278
             std::endl;
01279
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01280
01281
        memset(alpha, mtk::kZero, sizeof(alpha[0])*dim_null_);
01282
01283
         for (auto ii = 0; ii < dim_null_; ++ii)</pre>
01284
         alpha[ii] = lambda[ii]/weights_cbs_[ii] ;
01285
01286
         #if MTK_DEBUG_LEVEL > 0
01287
        std::cout << "alpha =" << std::endl;
01288
01289
         for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01290
          std::cout << std::setw(12) << alpha[ii] << std::endl;</pre>
01291
01292
        std::cout << std::endl;
01293
        #endif
01294
01296
01297
        trv {
          mim_bndy_ = new mtk::Real[num_bndy_coeffs_*dim_null_];
01298
01299
        } catch (std::bad_alloc &memory_allocation_exception) {
01300
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01301
            std::endl;
01302
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01303
01304
        memset(mim_bndy_, mtk::kZero, sizeof(mim_bndy_[0])*num_bndy_coeffs_*dim_null_);
01305
01306
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01307
          for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01308
            mim_bndy_[ii*dim_null_ + jj] =
               prem_apps_[ii*dim_null_ + jj] +
01309
01310
               alpha[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01311
          }
        }
01312
01313
        #if MTK_DEBUG_LEVEL >0
std::cout << "Collection of mimetic approximations:" << std::endl;</pre>
01314
01315
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01316
          for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01317
01318
            std::cout << std::setw(13) << mim_bndy_[ii*dim_null_ + jj];</pre>
01319
01320
          std::cout << std::endl;
01321
01322
        std::cout << std::endl;
01323
        #endif
01324
01325
        delete[] lambda;
01326
        lambda = nullptr;
01327
01328
        delete[] alpha;
01329
        alpha = nullptr;
01330
01331
        return true;
01332 }
01333
01334 bool mtk::Div1D::AssembleOperator(void) {
01335
        // The output array will have this form:
01336
01337
        // 1. The first entry of the array will contain the used order order_accuracy_.
        // 2. The second entry of the array will contain the collection of
01338
01339
        // approximating coefficients for the interior of the grid.
01340
        // 3. IF order_accuracy_ > 2, then the third entry will contain a collection of weights.
        // 4. IF order_accuracy_ > 2, the next \dim_null_ entries will contain the collections of // approximating coefficients for the west boundary of the grid.
01341
01342
01343
01344
        if (order_accuracy_ > mtk::kDefaultOrderAccuracy) {
01345
          divergence_length_ =
01346
            1 + order_accuracy_ + order_accuracy_ + dim_null_*num_bndy_coeffs_;
01347
        } else {
01348
          divergence_length_ = 1 + order_accuracy_;
01349
01350
         #if MTK_DEBUG_LEVEL > 0
01351
        std::cout << "divergence_length_ = " << divergence_length_ << std::endl;</pre>
01352
01353
        #endif
01354
01355
01356
          divergence_ = new double[divergence_length_];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<</pre>
01357
01358
```

```
01359
01360
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01361
01362
        memset(divergence_, mtk::kZero, sizeof(divergence_[0])*divergence_length_);
01365
        divergence_[0] = order_accuracy_;
01367
01369
01370
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01371
        divergence_[ii + 1] = coeffs_interior_[ii];
01372
01373
01375
01376
        if (order_accuracy_ > 2) {
01377
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01378
            divergence_[(1 + order_accuracy_) + ii] = weights_cbs_[ii];
01379
       }
01380
01381
01384
01385
       if (order_accuracy_ > 2) {
        auto offset = (2*order_accuracy_ + 1);
int mm{};
01386
01387
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01388
            for (auto jj = 0; jj < num_bndy_coeffs_; ++jj) {
01389
              divergence_[offset + (mm)] = mim_bndy_[jj*dim_null_ + ii];
01390
01391
               ++mm;
01392
            }
01393
         }
01394
01395
        #if MTK_DEBUG_LEVEL > 0
std::cout << "1D " << order_accuracy_ << "-order div built!" << std::endl;</pre>
01396
01397
01398
        std::cout << std::endl;
01399
        #endif
01400
01401
        return true;
01402 }
```

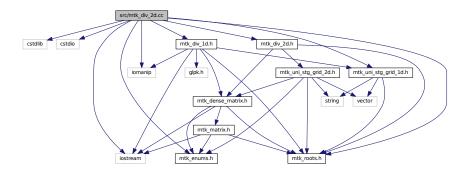
17.63 src/mtk_div_2d.cc File Reference

Implements the class Div2D.

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_uni_stg_grid_ld.h"
#include "mtk_div_ld.h"
#include "mtk_div_2d.h"
```

17.64 mtk_div_2d.cc 317

Include dependency graph for mtk_div_2d.cc:



17.63.1 Detailed Description

This class implements a 2D divergence matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_div_2d.cc.

17.64 mtk div 2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
```

```
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "mtk_roots.h"
00064 #include "mtk_enums.h"
00065 #include "mtk_uni_stg_grid_1d.h"
00066 #include "mtk_div_1d.h"
00067 #include "mtk_div_2d.h"
00068
00069 mtk::Div2D::Div2D():
00070 order_accuracy_(),
00071 mimetic_threshold_() {}
00072
00073 mtk::Div2D::Div2D(const Div2D &div):
00074 order_accuracy_(div.order_accuracy_),
00075
       mimetic_threshold_(div.mimetic_threshold_) {}
00076
00077 mtk::Div2D::~Div2D() {}
00078
00079 bool mtk::Div2D::ConstructDiv2D(const
     mtk::UniStgGrid2D &grid,
08000
                                       int order_accuracy,
00081
                                       mtk::Real mimetic_threshold) {
00082
        int num_cells_x = grid.num_cells_x();
int num_cells_y = grid.num_cells_y();
00083
00084
00085
        int mx = num\_cells\_x + 2; // Dx vertical dimension.
00086
        int nx = num_cells_x + 1; // Dx horizontal dimension. int my = num_cells_y + 2; // Dy vertical dimension. int ny = num_cells_y + 1; // Dy horizontal dimension.
00087
00088
00089
00090
00091
        mtk::Div1D div;
00092
00093
        bool info = div.ConstructDiv1D(order_accuracy, mimetic_threshold);
00094
00095
        if (!info) {
00096
         std::cerr << "Mimetic div could not be built." << std::endl;
00097
         return info;
00098
00099
00100
        auto west = grid.west_bndy();
00101
       auto east = grid.east_bndy();
        auto south = grid.south_bndy();
00102
        auto north = grid.east_bndy();
00103
00104
00105
        mtk::UniStgGrid1D grid_x(west, east, num_cells_x);
00106
        mtk::UniStgGrid1D grid_y(south, north, num_cells_y);
00107
00108
        mtk::DenseMatrix dx(div.ReturnAsDenseMatrix(grid_x));
        mtk::DenseMatrix dy(div.ReturnAsDenseMatrix(grid_y));
00109
00110
00111
        bool padded{true};
00112
        bool transpose(false);
00113
00114
        mtk::DenseMatrix ix(num_cells_x, padded, transpose);
00115
        mtk::DenseMatrix iv(num cells v, padded, transpose);
00116
00117
        mtk::DenseMatrix dxy(mtk::DenseMatrix::Kron(iy, dx));
00118
        mtk::DenseMatrix dyx(mtk::DenseMatrix::Kron(dy, ix));
00119
        #if MTK_DEBUG_LEVEL > 0
00120
        std::cout << "Dx: " << mx << " by " << nx << std::endl;
00121
        00122
00123
```

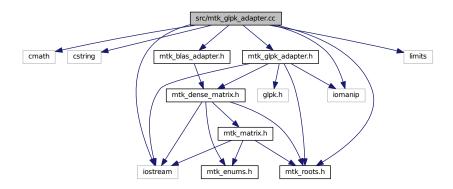
```
00124
         std::cout << "Ix : " << num_cells_x<< " by " << nx << std::endl;
00125
        std::cout << "Div 2D: " << mx*num_cells_y + my*num_cells_x << " by " <<
          nx*ny <<std::endl;</pre>
00126
00127
00128
00129
        mtk::DenseMatrix d2d(mx*my, nx*num_cells_y + ny*num_cells_x);
00130
00131
        for (auto ii = 0; ii < mx*my; ii++) {</pre>
         for (auto jj = 0; jj < nx*num_cells_y; jj++) {
   d2d.SetValue(ii, jj, dxy.GetValue(ii,jj));</pre>
00132
00133
00134
00135
          for(auto kk=0; kk<ny*num_cells_x; kk++) {</pre>
00136
             d2d.SetValue(ii, kk + nx*num_cells_y, dyx.GetValue(ii, kk));
00137
00138
00139
00140
        divergence_ = d2d;
00141
00142
        return info;
00143 }
00144
00145 mtk::DenseMatrix mtk::Div2D::ReturnAsDenseMatrix() const {
00146
00147
         return divergence :
00148 }
```

17.65 src/mtk_glpk_adapter.cc File Reference

Adapter class for the GLPK API.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include "mtk_roots.h"
#include "mtk_blas_adapter.h"
#include "mtk_glpk_adapter.h"
```

Include dependency graph for mtk_glpk_adapter.cc:



17.65.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

See also

```
http://www.gnu.org/software/glpk/
```

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_glpk_adapter.cc.

17.66 mtk_glpk_adapter.cc

```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00025
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed, unless these modifications are made through the project's GitHub
00029 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00030 should be developed and included in any deliverable.
00031
00032 2. Redistributions of source code must be done through direct
00033 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00034
00035 3. Redistributions in binary form must reproduce the above copyright notice,
00036 this list of conditions and the following disclaimer in the documentation and/or
00037 other materials provided with the distribution.
00038
00039 4. Usage of the binary form on proprietary applications shall require explicit
00040 prior written permission from the the copyright holders, and due credit should
00041 be given to the copyright holders.
00042
00043 5. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00046
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00064
00065 #include <cmath>
00066 #include <cstring>
00067
00068 #include <iostream>
00069 #include <iomanip>
00070 #include <limits>
00071
00072 #include "mtk roots.h"
```

```
00073 #include "mtk_blas_adapter.h"
00074 #include "mtk_glpk_adapter.h"
00075
00076 mtk::Real mtk::GLPKAdapter::SolveSimplexAndCompare(
     mtk::Real *A,
00077
00078
                                                            int ncols,
00079
                                                             int kk,
00080
                                                            mtk::Real *hh,
                                                            mtk::Real *qq,
00082
                                                            int robjective,
00083
                                                            mtk::Real mimetic_threshold,
00084
                                                            int copy) {
00085
00086
        #if MTK_DEBUG_LEVEL > 0
00087
        char mps_file_name[18]; // File name for the MPS files.
00088
        #endif
00089
        char rname[5];
                                  // Row name.
00090
        char cname[5];
                                 // Column name.
00091
00092
        glp_prob *lp; // Linear programming problem.
00093
        int *ia; // Array for the problem.
int *ja; // Array for the problem.
00094
00095
00096
        int problem_size; // Size of the problem.
00097
                           // Number of rows.
00098
        int lp_nrows;
                           // Number of columns.
00099
        int lp_ncols;
                           // Size of the matrix.
00100
        int matsize;
        int glp_index{1}; // Index of the objective function.
00101
00102
                           // Iterator.
        int ii;
00103
                           // Iterator.
        int jj;
00104
                                    \ensuremath{//} Array for the problem.
00105
        mtk::Real *ar;
        mtk::Real *objective;
                                   \ensuremath{//} Array containing the objective function.
00106
                                   // Array containing the rhs.
        mtk::Real *rhs;
00107
00108
        mtk::Real *err;
                                    // Array of errors.
00109
                                    // Norm-2 of the error.
00110
        mtk::Real x1;
00111
00112
        #if MTK_DEBUG_LEVEL > 0
                                   // Value of the objective function.
00113
        mtk::Real obj_value;
00114
        #endif
00115
00116
        lp\_nrows = kk;
00117
        lp_ncols = kk;
00118
00119
        matsize = lp_nrows*lp_ncols;
00120
00122
00124
        problem_size = lp_nrows*lp_ncols + 1;
00125
00126
00127
          ia = new int[problem_size];
00128
        } catch (std::bad_alloc &memory_allocation_exception) {
00129
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00130
            std::endl;
00131
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00132
00133
        memset(ia, 0, sizeof(ia[0])*problem_size);
00134
00135
00136
          ja = new int[problem_size];
00137
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00138
00139
            std::endl;
00140
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00141
        memset(ja, 0, sizeof(ja[0])*problem_size);
00142
00143
00144
00145
          ar = new mtk::Real[problem_size];
        } catch (std::bad_alloc &memory_allocation_exception) {
00146
00147
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00148
            std::endl;
00149
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00150
00151
        memset(ar, mtk::kZero, sizeof(ar[0])*problem_size);
00152
00153
00154
          objective = new mtk::Real[lp_ncols + 1];
```

```
} catch (std::bad_alloc &memory_allocation_exception) {
00156
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00157
           std::endl;
00158
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00159
00160
       memset(objective, mtk::kZero, sizeof(objective[0])*(lp_ncols + 1));
00161
00162
00163
         rhs = new mtk::Real[lp_nrows + 1];
        } catch (std::bad_alloc &memory_allocation_exception) {
00164
00165
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00166
           std::endl;
00167
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00168
00169
        memset(rhs, mtk::kZero, sizeof(rhs[0])*(lp_nrows + 1));
00170
00171
        trv {
         err = new mtk::Real[lp_nrows];
00172
00173
        } catch (std::bad_alloc &memory_allocation_exception) {
00174
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00175
            std::endl;
00176
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00177
00178
       memset(err, mtk::kZero, sizeof(err[0])*(lp_nrows));
00179
00180
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Problem size: " << problem_size << std::endl;
00181
        std::cout << "lp_nrows = " << lp_nrows << std::endl;
00182
        std::cout << "lp_ncols = " << lp_ncols << std::endl;
00183
00184
        std::cout << std::endl;
00185
        #endif
00186
00187
        lp = glp_create_prob();
00188
        glp_set_prob_name (lp, "mtk::GLPKAdapter::Simplex");
00189
00190
00191
        glp_set_obj_dir (lp, GLP_MIN);
00192
00194
00195
        glp_add_rows(lp, lp_nrows);
00196
00197
        for (ii = 1; ii <= lp_nrows; ++ii) {</pre>
          sprintf(rname, "R%02d",ii);
00198
00199
          glp_set_row_name(lp, ii, rname);
00200
00201
00202
        glp_add_cols(lp, lp_ncols);
00203
00204
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00205
          sprintf(cname, "Q%02d",ii);
00206
         glp_set_col_name (lp, ii, cname);
00207
00208
00210
00211
        #if MTK_DEBUG_LEVEL>0
00212
        std::cout << "Using row " << robjective + 1 << " as objective." << std::endl;
00213
00214
        for (jj = 0; jj < kk; ++jj) {
00215
         objective[glp_index] = A[jj + robjective * ncols];
00216
         glp_index++;
00217
00218
        #if MTK_DEBUG_LEVEL >0
00219
        std::cout << std::endl;</pre>
00220
        #endif
00221
00223
        glp\_index = 1;
00225
        rhs[0] = mtk::kZero;
00226
        for (ii = 0; ii <= lp_nrows; ++ii) {</pre>
         if (ii != robjective) {
00227
00228
           rhs[glp_index] = hh[ii];
00229
            glp_set_row_bnds(lp, glp_index, GLP_UP, 0.0, rhs[glp_index]);
00230
            glp_index++;
00231
         }
00232
00233
        #if MTK DEBUG LEVEL > 0
00234
00235
        std::cout << "rhs =" << std::endl;
        for (auto ii = 0; ii < lp_nrows; ++ii) {</pre>
00236
00237
         std::cout << std::setw(15) << rhs[ii] << std::endl;
00238
```

```
00239
        std::cout << std::endl;
00240
00241
00243
00244
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00245
         glp_set_obj_coef (lp, ii, objective[ii]);
00246
00247
00249
00250
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00251
         glp_set_col_bnds (lp, ii, GLP_LO, mimetic_threshold, 0.0);
00252
00253
00255
00256
        glp\_index = 1;
00257
        for (ii = 0; ii <= kk; ++ii) {
00258
          for (jj = 0; jj < kk; ++jj) {</pre>
            if (ii != robjective) {
00259
00260
              ar[glp_index] = A[jj + ii * ncols];
00261
               glp_index++;
00262
            }
00263
          }
00264
        }
00265
00266
        qlp\_index = 0;
00267
        for (ii = 1; ii < problem_size; ++ii) {
  if (((ii - 1) % lp_ncols) == 0) {</pre>
00268
00269
00270
            glp_index++;
00271
          ia[ii] = glp_index;
ja[ii] = (ii - 1) % lp_ncols + 1;
00272
00273
00274
00275
00276
        glp_load_matrix (lp, matsize, ia, ja, ar);
00277
        #if MTK_DEBUG_LEVEL > 0
sprintf(mps_file_name, "LP_MPS_row_%02d.mps", robjective);
00278
00279
        glp_write_mps(lp, GLP_MPS_FILE, nullptr, mps_file_name);
00280
00281
00282
00284
00285
        glp_simplex (lp, nullptr);
00286
00287
        // Check status of the solution.
00288
00289
        if (glp_get_status(lp) == GLP_OPT) {
00290
00291
          for(ii = 1; ii <= lp_ncols; ++ii) {</pre>
00292
           err[ii - 1] = qq[ii - 1] - glp_get_col_prim(lp,ii);
00293
00294
00295
          #if MTK_DEBUG_LEVEL > 0
00296
          obj_value = glp_get_obj_val (lp);
00297
          std::cout << std::setw(12) << "CBS" << std::setw(12) << "CRS" << std::endl;
00298
          for (ii = 0; ii < lp_ncols; ++ii) {</pre>
           std::cout << "q_" << ii + 1 << " = " << std::setw(12) <<
00299
00300
               glp_get_col_prim(lp,ii + 1) << std::setw(12) << qq[ii] << std::endl;</pre>
00301
00302
          std::cout << "Objective function value (row " << robjective + 1 << ") = " <<
00303
            obj_value << std::endl;
00304
          #endif
00305
00306
          if (copy) {
           for (ii = 0; ii < lp_ncols; ++ii) {</pre>
00307
00308
              qq[ii] = glp_get_col_prim(lp,ii + 1);
00309
00310
            // Preserve the bottom values of qq.
00311
00312
00313
          x1 = mtk::BLASAdapter::RealNRM2(err,lp_ncols);
00314
00315
        } else {
00316
          x1 = std::numeric limits<mtk::Real>::infinity();
00317
00318
00319
        glp delete prob (lp);
00320
        glp_free_env ();
00321
00322
        delete [] ia;
00323
        delete [] ja;
```

```
00324 delete [] ar;

00325 delete [] objective;

00326 delete [] rhs;

00327 delete [] err;

00328

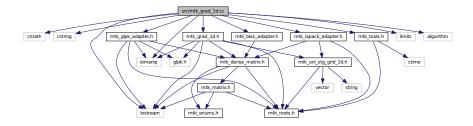
00329 return x1;

00330 }
```

17.67 src/mtk_grad_1d.cc File Reference

Implements the class Grad1D.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_grad_ld.h"
Include dependency graph for mtk_grad_ld.cc:
```



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Functions

• std::ostream & mtk::operator<< (std::ostream &stream, mtk::Grad1D &in)

17.67.1 Detailed Description

This class implements a 1D gradient matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

17.68 mtk_grad_1d.cc 325

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Overload ostream operator as in mtk::Lap1D.

Todo Implement creation of ■ w. mtk::BLASAdapter.

Definition in file mtk_grad_1d.cc.

17.68 mtk_grad_1d.cc

```
00001
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00021
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed, unless these modifications are made through the project's GitHub
00025 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00026 should be developed and included in any deliverable.
00027
00028 2. Redistributions of source code must be done through direct
00029 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00030
00031 3. Redistributions in binary form must reproduce the above copyright notice,
00032 this list of conditions and the following disclaimer in the documentation and/or
00033 other materials provided with the distribution.
00034
00035 4. Usage of the binary form on proprietary applications shall require explicit
00036 prior written permission from the the copyright holders, and due credit should
00037 be given to the copyright holders.
00038
00039 5. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00061 #include <cmath>
00062 #include <cstring>
00063
00064 #include <iostream>
00065 #include <iomanip>
00066 #include <limits>
00067 #include <algorithm>
00068
00069 #include "mtk tools.h"
00070
00071 #include "mtk_blas_adapter.h"
00072 #include "mtk_lapack_adapter.h"
00073 #include "mtk_glpk_adapter.h'
00074
```

```
00075 #include "mtk_grad_1d.h"
00076
00077 namespace mtk {
00078
00079 std::ostream& operator <<(std::ostream &stream, mtk::Grad1D &in) {
08000
00082
00083
        stream << "gradient_[0] = " << std::setw(9) << in.gradient_[0] << std::endl;</pre>
00084
        stream << "gradient_[1:" << in.order_accuracy_ << "] = ";
00087
        for (auto ii = 1; ii <= in.order_accuracy_; ++ii)</pre>
00088
00089
         stream << std::setw(9) << in.gradient_[ii] << " ";
00090
00091
        stream << std::endl;
00092
00094
00095
        stream << "gradient_[" << in.order_accuracy_ + 1 << ":" <<
          2*in.order_accuracy_ << "] = ";
00096
       for (auto ii = in.order_accuracy_ + 1; ii <= 2*in.</pre>
00097
      order_accuracy_; ++ii) {
00098
         stream << std::setw(9) << in.gradient_[ii] << " ";
00099
00100
        stream << std::endl;
00101
00103
        int offset{2*in.order_accuracy_ + 1};
00104
00105
        int mm {};
00106
        stream << "gradient_[" << offset + mm << ":" <<
00107
          offset + mm + in.num_bndy_coeffs_ - 1 << "] = ";
00108
00109
        if (in.order_accuracy_ > mtk::kDefaultOrderAccuracy) {
   for (auto ii = 0; ii < in.num_bndy_approxs_; ++ii)</pre>
00110
00111
            for (auto jj = 0; jj < in.num_bndy_coeffs_; jj++) {
  auto value = in.gradient_[offset + (mm)];</pre>
00112
00113
00114
               stream << std::setw(9) << value << " ";
00115
               mm++;
            }
00116
00117
00118
        } else {
          stream << std::setw(9) << in.gradient_[offset + 0] << ' ';</pre>
00119
           stream << std::setw(9) << in.gradient_[offset + 1] << ' ';
00120
           stream << std::setw(9) << in.gradient_[offset + 2] << ' ';</pre>
00121
00122
00123
        stream << std::endl;
00124
00125
        return stream;
00126 }
00127 }
00128
00129 mtk::Grad1D::Grad1D():
00130 order_accuracy_(mtk::kDefaultOrderAccuracy),
        dim_null_(),
00131
00132
       num_bndy_approxs_(),
00133
        num_bndy_coeffs_(),
       gradient_length_(),
00134
00135
        minrow_(),
00136
       row_(),
00137
        coeffs_interior_(),
00138
        prem_apps_(),
00139
        weights_crs_(),
00140
        weights_cbs_(),
00141
        mim_bndy_(),
00142
        gradient_(),
00143
        mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00144
00145 mtk::Grad1D::Grad1D(const Grad1D &grad):
00146 order_accuracy_(grad.order_accuracy_),
00147
        dim_null_(grad.dim_null_),
00148
        num_bndy_approxs_(grad.num_bndy_approxs_),
        num_bndy_coeffs_(grad.num_bndy_coeffs_),
gradient_length_(grad.gradient_length_),
00149
00150
00151
        minrow_(grad.minrow_),
00152
        row (grad.row ),
00153
        coeffs_interior_(grad.coeffs_interior_),
00154
        prem_apps_(grad.prem_apps_),
00155
        weights_crs_(grad.weights_crs_),
00156
        weights_cbs_(grad.weights_cbs_),
        mim_bndy_(grad.mim_bndy_),
00157
00158
        gradient_(grad.gradient_),
```

17.68 mtk_grad_1d.cc 327

```
00159
        mimetic_threshold_(grad.mimetic_threshold_) {}
00160
00161 mtk::Grad1D::~Grad1D() {
00162
00163
        delete[] coeffs_interior_;
00164
        coeffs_interior_ = nullptr;
00165
00166
        delete[] prem_apps_;
00167
        prem_apps_ = nullptr;
00168
00169
        delete[] weights_crs_;
00170
        weights_crs_ = nullptr;
00171
00172
        delete[] weights_cbs_;
00173
        weights_cbs_ = nullptr;
00174
00175
        delete[] mim_bndy_;
        mim_bndy_ = nullptr;
00176
00177
00178
        delete[] gradient_;
00179
        gradient_ = nullptr;
00180 }
00181
00182 bool mtk::Grad1D::ConstructGrad1D(int order_accuracy,
      Real mimetic_threshold) {
00183
00184
        #if MTK DEBUG LEVEL > 0
00185
        mtk::Tools::Prevent(order_accuracy < 2, __FILE__,</pre>
                                                               __LINE__,
                                                                          __func__);
        mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(mimetic_threshold <= mtk::kZero,</pre>
00186
00187
00188
                                _FILE__, __LINE__, __func__);
00189
        if (order_accuracy >= mtk::kCriticalOrderAccuracyGrad) {
00190
         std::cout << "WARNING: Numerical accuracy is high." << std::endl;</pre>
0.0191
        }
00192
00193
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;
std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;</pre>
00194
00195
00196
        #endif
00197
00198
        order_accuracy_ = order_accuracy;
00199
        mimetic_threshold_ = mimetic_threshold;
00200
00202
00203
        bool abort_construction = ComputeStencilInteriorGrid();
00204
00205
        \#if MTK_DEBUG_LEVEL > 0
00206
        if (!abort_construction) {
00207
          std::cerr << "Could NOT complete stage 1." << std::endl;</pre>
00208
          std::cerr << "Exiting..." << std::endl;</pre>
00209
          return false;
00210
00211
        #endif
00212
00213
         // At this point, we already have the values for the interior stencil stored
00214
        // in the coeffs_interior_ array.
00215
00216
        dim_null_ = order_accuracy_/2 - 1;
00217
00218
        num_bndy_approxs_ = dim_null_ + 1;
00219
00220
        #ifdef MTK_PRECISION_DOUBLE
00221
        num\_bndy\_coeffs\_ = (int) (3.0*((mtk::Real) order\_accuracy\_)/2.0);
        #else
00222
00223
        num_bndy_coeffs_ = (int) (3.0f*((mtk::Real) order_accuracy_)/2.0f);
00224
         #endif
00225
00227
00228
        // For this we will follow recommendations given in:
00229
00230
        // http://icl.cs.utk.edu/lapack-forum/viewtopic.php?f=5&t=4506
00231
00232
        // We will compute the QR Factorization of the transpose, as in the
00233
        // following (MATLAB) pseudo-code:
00234
00235
        // [Q,R] = qr(V'); % Full QR as defined in
00236
        // % http://www.stanford.edu/class/ee263/notes/qr_matlab.pdf
00237
00238
        // null-space = Q(:, last (order_accuracy_/2 - 1) columns of Q);
00239
00240
         // However, given the nature of the Vandermonde matrices we've just
```

```
00241
        // computed, they all posses the same null-space. Therefore, we impose the
00242
        // convention of computing the null-space of the first Vandermonde matrix
00243
        // (west boundary).
00244
00245
        // In the case of the gradient, the first Vandermonde system has a unique
00246
        // solution for the case of second-order-accuracy. Ergo, the Vandermonde
00247
        // matrix used to assemble said system, will have an empty null-space.
00248
00249
        // Therefore, we only compute a rational basis for the case of order higher
00250
        // than second.
00251
00252
        if (dim_null_ > 0) {
00253
00254
          abort_construction = ComputeRationalBasisNullSpace();
00255
00256
          #if MTK_DEBUG_LEVEL > 0
00257
          if (!abort_construction) {
00258
            std::cerr << "Could NOT complete stage 2.1." << std::endl;
00259
            std::cerr << "Exiting..." << std::endl;
00260
            return false;
00261
00262
          #endif
00263
        }
00264
00266
00267
        abort_construction = ComputePreliminaryApproximations();
00268
00269
        #if MTK DEBUG LEVEL > 0
00270
        if (!abort_construction) {
00271
          std::cerr << "Could NOT complete stage 2.2." << std::endl;
          std::cerr << "Exiting..." << std::endl;
00272
00273
          return false;
00274
00275
        #endif
00276
00278
00279
        abort_construction = ComputeWeights();
00280
00281
        #if MTK DEBUG LEVEL > 0
00282
        if (!abort_construction) {
         std::cerr << "Could NOT complete stage 2.3." << std::endl;
std::cerr << "Exiting..." << std::endl;</pre>
00283
00284
00285
         return false;
00286
00287
        #endif
00288
00290
00291
        if (dim_null_ > 0) {
00292
00293
          abort_construction = ComputeStencilBoundaryGrid();
00294
00295
          #if MTK_DEBUG_LEVEL > 0
00296
          if (!abort_construction) {
00297
            std::cerr << "Could NOT complete stage 2.4." << std::endl;</pre>
            std::cerr << "Exiting..." << std::endl;
00298
00299
            return false;
00300
00301
          #endif
00302
00303
00305
00306
        // Once we have the following three collections of data:
        // (a) the coefficients for the interior,
00307
00308
             (b) the coefficients for the boundary (if it applies),
             (c) and the weights (if it applies),
00309
00310
        // we will store everything in the output array:
00311
00312
        abort_construction = AssembleOperator();
00313
00314
        #if MTK_DEBUG_LEVEL > 0
00315
        if (!abort_construction) {
         std::cerr << "Could NOT complete stage 3." << std::endl;
std::cerr << "Exiting..." << std::endl;</pre>
00316
00317
00318
          return false;
00319
00320
        #endif
00321
00322
        return true:
00323 }
00324
00325 int mtk::Grad1D::num bndv coeffs() const {
```

```
00326
00327
        return num_bndy_coeffs_;
00328 }
00329
00330 mtk::Real *mtk::Grad1D::coeffs_interior() const {
00331
00332
        return coeffs_interior_;
00333 }
00334
00335 mtk::Real *mtk::Grad1D::weights_crs() const {
00337
        return weights_crs_;
00338 }
00339
00340 mtk::Real *mtk::Grad1D::weights_cbs() const {
00341
00342
        return weights cbs ;
00343 }
00344
00345 mtk::DenseMatrix mtk::Grad1D::mim_bndy() const {
00346
00347
        mtk::DenseMatrix xx(dim null , 3*order accuracy /2);
00348
00349
       auto counter = 0;
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00350
          for(auto jj = 0; jj < 3*order_accuracy_/2; ++jj) {</pre>
00351
            xx.SetValue(ii,jj, gradient_[2*order_accuracy_ + 1 + counter]);
00352
00353
            counter++;
         }
00354
00355
00356
00357
        return xx;
00358 }
00359
00360 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix(
     mtk::Real west,
00361
                                                            mtk::Real east,
00362
                                                            int num_cells_x) const {
00363
        int nn{num_cells_x}; // Number of cells on the grid.
00364
00365
00366
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(east < west, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(nn < 3*order_accuracy_ - 2, __FILE__, __LINE__, __func__);</pre>
00367
00368
00369
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00370
00371
00372
        mtk::Real delta_x = (east - west)/((mtk::Real) num_cells_x);
00373
00374
        mtk::Real inv_delta_x{mtk::kOne/delta_x};
00375
        int gg_num_rows = nn + 1;
00376
00377
        int gg_num_cols = nn + 2;
00378
        int elements_per_row = num_bndy_coeffs_;
00379
        int num_extra_rows = order_accuracy_/2;
00380
00381
        // Output matrix featuring sizes for gradient operators.
00382
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00383
00385
00386
        auto ee_index = 0;
00387
        for (auto ii = 0; ii < num_extra_rows; ii++) {</pre>
          auto cc = 0;
00388
          for (auto jj = 0; jj < gg_num_cols; jj++) {</pre>
00389
00390
            if(cc >= elements_per_row) {
00391
              out.SetValue(ii, jj, mtk::kZero);
00392
            } else {
00393
              out.SetValue(ii, jj,
00394
                            gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00395
              cc++;
00396
            }
00397
          }
00398
        }
00399
00401
        for (auto ii = num_extra_rows; ii < gg_num_rows - num_extra_rows; ii++) {</pre>
00402
00403
          auto jj = ii - num_extra_rows + 1;
00404
          for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {</pre>
00405
            out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00406
00407
```

```
00408
00410
        ee_index = 0;
00411
00412
       for (auto ii = gg_num_rows - 1; ii >= gg_num_rows - num_extra_rows; ii--) {
00413
00414
          for (auto jj = gg_num_cols - 1; jj >= 0; jj--) {
00415
           if(cc >= elements_per_row) {
00416
             out.SetValue(ii,jj,mtk::kZero);
00417
            } else {
             out.SetValue(ii,jj,
00418
00419
                            -gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00420
00421
            }
00422
00423
        }
00424
00425
       return out;
00426 }
00427
00428 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix(
00429
        const UniStgGrid1D &grid) const {
00430
00431
        int nn{grid.num cells x()}; // Number of cells on the grid.
00432
00433
        #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(nn < 3*order_accuracy_ - 2, __FILE__, __LINE__, __func__);</pre>
00434
00435
00436
        #endif
00437
00438
        mtk::Real inv_delta_x{mtk::kOne/grid.delta_x()};
00439
00440
        int gg_num_rows = nn + 1;
00441
        int gg_num_cols = nn + 2;
        int elements_per_row = num_bndy_coeffs_;
00442
00443
        int num_extra_rows = order_accuracy_/2;
00444
00445
        // Output matrix featuring sizes for gradient operators.
00446
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00447
00449
00450
       auto ee_index = 0;
00451
        for (auto ii = 0; ii < num_extra_rows; ii++) {</pre>
         auto cc = 0;
00452
          for(auto jj = 0; jj < gg_num_cols; jj++) {</pre>
00453
00454
           if(cc >= elements_per_row) {
00455
              out.SetValue(ii, jj, mtk::kZero);
00456
            } else {
00457
              out.SetValue(ii,jj,
00458
                            gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00459
              cc++;
00460
            }
00461
          }
00462
       }
00463
00465
00466
        for (auto ii = num_extra_rows; ii < gg_num_rows - num_extra_rows; ii++) {</pre>
00467
         auto jj = ii - num_extra_rows + 1;
00468
          for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {</pre>
00469
            out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00470
          }
00471
       }
00472
00474
00475
        ee_index = 0;
00476
        for (auto ii = gg_num_rows - 1; ii >= gg_num_rows - num_extra_rows; ii--) {
00477
          auto cc = 0;
00478
          for (auto jj = gg_num_cols - 1; jj >= 0; jj--) {
00479
           if(cc >= elements_per_row) {
00480
             out.SetValue(ii,jj,mtk::kZero);
00481
            } else {
00482
              out.SetValue(ii,jj,
00483
                            -gradient [2*order accuracy + 1 + ee index++]*inv delta x);
00484
              cc++;
00485
            }
00486
00487
        }
00488
00489
        return out;
00490 }
00491
00492 mtk::DenseMatrix mtk::Grad1D::ReturnAsDimensionlessDenseMatrix
```

17.68 mtk_grad_1d.cc 331

```
00493
       int num_cells_x) const {
00494
00495
        int nn{num_cells_x}; // Number of cells on the grid.
00496
00497
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(nn < 3*order_accuracy_ - 2, __FILE__, __LINE__, __func__);</pre>
00498
00499
00500
00501
00502
        int gg_num_rows = nn + 1;
00503
        int gg_num_cols = nn + 2;
00504
        int elements_per_row = num_bndy_coeffs_;
00505
        int num_extra_rows = order_accuracy_/2;
00506
00507
        // Output matrix featuring sizes for gradient operators.
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00508
00509
00511
00512
        auto ee_index = 0;
        for (auto ii = 0; ii < num_extra_rows; ii++) {</pre>
00513
00514
          auto cc = 0;
00515
          for(auto jj = 0; jj < gg_num_cols; jj++) {</pre>
            if(cc >= elements_per_row) {
00516
00517
              out.SetValue(ii, jj, mtk::kZero);
00518
            } else {
              out.SetValue(ii, jj,
00519
00520
                            gradient_[2*order_accuracy_ + 1 + ee_index++]);
00521
              cc++:
00522
00523
          }
00524
        }
00525
00527
        for (auto ii = num_extra_rows; ii < gg_num_rows - num_extra_rows; ii++) {</pre>
00528
          auto jj = ii - num_extra_rows + 1;
00529
          for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {</pre>
00530
00531
            out.SetValue(ii, jj, coeffs_interior_[cc]);
00532
00533
00534
00536
00537
        ee_index = 0;
00538
        for (auto ii = gg_num_rows - 1; ii >= gg_num_rows - num_extra_rows; ii--) {
00539
         auto cc = 0;
00540
          for (auto jj = gg_num_cols - 1; jj >= 0; jj--) {
00541
           if(cc >= elements_per_row) {
00542
              out.SetValue(ii, jj, mtk::kZero);
00543
            } else {
00544
              out.SetValue(ii,jj,
00545
                             -gradient_[2*order_accuracy_ + 1 + ee_index++]);
00546
00547
00548
00549
00550
00551
        return out;
00552 }
00553
00554 bool mtk::Grad1D::ComputeStencilInteriorGrid() {
00557
00558
       mtk::Real* pp{}; // Spatial coordinates to create interior stencil.
00559
00560
00561
         pp = new mtk::Real[order_accuracy_];
        } catch (std::bad_alloc &memory_allocation_exception) {
00562
00563
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00564
            std::endl;
00565
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00566
00567
        memset(pp, mtk::kZero, sizeof(pp[0])*order_accuracy_);
00568
00569
        #ifdef MTK_PRECISION_DOUBLE
00570
        pp[0] = 1.0/2.0 - ((mtk::Real) order_accuracy_)/2.0;
00571
        #else
00572
        pp[0] = 1.0f/2.0f - ((mtk::Real) order_accuracy_)/2.0f;
00573
        #endif
00574
00575
        for (auto ii = 1; ii < order_accuracy_; ++ii) {
   pp[ii] = pp[ii - 1] + mtk::kOne;</pre>
00576
```

```
00577
00578
00579
         #if MTK_DEBUG_LEVEL > 0
00580
         std::cout << "pp =" << std::endl;
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00581
00582
          std::cout << std::setw(12) << pp[ii];
00583
00584
        std::cout << std::endl << std::endl;
00585
         #endif
00586
00588
00589
        bool transpose{false};
00590
00591
        mtk::DenseMatrix vander_matrix(pp,order_accuracy_,order_accuracy_,transpose);
00592
00593
        #if MTK_DEBUG_LEVEL > 0
00594
         std::cout << "vander_matrix = " << std::endl;</pre>
00595
         std::cout << vander_matrix << std::endl << std::endl;</pre>
00596
00597
00599
00600
00601
          coeffs_interior_ = new mtk::Real[order_accuracy_];
         } catch (std::bad_alloc &memory_allocation_exception) {
00602
00603
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00604
            std::endl;
00605
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00606
00607
        memset(coeffs_interior_, mtk::kZero, sizeof(coeffs_interior_[0])*order_accuracy_);
00608
00609
        coeffs_interior_[1] = mtk::kOne;
00610
        #if MTK_DEBUG_LEVEL > 0
std::cout << "oo =" << std::endl;</pre>
00611
00612
        for (auto ii = 0; ii < order_accuracy_; ++ii) {
   std::cout << std::setw(12) << coeffs_interior_[ii] << std::endl;</pre>
00613
00614
00615
00616
         std::cout << std::endl;
00617
         #endif
00618
00620
00621
        int info{mtk::LAPACKAdapter::SolveDenseSystem(vander_matrix,
00622
                                                            coeffs_interior_) };
00623
00624
        #if MTK_DEBUG_LEVEL > 0
00625
        if (!info) {
00626
           std::cout << "System solved! Interior stencil attained!" << std::endl;</pre>
00627
           std::cout << std::endl;</pre>
00628
00629
00630
           std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
           std::cerr << "Exiting..." << std::endl;
00631
00632
          return false;
00633
00634
         #endif
00635
00636
         #if MTK_DEBUG_LEVEL > 0
00637
         std::cout << "coeffs_interior_ =" << std::endl;</pre>
00638
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00639
          std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
00640
00641
        std::cout << std::endl << std::endl;</pre>
00642
        #endif
00643
00644
        delete [] pp;
00645
        pp = nullptr;
00646
00647
        return true;
00648 }
00649
00650 bool mtk::Grad1D::ComputeRationalBasisNullSpace(void) {
00651
00653
00654
        mtk::Real* gg{}; // Generator vector for the first Vandermonde matrix.
00655
00656
        trv {
          gg = new mtk::Real[num_bndy_coeffs_];
00657
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00658
00659
00660
             std::endl:
00661
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
```

```
00662
00663
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00664
        #ifdef MTK_PRECISION_DOUBLE
00665
00666
        gg[1] = 1.0/2.0;
00667
00668
        gg[1] = 1.0f/2.0f;
00669
00670
        for (auto ii = 2; ii < num_bndy_coeffs_; ++ii) {</pre>
00671
         gg[ii] = gg[ii - 1] + mtk::kOne;
00672
00673
00674
        #if MTK_DEBUG_LEVEL > 0
00675
        std::cout << "gg =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00676
00677
         std::cout << std::setw(12) << gg[ii];
00678
00679
        std::cout << std::endl << std::endl;
00680
        #endif
00681
00683
00684
        bool tran{true}; // Should I transpose the Vandermonde matrix.
00685
00686
        mtk::DenseMatrix aa west t(gg, num bndv coeffs , order accuracy + 1, tran);
00687
00688
        #if MTK DEBUG LEVEL > 0
        std::cout << "aa_west_t =" << std::endl;
00689
        std::cout << aa_west_t << std::endl;
00690
00691
        #endif
00692
00694
00695
        mtk::DenseMatrix qq_t(mtk::LAPACKAdapter::QRFactorDenseMatrix
      (aa_west_t));
00696
        #if MTK_DEBUG_LEVEL > 0
std::cout << "qq_t = " << std::endl;</pre>
00697
00698
00699
        std::cout << qq_t << std::endl;
00700
        #endif
00701
00703
00704
        int kk_num_rows{num_bndy_coeffs_};
00705
        int kk_num_cols{dim_null_};
00706
00707
        mtk::DenseMatrix kk(kk_num_rows, kk_num_cols);
00708
00709
        // In the case of the gradient, even though we must solve for a null-space
00710
        \ensuremath{//} of dimension 2, we must only extract ONE basis for the kernel.
00711
        // We perform this extraction here:
00712
00713
        int aux_{kk_num_rows - kk_num_cols};
00714
        for (auto ii = kk_num_rows - kk_num_cols; ii < kk_num_rows; ii++) {</pre>
00715
          aux_--;
00716
          for (auto jj = 0; jj < kk_num_rows; jj++) {</pre>
00717
            kk.data()[jj*kk_num_cols + (kk_num_rows - kk_num_cols - aux_ - 1)] =
00718
               qq_t.data()[ii*num_bndy_coeffs_ + jj];
00719
00720
00721
00722
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "kk =" << std::endl;
00723
        std::cout << kk << std::endl;
00724
        std::cout << "kk.num_rows() = " << kk.num_rows() << std::endl;
00725
        std::cout << "kk.num_cols() = " << kk.num_cols() << std::endl;
00726
00727
        std::cout << std::endl;
00728
        #endif
00729
00731
00732
        // Scale thus requesting that the last entries of the attained basis for the
00733
        // null-space, adopt the pattern we require.
00734
        // Essentially we will implement the following MATLAB pseudo-code:
00735
        // scalers = kk(num_bndy_approxs - (dim_null - 1):num_bndy_approxs,:)\B
00736
        // SK = kk*scalers
00737
        // where SK is the scaled null-space.
00738
00739
        // In this point, we almost have all the data we need correctly allocated
00740
        // in memory. We will create the matrix iden_, and elements we wish to scale in
00741
        // the kk array. Using the concept of the leading dimension, we could just
        // use kk, with the correct leading dimension and that is it. BUT I DO NOT // GET how does it work. So I will just create a matrix with the content of
00742
00743
00744
        \ensuremath{//} this array that we need, solve for the scalers and then scale the
00745
        // whole kk:
```

```
00746
00747
        // We will then create memory for that sub-matrix of kk (subk).
00748
        mtk::DenseMatrix subk(dim_null_, dim_null_);
00749
00750
00751
        auto zz = 0:
00752
        for (auto ii = order_accuracy_ + 1; ii < num_bndy_coeffs_; ii++) {</pre>
00753
         for (auto jj = 0; jj < dim_null_; jj++) {</pre>
00754
            subk.data()[zz*(dim_null_) + jj] = kk.data()[ii*(dim_null_) + jj];
00755
00756
          zz++;
00757
00758
00759
        #if MTK_DEBUG_LEVEL > 0
00760
        std::cout << "subk =" << std::endl;
00761
        std::cout << subk << std::endl;
00762
        #endif
00763
00764
        subk.Transpose();
00765
00766
        #if MTK_DEBUG_LEVEL > 0
00767
        std::cout << "subk_t =" << std::endl;
00768
        std::cout << subk << std::endl;
00769
        #endif
00770
00771
        bool padded{false};
00772
        tran = false;
00773
00774
        mtk::DenseMatrix iden(dim_null_, padded, tran);
00775
00776
        #if MTK_DEBUG_LEVEL > 0
std::cout << "iden =" << std::endl;</pre>
00777
00778
        std::cout << iden << std::endl;
00779
        #endif
00780
00781
        // Solve the system to compute the scalers.
00782
        // An example of the system to solve, for k = 8, is:
00783
        11
       // subk*scalers = iden or
00784
00785
       11
        // | 0.386018 -0.0339244 -0.129478 | | 1 0 0 | 
// | -0.119774 0.0199423 0.0558632 |*scalers = | 0 1 0 |
                                                              | 1 0 0 |
00786
00787
        // | 0.0155708 -0.00349546 -0.00853182 |
00788
00789
        11
        // Notice this is a nrhs = 3 system.
00790
00791
        // Noteworthy: we do NOT ACTUALLY ALLOCATE space for the scalers... they
00792
        \ensuremath{//} will be stored in the created identity matrix.
00793
        // Let us first transpose subk (because of LAPACK):
00794
00795
        int info{mtk::LAPACKAdapter::SolveDenseSystem(subk, iden)};
00796
00797
        #if MTK_DEBUG_LEVEL > 0
00798
        if (!info) {
00799
         std::cout << "System successfully solved!" <<
00800
00801
00802
        std::cerr << "Something went wrong solving system! info = " << info <<
00803
         std::cerr << "Exiting..." << std::endl;
00804
00805
         return false;
00806
00807
        std::cout << std::endl;
00808
        #endif
00809
00810
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Computed scalers:" << std::endl;</pre>
00811
        std::cout << iden << std::endl;
00812
00813
        #endif
00814
00815
        // Multiply the two matrices to attain a scaled basis for null-space.
00816
00817
        rat basis null space = mtk::BLASAdapter::RealDenseMM(kk, iden);
00818
00819
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Rational basis for the null-space:" << std::endl;
00820
00821
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00822
00823
00824
        // At this point, we have a rational basis for the null-space, with the
00825
        // pattern we need! :)
00826
```

```
00827
        delete [] gg;
00828
        gg = nullptr;
00829
00830
        return true;
00831 }
00832
00833 bool mtk::Grad1D::ComputePreliminaryApproximations() {
00834
00836
00837
        mtk::Real *gg{}; // Generator vector for the first approximation.
00838
00839
00840
          gg = new mtk::Real[num_bndy_coeffs_];
        } catch (std::bad_alloc &memory_allocation_exception) {
00841
00842
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00843
            std::endl;
00844
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00845
00846
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00847
00848
        #ifdef MTK_PRECISION_DOUBLE
00849
        qq[1] = 1.0/2.0;
00850
         #else
00851
        qq[1] = 1.0f/2.0f;
00852
         #endif
         for (auto ii = 2; ii < num_bndy_coeffs_; ++ii) {</pre>
00853
          gg[ii] = gg[ii - 1] + mtk::kOne;
00854
00855
00856
00857
        #if MTK DEBUG LEVEL > 0
00858
        std::cout << "gg0 =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00859
00860
          std::cout << std::setw(12) << gg[ii];
00861
00862
        std::cout << std::endl << std::endl;
00863
        #endif
00864
00865
         \ensuremath{//} Allocate 2D array to store the collection of preliminary approximations.
00866
        try {
          prem_apps_ = new mtk::Real[num_bndy_coeffs_*num_bndy_approxs_];
00867
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<</pre>
00868
00869
00870 std::endl;
00871
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00872
00873
        memset (prem_apps_,
00874
                mtk::kZero,
00875
                sizeof(prem_apps_[0])*num_bndy_coeffs_*num_bndy_approxs_);
00876
00878
00879
        for (auto 11 = 0; 11 < num_bndy_approxs_; ++11) {</pre>
00880
00881
           \ensuremath{//} Re-check new generator vector for every iteration except for the first.
00882
           #if MTK_DEBUG_LEVEL > 0
00883
          if (11 > 0) {
00884
             std::cout << "gg" << 11 << " =" << std::endl;
00885
             for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00886
              std::cout << std::setw(12) << gg[ii];
00887
00888
            std::cout << std::endl << std::endl;
00889
00890
           #endif
00891
00893
00894
          bool transpose(false);
00895
00896
           mtk::DenseMatrix aa(gg,
00897
                                 num_bndy_coeffs_, order_accuracy_ + 1,
00898
                                  transpose);
00899
00900
           #if MTK_DEBUG_LEVEL > 0
          std::cout << "aa_" << 11 << " =" << std::endl;
std::cout << aa << std::endl;</pre>
00901
00902
00903
           #endif
00904
00906
00907
          mtk::Real *ob{};
00908
00909
           auto ob_ld = num_bndy_coeffs_;
00910
00911
           try {
```

```
00912
            ob = new mtk::Real[ob_ld];
00913
          } catch (std::bad_alloc &memory_allocation_exception) {
00914
           std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00915
              std::endl;
00916
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00917
00918
          memset(ob, mtk::kZero, sizeof(ob[0])*ob_ld);
00919
00920
          ob[1] = mtk::kOne;
00921
          #if MTK_DEBUG_LEVEL > 0
00922
          std::cout << "ob = " << std::endl << std::endl;
00923
00924
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
00925
            std::cout << std::setw(12) << ob[ii] << std::endl;
00926
00927
          std::cout << std::endl;</pre>
00928
          #endif
00929
00931
00932
          // However, this is an under-determined system of equations. So we can not
          // use the same LAPACK routine (dgesv_). We will instead use dgels_, through
00933
00934
          // our LAPACKAdapter class.
00935
00936
          int info {
00937
           mtk::LAPACKAdapter::SolveRectangularDenseSystem(aa, ob
      , ob_ld)};
00938
00939
          #if MTK DEBUG LEVEL > 0
00940
          if (!info ) {
            std::cout << "System successfully solved!" << std::endl << std::endl;
00941
00942
          } else {
00943
           std::cerr << "Error solving system! info = " << info_ << std::endl;
00944
00945
          #endif
00946
00947
          #if MTK DEBUG LEVEL > 0
          std::cout << "ob =" << std::endl;
00948
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
00949
00950
           std::cout << std::setw(12) << ob[ii] << std::endl;
00951
00952
          std::cout << std::endl;
00953
          #endif
00954
00956
00957
          // This implies a DAXPY operation. However, we must construct the arguments
00958
          // for this operation.
00959
00961
          // Save them into the ob_bottom array:
00962
00963
          Real *ob_bottom{}; // Bottom part of the attained kernel used to scale it.
00964
00965
00966
           ob_bottom = new mtk::Real[dim_null_];
00967
          } catch (std::bad_alloc &memory_allocation_exception) {
00968
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00969
              std::endl;
00970
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00971
00972
          memset(ob_bottom, mtk::kZero, sizeof(ob_bottom[0])*dim_null_);
00973
00974
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00975
           ob_bottom[(dim_null_ - 1) - ii] = ob[num_bndy_coeffs_ - ii - 1];
00976
00977
00978
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "ob_bottom =" << std::endl;</pre>
00979
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00980
00981
            std::cout << std::setw(12) << ob_bottom[ii] << std::endl;</pre>
00982
00983
          std::cout << std::endl;</pre>
00984
          #endif
00985
00987
00988
          // We must computed an scaled ob, sob, using the scaled null-space in
00989
          // rat basis null space .
00990
          // Such operation is: sob = ob - rat_basis_null_space_*ob_bottom
                                 ob = -1.0*rat_basis_null_space_*ob_bottom + 1.0*ob
00991
          // or:
00992
                                   Y =
          // thus:
                                          a*A
                                                                 b*Y (DAXPY).
                                                 * X
00993
00994
          #if MTK DEBUG LEVEL > 0
          std::cout << "Rational basis for the null-space:" << std::endl;
00995
```

17.68 mtk_grad_1d.cc 337

```
00996
          std::cout << rat_basis_null_space_ << std::endl;</pre>
00997
00998
00999
          mtk::Real alpha{-mtk::kOne};
01000
          mtk::Real beta{mtk::kOne};
01001
01002
          mtk::BLASAdapter::RealDenseMV(alpha, rat_basis_null_space_,
01003
                                          ob_bottom, beta, ob);
01004
01005
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "scaled ob:" << std::endl;</pre>
01006
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01007
01008
            std::cout << std::setw(12) << ob[ii] << std::endl;
01009
01010
          std::cout << std::endl;
01011
          #endif
01012
01013
          // We save the recently scaled solution, into an array containing these.
01014
          // We can NOT start building the pi matrix, simply because I want that part
01015
          // to be separated since its construction depends on the algorithm we want
01016
          // to implement.
01017
01018
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01019
           prem_apps_[ii*num_bndy_approxs_ + 11] = ob[ii];
01020
01021
          // After the first iteration, simply shift the entries of the last
01022
01023
          // generator vector used:
01024
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01025
            gg[ii]--;
01026
01027
01028
          // Garbage collection for this loop:
01029
          delete[] ob;
01030
          ob = nullptr;
01031
01032
          delete[] ob_bottom;
01033
          ob_bottom = nullptr;
        } // End of: for (ll = 0; ll < dim_null; ll++);
01034
01035
01036
        #if MTK_DEBUG_LEVEL > 0
01037
        std::cout << "Matrix post-scaled preliminary apps: " << std::endl;</pre>
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii)</pre>
01038
01039
          for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {</pre>
01040
            std::cout << std::setw(12) << prem_apps_[ii*num_bndy_approxs_ + jj];</pre>
01041
01042
          std::cout << std::endl;</pre>
01043
01044
        std::cout << std::endl;
01045
        #endif
01046
01047
        delete[] gg;
01048
        gg = nullptr;
01049
01050
        return true;
01051 }
01052
01053 bool mtk::Grad1D::ComputeWeights() {
01054
01055
        // Matrix to copmpute the weights as in the CRSA.
01056
        mtk::DenseMatrix pi(num_bndy_coeffs_, num_bndy_coeffs_ - 1);
01057
01059
01060
        // Assemble the pi matrix using:
01061
        // 1. The collection of scaled preliminary approximations.
01062
        // 2. The collection of coefficients approximating at the interior.
01063
        // 3. The scaled basis for the null-space.
01064
01065
        // 1.1. Process array of scaled preliminary approximations.
01066
01067
        // These are queued in scaled_solutions. Each one of these, will be a column
01068
        // of the pi matrix:
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01069
          for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {
  pi.data()[ii*(2*(num_bndy_approxs_ - 1) + (order_accuracy_/2 + 1)) + jj] =</pre>
01070
01071
01072
              {\tt prem\_apps\_[ii*num\_bndy\_approxs\_ + jj];}
01073
01074
01075
01076
        // 1.2. Add columns from known stencil approximating at the interior.
01077
```

```
01078
        // However, these must be padded by zeros, according to their position in the
01079
        // final pi matrix:
01080
        auto mm = 1;
01081
        for (auto jj = num_bndy_approxs_; jj < order_accuracy_; ++jj) {</pre>
01082
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01083
           auto de = (ii + mm) * (2*(num\_bndy\_approxs\_ - 1) +
01084
              (order_accuracy_/2 + 1)) + jj;
01085
            pi.data()[de] = coeffs_interior_[ii];
01086
01087
          ++mm;
        }
01088
01089
01090
        rat basis null space .OrderColMajor();
01091
01092
        #if MTK_DEBUG_LEVEL > 0
01093
        std::cout << "Rational basis for the null-space (col. major):" << std::endl;</pre>
01094
        std::cout << rat_basis_null_space_ << std::endl;</pre>
01095
        #endif
01096
01097
        // 1.3. Add final set of columns: rational basis for null-space.
01098
        01099
01100
01101
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01102
            auto og =
01103
             (jj - (dim_null_ + (order_accuracy_/2 + 1))) *num_bndy_coeffs_ + ii;
            auto de = ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj;
01104
01105
            pi.data()[de] = rat_basis_null_space_.data()[og];
         }
01106
01107
01108
        #if MTK DEBUG LEVEL >0
01109
        std::cout << "coeffs_interior_ =" << std::endl;</pre>
01110
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01111
01112
         std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
01113
01114
        std::cout << std::endl << std::endl;
01115
        #endif
01116
        #if MTK DEBUG LEVEL >0
01117
01118
        std::cout << "Constructed pi matrix for CRS Algorithm: " << std::endl;
01119
        std::cout << pi << std::endl;
01120
        #endif
01121
01123
01124
        // This imposes the mimetic condition.
01125
01126
       mtk::Real *hh{}; // Right-hand side to compute weights in the C{R,B}SA.
01127
01128
01129
         hh = new mtk::Real[num_bndy_coeffs_];
01130
        } catch (std::bad_alloc &memory_allocation_exception) {
01131
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01132
            std::endl;
01133
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01134
01135
        memset(hh, mtk::kZero, sizeof(hh[0])*num_bndy_coeffs_);
01136
01137
        hh[0] = -mtk::kOne;
01138
        for (auto ii = (order_accuracy_/2 + 2 - 1); ii < num_bndy_coeffs_; ++ii) {</pre>
01139
         auto aux_xx = mtk::kZero;
01140
          for (auto jj = 0; jj < ((ii - (order_accuracy_/2 - 1)) - 1); ++jj) {</pre>
01141
            aux_xx += coeffs_interior_[jj];
01142
01143
          hh[ii] = -mtk::kOne*aux_xx;
01144
        }
01145
01147
01148
        // That is, we construct a system, to solve for the weights.
01149
01150
        // Once again we face the challenge of solving with LAPACK. However, for the
        // CRSA, this matrix PI is over-determined, since it has more rows than
01151
        // unknowns. However, according to the theory, the solution to this system is
01152
        // unique. We will use dgels_.
01153
01154
01155
        trv {
         weights_cbs_ = new mtk::Real[num_bndy_coeffs_];
01156
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
01157
01158
            std::endl:
01159
01160
          std::cerr << memory allocation exception.what() << std::endl;</pre>
```

```
01161
01162
        memset(weights_cbs_, mtk::kZero, sizeof(weights_cbs_[0])*num_bndy_coeffs_);
01163
01164
        int weights ld{pi.num cols() + 1};
01165
01166
        // Preserve hh.
01167
        std::copy(hh, hh + weights_ld, weights_cbs_);
01168
01169
        pi.Transpose();
01170
01171
        int info{
01172
         mtk::LAPACKAdapter::SolveRectangularDenseSystem(pi,
01173
                                                              weights_cbs_, weights_ld)
01174
01175
01176
        #if MTK_DEBUG_LEVEL > 0
01177
        if (!info) {
01178
         std::cout << "System successfully solved!" << std::endl << std::endl;</pre>
01179
        } else {
01180
         std::cerr << "Error solving system! info = " << info << std::endl;
01181
01182
        #endif
01183
01184
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "hh =" << std::endl;
01185
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01186
          std::cout << std::setw(11) << hh[ii] << std::endl;
01187
01188
01189
        std::cout << std::endl;
01190
        #endif
01191
01192
        // Preserve the original weights for research.
01193
01194
01195
          weights_crs_ = new mtk::Real[num_bndy_coeffs_];
01196
        } catch (std::bad_alloc &memory_allocation_exception) {
01197
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01198
            std::endl;
01199
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01200
01201
        memset(weights_crs_, mtk::kZero, sizeof(weights_crs_[0])*num_bndy_coeffs_);
01202
01203
        std::copy(weights_cbs_, weights_cbs_ + (weights_ld - 1), weights_crs_);
01204
01205
        #if MTK_DEBUG_LEVEL > 0
01206
        std::cout << "weights_CRSA + lambda =" << std::endl;
01207
        for (auto ii = 0; ii < weights_ld - 1; ++ii)</pre>
01208
          std::cout << std::setw(12) << weights_crs_[ii] << std::endl;</pre>
01209
01210
        std::cout << std::endl;
01211
01212
01214
        if (order_accuracy_ >= mtk::kCriticalOrderAccuracyGrad) {
01215
01216
01217
          int minrow_{std::numeric_limits<int>::infinity()};
01218
01219
          mtk::Real norm{mtk::BLASAdapter::RealNRM2(weights_cbs_,
      order_accuracy_) };
01220
          mtk::Real minnorm{std::numeric_limits<mtk::Real>::infinity()};
01221
01223
01224
          mtk::DenseMatrix phi(order_accuracy_ + 1, order_accuracy_);
01225
01226
          // 6.1. Insert preliminary approximations to first set of columns.
01227
01228
          for (auto ii = 0; ii < order_accuracy_ + 1; ++ii) {</pre>
01229
            for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {</pre>
01230
              phi.data()[ii*(order_accuracy_) + jj] =
01231
                 prem_apps_[ii*num_bndy_approxs_ + jj];
01232
            }
01233
          }
01234
          // 6.2. Skip a column and negate preliminary approximations.
01235
01236
          for (auto jj = 0; jj < order_accuracy_ + 1; jj++) {
   for (auto ii = 1; ii < num_bndy_approxs_; ii++) {</pre>
01237
01238
              auto de = (ii+ order_accuracy - num_bndy_approxs_+ jj*order_accuracy_);
auto og = (num_bndy_approxs_ - ii + (jj)*num_bndy_approxs_);
01239
01240
01241
              phi.data()[de] = -prem_apps_[og];
01242
```

```
01243
01244
01245
           // 6.3. Flip negative columns up-down.
01246
01247
           for (auto ii = 0; ii < order_accuracy_/2; ii++) {</pre>
01248
            for (auto jj = num_bndy_approxs_ + 1; jj < order_accuracy_; jj++) {</pre>
01249
               auto aux = phi.data()[ii*order_accuracy_ + jj];
               phi.data()[ii*order_accuracy_ + jj] =
   phi.data()[(order_accuracy_ - ii)*order_accuracy_ + jj];
phi.data()[(order_accuracy_ - ii)*order_accuracy_ + jj] = aux;
01250
01251
01252
01253
01254
01255
01256
           // 6.4. Insert stencil.
01257
01258
           auto mm = 0;
01259
           for (auto jj = num_bndy_approxs_; jj < num_bndy_approxs_ + 1; jj++) {</pre>
            for (auto ii = 0; ii < order_accuracy_ + 1; ii++) {</pre>
01260
01261
               if (ii == 0) {
01262
                phi.data()[jj] = 0.0;
01263
               } else {
01264
                 phi.data()[(ii + mm)*order_accuracy_ + jj] = coeffs_interior_[ii - 1];
01265
               }
01266
            }
01267
            mm++;
01268
           }
01269
01270
           #if MTK DEBUG LEVEL > 0
           std::cout << "phi =" << std::endl;
01271
01272
           std::cout << phi << std::endl;
01273
           #endif
01274
01276
          mtk::Real *lamed{}; // Used to build big lambda.
01277
01278
01279
01280
             lamed = new mtk::Real[num_bndy_approxs_ - 1];
01281
           } catch (std::bad_alloc &memory_allocation_exception) {
01282
             std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01283
               std::endl;
01284
             std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01285
01286
           memset(lamed, mtk::kZero, sizeof(lamed[0])*(num_bndy_approxs_ - 1));
01287
01288
           for (auto ii = 0; ii < num_bndy_approxs_ - 1; ++ii) {</pre>
01289
             lamed[ii] = hh[ii + order_accuracy_ + 1] ;
01290
01291
           #if MTK_DEBUG_LEVEL > 0
std::cout << "lamed =" << std::endl;</pre>
01292
01293
           for (auto ii = 0; ii < num_bndy_approxs_ - 1; ++ii) {</pre>
01294
01295
             std::cout << std::setw(12) << lamed[ii] << std::endl;</pre>
01296
01297
           std::cout << std::endl;</pre>
01298
           #endif
01299
01300
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01301
            mtk::Real temp = mtk::kZero;
01302
             for(auto jj = 0; jj < num_bndy_approxs_ - 1; ++jj) {</pre>
01303
               temp = temp +
01304
                 lamed[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01305
01306
             hh[ii] = hh[ii] - temp;
01307
01308
01309
           #if MTK_DEBUG_LEVEL > 0
           std::cout << "big_lambda =" << std::endl;</pre>
01310
01311
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01312
            std::cout << std::setw(12) << hh[ii] << std::endl;
01313
01314
           std::cout << std::endl;
01315
           #endif
01316
01318
01319
           int copy_result{}; // Should I replace the solution... not for now.
01320
01321
           mtk::Real normerr ; // Norm of the error for the solution on each row.
01322
01323
           for(auto row_= 0; row_ < order_accuracy_ + 1; ++row_) {</pre>
             normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
01324
      data(),
```

17.68 mtk_grad_1d.cc 341

```
01325
                                                                       order_accuracy_ + 1,
01326
                                                                       order_accuracy_,
01327
                                                                       order_accuracy_,
01328
01329
                                                                       weights_cbs_,
01330
                                                                       row_,
01331
                                                                       mimetic_threshold_,
01332
                                                                       copy_result);
01333
             mtk::Real aux{normerr_/norm};
01334
01335
             #if MTK_DEBUG_LEVEL>0
01336
             std::cout << "Relative norm: " << aux << " " << std::endl;
01337
             std::cout << std::endl;</pre>
01338
             #endif
01339
01340
            if (aux < minnorm) {</pre>
01341
              minnorm = aux:
               minrow_= row_;
01342
01343
             }
01344
01345
01346
           #if MTK_DEBUG_LEVEL > 0
01347
           std::cout << "weights_CBSA + lambda (after brute force search):" <<</pre>
01348
            std::endl;
           for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01349
01350
            std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01351
01352
           std::cout << std::endl;
           #endif
01353
01354
01356
           // After we know which row yields the smallest relative norm that row is
01357
01358
           // chosen to be the objective function and the result of the optimizer is
           // chosen to be the new weights_.
01359
01360
01361
           #if MTK DEBUG LEVEL > 0
01362
           std::cout << "Minimum Relative Norm " << minnorm << " found at row " <<
            minrow_ + 1 << std::endl;
01363
01364
           std::cout << std::endl;
01365
           #endif
01366
01367
           copy_result = 1;
01368
           normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
      data(),
01369
                                                                     order_accuracy_ + 1,
01370
                                                                     order_accuracy_,
01371
                                                                     order_accuracy_,
01372
                                                                    hh,
01373
                                                                     weights_cbs_,
01374
01375
                                                                    mimetic_threshold_,
01376
                                                                    copy_result);
01377
           mtk::Real aux_{normerr_/norm};
01378
           \#if MTK_DEBUG_LEVEL > 0
01379
           std::cout << "Relative norm: " << aux_ << std::endl;</pre>
01380
           std::cout << std::endl;</pre>
01381
           #endif
01382
01383
           delete [] lamed;
01384
           lamed = nullptr;
01385
01386
01387
        delete [] hh;
01388
        hh = nullptr;
01389
01390
        return true;
01391 }
01392
01393 bool mtk::Grad1D::ComputeStencilBoundaryGrid(void) {
01394
01395
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "weights_* + lambda =" << std::endl;
for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {
   std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01396
01397
01398
01399
01400
        std::cout << std::endl;
01401
         #endif
01402
01404
01405
        mtk::Real *lambda{}; // Collection of bottom values from weights .
01406
```

```
01407
        try {
          lambda = new mtk::Real[dim_null_];
01408
         } catch (std::bad_alloc &memory_allocation_exception) {
01409
01410
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01411
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01412
01413
01414
        memset(lambda, mtk::kZero, sizeof(lambda[0])*dim_null_);
01415
01416
         for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
          lambda[ii] = weights_cbs_[order_accuracy_ + ii];
01417
01418
01419
01420
        #if MTK_DEBUG_LEVEL > 0
01421
         std::cout << "lambda =" << std::endl;
01422
         for (auto ii = 0; ii < dim_null_; ++ii)</pre>
01423
          std::cout << std::setw(12) << lambda[ii] << std::endl;</pre>
01424
01425
        std::cout << std::endl;
01426
        #endif
01427
01429
01430
        mtk::Real *alpha{}; // Collection of alpha values.
01431
01432
        try {
          alpha = new mtk::Real[dim_null_];
01433
        } catch (std::bad_alloc &memory_allocation_exception) {
01434
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01435
01436
            std::endl:
01437
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01438
        memset(alpha, mtk::kZero, sizeof(alpha[0])*dim null );
01439
01440
        alpha[ii] = lambda[ii]/weights_cbs_[ii];
}
         for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01441
01442
01443
01444
        #if MTK_DEBUG_LEVEL > 0
std::cout << "alpha =" << std::endl;</pre>
01445
01446
         for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01447
01448
          std::cout << std::setw(12) << alpha[ii] << std::endl;</pre>
01449
01450
         std::cout << std::endl;
01451
         #endif
01452
01454
01455
01456
          mim_bndy_ = new mtk::Real[num_bndy_coeffs_*num_bndy_approxs_];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
01457
01458
01459
             std::endl:
01460
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01461
01462
        memset (mim_bndy_,
01463
               mtk::kZero,
01464
                sizeof(mim_bndy_[0])*num_bndy_coeffs_*num_bndy_approxs_);
01465
01466
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01467
         for (auto jj = 0; jj < (num_bndy_approxs_ - 1); ++jj) {</pre>
01468
             mim_bndy_[ii*num_bndy_approxs_ + jj] =
                                                    jj] +
01469
               prem_apps_[ii*num_bndy_approxs_ +
01470
               alpha[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01471
          }
01472
        }
01473
         for(auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01475
          mim_bndy_[ii*num_bndy_approxs_ + (num_bndy_approxs_ - 1)] =
01476
            prem_apps_[ii*num_bndy_approxs_ + (num_bndy_approxs_ - 1)];
01477
01478
01479
        #if MTK_DEBUG_LEVEL > 0
         std::cout << "Collection of mimetic approximations:" << std::endl;</pre>
01480
01481
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
          for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {
   std::cout << std::setw(13) << mim_bndy_[ii*num_bndy_approxs_ + jj];</pre>
01482
01483
01484
01485
          std::cout << std::endl;
01486
01487
         std::cout << std::endl;
01488
         #endif
01489
```

17.68 mtk_grad_1d.cc 343

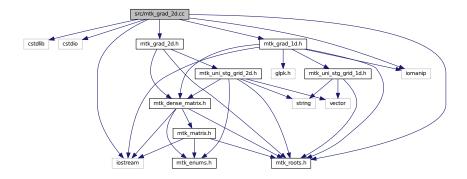
```
01490
        delete[] lambda;
01491
        lambda = nullptr;
01492
01493
        delete[] alpha;
01494
        alpha = nullptr;
01495
01496
        return true;
01497 }
01498
01499 bool mtk::Grad1D::AssembleOperator(void) {
01500
01501
        // The output array will have this form:
01502
        // 1. The first entry of the array will contain the used order kk.
        // 2. The second entry of the array will contain the collection of
01503
01504
        // approximating coefficients for the interior of the grid.
01505
        // 3. The third entry will contain a collection of weights.
01506
        // 4. The next dim_null - 1 entries will contain the collections of
01507
        // approximating coefficients for the west boundary of the grid.
01508
01509
        gradient_length_ = 1 + order_accuracy_ + order_accuracy_ +
01510
          num_bndy_approxs_*num_bndy_coeffs_;
01511
01512
        #if MTK DEBUG LEVEL > 0
01513
        std::cout << "gradient_length_ = " << gradient_length_ << std::endl;</pre>
01514
        #endif
01515
01516
        trv {
          gradient_ = new mtk::Real[gradient_length_];
01517
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
01518
01519
            std::endl:
01520
01521
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01522
01523
        memset(gradient_, mtk::kZero, sizeof(gradient_[0])*gradient_length_);
01524
01526
01527
        gradient_[0] = order_accuracy_;
01528
01531
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01532
01533
         gradient_[ii + 1] = coeffs_interior_[ii];
01534
01535
01537
01538
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01539
          gradient_[(order_accuracy_ + 1) + ii] = weights_cbs_[ii];
01540
01541
01544
01545
        int offset{2*order_accuracy_ + 1};
01546
01547
        int aux {}; // Auxiliary variable.
01548
        if (order_accuracy_ > mtk::kDefaultOrderAccuracy) {
01549
01550
         for (auto ii = 0; ii < num_bndy_approxs_ ; ii++) {</pre>
01551
            for (auto jj = 0; jj < num_bndy_coeffs_; jj++) {</pre>
01552
              gradient_[offset + aux] = mim_bndy_[jj*num_bndy_approxs_ + ii];
01553
01554
01555
        } else {
01556
01557
          gradient_[offset + 0] = prem_apps_[0];
01558
          gradient_[offset + 1] = prem_apps_[1];
01559
          gradient_[offset + 2] = prem_apps_[2];
01560
01561
01562
        #if MTK_DEBUG_LEVEL > 0
01563
        std::cout << "1D " << order_accuracy_ << "-order grad built!" << std::endl;
01564
        std::cout << std::endl;
01565
        #endif
01566
01567
        return true;
01568 }
```

17.69 src/mtk_grad_2d.cc File Reference

Implements the class Grad2D.

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_grad_ld.h"
#include "mtk_grad_2d.h"
```

Include dependency graph for mtk_grad_2d.cc:



17.69.1 Detailed Description

This class implements a 2D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (C← BSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_grad_2d.cc.

17.70 mtk_grad_2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
{\tt 00024} 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
```

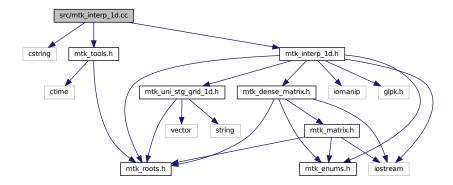
```
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "mtk_roots.h"
00064 #include "mtk_grad_ld.h"
00065 #include "mtk_grad_2d.h"
00066
00067 mtk::Grad2D::Grad2D():
00068 order_accuracy_(),
00069
       mimetic_threshold_() {}
00070
00071 mtk::Grad2D::Grad2D(const Grad2D &grad):
00072
       order_accuracy_(grad.order_accuracy_)
00073
       mimetic_threshold_(grad.mimetic_threshold_) {}
00074
00075 mtk::Grad2D::~Grad2D() {}
00076
00077 bool mtk::Grad2D::ConstructGrad2D(const
     mtk::UniStgGrid2D &grid,
00078
                                          int order_accuracy,
00079
                                          mtk::Real mimetic_threshold) {
00080
00081
        int num_cells_x = grid.num_cells_x();
00082
        int num_cells_y = grid.num_cells_y();
00083
00084
        int mx = num_cells_x + 1; // Gx vertical dimension
        int nx = num_cells_x + 2;  // Gx horizontal dimension
int my = num_cells_y + 1;  // Gy vertical dimension
int ny = num_cells_y + 2;  // Gy horizontal dimension
00085
00086
00087
00088
00089
        mtk::Grad1D grad;
00090
00091
        bool info = grad.ConstructGrad1D(order_accuracy, mimetic_threshold);
00092
00093
        if (!info) {
00094
         std::cerr << "Mimetic grad could not be built." << std::endl;
00095
          return info;
00096
00097
00098
        auto west = grid.west bndv();
00099
        auto east = grid.east bndy();
00100
        auto south = grid.south_bndy();
00101
        auto north = grid.east_bndy();
00102
        mtk::UniStgGrid1D grid_x(west, east, num_cells_x);
00103
00104
        mtk::UniStgGrid1D grid_y(south, north, num_cells_y);
00105
00106
        mtk::DenseMatrix Gx(grad.ReturnAsDenseMatrix(grid x));
```

```
00107
        mtk::DenseMatrix Gy(grad.ReturnAsDenseMatrix(grid_y));
00108
00109
        bool padded{true};
00110
        bool transpose{true};
00111
00112
        mtk::DenseMatrix tix(num_cells_x, padded, transpose);
00113
        mtk::DenseMatrix tiy(num_cells_y, padded, transpose);
00114
00115
        mtk::DenseMatrix gxy(mtk::DenseMatrix::Kron(tiy, Gx));
00116
       mtk::DenseMatrix gyx(mtk::DenseMatrix::Kron(Gy, tix));
00117
00118
        #if MTK_DEBUG_LEVEL > 0
00119
        std::cout << "Gx: " << mx << " by " << nx << std::endl;
        std::cout << "Transpose Iy: " << num_cells_y << " by " << ny  << std::endl;
00121
        std::cout << "Gy: " << my << " by " << ny << std::endl;
        std::cout << "Transpose Ix: " << num_cells_x << " by " << nx << std::endl;
        std::cout << "Grad 2D: " << mx*num_cells_y + my*num_cells_x << " by " <<
00123
         nx*ny <<std::endl;
00124
00125
        #endif
00126
00127
        mtk::DenseMatrix g2d(mx*num_cells_y + my*num_cells_x, nx*ny);
00128
        for(auto ii = 0; ii < nx*ny; ii++) {
  for(auto jj = 0; jj < mx*num_cells_y; jj++) {</pre>
00129
00130
00131
            g2d.SetValue(jj,ii, gxy.GetValue(jj,ii));
00132
00133
          for(auto kk = 0; kk < my*num_cells_x; kk++) {</pre>
            g2d.SetValue(kk + mx*num_cells_y, ii, gyx.GetValue(kk,ii));
00134
00135
00136
00137
00138
        gradient_ = g2d;
00139
0.0140
        return info;
00141 }
00142
00143 mtk::DenseMatrix mtk::Grad2D::ReturnAsDenseMatrix() const {
00144
00145
        return gradient_;
00146 }
```

17.71 src/mtk_interp_1d.cc File Reference

Includes the implementation of the class Interp1D.

```
#include <cstring>
#include "mtk_tools.h"
#include "mtk_interp_1d.h"
Include dependency graph for mtk_interp_1d.cc:
```



Namespaces

mtk

Mimetic Methods Toolkit namespace.

Functions

• std::ostream & mtk::operator<< (std::ostream &stream, mtk::Interp1D &in)

17.71.1 Detailed Description

This class implements a 1D interpolation operator.

Author

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Johnny Corbino jcorbino at mail dot sdsu dot edu

Definition in file mtk_interp_1d.cc.

17.72 mtk_interp_1d.cc

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed, unless these modifications are made through the project's GitHub
00022 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00023 should be developed and included in any deliverable.
00025 2. Redistributions of source code must be done through direct
00026 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00028 3. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 4. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders, and due credit should
00034 be given to the copyright holders.
00036 5. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; 00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
```

```
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #include <cstring>
00059
00060 #include "mtk_tools.h"
00061
00062 #include "mtk_interp_1d.h"
00064 namespace mtk {
00065
00066 std::ostream& operator <<(std::ostream &stream, mtk::InterplD &in) {
00069
00070
        stream << "coeffs_interior_[1:" << in.order_accuracy_ << "] = ";</pre>
00071
        for (auto ii = 0; ii < in.order_accuracy_; ++ii) {</pre>
00072
         stream << std::setw(9) << in.coeffs_interior_[ii] << " ";</pre>
00073
00074
        stream << std::endl;
00075
00076
        return stream:
00077 }
00078 }
00079
00080 mtk::InterplD::InterplD():
        dir_interp_(mtk::SCALAR_TO_VECTOR),
00081
        order_accuracy_(mtk::kDefaultOrderAccuracy),
00082
00083
        coeffs_interior_(nullptr) {}
00084
00085 mtk::Interp1D::Interp1D(const Interp1D &interp):
00086
       dir_interp_(interp.dir_interp_),
00087
        order_accuracy_(interp.order_accuracy_),
00088
        coeffs_interior_(interp.coeffs_interior_) {}
00089
00090 mtk::Interp1D::~Interp1D() {
00091
00092
        delete[] coeffs_interior_;
00093
        coeffs_interior_ = nullptr;
00094 }
00095
00096 bool mtk::InterplD::ConstructInterplD(int order_accuracy,
      mtk::DirInterp dir) {
00097
00098
        #if MTK_DEBUG_LEVEL > 0
00099
        mtk::Tools::Prevent(order_accuracy < 2, __FILE__,</pre>
                                                            __LINE__, __func__);
00100
        mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE__, __LINE__, __func__);
00101
        mtk::Tools::Prevent(dir < mtk::SCALAR_TO_VECTOR &&</pre>
00102
                             dir > mtk::VECTOR_TO_SCALAR,
00103
                             __FILE__, __LINE__, __func__);
00104
00105
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;</pre>
00106
00107
00108
        order_accuracy_ = order_accuracy;
00109
00111
00112
        try {
00113
         coeffs_interior_ = new mtk::Real[order_accuracy_];
00114
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00115
00116
00117
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00118
00119
       memset(coeffs_interior_,
00120
               mtk::kZero,
               sizeof(coeffs_interior_[0])*order_accuracy_);
00122
00123
        for (int ii = 0; ii < order_accuracy_; ++ii) {</pre>
00124
         coeffs_interior_[ii] = mtk::kOne;
00125
00126
00127
        return true:
00128 }
00129
00130 mtk::Real *mtk::Interp1D::coeffs interior() const {
00131
00132
        return coeffs interior :
00133 }
00134
00135 mtk::DenseMatrix mtk::Interp1D::ReturnAsDenseMatrix(
```

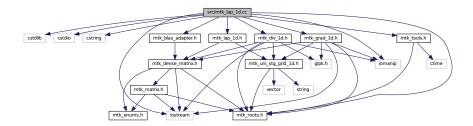
```
00136
        const UniStgGrid1D &grid) const {
00137
00138
         int nn\{grid.num\_cells\_x()\}; // Number of cells on the grid.
00139
00140
         #if MTK_DEBUG_LEVEL > 0
00141
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00142
         #endif
00143
        int gg_num_rows{); // Number of rows.
int gg_num_cols{}; // Number of columns.
00144
00145
00147
        if (dir_interp_ == mtk::SCALAR_TO_VECTOR) {
00148
         gg_num_rows = nn + 1;
           gg_num_cols = nn + 2;
00149
00150
        } else {
00151
          gg_num_rows = nn + 2;
          gg_num_cols = nn + 1;
00152
00153
00154
00155
        // Output matrix featuring sizes for gradient operators.
00156
00157
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00158
00160
00161
        out.SetValue(0, 0, mtk::kOne);
00162
00164
         for (auto ii = 1; ii < gg_num_rows - 1; ++ii) {</pre>
00165
         for(auto jj = ii ; jj < order_accuracy_ + ii; ++jj) {
  out.SetValue(ii, jj, mtk::kOne/order_accuracy_);</pre>
00166
00167
00168
00169
00170
00172
        out.SetValue(gg_num_rows - 1, gg_num_cols - 1, mtk::kOne);
00173
00174
00175
        return out;
00176 }
```

17.73 src/mtk_lap_1d.cc File Reference

Includes the implementation of the class Lap1D.

```
#include <cstdlib>
#include <cstdio>
#include <cstring>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_blas_adapter.h"
#include "mtk_grad_ld.h"
#include "mtk_div_ld.h"
#include "mtk_lap_ld.h"
```

Include dependency graph for mtk_lap_1d.cc:



Namespaces

mtk

Mimetic Methods Toolkit namespace.

Functions

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Lap1D &in)

17.73.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk lap 1d.cc.

17.74 mtk_lap_1d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions in binary form must reproduce the above copyright notice, 00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 4. Usage of the binary form on proprietary applications shall require explicit
```

17.74 mtk lap 1d.cc 351

```
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059 #include <cstring>
00060
00061 #include <iostream>
00062 #include <iomanip>
00063
00064 #include "mtk_roots.h"
00065 #include "mtk_tools.h"
00066 #include "mtk_blas_adapter.h"
00067 #include "mtk_grad_1d.h'
00068 #include "mtk_div_1d.h"
00069 #include "mtk_lap_1d.h"
00070
00071 namespace mtk {
00072
00073 std::ostream& operator <<(std::ostream &stream, mtk::Lap1D &in) {
00074
00076
00077
        stream << "laplacian_[0] = " << in.laplacian_[0] << std::endl << std::endl;</pre>
00078
00080
        stream << "laplacian_[1:" << 2*in.order_accuracy_ - 1 << "] = " <<
00081
00082
         std::endl << std::endl;
        for (auto ii = 1; ii <= (2*in.order_accuracy_ - 1); ++ii) {</pre>
00083
00084
         stream << std::setw(13) << in.laplacian_[ii] << " ";
00085
00086
        stream << std::endl << std::endl;
00087
00089
00090
        auto offset = 1 + (2*in.order_accuracy_ - 1);
00091
        stream << "laplacian_[" << offset << ":" << offset +
   (in.order_accuracy_ - 1)*(2*in.order_accuracy_) - 1 << "] = " <</pre>
00092
00093
00094
          std::endl << std::endl;
00095
00096
        for (auto ii = 0; ii < in.order_accuracy_ - 1; ++ii)</pre>
00097
         for (auto jj = 0; jj < 2*in.order_accuracy_; ++jj) {</pre>
00098
            stream << std::setw(13) <<
              in.laplacian_[offset + ii*(2*in.order_accuracy_) + jj];
00099
00100
00101
          stream << std::endl;</pre>
00102
        }
00103
00104
        return stream;
00105 }
00106 }
00107
00108 mtk::Lap1D::Lap1D():
00109 order_accuracy_(mtk::kDefaultOrderAccuracy),
00110
        laplacian_length_(),
        mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00111
00112
00113 mtk::Lap1D::~Lap1D() {
00114
00115
       delete [] laplacian_;
```

```
00116 laplacian_ = nullptr;
00117 }
00118
00119 bool mtk::Lap1D::ConstructLap1D(int order_accuracy,
00120
                                       mtk::Real mimetic_threshold) {
00121
00122
        #if MTK DEBUG LEVEL > 0
00123
       mtk::Tools::Prevent(order_accuracy < 2, __FILE__, __LINE__,</pre>
                                                                      __func__);
       mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE__, __LINE__, __func__);
00124
       mtk::Tools::Prevent(mimetic_threshold <= mtk::kZero,</pre>
00125
00126
                             __FILE__, __LINE__, __func__);
00127
00128
        if (order_accuracy >= mtk::kCriticalOrderAccuracyDiv) {
         std::cout << "WARNING: Numerical accuracy is high." << std::endl;
00129
00130
00131
00132
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;</pre>
        std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;
00133
00134
        #endif
00135
00136
        order_accuracy_ = order_accuracy;
00137
        mimetic_threshold_ = mimetic_threshold;
00138
00140
00141
       mtk::Grad1D grad; // Mimetic gradient.
00142
00143
        bool info = grad.ConstructGrad1D(order_accuracy_, mimetic_threshold_);
00144
00145
        if (!info) {
         std::cerr << "Mimetic grad could not be built." << std::endl;
00146
00147
         return false;
00148
00149
00151
00152
        mtk::Div1D div: // Mimetic divergence.
00153
00154
        info = div.ConstructDiv1D(order_accuracy_, mimetic_threshold_);
00155
        if (!info) {
00156
         std::cerr << "Mimetic div could not be built." << std::endl;
00157
00158
         return false;
00159
00160
00162
00163
        \ensuremath{//} Since these are mimetic operator, we must multiply the matrices arising
00164
        // from both the divergence and the Laplacian, in order to get the
00165
        // approximating coefficients for the Laplacian operator.
00166
00167
        // However, we must choose a grid that implied a step size of 1, so to get
00168
        // the approximating coefficients, without being affected from the
00169
        // normalization with respect to the grid.
00170
00171
        // Also, the grid must be of the minimum size to support the requested order
00172
        \ensuremath{//} of accuracy. We must please the divergence.
00173
00174
        mtk::UniStgGrid1D aux(mtk::kZero,
                               (mtk::Real) 3*order_accuracy_ - 1,
00175
00176
                               3*order_accuracy_ - 1);
00177
00178
        #if MTK_DEBUG_LEVEL > 0
00179
        std::cout << "aux =" << std::endl;
00180
        std::cout << aux << std::endl;</pre>
        std::cout <<"aux.delta_x() = " << aux.delta_x() << std::endl;
00181
00182
        std::cout << std::endl;</pre>
00183
00184
00185
        mtk::DenseMatrix grad_m(grad.ReturnAsDenseMatrix(aux));
00186
00187
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "grad_m =" << std::endl;
00188
00189
        std::cout << grad_m << std::endl;
00190
        #endif
00191
00192
        mtk::DenseMatrix div m(div.ReturnAsDenseMatrix(aux));
00193
00194
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "div_m =" << std::endl;
00195
        std::cout << div_m << std::endl;
00196
00197
        #endif
00198
00202
```

17.74 mtk lap 1d.cc 353

```
00203
        mtk::DenseMatrix lap; // Laplacian matrix to hold to computed coefficients.
00204
00205
         lap = mtk::BLASAdapter::RealDenseMM(div_m, grad_m);
00206
00207
         #if MTK_DEBUG_LEVEL > 0
00208
        std::cout << "lap =" << std::endl;
00209
         std::cout << lap << std::endl;
00210
00211
00213
00215
00216
         // The output array will have this form:
00217
        // 1. The first entry of the array will contain the used order kk.
        // 2. The second entry of the array will contain the collection of
00218
00219
        // approximating coefficients for the interior of the grid.
00220
        // 3. The next entries will contain the collections of approximating
00221
         // coefficients for the west boundary of the grid.
00222
        laplacian_length_ = 1 + (2*order_accuracy_ - 1) +
  (order_accuracy_ - 1) * (2*order_accuracy_);
00223
00224
00225
00226
        #if MTK_DEBUG_LEVEL > 0
00227
        std::cout << "laplacian_length_ = " << laplacian_length_ << std::endl;</pre>
00228
        std::cout << std::endl;
00229
        #endif
00230
00231
          laplacian_ = new mtk::Real[laplacian_length_];
00232
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00233
00234
00235
             std::endl:
00236
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00237
00238
        memset(laplacian_, mtk::kZero, sizeof(laplacian_[0])*laplacian_length_);
00239
00241
00242
        laplacian_[0] = order_accuracy_;
00243
00246
         for (auto ii = 0; ii < 2*order_accuracy_ - 1; ++ii) {</pre>
00247
00248
          laplacian_[ii + 1] = lap.GetValue(1 + (order_accuracy_ - 1), ii + 1);
00249
00250
00252
00253
        auto offset = 1 + (2*order_accuracy_ - 1);
00254
00255
         for (auto ii = 0; ii < order_accuracy_ - 1; ++ii)</pre>
00256
           for (auto jj = 0; jj < 2*order_accuracy_; ++jj)</pre>
00257
             laplacian_[offset + ii*(2*order_accuracy_) + jj] =
00258
               lap.GetValue(1 + ii, jj);
00259
00260
00261
00262
        return true;
00263 }
00264
00265 mtk::DenseMatrix mtk::Lap1D::ReturnAsDenseMatrix(
00266
        const UniStgGrid1D &grid) const {
00267
00268
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00269
00270
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00271
00272
        mtk::Tools::Prevent(nn < 3*order_accuracy_ - 1, __FILE__, __LINE__, __func__);</pre>
00273
00274
00275
        mtk::DenseMatrix lap(nn + 2, nn + 2); // Laplacian matrix to be returned.
00276
00277
        mtk::Real idx{mtk::kOne/(grid.delta_x()*grid.delta_x())}; // Inverse of
       dx^2.
00278
00280
00281
        auto offset = (1 + 2*order_accuracy_ - 1);
00282
00283
         for (auto ii = 0; ii < order_accuracy_ - 1; ++ii) {</pre>
          for (auto jj = 0; jj < 2*order_accuracy_; ++jj) {
  lap.SetValue(1 + ii,</pre>
00284
00285
00286
00287
                           idx*laplacian_[offset + ii*2*order_accuracy_ + jj]);
00288
00289
        }
```

```
00290
00292
00293
        offset = 1 + (order_accuracy_ - 1);
00294
00295
        int kk{1};
00296
       for (auto ii = order_accuracy_; ii <= nn - (order_accuracy_ - 1); ++ii) {</pre>
00297
          int mm{1};
00298
         for (auto jj = 0; jj < 2*order_accuracy_ - 1; ++jj) {</pre>
00299
            lap.SetValue(ii, jj + kk, idx*laplacian_[mm]);
00300
           mm = mm + 1;
00301
00302
         kk = kk + 1;
00303
00304
00306
00307
        offset = (1 + 2*order_accuracy_ - 1);
00308
00309
        auto aux = order_accuracy_ + (nn - 2*(order_accuracy_ - 1));
00310
00311
        auto 11 = 1;
00312
        auto rr = 1;
        for (auto ii = nn; ii > aux - 1; --ii) {
00313
00314
          auto cc = 0;
00315
         for (auto jj = nn + 2 - 1; jj >= (nn + 2) - 2*order_accuracy_; --jj) {
00316
            lap.SetValue(ii, jj, lap.GetValue(rr,cc));
00317
            ++11;
00318
           ++cc;
00319
00320
         rr++;
00321
00322
00329
00330
       return lap;
00331 }
00332
00333 const mtk::Real* mtk::Lap1D::data(const UniStgGrid1D &grid) const {
00334
00335
       mtk::DenseMatrix tmp;
00336
       tmp = ReturnAsDenseMatrix(grid);
00337
00338
00339
        return tmp.data();
00340 }
```

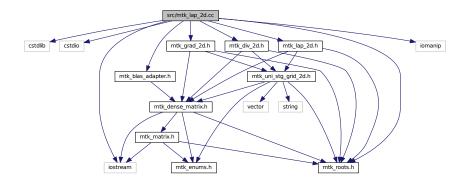
17.75 src/mtk_lap_2d.cc File Reference

Includes the implementation of the class Lap2D.

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_blas_adapter.h"
#include "mtk_grad_2d.h"
#include "mtk_div_2d.h"
#include "mtk_lap_2d.h"
```

17.76 mtk lap 2d.cc 355

Include dependency graph for mtk_lap_2d.cc:



17.75.1 Detailed Description

This class implements a 2D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_lap_2d.cc.

17.76 mtk lap 2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed, unless these modifications are made through the project's GitHub
00021 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00022 should be developed and included in any deliverable.
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00027 3. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 4. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders, and due credit should
00033 be given to the copyright holders.
00034
00035 5. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
```

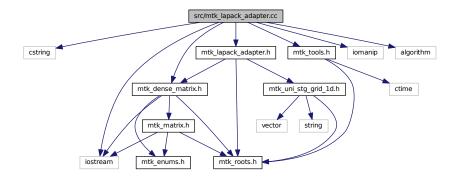
```
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "mtk_roots.h"
00064 #include "mtk_blas_adapter.h"
00065 #include "mtk_grad_2d.h"
00066 #include "mtk_div_2d.h"
00067 #include "mtk_lap_2d.h"
00068
00069 mtk::Lap2D::Lap2D(): order_accuracy_(), mimetic_threshold_() {}
00070
00071 mtk::Lap2D::Lap2D(const Lap2D &lap):
00072
       order_accuracy_(lap.order_accuracy_),
00073
       mimetic_threshold_(lap.mimetic_threshold_) {}
00074
00075 mtk::Lap2D::~Lap2D() {}
00076
00077 bool mtk::Lap2D::ConstructLap2D(const
     mtk::UniStgGrid2D &grid,
00078
                                      int order_accuracy,
00079
                                      mtk::Real mimetic_threshold) {
00080
       mtk::Grad2D gg;
00081
00082
       mtk::Div2D dd;
00083
00084
       bool info{gg.ConstructGrad2D(grid, order_accuracy, mimetic_threshold)};
00085
        if (!info) {
00086
         std::cerr << "Mimetic lap could not be built." << std::endl;</pre>
00087
00088
         return info;
00089
00090
00091
        info = dd.ConstructDiv2D(grid, order_accuracy, mimetic_threshold);
00092
00093
00094
         std::cerr << "Mimetic div could not be built." << std::endl;
00095
         return info;
00096
00097
00098
       mtk::DenseMatrix ggm(gg.ReturnAsDenseMatrix());
00099
        mtk::DenseMatrix ddm(dd.ReturnAsDenseMatrix());
00100
00101
        laplacian_ = mtk::BLASAdapter::RealDenseMM(ddm, ggm);
00102
00103
        return info;
00104 }
00105
00106 mtk::DenseMatrix mtk::Lap2D::ReturnAsDenseMatrix() const {
        return laplacian_;
00109 }
00110
00111 mtk::Real *mtk::Lap2D::data() const {
00112
00113
        return laplacian_.data();
00114 }
```

17.77 src/mtk_lapack_adapter.cc File Reference

Adapter class for the LAPACK API.

```
#include <cstring>
#include <iostream>
#include <iomanip>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_dense_matrix.h"
#include "mtk_lapack_adapter.h"
```

Include dependency graph for mtk_lapack_adapter.cc:



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Functions

- void mtk::sgesv_ (int *n, int *nrhs, Real *a, int *lda, int *ipiv, Real *b, int *ldb, int *info)
- void mtk::sgels_ (char *trans, int *m, int *n, int *nrhs, Real *a, int *lda, Real *b, int *ldb, Real *work, int *lwork, int *info)

Single-precision GEneral matrix Least Squares solver.

- void mtk::sgeqrf_ (int *m, int *n, Real *a, int *lda, Real *tau, Real *work, int *lwork, int *info)
 Single-precision GEneral matrix QR Factorization.
- void mtk::sormqr_ (char *side, char *trans, int *m, int *n, int *k, Real *a, int *lda, Real *tau, Real *c, int *ldc, Real *work, int *lwork, int *info)

Single-precision Orthogonal Matrix from QR factorization.

17.77.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

See also

```
http://www.netlib.org/lapack/
```

Todo Write documentation using LaTeX.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk lapack adapter.cc.

17.78 mtk_lapack_adapter.cc

```
00001
00021 /*
00022 Copyright (C) 2015, Computational Science Research Center, San Diego State
00023 University. All rights reserved.
00025 Redistribution and use in source and binary forms, with or without modification,
00026 are permitted provided that the following conditions are met:
00027
00028 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00029 and a copy of the modified files should be reported once modifications are
00030 completed, unless these modifications are made through the project's GitHub
00031 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00032 should be developed and included in any deliverable.
00033
00034 2. Redistributions of source code must be done through direct
00035 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00036
00037 3. Redistributions in binary form must reproduce the above copyright notice,
00038 this list of conditions and the following disclaimer in the documentation and/or
00039 other materials provided with the distribution.
00040
00041 4. Usage of the binary form on proprietary applications shall require explicit
00042 prior written permission from the the copyright holders, and due credit should
00043 be given to the copyright holders.
00044
00045 5. Neither the name of the copyright holder nor the names of its contributors
00046 may be used to endorse or promote products derived from this software without
00047 specific prior written permission.
00049 The copyright holders provide no reassurances that the source code provided does
00050 not infringe any patent, copyright, or any other intellectual property rights of
00051 third parties. The copyright holders disclaim any liability to any recipient for
00052 claims brought against recipient by any third party for infringement of that
00053 parties intellectual property rights.
00055 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00056 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00057 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00058 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00059 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00060 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00061 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00062 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00063 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00064 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00065 */
00066
00067 #include <cstring>
00068
00069 #include <iostream>
00070 #include <iomanip>
```

```
00071
00072 #include <algorithm>
00073
00074 #include "mtk_tools.h"
00075 #include "mtk_dense_matrix.h"
00076 #include "mtk_lapack_adapter.h"
00077
00078 namespace mtk {
00079
00080 extern "C" {
00081
00082 #ifdef MTK_PRECISION_DOUBLE
00083
00102 void dgesv_(int* n,
00103
                  int* nrhs,
00104
                  Real* a,
00105
                  int* lda,
                  int* ipiv,
00106
00107
                  Real* b,
00108
                  int* ldb,
00109
                  int* info);
00110 #else
00111
00130 void sgesv_(int* n,
00131
                  int* nrhs.
00132
                  Real* a,
00133
                  int* lda,
                  int* ipiv,
00134
00135
                  Real* b.
                  int* ldb,
00136
00137
                  int* info);
00138 #endif
00139
00140 #ifdef MTK_PRECISION_DOUBLE
00141
00184 void dgels_(char* trans,
00185
                  int* m,
                  int* n,
00186
00187
                  int* nrhs,
00188
                  Real* a,
00189
                  int* lda,
00190
                  Real* b,
                  int* ldb,
00191
00192
                  Real* work,
00193
                  int* lwork,
00194
                  int* info);
00195 #else
00196
00239 void sgels_(char* trans,
00240
                  int* m,
00241
                  int* n,
00242
                  int* nrhs,
00243
                  Real* a,
00244
                  int* lda,
00245
                  Real* b,
00246
                  int* ldb,
00247
                  Real* work,
00248
                  int* lwork,
00249
                  int* info);
00250 #endif
00252 #ifdef MTK_PRECISION_DOUBLE
00282 void dgeqrf_(int *m,
                 int *n,
                   Real *a,
                   int *lda,
00286
                   Real *tau,
00287
                   Real *work,
00288
                   int *lwork,
00289
                   int *info);
00290 #else
00291
00320 void sgeqrf_(int *m,
00321
                   int *n.
00322
                   Real *a.
                   int *lda,
00323
00324
                   Real *tau,
00325
                   Real *work,
00326
                   int *lwork,
int *info);
00327
```

```
00328 #endif
00329
00330 #ifdef MTK_PRECISION_DOUBLE
00331
00365 void dormqr_(char *side,
00366
                   char *trans,
00367
                   int *m,
00368
                   int *n,
00369
                   int *k,
00370
                  Real *a,
00371
                   int *lda,
00372
                   Real *tau,
00373
                   Real *c,
00374
                   int *ldc,
00375
                   Real *work,
00376
                   int *lwork,
00377
                   int *info);
00378 #else
00379
00413 void sormqr_(char *side,
00414
                   char *trans,
00415
                   int *m.
00416
                   int *n,
00417
                  int *k,
00418
                  Real *a,
                   int *lda,
00419
00420
                   Real *tau,
00421
                  Real *c,
00422
                   int *ldc,
00423
                   Real *work,
                   int *lwork,
00424
00425
                   int *info);
00426 #endif
00427 }
00428 }
00429
00430 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
00431
                                               mtk::Real *rhs) {
00432
00433
       #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(rhs == nullptr, __FILE__, __LINE__, __func__);
00434
00435
        #endif
00436
00437
        int *ipiv{};
                                     // Array for pivoting information.
00438
        int nrhs{1};
                                     // Number of right-hand sides.
00439
        int info{};
                                     \ensuremath{//} Status of the solution.
00440
        int mm_rank{mm.num_rows()}; // Rank of the matrix.
00441
00442
00443
         ipiv = new int[mm_rank];
00444
       } catch (std::bad_alloc &memory_allocation_exception) {
00445
        std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00446
            std::endl;
00447
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00448
00449
       memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00450
00451
        int ldbb = mm_rank;
00452
        int mm_ld = mm_rank;
00453
00454
        #ifdef MTK_PRECISION_DOUBLE
00455
        dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, rhs, &ldbb, &info);
00456
        #else
00457
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, rhs, &ldbb, &info);
00458
        #endif
00459
00460
       delete [] ipiv;
00461
00462
       return info;
00463 }
00464
00465 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
                                               mtk::DenseMatrix &bb) {
00467
        int nrhs{bb.num_rows()}; // Number of right-hand sides.
00468
00469
00470
        #if MTK_DEBUG_LEVEL > 0
00471
       mtk::Tools::Prevent(nrhs <= 0, __FILE__, __LINE__, __func__);</pre>
00472
       #endif
```

```
00473
00474
        int *ipiv{};
                                      // Array for pivoting information.
00475
        int info{};
                                      // Status of the solution.
        int mm_rank{mm.num_rows()}; // Rank of the matrix.
00476
00477
00478
00479
          ipiv = new int[mm_rank];
00480
        } catch (std::bad_alloc &memory_allocation_exception) {
00481
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00482
            std::endl;
00483
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00484
00485
        memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00486
00487
        int ldbb = mm_rank;
00488
       int mm_ld = mm_rank;
00489
00490
        #ifdef MTK_PRECISION_DOUBLE
00491
        dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, bb.data(), &ldbb, &info);
00492
        #else
00493
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, bb.data(), &ldbb, &info);
00494
        #endif
00495
00496
        delete [] ipiv;
00497
00498
        // After output, the data in the matrix will be column-major ordered.
00499
00500
       bb.SetOrdering(mtk::COL MAJOR);
0.0501
00502
        #if MTK_DEBUG_LEVEL > 0
00503
        std::cout << "bb_col_maj_ord =" << std::endl;</pre>
00504
        std::cout << bb << std::endl;</pre>
00505
        #endif
00506
        bb.OrderRowMajor();
00507
00508
        #if MTK_DEBUG_LEVEL > 0
std::cout << "bb_row_maj_ord =" << std::endl;</pre>
00509
0.0510
        std::cout << bb << std::endl;</pre>
00511
00512
        #endif
00513
00514
        return info;
00515 }
00516
00517 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
00518
                                                 mtk::UniStgGrid1D &rhs) {
00519
00520
        int nrhs{1}; // Number of right-hand sides.
00521
00522
        int *ipiv{};
                                      // Array for pivoting information.
00523
        int info{};
                                      \ensuremath{//} Status of the solution.
00524
       int mm_rank{mm.num_rows()}; // Rank of the matrix.
00525
00526
00527
          ipiv = new int[mm_rank];
00528
        } catch (std::bad_alloc &memory_allocation_exception) {
00529
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00530
            std::endl;
00531
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00532
00533
        memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00534
00535
        int ldbb = mm_rank;
00536
        int mm_ld = mm_rank;
00537
00538
        mm.OrderColMajor();
00539
00540
        #ifdef MTK_PRECISION_DOUBLE
00541
        dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv,
00542
               rhs.discrete_field_u(), &ldbb, &info);
00543
        #else
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv,
00544
00545
               rhs.discrete_field_u(), &ldbb, &info);
00546
00547
00548
        mm.OrderRowMajor();
00549
00550
        delete [] ipiv;
00551
00552
        return info;
```

```
00553 }
00555 mtk::DenseMatrix mtk::LAPACKAdapter::QRFactorDenseMatrix
      (mtk::DenseMatrix &aa) {
00556
00557
       mtk::Real *work{}; // Working array.
00558
       mtk::Real *tau{}; // Array for the Householder scalars.
00559
00560
        // Prepare to factorize: allocate and inquire for the value of lwork.
00561
00562
          work = new mtk::Real[1];
00563
        } catch (std::bad_alloc &memory_allocation_exception) {
00564
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
           std::endl;
00565
00566
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00567
00568
       memset(work, mtk::kZero, sizeof(aa.data()[0])*1);
00569
00570
        int lwork{-1};
00571
        int info{};
00572
00573
        int aa num cols = aa.num cols();
00574
        int aaT_num_rows = aa.num_cols();
00575
        int aaT_num_cols = aa.num_rows();
00576
00577
        #if MTK DEBUG LEVEL > 0
00578
        std::cout << "Input matrix BEFORE QR factorization:" << std::endl;</pre>
00579
        std::cout << aa << std::endl;
00580
        #endif
00581
00582
        #ifdef MTK PRECISION DOUBLE
00583
       dgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00584
                tau.
00585
                work, &lwork, &info);
00586
        #else
00587
        fgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00588
                tau,
00589
                work, &lwork, &info);
00590
       #endif
00591
00592
        #if MTK_DEBUG_LEVEL > 0
00593
        if (info == 0) {
00594
         lwork = (int) work[0];
00595
        } else {
00596
         std::cerr << "Could not get value for lwork on line " << __LINE__ - 5 <<
00597
           std::endl;
00598
         std::cerr << "Exiting..." << std::endl;
00599
       #endif
00600
00601
00602
        #if MTK_DEBUG_LEVEL>0
        std::cout << "lwork = " << std::endl << std::setw(12) << lwork << std::endl
00603
00604
         << std::endl;
00605
        #endif
00606
00607
        delete [] work;
00608
       work = nullptr;
00609
        // Once we know lwork, we can actually invoke the factorization:
00610
00611
        try {
00612
         work = new mtk::Real [lwork];
00613
        } catch (std::bad_alloc &memory_allocation_exception) {
00614
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00615
            std::endl;
00616
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00617
00618
       memset(work, mtk::kZero, sizeof(work[0])*lwork);
00619
00620
       int ltau = std::min(aaT_num_rows,aaT_num_cols);
00621
00622
00623
         tau = new mtk::Real [ltau];
00624
        } catch (std::bad_alloc &memory_allocation_exception) {
00625
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00626
           std::endl;
00627
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00628
00629
       memset(tau, mtk::kZero, sizeof(0.0)*ltau);
00630
00631
        #ifdef MTK PRECISION DOUBLE
       dgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00632
```

```
00633
                tau, work, &lwork, &info);
00634
        #else
00635
        fgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
                tau, work, &lwork, &info);
00636
00637
        #endif
00638
00639
        if (!info) {
00640
         #if MTK_DEBUG_LEVEL > 0
00641
         std::cout << "QR factorization completed!" << std::endl << std::endl;</pre>
          #endif
00642
00643
        } else {
         std::cerr << "Error solving system! info = " << info << std::endl;</pre>
00644
00645
         std::cerr << "Exiting..." << std::endl;
00646
00647
00648
        #if MTK_DEBUG_LEVEL > 0
00649
        std::cout << "Input matrix AFTER QR factorization:" << std::endl;</pre>
00650
        std::cout << aa << std::endl;
00651
        #endif
00652
00653
        // We now generate the real matrix O with orthonormal columns. This has to
00654
        // be done separately since the actual output of dgeqrf_ (AA_) represents
00655
        // the orthogonal matrix Q as a product of min(aa_num_rows,aa_num_cols)
00656
        // elementary Householder reflectors. Notice that we must re-inquire the new
00657
        // value for lwork that is used.
00658
00659
        bool padded{false}:
00660
00661
        bool transpose{false};
00662
00663
       mtk::DenseMatrix QQ_(aa.num_cols(),padded,transpose);
00664
00665
        #if MTK_DEBUG_LEVEL > 0
std::cout << "Initialized QQ_T: " << std::endl;</pre>
00666
        std::cout << QQ_ << std::endl;
00667
00668
        #endif
00669
00670
        // Assemble the QQ_ matrix:
00671
        lwork = -1;
00672
00673
        delete[] work;
00674
        work = nullptr;
00675
00676
00677
         work = new mtk::Real[1];
00678
        } catch (std::bad_alloc &memory_allocation_exception) {
00679
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00680
           std::endl;
00681
          std::cerr << memory_allocation_exception.what() <<</pre>
00682
            std::endl;
00683
00684
        memset(work, mtk::kZero, sizeof(work[0])*1);
00685
00686
        char side_{'L'};
00687
        char trans_{'N'};
00688
00689
        int aux = QQ_.num_rows();
00690
00691
        #ifdef MTK_PRECISION_DOUBLE
00692
        dormqr_(&side_, &trans_,
                &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00693
00694
                QQ_.data(), &aux, work, &lwork, &info);
00695
        #else
00696
        formqr_(&side_, &trans_,
00697
                &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00698
                QQ_.data(), &aux, work, &lwork, &info);
00699
00700
00701
        #if MTK_DEBUG_LEVEL > 0
00702
        if (info == 0) {
00703
         lwork = (int) work[0];
00704
        } else {
         std::cerr << "Could not get lwork on line " << __LINE__ - 5 << std::endl;
00705
         std::cerr << "Exiting..." << std::endl;
00706
00707
00708
        #endif
00709
00710
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "lwork = " << std::endl << std::setw(12) << lwork <<
00711
00712
         std::endl << std::endl;
00713
        #endif
```

```
00714
00715
        delete[] work;
00716
        work = nullptr;
00717
00718
       try {
00719
         work = new mtk::Real[lwork];
00720
        } catch (std::bad_alloc &memory_allocation_exception) {
00721
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00722
            std::endl;
00723
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00724
00725
       memset(work, mtk::kZero, sizeof(work[0])*lwork);
00726
00727
        #ifdef MTK_PRECISION_DOUBLE
00728
        dormqr_(&side_, &trans_,
00729
                &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00730
                QQ_.data(), &aux, work, &lwork, &info);
00731
        #else
00732
        formgr_(&side_, &trans_,
                &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00733
00734
                QQ_.data(), &aux, work, &lwork, &info);
00735
        #endif
00736
00737
        if (!info) {
00738
         #if MTK_DEBUG_LEVEL>0
00739
         std::cout << "Q matrix successfully assembled!" << std::endl << std::endl;</pre>
00740
          #endif
00741
        } else {
00742
         std::cerr << "Something went wrong solving system! info = " << info <<
00743
           std::endl;
         std::cerr << "Exiting..." << std::endl;
00744
00745
00746
00747
        delete[] work;
00748
       work = nullptr;
00749
00750
       delete[] tau;
00751
        tau = nullptr;
00752
00753
        return QQ_;
00754 }
00755
{\tt 00756\ int\ mtk::LAPACKAdapter::SolveRectangularDenseSystem(const)}
     mtk::DenseMatrix &aa,
00757
                                                           mtk::Real *ob_,
00758
                                                           int ob_ld_) {
00759
00760
        // We first invoke the solver to query for the value of lwork. For this,
00761
        // we must at least allocate enough space to allow access to {\tt WORK(1)} , or
00762
        // work[0]:
00763
00764
        // If LWORK = -1, then a workspace query is assumed; the routine only
00765
        // calculates the optimal size of the WORK array, returns this value as
00766
        // the first entry of the WORK array, and no error message related to
00767
        // LWORK is issued by XERBLA.
00768
00769
       mtk::Real *work{}; // Work array.
00770
00771
00772
         work = new mtk::Real[1];
00773
        } catch (std::bad_alloc &memory_allocation_exception) {
00774
         std::cerr << "Memory allocation exception on line " << _
                                                                     _LINE__ - 3 << std::endl;
00775
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00776
00777
        memset(work, mtk::kZero, sizeof(work[0])*1);
00778
00779
        char trans_{'N'};
00780
        int nrhs_{1};
00781
        int info{0};
00782
        int lwork{-1};
00783
00784
        int AA_num_rows_ = aa.num_cols();
int AA_num_cols_ = aa.num_rows();
00785
        int AA_ld_ = std::max(1,aa.num_cols());
00786
00787
00788
        #ifdef MTK PRECISION DOUBLE
00789
        dgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00790
               ob_, &ob_ld_,
00791
               work, &lwork, &info);
00792
        #else
00793
        sgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
```

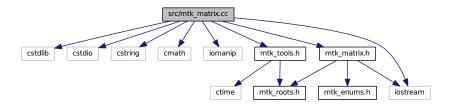
```
00794
                ob_, &ob_ld_,
00795
                work, &lwork, &info);
00796
        #endif
00797
00798
        if (info == 0) {
00799
         lwork = (int) work[0];
00800
00801
         std::cerr << "Could not get value for lwork on line " << __LINE__ - 2 <<
00802
         std::cerr << "Exiting..." << std::endl;
00804
          return info;
00805
00806
        #if MTK_DEBUG_LEVEL > 0
00807
        std::cout << "lwork = " << std::endl << std::setw(12) << lwork <<
80800
00809
         std::endl << std::endl;
00810
00811
00812
        // We then use lwork's new value to create the work array:
00813
        delete[] work;
00814
        work = nullptr;
00815
00816
00817
          work = new mtk::Real[lwork];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 << std::endl;</pre>
00818
00819
00820
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00821
00822
        memset(work, 0.0, sizeof(work[0])*lwork);
00823
00824
        // We now invoke the solver again:
00825
        #ifdef MTK PRECISION DOUBLE
00826
        dgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00827
               ob_, &ob_ld_,
                work, &lwork, &info);
00828
00829
        #else
00830
        sgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00831
               ob_, &ob_ld_,
00832
                work, &lwork, &info);
       #endif
00833
00834
00835
        delete [] work;
00836
        work = nullptr;
00837
00838
        return info;
00839 }
```

17.79 src/mtk_matrix.cc File Reference

Implementing the representation of a matrix in the MTK.

```
#include <cstdlib>
#include <cstdio>
#include <cstring>
#include <cmath>
#include <iomanip>
#include <iostream>
#include "mtk_tools.h"
#include "mtk_matrix.h"
```

Include dependency graph for mtk_matrix.cc:



17.79.1 Detailed Description

Implementation of the representation for the matrices implemented in the MTK.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk matrix.cc.

17.80 mtk matrix.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE 00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
```

17.80 mtk matrix.cc 367

```
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <cstdlib>
00057 #include <cstdio>
00058 #include <cstring>
00059 #include <cmath>
00060
00061 #include <iomanip>
00062 #include <iostream>
00063
00064 #include "mtk_tools.h"
00065 #include "mtk_matrix.h"
00066
00067 mtk::Matrix::Matrix():
00068 storage_(mtk::DENSE),
       ordering_(mtk::ROW_MAJOR),
00069
00070
       num rows (),
00071
       num_cols_(),
00072
       num values ().
00073
        ld_(),
00074
        num_zero_(),
00075
        num_non_zero_(),
00076
        num null (),
00077
        num_non_null_(),
00078
        kl_(),
00079
        ku_(),
00080
        bandwidth_(),
00081
        abs_density_(),
00082
        rel_density_(),
00083
        abs_sparsity_(),
00084
        rel_sparsity_() {}
00085
00086 mtk::Matrix::Matrix(const Matrix &in):
00087
        storage_(in.storage_),
00088
       ordering_(in.ordering_),
00089
        num_rows_(in.num_rows_),
00090
        num_cols_(in.num_cols_),
00091
        num_values_(in.num_values_),
00092
        ld_(in.ld_),
00093
        num_zero_(in.num_zero_),
00094
        num_non_zero_(in.num_non_zero_),
00095
        num_null_(in.num_null_),
00096
        num_non_null_(in.num_non_null_),
00097
        kl_(in.kl_),
00098
        ku_(in.ku_),
00099
        bandwidth_(in.bandwidth_),
00100
        abs_density_(in.abs_density_),
00101
        rel_density_(in.rel_density_),
00102
        abs_sparsity_(in.abs_sparsity_),
00103
       rel_sparsity_(in.rel_sparsity_) {}
00104
00105 mtk::Matrix::~Matrix() noexcept {}
00106
00107 mtk::MatrixStorage mtk::Matrix::storage() const noexcept {
00108
00109
        return storage_;
00110 }
00111
00112 mtk::MatrixOrdering mtk::Matrix::ordering() const noexcept {
00113
00114
       return ordering_;
00115 }
00116
00117 int mtk::Matrix::num_rows() const noexcept {
00118
00119
        return num rows ;
00120 }
00121
00122 int mtk::Matrix::num_cols() const noexcept {
00123
00124
       return num_cols_;
00125 }
00126
00127 int mtk::Matrix::num_values() const noexcept {
00128
00129
        return num_values_;
```

```
00130 }
00131
00132 int mtk::Matrix::ld() const noexcept {
00133
00134
        return ld_;
00135 }
00136
00137 int mtk::Matrix::num_zero() const noexcept {
00138
00139
        return num_zero_;
00140 }
00141
00142 int mtk::Matrix::num_non_zero() const noexcept {
00143
00144
        return num_non_zero_;
00145 }
00146
00147 int mtk::Matrix::num_null() const noexcept {
00148
00149
        return num null ;
00150 }
00151
00152 int mtk::Matrix::num_non_null() const noexcept {
00153
00154
       return num_non_null_;
00155 }
00156
00157 int mtk::Matrix::kl() const noexcept {
00158
00159
        return kl_;
00160 }
00161
00162 int mtk::Matrix::ku() const noexcept {
00163
00164
        return ku :
00165 }
00166
00167 int mtk::Matrix::bandwidth() const noexcept {
00168
00169
        return bandwidth_;
00170 }
00171
00172 mtk::Real mtk::Matrix::rel_density() const noexcept {
00173
00174
        return rel_density_;
00175 }
00176
00177 mtk::Real mtk::Matrix::abs_sparsity() const noexcept {
00178
00179
        return abs_sparsity_;
00180 }
00181
00182 mtk::Real mtk::Matrix::rel_sparsity() const noexcept {
00183
00184
        return rel_sparsity_;
00185 }
00186
00187 void mtk::Matrix::set_storage(const mtk::MatrixStorage &ss)
     noexcept {
00188
00189
       #if MTK_DEBUG_LEVEL > 0
00190
       mtk::Tools::Prevent(!(ss == mtk::DENSE ||
00191
                             ss == mtk::BANDED ||
                              ss == mtk::CRS),
00192
00193
                            __FILE__, __LINE__, __func__);
00194
        #endif
00195
00196
       storage_ = ss;
00197 }
00198
00199 void mtk::Matrix::set_ordering(const
     mtk::MatrixOrdering &oo) noexcept {
00200
00201
        #if MTK_DEBUG_LEVEL > 0
00202
       mtk::Tools::Prevent(!(oo == mtk::ROW_MAJOR || oo ==
     mtk::COL_MAJOR),
00203
                            __FILE__, __LINE__, __func__);
00204
       #endif
00205
00206
        ordering_ = oo;
00207
```

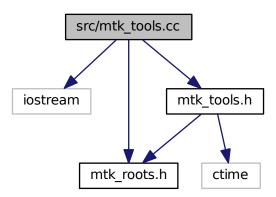
```
ld_ = (ordering_ == mtk::ROW_MAJOR)?
00208
00209
          std::max(1,num_cols_): std::max(1,num_rows_);
00210 }
00211
00212 void mtk::Matrix::set_num_rows(const int &in) noexcept {
00213
00214
        #if MTK_DEBUG_LEVEL > 0
00215
        mtk::Tools::Prevent(in < 1, __FILE__, __LINE__, __func__);</pre>
00216
        #endif
00217
00218
        num_rows_ = in;
00219
        num_values_ = num_rows_*num_cols_;
00220
        ld_ = (ordering_ == mtk::ROW_MAJOR)?
00221
          std::max(1,num_cols_): std::max(1,num_rows_);
00222 }
00223
00224 void mtk::Matrix::set_num_cols(const int &in) noexcept {
00225
00226
        #if MTK_DEBUG_LEVEL > 0
00227
        mtk::Tools::Prevent(in < 1, __FILE__, __LINE__, __func__);</pre>
00228
        #endif
00229
00230
        num_cols_ = in;
00231
        num_values_ = num_rows_*num_cols_;
00232
        ld_ = (ordering_ == mtk::ROW_MAJOR)?
00233
          std::max(1,num_cols_): std::max(1,num_rows_);
00234 }
00235
00236 void mtk::Matrix::set_num_zero(const int &in) noexcept {
00237
00238
        #if MTK DEBUG LEVEL > 0
00239
        mtk::Tools::Prevent(in < 0, __FILE__, __LINE__, __func__);</pre>
00240
        #endif
00241
00242
        num_zero_ = in;
00243
        num_non_zero_ = num_values_ - num_zero_;
00244
00246
        rel_density_ = (mtk::Real) num_non_zero_/num_values_;
00247
        rel_sparsity_ = 1.0 - rel_density_;
00248 }
00249
00250 void mtk::Matrix::set_num_null(const int &in) noexcept {
00251
00252
        #if MTK DEBUG LEVEL > 0
00253
        mtk::Tools::Prevent(in < 0, __FILE__, __LINE__, __func__);</pre>
00254
        #endif
00255
00256
        num_null_ = in;
00257
        num_non_null_ = num_values_ - num_null_;
00258
00260
        abs_density_ = (mtk::Real) num_non_null_/num_values_;
00261
        abs_sparsity_ = 1.0 - abs_density_;
00262 }
00263
00264 void mtk::Matrix::IncreaseNumZero() noexcept {
00265
00267
00268
       num_zero_++;
00269
       num_non_zero_ = num_values_ - num_zero_;
00270
        rel_density_ = (mtk::Real) num_non_zero_/num_values_;
00271
       rel_sparsity_ = 1.0 - rel_density_;
00272 }
00273
00274 void mtk::Matrix::IncreaseNumNull() noexcept {
00275
00277
00278
       num_null_++;
        num_non_null_ = num_values_ - num_null_;
00279
       abs_density_ = (mtk::Real) num_non_null_/num_values_;
abs_sparsity_ = 1.0 - abs_density_;
00280
00281
00282 }
```

17.81 src/mtk_tools.cc File Reference

Implements a execution tool manager class.

```
#include <iostream>
#include "mtk_roots.h"
#include "mtk_tools.h"
```

Include dependency graph for mtk tools.cc:



17.81.1 Detailed Description

Basic tools to ensure execution correctness.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk tools.cc.

17.82 mtk tools.cc

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
```

17.82 mtk tools.cc 371

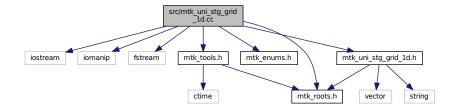
```
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <iostream>
00057
00058 #include "mtk roots.h"
00059 #include "mtk_tools.h"
00060
00061 void mtk::Tools::Prevent(const bool condition,
00062
                                const char *const fname,
00063
                                int lineno,
00064
                                const char *const fxname) noexcept {
00065
00067
        #if MTK DEBUG LEVEL > 0
00068
        if (lineno < 1) {</pre>
00069
          std::cerr << __FILE__ << ": " << "Incorrect parameter at line " <<
__LINE__ - 2 << " (" << __func__ << ")" << std::endl;</pre>
00070
00071
00072
          exit(EXIT_FAILURE);
00073
00074
        #endif
00075
00076
        if (condition) {
          std::cerr << fname << ": " << "Incorrect parameter at line " << li>lineno << " (" << fxname << ")" << std::endl;
00077
00078
00079
          exit(EXIT_FAILURE);
00080
00081 }
00082
00084
00085 int mtk::Tools::test_number_; // Used to control the correctness of the test.
00086
00087 mtk::Real mtk::Tools::duration_; // Duration of the current test.
00088
00089 clock_t mtk::Tools::begin_time_; // Used to time tests.
00090
00091 void mtk::Tools::BeginUnitTestNo(const int &nn) noexcept {
00092
00093
        #if MTK DEBUG LEVEL > 0
00094
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00095
        #endif
00096
00097
        test number = nn;
00098
00099
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Beginning test " << nn << "." << std::endl;
00100
00101
        #endif
00102
        begin_time_ = clock();
00103 }
00104
00105 void mtk::Tools::EndUnitTestNo(const int &nn) noexcept {
00106
        #if MTK_DEBUG_LEVEL > 0
00107
00108
       mtk::Tools::Prevent(test number != nn, FILE , LINE , func );
00109
        #endif
00110
00111
        duration = mtk::Real(clock() - begin time )/CLOCKS PER SEC:
00112 }
00113
00114 void mtk::Tools::Assert(const bool &condition) noexcept {
```

17.83 src/mtk_uni_stg_grid_1d.cc File Reference

Implementation of an 1D uniform staggered grid.

```
#include <iostream>
#include <iomanip>
#include <fstream>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_tools.h"
#include "mtk_uni_stg_grid_ld.h"
```

Include dependency graph for mtk_uni_stg_grid_1d.cc:



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Functions

• std::ostream & mtk::operator<< (std::ostream &stream, mtk::UniStgGrid1D &in)

17.83.1 Detailed Description

Implementation of an 1D uniform staggered grid.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_uni_stg_grid_1d.cc.

17.84 mtk_uni_stg_grid_1d.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <iostream>
00057 #include <iomanip>
00058 #include <fstream>
00059
00060 #include "mtk_roots.h"
00061 #include "mtk_enums.h"
00062 #include "mtk_tools.h"
00063
00064 #include "mtk_uni_stg_grid_1d.h"
00066 namespace mtk {
00068 std::ostream& operator <<(std::ostream &stream, mtk::UniStgGrid1D &in) {
        stream << '[' << in.west_bndy_x_ << ':' << in.num_cells_x_ << ':' <<
00071
       in.east_bndy_x_ << "] = " << std::endl << std::endl;
00072
00074
00075
        stream << "x:";
00076
        for (unsigned int ii = 0; ii < in.discrete_domain_x_.size(); ++ii) {</pre>
00077
         stream << std::setw(10) << in.discrete_domain_x_[ii];</pre>
00078
00079
        stream << std::endl;
00080
00082
00083
        if (in.nature == mtk::SCALAR) {
         stream << "u:";
00084
00085
00086
       else (
         stream << "v:";
00087
00088
```

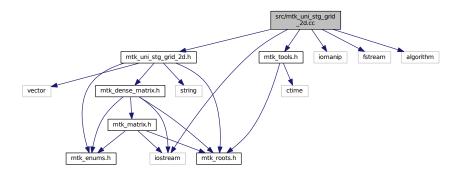
```
00089
        for (unsigned int ii = 0; ii < in.discrete_field_u_.size(); ++ii) {</pre>
00090
         stream << std::setw(10) << in.discrete_field_u_[ii];</pre>
00091
00092
00093
        stream << std::endl;</pre>
00094
00095
        return stream;
00096 }
00097 }
00099 mtk::UniStgGrid1D::UniStgGrid1D():
00100
         nature_(),
00101
          discrete_domain_x_(),
00102
          discrete_field_u_(),
00103
          west_bndy_x_(),
00104
         east_bndy_x_(),
00105
          num_cells_x_(),
00106
          delta_x_() {}
00107
00108 mtk::UniStgGrid1D::UniStgGrid1D(const
     UniStgGrid1D &grid):
00109
          nature (grid.nature ).
00110
          west_bndy_x_(grid.west_bndy_x_),
00111
          \verb| east_bndy_x_(grid.east_bndy_x_)|,
00112
          num_cells_x_(grid.num_cells_x_),
00113
          delta x (grid.delta x ) {
00114
00115
          std::copy(grid.discrete_domain_x_.begin(),
00116
                    grid.discrete_domain_x_.begin() + grid.
     discrete_domain_x_.size(),
00117
                    discrete_domain_x_.begin());
00118
          std::copy(grid.discrete_field_u_.begin(),
00119
00120
                    grid.discrete_field_u_.begin() + grid.
     discrete_field_u_.size(),
00121
                    discrete_field_u_.begin());
00122 }
00123
00124 mtk::UniStgGrid1D::UniStgGrid1D(const Real &west_bndy_x,
00125
                                       const Real &east_bndy_x,
00126
                                       const int &num_cells_x,
00127
                                       const mtk::FieldNature &nature) {
00128
00129
        #if MTK DEBUG LEVEL > 0
00130
       mtk::Tools::Prevent(west_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00131
        mtk::Tools::Prevent(east_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00132
        mtk::Tools::Prevent(east_bndy_x <= west_bndy_x, __FILE__, __LINE__, __func__);</pre>
00133
       mtk::Tools::Prevent(num_cells_x < 0, __FILE__, __LINE__, __func__);</pre>
00134
       #endif
00135
00136
        nature_ = nature;
        west_bndy_x_ = west_bndy_x;
east_bndy_x_ = east_bndy_x;
00137
00138
00139
        num_cells_x_ = num_cells_x;
00140
00141
        delta_x_ = (east_bndy_x - west_bndy_x)/((mtk::Real) num_cells_x);
00142 }
00143
00144 mtk::UniStgGrid1D::~UniStgGrid1D() {}
00145
00146 mtk::Real mtk::UniStgGrid1D::west_bndy_x() const {
00147
00148
        return west_bndy_x_;
00149 }
00150
00151 mtk::Real mtk::UniStgGrid1D::east_bndy_x() const {
00152
00153
       return east_bndy_x_;
00154 }
00155
00156 mtk::Real mtk::UniStgGrid1D::delta_x() const {
00157
00158
        return delta x :
00159 }
00160
00161 const mtk::Real *mtk::UniStqGrid1D::discrete_domain_x() const
00162
00163
        return discrete_domain_x_.data();
00164 }
00165
```

```
00166 mtk::Real *mtk::UniStgGrid1D::discrete_field_u() {
00167
00168
        return discrete_field_u_.data();
00169 }
00170
00171 int mtk::UniStgGrid1D::num_cells_x() const {
00172
00173
        return num_cells_x_;
00174 }
00175
00176 void mtk::UniStgGrid1D::BindScalarField(
00177
         mtk::Real (*ScalarField) (mtk::Real xx)) {
00178
00179
       #if MTK_DEBUG_LEVEL > 0
00180
       mtk::Tools::Prevent(nature_ == mtk::VECTOR, __FILE__, __LINE__, __func__);
00181
        #endif
00182
00184
00185
        discrete_domain_x_.reserve(num_cells_x_ + 2);
00186
00187
        discrete_domain_x_.push_back(west_bndy_x_);
00188
        #ifdef MTK_PRECISION_DOUBLE
00189
        auto first_center = west_bndy_x_ + delta_x_/2.0;
00190
        #else
00191
        auto first_center = west_bndy_x_ + delta_x_/2.0f;
00192
        #endif
        discrete_domain_x_.push_back(first_center);
for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00193
00194
00195
         discrete_domain_x_.push_back(first_center + ii*delta_x_);
00196
00197
        discrete_domain_x_.push_back(east_bndy_x_);
00198
00200
00201
        discrete_field_u_.reserve(num_cells_x_ + 2);
00202
00203
        discrete_field_u_.push_back(ScalarField(west_bndy_x_));
00204
00205
        discrete_field_u_.push_back(ScalarField(first_center));
00206
        for (auto ii = 1; ii < num_cells_x_; ++ii)</pre>
00207
         discrete_field_u_.push_back(ScalarField(first_center + ii*delta_x_));
00208
00209
        discrete_field_u_.push_back(ScalarField(east_bndy_x_));
00210 }
00211
00212 void mtk::UniStgGrid1D::BindVectorField(
00213
          mtk::Real (*VectorField) (mtk::Real xx)) {
00214
00215
        #if MTK_DEBUG_LEVEL > 0
00216
        mtk::Tools::Prevent(nature_ == mtk::SCALAR, __FILE__, __LINE__, __func__);
00217
        #endif
00218
00220
00221
        discrete_domain_x_.reserve(num_cells_x_ + 1);
00222
00223
        \label{local_discrete_domain_x_.push_back (west_bndy_x_);} \\
00224
        for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00225
         discrete_domain_x_.push_back(west_bndy_x_ + ii*delta_x_);
00226
00227
        discrete_domain_x_.push_back(east_bndy_x_);
00228
00230
00231
        discrete_field_u_.reserve(num_cells_x_ + 1);
00232
00233
        discrete_field_u_.push_back(VectorField(west_bndy_x_));
00234
        for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00235
          discrete_field_u_.push_back(VectorField(west_bndy_x_ + ii*delta_x_));
00236
00237
        discrete_field_u_.push_back(VectorField(east_bndy_x_));
00238 }
00239
00240 bool mtk::UniStgGrid1D::WriteToFile(std::string filename,
00241
                                            std::string space_name,
00242
                                            std::string field_name) const {
00243
00244
       std::ofstream output_dat_file; // Output file.
00245
00246
        output dat file.open(filename);
00247
00248
        if (!output_dat_file.is_open()) {
00249
          return false;
00250
```

17.85 src/mtk_uni_stg_grid_2d.cc File Reference

Implementation of a 2D uniform staggered grid.

```
#include <iostream>
#include <iomanip>
#include <fstream>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_uni_stg_grid_2d.h"
Include dependency graph for mtk_uni_stg_grid_2d.cc:
```



Namespaces

• mtk

Mimetic Methods Toolkit namespace.

Functions

• std::ostream & mtk::operator<< (std::ostream &stream, mtk::UniStgGrid2D &in)

17.85.1 Detailed Description

Implementation of a 2D uniform staggered grid.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_uni_stg_grid_2d.cc.

17.86 mtk_uni_stg_grid_2d.cc

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <iostream>
00057 #include <iomanip>
00058 #include <fstream>
00060 #include <algorithm>
00062 #include "mtk_tools.h"
00063 #include "mtk_uni_stg_grid_2d.h"
00064
00065 namespace mtk {
00066
00067 std::ostream& operator <<(std::ostream &stream, mtk::UniStgGrid2D &in) {
00068
00069
        stream << '[' << in.west_bndy_ << ':' << in.num_cells_x_ << ':' <<
00070
       in.east_bndy_ << "] x ";
00071
00072
        stream << '[' << in.south_bndy_ << ':' << in.num_cells_y_ << ':' <<
        in.north_bndy_ << "] = " << std::endl << std::endl;
00073
00074
00076
00077
        stream << "x:":
```

```
00078
        for (unsigned int ii = 0; ii < in.discrete_domain_x_.size(); ++ii) {</pre>
00079
         stream << std::setw(10) << in.discrete_domain_x_[ii];</pre>
00080
00081
        stream << std::endl;
00082
00083
        stream << "y:";
00084
        for (unsigned int ii = 0; ii < in.discrete_domain_y_.size(); ++ii) {</pre>
00085
         stream << std::setw(10) << in.discrete_domain_y_[ii];</pre>
00086
00087
        stream << std::endl;
00088
00090
00091
        if (in.nature_ == mtk::SCALAR) {
          stream << "u:" << std::endl;
00092
00093
          if (in.discrete_field_.size() > 0) {
00094
            for (int ii = 0; ii < in.num_cells_x_ + 2; ++ii) {</pre>
00095
              for (int jj = 0; jj < in.num_cells_y_ + 2; ++jj) {</pre>
                stream << std::setw(10) << in.discrete_field_[ii*in.
00096
      num_cells_y_ + jj];
00097
             }
00098
              stream << std::endl;
00099
            }
00100
00101
        } else {
00102
          int mm{in.num_cells_x_};
00103
00104
          int nn{in.num_cells_y_};
          int p_offset{nn*(mm + 1) - 1};
00105
00106
          stream << "p(x,y):" << std::endl;
00107
          for (int ii = 0; ii < nn; ++ii) {
  for (int jj = 0; jj < mm + 1; ++jj) {
00108
00109
00110
              stream << std::setw(10) << in.discrete_field_[ii*(mm + 1) + jj];</pre>
00111
00112
            stream << std::endl;
00113
00114
          stream << std::endl;
00115
          stream << "q(x,y):" << std::endl;
00116
          for (int ii = 0; ii < nn + 1; ++ii) {
00117
            for (int jj = 0; jj < mm; ++jj) {</pre>
00118
              stream << std::setw(10) <<
00119
00120
                in.discrete_field_[p_offset + ii*mm + jj];
00121
00122
            stream << std::endl;</pre>
00123
00124
          stream << std::endl;</pre>
00125
00126
        return stream;
00127
00128 }
00129 }
00130
00131 mtk::UniStgGrid2D::UniStgGrid2D():
00132
          discrete_domain_x_(),
00133
          discrete_domain_y_(),
00134
          discrete_field_(),
00135
          nature_(),
00136
          west_bndy_(),
00137
          east_bndy_(),
00138
          num_cells_x_(),
00139
          delta_x_(),
00140
          south_bndy_(),
00141
          north_bndy_(),
          num_cells_y_(),
00142
00143
          delta_y_() {}
00145 mtk::UniStgGrid2D::UniStgGrid2D(const
     UniStgGrid2D &grid):
00146
          nature_(grid.nature_),
00147
          west_bndy_(grid.west_bndy_),
00148
          east_bndy_(grid.east_bndy_),
00149
          num cells x (grid.num cells x ),
00150
          delta x (grid.delta x ),
00151
          south_bndy_(grid.south_bndy_),
00152
          north_bndy_(grid.north_bndy_),
          num_cells_y_(grid.num_cells_y_),
00153
00154
          delta_y_(grid.delta_y_) {
00155
00156
          std::copy(grid.discrete_domain_x_.begin(),
                     grid.discrete_domain_x_.begin() + grid.
00157
```

```
discrete_domain_x_.size(),
00158
                      discrete_domain_x_.begin());
00159
00160
           std::copy(grid.discrete_domain_y_.begin(),
                      grid.discrete_domain_y_.begin() + grid.
00161
      discrete_domain_y_.size(),
00162
                     discrete_domain_y_.begin());
00163
00164
           std::copy(grid.discrete_field_.begin(),
                      grid.discrete_field_.begin() + grid.discrete_field_.size(),
00165
00166
                      discrete_field_.begin());
00167 }
00168
00169 mtk::UniStgGrid2D::UniStgGrid2D(const Real &west_bndy,
                                           const Real &east_bndy,
00171
                                           const int &num_cells_x,
00172
                                           const Real &south_bndy,
00173
                                           const Real &north_bndy,
00174
                                           const int &num_cells_y,
00175
                                           const mtk::FieldNature &nature) {
00176
00177
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(west_bndy < mtk::kZero, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(east_bndy < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00178
00179
00180
        mtk::Tools::Prevent(east_bndy <= west_bndy, __FILE__, __LINE__, _</pre>
                                                                                   func__);
        mtk::Tools::Prevent(num_cells_x < 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(south_bndy < mtk::kZero, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(north_bndy < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00181
00182
00183
00184
        mtk::Tools::Prevent(north_bndy <= south_bndy,</pre>
        __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(num_cells_y < 0, __FILE__, __LINE__, __func__);
00185
00186
00187
         #endif
00188
00189
         nature_ = nature;
00190
        west_bndy_ = west_bndy;
00191
         east_bndy_ = east_bndy;
00192
00193
         num_cells_x_ = num_cells_x;
00194
00195
         south_bndy_ = south_bndy;
        north_bndy_ = north_bndy;
00196
00197
         num_cells_y_ = num_cells_y;
00198
00199
         delta_x_ = (east_bndy_ - west_bndy_)/((mtk::Real) num_cells_x);
        delta_y_ = (north_bndy_ - south_bndy_)/((mtk::Real) num_cells_y);
00200
00201 }
00202
00203 mtk::UniStgGrid2D::~UniStgGrid2D() {}
00204
00205 mtk::FieldNature mtk::UniStgGrid2D::nature() const {
00206
00207
         return nature_;
00208 }
00209
00210 mtk::Real mtk::UniStgGrid2D::west_bndy() const {
00211
00212
         return west_bndy_;
00213 }
00214
00215 mtk::Real mtk::UniStgGrid2D::east_bndy() const {
00216
00217
        return east_bndy_;
00218 }
00219
00220 int mtk::UniStgGrid2D::num_cells_x() const {
         return num_cells_x_;
00223 }
00224
00225 mtk::Real mtk::UniStgGrid2D::delta_x() const {
00226
00227
         return delta x ;
00228 }
00229
00230 const mtk::Real* mtk::UniStqGrid2D::discrete_domain_x() const
00231
00232
        return discrete domain x .data();
00233 }
00234
00235 mtk::Real mtk::UniStqGrid2D::south bndv() const {
```

```
00236
00237
        return south_bndy_;
00238 }
00239
00240 mtk::Real mtk::UniStgGrid2D::north_bndy() const {
00241
00242
        return north_bndy_;
00243 }
00244
00245 int mtk::UniStgGrid2D::num_cells_y() const {
00246
00247
        return num_cells_y_;
00248 }
00249
00250 mtk::Real mtk::UniStgGrid2D::delta_y() const {
00252
        return delta v :
00253 }
00254
00255 bool mtk::UniStgGrid2D::Bound() const {
00256
00257
        return discrete field .size() != 0;
00258 }
00259
00260 const mtk::Real* mtk::UniStgGrid2D::discrete domain v() const
00261
00262
        return discrete_domain_y_.data();
00263 }
00264
00265 mtk::Real* mtk::UniStqGrid2D::discrete field() {
00266
00267
        return discrete_field_.data();
00268 }
00269
00270 void mtk::UniStgGrid2D::BindScalarField(Real (*ScalarField)(
     Real xx, Real yy)) {
00271
00272
        #if MTK DEBUG LEVEL > 0
00273
        mtk::Tools::Prevent(nature_ != mtk::SCALAR, __FILE__, __LINE__, __func__);
00274
        #endif
00275
00277
00278
        discrete_domain_x_.reserve(num_cells_x_ + 2);
00279
00280
        discrete_domain_x_.push_back(west_bndy_);
00281
        #ifdef MTK_PRECISION_DOUBLE
00282
        auto first_center = west_bndy_ + delta_x_/2.0;
00283
        #else
00284
        auto first_center = west_bndy_ + delta_x_/2.0f;
00285
        #endif
00286
        discrete_domain_x_.push_back(first_center);
00287
        for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00288
          discrete_domain_x_.push_back(first_center + ii*delta_x_);
00289
00290
        discrete_domain_x_.push_back(east_bndy_);
00291
00293
00294
        discrete_domain_y_.reserve(num_cells_y_ + 2);
00295
00296
        discrete_domain_y_.push_back(south_bndy_);
00297
        #ifdef MTK_PRECISION_DOUBLE
00298
        first_center = south_bndy_ + delta_x_/2.0;
00299
        #else
00300
        first_center = south_bndy_ + delta_x_/2.0f;
00301
        #endif
        discrete_domain_y_.push_back(first_center);
for (auto ii = 1; ii < num_cells_y_; ++ii) {</pre>
00302
00303
00304
          discrete_domain_y_.push_back(first_center + ii*delta_y_);
00305
00306
        discrete domain v .push back(north bndv );
00307
00309
00310
        discrete field .reserve((num cells x + 2)*(num cells y + 2));
00311
00312
        for (int ii = 0; ii < num_cells_y_ + 2; ++ii) {</pre>
          for (int jj = 0; jj < num_cells_x_ + 2; ++jj) {
   #if MTK_DEBUG_LEVEL > 0
00313
00314
            std::cout << "Pushing value for x = " << discrete_domain_x_[jj] <<
00315
               " y = " << discrete_domain_y_[ii] << std::endl;</pre>
00316
00317
            #endif
```

```
00318
            discrete_field_.push_back(ScalarField(discrete_domain_x_[jj],
00319
                                                     discrete_domain_y_[ii]));
00320
00321
00322 }
00323
00324 void mtk::UniStgGrid2D::BindVectorFieldPComponent(
00325
       mtk::Real (*VectorField) (mtk::Real xx, mtk::Real yy)) {
00326
00327
        int mm{num_cells_x_};
00328
        int nn{num_cells_y_};
00329
00330
        int total{nn*(mm + 1) + mm*(nn + 1)};
00331
00332
        #ifdef MTK_PRECISION_DOUBLE
00333
        double half_delta_x{delta_x_/2.0};
00334
        double half_delta_y{delta_y_/2.0};
00335
        #else
00336
        float half_delta_x{delta_x_/2.0f};
00337
        float half_delta_y{delta_y_/2.0f};
00338
        #endif
00339
00341
00342
        // We need every data point of the discrete domain; i.e. we need all the
00343
        // nodes and all the centers. There are mm centers for the x direction, and
00344
        // nn centers for the y direction. Since there is one node per center, that
        // amounts to 2*mm. If we finally consider the final boundary node, it // amounts to a total of 2*mm+1 for the x direction. Analogously, for the
00345
00346
00347
        // y direction, this amounts to 2*nn + 1.
00348
00349
        discrete_domain_x_.reserve(2*mm + 1);
00350
00351
        discrete_domain_x_.push_back(west_bndy_);
00352
        for (int ii = 1; ii < (2*mm + 1); ++ii) {
00353
          discrete_domain_x_.push_back(west_bndy_ + ii*half_delta_x);
00354
00355
00357
00358
        discrete_domain_y_.reserve(2*nn + 1);
00359
00360
        discrete_domain_y_.push_back(south_bndy_);
00361
        for (int ii = 1; ii < (2*nn + 1); ++ii) {
00362
          discrete_domain_y_.push_back(south_bndy_ + ii*half_delta_y);
00363
00364
00366
00367
        discrete_field_.reserve(total);
00368
        // For each y-center.
00369
00370
        for (int ii = 1; ii < 2*nn + 1; ii += 2) {
00371
00372
          // Bind all of the x-nodes for this y-center.
00373
          for (int jj = 0; jj < 2*mm + 1; jj += 2) {
00374
            discrete_field_.push_back(VectorField(discrete_domain_x_[jj],
00375
                                                     discrete_domain_y_[ii]));
00376
00377
            #if MTK_DEBUG_LEVEL > 0
00378
            std::cout << "Binding v at x = " << discrete_domain_x_[jj] << " y = " <<
               discrete_domain_y_[ii] << " = " <<
00379
00380
              VectorField(discrete_domain_x_[jj], discrete_domain_y_[ii]) << std::endl;</pre>
00381
             #endif
00382
00383
00384
        #if MTK_DEBUG_LEVEL > 0
00385
        std::cout << std::endl;
00386
        #endif
00387 }
00388
00389 void mtk::UniStgGrid2D::BindVectorFieldQComponent(
00390
        mtk::Real (*VectorField) (mtk::Real xx, mtk::Real yy)) {
00391
00392
        int mm{num cells x };
00393
        int nn{num cells v };
00394
00396
        // For each y-node.
for (int ii = 0; ii < 2*nn + 1; ii += 2) {
00397
00398
00399
00400
          // Bind all of the x-center for this y-node.
00401
          for (int jj = 1; jj < 2*mm + 1; jj += 2) {
            discrete_field_.push_back(VectorField(discrete_domain_x_[jj],
00402
```

```
00403
                                                                                              discrete_domain_y_[ii]));
00404
00405
                      #if MTK_DEBUG_LEVEL > 0
                      std::cout << "Binding v at x = " << discrete_domain_x_[jj] << " y = " <<
00406
                          \label{eq:discrete_domain_y_[ii]} \begin{tabular}{ll} \begin{tab
00407
00408
                          VectorField(discrete_domain_x_[jj], discrete_domain_y_[ii]) << std::endl;</pre>
00409
00410
00411
              #if MTK_DEBUG_LEVEL > 0
00412
00413
               std::cout << std::endl;
00414
               #endif
00415 }
00416
00417 void mtk::UniStgGrid2D::BindVectorField(
00418
             Real (*VectorFieldPComponent) (Real xx, Real yy),
00419
              Real (*VectorFieldQComponent) (Real xx, Real yy)) {
00420
00421
               #if MTK_DEBUG_LEVEL > 0
00422
              mtk::Tools::Prevent(nature_ != mtk::VECTOR, __FILE__, __LINE__, __func__);
00423
              #endif
00424
00425
               BindVectorFieldPComponent(VectorFieldPComponent);
00426
              BindVectorFieldQComponent(VectorFieldQComponent);
00427 }
00428
00429 bool mtk::UniStqGrid2D::WriteToFile(std::string filename,
00430
                                                                               std::string space_name_x,
00431
                                                                               std::string space_name_y,
00432
                                                                               std::string field_name) const {
00433
00434
              std::ofstream output_dat_file; // Output file.
00435
00436
              output_dat_file.open(filename);
00437
00438
              if (!output_dat_file.is_open()) {
00439
                return false;
00440
00441
              if (nature_ == mtk::SCALAR) {
00442
               output_dat_file << "# " << space_name_x << ' ' << space_name_y << ' ' <<
00443
00444
                     field_name << std::endl;
00445
00446
                  int idx{};
00447
                 for (unsigned int ii = 0; ii < discrete_domain_y_.size(); ++ii) {</pre>
00448
                      for (unsigned int jj = 0; jj < discrete_domain_x_.size(); ++jj) {</pre>
00449
                          output_dat_file << discrete_domain_x_[jj] << ^{\prime} ^{\prime} <<
                                                              discrete_domain_y_[ii] << ' ' <<
00450
00451
                                                              discrete_field_[idx] <<
00452
                                                            std::endl;
00453
                         idx++;
00454
00455
                      output_dat_file << std::endl;</pre>
00456
00457
               } else {
00458
                  output_dat_file << "# " << space_name_x << ' ' << space_name_y << ' ' <<</pre>
00459
                     field_name << std::endl;
00460
00461
                  output_dat_file << "# Horizontal component:" << std::endl;</pre>
00462
00463
                  int mm{num_cells_x_};
00464
                  int nn{num_cells_y_};
00465
00467
00468
                  // For each y-center.
                   int idx{};
00470
                  for (int ii = 1; ii < 2*nn + 1; ii += 2) {
00471
                      // Bind all of the x-nodes for this y-center.
00472
                      for (int jj = 0; jj < 2*mm + 1; jj += 2) {
00473
                          output_dat_file << discrete_domain_x_[jj] << ' ' <<</pre>
00474
00475
                             discrete_domain_y_[ii] << ' ' << discrete_field_[idx] << ' ' <<
00476
                             mtk::kZero << std::endl;</pre>
00477
00478
                          ++idx;
00479
                     }
00480
00481
00483
                   int p_offset\{nn*(mm + 1) - 1\};
00484
                   idx = 0:
                  output_dat_file << "# Vertical component:" << std::endl;</pre>
00485
```

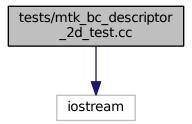
```
00486
             // For each y-node.
00487
            for (int ii = 0; ii < 2*nn + 1; ii += 2) {
00488
               // Bind all of the x-center for this y-node.
00489
              for (int jj = 1; jj < 2*mm + 1; jj += 2) {
00490
                  output_dat_file << discrete_domain_x_[jj] << ' ' <<
    discrete_domain_y_[ii] << ' ' << mtk::kZero << ' ' <<
    discrete_field_[p_offset + idx] << std::endl;</pre>
00491
00492
00493
00494
00495
                  ++idx;
00496
00497
           }
00498
00499
00500
          output_dat_file.close();
00502
          return true;
00503 }
```

17.87 tests/mtk_bc_descriptor_2d_test.cc File Reference

Test file for the mtk::BCDescriptor2D class.

```
#include <iostream>
```

Include dependency graph for mtk_bc_descriptor_2d_test.cc:



Functions

• int main ()

17.87.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_bc_descriptor_2d_test.cc.

17.87.2 Function Documentation

```
17.87.2.1 int main ( )
```

Definition at line 196 of file mtk bc descriptor 2d test.cc.

17.88 mtk_bc_descriptor_2d_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00056 #include <cmath>
00057 #include <ctime>
00058
00059 #include <iostream>
00060
00061 #include "mtk.h"
00062
00063 void TestDefaultConstructorGetters() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
00067
       mtk::BCDescriptor2D bcd;
00068
00069
       bool assertion{true};
00070
00071
        assertion = assertion && bcd.highest_order_diff_west() == -1;
00072
        assertion = assertion && bcd.highest_order_diff_east() == -1;
00073
        assertion = assertion && bcd.highest order diff south() == -1;
00074
        assertion = assertion && bcd.highest_order_diff_north() == -1;
00075
00076
       mtk::Tools::EndUnitTestNo(1):
```

```
00077
       mtk::Tools::Assert(assertion);
00078 }
00079
00080 mtk::Real cc(const mtk::Real &xx, const mtk::Real &yy) {
00081
00082
        return mtk::kOne:
00083 }
00084
00085 void TestPushBackImposeOnLaplacianMatrix() {
00087
        mtk::Tools::BeginUnitTestNo(2);
00088
00089
       mtk::BCDescriptor2D bcd;
00090
00091
       bool assertion{true};
00092
00093
       bcd.PushBackWestCoeff(cc);
00094
       bcd.PushBackEastCoeff(cc);
00095
        bcd.PushBackSouthCoeff(cc);
00096
       bcd.PushBackNorthCoeff(cc);
00097
00098
       assertion = assertion && bcd.highest_order_diff_west() == 0;
00099
       assertion = assertion && bcd.highest_order_diff_east() == 0;
00100
       assertion = assertion && bcd.highest_order_diff_south() == 0;
00101
       assertion = assertion && bcd.highest_order_diff_north() == 0;
00102
00103
       mtk::Real aa = 0.0;
       mtk::Real bb = 1.0;
00104
00105
       mtk::Real cc = 0.0:
       mtk::Real dd = 1.0;
00106
00107
00108
        int nn = 5:
00109
        int mm = 5:
00110
       mtk::UniStgGrid2D llg(aa, bb, nn, cc, dd, mm);
00111
00112
00113
       mtk::Lap2D 11;
00114
00115
        assertion = 11.ConstructLap2D(11g);
00116
00117
        if (!assertion) {
         std::cerr << "Mimetic lap (2nd order) could not be built." << std::endl;</pre>
00118
        }
00119
00120
00121
        mtk::DenseMatrix llm(ll.ReturnAsDenseMatrix());
00122
00123
        assertion = assertion && (llm.num_rows() != 0);
00124
00125
        bcd.ImposeOnLaplacianMatrix(llg, llm);
00126
00127
        assertion = assertion && llm.WriteToFile("mtk_bc_descriptor_2d_test_02.dat");
00128
00129
        mtk::Tools::EndUnitTestNo(2);
00130
       mtk::Tools::Assert(assertion);
00131 }
00132
00133 mtk::Real ScalarField(mtk::Real xx, mtk::Real yy) {
00134
00135
       mtk::Real aux{-(1.0/2.0)*xx*xx - (1.0/2.0)*yy*yy};
00136
00137
        return xx*yy*exp(aux);
00138 }
00139
00140 mtk::Real HomogeneousDiricheletBC(mtk::Real xx, mtk::Real yy) {
00141
00142
        return mtk::kZero;
00143 }
00144
00145 void TestImposeOnGrid() {
00146
00147
       mtk::Tools::BeginUnitTestNo(3);
00148
00149
       mtk::Real aa = 0.0;
00150
       mtk::Real bb = 1.0;
00151
       mtk::Real cc = 0.0;
00152
       mtk::Real dd = 1.0:
00153
00154
        int nn = 5;
00155
        int mm = 5;
00156
       mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm);
00157
```

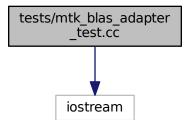
```
00158
00159
        gg.BindScalarField(ScalarField);
00160
        mtk::BCDescriptor2D desc;
00161
00162
00163
        desc.set_west_condition(HomogeneousDiricheletBC);
00164
        desc.set_east_condition(HomogeneousDiricheletBC);
00165
        desc.set_south_condition(HomogeneousDiricheletBC);
00166
        desc.set_north_condition(HomogeneousDiricheletBC);
00167
00168
        desc.ImposeOnGrid(gg);
00169
00170
        bool assertion {gg.WriteToFile("mtk_bc_descriptor_2d_test_03.dat",
00171
00172
00173
                                        "u(x,y)")};
00174
00175
        if(!assertion) {
00176
          std::cerr << "Error writing to file." << std::endl;
00177
00178
00179
        mtk::Tools::EndUnitTestNo(3);
00180
       mtk::Tools::Assert(assertion);
00181 }
00182
00183 int main () {
00184
        std::cout << "Testing mtk::BCDescriptor2D class." << std::endl;</pre>
00185
00186
        TestDefaultConstructorGetters();
00187
00188
        TestPushBackImposeOnLaplacianMatrix();
00189
        TestImposeOnGrid();
00190 }
00191
00192 #else
00193 #include <iostream>
00194 using std::cout;
00195 using std::endl;
00196 int main () { 00197 \,\, cout << "This code HAS to be compiled with support for C++11." << endl;
00198
       cout << "Exiting..." << endl;</pre>
00199 }
00200 #endif
```

17.89 tests/mtk_blas_adapter_test.cc File Reference

Test file for the mtk::BLASAdapter class.

#include <iostream>

Include dependency graph for mtk_blas_adapter_test.cc:



Functions

• int main ()

17.89.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk blas adapter test.cc.

17.89.2 Function Documentation

```
17.89.2.1 int main ( )
```

Definition at line 109 of file mtk_blas_adapter_test.cc.

17.90 mtk_blas_adapter_test.cc

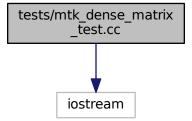
```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
```

```
00054 #if __cplusplus == 201103L
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void TestRealDenseMM() {
00061
00062
       mtk::Tools::BeginUnitTestNo(1);
00063
00064
        int rr = 2;
00065
       int cc = 3;
00066
00067
       mtk::DenseMatrix aa(rr,cc);
00068
00069
       aa.SetValue(0,0,1.0);
00070
       aa.SetValue(0,1,2.0);
00071
       aa.SetValue(0,2,3.0);
00072
       aa.SetValue(1,0,4.0);
00073
       aa.SetValue(1,1,5.0);
00074
       aa.SetValue(1,2,6.0);
00075
00076
       mtk::DenseMatrix bb(cc,rr);
00077
00078
       bb.SetValue(0,0,7.0);
00079
       bb.SetValue(0,1,8.0);
00080
       bb.SetValue(1,0,9.0);
       bb.SetValue(1,1,10.0);
00081
00082
       bb.SetValue(2,0,11.0);
00083
       bb.SetValue(2,1,12.0);
00084
00085
       mtk::DenseMatrix pp = mtk::BLASAdapter::RealDenseMM(aa,bb);
00086
00087
       mtk::DenseMatrix ff(rr,rr);
00088
00089
       ff.SetValue(0,0,58.0);
00090
        ff.SetValue(0,1,64.00);
00091
        ff.SetValue(1,0,139.0);
00092
       ff.SetValue(1,1,154.0);
00093
00094
       mtk::Tools::EndUnitTestNo(1);
00095
       mtk::Tools::Assert(pp == ff);
00096 }
00097
00098 int main () {
00099
00100
        std::cout << "Testing mtk::BLASAdapter class." << std::endl;</pre>
00101
00102
       TestRealDenseMM();
00103 }
00104
00105 #else
00106 #include <iostream>
00107 using std::cout;
00108 using std::endl;
00109 int main () {
00110 cout << "This code HAS to be compiled with support for C++11." << endl;
00111
       cout << "Exiting..." << endl;</pre>
00112 }
00113 #endif
```

17.91 tests/mtk dense matrix test.cc File Reference

Test file for the mtk::DenseMatrix class.

#include <iostream>
Include dependency graph for mtk dense matrix test.cc:



Functions

• int main ()

17.91.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_dense_matrix_test.cc.

17.91.2 Function Documentation

```
17.91.2.1 int main ( )
```

Definition at line 330 of file mtk_dense_matrix_test.cc.

17.92 mtk_dense_matrix_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
```

```
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057 #include <ctime>
00058
00059 #include "mtk.h"
00060
00061 void TestDefaultConstructor() {
00062
       mtk::Tools::BeginUnitTestNo(1);
00063
00064
00065
       mtk::DenseMatrix ml;
00066
00067
       mtk::Tools::EndUnitTestNo(1);
00068
       mtk::Tools::Assert(m1.data() == nullptr);
00069 }
00070
00071 void TestConstructorWithNumRowsNumCols() {
00072
00073
       mtk::Tools::BeginUnitTestNo(2);
00074
00075
        int rr = 4;
00076
       int cc = 7;
00077
00078
       mtk::DenseMatrix m2(rr,cc);
00079
08000
       mtk::Tools::EndUnitTestNo(2);
00081
00082
00083
         m2.data() != nullptr && m2.num_rows() == rr && m2.num_cols() == cc;
00084
00085
       mtk::Tools::Assert(assertion);
00086 }
00087
00088 void TestConstructAsIdentity() {
00089
00090
       mtk::Tools::BeginUnitTestNo(3);
00091
00092
        int rank = 5;
00093
        bool padded = true;
00094
       bool transpose = false;
00095
00096
        mtk::DenseMatrix m3(rank.padded.transpose);
00097
00098
       mtk::DenseMatrix rr(rank + 2, rank);
00099
        for (int ii = 0; ii < rank; ++ii) {</pre>
00100
00101
         rr.SetValue(ii + 1, ii, mtk::kOne);
00102
00103
       mtk::Tools::EndUnitTestNo(3);
00104
```

```
00105
       mtk::Tools::Assert(m3 == rr);
00106 }
00107
        void TestConstructAsVandermonde() {
00108
00109
00110
        mtk::Tools::BeginUnitTestNo(4);
00111
00112
        int rank = 5;
00113
        bool padded = false;
00114
        bool transpose = false;
00115
00116
        mtk::DenseMatrix m4(rank,padded,transpose);
00117
00118
       mtk::DenseMatrix rr(rank, rank);
00119
00120
        for (int ii = 0; ii < rank; ++ii) {</pre>
00121
         rr.SetValue(ii, ii, mtk::kOne);
00122
00123
00124
       mtk::Tools::EndUnitTestNo(4);
00125
       mtk::Tools::Assert (m4 == rr);
00126 }
00127
00128 void TestSetValueGetValue() {
00129
       mtk::Tools::BeginUnitTestNo(5);
00130
00131
        int rr = 4;
00132
00133
        int cc = 7;
00134
00135
        mtk::DenseMatrix m5(rr.cc):
00136
00137
        for (auto ii = 0; ii < rr; ++ii) {</pre>
         for (auto jj = 0; jj < cc; ++jj) {</pre>
00138
           m5.SetValue(ii, jj, (mtk::Real) ii + jj);
00139
00140
00141
        }
00142
00143
        mtk::Real *vals = m5.data();
00144
00145
        bool assertion{true};
00146
00147
        for (auto ii = 0; ii < rr && assertion; ++ii) {</pre>
00148
          for (auto jj = 0; jj < cc && assertion; ++jj) {</pre>
00149
            assertion = assertion && m5.GetValue(ii,jj) == vals[ii*cc + jj];
00150
00151
00152
00153
        mtk::Tools::EndUnitTestNo(5);
00154
        mtk::Tools::Assert(assertion);
00155 }
00156
00157 void TestConstructAsVandermondeTranspose() {
00158
00159
       mtk::Tools::BeginUnitTestNo(6);
00160
        bool transpose = false;
00161
00162
        int generator_length = 3;
00163
        int progression_length = 4;
00164
00165
        mtk::Real generator[] = {-0.5, 0.5, 1.5};
00166
00167
        mtk::DenseMatrix m6(generator, generator_length, progression_length, transpose);
00168
00169
        transpose = true;
00170
00171
        mtk::DenseMatrix m7(generator,generator_length,progression_length,transpose);
00172
        mtk::DenseMatrix rr(progression_length, generator_length);
00173
00174
        rr.SetValue(0, 0, 1.0);
00175
       rr.SetValue(0, 1, 1.0);
00176
       rr.SetValue(0, 2, 1.0);
00177
00178
        rr.SetValue(1, 0, -0.5);
00179
       rr.SetValue(1, 1, 0.5);
00180
       rr.SetValue(1, 2, 1.5);
00181
00182
        rr.SetValue(2, 0, 0.25);
00183
        rr.SetValue(2, 1, 0.25);
00184
        rr.SetValue(2, 2, 2.25);
00185
```

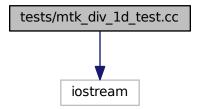
```
00186
        rr.SetValue(3, 0, -0.125);
00187
       rr.SetValue(3, 1, 0.125);
00188
        rr.SetValue(3, 2, 3.375);
00189
00190
        mtk::Tools::EndUnitTestNo(6);
00191
        mtk::Tools::Assert(m7 == rr);
00192 }
00193
00194 void TestKron() {
00195
00196
        mtk::Tools::BeginUnitTestNo(7);
00197
00198
        bool padded = false;
00199
        bool transpose = false;
00200
        int lots_of_rows = 2;
00201
        int lots_of_cols = 5;
00202
        mtk::DenseMatrix m8(lots_of_rows, padded, transpose);
00203
00204
        mtk::DenseMatrix m9(lots_of_rows,lots_of_cols);
00205
00206
        for (auto ii = 0; ii < lots_of_rows; ++ii) {</pre>
00207
         for (auto jj = 0; jj < lots_of_cols; ++jj) {</pre>
00208
            m9.SetValue(ii,jj,(mtk::Real) ii*lots_of_cols + jj + 1);
00209
00210
00211
00212
        mtk::DenseMatrix m10 = mtk::DenseMatrix::Kron(m8,m9);
00213
00214
        mtk::DenseMatrix rr(lots_of_rows*lots_of_rows, lots_of_rows*lots_of_cols);
00215
00216
        rr.Set.Value(0.0.1.0):
00217
        rr.SetValue(0,1,2.0);
00218
        rr.SetValue(0,2,3.0);
00219
        rr.SetValue(0,3,4.0);
00220
        rr.SetValue(0,4,5.0);
00221
        rr.SetValue(0,5,0.0);
00222
        rr.SetValue(0,6,0.0);
00223
        rr.SetValue(0,7,0.0);
00224
        rr.SetValue(0,8,0.0);
00225
        rr.SetValue(0,9,0.0);
00226
00227
        rr.SetValue(1,0,6.0);
00228
        rr.SetValue(1,1,7.0);
00229
        rr.SetValue(1,2,8.0);
00230
        rr.SetValue(1,3,9.0);
00231
        rr.SetValue(1,4,10.0);
00232
        rr.SetValue(1,5,0.0);
00233
        rr.SetValue(1,6,0.0);
00234
        rr.SetValue(1,7,0.0);
00235
        rr.SetValue(1,8,0.0);
00236
       rr.SetValue(1,9,0.0);
00237
00238
       rr.SetValue(2,0,0.0);
00239
        rr.SetValue(2,1,0.0);
00240
       rr.SetValue(2,2,0.0);
00241
        rr.SetValue(2,3,0.0);
00242
        rr.SetValue(2,4,0.0);
00243
        rr.SetValue(2,5,1.0);
00244
        rr.SetValue(2,6,2.0);
00245
        rr.SetValue(2,7,3.0);
00246
        rr.SetValue(2,8,4.0);
00247
        rr.SetValue(2,9,5.0);
00248
00249
        rr.SetValue(3,0,0.0);
00250
       rr.SetValue(3,1,0.0);
00251
        rr.SetValue(3,2,0.0);
00252
       rr.SetValue(3,3,0.0);
00253
        rr.SetValue(3,4,0.0);
00254
       rr.SetValue(3,5,6.0);
00255
        rr.SetValue(3,6,7.0);
00256
       rr.SetValue(3,7,8.0);
00257
        rr.SetValue(3,8,9.0);
00258
        rr.SetValue(3,9,10.0);
00259
00260
        mtk::Tools::EndUnitTestNo(7);
00261
       mtk::Tools::Assert(m10 == rr);
00262 }
00263
00264 void TestConstructWithNumRowsNumColsAssignmentOperator() {
00265
00266
       mtk::Tools::BeginUnitTestNo(8);
```

```
00267
00268
        int lots_of_rows = 4;
        int lots_of_cols = 3;
       mtk::DenseMatrix m11(lots_of_rows,lots_of_cols);
00270
00271
00272
        for (auto ii = 0; ii < lots_of_rows; ++ii) {</pre>
00273
         for (auto jj = 0; jj < lots_of_cols; ++jj) {</pre>
00274
            m11.SetValue(ii, jj, (mtk::Real) ii*lots_of_cols + jj + 1);
00275
00276
        }
00277
00278
       m11.Transpose();
00279
       mtk::DenseMatrix m12;
00281
00282
       m12 = m11;
00283
00284
       mtk::Tools::EndUnitTestNo(8);
00285
       mtk::Tools::Assert(m11 == m12);
00286 }
00287
00288 void TestConstructAsVandermondeTransposeAssignmentOperator() {
00289
00290
        mtk::Tools::BeginUnitTestNo(9);
00291
00292
        bool transpose = false;
00293
        int qq_1 = 3;
        int progression_length = 4;
00294
00295
        mtk::Real gg[] = {-0.5, 0.5, 1.5};
00296
00297
        mtk::DenseMatrix m13(gg, gg_1 ,progression_length, transpose);
00298
00299
       mtk::DenseMatrix m14;
00300
00301
       m14 = m13:
00302
00303
       m13.Transpose();
00304
00305
       m14 = m13;
00306
00307
        mtk::Tools::EndUnitTestNo(9);
00308
       mtk::Tools::Assert(m13 == m14);
00309 }
00310
00311 int main () {
00312
00313
        std::cout << "Testing mtk::DenseMatrix class." << std::endl;</pre>
00314
00315
       TestDefaultConstructor();
00316
        TestConstructorWithNumRowsNumCols();
00317
       TestConstructAsIdentity();
00318
       TestConstructAsVandermonde();
00319
       TestSetValueGetValue();
00320
        TestConstructAsVandermondeTranspose();
00321
       TestKron();
00322
       TestConstructWithNumRowsNumColsAssignmentOperator();
00323
       TestConstructAsVandermondeTransposeAssignmentOperator();
00324 }
00325
00326 #else
00327 #include <iostream>
00328 using std::cout;
00329 using std::endl;
00330 int main () { 00331 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00333 }
00334 #endif
```

17.93 tests/mtk_div_1d_test.cc File Reference

Testing the mimetic 1D divergence, constructed with the CBS algorithm.

#include <iostream>
Include dependency graph for mtk div 1d test.cc:



Functions

• int main ()

17.93.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_div_1d_test.cc.

17.93.2 Function Documentation

```
17.93.2.1 int main ( )
```

Definition at line 288 of file mtk_div_1d_test.cc.

17.94 mtk_div_1d_test.cc

```
00001 /*
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State 00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification, 00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu 00016 and a copy of the modified files should be reported once modifications are 00017 completed, unless these modifications are made through the project's GitHub 00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications 0019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct 00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk 00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
```

```
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT 00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void TestDefaultConstructorFactoryMethodDefault() {
00061
00062
        mtk::Tools::BeginUnitTestNo(1);
00063
       mtk::Div1D div2;
00064
00065
00066
        bool assertion = div2.ConstructDiv1D();
00067
00068
        if (!assertion) {
00069
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00070
00071
00072
        mtk::Tools::EndUnitTestNo(1);
00073
        mtk::Tools::Assert(assertion);
00074 }
00075
00076 void TestDefaultConstructorFactoryMethodFourthOrder() {
00077
00078
        mtk::Tools::BeginUnitTestNo(2);
00079
00080
        mtk::Div1D div4;
00081
00082
        bool assertion = div4.ConstructDiv1D(4);
00083
00084
        if (!assertion)
         std::cerr << "Mimetic div (4th order) could not be built." << std::endl;
00085
00086
00087
00088
        mtk::Tools::EndUnitTestNo(2);
00089
        mtk::Tools::Assert(assertion);
00090 }
00091
00092 void TestDefaultConstructorFactoryMethodSixthOrder() {
00093
00094
        mtk::Tools::BeginUnitTestNo(3);
00095
00096
        mtk::Div1D div6;
00097
00098
        bool assertion = div6.ConstructDiv1D(6);
00099
00100
        if (!assertion) {
         std::cerr << "Mimetic div (6th order) could not be built." << std::endl;
00101
00102
00103
00104
        mtk::Tools::EndUnitTestNo(3):
00105
        mtk::Tools::Assert(assertion);
```

```
00106 }
00107
00108 void TestDefaultConstructorFactoryMethodEightOrderDefThreshold() {
00109
00110
       mtk::Tools::BeginUnitTestNo(4);
00111
00112
       mtk::Div1D div8;
00113
00114
       bool assertion = div8.ConstructDiv1D(8);
00115
00116
       if (!assertion)
00117
         std::cerr << "Mimetic div (8th order) could not be built." << std::endl;
00118
00119
00120
       mtk::Tools::EndUnitTestNo(4);
00121
       mtk::Tools::Assert(assertion);
00122 }
00123
00124 void TestDefaultConstructorFactoryMethodTenthOrderDefThreshold() {
00125
00126
       mtk::Tools::BeginUnitTestNo(5);
00127
00128
       mtk::Div1D div10;
00129
00130
       bool assertion = div10.ConstructDiv1D(10);
00131
00132
       if (!assertion) {
         std::cerr << "Mimetic div (10th order) could not be built." << std::endl;
00133
00134
00135
00136
       mtk::Tools::EndUnitTestNo(5);
00137
       mtk::Tools::Assert (assertion);
00138 }
00139
00140 void TestDefaultConstructorFactoryMethodTwelfthOrderDefThreshold() {
0.0141
00142
       mtk::Tools::BeginUnitTestNo(6);
00143
00144
       mtk::Div1D div12;
00145
00146
       bool assertion = div12.ConstructDiv1D(12);
00147
00148
       if (!assertion) {
         std::cerr << "Mimetic div (12th order) could not be built." << std::endl;</pre>
00149
00150
00151
00152
       mtk::Tools::EndUnitTestNo(6);
00153
       mtk::Tools::Assert(assertion);
00154 }
00155
00157
00158
       mtk::Tools::BeginUnitTestNo(7);
00159
00160
       mtk::Div1D div14;
00161
00162
       bool assertion = div14.ConstructDiv1D(14);
00163
00164
       if (!assertion) {
00165
         std::cerr << "Mimetic div (14th order) could not be built." << std::endl;
00166
00167
00168
       mtk::Tools::EndUnitTestNo(7);
00169
       mtk::Tools::Assert(assertion);
00170 }
00171
00172 void TestSecondOrderReturnAsDenseMatrixWithGrid() {
00173
00174
       mtk::Tools::BeginUnitTestNo(8);
00175
00176
       mtk::Div1D div2;
00177
00178
       bool assertion = div2.ConstructDiv1D();
00179
00180
       if (!assertion) {
00181
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00182
00183
00184
       mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00185
       mtk::DenseMatrix div2m(div2.ReturnAsDenseMatrix(grid));
00186
```

```
00187
00188
        int rr{7};
00189
        int cc{6};
00190
00191
        mtk::DenseMatrix ref(rr, cc);
00192
00193
00194
        ref.SetValue(1,0,-5.0);
00195
        ref.SetValue(1,1,5.0);
00196
        ref.SetValue(1,2,0.0);
00197
        ref.SetValue(1,3,0.0);
00198
        ref.SetValue(1,4,0.0);
00199
        ref.SetValue(1,5,0.0);
00200
       ref.SetValue(1,6,0.0);
00201
00202
        // Row 3.
00203
        ref.SetValue(2,0,0.0);
00204
        ref.SetValue(2,1,-5.0);
00205
        ref.SetValue(2,2,5.0);
00206
        ref.SetValue(2,3,0.0);
00207
        ref.SetValue(2,4,0.0);
00208
       ref.SetValue(2,5,0.0);
00209
       ref.SetValue(2,6,0.0);
00210
00211
        // Row 4.
        ref.SetValue(3,0,0.0);
00212
00213
        ref.SetValue(3,1,0.0);
00214
        ref.SetValue(3,2,-5.0);
00215
        ref.SetValue(3,3,5.0);
00216
        ref.SetValue(3,4,0.0);
00217
        ref.SetValue(3,5,0.0);
00218
        ref.SetValue(3,6,0.0);
00219
        // Row 5.
00220
00221
        ref.SetValue(4,0,0.0);
        ref.SetValue(4,1,0.0);
00222
00223
        ref.SetValue(4,2,0.0);
00224
        ref.SetValue(4,3,-5.0);
00225
        ref.SetValue(4,4,5.0);
00226
        ref.SetValue(4,5,0.0);
00227
        ref.SetValue(4,6,0.0);
00228
00229
        // Row 6.
00230
        ref.SetValue(5,0,0.0);
00231
        ref.SetValue(5,1,0.0);
00232
        ref.SetValue(5,2,0.0);
00233
        ref.SetValue(5,3,0.0);
00234
        ref.SetValue(5,4,-5.0);
00235
        ref.SetValue(5,5,5.0);
00236
        ref.SetValue(5,6,0.0);
00237
00238
        assertion = assertion && (div2m == ref);
00239
00240
        mtk::Tools::EndUnitTestNo(8);
00241
       mtk::Tools::Assert(assertion);
00242 }
00243
00244 void TestFourthOrderReturnAsDenseMatrixWithGrid() {
00245
00246
       mtk::Tools::BeginUnitTestNo(9);
00247
00248
       mtk::Div1D div4;
00249
00250
       bool assertion = div4.ConstructDiv1D(4);
00251
00252
        if (!assertion)
00253
         std::cerr << "Mimetic div (4th order) could not be built." << std::endl;
00254
00255
00256
        std::cout << div4 << std::endl;
00257
00258
       mtk::UniStgGrid1D grid(0.0, 1.0, 11);
00259
00260
        std::cout << grid << std::endl;
00261
00262
       mtk::DenseMatrix div4m(div4.ReturnAsDenseMatrix(grid));
00263
00264
        std::cout << div4m << std::endl;
00265
00266
       mtk::Tools::EndUnitTestNo(9);
00267 }
```

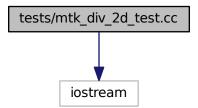
```
00268
00269 int main () {
00270
00271
        std::cout << "Testing mtk::Div1D class." << std::endl;</pre>
00273
       TestDefaultConstructorFactoryMethodDefault();
        TestDefaultConstructorFactoryMethodFourthOrder();
00275
       TestDefaultConstructorFactoryMethodSixthOrder();
00276
        TestDefaultConstructorFactoryMethodEightOrderDefThreshold();
       TestDefaultConstructorFactoryMethodTenthOrderDefThreshold();
       TestDefaultConstructorFactoryMethodTwelfthOrderDefThreshold();
00279
       TestDefaultConstructorFactoryMethodFourteenthOrderDefThreshold();
00280
        TestSecondOrderReturnAsDenseMatrixWithGrid();
00281
       TestFourthOrderReturnAsDenseMatrixWithGrid();
00282 }
00283
00284 #else
00285 #include <iostream>
00286 using std::cout;
00287 using std::endl;
00288 int main () {
00289 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;</pre>
00291 }
00292 #endif
```

17.95 tests/mtk div 2d test.cc File Reference

Test file for the mtk::Div2D class.

#include <iostream>

Include dependency graph for mtk div 2d test.cc:



Functions

• int main ()

17.95.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_div_2d_test.cc.

17.95.2 Function Documentation

```
17.95.2.1 int main ( )
```

Definition at line 139 of file mtk div 2d test.cc.

17.96 mtk_div_2d_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <cmath>
00057 #include <ctime>
00059 #include <iostream>
00060
00061 #include "mtk.h"
00062
00063 void TestDefaultConstructorFactory() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
00067
       mtk::Div2D dd:
00068
00069
       mtk::Real aa = 0.0;
00070
       mtk::Real bb = 1.0;
00071
       mtk::Real cc = 0.0:
00072
       mtk::Real ee = 1.0;
00073
```

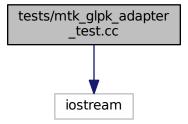
```
00074
        int nn = 5;
00075
       int mm = 5;
00076
00077
        mtk::UniStgGrid2D ddg(aa, bb, nn, cc, ee, mm);
00078
00079
        bool assertion = dd.ConstructDiv2D(ddg);
08000
00081
        if (!assertion) {
00082
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00083
00084
00085
       mtk::Tools::EndUnitTestNo(1);
00086
       mtk::Tools::Assert(assertion);
00087 }
00088
00089 void TestReturnAsDenseMatrixWriteToFile() {
00090
00091
       mtk::Tools::BeginUnitTestNo(2);
00092
00093
       mtk::Div2D dd;
00094
00095
       mtk::Real aa = 0.0;
00096
       mtk::Real bb = 1.0;
00097
       mtk::Real cc = 0.0;
00098
       mtk::Real ee = 1.0;
00099
00100
        int nn = 5:
        int mm = 5;
00101
00102
00103
       mtk::UniStgGrid2D ddg(aa, bb, nn, cc, ee, mm);
00104
00105
        bool assertion = dd.ConstructDiv2D(ddg);
00106
00107
        if (!assertion) {
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00108
00109
00110
00111
        mtk::DenseMatrix ddm(dd.ReturnAsDenseMatrix());
00112
00113
        assertion = assertion && (ddm.num_rows() != mtk::kZero);
00114
00115
        std::cout << ddm << std::endl;</pre>
00116
00117
        assertion = assertion && ddm.WriteToFile("mtk_div_2d_test_02.dat");
00118
00119
        if(!assertion)
00120
         std::cerr << "Error writing to file." << std::endl;
00121
00122
00123
        mtk::Tools::EndUnitTestNo(2);
00124
       mtk::Tools::Assert(assertion);
00125 }
00126
00127 int main () {
00128
00129
        std::cout << "Testing mtk::Div2D class." << std::endl;</pre>
00130
00131
        TestDefaultConstructorFactory();
00132
       TestReturnAsDenseMatrixWriteToFile();
00133 }
00134
00135 #else
00136 #include <iostream>
00137 using std::cout;
00138 using std::endl;
00139 int main () {
00140 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00141
00142 }
00143 #endif
```

17.97 tests/mtk_glpk_adapter_test.cc File Reference

Test file for the mtk::GLPKAdapter class.

#include <iostream>

Include dependency graph for mtk_glpk_adapter_test.cc:



Functions

• int main ()

17.97.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Test the mtk::GLPKAdapter class.

Definition in file mtk_glpk_adapter_test.cc.

17.97.2 Function Documentation

```
17.97.2.1 int main ( )
```

Definition at line 81 of file mtk_glpk_adapter_test.cc.

17.98 mtk_glpk_adapter_test.cc

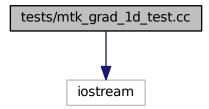
```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
```

```
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059 #include <ctime>
00060
00061 #include "mtk.h"
00062
00063 void Test1() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
00067
       mtk::Tools::EndUnitTestNo(1);
00068 }
00069
00070 int main () {
00071
00072
        std::cout << "Testing mtk::GLPKAdapter class." << std::endl;</pre>
00073
00074
       Test1();
00075 }
00076
00077 #else
00078 #include <iostream>
00079 using std::cout;
00080 using std::endl;
00081 int main () {
00082 cout << "This code HAS to be compiled with support for C++11." << endl;
00083
       cout << "Exiting..." << endl;</pre>
00084 }
00085 #endif
```

17.99 tests/mtk_grad_1d_test.cc File Reference

Testing the mimetic 1D gradient, constructed with the CBS algorithm.

#include <iostream>
Include dependency graph for mtk grad 1d test.cc:



Functions

• int main ()

17.99.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_grad_1d_test.cc.

17.99.2 Function Documentation

```
17.99.2.1 int main ( )
```

Definition at line 296 of file mtk_grad_1d_test.cc.

17.100 mtk_grad_1d_test.cc

```
00001  
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State  
00010 University. All rights reserved.  
00011  
00012 Redistribution and use in source and binary forms, with or without modification,  
00013 are permitted provided that the following conditions are met:  
00014  
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu  
00016 and a copy of the modified files should be reported once modifications are  
00017 completed, unless these modifications are made through the project's GitHub  
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications  
00019 should be developed and included in any deliverable.  
00020  
00021 2. Redistributions of source code must be done through direct  
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk  
00023  
00024 3. Redistributions in binary form must reproduce the above copyright notice,
```

```
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT 00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void TestDefaultConstructorFactoryMethodDefault() {
00061
00062
        mtk::Tools::BeginUnitTestNo(1);
00063
       mtk::Grad1D grad2;
00064
00065
00066
        bool assertion = grad2.ConstructGrad1D();
00067
00068
        if (!assertion) {
00069
          std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00070
00071
00072
00073
        std::cout << grad2 << std::endl;
00074
00075
        mtk::Tools::EndUnitTestNo(1);
00076
        mtk::Tools::Assert(assertion);
00077 }
00078
00079 void TestDefaultConstructorFactoryMethodFourthOrder() {
08000
00081
        mtk::Tools::BeginUnitTestNo(2);
00082
00083
        mtk::Grad1D grad4;
00084
00085
        bool assertion = grad4.ConstructGrad1D(4);
00086
00087
        if (!assertion) {
00088
          std::cerr << "Mimetic grad (4th order) could not be built." << std::endl;</pre>
00089
00090
00091
        std::cout << grad4 << std::endl;
00092
00093
        mtk::Tools::EndUnitTestNo(2);
00094
        mtk::Tools::Assert (assertion);
00095 }
00096
00097 void TestDefaultConstructorFactoryMethodSixthOrder() {
00098
00099
        mtk::Tools::BeginUnitTestNo(3);
00100
00101
       mtk::Grad1D grad6;
00102
00103
        bool assertion = grad6.ConstructGrad1D(6);
00104
00105
       if (!assertion) {
```

```
00106
          std::cerr << "Mimetic grad (6th order) could not be built." << std::endl;
00107
00108
00109
        std::cout << grad6 << std::endl;
00110
00111
        mtk::Tools::EndUnitTestNo(3);
00112
       mtk::Tools::Assert(assertion);
00113 }
00114
00115 void TestDefaultConstructorFactoryMethodEightOrderDefThreshold() {
00116
00117
       mtk::Tools::BeginUnitTestNo(4);
00118
00119
       mtk::Grad1D grad8;
00120
00121
       bool assertion = grad8.ConstructGrad1D(8);
00122
00123
        if (!assertion) {
00124
         std::cerr << "Mimetic grad (8th order) could not be built." << std::endl;
00125
00126
00127
        std::cout << grad8 << std::endl;
00128
00129
       mtk::Tools::EndUnitTestNo(4);
00130
       mtk::Tools::Assert(assertion);
00131 }
00132
00133 void TestDefaultConstructorFactoryMethodTenthOrderDefThreshold() {
00134
00135
       mtk::Tools::BeginUnitTestNo(5);
00136
00137
       mtk::Grad1D grad10;
00138
00139
        bool assertion = grad10.ConstructGrad1D(10);
00140
00141
        if (!assertion) {
00142
         std::cerr << "Mimetic grad (10th order) could not be built." << std::endl;
00143
00144
00145
        std::cout << grad10 << std::endl;
00146
00147
        mtk::Tools::EndUnitTestNo(5);
00148
       mtk::Tools::Assert(assertion);
00149 }
00150
00151 void TestReturnAsDenseMatrixWithGrid() {
00152
00153
        mtk::Tools::BeginUnitTestNo(6);
00154
00155
       mtk::Grad1D grad2;
00156
00157
        bool assertion = grad2.ConstructGrad1D();
00158
00159
00160
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00161
00162
00163
        mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00164
00165
       mtk::DenseMatrix grad2m(grad2.ReturnAsDenseMatrix(grid));
00166
00167
        int rr{6};
00168
       int cc{7};
00169
00170
       mtk::DenseMatrix ref(rr, cc);
00171
00172
        // Row 1.
00173
        ref.SetValue(0,0,-13.3333);
       ref.SetValue(0,1,15);
00174
00175
        ref.SetValue(0,2,-1.66667);
00176
       ref.SetValue(0,3,0.0);
00177
        ref.SetValue(0,4,0.0);
00178
       ref.SetValue(0,5,0.0);
00179
       ref.SetValue(0,6,0.0);
00180
00181
        // Row 2.
       ref.SetValue(1,0,0.0);
00182
00183
        ref.SetValue(1,1,-5.0);
00184
       ref.SetValue(1,2,5.0);
00185
        ref.SetValue(1,3,0.0);
00186
       ref.SetValue(1,4,0.0);
```

```
00187
        ref.SetValue(1,5,0.0);
00188
       ref.SetValue(1,6,0.0);
00189
00190
        // Row 3.
00191
        ref.SetValue(2,0,0.0);
00192
        ref.SetValue(2,1,0.0);
00193
        ref.SetValue(2,2,-5.0);
00194
        ref.SetValue(2,3,5.0);
00195
        ref.SetValue(2,4,0.0);
00196
       ref.SetValue(2,5,0.0);
00197
        ref.SetValue(2,6,0.0);
00198
00199
        // Row 4.
       ref.SetValue(3,0,0.0);
00200
00201
        ref.SetValue(3,1,0.0);
00202
        ref.SetValue(3,2,0.0);
00203
        ref.SetValue(3,3,-5.0);
00204
        ref.SetValue(3,4,5.0);
00205
        ref.SetValue(3,5,0.0);
00206
       ref.SetValue(3,6,0.0);
00207
00208
        // Row 5.
00209
        ref.SetValue(4,0,0.0);
00210
       ref.SetValue(4,1,0.0);
00211
        ref.SetValue(4,2,0.0);
       ref.SetValue(4,3,0.0);
00212
00213
        ref.SetValue(4,4,-5.0);
00214
       ref.SetValue(4,5,5.0);
00215
        ref.SetValue(4,6,0.0);
00216
00217
        // Row 6.
00218
       ref.SetValue(5,0,0.0);
00219
        ref.SetValue(5,1,0.0);
00220
        ref.SetValue(5,2,0.0);
        ref.SetValue(5,3,0.0);
00221
00222
        ref.SetValue(5,4,1.66667);
00223
        ref.SetValue(5,5,-15.0);
00224
        ref.SetValue(5,6,13.3333);
00225
       mtk::Tools::EndUnitTestNo(6);
00226
00227
       mtk::Tools::Assert(grad2m == ref);
00228 }
00229
00230 void TestReturnAsDimensionlessDenseMatrix() {
00231
00232
       mtk::Tools::BeginUnitTestNo(7);
00233
00234
       mtk::Grad1D grad4;
00235
00236
        bool assertion = grad4.ConstructGrad1D(4);
00237
00238
        if (!assertion) {
00239
         std::cerr << "Mimetic grad (4th order) could not be built." << std::endl;</pre>
00240
00241
00242
        mtk::DenseMatrix grad4m(grad4.ReturnAsDimensionlessDenseMatrix
      (10));
00243
00244
        std::cout << grad4m << std::endl;
00245
00246
        mtk::Tools::EndUnitTestNo(7);
00247
       mtk::Tools::Assert(assertion);
00248 }
00249
00250 void TestWriteToFile() {
00251
00252
       mtk::Tools::BeginUnitTestNo(8);
00253
00254
       mtk::Grad1D grad2;
00255
00256
        bool assertion = grad2.ConstructGrad1D();
00257
00258
        if (!assertion) {
00259
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00260
00261
00262
        mtk::UniStgGrid1D grid(0.0, 1.0, 50);
00263
00264
       mtk::DenseMatrix grad2m(grad2.ReturnAsDenseMatrix(grid));
00265
00266
        std::cout << grad2m << std::endl;
```

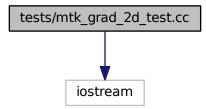
```
00267
00268
        assertion = assertion && grad2m.WriteToFile("mtk_grad_1d_test_08.dat");
00270
        if(!assertion) {
00271
         std::cerr << "Error writing to file." << std::endl;</pre>
00272
00273
00274
       mtk::Tools::EndUnitTestNo(8);
00275
       mtk::Tools::Assert(assertion);
00276 }
00277
00278 int main () {
00279
       std::cout << "Testing mtk::Grad1D class." << std::endl;</pre>
00281
       TestDefaultConstructorFactoryMethodDefault();
00283
        TestDefaultConstructorFactoryMethodFourthOrder();
00284
       TestDefaultConstructorFactoryMethodSixthOrder();
00285
        TestDefaultConstructorFactoryMethodEightOrderDefThreshold();
00286 TestDefaultConstructorFactoryMethodTenthOrderDefThreshold();
00287
        TestReturnAsDenseMatrixWithGrid();
00288
       TestReturnAsDimensionlessDenseMatrix();
00289
       TestWriteToFile();
00290 }
00291
00292 #else
00293 #include <iostream>
00294 using std::cout;
00295 using std::endl;
00296 int main () {
00297    cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00299 1
00300 #endif
```

17.101 tests/mtk_grad_2d_test.cc File Reference

Test file for the mtk::Grad2D class.

```
#include <iostream>
```

Include dependency graph for mtk_grad_2d_test.cc:



Functions

• int main ()

17.101.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_grad_2d_test.cc.

17.101.2 Function Documentation

```
17.101.2.1 int main ( )
```

Definition at line 139 of file mtk grad 2d test.cc.

17.102 mtk_grad_2d_test.cc

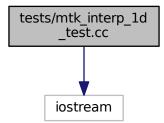
```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <cmath>
00057 #include <ctime>
00058
00059 #include <iostream>
00060
00061 #include "mtk.h"
00062
00063 void TestDefaultConstructorFactory() {
```

```
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
       mtk::Grad2D gg;
00067
00068
00069
       mtk::Real aa = 0.0;
00070
       mtk::Real bb = 1.0;
00071
       mtk::Real cc = 0.0;
00072
       mtk::Real dd = 1.0;
00073
00074
        int nn = 5;
00075
       int mm = 5;
00076
00077
       mtk::UniStgGrid2D ggg(aa, bb, nn, cc, dd, mm, mtk::VECTOR);
00078
00079
       bool assertion = gg.ConstructGrad2D(ggg);
00080
00081
        if (!assertion) {
00082
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00083
00084
00085
       mtk::Tools::EndUnitTestNo(1);
00086
       mtk::Tools::Assert (assertion);
00087 }
00088
00089 void TestReturnAsDenseMatrixWriteToFile() {
00090
00091
       mtk::Tools::BeginUnitTestNo(2);
00092
00093
       mtk::Grad2D gg;
00094
00095
       mtk::Real aa = 0.0;
00096
       mtk::Real bb = 1.0:
       mtk::Real cc = 0.0;
00097
       mtk::Real dd = 1.0;
00098
00099
00100
        int nn = 5;
00101
        int mm = 5;
00102
        mtk::UniStgGrid2D ggg(aa, bb, nn, cc, dd, mm, mtk::VECTOR);
00103
00104
00105
        bool assertion = gg.ConstructGrad2D(ggg);
00106
00107
        if (!assertion) {
00108
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00109
00110
00111
        mtk::DenseMatrix ggm(gg.ReturnAsDenseMatrix());
00112
00113
        assertion = assertion && (ggm.num_rows() != mtk::kZero);
00114
00115
       std::cout << ggm << std::endl;
00116
00117
        assertion = assertion && ggm.WriteToFile("mtk_grad_2d_test_02.dat");
00118
00119
        if(!assertion) {
00120
         std::cerr << "Error writing to file." << std::endl;
00121
00122
00123
       mtk::Tools::EndUnitTestNo(2);
00124
       mtk::Tools::Assert(assertion);
00125 }
00126
00127 int main () {
00128
00129
       std::cout << "Testing mtk::Grad2D class." << std::endl;</pre>
00130
00131
        TestDefaultConstructorFactory();
00132
       TestReturnAsDenseMatrixWriteToFile();
00133 }
00134
00135 #else
00136 #include <iostream>
00137 using std::cout;
00138 using std::endl;
00139 int main () {
00140 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00141
00142 }
00143 #endif
```

17.103 tests/mtk_interp_1d_test.cc File Reference

Testing the 1D interpolation.

```
#include <iostream>
Include dependency graph for mtk_interp_1d_test.cc:
```



Functions

• int main ()

17.103.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Johnny Corbino - jcorbino at mail dot sdsu dot edu

Definition in file mtk_interp_1d_test.cc.

17.103.2 Function Documentation

```
17.103.2.1 int main ( )
```

Definition at line 113 of file mtk_interp_1d_test.cc.

17.104 mtk_interp_1d_test.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
```

```
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059
00060 #include "mtk.h"
00061
00062 void TestDefaultConstructorFactoryMethodDefault() {
00063
00064
       mtk::Tools::BeginUnitTestNo(1);
00065
00066
       mtk::Interp1D inter;
00067
00068
        bool assertion = inter.ConstructInterp1D();
00069
00070
        if (!assertion) {
00071
         std::cerr << "Mimetic interp could not be built." << std::endl;</pre>
00072
00073
00074
        mtk::Tools::EndUnitTestNo(1);
00075
        mtk::Tools::Assert(assertion);
00076 }
00077
00078 void TestReturnAsDenseMatrixWithGrid() {
00079
00080
       mtk::Tools::BeginUnitTestNo(2);
00081
00082
       mtk::Interp1D inter;
00083
00084
        bool assertion = inter.ConstructInterplD();
00085
00086
        if (!assertion) {
00087
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00088
00089
00090
        mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00091
00092
       mtk::DenseMatrix interpm(inter.ReturnAsDenseMatrix(grid));
00093
00094
       assertion =
00095
         assertion && interpm.GetValue(0,0) == 1.0 && interpm.GetValue(5,6) == 1.0;
00096
00097
       mtk::Tools::EndUnitTestNo(2);
00098
       mtk::Tools::Assert (assertion);
00099 }
```

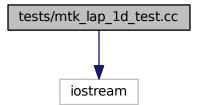
```
00100
00101 int main () {
00102
00103
         std::cout << "Testing mtk::Interp1D class." << std::endl;</pre>
00104
00105
        TestDefaultConstructorFactoryMethodDefault();
00106
         TestReturnAsDenseMatrixWithGrid();
00107 }
00108
00109 #else
00110 #include <iostream>
00111 using std::cout;
00112 using std::endl;
00113 int main () {
00114 cout << "This code HAS to be compiled with support for C++11." << endl;
00115 cout << "Exiting..." << endl;
00116 }
00117 #endif
```

17.105 tests/mtk_lap_1d_test.cc File Reference

Testing the 1D Laplacian operator.

```
#include <iostream>
```

Include dependency graph for mtk_lap_1d_test.cc:



Functions

• int main ()

17.105.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Johnny Corbino - jcorbino at mail dot sdsu dot edu

Definition in file mtk_lap_1d_test.cc.

17.105.2 Function Documentation

```
17.105.2.1 int main ( )
```

Definition at line 193 of file mtk_lap_1d_test.cc.

17.106 mtk_lap_1d_test.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00058 #include <iostream>
00059
00060 #include "mtk.h"
00062 void TestDefaultConstructorFactoryMethodDefault() {
00064
       mtk::Tools::BeginUnitTestNo(1);
00065
00066
       mtk::Lap1D lap2;
00067
00068
        bool assertion = lap2.ConstructLap1D();
00069
00070
        if (!assertion) {
00071
         std::cerr << "Mimetic lap (2nd order) could not be built." << std::endl;</pre>
00072
00073
00074
       mtk::Tools::EndUnitTestNo(1);
00075
       mtk::Tools::Assert (assertion);
00076 }
00077
00078 void TestDefaultConstructorFactorvMethodFourthOrder() {
```

```
00079
08000
        mtk::Tools::BeginUnitTestNo(2);
00081
00082
        mtk::Lap1D lap4;
00083
00084
        bool assertion = lap4.ConstructLap1D(4);
00085
00086
        if (!assertion) {
00087
         std::cerr << "Mimetic lap (4th order) could not be built." << std::endl;
00088
00089
00090
        mtk::Tools::EndUnitTestNo(2);
00091
       mtk::Tools::Assert(assertion);
00092 }
00093
00094 void TestDefaultConstructorFactoryMethodSixthOrder() {
00095
00096
       mtk::Tools::BeginUnitTestNo(3);
00097
00098
       mtk::Lap1D lap6;
00099
00100
        bool assertion = lap6.ConstructLap1D(6);
00101
00102
        if (!assertion) {
00103
         std::cerr << "Mimetic lap (6th order) could not be built." << std::endl;
00104
00105
00106
       mtk::Tools::EndUnitTestNo(3);
00107
       mtk::Tools::Assert(assertion);
00108 }
00109
00110 void TestDefaultConstructorFactoryMethodEightOrderDefThreshold() {
00111
        mtk::Tools::BeginUnitTestNo(4);
00112
00113
        mtk::Lap1D lap8;
00114
00115
00116
        bool assertion = lap8.ConstructLap1D(8);
00117
        if (!assertion) {
00118
00119
         std::cerr << "Mimetic lap (8th order) could not be built." << std::endl;
00120
00121
00122
        mtk::Tools::EndUnitTestNo(4);
00123 }
00124
00125 void TestDefaultConstructorFactoryMethodTenthOrderDefThreshold() {
00126
00127
        mtk::Tools::BeginUnitTestNo(5);
00128
00129
       mtk::Lap1D lap10;
00130
00131
        bool assertion = lap10.ConstructLap1D(10);
00132
00133
        if (!assertion)
00134
          std::cerr << "Mimetic lap (10th order) could not be built." << std::endl;</pre>
00135
00136
00137
        mtk::Tools::EndUnitTestNo(5);
00138 }
00139
00140 void TestDefaultConstructorFactoryMethodTwelfthOrderDefThreshold() {
00141
00142
       mtk::Tools::BeginUnitTestNo(6);
00143
00144
       mtk::Lap1D lap12;
00145
00146
       bool assertion = lap12.ConstructLap1D(12);
00147
00148
        if (!assertion) {
00149
         std::cerr << "Mimetic lap (12th order) could not be built." << std::endl;
00150
00151
00152
       mtk::Tools::EndUnitTestNo(6);
00153 }
00154
00155 void TestReturnAsDenseMatrix() {
00156
00157
        mtk::Tools::BeginUnitTestNo(8);
00158
00159
       mtk::Lap1D lap4;
```

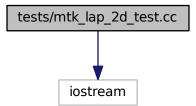
```
00160
00161
        bool assertion = lap4.ConstructLap1D(4);
00162
        if (!assertion) {
00163
00164
         std::cerr << "Mimetic lap (4th order) could not be built." << std::endl;</pre>
00165
00166
00167
        mtk::UniStgGrid1D aux(0.0, 1.0, 11);
00168
00169
       mtk::DenseMatrix lap4_m(lap4.ReturnAsDenseMatrix(aux));
00170
00171
        assertion = assertion &&
00172
            abs(lap4_m.GetValue(1, 0) - 385.133) < mtk::kDefaultTolerance &&
00173
            abs(lap4_m.GetValue(11, 12) - 385.133) < mtk::kDefaultTolerance;
00174
       mtk::Tools::EndUnitTestNo(8);
00175
       mtk::Tools::Assert(assertion);
00176 }
00177
00178 int main () {
00179
00180
       std::cout << "Testing MTK 1D Laplacian" << std::endl;</pre>
00181
00182
        TestDefaultConstructorFactoryMethodDefault();
00183
        TestDefaultConstructorFactoryMethodFourthOrder();
00184
        TestDefaultConstructorFactoryMethodSixthOrder();
        {\tt TestDefaultConstructorFactoryMethodEightOrderDefThreshold();}
00185
        TestDefaultConstructorFactoryMethodTenthOrderDefThreshold();
00186
00187
        {\tt TestDefaultConstructorFactoryMethodTwelfthOrderDefThreshold();}
00188
       TestReturnAsDenseMatrix();
00189 }
00190
00191 #else
00192 #include <iostream>
00193 int main () {
        std::cout << "This code HAS to be compiled to support C++11." << std::endl;
00194
        std::cout << "Exiting..." << std::endl;
00195
00196 }
00197 #endif
```

17.107 tests/mtk_lap_2d_test.cc File Reference

Test file for the mtk::Lap2D class.

#include <iostream>

Include dependency graph for mtk_lap_2d_test.cc:



Functions

• int main ()

17.107.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk lap 2d test.cc.

17.107.2 Function Documentation

```
17.107.2.1 int main ( )
```

Definition at line 139 of file mtk lap 2d test.cc.

17.108 mtk_lap_2d_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00027
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00031
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <cmath>
00057 #include <ctime>
00058
00059 #include <iostream>
00060
```

```
00061 #include "mtk.h"
00062
00063 void TestDefaultConstructorFactory() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
00067
       mtk::Lap2D 11;
00068
00069
       mtk::Real aa = 0.0;
00070
       mtk::Real bb = 1.0;
00071
       mtk::Real cc = 0.0;
00072
       mtk::Real dd = 1.0;
00073
00074
        int nn = 5;
00075
        int mm = 5;
00076
00077
       mtk::UniStgGrid2D llg(aa, bb, nn, cc, dd, mm);
00078
00079
       bool assertion = 11.ConstructLap2D(11g);
00080
00081
        if (!assertion) {
00082
         std::cerr << "Mimetic lap (2nd order) could not be built." << std::endl;
00083
00084
00085
       mtk::Tools::EndUnitTestNo(1);
00086
       mtk::Tools::Assert(assertion);
00087 }
00088
00089 void TestReturnAsDenseMatrixWriteToFile() {
00090
00091
       mtk::Tools::BeginUnitTestNo(2);
00092
00093
       mtk::Lap2D 11;
00094
       mtk::Real aa = 0.0;
00095
       mtk::Real bb = 1.0;
00096
00097
       mtk::Real cc = 0.0;
00098
       mtk::Real dd = 1.0;
00099
00100
        int nn = 5;
00101
        int mm = 5;
00102
00103
       mtk::UniStgGrid2D llg(aa, bb, nn, cc, dd, mm);
00104
00105
       bool assertion = 11.ConstructLap2D(11g);
00106
00107
        if (!assertion) {
         std::cerr << "Mimetic lap (2nd order) could not be built." << std::endl;
00108
00109
00110
00111
       mtk::DenseMatrix llm(ll.ReturnAsDenseMatrix());
00112
00113
        assertion = assertion && (llm.num_rows() != 0);
00114
00115
        std::cout << 11m << std::endl;
00116
00117
        assertion = assertion && llm.WriteToFile("mtk_lap_2d_test_02.dat");
00118
00119
        if(!assertion)
00120
         std::cerr << "Error writing to file." << std::endl;
00121
00122
00123
       mtk::Tools::EndUnitTestNo(2);
00124
       mtk::Tools::Assert(assertion);
00125 }
00126
00127 int main () {
00128
00129
       std::cout << "Testing mtk::Lap2D class." << std::endl;
00130
00131
       TestDefaultConstructorFactory();
00132
       TestReturnAsDenseMatrixWriteToFile();
00133 }
00134
00135 #else
00136 #include <iostream>
00137 using std::cout;
00138 using std::endl;
00139 int main () {
        cout << "This code HAS to be compiled with support for C++11." << endl;</pre>
00140
       cout << "Exiting..." << endl;</pre>
00141
```

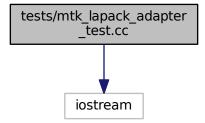
```
00142 }
00143 #endif
```

17.109 tests/mtk_lapack_adapter_test.cc File Reference

Test file for the mtk::LAPACKAdapter class.

```
#include <iostream>
```

Include dependency graph for mtk_lapack_adapter_test.cc:



Functions

• int main ()

17.109.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Test the mtk::LAPACKAdapter class.

Definition in file mtk_lapack_adapter_test.cc.

17.109.2 Function Documentation

```
17.109.2.1 int main ( )
```

Definition at line 81 of file mtk_lapack_adapter_test.cc.

17.110 mtk_lapack_adapter_test.cc

```
00001
00010 /*
```

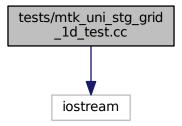
```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed, unless these modifications are made through the project's GitHub
00020 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00021 should be developed and included in any deliverable.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026 3. Redistributions in binary form must reproduce the above copyright notice,
00027 this list of conditions and the following disclaimer in the documentation and/or
00028 other materials provided with the distribution.
00029
00030 4. Usage of the binary form on proprietary applications shall require explicit
00031 prior written permission from the the copyright holders, and due credit should
00032 be given to the copyright holders.
00033
00034 5. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059 #include <ctime>
00060
00061 #include "mtk.h"
00062
00063 void Test1() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
       mtk::Tools::EndUnitTestNo(1);
00067
00068 }
00069
00070 int main () {
00071
00072
        std::cout << "Testing mtk::LAPACKAdapter class." << std::endl;</pre>
00073
00074
       Test1();
00075 }
00076
00077 #else
00078 #include <iostream>
00079 using std::cout;
00080 using std::endl;
00081 int main () {
       cout << "This code HAS to be compiled with support for C++11." << endl;</pre>
00082
       cout << "Exiting..." << endl;
00083
00084 }
00085 #endif
```

17.111 tests/mtk_uni_stg_grid_1d_test.cc File Reference

Test file for the mtk::UniStgGrid1D class.

```
#include <iostream>
```

Include dependency graph for mtk_uni_stg_grid_1d_test.cc:



Functions

• int main ()

17.111.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_uni_stg_grid_1d_test.cc.

17.111.2 Function Documentation

```
17.111.2.1 int main ( )
```

Definition at line 172 of file mtk_uni_stg_grid_1d_test.cc.

17.112 mtk_uni_stg_grid_1d_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
```

```
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057 #include <ctime>
00058
00059 #include "mtk.h"
00060
00061 void TestDefaultConstructor() {
00062
00063
       mtk::Tools::BeginUnitTestNo(1);
00064
00065
       mtk::UniStgGrid1D gg;
00066
00067
        mtk::Tools::EndUnitTestNo(1);
00068
       mtk::Tools::Assert(gg.delta_x() == mtk::kZero);
00069 }
00070
00071 mtk::Real ScalarField(mtk::Real xx) {
00072
00073
        return 2.0*xx;
00074 }
00075
00076 void TestConstructWithWestBndyEastBndyNumCellsOStreamOperatorBindScalarField() {
00077
00078
       mtk::Tools::BeginUnitTestNo(2);
00079
08000
        mtk::Real aa = 0.0;
00081
        mtk::Real bb = 1.0;
00082
00083
        int nn = 5;
00084
00085
       mtk::UniStgGrid1D gg(aa, bb, nn);
00086
00087
       gg.BindScalarField(ScalarField);
00088
00089
        std::cout << qq << std::endl;
00090
00091
        mtk::Tools::EndUnitTestNo(2);
       mtk::Tools::Assert(gq.delta_x() == 0.2 && gq.
00092
      num cells x() == 5);
00093 }
00094
00095 void TestBindScalarFieldWriteToFile() {
00096
        mtk::Tools::BeginUnitTestNo(3);
00097
```

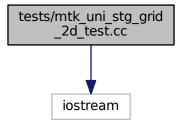
```
00098
00099
       mtk::Real aa = 0.0;
00100
       mtk::Real bb = 1.0;
00101
00102
        int nn = 5;
00103
00104
       mtk::UniStgGrid1D gg(aa, bb, nn);
00105
00106
       bool assertion{true};
00107
00108
       gg.BindScalarField(ScalarField);
00109
00110
       assertion =
00111
         assertion &&
00112
          gg.discrete_field_u()[0] == 0.0 &&
00113
         gg.discrete_field_u()[gg.num_cells_x() + 2 - 1] == 2.0;
00114
00115
        if(!gg.WriteToFile("mtk_uni_stg_grid_1d_test_03.dat", "x", "u(x)")) {
         std::cerr << "Error writing to file." << std::endl;
00116
         assertion = false;
00117
00118
       }
00119
00120
       mtk::Tools::EndUnitTestNo(3);
00121
       mtk::Tools::Assert(assertion);
00122 }
00123
00124 mtk::Real VectorFieldPComponent(mtk::Real xx) {
00125
00126
       return xx*xx;
00127 }
00128
00129 void TestBindVectorField() {
00130
00131
       mtk::Tools::BeginUnitTestNo(4);
00132
00133
       mtk::Real aa = 0.0;
00134
       mtk::Real bb = 1.0;
00135
00136
       int nn = 20;
00137
00138
       mtk::UniStgGrid1D gg(aa, bb, nn, mtk::VECTOR);
00139
00140
       bool assertion{true};
00141
00142
       gg.BindVectorField(VectorFieldPComponent);
00143
00144
       assertion =
00145
         assertion &&
00146
          gg.discrete_field_u()[0] == 0.0 &&
00147
         gg.discrete_field_u()[gg.num_cells_x() + 1 - 1] == 1.0;
00148
00149
        if(!gg.WriteToFile("mtk_uni_stg_grid_ld_test_04.dat", "x", "v(x)")) {
00150
         std::cerr << "Error writing to file." << std::endl;</pre>
00151
          assertion = false;
00152
00153
00154
       mtk::Tools::EndUnitTestNo(4);
00155
       mtk::Tools::Assert(assertion);
00156 }
00157
00158 int main () {
00159
00160
       std::cout << "Testing mtk::UniStgGrid1D class." << std::endl;</pre>
00161
00162
       TestDefaultConstructor();
        {\tt TestConstructWithWestBndyEastBndyNumCellsOStreamOperatorBindScalarField();}
00163
       TestBindScalarFieldWriteToFile();
00164
00165
       TestBindVectorField();
00166 }
00167
00168 #else
00169 #include <iostream>
00170 using std::cout;
00171 using std::endl;
00172 int main () {
00173 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00174
00175 }
00176 #endif
```

17.113 tests/mtk_uni_stg_grid_2d_test.cc File Reference

Test file for the mtk::UniStgGrid2D class.

```
#include <iostream>
```

Include dependency graph for mtk_uni_stg_grid_2d_test.cc:



Functions

• int main ()

17.113.1 Detailed Description

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk_uni_stg_grid_2d_test.cc.

17.113.2 Function Documentation

```
17.113.2.1 int main ( )
```

Definition at line 202 of file mtk_uni_stg_grid_2d_test.cc.

17.114 mtk_uni_stg_grid_2d_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed, unless these modifications are made through the project's GitHub
```

```
00018 page: http://www.csrc.sdsu.edu/mtk. Documentation related to said modifications
00019 should be developed and included in any deliverable.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions in binary form must reproduce the above copyright notice,
00025 this list of conditions and the following disclaimer in the documentation and/or
00026 other materials provided with the distribution.
00028 4. Usage of the binary form on proprietary applications shall require explicit
00029 prior written permission from the the copyright holders, and due credit should
00030 be given to the copyright holders.
00032 5. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <cmath>
00057 #include <ctime>
00058
00059 #include <iostream>
00060
00061 #include "mtk.h"
00062
00063 void TestDefaultConstructor() {
00064
00065
       mtk::Tools::BeginUnitTestNo(1);
00066
00067
       mtk::UniStgGrid2D gg;
00068
00069
       mtk::Tools::EndUnitTestNo(1);
       mtk::Tools::Assert(gg.delta_x() == mtk::kZero && gg.
00070
     delta_y() == mtk::kZero);
00071 }
00072
00073 void
00074 TestConstructWithWestEastNumCellsXSouthNorthBndysNumCellsYOStreamOperator() {
00075
00076
       mtk::Tools::BeginUnitTestNo(2);
00077
00078
       mtk::Real aa = 0.0;
00079
       mtk::Real bb = 1.0;
00080
       mtk::Real cc = 0.0;
       mtk::Real dd = 1.0;
00081
00082
00083
        int nn = 5:
00084
        int mm = 7;
00085
00086
       mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm);
00087
00088
        std::cout << gg << std::endl;
00089
00090
       mtk::Tools::EndUnitTestNo(2);
00091
        mtk::Tools::Assert(gg.delta_x() == 0.2 &&
00092
                            abs(gg.delta_y() - 0.142857) <
     mtk::kDefaultTolerance);
00093 }
00094
00095 void TestGetters() {
00096
```

```
00097
       mtk::Tools::BeginUnitTestNo(3);
00098
00099
       mtk::Real aa = 0.0;
00100
       mtk::Real bb = 1.0;
00101
       mtk::Real cc = 0.0;
00102
       mtk::Real dd = 1.0;
00103
00104
        int nn = 5;
00105
        int mm = 7;
00106
00107
       mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm);
00108
00109
       bool assertion{true};
00110
00111
       assertion = assertion && (gg.west_bndy() == aa);
00112
       assertion = assertion && (gg.east_bndy() == bb);
00113
       assertion = assertion && (gg.num_cells_x() == nn);
       assertion = assertion && (gg.south_bndy() == cc);
00114
00115
       assertion = assertion && (gg.north_bndy() == dd);
       assertion = assertion && (gg.num_cells_y() == mm);
00116
00117
00118
       mtk::Tools::EndUnitTestNo(3);
00119
       mtk::Tools::Assert(assertion);
00120 }
00121
00122 mtk::Real ScalarField(mtk::Real xx, mtk::Real vy) {
00123
00124
       mtk::Real aux\{-(1.0/2.0) * xx * xx - (1.0/2.0) * yy * yy\};
00125
00126
       return xx*yy*exp(aux);
00127 }
00128
00129 void TestBindScalarFieldWriteToFile() {
00130
00131
       mtk::Tools::BeginUnitTestNo(4);
00132
00133
       mtk::Real aa = 0.0;
       mtk::Real bb = 1.0;
00134
00135
       mtk::Real cc = 0.0;
       mtk::Real dd = 1.0;
00136
00137
00138
        int nn = 5;
       int mm = 5;
00139
00140
00141
       mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm);
00142
00143
        gg.BindScalarField(ScalarField);
00144
00145
        if(!gg.WriteToFile("mtk_uni_stg_grid_2d_test_04.dat", "x", "y", "u(x,y)")) {
00146
         std::cerr << "Error writing to file." << std::endl;</pre>
00147
00148
00149
       mtk::Tools::EndUnitTestNo(4);
00150 }
00151
00152 mtk::Real VectorFieldPComponent(mtk::Real xx, mtk::Real yy) {
00153
00154
       return xx + 0.01;
00155 }
00156
00157 mtk::Real VectorFieldQComponent(mtk::Real xx, mtk::Real yy) {
00158
00159
        return yy + 0.01;
00160 }
00161
00162 void TestBindVectorField() {
00163
00164
       mtk::Tools::BeginUnitTestNo(5);
00165
00166
       mtk::Real aa = 0.0;
00167
       mtk::Real bb = 1.0;
00168
       mtk::Real cc = 0.0;
00169
       mtk::Real dd = 1.0;
00170
00171
        int nn = 5;
00172
       int mm = 5:
00173
00174
       mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm, mtk::VECTOR);
00175
00176
        gg.BindVectorField(VectorFieldPComponent, VectorFieldOComponent);
00177
```

```
00178
        std::cout << gg << std::endl;
00179
        if(!gg.WriteToFile("mtk_uni_stg_grid_2d_test_05.dat", "x", "y", "v(x,y)")) {
00180
00181
         std::cerr << "Error writing to file." << std::endl;</pre>
00182
00183
00184
       mtk::Tools::EndUnitTestNo(5);
00185 }
00186
00187 int main () {
00188
00189
       std::cout << "Testing mtk::UniStgGrid2D class." << std::endl;</pre>
00190
00191
       TestDefaultConstructor();
00192
        TestConstructWithWestEastNumCellsXSouthNorthBndysNumCellsYOStreamOperator();
00193 TestGetters();
00194
       TestBindScalarFieldWriteToFile();
00195
       TestBindVectorField();
00196 }
00197
00198 #else
00199 #include <iostream>
00200 using std::cout;
00201 using std::endl;
00202 int main () {
00203 cout << "This code HAS to be compiled with support for C++11." << endl;
00205 }
00206 #endif
```

Index

BANDED Enumerations., 35
COL_MAJOR Enumerations., 35
CRS Enumerations., 35
DENSE Enumerations., 35 Data structures., 37
Enumerations., 34 BANDED, 35 COL_MAJOR, 35 CRS, 35 DENSE, 35 ROW_MAJOR, 35 SCALAR, 34 SCALAR_TO_VECTOR, 34 VECTOR, 34 VECTOR_TO_SCALAR, 34 Execution tools., 36
Grids., 39
Grids., 39 Mimetic operators., 40 mtk, 41 operator<<, 43, 44
Mimetic operators., 40 mtk, 41
Mimetic operators., 40 mtk, 41 operator<<, 43, 44
Mimetic operators., 40 mtk, 41 operator<<, 43, 44 Numerical methods., 38 operator<< mtk, 43, 44 ROW_MAJOR
Mimetic operators., 40 mtk, 41 operator<<, 43, 44 Numerical methods., 38 operator<< mtk, 43, 44 ROW_MAJOR Enumerations., 35 Real
Mimetic operators., 40 mtk, 41 operator<<, 43, 44 Numerical methods., 38 operator<< mtk, 43, 44 ROW_MAJOR Enumerations., 35
Mimetic operators., 40 mtk, 41 operator<<, 43, 44 Numerical methods., 38 operator<< mtk, 43, 44 ROW_MAJOR Enumerations., 35 Real Roots., 32 Roots., 31 Real, 32 SCALAR
Mimetic operators., 40 mtk, 41 operator<<, 43, 44 Numerical methods., 38 operator<< mtk, 43, 44 ROW_MAJOR Enumerations., 35 Real Roots., 32 Roots., 31 Real, 32

Enumerations., 34 VECTOR_TO_SCALAR Enumerations., 34