MTK: Mimetic Methods Toolkit

Generated by Doxygen 1.8.6

Thu Oct 15 2015 13:15:34

# **Contents**

1	Intro	duction	1
	1.1	MTK Concerns	1
	1.2	MTK Flavors	1
	1.3	Contact, Support and Credits	2
	1.4	Acknowledgements and Contributions	2
2	Prog	gramming Tools	3
3	Lice	nsing and Modifications	5
4	Read	d Me File and Installation Instructions	7
5	Test	s and Test Architectures	11
6	Exar	nples	13
7	User	Manual, References and Theory	15
8	Todo	D List	17
9	Bug	List	19
10	Mod	ule Index	21
	10.1	Modules	21
11	Nam	espace Index	23
	11.1	Namespace List	23
12		s Index	25
	12.1	Class List	25
13	File	Index	27
	13.1	File List	27

iv CONTENTS

14	Mod	ule Doc	umentation	31
	14.1	Roots.		31
		14.1.1	Detailed Description	31
		14.1.2	Typedef Documentation	32
			14.1.2.1 Real	32
		14.1.3	Variable Documentation	32
			14.1.3.1 kCriticalOrderAccuracyDiv	32
			14.1.3.2 kCriticalOrderAccuracyGrad	32
			14.1.3.3 kDefaultMimeticThreshold	32
			14.1.3.4 kDefaultOrderAccuracy	32
			14.1.3.5 kDefaultTolerance	32
			14.1.3.6 kOne	32
			14.1.3.7 kZero	32
	14.2	Enume	rations	33
		14.2.1	Detailed Description	33
		14.2.2	Enumeration Type Documentation	33
			14.2.2.1 Dirlnterp	33
			14.2.2.2 FieldNature	33
			14.2.2.3 MatrixOrdering	34
			14.2.2.4 MatrixStorage	34
	14.3	Execut	on tools.	35
		14.3.1	Detailed Description	35
	14.4	Data st	ructures	36
		14.4.1	Detailed Description	36
	14.5	Numer	cal methods	37
		14.5.1	Detailed Description	37
	14.6	Grids.		38
		14.6.1	Detailed Description	38
	14.7	Mimetio	coperators	39
		14.7.1	Detailed Description	39
15	Nam	espace	Documentation	41
	15.1	mtk Na	mespace Reference	41
		15.1.1	Function Documentation	43
			15.1.1.1 operator<<	43
			15.1.1.2 operator<<	43
			15.1.1.3 operator<<	43

CONTENTS

			15.1.1.4 operator <<	43
			15.1.1.5 operator <<	44
			15.1.1.6 operator <<	44
			15.1.1.7 operator<<	44
			15.1.1.8 saxpy	45
			15.1.1.9 sgels	45
			15.1.1.10 sgemm	46
			15.1.1.11 sgemv	47
			15.1.1.12 sgeqrf	47
			15.1.1.13 sgesv	47
			15.1.1.14 snrm2	48
			15.1.1.15 sormqr	48
16	Class	e Doour	mentation	51
10			CDesc1D Class Reference	
	10.1		Detailed Description	
			Member Function Documentation	
		10.1.2	16.1.2.1 ImposeOnGrid	
			16.1.2.2 ImposeOnOperator	
	16.2	mtk::Bl	ASAdapter Class Reference	
			Detailed Description	
			Member Function Documentation	
			16.2.2.1 RealAXPY	
			16.2.2.2 RealDenseMM	
			16.2.2.3 RealDenseMV	
			16.2.2.4 RealNRM2	
			16.2.2.5 RelNorm2Error	
	16.3	mtk::De	enseMatrix Class Reference	59
			Detailed Description	
		16.3.2	Constructor & Destructor Documentation	62
			16.3.2.1 DenseMatrix	62
			16.3.2.2 DenseMatrix	62
			16.3.2.3 DenseMatrix	63
			16.3.2.4 DenseMatrix	64
			16.3.2.5 DenseMatrix	64
			16.3.2.6 ~DenseMatrix	65
		16.3.3	Member Function Documentation	65

vi CONTENTS

	16.3.3.1	data		65
	16.3.3.2	GetValue		66
	16.3.3.3	Kron		67
	16.3.3.4	matrix_properties		68
	16.3.3.5	num_cols		69
	16.3.3.6	num_rows		69
	16.3.3.7	operator=		70
	16.3.3.8	OrderColMajor		71
	16.3.3.9	OrderRowMajor		72
	16.3.3.10	SetOrdering		72
	16.3.3.11	SetValue		73
	16.3.3.12	? Transpose		74
16.3.4	Friends A	And Related Function Documentation		74
	16.3.4.1	operator<<		75
16.3.5	Member [	Data Documentation		75
	16.3.5.1	data		75
	16.3.5.2	matrix_properties		75
mtk::Di	v1D Class	Reference		75
16.4.1	Detailed [	Description		78
16.4.2	Construct	tor & Destructor Documentation		78
	16.4.2.1	Div1D		78
	16.4.2.2	Div1D		78
	16.4.2.3	~Div1D		78
16.4.3	Member F	Function Documentation		79
	16.4.3.1	AssembleOperator		79
	16.4.3.2	coeffs_interior		79
	16.4.3.3	ComputePreliminaryApproximations		79
	16.4.3.4	ComputeRationalBasisNullSpace		80
	16.4.3.5	ComputeStencilBoundaryGrid		81
	16.4.3.6	ComputeStencilInteriorGrid		81
	16.4.3.7	ComputeWeights		82
	16.4.3.8	ConstructDiv1D		83
	16.4.3.9	mim_bndy		83
	16.4.3.10	num_bndy_coeffs		84
	16.4.3.11	ReturnAsDenseMatrix		84
	16.4.3.12	weights_cbs		85
	16.4.3.13	weights_crs		85
	16.3.5 mtk::Div 16.4.1 16.4.2	16.3.3.2 16.3.3.3 16.3.3.4 16.3.3.5 16.3.3.6 16.3.3.7 16.3.3.8 16.3.3.9 16.3.3.10 16.3.3.11 16.3.3.12 16.3.4 16.3.4.1 16.3.5 16.3.5.1 16.3.5.2 mtk::Div1D Class 16.4.1 Detailed 16.4.2 Construct 16.4.2.1 16.4.2.2 16.4.2.3 16.4.3.1 16.4.3.2 16.4.3.3 16.4.3.4 16.4.3.5 16.4.3.6 16.4.3.7 16.4.3.8 16.4.3.9 16.4.3.10 16.4.3.11 16.4.3.12	16.3.3.2 GetValue 16.3.3.3 Kron 16.3.3.4 matrix_properties 16.3.3.5 num_cols 16.3.3.6 num_rows 16.3.3.7 operator= 16.3.3.8 OrderColMajor 16.3.3.10 SetOrdering 16.3.3.11 SetValue 16.3.3.12 Transpose 16.3.4 Friends And Related Function Documentation 16.3.4.1 operator<< 16.3.5 Member Data Documentation 16.3.5.1 data	16.3.3.5 num_cols. 16.3.3.6 num_rows 16.3.3.7 operator=. 16.3.3.8 OrderColMajor 16.3.3.9 OrderRowMajor 16.3.3.10 SetOrdering 16.3.3.11 SetValue 16.3.3.12 Transpose 16.3.4 Friends And Related Function Documentation 16.3.4.1 operator<< 16.3.5 Member Data Documentation 16.3.5.1 data

CONTENTS vii

	16.4.4	Friends And Related Function Documentation
		16.4.4.1 operator <<
	16.4.5	Member Data Documentation
		16.4.5.1 coeffs_interior
		16.4.5.2 dim_null
		16.4.5.3 divergence
		16.4.5.4 divergence_length
		16.4.5.5 mim_bndy
		16.4.5.6 mimetic_threshold
		16.4.5.7 minrow
		16.4.5.8 num_bndy_coeffs
		16.4.5.9 order_accuracy
		16.4.5.10 prem_apps
		16.4.5.11 rat_basis_null_space
		16.4.5.12 row
		16.4.5.13 weights_cbs
		16.4.5.14 weights_crs
16.5	mtk::Di	v2D Class Reference
	16.5.1	Detailed Description
	16.5.2	Constructor & Destructor Documentation
		16.5.2.1 Div2D
		16.5.2.2 Div2D
		16.5.2.3 ~Div2D
	16.5.3	Member Function Documentation
		16.5.3.1 ConstructDiv2D
		16.5.3.2 ReturnAsDenseMatrix
	16.5.4	Member Data Documentation
		16.5.4.1 divergence
		16.5.4.2 mimetic_threshold
		16.5.4.3 order_accuracy
16.6	mtk::Gl	PKAdapter Class Reference
	16.6.1	Detailed Description
	16.6.2	Member Function Documentation
		16.6.2.1 SolveSimplexAndCompare
16.7	mtk::Gr	ad1D Class Reference
	16.7.1	Detailed Description
	16.7.2	Constructor & Destructor Documentation

viii CONTENTS

		16.7.2.1	Grad1D	96
		16.7.2.2	Grad1D	96
		16.7.2.3	$\sim$ Grad1D	97
	16.7.3	Member F	Function Documentation	97
		16.7.3.1	AssembleOperator	97
		16.7.3.2	coeffs_interior	97
		16.7.3.3	ComputePreliminaryApproximations	97
		16.7.3.4	ComputeRationalBasisNullSpace	98
		16.7.3.5	ComputeStencilBoundaryGrid	99
		16.7.3.6	ComputeStencilInteriorGrid	99
		16.7.3.7	ComputeWeights	100
		16.7.3.8	ConstructGrad1D	100
		16.7.3.9	mim_bndy	101
		16.7.3.10	num_bndy_coeffs	102
		16.7.3.11	ReturnAsDenseMatrix	102
		16.7.3.12	ReturnAsDenseMatrix	103
		16.7.3.13	weights_cbs	103
		16.7.3.14	weights_crs	104
	16.7.4	Friends A	and Related Function Documentation	104
		16.7.4.1	operator<<	104
	16.7.5	Member [	Data Documentation	104
		16.7.5.1	coeffs_interior	104
		16.7.5.2	$dim\_null\_\dots$	104
		16.7.5.3	gradient	104
		16.7.5.4	gradient_length	104
		16.7.5.5	mim_bndy	104
		16.7.5.6	mimetic_threshold	104
		16.7.5.7	minrow	105
		16.7.5.8	num_bndy_approxs	105
		16.7.5.9	num_bndy_coeffs	105
		16.7.5.10	order_accuracy	105
		16.7.5.11	prem_apps	105
		16.7.5.12	rat_basis_null_space	105
		16.7.5.13	row	105
		16.7.5.14	weights_cbs	105
		16.7.5.15	weights_crs	105
16.8	mtk::Gr	ad2D Clas	ss Reference	105

CONTENTS ix

16.8.1	Detailed Description
16.8.2	Constructor & Destructor Documentation
	16.8.2.1 Grad2D
	16.8.2.2 Grad2D
	16.8.2.3 ~Grad2D
16.8.3	Member Function Documentation
	16.8.3.1 ConstructGrad2D
	16.8.3.2 ReturnAsDenseMatrix
16.8.4	Member Data Documentation
	16.8.4.1 gradient
	16.8.4.2 mimetic_threshold
	16.8.4.3 order_accuracy
16.9 mtk::Int	terp1D Class Reference
16.9.1	Detailed Description
16.9.2	Constructor & Destructor Documentation
	16.9.2.1 Interp1D
	16.9.2.2 Interp1D
	16.9.2.3 ~Interp1D
16.9.3	Member Function Documentation
	16.9.3.1 coeffs_interior
	16.9.3.2 ConstructInterp1D
	16.9.3.3 ReturnAsDenseMatrix
16.9.4	Friends And Related Function Documentation
	16.9.4.1 operator <<
16.9.5	Member Data Documentation
	16.9.5.1 coeffs_interior
	16.9.5.2 dir_interp
	16.9.5.3 order_accuracy
16.10mtk::Int	terp2D Class Reference
16.10.1	Detailed Description
16.10.2	Constructor & Destructor Documentation
	16.10.2.1 Interp2D
	16.10.2.2 Interp2D
	16.10.2.3 ~Interp2D
16.10.3	Member Function Documentation
	16.10.3.1 ConstructInterp2D
	16.10.3.2 ReturnAsDenseMatrix

CONTENTS

16.10.4 Member Data Documentation
16.10.4.1 interpolator
16.10.4.2 mimetic_threshold
16.10.4.3 order_accuracy
16.11mtk::Lap1D Class Reference
16.11.1 Detailed Description
16.11.2 Constructor & Destructor Documentation
16.11.2.1 Lap1D
16.11.2.2 Lap1D
16.11.2.3 ~Lap1D
16.11.3 Member Function Documentation
16.11.3.1 ConstructLap1D
16.11.3.2 Data
16.11.3.3 ReturnAsDenseMatrix
16.11.4 Friends And Related Function Documentation
16.11.4.1 operator<<
16.11.5 Member Data Documentation
16.11.5.1 laplacian
16.11.5.2 laplacian_length
16.11.5.3 mimetic_threshold
16.11.5.4 order_accuracy
16.12mtk::Lap2D Class Reference
16.12.1 Detailed Description
16.12.2 Constructor & Destructor Documentation
16.12.2.1 Lap2D
16.12.2.2 Lap2D
16.12.2.3 ~Lap2D
16.12.3 Member Function Documentation
16.12.3.1 ConstructLap2D
16.12.3.2 ReturnAsDenseMatrix
16.12.4 Member Data Documentation
16.12.4.1 laplacian
16.12.4.2 mimetic_threshold
16.12.4.3 order_accuracy
16.13mtk::LAPACKAdapter Class Reference
16.13.1 Detailed Description
16.13.2 Member Function Documentation

CONTENTS xi

16.13.2.1 QRFactorDenseMatrix
16.13.2.2 SolveDenseSystem
16.13.2.3 SolveDenseSystem
16.13.2.4 SolveDenseSystem
16.13.2.5 SolveRectangularDenseSystem
16.14mtk::Matrix Class Reference
16.14.1 Detailed Description
16.14.2 Constructor & Destructor Documentation
16.14.2.1 Matrix
16.14.2.2 Matrix
16.14.2.3 ~Matrix
16.14.3 Member Function Documentation
16.14.3.1 abs_density
16.14.3.2 abs_sparsity
16.14.3.3 bandwidth
16.14.3.4 IncreaseNumNull
16.14.3.5 IncreaseNumZero
16.14.3.6 kl
16.14.3.7 ku
16.14.3.8 ld
16.14.3.9 num_cols
16.14.3.10num_non_null
16.14.3.11num_non_zero
16.14.3.12num_null
16.14.3.13num_rows
16.14.3.14num_values
16.14.3.15num_zero
16.14.3.16ordering
16.14.3.17rel_density
16.14.3.18rel_sparsity
16.14.3.19set_num_cols
16.14.3.20set_num_null
16.14.3.21set_num_rows
16.14.3.22set_num_zero
16.14.3.23set_ordering
16.14.3.24set_storage
16.14.3.25storage

xii CONTENTS

CONTENTS xiii

16.16.2.2 EndTestNo
16.16.2.3 Prevent
16.16.3 Member Data Documentation
16.16.3.1 begin_time
16.16.3.2 test_number
16.17mtk::UniStgGrid1D Class Reference
16.17.1 Detailed Description
16.17.2 Constructor & Destructor Documentation
16.17.2.1 UniStgGrid1D
16.17.2.2 UniStgGrid1D
16.17.2.3 UniStgGrid1D
16.17.2.4 ~UniStgGrid1D
16.17.3 Member Function Documentation
16.17.3.1 BindScalarField
16.17.3.2 BindVectorField
16.17.3.3 delta_x
16.17.3.4 discrete_domain_x
16.17.3.5 discrete_field_u
16.17.3.6 east_bndy_x
16.17.3.7 num_cells_x
16.17.3.8 west_bndy_x
16.17.3.9 WriteToFile
16.17.4 Friends And Related Function Documentation
16.17.4.1 operator<<
16.17.5 Member Data Documentation
16.17.5.1 delta_x
16.17.5.2 discrete_domain_x
16.17.5.3 discrete_field_u
16.17.5.4 east_bndy_x
16.17.5.5 nature
16.17.5.6 num_cells_x
16.17.5.7 west_bndy_x
16.18mtk::UniStgGrid2D Class Reference
16.18.1 Detailed Description
16.18.2 Constructor & Destructor Documentation
16.18.2.1 UniStgGrid2D
16.18.2.2 UniStgGrid2D

xiv CONTENTS

16.18.2.3 UniStgGrid2D	160
16.18.2.4 ~UniStgGrid2D	161
16.18.3 Member Function Documentation	161
16.18.3.1 BindScalarField	161
16.18.3.2 BindVectorFieldPComponent	161
16.18.3.3 BindVectorFieldQComponent	162
16.18.3.4 delta_x	162
16.18.3.5 delta_y	162
16.18.3.6 discrete_domain_x	162
16.18.3.7 discrete_domain_y	162
16.18.3.8 discrete_field_u	162
16.18.3.9 east_bndy_x	163
16.18.3.10north_bndy_y	163
16.18.3.11num_cells_x	163
16.18.3.12hum_cells_y	163
16.18.3.13south_bndy_y	164
16.18.3.14west_bndy_x	164
16.18.3.15WriteToFile	165
16.18.4 Friends And Related Function Documentation	165
16.18.4.1 operator<<	165
16.18.5 Member Data Documentation	165
16.18.5.1 delta_x	165
16.18.5.2 delta_y	166
16.18.5.3 discrete_domain_x	166
16.18.5.4 discrete_domain_y	166
16.18.5.5 discrete_field_u	166
16.18.5.6 east_bndy_x	166
16.18.5.7 nature	166
16.18.5.8 north_bndy_y	166
16.18.5.9 num_cells_x	166
16.18.5.10num_cells_y	166
16.18.5.11south_bndy_y	166
16.18.5.12west_bndy_x	166
17 File Documentation	169
17.1 examples/minimalistic_poisson_1d/minimalistic_poisson_1d.cc File Reference	
17.1.1 Detailed Description	

CONTENTS xv

17.1.2 Function Documentation
17.1.2.1 main
17.2 minimalistic_poisson_1d.cc
17.3 examples/poisson_1d/poisson_1d.cc File Reference
17.3.1 Detailed Description
17.3.2 Function Documentation
17.3.2.1 main
17.4 poisson_1d.cc
17.5 include/mtk.h File Reference
17.5.1 Detailed Description
17.6 mtk.h
17.7 include/mtk_bc_desc_1d.h File Reference
17.8 mtk_bc_desc_1d.h
17.9 include/mtk_blas_adapter.h File Reference
17.9.1 Detailed Description
17.10mtk_blas_adapter.h
17.11include/mtk_dense_matrix.h File Reference
17.11.1 Detailed Description
17.12mtk_dense_matrix.h
17.13include/mtk_div_1d.h File Reference
17.13.1 Detailed Description
17.14mtk_div_1d.h
17.15include/mtk_div_2d.h File Reference
17.15.1 Detailed Description
17.16mtk_div_2d.h
17.17include/mtk_enums.h File Reference
17.17.1 Detailed Description
17.18mtk_enums.h
17.19include/mtk_glpk_adapter.h File Reference
17.19.1 Detailed Description
17.20mtk_glpk_adapter.h
17.21include/mtk_grad_1d.h File Reference
17.21.1 Detailed Description
17.22mtk_grad_1d.h
17.23include/mtk_grad_2d.h File Reference
17.23.1 Detailed Description
17.24mtk_grad_2d.h

xvi CONTENTS

17.25include/mtk_interp_1d.h File Reference
17.25.1 Detailed Description
17.26mtk_interp_1d.h
17.27include/mtk_interp_2d.h File Reference
17.27.1 Detailed Description
17.28mtk_interp_2d.h
17.29include/mtk_lap_1d.h File Reference
17.29.1 Detailed Description
17.30mtk_lap_1d.h
17.31include/mtk_lap_2d.h File Reference
17.31.1 Detailed Description
17.32mtk_lap_2d.h
17.33include/mtk_lapack_adapter.h File Reference
17.33.1 Detailed Description
17.34mtk_lapack_adapter.h
17.35include/mtk_matrix.h File Reference
17.35.1 Detailed Description
17.36mtk_matrix.h
17.37include/mtk_quad_1d.h File Reference
17.37.1 Detailed Description
17.38mtk_quad_1d.h
17.39include/mtk_roots.h File Reference
17.39.1 Detailed Description
17.40mtk_roots.h
17.41include/mtk_tools.h File Reference
17.41.1 Detailed Description
17.42mtk_tools.h
17.43include/mtk_uni_stg_grid_1d.h File Reference
17.43.1 Detailed Description
17.44mtk_uni_stg_grid_1d.h
17.45include/mtk_uni_stg_grid_2d.h File Reference
17.45.1 Detailed Description
17.46mtk_uni_stg_grid_2d.h
17.47Makefile.inc File Reference
17.48Makefile.inc
17.49README.md File Reference
17.50README.md

CONTENTS xvii

17.51src/mtk_bc_desc_1d.cc File Reference
17.52mtk_bc_desc_1d.cc
17.53src/mtk_blas_adapter.cc File Reference
17.54mtk_blas_adapter.cc
17.55src/mtk_dense_matrix.cc File Reference
17.55.1 Detailed Description
17.56mtk_dense_matrix.cc
17.57src/mtk_div_1d.cc File Reference
17.57.1 Detailed Description
17.58mtk_div_1d.cc
17.59src/mtk_div_2d.cc File Reference
17.59.1 Detailed Description
17.60mtk_div_2d.cc
17.61src/mtk_glpk_adapter.cc File Reference
17.61.1 Detailed Description
17.62mtk_glpk_adapter.cc
17.63src/mtk_grad_1d.cc File Reference
17.63.1 Detailed Description
17.64mtk_grad_1d.cc
17.65src/mtk_grad_2d.cc File Reference
17.65.1 Detailed Description
17.66mtk_grad_2d.cc
17.67src/mtk_interp_1d.cc File Reference
17.67.1 Detailed Description
17.68mtk_interp_1d.cc
17.69src/mtk_lap_1d.cc File Reference
17.69.1 Detailed Description
17.70mtk_lap_1d.cc
17.71src/mtk_lap_2d.cc File Reference
17.72mtk_lap_2d.cc
17.73src/mtk_lapack_adapter.cc File Reference
17.73.1 Detailed Description
17.74mtk_lapack_adapter.cc
17.75src/mtk_matrix.cc File Reference
17.75.1 Detailed Description
17.76mtk_matrix.cc
17.77src/mtk_tools.cc File Reference

xviii CONTENTS

17.77.1 Detailed Description
17.78mtk_tools.cc
17.79src/mtk_uni_stg_grid_1d.cc File Reference
17.79.1 Detailed Description
17.80mtk_uni_stg_grid_1d.cc
17.81 src/mtk_uni_stg_grid_2d.cc File Reference
17.81.1 Detailed Description
17.82mtk_uni_stg_grid_2d.cc
17.83tests/mtk_blas_adapter_test.cc File Reference
17.83.1 Detailed Description
17.83.2 Function Documentation
17.83.2.1 main
17.84mtk_blas_adapter_test.cc
17.85tests/mtk_dense_matrix_test.cc File Reference
17.85.1 Detailed Description
17.85.2 Function Documentation
17.85.2.1 main
17.86mtk_dense_matrix_test.cc
17.87tests/mtk_div_1d_test.cc File Reference
17.87.1 Detailed Description
17.87.2 Function Documentation
17.87.2.1 main
17.88mtk_div_1d_test.cc
17.89tests/mtk_glpk_adapter_test.cc File Reference
17.89.1 Detailed Description
17.89.2 Function Documentation
17.89.2.1 main
17.90mtk_glpk_adapter_test.cc
17.91tests/mtk_grad_1d_test.cc File Reference
17.91.1 Detailed Description
17.91.2 Function Documentation
17.91.2.1 main
17.92mtk_grad_1d_test.cc
17.93tests/mtk_interp_1d_test.cc File Reference
17.93.1 Detailed Description
17.93.2 Function Documentation
17.93.2.1 main

CONTENTS xix

17.94mtk_interp_1d_test.cc
17.95tests/mtk_lap_1d_test.cc File Reference
17.95.1 Function Documentation
17.95.1.1 main
17.96mtk_lap_1d_test.cc
17.97tests/mtk_lapack_adapter_test.cc File Reference
17.97.1 Detailed Description
17.97.2 Function Documentation
17.97.2.1 main
17.98mtk_lapack_adapter_test.cc
17.99tests/mtk_uni_stg_grid_1d_test.cc File Reference
17.99.1 Detailed Description
17.99.2 Function Documentation
17.99.2.1 main
17.10@htk_uni_stg_grid_1d_test.cc
17.101ests/mtk_uni_stg_grid_2d_test.cc File Reference
17.101. Detailed Description
17.101. Function Documentation
17.101.2.1main
17.102htk_uni_stg_grid_2d_test.cc
Index 354

### Introduction

We define numerical methods that are based on discretizations preserving the properties of their continuum counterparts to be **mimetic**.

The **Mimetic Methods Toolkit (MTK)** is a C++ library for mimetic numerical methods. It is a set of classes for **mimetic quadratures**, **mimetic interpolation**, and **mimetic discretization methods** for the numerical solution of ordinary and partial differential equations.

#### 1.1 MTK Concerns

Since collaborative development efforts are definitely important in achieving the level of generality we intend the library to possess, we have divided the library's source code according to the designated purpose the classes possess within the library. These divisions (or concerns) are grouped by layers, and are hierarchically related by the dependence they have among them.

One concern is said to depend on another one, if the classes the first concern includes, rely on the classes the second concern includes.

In order of dependence these are:

- 1. Roots.
- 2. Enumerations.
- 3. Tools.
- 4. Data Structures.
- 5. Numerical Methods.
- 6. Grids.
- 7. Mimetic Operators.

### 1.2 MTK Flavors

The MTK collection of wrappers is:

1. MMTK: MATLAB wrappers collection for MTK; intended for sequential computations.

Others are being designed and developed.

2 Introduction

### 1.3 Contact, Support and Credits

The MTK is developed by researchers and adjuncts to the Computational Science Research Center (CSRC) at San Diego State University (SDSU).

Developers are members of:

- 1. Mimetic Numerical Methods Research and Development Group.
- 2. Computational Geoscience Research and Development Group.
- 3. Ocean Modeling Research and Development Group.

Currently the developers are:

- 1. Eduardo J. Sanchez, Ph.D. esanchez at mail dot sdsu dot edu ejspeiro
- 2. Jose E. Castillo, Ph.D. jcastillo at mail dot sdsu dot edu
- 3. Guillermo F. Miranda, Ph.D. unigrav at hotmail dot com
- 4. Christopher P. Paolini, Ph.D. paolini at engineering dot sdsu dot edu
- 5. Angel Boada.
- 6. Johnny Corbino.
- 7. Raul Vargas-Navarro.

### 1.4 Acknowledgements and Contributions

The authors would like to acknowledge valuable advising, contributions and feedback, from research personnel at the Computational Science Research Center at San Diego State University, which were vital to the fruition of this work. Specifically, our thanks go to (alphabetical order):

- 1. Mohammad Abouali, Ph.D.
- 2. Dany De Cecchis, Ph.D.
- 3. Julia Rossi.

# **Programming Tools**

The development of MTK has been made possible through the use of the following applications:

- 1. Editor: Kate KDE Advanced Text Editor. Version 3.13.3. Using KDE Development Platform 4.13.3 (C) 2000-2005. The Kate Authors.
- 2. Compiler: gcc version 4.4.5 (Ubuntu/Linaro 4.4.4-14ubuntu5). Copyright (C) 2013 Free Software Foundation, Inc.
- 3. Debugger: GNU gdb (Ubuntu 7.7.1-0ubuntu5~14.04.2) 7.7.1. Copyright (C) 2014 Free Software Foundation, Inc.

1	Programming Tools

## **Licensing and Modifications**

Copyright (C) 2015, Computational Science Research Center, San Diego State University. All rights reserved.

Redistribution and use in source and binary forms, with or without modification, are permitted provided that the following conditions are met:

- 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu and a copy of the modified files should be reported once modifications are completed. Documentation related to said modifications should be included.
- 2. Redistributions of source code must be done through direct downloads from the project's GitHub page: http-://www.csrc.sdsu.edu/mtk
- 3. Redistributions of source code must retain the above copyright notice, this list of conditions and the following disclaimer.
- 4. Redistributions in binary form must reproduce the above copyright notice, this list of conditions and the following disclaimer in the documentation and/or other materials provided with the distribution.
- 5. Usage of the binary form on proprietary applications shall require explicit prior written permission from the the copyright holders.
- 6. Neither the name of the copyright holder nor the names of its contributors may be used to endorse or promote products derived from this software without specific prior written permission.

The copyright holders provide no reassurances that the source code provided does not infringe any patent, copyright, or any other intellectual property rights of third parties. The copyright holders disclaim any liability to any recipient for claims brought against recipient by any third party for infringement of that parties intellectual property rights.

THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.

Licensing and	Modifications
---------------	---------------

## **Read Me File and Installation Instructions**

**README File for the Mimetic Methods Toolkit (MTK)** 

By: Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu

### 1. Description

We define numerical methods that are based on discretizations preserving the properties of their continuum counterparts to be  $\mathbf{mimetic}$ .

The Mimetic Methods Toolkit (MTK) is a C++ library for mimetic numerical methods. It is arranged as a set of classes for mimetic quadratures, mimetic interpolation, and mimetic discretization methods for the numerical solution of ordinary and partial differential equations.

### 2. Dependencies

This README assumes all of these dependencies are installed in the following folder:

\$(HOME)/Libraries/

In this version, the MTK optionally uses ATLAS-optimized BLAS and LAPACK routines for the internal computation on some of the layers. However, ATLAS requires both BLAS and LAPACK in order to create their optimized distributions. Therefore, the following dependencies tree arises:

#### For Linux:

```
    LAPACK - Available from: http://www.netlib.org/lapack/
        1. BLAS - Available from: http://www.netlib.org/blas/
    GLPK - Available from: https://www.gnu.org/software/glpk/
    (Optional) ATLAS - Available from: http://math-atlas.sourceforge.net/
        1. BLAS - Available from: http://www.netlib.org/blas/
        2. LAPACK - Available from: http://www.netlib.org/lapack/
    (Optional) Valgrind - Available from: http://valgrind.org/
    (Optional) Doxygen - Available from http://www.stack.nl/~dimitri/doxygen/
```

#### For OS X:

```
1. GLPK - Available from: https://www.gnu.org/software/glpk/
```

#### 3. Installation

#### PART 1. CONFIGURATION OF THE MAKEFILE.

The following steps are required the build and test the MTK. Please use the accompanying Makefile.inc file, which should provide a solid template to start with. The following command provides help on the options for make:

```
$ make help
----
Makefile for the MTK.
Options are:
```

```
- make: builds only the library and the examples.
- all: builds the library, the examples and the documentation.
- mtklib: builds the library, i.e. generates the archive files.
- test: generates the tests.
- example: generates the examples.
- gendoc: generates the documentation for the library.
- clean: cleans ALL the generated files.
- cleanlib: cleans the generated archive and object files.
- cleantest: cleans the generated tests executables.
- cleanexample: cleans the generated examples executables.
```

#### PART 2. BUILD THE LIBRARY.

```
$ make

If successful you'll read (before building the examples):
---- Library created! Check in /home/ejspeiro/Dropbox/MTK/lib

Examples and tests will also be built.
```

#### 4. Frequently Asked Questions

```
Q: Why haven't you guys implemented GBS to build the library?
A: I'm on it as we speak!;)

Q: Is there any main reference when it comes to the theory on Mimetic Methods?
A: Yes! Check: http://www.csrc.sdsu.edu/mimetic-book

Q: Do I need to generate the documentation myself?
A: You can if you want to... but if you DO NOT want to, just go to our website.
```

### 5. Contact, Support, and Credits

```
The MTK is developed by researchers and adjuncts to the Computational Science Research Center (CSRC) at San Diego State University (SDSU).
```

Developers are members of:

- 1. Mimetic Numerical Methods Research and Development Group.
- 2. Computational Geoscience Research and Development Group.
- 3. Ocean Modeling Research and Development Group.

Currently the developers are:

#### Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu - ejspeiro

- 2. Jose E. Castillo, Ph.D. jcastillo at mail dot sdsu dot edu
- 3. Guillermo F. Miranda, Ph.D. unigrav at hotmail dot com
- 4. Christopher P. Paolini, Ph.D. paolini at engineering dot sdsu dot edu
- 5. Angel Boada.
- 6. Johnny Corbino.
- 7. Raul Vargas-Navarro.

Finally, please feel free to contact me with suggestions or corrections:

Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu - ejspeiro

Thanks and happy coding!

## **Tests and Test Architectures**

Tests are given in the files list section. They are provided in the /tests/ folder within the distributed software.

In this page we intend to make a summary of all of the architectures in where the MTK has been tested. The MTK is intended to be as portable as possible throughout architectures. The following architectures have provided flawless installations of the API and correct execution of the examples:

1. Linux 3.2.0-23-generic-pae #36-Ubuntu SMP i386 GNU/Linux
 Intel(R) Pentium(R) M processor 1.73GHz 2048 KB of cache and stepping of 8
 gcc version 4.6.3 (Ubuntu/Linaro 4.6.3-lubuntu5)

Further architectures will be tested!

Tests	and	Teet	Arch	nited	tures

# **Examples**

Examples are given in the files list section. They are provided in the /examples/ folder within the distributed software.

14 **Examples** 

# **User Manual, References and Theory**

The main source of references for this work can be found in:

http://www.csrc.sdsu.edu/mimetic-book/

However, a .PDF copy of this manual can be found here.

User Manual,	References	and	Theory

## **Todo List**

#### Member mtk::DenseMatrix::Kron (const DenseMatrix &aa, const DenseMatrix &bb)

Implement Kronecker product using the BLAS.

#### Member mtk::DenseMatrix::OrderColMajor ()

Improve this so that no new arrays have to be created.

#### Member mtk::DenseMatrix::OrderRowMajor ()

Improve this so that no new arrays have to be created.

#### Member mtk::DenseMatrix::Transpose ()

Improve this so that no extra arrays have to be created.

#### Class mtk::GLPKAdapter

Rescind from the GLPK as the numerical core for CLO problems.

#### Member mtk::Matrix::IncreaseNumNull ()

Review the definition of sparse matrices properties.

#### Member mtk::Matrix::IncreaseNumZero ()

Review the definition of sparse matrices properties.

#### Member mtk::Tools::Prevent (const bool condition, const char \*fname, int lineno, const char \*fxname)

Check if this is the best way of stalling execution.

#### Member mtk::Tools::test\_number\_

Check usage of static methods and private members.

#### File mtk\_div\_1d.cc

Overload ostream operator as in mtk::Lap1D.

Implement creation of ■ w. mtk::BLASAdapter.

#### File mtk\_glpk\_adapter\_test.cc

Test the mtk::GLPKAdapter class.

#### File mtk\_grad\_1d.cc

Overload ostream operator as in mtk::Lap1D.

Implement creation of ■ w. mtk::BLASAdapter.

### File mtk\_lapack\_adapter\_test.cc

Test the mtk::LAPACKAdapter class.

18 Todo List

#### File mtk\_quad\_1d.h

Implement this class.

#### File mtk\_roots.h

Documentation should (better?) capture effects from selective compilation.

Test selective precision mechanism.

#### File mtk\_uni\_stg\_grid\_1d.h

Create overloaded binding routines that read data from files.

#### File mtk\_uni\_stg\_grid\_2d.h

Create overloaded binding routines that read data from files.

# **Bug List**

Member mtk::Matrix::set\_num\_null (int in)

-nan assigned on construction time due to num\_values\_ being 0.

Member mtk::Matrix::set\_num\_zero (int in)

-nan assigned on construction time due to num\_values\_ being 0.

20	Bug List

# **Module Index**

## 10.1 Modules

Here is a list of all modules:

oots	1
numerations	3
xecution tools	Ę
ata structures	$\epsilon$
umerical methods	7
rids	ξ
limetic operators	S

22	Module Index

# Namespace Index

1	1		1	Na	am	esp	oac	e l	_ist
---	---	--	---	----	----	-----	-----	-----	------

Here is a list	t of all namespaces with brief descriptions:
mtk	
	Mimetic Methods Toolkit namespace

24 Namespace Index

# **Class Index**

## 12.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:	
mtk::BCDesc1D	 5
mtk::BLASAdapter	
Adapter class for the BLAS API	 5
mtk::DenseMatrix	
Defines a common dense matrix, using a 1D array	 5
mtk::Div1D	
Implements a 1D mimetic divergence operator	 7
mtk::Div2D	
mtk::GLPKAdapter	
Adapter class for the GLPK API	 9
mtk::Grad1D	
Implements a 1D mimetic gradient operator	 9
mtk::Grad2D	
mtk::Interp1D	
Implements a 1D interpolation operator	 10
mtk::Interp2D	 11
mtk::Lap1D	
Implements a 1D mimetic Laplacian operator	 11
mtk::Lap2D	 11
mtk::LAPACKAdapter	
Adapter class for the LAPACK API	 12
mtk::Matrix	
Definition of the representation of a matrix in the MTK	 12
mtk::Quad1D	
Implements a 1D mimetic quadrature	 14
mtk::Tools	
Tool manager class	 14
mtk::UniStgGrid1D	
Uniform 1D Staggered Grid	 14
mtk::UniStgGrid2D	
Haife and OD Observational Original	4.5

26	Class Index

# File Index

### 13.1 File List

Here is a list of all files with brief descriptions:

Makefile.inc
examples/minimalistic_poisson_1d/minimalistic_poisson_1d.cc
Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs
examples/poisson_1d/poisson_1d.cc
Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs
include/mtk.h
Includes the entire API
include/mtk_bc_desc_1d.h
include/mtk_blas_adapter.h
Adapter class for the BLAS API
include/mtk_dense_matrix.h
Defines a common dense matrix, using a 1D array
include/mtk_div_1d.h
Includes the definition of the class Div1D
include/mtk_div_2d.h
Includes the definition of the class Div2D
include/mtk_enums.h
Considered enumeration types in the MTK
include/mtk_glpk_adapter.h
Adapter class for the GLPK API
include/mtk_grad_1d.h
Includes the definition of the class Grad1D
include/mtk_grad_2d.h
Includes the definition of the class Grad2D
include/mtk_interp_1d.h
Includes the definition of the class Interp1D
include/mtk_interp_2d.h
Includes the definition of the class Interp2D
include/mtk_lap_1d.h
Includes the definition of the class Lap1D
include/mtk_lap_2d.h
Includes the implementation of the class Lap2D
$-\cdot$
Adapter class for the LAPACK API

28 File Index

include/mtk_matrix.h  Definition of the representation of a matrix in the MTK
include/mtk_quad_1d.h
Includes the definition of the class Quad1D
include/mtk_roots.h
Fundamental definitions to be used across all classes of the MTK
include/mtk_tools.h
Tool manager class
include/mtk_uni_stg_grid_1d.h
Definition of an 1D uniform staggered grid
include/mtk_uni_stg_grid_2d.h
Definition of an 2D uniform staggered grid
src/mtk_bc_desc_1d.cc
src/mtk_blas_adapter.cc
src/mtk_dense_matrix.cc
Implements a common dense matrix, using a 1D array
src/mtk div 1d.cc
Implements the class Div1D
src/mtk div 2d.cc
Implements the class Div2D
src/mtk glpk adapter.cc
Adapter class for the GLPK API
src/mtk grad 1d.cc
Implements the class Grad1D
src/mtk_grad_2d.cc
Implements the class Grad2D
·
src/mtk_interp_1d.cc
Includes the implementation of the class Interp1D
src/mtk_lap_1d.cc
Includes the implementation of the class Lap1D
src/mtk_lap_2d.cc
src/mtk_lapack_adapter.cc
Adapter class for the LAPACK API
src/mtk_matrix.cc
Implementing the representation of a matrix in the MTK
src/mtk_tools.cc
Implements a execution tool manager class
src/mtk_uni_stg_grid_1d.cc
Implementation of an 1D uniform staggered grid
src/mtk_uni_stg_grid_2d.cc
Implementation of a 2D uniform staggered grid
tests/mtk_blas_adapter_test.cc
Test file for the mtk::BLASAdapter class
tests/mtk_dense_matrix_test.cc
Test file for the mtk::DenseMatrix class
tests/mtk_div_1d_test.cc
Testing the mimetic 1D divergence, constructed with the CBS algorithm
tests/mtk_glpk_adapter_test.cc
Test file for the mtk::GLPKAdapter class
tests/mtk_grad_1d_test.cc
Testing the mimetic 1D gradient, constructed with the CBS algorithm
tests/mtk_interp_1d_test.cc
Testing the 1D interpolation
tests/mtk_lap_1d_test.cc

13.1 File List 29

tests/mtk_lapack_adapter_test.cc	
Test file for the mtk::LAPACKAdapter class	340
tests/mtk_uni_stg_grid_1d_test.cc	
Test file for the mtk::UniStgGrid1D class	348
tests/mtk_uni_stg_grid_2d_test.cc	
Test file for the mtk::UniStgGrid2D class	35

30	File Index

## **Module Documentation**

### 14.1 Roots.

Fundamental execution parameters and defined types.

#### **Typedefs**

· typedef float mtk::Real

Users can simply change this to build a double- or single-precision MTK.

#### **Variables**

const float mtk::kZero {0.0f}

MTK's zero defined according to selective compilation.

const float mtk::kOne {1.0f}

MTK's one defined according to selective compilation.

const float mtk::kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

• const int mtk::kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

const float mtk::kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

const int mtk::kCriticalOrderAccuracyDiv {8}

At this order (and higher) we must use the CBSA to construct.

• const int mtk::kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

#### 14.1.1 Detailed Description

Fundamental execution parameters and defined types.

32 Module Documentation

```
14.1.2 Typedef Documentation
14.1.2.1 mtk::Real
Definition at line 83 of file mtk_roots.h.
14.1.3 Variable Documentation
14.1.3.1 mtk::kCriticalOrderAccuracyDiv {8}
Definition at line 157 of file mtk roots.h.
14.1.3.2 mtk::kCriticalOrderAccuracyGrad {10}
Definition at line 166 of file mtk_roots.h.
14.1.3.3 mtk::kDefaultMimeticThreshold {1e-6f}
Warning
     Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 147 of file mtk_roots.h.
14.1.3.4 mtk::kDefaultOrderAccuracy {2}
Warning
      Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 133 of file mtk roots.h.
14.1.3.5 mtk::kDefaultTolerance {1e-7f}
Definition at line 121 of file mtk_roots.h.
14.1.3.6 mtk::kOne {1.0f}
Warning
     Declared as double if MTK_PRECISION_DOUBLE is defined.
Definition at line 108 of file mtk_roots.h.
14.1.3.7 mtk::kZero {0.0f}
Warning
      Declared as double if MTK_PRECISION_DOUBLE is defined.
```

Definition at line 107 of file mtk\_roots.h.

14.2 Enumerations. 33

#### 14.2 Enumerations.

Enumerations.

#### **Enumerations**

enum mtk::MatrixStorage { mtk::DENSE, mtk::BANDED, mtk::CRS }

Considered matrix storage schemes to implement sparse matrices.

enum mtk::MatrixOrdering { mtk::ROW\_MAJOR, mtk::COL\_MAJOR }

Considered matrix ordering (for Fortran purposes).

enum mtk::FieldNature { mtk::SCALAR, mtk::VECTOR }

Nature of the field discretized in a given grid.

enum mtk::DirInterp { mtk::SCALAR\_TO\_VECTOR, mtk::VECTOR\_TO\_SCALAR }

1D interpolation operator.

#### 14.2.1 Detailed Description

Enumerations.

#### 14.2.2 Enumeration Type Documentation

14.2.2.1 enum mtk::DirInterp

Implements an arithmetic average.

Enumerator

```
SCALAR_TO_VECTOR
VECTOR_TO_SCALAR
```

Definition at line 127 of file mtk\_enums.h.

14.2.2.2 enum mtk::FieldNature

Fields can be scalar or vector in nature.

See Also

```
https://en.wikipedia.org/wiki/Scalar_field
https://en.wikipedia.org/wiki/Vector_field
```

#### Enumerator

SCALAR Scalar-valued field.

VECTOR Vector-valued field.

Definition at line 113 of file mtk enums.h.

34 Module Documentation

#### 14.2.2.3 enum mtk::MatrixOrdering

Row-major ordering is used for most application in C/C++. For Fortran purposes, the matrices must be listed in a column-major ordering.

#### See Also

```
https://en.wikipedia.org/wiki/Row-major_order
```

#### Enumerator

```
ROW_MAJOR Row-major ordering (C/C++).

COL_MAJOR Column-major ordering (Fortran).
```

Definition at line 95 of file mtk\_enums.h.

#### 14.2.2.4 enum mtk::MatrixStorage

The considered sparse storage schemes are selected so that these are compatible with some of the most used mathematical APIs, as follows: DENSE and BANDED for BLAS, LAPACK, and Scalapack. Finally, CRS for Superlu.

#### Enumerator

**DENSE** Dense matrices, implemented as a 1D array: DenseMatrix.

**BANDED** Banded matrices ala LAPACK and ScaLAPACK: Must be implemented.

CRS Compressed-Rows Storage: Must be implemented.

Definition at line 77 of file mtk\_enums.h.

14.3 Execution tools. 35

## 14.3 Execution tools.

Tools to ensure execution correctness.

#### Classes

class mtk::Tools

Tool manager class.

## 14.3.1 Detailed Description

Tools to ensure execution correctness.

36 Module Documentation

### 14.4 Data structures.

Fundamental data structures.

#### Classes

• class mtk::DenseMatrix

Defines a common dense matrix, using a 1D array.

class mtk::Matrix

Definition of the representation of a matrix in the MTK.

### 14.4.1 Detailed Description

Fundamental data structures.

14.5 Numerical methods. 37

### 14.5 Numerical methods.

Adapter classes and auxiliary numerical methods.

#### Classes

• class mtk::BLASAdapter

Adapter class for the BLAS API.

• class mtk::GLPKAdapter

Adapter class for the GLPK API.

• class mtk::LAPACKAdapter

Adapter class for the LAPACK API.

#### 14.5.1 Detailed Description

Adapter classes and auxiliary numerical methods.

38 Module Documentation

### 14.6 Grids.

Uniform rectangular staggered grids.

#### **Classes**

• class mtk::UniStgGrid1D

Uniform 1D Staggered Grid.

class mtk::UniStgGrid2D

Uniform 2D Staggered Grid.

#### 14.6.1 Detailed Description

Uniform rectangular staggered grids.

### 14.7 Mimetic operators.

Mimetic operators.

#### Classes

class mtk::Div1D

Implements a 1D mimetic divergence operator.

· class mtk::Grad1D

Implements a 1D mimetic gradient operator.

class mtk::Interp1D

Implements a 1D interpolation operator.

· class mtk::Lap1D

Implements a 1D mimetic Laplacian operator.

· class mtk::Quad1D

Implements a 1D mimetic quadrature.

#### 14.7.1 Detailed Description

Mimetic operators.

40 **Module Documentation** 

## **Namespace Documentation**

### 15.1 mtk Namespace Reference

Mimetic Methods Toolkit namespace.

#### **Classes**

- class BCDesc1D
- class BLASAdapter

Adapter class for the BLAS API.

class DenseMatrix

Defines a common dense matrix, using a 1D array.

class Div1D

Implements a 1D mimetic divergence operator.

- class Div2D
- · class GLPKAdapter

Adapter class for the GLPK API.

· class Grad1D

Implements a 1D mimetic gradient operator.

- class Grad2D
- class Interp1D

Implements a 1D interpolation operator.

- class Interp2D
- class Lap1D

Implements a 1D mimetic Laplacian operator.

- class Lap2D
- · class LAPACKAdapter

Adapter class for the LAPACK API.

class Matrix

Definition of the representation of a matrix in the MTK.

· class Quad1D

Implements a 1D mimetic quadrature.

• class Tools

Tool manager class.

· class UniStgGrid1D

Uniform 1D Staggered Grid.

class UniStgGrid2D

Uniform 2D Staggered Grid.

#### **Typedefs**

typedef float Real

Users can simply change this to build a double- or single-precision MTK.

#### **Enumerations**

enum MatrixStorage { DENSE, BANDED, CRS }

Considered matrix storage schemes to implement sparse matrices.

enum MatrixOrdering { ROW\_MAJOR, COL\_MAJOR }

Considered matrix ordering (for Fortran purposes).

enum FieldNature { SCALAR, VECTOR }

Nature of the field discretized in a given grid.

enum DirInterp { SCALAR\_TO\_VECTOR, VECTOR\_TO\_SCALAR }

1D interpolation operator.

#### **Functions**

- float snrm2 (int \*n, float \*x, int \*incx)
- void saxpy\_ (int \*n, float \*sa, float \*sx, int \*incx, float \*sy, int \*incy)
- void sgemv\_ (char \*trans, int \*m, int \*n, float \*alpha, float \*a, int \*lda, float \*x, int \*incx, float \*beta, float \*y, int \*incy)
- void sgemm\_ (char \*transa, char \*transb, int \*m, int \*n, int \*k, double \*alpha, double \*a, int \*lda, double \*b, aamm int \*ldb, double \*beta, double \*c, int \*ldc)
- std::ostream & operator<< (std::ostream &stream, mtk::DenseMatrix &in)</li>
- std::ostream & operator<< (std::ostream &stream, mtk::Div1D &in)</li>
- std::ostream & operator<< (std::ostream &stream, mtk::Grad1D &in)</li>
- std::ostream & operator<< (std::ostream &stream, mtk::Interp1D &in)</li>
- std::ostream & operator<< (std::ostream &stream, mtk::Lap1D &in)</li>
- void sgesv (int \*n, int \*nrhs, Real \*a, int \*lda, int \*ipiv, Real \*b, int \*ldb, int \*info)
- void sgels\_ (char \*trans, int \*m, int \*n, int \*nrhs, Real \*a, int \*lda, Real \*b, int \*ldb, Real \*work, int \*lwork, int \*info)

Single-precision GEneral matrix Least Squares solver.

void sgeqrf (int \*m, int \*n, Real \*a, int \*lda, Real \*tau, Real \*work, int \*lwork, int \*info)

Single-precision GEneral matrix QR Factorization.

• void sormqr\_ (char \*side, char \*trans, int \*m, int \*n, int \*k, Real \*a, int \*lda, Real \*tau, Real \*c, int \*ldc, Real \*work, int \*lwork, int \*info)

Single-precision Orthogonal Matrix from QR factorization.

- std::ostream & operator<< (std::ostream &stream, mtk::UniStgGrid1D &in)</li>
- std::ostream & operator<< (std::ostream &stream, mtk::UniStgGrid2D &in)</li>

#### **Variables**

const float kZero {0.0f}

MTK's zero defined according to selective compilation.

• const float kOne {1.0f}

MTK's one defined according to selective compilation.

const float kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

const int kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

const float kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

const int kCriticalOrderAccuracyDiv {8}

At this order (and higher) we must use the CBSA to construct.

• const int kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

#### 15.1.1 Function Documentation

- 15.1.1.1 std::ostream& mtk::operator << ( std::ostream & stream, mtk::Interp1D & in )
  - 1. Print approximating coefficients for the interior.

Definition at line 66 of file mtk\_interp\_1d.cc.

- 15.1.1.2 std::ostream& mtk::operator<< ( std::ostream & stream, mtk::UniStgGrid2D & in )
  - 1. Print spatial coordinates.
  - 2. Print scalar field.

Definition at line 66 of file mtk\_uni\_stg\_grid\_2d.cc.

- 15.1.1.3 std::ostream& mtk::operator << ( std::ostream & stream, mtk::UniStgGrid1D & in )
  - 1. Print spatial coordinates.
  - 2. Print scalar field.

Definition at line 68 of file mtk\_uni\_stg\_grid\_1d.cc.

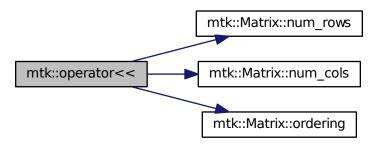
- 15.1.1.4 std::ostream& mtk::operator<< ( std::ostream & stream, mtk::Lap1D & in )
  - 1. Print order of accuracy.
  - 2. Print approximating coefficients for the interior.
  - 3. No weights, thus print the mimetic boundary coefficients.

Definition at line 73 of file mtk lap 1d.cc.

15.1.1.5 std::ostream& mtk::operator<< ( std::ostream & stream, mtk::DenseMatrix & in )

Definition at line 75 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



15.1.1.6 std::ostream& mtk::operator<< ( std::ostream & stream, mtk::Grad1D & in )

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk\_grad\_1d.cc.

15.1.1.7 std::ostream& mtk::operator<< ( std::ostream & stream, mtk::Div1D & in )

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk\_div\_1d.cc.

15.1.1.8 void mtk::saxpy\_( int \* n, float \* sa, float \* sx, int \* incx, float \* sy, int \* incy)

Here is the caller graph for this function:



15.1.1.9 void mtk::sgels\_( char \* trans, int \* m, int \* n, int \* nrhs, Real \* a, int \* lda, Real \* b, int \* ldb, Real \* work, int \* lwork, int \* info )

SGELS solves overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and m >= n: find the least squares solution of an overdetermined system, i.e., solve the least squares problem

```
minimize || B - A*X ||.
```

- 2. If TRANS = 'N' and m < n: find the minimum norm solution of an underdetermined system A \* X = B.
- 3. If TRANS = 'T' and m > = n: find the minimum norm solution of an undetermined system A\*\*T \* X = B.
- 4. If TRANS = 'T' and m < n: find the least squares solution of an overdetermined system, i.e., solve the least squares problem

```
minimize || B - A**T * X ||.
```

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

#### See Also

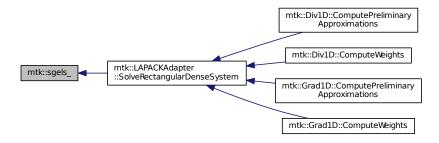
http://www.math.utah.edu/software/lapack/lapack-s/sgels.html

#### **Parameters**

in	trans	Am I giving the transpose of the matrix?
in	т	The number of rows of the matrix a. $m \ge 0$ .
in	n	The number of columns of the matrix a. $n \ge 0$ .
in	nrhs	The number of right-hand sides.
in,out	а	On entry, the m-by-n matrix a.
in	lda	The leading dimension of a. $lda \ge max(1,m)$ .

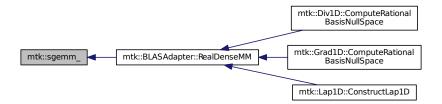
in,out	b	On entry, matrix b of right-hand side vectors.	
in	ldb	The leading dimension of b. $ldb \ge max(1,m,n)$ .	
in,out	work	On exit, if info = 0, work(1) is optimal lwork.	
in,out	lwork	The dimension of the array work.	
in,out	info	If info = 0, then successful exit.	

Here is the caller graph for this function:



15.1.1.10 void mtk::sgemm\_ ( char \* transa, char \* transb, int \* m, int \* n, int \* k, double \* a, int \* a, double \* a, int \* a, double \* a, int \* a, double \* a, int \* a

Here is the caller graph for this function:



15.1.1.11 void mtk::sgemv\_( char \* trans, int \* m, int \* n, float \* a, float \* a, int \* a, float \* a, int \* a, int \* a, float \* a, float \* a, float \* a, float \* a, int \* a, float \*

Here is the caller graph for this function:



15.1.1.12 void mtk::sgeqrf\_( int \* m, int \* n, Real \* a, int \* Ida, Real \* tau, Real \* work, int \* Iwork, int \*

Single-Precision Orthogonal Make Q from QR: dormqr\_ overwrites the general real M-by-N matrix C with (Table 1):

TRANS = 'N': Q \* C C \* Q TRANS = 'T': Q\*\*T \* C C \* Q\*\*T

where Q is a real orthogonal matrix defined as the product of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of order N if SIDE = 'R'.

#### See Also

http://www.netlib.org/lapack/explore-html/df/d97/sgeqrf\_8f.html

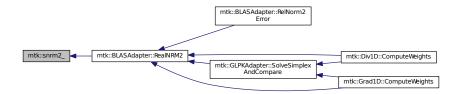
#### **Parameters**

in	m	The number of columns of the matrix $a. n \ge 0$ .	
in	n	The number of columns of the matrix a. $n \ge 0$ .	
in,out	а	On entry, the n-by-n matrix a.	
in	lda	Leading dimension matrix. LDA $\geq$ = max(1,M).	
in,out	tau	Scalars from elementary reflectors. min(M,N).	
in,out	work	Workspace. info = 0, work(1) is optimal lwork.	
in	lwork	The dimension of work. $ $   $ $	
in	info	info = 0: successful exit.	

15.1.1.13 void mtk::sgesv\_( int \* n, int \* nrhs, Real \* a, int \* Ida, int \* ipiv, Real \* b, int \* Idb, int \* info )

15.1.1.14 float mtk::snrm2\_( int \* n, float \* x, int \* incx)

Here is the caller graph for this function:



15.1.1.15 void mtk::sormqr\_( char \* side, char \* trans, int \* m, int \* n, int \* k, Real \* a, int \* lda, Real \* tau, Real \* c, int \* ldc, Real \* work, int \* lwork, int \* info )

Single-Precision Orthogonal Make Q from QR: sormqr\_ overwrites the general real M-by-N matrix C with (Table 1):

TRANS = 'N': Q \* C C \* Q TRANS = 'T': Q\*\*T \* C C \* Q\*\*T

where Q is a real orthogonal matrix defined as the product of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of order N if SIDE = 'R'.

#### See Also

http://www.netlib.org/lapack/explore-html/d0/d98/sormqr\_8f\_source.html

#### **Parameters**

	-!-!-	One Table 4 above	
in	side	See Table 1 above.	
in	trans	See Table 1 above.	
in	т	Number of rows of the C matrix.	
in	n	Number of columns of the C matrix.	
in	k	Number of reflectors.	
in,out	а	The matrix containing the reflectors.	
in	lda	The dimension of work. Iwork $\geq \max(1,n)$ .	
in	tau	Scalar factors of the elementary reflectors.	
in	С	Output matrix.	
in	ldc	Leading dimension of the output matrix.	
in,out	work	Workspace. info = 0, work(1) optimal lwork.	
in	lwork	The dimension of work.	

in,out	info	info = 0: successful exit.

Namespace I	Documentation
-------------	---------------

## **Class Documentation**

### 16.1 mtk::BCDesc1D Class Reference

#include <mtk\_bc\_desc\_1d.h>
Collaboration diagram for mtk::BCDesc1D:

mtk::BCDesc1D

- + ImposeOnOperator()
- + ImposeOnGrid()

#### **Static Public Member Functions**

- static void ImposeOnOperator (DenseMatrix &matrix, const std::vector< Real > &west, const std::vector< Real > &east)
- static void ImposeOnGrid (UniStgGrid1D &grid, const Real &omega, const Real &epsilon)

#### 16.1.1 Detailed Description

Definition at line 9 of file mtk\_bc\_desc\_1d.h.

#### 16.1.2 Member Function Documentation

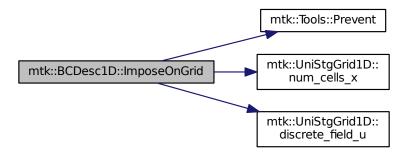
52 Class Documentation

16.1.2.1 void mtk::BCDesc1D::ImposeOnGrid ( mtk::UniStgGrid1D & grid, const Real & omega, const Real & epsilon )

- 1. Assign the west condition.
- 2. Assign the east condition.

Definition at line 30 of file mtk\_bc\_desc\_1d.cc.

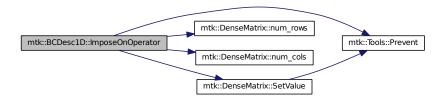
Here is the call graph for this function:



- 16.1.2.2 void mtk::BCDesc1D::ImposeOnOperator ( mtk::DenseMatrix & matrix, const std::vector < Real > & west, const std::vector < Real > & east ) [static]
  - 1. Assign the west array.
  - 2. Assign the east array.

Definition at line 5 of file mtk\_bc\_desc\_1d.cc.

Here is the call graph for this function:



The documentation for this class was generated from the following files:

- include/mtk\_bc\_desc\_1d.h
- src/mtk\_bc\_desc\_1d.cc

# 16.2 mtk::BLASAdapter Class Reference

Adapter class for the BLAS API.

#include <mtk\_blas\_adapter.h>

Collaboration diagram for mtk::BLASAdapter:

# mtk::BLASAdapter

- + RealNRM2()
- + RealAXPY()
- + RelNorm2Error()
- + RealDenseMV()
- + RealDenseMM()

### **Static Public Member Functions**

• static Real RealNRM2 (Real \*in, int &in length)

Compute the  $||\mathbf{x}||_2$  of given array  $\mathbf{x}$ .

• static void RealAXPY (Real alpha, Real \*xx, Real \*yy, int &in\_length)

Real-Arithmetic Scalar-Vector plus a Vector.

• static Real RelNorm2Error (Real \*computed, Real \*known, int length)

Computes the relative norm-2 of the error.

static void RealDenseMV (Real &alpha, DenseMatrix &aa, Real \*xx, Real &beta, Real \*yy)

Real-Arithmetic General (Dense matrices) Matrix-Vector Multiplier.

• static DenseMatrix RealDenseMM (DenseMatrix &aa, DenseMatrix &bb)

Real-Arithmetic General (Dense matrices) Matrix-Matrix multiplier.

# 16.2.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the BLAS.

The **BLAS** (**Basic Linear Algebra Subprograms**) are routines that provide standard building blocks for performing basic vector and matrix operations. The Level 1 BLAS perform scalar, vector and vector-vector operations, the Level 2 BLAS perform matrix-vector operations, and the Level 3 BLAS perform matrix operations.

### See Also

http://www.netlib.org/blas/

Definition at line 96 of file mtk blas adapter.h.

# 16.2.2 Member Function Documentation

16.2.2.1 void mtk::BLASAdapter::RealAXPY ( mtk::Real alpha, mtk::Real \* xx, mtk::Real \* yy, int & in\_length ) [static]

Performs

$$\mathbf{y} := \alpha \mathbf{A} mathb f x + \mathbf{y}$$

### **Parameters**

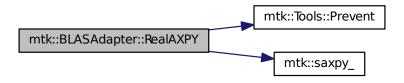
in	alpha	Scalar of the first array.
in	XX	First array.
in	уу	Second array.
in	in_length	Lengths of the given arrays.

### Returns

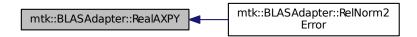
Norm-2 of the given array.

Definition at line 339 of file mtk\_blas\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.2.2.2 mtk::DenseMatrix mtk::BLASAdapter::RealDenseMM ( mtk::DenseMatrix & aa, mtk::DenseMatrix & bb ) [static]

Performs:

C := AB

### **Parameters**

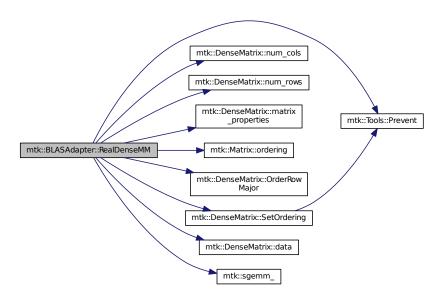
in	aa	First matrix.
in	bb	Second matrix.

# See Also

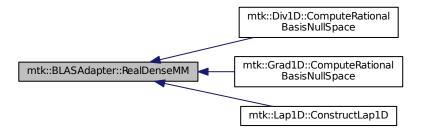
http://ejspeiro.github.io/Netlib-and-CPP/

Definition at line 409 of file mtk\_blas\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.2.2.3 void mtk::BLASAdapter::RealDenseMV ( mtk::Real & alpha, mtk::DenseMatrix & aa, mtk::Real \* xx, mtk::Real & beta, mtk::Real \* yy ) [static]

Performs

$$\mathbf{y} := \alpha \mathbf{A} \mathbf{x} + \beta \mathbf{y}$$

### **Parameters**

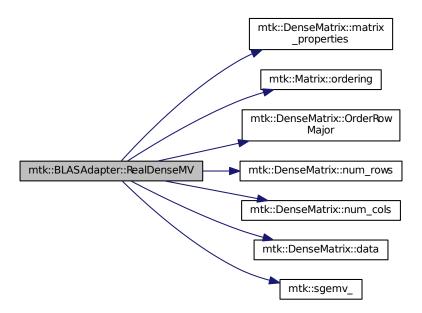
in	alpha	First scalar.
in	aa	Given matrix.
in	XX	First vector.
in	beta	Second scalar.
in,out	уу	Second vector (output).

### See Also

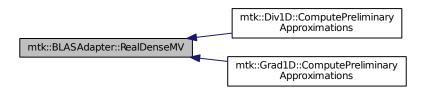
http://ejspeiro.github.io/Netlib-and-CPP/

Definition at line 378 of file mtk\_blas\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.2.2.4 mtk::Real mtk::BLASAdapter::RealNRM2 ( Real \* in, int & in\_length ) [static]

### **Parameters**

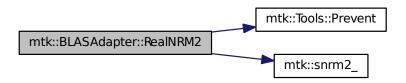
in	in	Input array.
in	in_length	Length of the array.

### Returns

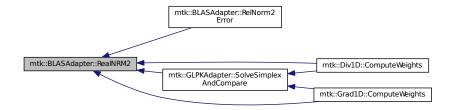
Norm-2 of the given array.

Definition at line 324 of file mtk\_blas\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.2.2.5 mtk::Real mtk::BLASAdapter::RelNorm2Error ( mtk::Real \* computed, mtk::Real \* known, int length ) [static]

We compute

$$\frac{||\mathbf{\tilde{x}}-\mathbf{x}||_2}{||\mathbf{x}||_2}.$$

### **Parameters**

in	known	Array containing the computed solution.
in	computed	Array containing the known solution (ref. solution).

### Returns

Relative norm-2 of the error, aka, the difference between the arrays.

Definition at line 358 of file mtk\_blas\_adapter.cc.

Here is the call graph for this function:



The documentation for this class was generated from the following files:

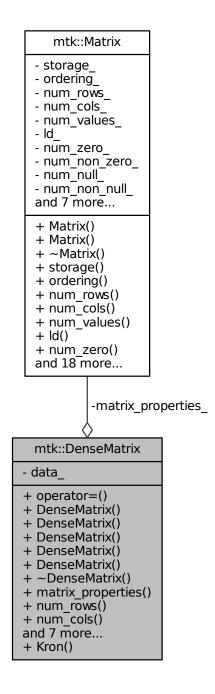
- include/mtk\_blas\_adapter.h
- src/mtk\_blas\_adapter.cc

# 16.3 mtk::DenseMatrix Class Reference

Defines a common dense matrix, using a 1D array.

#include <mtk\_dense\_matrix.h>

Collaboration diagram for mtk::DenseMatrix:



## **Public Member Functions**

DenseMatrix & operator= (const DenseMatrix &in)

Overloaded assignment operator.

• DenseMatrix ()

Default constructor.

• DenseMatrix (const DenseMatrix &in)

Copy constructor.

DenseMatrix (const int &num\_rows, const int &num\_cols)

Construct a dense matrix based on the given dimensions.

DenseMatrix (const int &rank, const bool &padded, const bool &transpose)

Construct a zero-rows-padded identity matrix.

• DenseMatrix (const Real \*gen, const int &gen\_length, const int &pro\_length, const bool &transpose)

Construct a dense Vandermonde matrix.

∼DenseMatrix ()

Destructor.

· Matrix matrix properties () const

Provides access to the matrix data.

int num\_rows () const

Gets the number of rows.

• int num cols () const

Gets the number of columns.

• Real \* data () const

Provides access to the matrix value array.

void SetOrdering (mtk::MatrixOrdering oo)

Sets the ordering of the matrix.

Real GetValue (const int &row\_coord, const int &col\_coord) const

Gets a value on the given coordinates.

void SetValue (const int &row\_coord, const int &col\_coord, const Real &val)

Sets a value on the given coordinates.

• void Transpose ()

Transpose this matrix.

• void OrderRowMajor ()

Make the matrix row-wise ordered.

void OrderColMajor ()

Make the matrix column-wise ordered.

### Static Public Member Functions

static DenseMatrix Kron (const DenseMatrix &aa, const DenseMatrix &bb)

Construct a dense matrix based on the Kronecker product of arguments.

### **Private Attributes**

Matrix matrix properties

Data related to the matrix nature.

• Real \* data

Array holding the data in contiguouos position in memory.

### **Friends**

• std::ostream & operator<< (std::ostream &stream, DenseMatrix &in)

Prints the matrix as a block of numbers (standard way).

# 16.3.1 Detailed Description

For developing purposes, it is better to have a not-so-intrincated data structure implementing matrices. This is the purpose of this class: to be used for prototypes of new code for small test cases. In every other instance, this should be replaced by the most appropriate sparse matrix.

Definition at line 92 of file mtk\_dense\_matrix.h.

### 16.3.2 Constructor & Destructor Documentation

16.3.2.1 mtk::DenseMatrix::DenseMatrix ( )

Definition at line 138 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



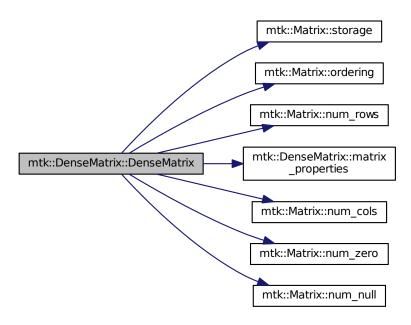
### 16.3.2.2 mtk::DenseMatrix::DenseMatrix ( const DenseMatrix & in )

### **Parameters**

in	in	Given matrix.

Definition at line 144 of file mtk dense matrix.cc.

Here is the call graph for this function:



16.3.2.3 mtk::DenseMatrix::DenseMatrix ( const int & num\_rows, const int & num\_cols )

### **Parameters**

ir	า	num_rows	Number of rows of the required matrix.
ir	า	num_cols	Number of rows of the required matrix.

# **Exceptions**



Definition at line 177 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



16.3.2.4 mtk::DenseMatrix::DenseMatrix ( const int & rank, const bool & padded, const bool & transpose )

Used in the construction of the mimetic operators.

Def\*\*. A padded matrix is a matrix with its first and last rows initialized to only zero values:

$$\bar{\mathbf{I}} = \left(\begin{array}{ccccc} 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ 0 & 0 & 0 & \dots & 0 \end{array}\right)$$

### **Parameters**

in	rank	Rank or number of rows/cols in square matrix.
in	padded	Should it be padded?
in	transpose	Should I return the transpose of the requested matrix?

### **Exceptions**

std::bad_alloc	

Definition at line 199 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



16.3.2.5 mtk::DenseMatrix::DenseMatrix ( const Real \* gen, const int & gen\_length, const int & pro\_length, const bool & transpose )

Def\*\*. In linear algebra, a **Vandermonde matrix** is a matrix with terms of a geometric progression in each row. This progression uses the terms of a given **generator vector**:

$$\mathbf{V} = \left(egin{array}{ccccc} 1 & lpha_1 & lpha_1^2 & \dots & lpha_1^{n-1} \ 1 & lpha_2 & lpha_2^2 & \dots & lpha_2^{n-1} \ 1 & lpha_3 & lpha_3^2 & \dots & lpha_3^{n-1} \ dots & dots & dots & dots \ 1 & lpha_m & lpha_m^2 & \dots & lpha_m^{n-1} \end{array}
ight)$$

This constructor generates a Vandermonde matrix, as defined above.

Obs\*\*. It in important to understand that the generator vectors to be used are nothing but a very particular instance of a grid. These are little chunks, little samples, if you will, of a grid which is rectangular and uniform. So the selected samples, on the <a href="mailto:mtk::Div1D">mtk::Div1D</a> and <a href="mailto:mtk::Grad1D">mtk::Grad1D</a>, basically represent the entire space, the entire grid. This is why nor the CRS nor the CBS algorithms may work for irregular geometries, such as curvilinear grids.

### **Parameters**

in	gen	Given generator vector.
in	gen_length	Length generator vector.
in	pro_length	Length the progression.
in	transpose	Should the transpose be created instead?

# **Exceptions**

std::bad_alloc	

Definition at line 237 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



16.3.2.6 mtk::DenseMatrix:: $\sim$ DenseMatrix ( )

Definition at line 285 of file mtk\_dense\_matrix.cc.

# 16.3.3 Member Function Documentation

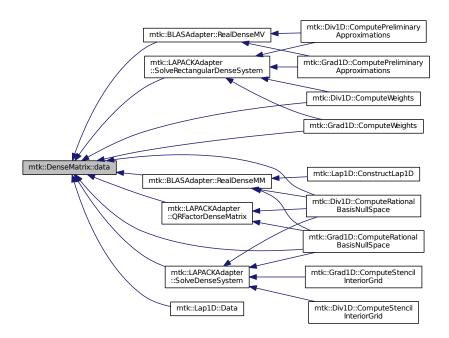
16.3.3.1 mtk::Real \* mtk::DenseMatrix::data ( ) const

### **Returns**

Pointer to an array of mtk::Real.

Definition at line 316 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:



16.3.3.2 mtk::Real mtk::DenseMatrix::GetValue ( const int & row\_coord, const int & col\_coord ) const

### **Parameters**

in	row_coord	Row coordinate.
in	col_coord	Column coordinate.

#### Returns

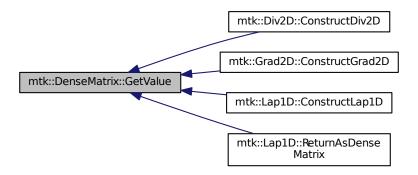
The required value at the specified coordinates.

Definition at line 321 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.3.3 mtk::DenseMatrix mtk::DenseMatrix::Kron ( const DenseMatrix & aa, const DenseMatrix & bb ) [static]

### **Parameters**

in	aa	First matrix.
in	bb	Second matrix.

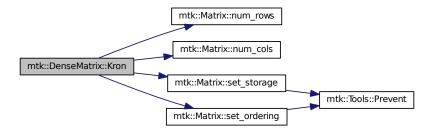
# **Exceptions**

std::bad_alloc	

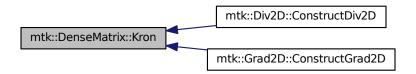
**Todo** Implement Kronecker product using the BLAS.

Definition at line 463 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



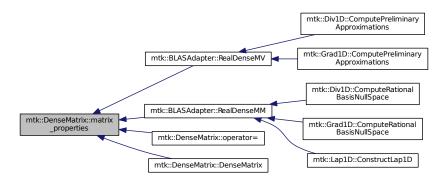
16.3.3.4 mtk::Matrix mtk::DenseMatrix::matrix\_properties ( ) const

Returns

Pointer to a Matrix.

Definition at line 291 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:



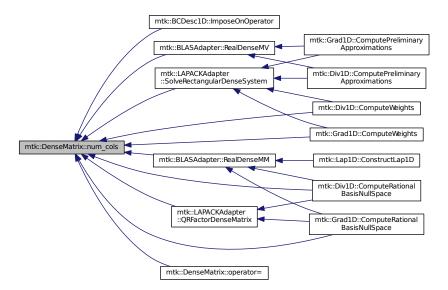
# 16.3.3.5 int mtk::DenseMatrix::num\_cols ( ) const

### Returns

Number of columns of the matrix.

Definition at line 311 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:



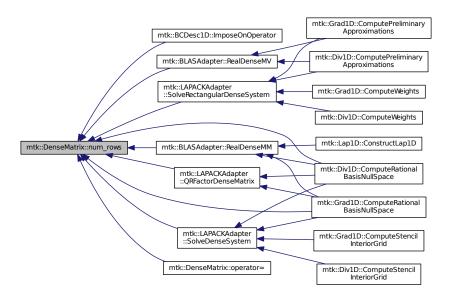
16.3.3.6 int mtk::DenseMatrix::num\_rows ( ) const

### **Returns**

Number of rows of the matrix.

Definition at line 306 of file mtk\_dense\_matrix.cc.

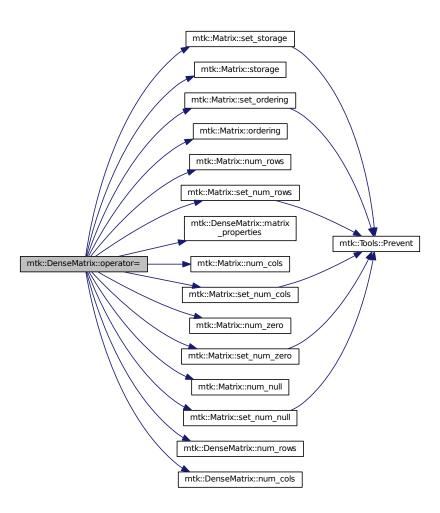
Here is the caller graph for this function:



16.3.3.7 mtk::DenseMatrix & mtk::DenseMatrix::operator= ( const DenseMatrix & in )

Definition at line 97 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:

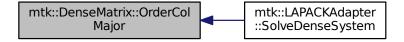


16.3.3.8 void mtk::DenseMatrix::OrderColMajor ( )

**Todo** Improve this so that no new arrays have to be created.

Definition at line 424 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:

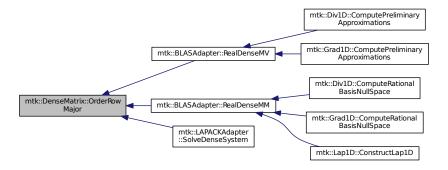


16.3.3.9 void mtk::DenseMatrix::OrderRowMajor ( )

**Todo** Improve this so that no new arrays have to be created.

Definition at line 383 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:



16.3.3.10 void mtk::DenseMatrix::SetOrdering ( mtk::MatrixOrdering oo )

### **Parameters**

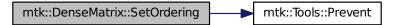
in	00	Ordering.

#### Returns

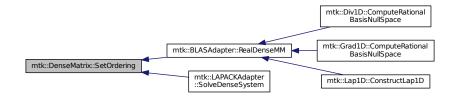
The required value at the specified coordinates.

Definition at line 296 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.3.3.11 void mtk::DenseMatrix::SetValue ( const int & row\_coord, const int & col\_coord, const Real & val )

### **Parameters**

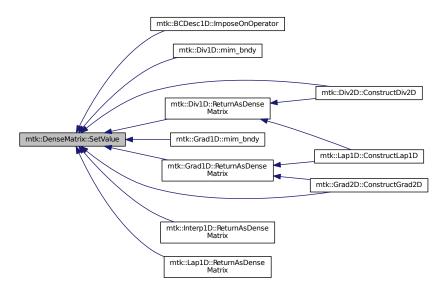
in	row_coord	Row coordinate.
in	col_coord	Column coordinate.
in	val	Row Actual value to be inserted.

Definition at line 333 of file mtk\_dense\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:

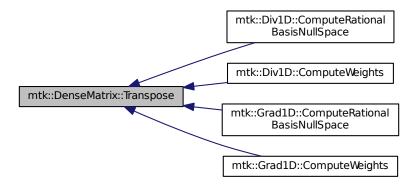


16.3.3.12 void mtk::DenseMatrix::Transpose ( )

**Todo** Improve this so that no extra arrays have to be created.

Definition at line 346 of file mtk\_dense\_matrix.cc.

Here is the caller graph for this function:



### 16.3.4 Friends And Related Function Documentation

16.3.4.1 std::ostream& operator<< ( std::ostream & stream, mtk::DenseMatrix & in ) [friend]

Definition at line 75 of file mtk\_dense\_matrix.cc.

### 16.3.5 Member Data Documentation

**16.3.5.1 Real**\* mtk::DenseMatrix::data\_ [private]

Definition at line 270 of file mtk\_dense\_matrix.h.

**16.3.5.2 Matrix mtk::DenseMatrix::matrix\_properties\_** [private]

Definition at line 268 of file mtk\_dense\_matrix.h.

The documentation for this class was generated from the following files:

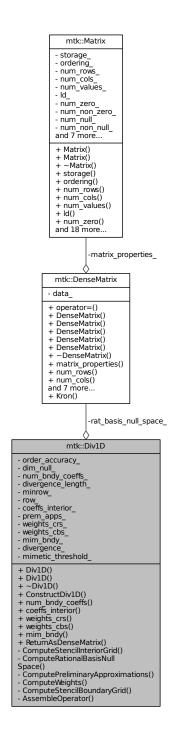
- include/mtk\_dense\_matrix.h
- src/mtk\_dense\_matrix.cc

# 16.4 mtk::Div1D Class Reference

Implements a 1D mimetic divergence operator.

#include <mtk\_div\_1d.h>

Collaboration diagram for mtk::Div1D:



# **Public Member Functions**

• Div1D ()

Default constructor.

• Div1D (const Div1D &div)

Copy constructor.

• ~Div1D ()

Destructor.

 bool ConstructDiv1D (int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimetic-Threshold)

Factory method implementing the CBS Algorithm to build operator.

• int num\_bndy\_coeffs () const

Returns how many coefficients are approximating at the boundary.

Real \* coeffs interior () const

Returns coefficients for the interior of the grid.

• Real \* weights\_crs (void) const

Return collection of weights as computed by the CRSA.

• Real \* weights\_cbs (void) const

Return collection of weights as computed by the CBSA.

• DenseMatrix mim\_bndy () const

Return collection of mimetic approximations at the boundary.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid)

Return the operator as a dense matrix.

#### **Private Member Functions**

bool ComputeStencilInteriorGrid (void)

Stage 1 of the CBS Algorithm.

bool ComputeRationalBasisNullSpace (void)

Stage 2.1 of the CBS Algorithm.

bool ComputePreliminaryApproximations (void)

Stage 2.2 of the CBS Algorithm.

bool ComputeWeights (void)

Stage 2.3 of the CBS Algorithm.

bool ComputeStencilBoundaryGrid (void)

Stage 2.4 of the CBS Algorithm.

bool AssembleOperator (void)

Stage 3 of the CBS Algorithm.

# **Private Attributes**

int order\_accuracy\_

Order of numerical accuracy of the operator.

• int dim\_null\_

Dim. null-space for boundary approximations.

int num bndy coeffs

Req. coeffs. per bndy pt. uni. order accuracy.

· int divergence\_length\_

Length of the output array.

int minrow

Row from the optimizer with the minimum rel. nor.

int row

Row currently processed by the optimizer.

• DenseMatrix rat\_basis\_null\_space\_

Rational b. null-space w. bndy.

Real \* coeffs interior

Interior stencil.

Real \* prem\_apps\_

2D array of boundary preliminary approximations.

Real \* weights\_crs\_

Array containing weights from CRSA.

• Real \* weights\_cbs\_

Array containing weights from CBSA.

• Real \* mim\_bndy\_

Array containing mimetic boundary approximations.

• Real \* divergence\_

Output array containing the operator and weights.

Real mimetic threshold

< Mimetic threshold.

### **Friends**

std::ostream & operator<< (std::ostream &stream, Div1D &in)</li>
 Output stream operator for printing.

# 16.4.1 Detailed Description

This class implements a 1D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 81 of file mtk div 1d.h.

### 16.4.2 Constructor & Destructor Documentation

```
16.4.2.1 mtk::Div1D::Div1D()
```

Definition at line 125 of file mtk\_div\_1d.cc.

16.4.2.2 mtk::Div1D::Div1D ( const Div1D & div )

# **Parameters**

in	div	Given divergence.
----	-----	-------------------

Definition at line 140 of file mtk\_div\_1d.cc.

16.4.2.3 mtk::Div1D::∼Div1D ( )

Definition at line 155 of file mtk div 1d.cc.

### 16.4.3 Member Function Documentation

```
16.4.3.1 bool mtk::Div1D::AssembleOperator(void) [private]
```

Construct the output array with the operator and its weights.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry the collection of coefficients for interior of grid.
- 3. IF order accuracy > 2, then third entry is the collection of weights.
- 4. IF order accuracy > 2, next dim null entries is approximating coefficients for the west boundary of the grid.

Definition at line 1333 of file mtk\_div\_1d.cc.

```
16.4.3.2 mtk::Real * mtk::Div1D::coeffs_interior( ) const
```

Returns

Coefficients for the interior of the grid.

Definition at line 320 of file mtk div 1d.cc.

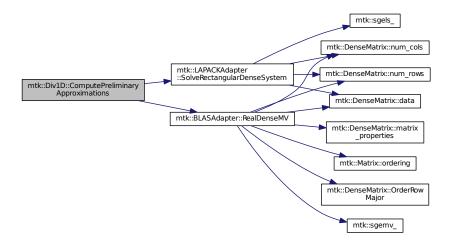
```
16.4.3.3 bool mtk::Div1D::ComputePreliminaryApproximations (void ) [private]
```

Compute the set of preliminary approximations on the boundary neighborhood.

- 1. Create generator vector for the first approximation.
- 2. Compute the dim null near-the-boundary columns of the pi matrix.
- 3. Create the Vandermonde matrix for this iteration.
- 4. New order-selector vector (gets re-written with LAPACK solutions).
- 5. Solving TT\*rr = ob yields the columns rr of the KK matrix.
- 6. Scale the KK matrix to make it a rational basis for null-space.
- 7. Extract the last dim\_null values of the pre-scaled ob.
- 8. Once we posses the bottom elements, we proceed with the scaling.

Definition at line 688 of file mtk div 1d.cc.

Here is the call graph for this function:



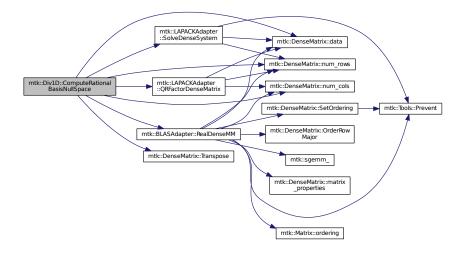
16.4.3.4 bool mtk::Div1D::ComputeRationalBasisNullSpace(void) [private]

Compute a rational basis for the null-space of the Vandermonde matrix approximating at the west boundary.

- 1. Create generator vector for the first approximation.
- 2. Create Vandermonde matrix.
- 3. QR-factorize the Vandermonde matrix.
- 4. Extract the basis for the null-space from Q matrix.
- 5. Scale null-space to make it rational.

Definition at line 512 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



16.4.3.5 bool mtk::Div1D::ComputeStencilBoundaryGrid(void) [private]

Compute mimetic stencil approximating at boundary.

- 1. Collect lambda values.
- 2. Compute alpha values.
- 3. Compute the mimetic boundary approximations.

Definition at line 1234 of file mtk\_div\_1d.cc.

16.4.3.6 bool mtk::Div1D::ComputeStencilInteriorGrid ( void ) [private]

Compute the stencil approximating the interior of the staggered grid.

- 1. Create vector for interior spatial coordinates.
- 2. Create Vandermonde matrix (using interior coordinates as generator).
- 3. Create order-selector vector.
- 4. Solve dense Vandermonde system to attain the interior coefficients.

Definition at line 413 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



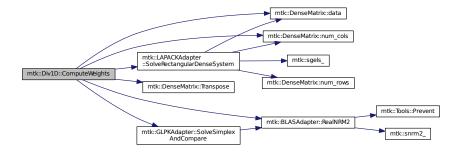
16.4.3.7 bool mtk::Div1D::ComputeWeights ( void ) [private]

Compute the set of mimetic weights to impose the mimetic condition.

- 1. Construct the matrix.
- 2. Use interior stencil to build proper RHS vector h.
- 3. Get weights (as **CRSA**):  $\blacksquare q = h$ .
- 4. If required order is greater than critical order, start the CBSA.
- 5. Create matrix from ■.
- 6. Prepare constraint vector as in the CBSA: ■.
- 7. Brute force search through all the rows of the  $\Phi$  matrix.
- 8. Apply solution found from brute force search.

Definition at line 908 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



16.4.3.8 bool mtk::Div1D::ConstructDiv1D ( int order\_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic\_threshold = kDefaultMimeticThreshold )

### Returns

Success of the construction.

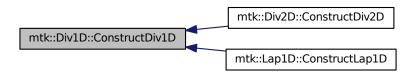
- 1. Compute stencil for the interior cells.
- 2. Compute a rational basis for the null-space for the first matrix.
- 3. Compute preliminary approximation (non-mimetic) on the boundaries.
- 4. Compute quadrature weights to impose the mimetic conditions.
- 5. Compute real approximation (mimetic) on the boundaries.
- 6. Assemble operator.

Definition at line 176 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



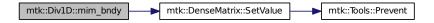
16.4.3.9 mtk::DenseMatrix mtk::Div1D::mim\_bndy ( ) const

#### Returns

Collection of mimetic approximations at the boundary.

Definition at line 336 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



16.4.3.10 int mtk::Div1D::num\_bndy\_coeffs ( ) const

#### Returns

How many coefficients are approximating at the boundary.

Definition at line 315 of file mtk div 1d.cc.

16.4.3.11 mtk::DenseMatrix mtk::Div1D::ReturnAsDenseMatrix ( const UniStgGrid1D & grid )

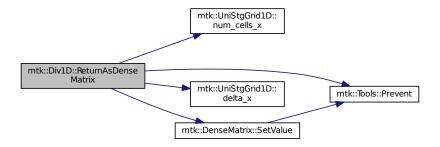
### Returns

The operator as a dense matrix.

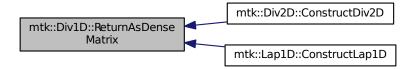
- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 351 of file mtk\_div\_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.4.3.12 mtk::Real \* mtk::Div1D::weights\_cbs ( void ) const

Returns

Collection of weights as computed by the CBSA.

Definition at line 330 of file mtk div 1d.cc.

16.4.3.13 mtk::Real \* mtk::Div1D::weights\_crs ( void ) const

Returns

Collection of weights as computed by the CRSA.

Definition at line 325 of file mtk\_div\_1d.cc.

### 16.4.4 Friends And Related Function Documentation

16.4.4.1 std::ostream & operator << ( std::ostream & stream, mtk::Div1D & in ) [friend]

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk\_div\_1d.cc.

### 16.4.5 Member Data Documentation

**16.4.5.1 Real**\* mtk::Div1D::coeffs\_interior\_ [private]

Definition at line 202 of file mtk\_div\_1d.h.

```
16.4.5.2 int mtk::Div1D::dim_null_ [private]
Definition at line 194 of file mtk_div_1d.h.
16.4.5.3 Real* mtk::Div1D::divergence_ [private]
Definition at line 207 of file mtk_div_1d.h.
16.4.5.4 int mtk::Div1D::divergence_length_ [private]
Definition at line 196 of file mtk_div_1d.h.
16.4.5.5 Real* mtk::Div1D::mim_bndy_ [private]
Definition at line 206 of file mtk div 1d.h.
16.4.5.6 Real mtk::Div1D::mimetic_threshold [private]
Definition at line 209 of file mtk_div_1d.h.
16.4.5.7 int mtk::Div1D::minrow_ [private]
Definition at line 197 of file mtk_div_1d.h.
16.4.5.8 int mtk::Div1D::num_bndy_coeffs_ [private]
Definition at line 195 of file mtk_div_1d.h.
16.4.5.9 int mtk::Div1D::order_accuracy_ [private]
Definition at line 193 of file mtk_div_1d.h.
16.4.5.10 Real* mtk::Div1D::prem_apps_ [private]
Definition at line 203 of file mtk div 1d.h.
16.4.5.11 DenseMatrix mtk::Div1D::rat_basis_null_space_ [private]
Definition at line 200 of file mtk div 1d.h.
16.4.5.12 int mtk::Div1D::row_ [private]
Definition at line 198 of file mtk div 1d.h.
```

16.4.5.13 Real\* mtk::Div1D::weights\_cbs\_ [private]

Definition at line 205 of file mtk\_div\_1d.h.

16.4.5.14 Real\* mtk::Div1D::weights\_crs\_ [private]

Definition at line 204 of file mtk\_div\_1d.h.

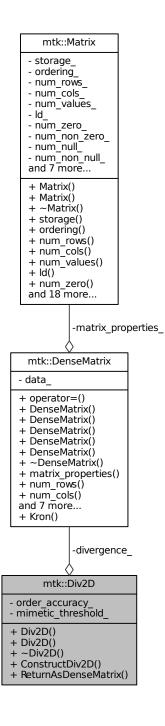
The documentation for this class was generated from the following files:

- include/mtk\_div\_1d.h
- src/mtk\_div\_1d.cc

# 16.5 mtk::Div2D Class Reference

#include <mtk\_div\_2d.h>

Collaboration diagram for mtk::Div2D:



# **Public Member Functions**

• Div2D ()

Default constructor.

• Div2D (const Div2D &div)

Copy constructor.

• ~Div2D ()

Destructor.

DenseMatrix ConstructDiv2D (const UniStgGrid2D &grid, int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix ()

Return the operator as a dense matrix.

### **Private Attributes**

DenseMatrix divergence

Actual operator.

· int order\_accuracy\_

Order of accuracy.

Real mimetic\_threshold\_

Mimetic Threshold.

# 16.5.1 Detailed Description

Definition at line 66 of file mtk div 2d.h.

#### 16.5.2 Constructor & Destructor Documentation

```
16.5.2.1 mtk::Div2D::Div2D()
```

Definition at line 69 of file mtk\_div\_2d.cc.

16.5.2.2 mtk::Div2D::Div2D ( const Div2D & div )

# **Parameters**

4	div	Civan divargance
111	div	Given divergence.

Definition at line 73 of file mtk\_div\_2d.cc.

```
16.5.2.3 mtk::Div2D::∼Div2D ( )
```

Definition at line 77 of file mtk\_div\_2d.cc.

### 16.5.3 Member Function Documentation

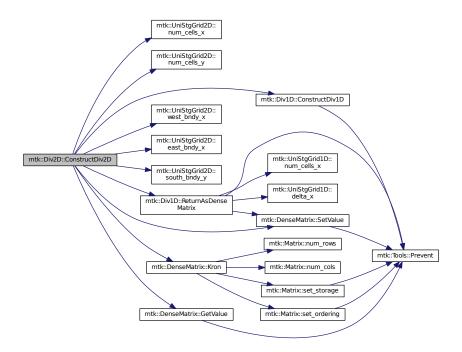
16.5.3.1 mtk::DenseMatrix mtk::Div2D::ConstructDiv2D ( const UniStgGrid2D & grid, int order\_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic\_threshold = kDefaultMimeticThreshold)

#### Returns

Success of the construction.

Definition at line 79 of file mtk\_div\_2d.cc.

Here is the call graph for this function:



# 16.5.3.2 mtk::DenseMatrix mtk::Div2D::ReturnAsDenseMatrix ( )

## Returns

The operator as a dense matrix.

Definition at line 144 of file mtk\_div\_2d.cc.

# 16.5.4 Member Data Documentation

**16.5.4.1 DenseMatrix mtk::Div2D::divergence** [private]

Definition at line 98 of file mtk\_div\_2d.h.

**16.5.4.2 Real mtk::Div2D::mimetic\_threshold** [private]

Definition at line 100 of file mtk\_div\_2d.h.

16.5.4.3 int mtk::Div2D::order\_accuracy\_ [private]

Definition at line 99 of file mtk div 2d.h.

The documentation for this class was generated from the following files:

- include/mtk\_div\_2d.h
- src/mtk div 2d.cc

# 16.6 mtk::GLPKAdapter Class Reference

Adapter class for the GLPK API.

#include <mtk\_glpk\_adapter.h>

Collaboration diagram for mtk::GLPKAdapter:

mtk::GLPKAdapter

+ SolveSimplexAndCompare()

## **Static Public Member Functions**

• static mtk::Real SolveSimplexAndCompare (mtk::Real \*A, int nrows, int ncols, int kk, mtk::Real \*hh, mtk::Real \*qq, int robjective, mtk::Real mimetic\_tol, int copy)

Solves a CLO problem and compares the solution to a reference solution.

# 16.6.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

#### Warning

We use the GLPK temporarily in order to test the CBSA, but it will be removed due to potential licensing issues.

#### See Also

```
http://www.gnu.org/software/glpk/
```

**Todo** Rescind from the GLPK as the numerical core for CLO problems.

Definition at line 101 of file mtk\_glpk\_adapter.h.

### 16.6.2 Member Function Documentation

16.6.2.1 mtk::Real mtk::GLPKAdapter::SolveSimplexAndCompare ( mtk::Real \* A, int nrows, int ncols, int kk, mtk::Real \* hh, mtk::Real \* qq, int robjective, mtk::Real mimetic\_tol, int copy ) [static]

This routine is the pivot of the CBSA. It solves a Constrained Linear Optimization (CLO) problem, and it compares the attained solution to a given reference solution. This comparison is done computing the norm-2 relative error.

#### **Parameters**

in	alpha	First scalar.
in	AA	Given matrix.
in	XX	First vector.
in	beta	Second scalar.
in	beta	Second scalar.
in,out	уу	Second vector (output).
in	XX	First vector.
in	beta	Second scalar.
in	beta	Second scalar.

#### Returns

Relative error computed between attained solution and provided ref.

#### Warning

GLPK indexes in [1,n], so we must get the extra space needed.

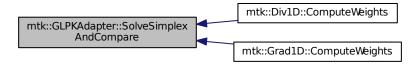
- 1. Memory allocation.
- 2. Fill the problem.
- 3. Copy the row to the vector objective.
- 4. Forming the RHS.
- 5. Setting up the objective function.
- 6. Setting up constraints.
- 7. Copy the matrix minus the row objective to the glpk problem.
- 8. Solve problem.

Definition at line 76 of file mtk\_glpk\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



The documentation for this class was generated from the following files:

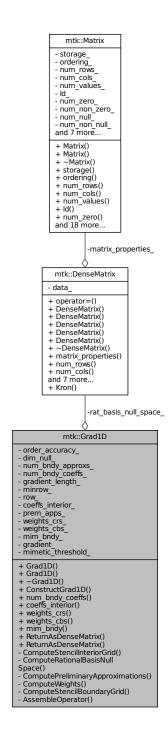
- include/mtk\_glpk\_adapter.h
- src/mtk\_glpk\_adapter.cc

# 16.7 mtk::Grad1D Class Reference

Implements a 1D mimetic gradient operator.

#include <mtk\_grad\_1d.h>

Collaboration diagram for mtk::Grad1D:



### **Public Member Functions**

• Grad1D ()

Default constructor.

Grad1D (const Grad1D &grad)

Copy constructor.

~Grad1D ()

Destructor.

 bool ConstructGrad1D (int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimetic-Threshold)

Factory method implementing the CBS Algorithm to build operator.

• int num\_bndy\_coeffs () const

Returns how many coefficients are approximating at the boundary.

Real \* coeffs interior () const

Returns coefficients for the interior of the grid.

• Real \* weights\_crs (void) const

Returns collection of weights as computed by the CRSA.

Real \* weights\_cbs (void) const

Returns collection of weights as computed by the CBSA.

• DenseMatrix mim\_bndy () const

Return collection of mimetic approximations at the boundary.

DenseMatrix ReturnAsDenseMatrix (Real west, Real east, int num\_cells\_x)

Returns the operator as a dense matrix.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid)

Returns the operator as a dense matrix.

### **Private Member Functions**

bool ComputeStencilInteriorGrid (void)

Stage 1 of the CBS Algorithm.

bool ComputeRationalBasisNullSpace (void)

Stage 2.1 of the CBS Algorithm.

bool ComputePreliminaryApproximations (void)

Stage 2.2 of the CBS Algorithm.

bool ComputeWeights (void)

Stage 2.3 of the CBS Algorithm.

bool ComputeStencilBoundaryGrid (void)

Stage 2.4 of the CBS Algorithm.

· bool AssembleOperator (void)

Stage 3 of the CBS Algorithm.

# **Private Attributes**

· int order\_accuracy\_

Order of numerical accuracy of the operator.

int dim null

Dim. null-space for boundary approximations.

int num\_bndy\_approxs\_

Req. approximations at and near the boundary.

int num\_bndy\_coeffs\_

Req. coeffs. per bndy pt. uni. order accuracy.

· int gradient\_length\_

Length of the output array.

int minrow

Row from the optimizer with the minimum rel. nor.

• int row\_

Row currently processed by the optimizer.

DenseMatrix rat\_basis\_null\_space\_

Rational b. null-space w. bndy.

• Real \* coeffs\_interior\_

Interior stencil.

• Real \* prem\_apps\_

2D array of boundary preliminary approximations.

Real \* weights\_crs\_

Array containing weights from CRSA.

• Real \* weights\_cbs\_

Array containing weights from CBSA.

Real \* mim\_bndy\_

Array containing mimetic boundary approximations.

· Real \* gradient\_

Output array containing the operator and weights.

- Real mimetic threshold
  - < Mimetic threshold.

# **Friends**

std::ostream & operator<< (std::ostream &stream, Grad1D &in)</li>
 Output stream operator for printing.

# 16.7.1 Detailed Description

This class implements a 1D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CB-SA).

Definition at line 81 of file mtk\_grad\_1d.h.

# 16.7.2 Constructor & Destructor Documentation

16.7.2.1 mtk::Grad1D::Grad1D( )

Definition at line 129 of file mtk\_grad\_1d.cc.

16.7.2.2 mtk::Grad1D::Grad1D ( const Grad1D & grad )

#### **Parameters**

in	div	Given divergence.
----	-----	-------------------

Definition at line 145 of file mtk\_grad\_1d.cc.

```
16.7.2.3 mtk::Grad1D::∼Grad1D ( )
```

Definition at line 161 of file mtk\_grad\_1d.cc.

#### 16.7.3 Member Function Documentation

```
16.7.3.1 bool mtk::Grad1D::AssembleOperator(void) [private]
```

Construct the output array with the operator and its weights.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry of the array will contain the collection of approximating coefficients for the interior of the grid.
- 3. The third entry will contain the collection of weights.
- 4. The next dim\_null + 1 entries will contain the collections of approximating coefficients for the west boundary of the grid.

Definition at line 1437 of file mtk\_grad\_1d.cc.

```
16.7.3.2 mtk::Real * mtk::Grad1D::coeffs_interior ( ) const
```

Returns

Coefficients for the interior of the grid.

Definition at line 330 of file mtk\_grad\_1d.cc.

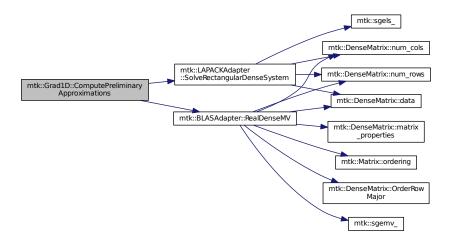
```
16.7.3.3 bool mtk::Grad1D::ComputePreliminaryApproximations (void ) [private]
```

Compute the set of preliminary approximations on the boundary neighborhood.

- 1. Create generator vector for the first approximation.
- 2. Compute the dim\_null near-the-boundary columns of the pi matrix.
- 3. Create the Vandermonde matrix for this iteration.
- 4. New order-selector vector (gets re-written with LAPACK solutions).
- 5. Solving TT\*rr = ob yields the columns rr of the kk matrix.
- 6. Scale the kk matrix to make it a rational basis for null-space.
- 7. Extract the last dim\_null values of the pre-scaled ob.
- 8. Once we posses the bottom elements, we proceed with the scaling.

Definition at line 771 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



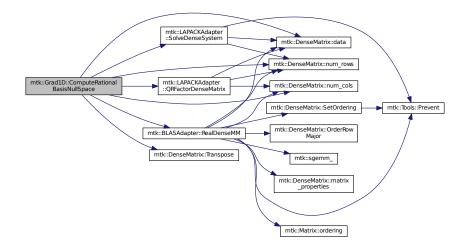
# 16.7.3.4 bool mtk::Grad1D::ComputeRationalBasisNullSpace(void) [private]

Compute a rational basis for the null-space of the Vandermonde matrix approximating at the west boundary.

- 1. Create generator vector for the first approximation.
- 2. Create Vandermonde matrix.
- 3. QR-factorize the Vandermonde matrix.
- 4. Extract the basis for the null-space from Q matrix.
- 5. Scale null-space to make it rational.

Definition at line 588 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



16.7.3.5 bool mtk::Grad1D::ComputeStencilBoundaryGrid (void ) [private]

Compute mimetic stencil approximating at boundary.

- 1. Collect lambda values.
- 2. Compute alpha values.
- 3. Compute the mimetic boundary approximations.

Definition at line 1331 of file mtk\_grad\_1d.cc.

16.7.3.6 bool mtk::Grad1D::ComputeStencilInteriorGrid ( void ) [private]

Compute the stencil approximating the interior of the staggered grid.

- 1. Create vector for interior spatial coordinates.
- 2. Create Vandermonde matrix (using interior coordinates as generator).
- 3. Create order-selector vector.
- 4. Solve dense Vandermonde system to attain the interior coefficients.

Definition at line 492 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



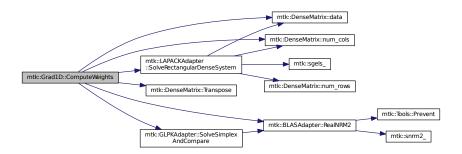
16.7.3.7 bool mtk::Grad1D::ComputeWeights (void ) [private]

Compute the set of mimetic weights to impose the mimetic condition.

- 1. Construct the matrix.
- 2. Use interior stencil to build proper RHS vector h.
- 3. Get weights (as **CRSA**):  $\blacksquare q = h$ .
- 4. If required order is greater than critical order, start the CBSA.
- 5. Create matrix from ■.
- 6. Prepare constraint vector as in the CBSA: ■.
- 7. Brute force search through all the rows of the  $\Phi$  matrix.
- 8. Apply solution found from brute force search.

Definition at line 991 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



16.7.3.8 bool mtk::Grad1D::ConstructGrad1D ( int order\_accuracy = kDefaultOrderAccuracy, Real mimetic\_threshold = kDefaultMimeticThreshold )

#### Returns

Success of the solution.

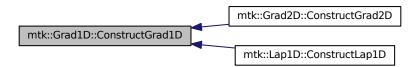
- 1. Compute stencil for the interior cells.
- 2. Compute a rational null-space from the first matrix transposed.
- 3. Compute preliminary approximation (non-mimetic) on the boundaries.
- 4. Compute quadrature weights to impose the mimetic conditions.
- 5. Compute real approximation (mimetic) on the boundaries.
- 6. Assemble operator.

Definition at line 182 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.7.3.9 mtk::DenseMatrix mtk::Grad1D::mim\_bndy ( ) const

#### Returns

Collection of mimetic approximations at the boundary.

Definition at line 345 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



16.7.3.10 int mtk::Grad1D::num\_bndy\_coeffs ( ) const

#### Returns

How many coefficients are approximating at the boundary.

Definition at line 325 of file mtk\_grad\_1d.cc.

16.7.3.11 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix ( mtk::Real west, mtk::Real east, int num\_cells\_x )

#### Returns

The operator as a dense matrix.

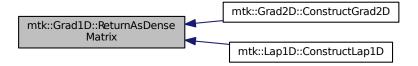
- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 360 of file mtk\_grad\_1d.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



# 16.7.3.12 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix ( const UniStgGrid1D & grid )

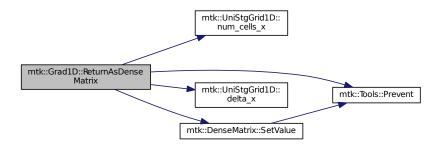
#### Returns

The operator as a dense matrix.

- 1. Insert mimetic boundary at the west.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the mimetic boundaries.

Definition at line 428 of file mtk grad 1d.cc.

Here is the call graph for this function:



## 16.7.3.13 mtk::Real \* mtk::Grad1D::weights\_cbs ( void ) const

## Returns

Collection of weights as computed by the CBSA.

Definition at line 340 of file mtk\_grad\_1d.cc.

```
16.7.3.14 mtk::Real * mtk::Grad1D::weights_crs ( void ) const
```

**Returns** 

Success of the solution.

Definition at line 335 of file mtk grad 1d.cc.

# 16.7.4 Friends And Related Function Documentation

16.7.4.1 std::ostream& operator<< ( std::ostream & stream, mtk::Grad1D & in ) [friend]

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. Print mimetic weights.
- 4. Print mimetic approximations at the boundary.

Definition at line 79 of file mtk\_grad\_1d.cc.

#### 16.7.5 Member Data Documentation

```
16.7.5.1 Real* mtk::Grad1D::coeffs_interior_ [private]
```

Definition at line 210 of file mtk\_grad\_1d.h.

```
16.7.5.2 int mtk::Grad1D::dim_null_ [private]
```

Definition at line 201 of file mtk\_grad\_1d.h.

```
16.7.5.3 Real* mtk::Grad1D::gradient_ [private]
```

Definition at line 215 of file mtk\_grad\_1d.h.

16.7.5.4 int mtk::Grad1D::gradient\_length\_ [private]

Definition at line 204 of file mtk\_grad\_1d.h.

16.7.5.5 Real\* mtk::Grad1D::mim\_bndy\_ [private]

Definition at line 214 of file mtk\_grad\_1d.h.

**16.7.5.6** Real mtk::Grad1D::mimetic\_threshold\_ [private]

Definition at line 217 of file mtk grad 1d.h.

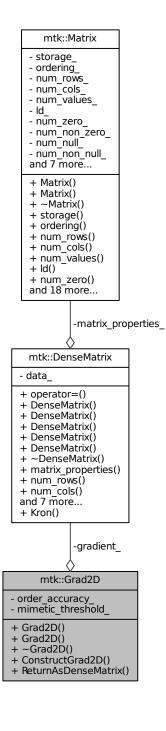
```
16.7.5.7 int mtk::Grad1D::minrow_ [private]
Definition at line 205 of file mtk_grad_1d.h.
16.7.5.8 int mtk::Grad1D::num_bndy_approxs_ [private]
Definition at line 202 of file mtk_grad_1d.h.
16.7.5.9 int mtk::Grad1D::num_bndy_coeffs_ [private]
Definition at line 203 of file mtk_grad_1d.h.
16.7.5.10 int mtk::Grad1D::order_accuracy_ [private]
Definition at line 200 of file mtk_grad_1d.h.
16.7.5.11 Real* mtk::Grad1D::prem_apps_ [private]
Definition at line 211 of file mtk_grad_1d.h.
16.7.5.12 DenseMatrix mtk::Grad1D::rat_basis_null_space_ [private]
Definition at line 208 of file mtk_grad_1d.h.
16.7.5.13 int mtk::Grad1D::row_ [private]
Definition at line 206 of file mtk_grad_1d.h.
16.7.5.14 Real* mtk::Grad1D::weights_cbs_ [private]
Definition at line 213 of file mtk_grad_1d.h.
16.7.5.15 Real* mtk::Grad1D::weights_crs_ [private]
Definition at line 212 of file mtk_grad_1d.h.
The documentation for this class was generated from the following files:
```

- include/mtk\_grad\_1d.h
- src/mtk\_grad\_1d.cc

# 16.8 mtk::Grad2D Class Reference

```
#include <mtk_grad_2d.h>
```

Collaboration diagram for mtk::Grad2D:



# **Public Member Functions**

Grad2D ()

Default constructor.

Grad2D (const Grad2D &grad)

Copy constructor.

• ~Grad2D ()

Destructor.

DenseMatrix ConstructGrad2D (const UniStgGrid2D &grid, int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimeticThreshold)

Factory method implementing the CBS Algorithm to build operator.

• DenseMatrix ReturnAsDenseMatrix ()

Return the operator as a dense matrix.

### **Private Attributes**

· DenseMatrix gradient\_

Actual operator.

· int order\_accuracy\_

Order of accuracy.

Real mimetic\_threshold\_

Mimetic Threshold.

# 16.8.1 Detailed Description

Definition at line 66 of file mtk\_grad\_2d.h.

#### 16.8.2 Constructor & Destructor Documentation

```
16.8.2.1 mtk::Grad2D::Grad2D( )
```

Definition at line 67 of file mtk\_grad\_2d.cc.

16.8.2.2 mtk::Grad2D::Grad2D ( const Grad2D & grad )

# **Parameters**

in div Given divergence.	
--------------------------	--

Definition at line 71 of file mtk\_grad\_2d.cc.

```
16.8.2.3 mtk::Grad2D::\simGrad2D ( )
```

Definition at line 75 of file mtk\_grad\_2d.cc.

### 16.8.3 Member Function Documentation

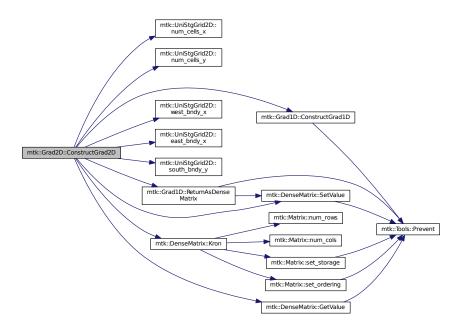
16.8.3.1 mtk::DenseMatrix mtk::Grad2D::ConstructGrad2D ( const UniStgGrid2D & grid, int order\_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic\_threshold = kDefaultMimeticThreshold)

#### Returns

Success of the construction.

Definition at line 77 of file mtk\_grad\_2d.cc.

Here is the call graph for this function:



16.8.3.2 mtk::DenseMatrix mtk::Grad2D::ReturnAsDenseMatrix ( )

### Returns

The operator as a dense matrix.

Definition at line 142 of file mtk\_grad\_2d.cc.

#### 16.8.4 Member Data Documentation

**16.8.4.1 DenseMatrix mtk::Grad2D::gradient\_** [private]

Definition at line 98 of file mtk\_grad\_2d.h.

**16.8.4.2 Real mtk::Grad2D::mimetic\_threshold** [private]

Definition at line 100 of file mtk\_grad\_2d.h.

16.8.4.3 int mtk::Grad2D::order\_accuracy\_ [private]

Definition at line 99 of file mtk\_grad\_2d.h.

The documentation for this class was generated from the following files:

- · include/mtk grad 2d.h
- src/mtk\_grad\_2d.cc

# 16.9 mtk::Interp1D Class Reference

Implements a 1D interpolation operator.

#include <mtk\_interp\_1d.h>

Collaboration diagram for mtk::Interp1D:

## mtk::Interp1D

- dir\_interp\_
- order\_accuracy\_
- coeffs\_interior\_
- + Interp1D()
- + Interp1D()
- + ~Interp1D()
- + ConstructInterp1D()
- + coeffs\_interior()
- + ReturnAsDenseMatrix()

### **Public Member Functions**

• Interp1D ()

Default constructor.

• Interp1D (const Interp1D &interp)

Copy constructor.

• ∼Interp1D ()

Destructor.

bool ConstructInterp1D (int order\_accuracy=kDefaultOrderAccuracy, mtk::DirInterp dir=SCALAR\_TO\_VECTOR)

Factory method to build operator.

Real \* coeffs\_interior () const

Returns coefficients for the interior of the grid.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid)

Returns the operator as a dense matrix.

### **Private Attributes**

DirInterp dir\_interp\_

Direction of interpolation.

· int order\_accuracy\_

Order of numerical accuracy of the operator.

• Real \* coeffs\_interior\_

Interior stencil.

### **Friends**

std::ostream & operator<< (std::ostream &stream, Interp1D &in)</li>
 Output stream operator for printing.

# 16.9.1 Detailed Description

This class implements a 1D interpolation operator.

Definition at line 82 of file mtk\_interp\_1d.h.

# 16.9.2 Constructor & Destructor Documentation

```
16.9.2.1 mtk::Interp1D::Interp1D()
```

Definition at line 80 of file mtk\_interp\_1d.cc.

16.9.2.2 mtk::Interp1D::Interp1D ( const Interp1D & interp )

#### **Parameters**

in	interp	Given interpolation operator.

Definition at line 85 of file mtk\_interp\_1d.cc.

```
16.9.2.3 mtk::Interp1D::∼Interp1D ( )
```

Definition at line 90 of file mtk\_interp\_1d.cc.

# 16.9.3 Member Function Documentation

```
16.9.3.1 mtk::Real * mtk::Interp1D::coeffs_interior ( ) const
```

Returns

Coefficients for the interior of the grid.

Definition at line 130 of file mtk\_interp\_1d.cc.

16.9.3.2 bool mtk::Interp1D::ConstructInterp1D ( int *order\_accuracy* = kDefaultOrderAccuracy, mtk::DirInterp *dir* = SCALAR\_TO\_VECTOR )

#### Returns

Success of the solution.

1. Compute stencil for the interior cells.

Definition at line 96 of file mtk\_interp\_1d.cc.

Here is the call graph for this function:



16.9.3.3 mtk::DenseMatrix mtk::Interp1D::ReturnAsDenseMatrix ( const UniStgGrid1D & grid )

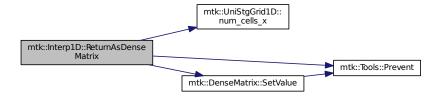
#### Returns

The operator as a dense matrix.

- 1. Preserve values at the boundary.
- 2. Insert coefficients for the interior of the grid.
- 3. Impose center-skew symmetry by permuting the boundaries.

Definition at line 135 of file mtk\_interp\_1d.cc.

Here is the call graph for this function:



### 16.9.4 Friends And Related Function Documentation

```
16.9.4.1 std::ostream& operator<< ( std::ostream & stream, mtk::Interp1D & in ) [friend]
```

1. Print approximating coefficients for the interior.

Definition at line 66 of file mtk\_interp\_1d.cc.

# 16.9.5 Member Data Documentation

```
16.9.5.1 Real* mtk::Interp1D::coeffs_interior_ [private]
```

Definition at line 127 of file mtk\_interp\_1d.h.

**16.9.5.2 DirInterp mtk::Interp1D::dir\_interp** [private]

Definition at line 123 of file mtk\_interp\_1d.h.

**16.9.5.3** int mtk::Interp1D::order\_accuracy\_ [private]

Definition at line 125 of file mtk\_interp\_1d.h.

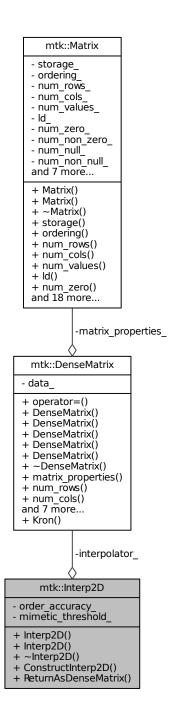
The documentation for this class was generated from the following files:

- include/mtk\_interp\_1d.h
- src/mtk\_interp\_1d.cc

# 16.10 mtk::Interp2D Class Reference

#include <mtk\_interp\_2d.h>

Collaboration diagram for mtk::Interp2D:



# **Public Member Functions**

- Interp2D ()
- Interp2D (const Interp2D &interp)

- ∼Interp2D ()
- DenseMatrix ConstructInterp2D (const UniStgGrid2D &grid, int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimeticThreshold)
- DenseMatrix ReturnAsDenseMatrix ()

### **Private Attributes**

- DenseMatrix interpolator\_
- · int order\_accuracy\_
- Real mimetic threshold

## 16.10.1 Detailed Description

Definition at line 67 of file mtk\_interp\_2d.h.

```
16.10.2 Constructor & Destructor Documentation

16.10.2.1 mtk::Interp2D::Interp2D()

16.10.2.2 mtk::Interp2D::Interp2D()

16.10.2.3 mtk::Interp2D::~Interp2D()

16.10.3 Member Function Documentation

16.10.3.1 DenseMatrix mtk::Interp2D::ConstructInterp2D() const UniStgGrid2D & grid, int order_accuracy = kDefaultOrderAccuracy, Real mimetic_threshold = kDefaultMimeticThreshold)

16.10.3.2 DenseMatrix mtk::Interp2D::ReturnAsDenseMatrix()

16.10.4 Member Data Documentation

16.10.4.1 DenseMatrix mtk::Interp2D::interpolator_ [private]

Definition at line 78 of file mtk_interp_2d.h.

16.10.4.2 Real mtk::Interp2D::mimetic_threshold_ [private]

Definition at line 80 of file mtk_interp_2d.h.
```

Definition at line 79 of file mtk\_interp\_2d.h.

**16.10.4.3** int mtk::Interp2D::order\_accuracy\_ [private]

The documentation for this class was generated from the following file:

• include/mtk\_interp\_2d.h

# 16.11 mtk::Lap1D Class Reference

Implements a 1D mimetic Laplacian operator.

#include <mtk\_lap\_1d.h>

Collaboration diagram for mtk::Lap1D:

# mtk::Lap1D

- order\_accuracy\_
- laplacian length
- laplacian\_
- mimetic threshold
- + Lap1D()
- + Lap1D()
- + ~Lap1D()
- + ConstructLap1D()
- + ReturnAsDenseMatrix()
- + Data()

### **Public Member Functions**

• Lap1D ()

Default constructor.

• Lap1D (const Lap1D &lap)

Copy constructor.

• ~Lap1D ()

Destructor.

 bool ConstructLap1D (int order\_accuracy=kDefaultOrderAccuracy, Real mimetic\_threshold=kDefaultMimetic-Threshold)

Factory method implementing the CBS Algorithm to build operator.

DenseMatrix ReturnAsDenseMatrix (const UniStgGrid1D &grid)

Return the operator as a dense matrix.

mtk::Real \* Data (const UniStgGrid1D &grid)

Return the operator as a dense array.

# **Private Attributes**

· int order\_accuracy\_

Order of numerical accuracy of the operator.

· int laplacian\_length\_

Length of the output array.

· Real \* laplacian\_

Output array containing the operator and weights.

Real mimetic\_threshold\_

< Mimetic threshold.

### **Friends**

std::ostream & operator << (std::ostream & stream, Lap1D &in)</li>
 Output stream operator for printing.

# 16.11.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

Definition at line 76 of file mtk lap 1d.h.

## 16.11.2 Constructor & Destructor Documentation

```
16.11.2.1 mtk::Lap1D::Lap1D()
```

Definition at line 108 of file mtk\_lap\_1d.cc.

16.11.2.2 mtk::Lap1D::Lap1D ( const Lap1D & lap )

### **Parameters**

in	lap	Given Laplacian.

```
16.11.2.3 mtk::Lap1D::~Lap1D()
```

Definition at line 113 of file mtk lap 1d.cc.

## 16.11.3 Member Function Documentation

16.11.3.1 bool mtk::Lap1D::ConstructLap1D ( int order\_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic\_threshold = kDefaultMimeticThreshold )

### Returns

Success of the solution.

- 1. Create gradient operator using specific values for the Laplacian.
- 2. Create gradient operator using specific values for the Laplacian.
- 3. Create both operators as matrices.
- 4. Multiply both operators:  $\breve{\mathbf{L}}_{x}^{k} = \breve{\mathbf{D}}_{x}^{k} \breve{\mathbf{G}}_{x}^{k}$
- 5. Extract the coefficients from the matrix and store them in the array.

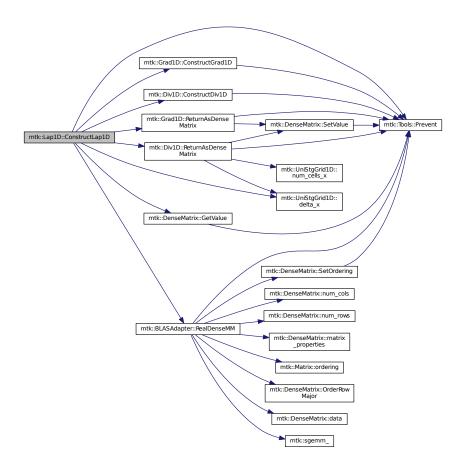
### Warning

We do not compute weights for this operator.

- 1. The first entry of the array will contain the order of accuracy.
- 2. The second entry of the array will contain the collection of approximating coefficients for the interior of the grid.
- 3. We DO NOT have weights in this operator. Copy mimetic bndy coeffs.

Definition at line 119 of file mtk\_lap\_1d.cc.

Here is the call graph for this function:



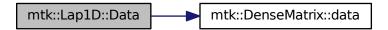
16.11.3.2 mtk::Real \* mtk::Lap1D::Data ( const UniStgGrid1D & grid )

#### Returns

The operator as a dense array.

Definition at line 332 of file mtk\_lap\_1d.cc.

Here is the call graph for this function:



16.11.3.3 mtk::DenseMatrix mtk::Lap1D::ReturnAsDenseMatrix ( const UniStgGrid1D & grid )

#### Returns

The operator as a dense matrix.

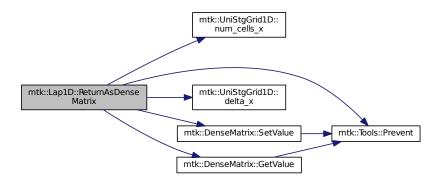
- 1. Extract mimetic coefficients from the west boundary.
- 2. Extract interior coefficients.
- 3. Extract mimetic coefficients from the west boundary to go east.

### Note

We could create two matrices of the requested size and multiply them, but that would be inefficient, since we already have the computed coefficients stored. We just have to set them in place, in a matrix of an adequate size, and multiply them times the inverse of the square of the step size, in order for the matrix to actually represent a differential operator.

Definition at line 265 of file mtk\_lap\_1d.cc.

Here is the call graph for this function:



### 16.11.4 Friends And Related Function Documentation

```
16.11.4.1 std::ostream& operator<<( std::ostream & stream, mtk::Lap1D & in ) [friend]
```

- 1. Print order of accuracy.
- 2. Print approximating coefficients for the interior.
- 3. No weights, thus print the mimetic boundary coefficients.

Definition at line 73 of file mtk\_lap\_1d.cc.

### 16.11.5 Member Data Documentation

```
16.11.5.1 Real* mtk::Lap1D::laplacian_ [private]
```

Definition at line 120 of file mtk\_lap\_1d.h.

```
16.11.5.2 int mtk::Lap1D::laplacian_length_ [private]
```

Definition at line 118 of file mtk\_lap\_1d.h.

```
16.11.5.3 Real mtk::Lap1D::mimetic_threshold_ [private]
```

Definition at line 122 of file mtk\_lap\_1d.h.

```
16.11.5.4 int mtk::Lap1D::order_accuracy_ [private]
```

Definition at line 117 of file mtk\_lap\_1d.h.

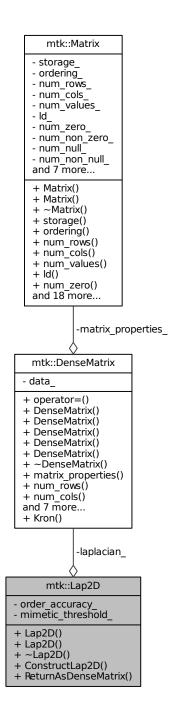
The documentation for this class was generated from the following files:

- include/mtk\_lap\_1d.h
- src/mtk\_lap\_1d.cc

# 16.12 mtk::Lap2D Class Reference

```
#include <mtk_lap_2d.h>
```

Collaboration diagram for mtk::Lap2D:



# **Public Member Functions**

- Lap2D ()
- Lap2D (const Lap2D &lap)

- ~Lap2D ()
- DenseMatrix ConstructLap2D (const UniStgGrid2D &grid, int order\_accuracy=kDefaultOrderAccuracy, Real mimetic threshold=kDefaultMimeticThreshold)
- DenseMatrix ReturnAsDenseMatrix ()

### **Private Attributes**

- DenseMatrix laplacian
- · int order\_accuracy\_
- Real mimetic\_threshold\_

### 16.12.1 Detailed Description

Definition at line 66 of file mtk\_lap\_2d.h.

```
16.12.2 Constructor & Destructor Documentation
```

```
16.12.2.1 mtk::Lap2D::Lap2D()
```

Definition at line 66 of file mtk\_lap\_2d.cc.

```
16.12.2.2 mtk::Lap2D::Lap2D ( const Lap2D & lap )
```

Definition at line 70 of file mtk\_lap\_2d.cc.

```
16.12.2.3 mtk::Lap2D::~Lap2D()
```

Definition at line 74 of file mtk\_lap\_2d.cc.

# 16.12.3 Member Function Documentation

16.12.3.1 mtk::DenseMatrix mtk::Lap2D::ConstructLap2D ( const UniStgGrid2D & grid, int order\_accuracy = kDefaultOrderAccuracy, mtk::Real mimetic\_threshold = kDefaultMimeticThreshold)

Definition at line 76 of file mtk\_lap\_2d.cc.

```
16.12.3.2 DenseMatrix mtk::Lap2D::ReturnAsDenseMatrix ( )
```

#### 16.12.4 Member Data Documentation

**16.12.4.1 DenseMatrix mtk::Lap2D::laplacian\_** [private]

Definition at line 77 of file mtk\_lap\_2d.h.

16.12.4.2 Real mtk::Lap2D::mimetic\_threshold\_ [private]

Definition at line 79 of file mtk lap 2d.h.

16.12.4.3 int mtk::Lap2D::order\_accuracy\_ [private]

Definition at line 78 of file mtk lap 2d.h.

The documentation for this class was generated from the following files:

- include/mtk lap 2d.h
- src/mtk\_lap\_2d.cc

# 16.13 mtk::LAPACKAdapter Class Reference

Adapter class for the LAPACK API.

#include <mtk\_lapack\_adapter.h>

Collaboration diagram for mtk::LAPACKAdapter:

## mtk::LAPACKAdapter

- + SolveDenseSystem()
- + SolveDenseSystem()
- + SolveDenseSystem()
- + SolveRectangularDenseSystem()
- + QRFactorDenseMatrix()

## **Static Public Member Functions**

• static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::Real \*rhs)

Solves a dense system of linear equations.

static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::DenseMatrix &rr)

Solves a dense system of linear equations.

static int SolveDenseSystem (mtk::DenseMatrix &mm, mtk::UniStgGrid1D &rhs)

Solves a dense system of linear equations.

• static int SolveRectangularDenseSystem (const mtk::DenseMatrix &aa, mtk::Real \*ob\_, int ob\_ld\_)

Solves overdetermined or underdetermined real linear systems.

• static mtk::DenseMatrix QRFactorDenseMatrix (DenseMatrix &matrix)

Performs a QR factorization on a dense matrix.

### 16.13.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

#### See Also

http://www.netlib.org/lapack/

Definition at line 92 of file mtk lapack adapter.h.

# 16.13.2 Member Function Documentation

16.13.2.1 mtk::DenseMatrix mtk::LAPACKAdapter::QRFactorDenseMatrix ( mtk::DenseMatrix & aa ) [static]

Adapts the MTK to LAPACK's routine.

### **Parameters**

in,out	matrix	Input matrix.	
--------	--------	---------------	--

#### **Returns**

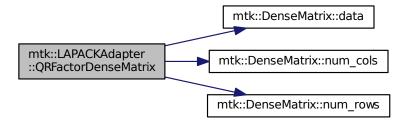
Matrix Q.

### **Exceptions**

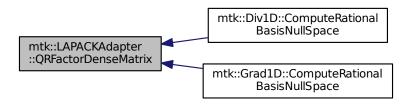
std::bad\_alloc

Definition at line 553 of file mtk\_lapack\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.13.2.2 int mtk::LAPACKAdapter::SolveDenseSystem ( mtk::DenseMatrix & mm, mtk::Real \* rhs ) [static]

Adapts the MTK to LAPACK's dgesv\_routine.

#### **Parameters**

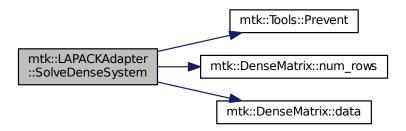
in	matrix	Input matrix.
in	rhs	Input right-hand sides vector.

# **Exceptions**

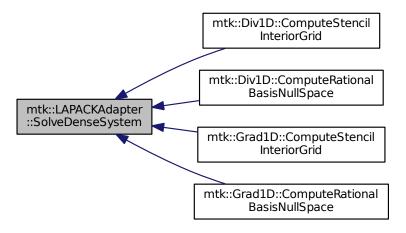
std::bad_alloc	

Definition at line 428 of file mtk\_lapack\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.13.2.3 int mtk::LAPACKAdapter::SolveDenseSystem ( mtk::DenseMatrix & mm, mtk::DenseMatrix & rr ) [static]

Adapts the MTK to LAPACK's dgesv\_routine.

#### **Parameters**

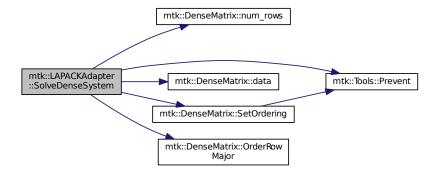
in	matrix	Input matrix.
in	rr	Input right-hand sides matrix.

# **Exceptions**

std::bad_alloc	

Definition at line 463 of file mtk\_lapack\_adapter.cc.

Here is the call graph for this function:



# 16.13.2.4 int mtk::LAPACKAdapter::SolveDenseSystem ( mtk::DenseMatrix & mm, mtk::UniStgGrid1D & rhs )

Adapts the MTK to LAPACK's dgesv\_routine.

# **Parameters**

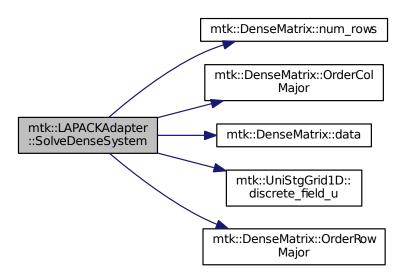
in	matrix	Input matrix.
in	rr	Input right-hand side from info on a grid.

# **Exceptions**

std::bad_alloc	

Definition at line 515 of file mtk\_lapack\_adapter.cc.

Here is the call graph for this function:



16.13.2.5 int mtk::LAPACKAdapter::SolveRectangularDenseSystem ( const mtk::DenseMatrix & aa, mtk::Real \* ob\_, int ob\_Id\_) [static]

Adapts the MTK to LAPACK's routine.

# Parameters

in,out	matrix	Input matrix.	

# Returns

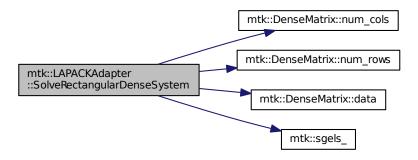
Success of the solution.

# **Exceptions**

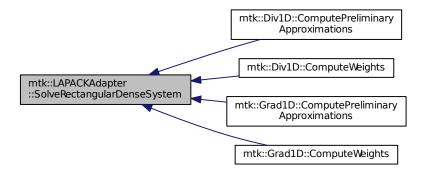
```
std::bad_alloc
```

Definition at line 754 of file mtk\_lapack\_adapter.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



The documentation for this class was generated from the following files:

- include/mtk\_lapack\_adapter.h
- src/mtk\_lapack\_adapter.cc

# 16.14 mtk::Matrix Class Reference

Definition of the representation of a matrix in the MTK.

#include <mtk\_matrix.h>

# Collaboration diagram for mtk::Matrix:

# mtk::Matrix - storage ordering - num\_rows\_ - num cols num\_values\_ - Id - num\_zero\_ - num\_non\_zero\_ - num\_null\_ num\_non\_null\_ and 7 more... + Matrix() + Matrix() + ~Matrix() + storage() + ordering() + num rows() + num cols() + num\_values() + Id()+ num zero() and 18 more...

# **Public Member Functions**

• Matrix ()

Default constructor.

• Matrix (const Matrix &in)

Copy constructor.

~Matrix ()

Destructor.

• MatrixStorage storage () const

Gets the type of storage of this matrix.

· MatrixOrdering ordering () const

Gets the type of ordering of this matrix.

• int num\_rows () const

Gets the number of rows.

• int num\_cols () const

Gets the number of rows.

int num\_values () const

Gets the number of values.

• int Id () const

Gets the matrix' leading dimension.

• int num\_zero () const

Gets the number of zeros.

• int num\_non\_zero () const

Gets the number of non-zero values.

int num\_null () const

Gets the number of null values.

• int num\_non\_null () const

Gets the number of non-null values.

• int kl () const

Gets the number of lower diagonals.

• int ku () const

Gets the number of upper diagonals.

• int bandwidth () const

Gets the bandwidth.

· Real abs density () const

Gets the absolute density.

• Real rel\_density () const

Gets the relative density.

• Real abs\_sparsity () const

Gets the Absolute sparsity.

• Real rel\_sparsity () const

Gets the Relative sparsity.

void set\_storage (const MatrixStorage &tt)

Sets the storage type of the matrix.

void set\_ordering (const MatrixOrdering &oo)

Sets the ordering of the matrix.

void set\_num\_rows (int num\_rows)

Sets the number of rows of the matrix.

void set\_num\_cols (int num\_cols)

Sets the number of columns of the matrix.

void set\_num\_zero (int in)

Sets the number of zero values of the matrix that matter.

• void set num null (int in)

Sets the number of zero values of the matrix that DO NOT matter.

void IncreaseNumZero ()

Increases the number of values that equal zero but with meaning.

void IncreaseNumNull ()

Increases the number of values that equal zero but with no meaning.

# **Private Attributes**

MatrixStorage storage\_

What type of matrix is this?

MatrixOrdering ordering\_

What kind of ordering is it following?

int num rows

Number of rows.

int num\_cols\_

Number of columns.

int num\_values\_

Number of total values in matrix.

int Id

Elements between successive rows when row-major.

int num zero

Number of zeros.

· int num\_non\_zero\_

Number of non-zero values.

int num null

Number of null (insignificant) values.

int num\_non\_null\_

Number of null (significant) values.

int kl

Number of lower diagonals on a banded matrix.

int ku

Number of upper diagonals on a banded matrix.

· int bandwidth\_

Bandwidth of the matrix.

Real abs\_density\_

Absolute density of matrix.

Real rel\_density\_

Relative density of matrix.

· Real abs\_sparsity\_

Absolute sparsity of matrix.

Real rel\_sparsity\_

Relative sparsity of matrix.

# 16.14.1 Detailed Description

Definition of the representation for the matrices implemented in the MTK.

Definition at line 75 of file mtk matrix.h.

### 16.14.2 Constructor & Destructor Documentation

16.14.2.1 mtk::Matrix::Matrix ( )

Definition at line 72 of file mtk matrix.cc.

16.14.2.2 mtk::Matrix::Matrix ( const Matrix & in )

#### **Parameters**

in in Given matrix.
---------------------

Definition at line 91 of file mtk\_matrix.cc.

```
16.14.2.3 mtk::Matrix::\simMatrix ( )
```

Definition at line 110 of file mtk matrix.cc.

# 16.14.3 Member Function Documentation

```
16.14.3.1 Real mtk::Matrix::abs_density ( ) const
```

See Also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

#### Returns

Absolute density of the matrix.

```
16.14.3.2 mtk::Real mtk::Matrix::abs_sparsity ( ) const
```

See Also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

### Returns

Absolute sparsity of the matrix.

Definition at line 182 of file mtk\_matrix.cc.

16.14.3.3 int mtk::Matrix::bandwidth ( ) const

Returns

Bandwidth of the matrix.

Definition at line 172 of file mtk\_matrix.cc.

16.14.3.4 void mtk::Matrix::IncreaseNumNull ( )

**Todo** Review the definition of sparse matrices properties.

Definition at line 279 of file mtk\_matrix.cc.

16.14.3.5 void mtk::Matrix::IncreaseNumZero ( )

**Todo** Review the definition of sparse matrices properties.

Definition at line 269 of file mtk\_matrix.cc.

16.14.3.6 int mtk::Matrix::kl ( ) const

Returns

Number of lower diagonals.

Definition at line 162 of file mtk matrix.cc.

16.14.3.7 int mtk::Matrix::ku ( ) const

Returns

Number of upper diagonals.

Definition at line 167 of file mtk\_matrix.cc.

16.14.3.8 int mtk::Matrix::ld ( ) const

Leading dimension of the data array is the number of elements between successive rows (for row major storage) in memory. Most of the cases, the leading dimension is the same as the number of columns.

Returns

Leading dimension of the matrix.

Definition at line 137 of file mtk matrix.cc.

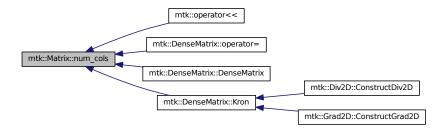
16.14.3.9 int mtk::Matrix::num\_cols ( ) const

Returns

Number of rows of the matrix.

Definition at line 127 of file mtk\_matrix.cc.

Here is the caller graph for this function:



```
16.14.3.10 int mtk::Matrix::num_non_null() const
```

#### See Also

```
http://www.csrc.sdsu.edu/research_reports/CSRCR2013-01.pdf
```

#### Returns

Number of non-null values of the matrix.

Definition at line 157 of file mtk\_matrix.cc.

16.14.3.11 int mtk::Matrix::num\_non\_zero ( ) const

#### Returns

Number of non-zero values of the matrix.

Definition at line 147 of file mtk\_matrix.cc.

16.14.3.12 int mtk::Matrix::num\_null() const

#### See Also

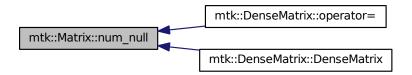
http://www.csrc.sdsu.edu/research\_reports/CSRCR2013-01.pdf

# Returns

Number of null values of the matrix.

Definition at line 152 of file mtk\_matrix.cc.

Here is the caller graph for this function:



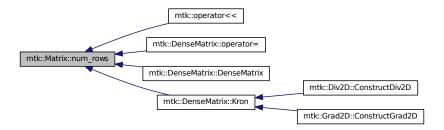
16.14.3.13 int mtk::Matrix::num\_rows ( ) const

Returns

Number of rows of the matrix.

Definition at line 122 of file mtk\_matrix.cc.

Here is the caller graph for this function:



16.14.3.14 int mtk::Matrix::num\_values ( ) const

Returns

Number of values of the matrix.

Definition at line 132 of file mtk\_matrix.cc.

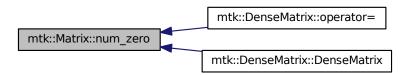
16.14.3.15 int mtk::Matrix::num\_zero ( ) const

Returns

Number of zeros of the matrix.

Definition at line 142 of file mtk\_matrix.cc.

Here is the caller graph for this function:



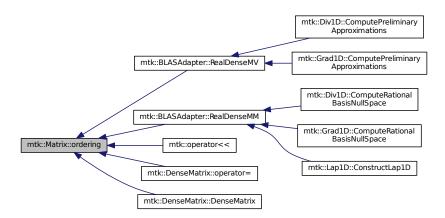
16.14.3.16 mtk::MatrixOrdering mtk::Matrix::ordering ( ) const

#### Returns

Type of ordering of this matrix.

Definition at line 117 of file mtk\_matrix.cc.

Here is the caller graph for this function:



16.14.3.17 mtk::Real mtk::Matrix::rel\_density ( ) const

# See Also

http://www.csrc.sdsu.edu/research\_reports/CSRCR2013-01.pdf

### Returns

Relative density of the matrix.

Definition at line 177 of file mtk\_matrix.cc.

16.14.3.18 mtk::Real mtk::Matrix::rel\_sparsity ( ) const

# See Also

http://www.csrc.sdsu.edu/research\_reports/CSRCR2013-01.pdf

# Returns

Relative sparsity of the matrix.

Definition at line 187 of file mtk\_matrix.cc.

16.14.3.19 void mtk::Matrix::set\_num\_cols ( int num\_cols )

# **Parameters**

in	num_cols	Number of columns.

Definition at line 229 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.3.20 void mtk::Matrix::set\_num\_null ( int in )

# **Parameters**

_			
	in	in	Number of zero values.

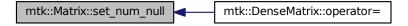
Bug -nan assigned on construction time due to num\_values\_ being 0.

Definition at line 255 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.3.21 void mtk::Matrix::set\_num\_rows ( int num\_rows )

#### **Parameters**

in	num_rows	Number of rows.
----	----------	-----------------

Definition at line 217 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.3.22 void mtk::Matrix::set\_num\_zero ( int in )

# **Parameters**

in	in	Number of zero values.

Bug -nan assigned on construction time due to num\_values\_ being 0.

Definition at line 241 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.3.23 void mtk::Matrix::set\_ordering ( const MatrixOrdering & oo )

# See Also

MatrixOrdering

# **Parameters**

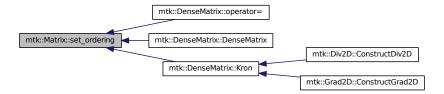
in	00	Ordering of the matrix.

Definition at line 204 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



16.14.3.24 void mtk::Matrix::set\_storage ( const MatrixStorage & tt )

See Also

MatrixStorage

#### **Parameters**

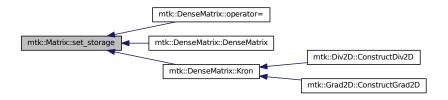
in	tt	Type of the matrix storage.
----	----	-----------------------------

Definition at line 192 of file mtk\_matrix.cc.

Here is the call graph for this function:



Here is the caller graph for this function:



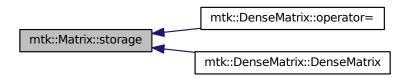
16.14.3.25 mtk::MatrixStorage mtk::Matrix::storage ( ) const

#### Returns

Type of storage of this matrix.

Definition at line 112 of file mtk\_matrix.cc.

Here is the caller graph for this function:



# 16.14.4 Member Data Documentation

**16.14.4.1 Real mtk::Matrix::abs\_density\_** [private]

Definition at line 296 of file mtk\_matrix.h.

**16.14.4.2 Real mtk::Matrix::abs\_sparsity\_** [private]

Definition at line 298 of file mtk\_matrix.h.

16.14.4.3 int mtk::Matrix::bandwidth\_ [private]

Definition at line 294 of file mtk\_matrix.h.

16.14.4.4 int mtk::Matrix::kl\_ [private]

Definition at line 292 of file mtk\_matrix.h.

16.14.4.5 int mtk::Matrix::ku\_ [private]

Definition at line 293 of file mtk matrix.h.

16.14.4.6 int mtk::Matrix::ld\_ [private]

Definition at line 285 of file mtk\_matrix.h.

16.14.4.7 int mtk::Matrix::num\_cols\_ [private]

Definition at line 283 of file mtk\_matrix.h.

```
16.14.4.8 int mtk::Matrix::num_non_null_ [private]
Definition at line 290 of file mtk_matrix.h.
16.14.4.9 int mtk::Matrix::num_non_zero_ [private]
Definition at line 288 of file mtk_matrix.h.
16.14.4.10 int mtk::Matrix::num_null_ [private]
Definition at line 289 of file mtk_matrix.h.
16.14.4.11 int mtk::Matrix::num_rows_ [private]
Definition at line 282 of file mtk matrix.h.
16.14.4.12 int mtk::Matrix::num_values_ [private]
Definition at line 284 of file mtk_matrix.h.
16.14.4.13 int mtk::Matrix::num_zero_ [private]
Definition at line 287 of file mtk matrix.h.
16.14.4.14 MatrixOrdering mtk::Matrix::ordering_ [private]
Definition at line 280 of file mtk_matrix.h.
16.14.4.15 Real mtk::Matrix::rel_density_ [private]
Definition at line 297 of file mtk matrix.h.
16.14.4.16 Real mtk::Matrix::rel_sparsity_ [private]
Definition at line 299 of file mtk matrix.h.
16.14.4.17 MatrixStorage mtk::Matrix::storage [private]
Definition at line 278 of file mtk_matrix.h.
The documentation for this class was generated from the following files:
```

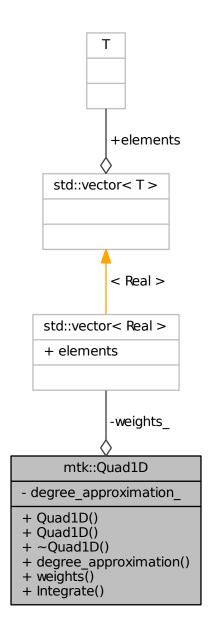
- include/mtk\_matrix.h
- src/mtk\_matrix.cc

# 16.15 mtk::Quad1D Class Reference

Implements a 1D mimetic quadrature.

#include <mtk\_quad\_1d.h>

Collaboration diagram for mtk::Quad1D:



# **Public Member Functions**

• Quad1D ()

Default constructor.

• Quad1D (const Quad1D &quad)

Copy constructor.

• ~Quad1D ()

Destructor.

int degree\_approximation () const

Get the degree of interpolating polynomial per sub-interval of domain.

• Real \* weights () const

Return collection of weights.

Real Integrate (Real(\*Integrand)(Real xx), UniStgGrid1D grid)

Mimetic integration routine.

# **Private Attributes**

· int degree\_approximation\_

Degree of the interpolating polynomial.

• std::vector< Real > weights\_

Collection of weights.

#### **Friends**

std::ostream & operator<< (std::ostream &stream, Quad1D &in)</li>

Output stream operator for printing.

# 16.15.1 Detailed Description

This class implements a 1D quadrature solver based on the mimetic discretization of the gradient operator.

Definition at line 81 of file mtk\_quad\_1d.h.

# 16.15.2 Constructor & Destructor Documentation

16.15.2.1 mtk::Quad1D::Quad1D( )

16.15.2.2 mtk::Quad1D::Quad1D ( const Quad1D & quad )

# **Parameters**

	in	div	Given quadrature.
--	----	-----	-------------------

```
16.15.2.3 mtk::Quad1D::~Quad1D()
```

# 16.15.3 Member Function Documentation

16.15.3.1 int mtk::Quad1D::degree\_approximation ( ) const

Returns

Degree of the interpolating polynomial per sub-interval of the domain.

#### 16.15.3.2 Real mtk::Quad1D::Integrate ( Real(\*)(Real xx) Integrand, UniStgGrid1D grid )

#### **Parameters**

in	Integrand	Real-valued function to integrate.
in	grid	Given integration domain.

#### Returns

Result of the integration.

16.15.3.3 Real\* mtk::Quad1D::weights ( ) const

Returns

Collection of weights.

#### 16.15.4 Friends And Related Function Documentation

16.15.4.1 std::ostream& operator<<( std::ostream & stream, Quad1D & in ) [friend]

# 16.15.5 Member Data Documentation

**16.15.5.1** int mtk::Quad1D::degree\_approximation\_ [private]

Definition at line 124 of file mtk\_quad\_1d.h.

16.15.5.2 std::vector<Real> mtk::Quad1D::weights\_ [private]

Definition at line 126 of file mtk\_quad\_1d.h.

The documentation for this class was generated from the following file:

• include/mtk\_quad\_1d.h

# 16.16 mtk::Tools Class Reference

Tool manager class.

#include <mtk\_tools.h>

Collaboration diagram for mtk::Tools:

# mtk::Tools

- test\_number\_
- begin\_time\_
- + Prevent()
- + BeginTestNo()
- + EndTestNo()

# **Static Public Member Functions**

• static void Prevent (const bool condition, const char \*fname, int lineno, const char \*fxname)

Enforces pre-conditions by preventing their complements from occur.

• static void BeginTestNo (const int &nn)

Begins the execution of a test.

• static void EndTestNo (const int &nn)

Ends the execution of a test.

# **Static Private Attributes**

static int test\_number\_

Current test being executed.

static clock\_t begin\_time\_

Elapsed time on current test.

# 16.16.1 Detailed Description

Basic tools to ensure execution correctness.

Definition at line 72 of file mtk\_tools.h.

# 16.16.2 Member Function Documentation

16.16.2.1 void mtk::Tools::BeginTestNo (const int & nn ) [static]

**Parameters** 

-			
	in	nn	Number of the test.

Definition at line 89 of file mtk\_tools.cc.

Here is the call graph for this function:



16.16.2.2 void mtk::Tools::EndTestNo ( const int & nn ) [static]

#### **Parameters**

in	nn	Number of the test.

Definition at line 101 of file mtk\_tools.cc.

Here is the call graph for this function:



16.16.2.3 void mtk::Tools::Prevent ( const bool condition, const char \* fname, int lineno, const char \* fxname ) [static]

# See Also

http://stackoverflow.com/questions/8884335/print-the-file-name-line-number-and-function

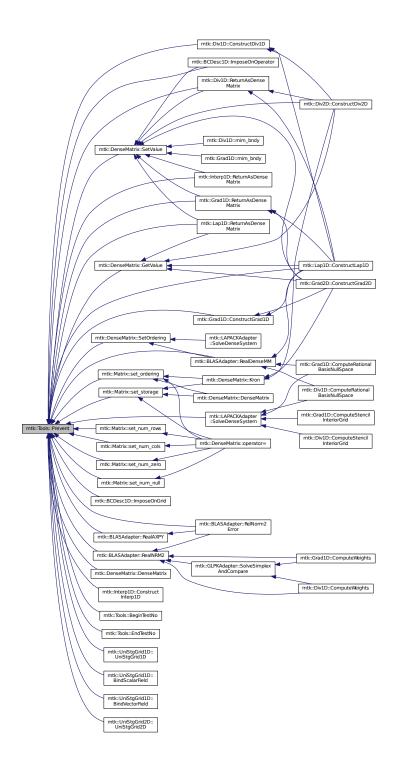
#### **Parameters**

in	condition	Complement of desired pre-condition.
in	fname	Name of the file being checked.
in	lineno	Number of the line where the check is executed.
in	fxname	Name of the module containing the check.

**Todo** Check if this is the best way of stalling execution.

Definition at line 61 of file mtk\_tools.cc.

Here is the caller graph for this function:



# 16.16.3 Member Data Documentation

16.16.3.1 clock\_t mtk::Tools::begin\_time\_ [static], [private]

Definition at line 106 of file mtk\_tools.h.

16.16.3.2 int mtk::Tools::test\_number\_ [static], [private]

Todo Check usage of static methods and private members.

Definition at line 104 of file mtk\_tools.h.

The documentation for this class was generated from the following files:

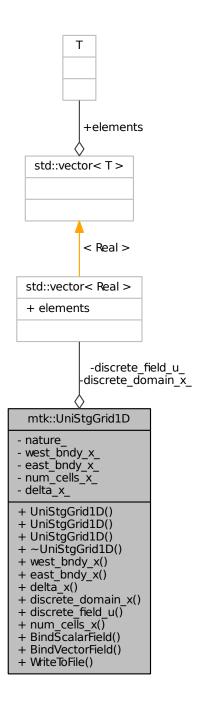
- include/mtk\_tools.h
- src/mtk\_tools.cc

# 16.17 mtk::UniStgGrid1D Class Reference

Uniform 1D Staggered Grid.

#include <mtk\_uni\_stg\_grid\_1d.h>

Collaboration diagram for mtk::UniStgGrid1D:



# **Public Member Functions**

• UniStgGrid1D ()

Default constructor.

UniStgGrid1D (const UniStgGrid1D &grid)

Copy constructor.

UniStgGrid1D (const Real &west\_bndy\_x, const Real &east\_bndy\_x, const int &num\_cells\_x, const mtk::Field-Nature &nature=mtk::SCALAR)

Construct a grid based on spatial discretization parameters.

∼UniStgGrid1D ()

Destructor.

• Real west\_bndy\_x () const

Provides access to west boundary spatial coordinate.

Real east\_bndy\_x () const

Provides access to east boundary spatial coordinate.

Real delta\_x () const

Provides access to the computed \$ x \$.

• Real \* discrete domain x ()

Provides access to the grid spatial data.

• Real \* discrete\_field\_u ()

Provides access to the grid field data.

int num\_cells\_x () const

Provides access to the number of cells of the grid.

void BindScalarField (Real(\*ScalarField)(Real xx))

Binds a given scalar field to the grid.

void BindVectorField (Real(\*VectorField)(Real xx))

Binds a given vector field to the grid.

bool WriteToFile (std::string filename, std::string space\_name, std::string field\_name)

Writes grid to a file compatible with Gnuplot 4.6.

#### **Private Attributes**

FieldNature nature\_

Nature of the discrete field.

std::vector< Real > discrete\_domain\_x\_

Array of spatial data.

std::vector< Real > discrete\_field\_u\_

Array of field's data.

Real west\_bndy\_x\_

West boundary spatial coordinate.

Real east\_bndy\_x\_

East boundary spatial coordinate.

Real num\_cells\_x\_

Number of cells discretizing the domain.

Real delta\_x\_

Produced  $\Delta x$ .

#### **Friends**

std::ostream & operator<< (std::ostream &stream, UniStgGrid1D &in)</li>

Prints the grid as a tuple of arrays.

# 16.17.1 Detailed Description

Uniform 1D Staggered Grid.

Definition at line 77 of file mtk\_uni\_stg\_grid\_1d.h.

# 16.17.2 Constructor & Destructor Documentation

16.17.2.1 mtk::UniStgGrid1D::UniStgGrid1D()

Definition at line 99 of file mtk\_uni\_stg\_grid\_1d.cc.

16.17.2.2 mtk::UniStgGrid1D::UniStgGrid1D ( const UniStgGrid1D & grid )

# **Parameters**

in	grid	Given grid.

Definition at line 108 of file mtk\_uni\_stg\_grid\_1d.cc.

16.17.2.3 mtk::UniStgGrid1D::UniStgGrid1D ( const Real & west\_bndy\_x, const Real & east\_bndy\_x, const int & num\_cells\_x, const mtk::FieldNature & nature = mtk::SCALAR )

#### **Parameters**

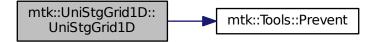
in	west_bndy_x	Coordinate for the west boundary.
in	east_bndy_x	Coordinate for the east boundary.
in	num_cells_x	Number of cells of the required grid.
in	nature	Nature of the discrete field to hold.

# See Also

mtk::FieldNature

Definition at line 124 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the call graph for this function:



16.17.2.4 mtk::UniStgGrid1D::~UniStgGrid1D()

Definition at line 144 of file mtk\_uni\_stg\_grid\_1d.cc.

# 16.17.3 Member Function Documentation

# 16.17.3.1 void mtk::UniStgGrid1D::BindScalarField ( Real(\*)(Real xx) ScalarField )

#### **Parameters**

in	ScalarField	Pointer to the function implementing the scalar field.

- 1. Create collection of spatial coordinates.
- 2. Create collection of field samples.

Definition at line 176 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the call graph for this function:



# 16.17.3.2 void mtk::UniStgGrid1D::BindVectorField ( Real(\*)(Real xx) VectorField )

We assume the field to be of the form:

$$\mathbf{v}(x) = v(x)\hat{\mathbf{i}}$$

# **Parameters**

in	VectorField	Pointer to the function implementing the vector field.

- 1. Create collection of spatial coordinates.
- 2. Create collection of field samples.

Definition at line 212 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the call graph for this function:



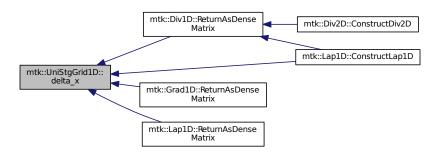
16.17.3.3 mtk::Real mtk::UniStgGrid1D::delta\_x ( ) const

Returns

Computed \$ x \$.

Definition at line 156 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the caller graph for this function:



16.17.3.4 mtk::Real \* mtk::UniStgGrid1D::discrete\_domain\_x ( )

Returns

Pointer to the spatial data.

Definition at line 161 of file mtk\_uni\_stg\_grid\_1d.cc.

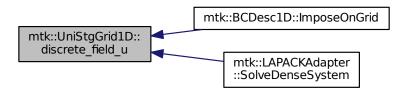
16.17.3.5 mtk::Real \* mtk::UniStgGrid1D::discrete\_field\_u ( )

Returns

Pointer to the field data.

Definition at line 166 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the caller graph for this function:



16.17.3.6 mtk::Real mtk::UniStgGrid1D::east\_bndy\_x ( ) const

Returns

East boundary spatial coordinate.

Definition at line 151 of file mtk\_uni\_stg\_grid\_1d.cc.

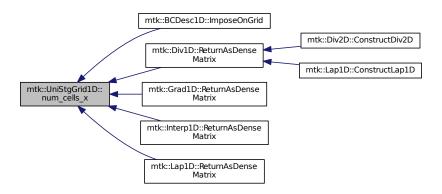
16.17.3.7 int mtk::UniStgGrid1D::num\_cells\_x ( ) const

Returns

Number of cells of the grid.

Definition at line 171 of file mtk\_uni\_stg\_grid\_1d.cc.

Here is the caller graph for this function:



16.17.3.8 mtk::Real mtk::UniStgGrid1D::west\_bndy\_x ( ) const

Returns

West boundary spatial coordinate.

Definition at line 146 of file mtk\_uni\_stg\_grid\_1d.cc.

16.17.3.9 bool mtk::UniStgGrid1D::WriteToFile ( std::string filename, std::string space\_name, std::string field\_name )

# **Parameters**

in	filename	Name of the output file.
in	space_name	Name for the first column of the data.

in	field_name	Name for the second column of the data.
----	------------	---

#### Returns

Success of the file writing process.

# See Also

```
http://www.gnuplot.info/
```

Definition at line 240 of file mtk uni stg grid 1d.cc.

#### 16.17.4 Friends And Related Function Documentation

```
16.17.4.1 std::ostream& operator<<( std::ostream & stream, mtk::UniStgGrid1D & in ) [friend]
```

- 1. Print spatial coordinates.
- 2. Print scalar field.

Definition at line 68 of file mtk\_uni\_stg\_grid\_1d.cc.

#### 16.17.5 Member Data Documentation

```
16.17.5.1 Real mtk::UniStgGrid1D::delta_x_ [private]
```

Definition at line 196 of file mtk\_uni\_stg\_grid\_1d.h.

```
16.17.5.2 std::vector<Real> mtk::UniStgGrid1D::discrete_domain_x_ [private]
```

Definition at line 190 of file mtk\_uni\_stg\_grid\_1d.h.

```
16.17.5.3 std::vector<Real> mtk::UniStgGrid1D::discrete_field_u_ [private]
```

Definition at line 191 of file mtk\_uni\_stg\_grid\_1d.h.

```
16.17.5.4 Real mtk::UniStgGrid1D::east_bndy_x_ [private]
```

Definition at line 194 of file mtk\_uni\_stg\_grid\_1d.h.

**16.17.5.5 FieldNature mtk::UniStgGrid1D::nature\_** [private]

Definition at line 188 of file mtk\_uni\_stg\_grid\_1d.h.

16.17.5.6 Real mtk::UniStgGrid1D::num\_cells\_x\_ [private]

Definition at line 195 of file mtk uni stg grid 1d.h.

**16.17.5.7 Real mtk::UniStgGrid1D::west\_bndy\_x** [private]

Definition at line 193 of file mtk\_uni\_stg\_grid\_1d.h.

The documentation for this class was generated from the following files:

• include/mtk\_uni\_stg\_grid\_1d.h

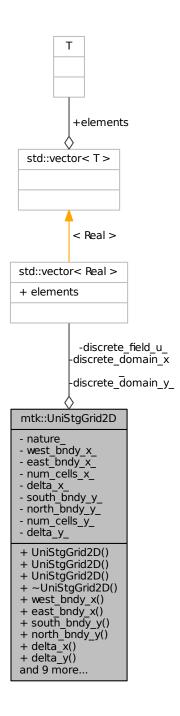
• src/mtk\_uni\_stg\_grid\_1d.cc

# 16.18 mtk::UniStgGrid2D Class Reference

Uniform 2D Staggered Grid.

#include <mtk\_uni\_stg\_grid\_2d.h>

Collaboration diagram for mtk::UniStgGrid2D:



# **Public Member Functions**

• UniStgGrid2D ()

Default constructor.

UniStgGrid2D (const UniStgGrid2D &grid)

Copy constructor.

UniStgGrid2D (const Real &west\_bndy\_x, const Real &east\_bndy\_x, const int &num\_cells\_x, const Real &south-bndy\_y, const Real &north\_bndy\_y, const int &num\_cells\_y, const mtk::FieldNature &nature=mtk::SCALAR)

Construct a grid based on spatial discretization parameters.

∼UniStgGrid2D ()

Destructor.

Real west\_bndy\_x () const

Provides access to west boundary spatial coordinate.

Real east bndy x () const

Provides access to east boundary spatial coordinate.

Real south\_bndy\_y () const

Provides access to south boundary spatial coordinate.

Real north\_bndy\_y () const

Provides access to north boundary spatial coordinate.

• Real delta\_x () const

Provides access to the computed \$ x \$.

• Real delta y () const

Provides access to the computed \$ y \$.

Real \* discrete\_domain\_x ()

Provides access to the grid spatial data.

Real \* discrete\_domain\_y ()

Provides access to the grid spatial data.

Real \* discrete\_field\_u ()

Provides access to the grid field data.

• int num\_cells\_x () const

Provides access to the number of cells of the grid.

• int num\_cells\_y () const

Provides access to the number of cells of the grid.

void BindScalarField (Real(\*ScalarField)(Real xx, Real yy))

Binds a given scalar field to the grid.

• void BindVectorFieldPComponent (Real(\*VectorField)(Real xx, Real yy))

Binds a given vector field to the grid.

void BindVectorFieldQComponent (Real(\*VectorField)(Real xx, Real yy))

Binds a given vector field to the grid.

• bool WriteToFile (std::string filename, std::string space\_name, std::string field\_name)

Writes grid to a file compatible with Gnuplot 4.6.

# **Private Attributes**

FieldNature nature\_

Nature of the discrete field.

std::vector< Real > discrete\_domain\_x\_

Array of spatial data.

std::vector < Real > discrete\_domain\_y\_

Array of spatial data.

std::vector< Real > discrete\_field\_u\_

Array of field's data.

Real west\_bndy\_x\_

West boundary spatial coordinate.

Real east\_bndy\_x\_

East boundary spatial coordinate.

Real num\_cells\_x\_

Number of cells discretizing the domain.

Real delta x

Produced  $\Delta x$ .

Real south\_bndy\_y\_

West boundary spatial coordinate.

Real north\_bndy\_y\_

East boundary spatial coordinate.

Real num\_cells\_y\_

Number of cells discretizing the domain.

Real delta\_y\_

Produced  $\Delta y$ .

# **Friends**

std::ostream & operator<< (std::ostream &stream, UniStgGrid2D &in)</li>

Prints the grid as a tuple of arrays.

# 16.18.1 Detailed Description

Uniform 2D Staggered Grid.

Definition at line 79 of file mtk\_uni\_stg\_grid\_2d.h.

# 16.18.2 Constructor & Destructor Documentation

16.18.2.1 mtk::UniStgGrid2D::UniStgGrid2D()

Definition at line 111 of file mtk\_uni\_stg\_grid\_2d.cc.

16.18.2.2 mtk::UniStgGrid2D::UniStgGrid2D ( const UniStgGrid2D & grid )

#### **Parameters**

in	grid	Given grid.
----	------	-------------

Definition at line 125 of file mtk\_uni\_stg\_grid\_2d.cc.

16.18.2.3 mtk::UniStgGrid2D::UniStgGrid2D ( const Real & west\_bndy\_x, const Real & east\_bndy\_x, const int & num\_cells\_x, const Real & south\_bndy\_y, const Real & north\_bndy\_y, const int & num\_cells\_y, const mtk::FieldNature & nature = mtk::SCALAR )

#### **Parameters**

in	west_bndy_x	Coordinate for the west boundary.
in	east_bndy_x	Coordinate for the east boundary.
in	num_cells_x	Number of cells of the required grid.
in	south_bndy_y	Coordinate for the west boundary.
in	north_bndy_y	Coordinate for the east boundary.
in	num_cells_y	Number of cells of the required grid.
in	nature	Nature of the discrete field to hold.

#### See Also

mtk::FieldNature

Definition at line 149 of file mtk\_uni\_stg\_grid\_2d.cc.

Here is the call graph for this function:



16.18.2.4 mtk::UniStgGrid2D::~UniStgGrid2D()

Definition at line 183 of file mtk\_uni\_stg\_grid\_2d.cc.

#### 16.18.3 Member Function Documentation

16.18.3.1 void mtk::UniStgGrid2D::BindScalarField ( Real(\*)(Real xx, Real yy) ScalarField )

#### **Parameters**

in	ScalarField	Pointer to the function implementing the scalar field.
----	-------------	--

16.18.3.2 void mtk::UniStgGrid2D::BindVectorFieldPComponent ( Real(\*)(Real xx, Real yy) VectorField )

We assume the field to be of the form:

$$\mathbf{v}(x) = p(x, y)\hat{\mathbf{i}} + q(x, y)\hat{\mathbf{j}}$$

162 Class Documentation

#### **Parameters**

in	VectorField	Pointer to the function implementing the vector field.
----	-------------	--

16.18.3.3 void mtk::UniStgGrid2D::BindVectorFieldQComponent ( Real(\*)(Real xx, Real yy) VectorField )

We assume the field to be of the form:

$$\mathbf{v}(x) = p(x, y)\hat{\mathbf{i}} + q(x, y)\hat{\mathbf{j}}$$

#### **Parameters**

in	VectorField	Pointer to the function implementing the vector field.
----	-------------	--

16.18.3.4 Real mtk::UniStgGrid2D::delta\_x ( ) const

Returns

Computed \$ x \$.

16.18.3.5 Real mtk::UniStgGrid2D::delta\_y ( ) const

Returns

Computed \$ y \$.

16.18.3.6 Real\* mtk::UniStgGrid2D::discrete\_domain\_x ( )

Returns

Pointer to the spatial data.

16.18.3.7 Real\* mtk::UniStgGrid2D::discrete\_domain\_y ( )

Returns

Pointer to the spatial data.

16.18.3.8 Real\* mtk::UniStgGrid2D::discrete\_field\_u ( )

Returns

Pointer to the field data.

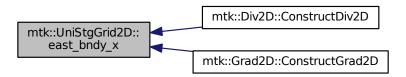
16.18.3.9 mtk::Real mtk::UniStgGrid2D::east\_bndy\_x ( ) const

Returns

East boundary spatial coordinate.

Definition at line 190 of file mtk\_uni\_stg\_grid\_2d.cc.

Here is the caller graph for this function:



16.18.3.10 mtk::Real mtk::UniStgGrid2D::north\_bndy\_y ( ) const

Returns

North boundary spatial coordinate.

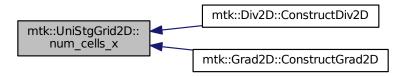
Definition at line 200 of file mtk\_uni\_stg\_grid\_2d.cc.

16.18.3.11 int mtk::UniStgGrid2D::num\_cells\_x ( ) const

Returns

Number of cells of the grid.

Here is the caller graph for this function:



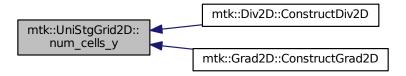
16.18.3.12 int mtk::UniStgGrid2D::num\_cells\_y ( ) const

164 Class Documentation

#### Returns

Number of cells of the grid.

Here is the caller graph for this function:



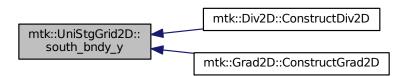
16.18.3.13 mtk::Real mtk::UniStgGrid2D::south\_bndy\_y ( ) const

#### Returns

South boundary spatial coordinate.

Definition at line 195 of file mtk\_uni\_stg\_grid\_2d.cc.

Here is the caller graph for this function:



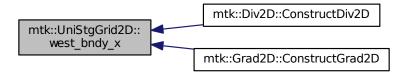
16.18.3.14 mtk::Real mtk::UniStgGrid2D::west\_bndy\_x ( ) const

#### Returns

West boundary spatial coordinate.

Definition at line 185 of file mtk\_uni\_stg\_grid\_2d.cc.

Here is the caller graph for this function:



16.18.3.15 bool mtk::UniStgGrid2D::WriteToFile ( std::string filename, std::string space\_name, std::string field\_name )

#### **Parameters**

in	filename	Name of the output file.
in	space_name	Name for the first column of the data.
in	field_name	Name for the second column of the data.

#### Returns

Success of the file writing process.

### See Also

http://www.gnuplot.info/

### 16.18.4 Friends And Related Function Documentation

16.18.4.1 std::ostream& operator<<( std::ostream & stream, mtk::UniStgGrid2D & in ) [friend]

- 1. Print spatial coordinates.
- 2. Print scalar field.

Definition at line 66 of file mtk\_uni\_stg\_grid\_2d.cc.

#### 16.18.5 Member Data Documentation

**16.18.5.1 Real mtk::UniStgGrid2D::delta\_x** [private]

Definition at line 253 of file mtk\_uni\_stg\_grid\_2d.h.

166 Class Documentation

```
16.18.5.2 Real mtk::UniStgGrid2D::delta_y [private]
Definition at line 258 of file mtk uni stg grid 2d.h.
16.18.5.3 std::vector<Real> mtk::UniStgGrid2D::discrete_domain_x_ [private]
Definition at line 246 of file mtk_uni_stg_grid_2d.h.
16.18.5.4 std::vector<Real> mtk::UniStgGrid2D::discrete_domain_y_ [private]
Definition at line 247 of file mtk_uni_stg_grid_2d.h.
16.18.5.5 std::vector<Real> mtk::UniStgGrid2D::discrete_field_u_ [private]
Definition at line 248 of file mtk_uni_stg_grid_2d.h.
16.18.5.6 Real mtk::UniStgGrid2D::east_bndy_x_ [private]
Definition at line 251 of file mtk uni stg grid 2d.h.
16.18.5.7 FieldNature mtk::UniStgGrid2D::nature [private]
Definition at line 244 of file mtk_uni_stg_grid_2d.h.
16.18.5.8 Real mtk::UniStgGrid2D::north_bndy_y_ [private]
Definition at line 256 of file mtk uni stg grid 2d.h.
16.18.5.9 Real mtk::UniStgGrid2D::num_cells_x_ [private]
Definition at line 252 of file mtk uni stg grid 2d.h.
16.18.5.10 Real mtk::UniStgGrid2D::num_cells_y_ [private]
Definition at line 257 of file mtk_uni_stg_grid_2d.h.
16.18.5.11 Real mtk::UniStgGrid2D::south_bndy_y_ [private]
Definition at line 255 of file mtk_uni_stg_grid_2d.h.
16.18.5.12 Real mtk::UniStgGrid2D::west_bndy_x_ [private]
Definition at line 250 of file mtk_uni_stg_grid_2d.h.
The documentation for this class was generated from the following files:
```

· include/mtk uni stg grid 2d.h

• src/mtk\_uni\_stg\_grid\_2d.cc

168 **Class Documentation** 

# **Chapter 17**

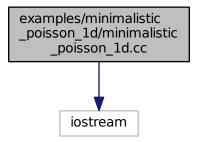
# **File Documentation**

# 17.1 examples/minimalistic\_poisson\_1d/minimalistic\_poisson\_1d.cc File Reference

Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs.

#include <iostream>

Include dependency graph for minimalistic\_poisson\_1d.cc:



## **Functions**

• int main ()

## 17.1.1 Detailed Description

We solve:

$$\nabla^2 p(x) = -s(x),$$

for 
$$x \in \Omega = [a, b] = [0, 1]$$
.

The source term function is defined as

$$s(x) = \frac{\lambda^2 \exp(\lambda x)}{\exp(\lambda) - 1}$$

where  $\lambda = -1$  is a parameter.

We consider Robin's boundary conditions of the form:

$$\alpha p(a) - \beta p'(a) = \omega$$
,

$$\alpha p(b) + \beta p'(b) = \varepsilon$$
.

The analytical solution for this problem is given by

$$p(x) = \frac{\exp(\lambda x) - 1}{\exp(\lambda) - 1}.$$

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Raul Vargas-Navarro - vargasna at rohan dot sdsu dot edu

Definition in file minimalistic\_poisson\_1d.cc.

### 17.1.2 Function Documentation

17.1.2.1 int main ( )

Definition at line 183 of file minimalistic poisson 1d.cc.

# 17.2 minimalistic\_poisson\_1d.cc

```
00001
00042 /*
00043 Copyright (C) 2015, Computational Science Research Center, San Diego State
00044 University. All rights reserved.
00046 Redistribution and use in source and binary forms, with or without modification,
00047 are permitted provided that the following conditions are met:
00049 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00050 and a copy of the modified files should be reported once modifications are
00051 completed. Documentation related to said modifications should be included.
00052
00053 2. Redistributions of source code must be done through direct
00054 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00056 3. Redistributions of source code must retain the above copyright notice, this
00057 list of conditions and the following disclaimer.
00058
00059 4. Redistributions in binary form must reproduce the above copyright notice,
00060 this list of conditions and the following disclaimer in the documentation and/or
00061 other materials provided with the distribution.
00062
00063 5. Usage of the binary form on proprietary applications shall require explicit
00064 prior written permission from the the copyright holders.
```

```
00065
00066 6. Neither the name of the copyright holder nor the names of its contributors
00067 may be used to endorse or promote products derived from this software without
00068 specific prior written permission.
00070 The copyright holders provide no reassurances that the source code provided does
00071 not infringe any patent, copyright, or any other intellectual property rights of
00072 third parties. The copyright holders disclaim any liability to any recipient for
00073 claims brought against recipient by any third party for infringement of that
00074 parties intellectual property rights.
00075
00076 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00077 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00078 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00079 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00080 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00081 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00082 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00083 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00084 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00085 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00086 */
00087
00088 #if __cplusplus == 201103L
00089
00090 #include <iostream>
00091 #include <fstream>
00092 #include <cmath>
00093
00094 #include <vector>
00095
00096 #include "mtk.h"
00097
00098 mtk::Real Source(mtk::Real xx) {
00099
00100
       mtk::Real lambda = -1.0;
00101
00102
       return lambda*lambda*exp(lambda*xx)/(exp(lambda) - 1.0);
00103 }
00104
00105 mtk::Real KnownSolution(mtk::Real xx) {
00106
00107
       mtk::Real lambda = -1.0;
00108
00109
       return (exp(lambda*xx) - 1.0)/(exp(lambda) - 1.0);
00110 }
00111
00112 int main () {
00113
       mtk::Real west_bndy_x = 0.0;
00114
00115
       mtk::Real east_bndy_x = 1.0;
       mtk::Real relative_norm_2_error{};
00116
00117
        int num_cells_x = 5;
00118
        mtk::Grad1D grad;
00119
       mtk::Lap1D lap;
00120
        std::vector<mtk::Real> west_coeffs;
        std::vector<mtk::Real> east_coeffs;
00121
00122
        mtk::UniStgGrid1D source(west_bndy_x, east_bndy_x, num_cells_x);
00123
       mtk::UniStgGrid1D comp_sol(west_bndy_x, east_bndy_x, num_cells_x);
00124
       mtk::UniStgGrid1D known_sol(west_bndy_x, east_bndy_x, num_cells_x);
00125
00126
        if (!lap.ConstructLap1D()) {
00127
         std::cerr << "Mimetic lap could not be built." << std::endl;
00128
         return EXIT_FAILURE;
00129
00130
00131
        mtk::DenseMatrix lapm(lap.ReturnAsDenseMatrix(comp_sol));
00132
00133
        if (!grad.ConstructGrad1D()) {
         std::cerr << "Mimetic grad could not be built." << std::endl;</pre>
00134
00135
         return EXIT_FAILURE;
00136
00137
00138
        mtk::DenseMatrix gradm(grad.ReturnAsDenseMatrix(comp sol));
00139
00140
        source.BindScalarField(Source);
00141
00142
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
         west_coeffs.push_back(-((exp(-1.0) - 1.0)/-1.0)*gradm.GetValue(0, ii));
00143
        }
00144
00145
```

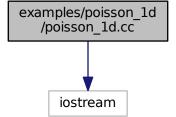
```
for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00147
          east_coeffs.push_back(((exp(-1.0) - 1.0)/-1.0)*gradm.GetValue(gradm.num_rows() - 1,
00148
                                                        gradm.num_cols() - 1 - ii));
00149
00150
00151
        west_coeffs[0] += -exp(-1.0);
00152
00153
        east\_coeffs[0] += -exp(-1.0);
00154
00155
        mtk::BCDesc1D::ImposeOnOperator(lapm, west_coeffs, east_coeffs);
00156
00157
        mtk::BCDesc1D::ImposeOnGrid(source, -1.0, 0.0);
00158
00159
        int info{mtk::LAPACKAdapter::SolveDenseSystem(lapm, source)};
00160
00161
        if (info != 0) {
00162
          std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
00163
          return EXIT_FAILURE;
00164
00165
00166
        source.WriteToFile("minimalistic_poisson_ld_comp_sol.dat", "x", "~u(x)");
00167
00168
        known sol.BindScalarField(KnownSolution);
00169
00170
        relative norm 2 error =
00171
          mtk::BLASAdapter::RelNorm2Error(source.discrete_field_u(),
00172
                                             known_sol.discrete_field_u(),
00173
                                             known_sol.num_cells_x());
00174
        std::cout << "relative_norm_2_error = ";</pre>
00175
00176
        std::cout << relative_norm_2_error << std::endl;</pre>
00177 }
00178
00179 #else
00180 #include <iostream>
00181 using std::cout;
00182 using std::endl;
00183 int main () {
00184    cout << "This code HAS to be compiled with support for C++11." << endl;
00185    cout << "Exiting..." << endl;
00186
       return EXIT_SUCCESS;
00187 }
00188 #endif
```

# 17.3 examples/poisson\_1d/poisson\_1d.cc File Reference

Poisson Equation on a 1D Uniform Staggered Grid with Robin BCs.

#include <iostream>

Include dependency graph for poisson\_1d.cc:



17.4 poisson\_1d.cc 173

#### **Functions**

• int main ()

#### 17.3.1 Detailed Description

We solve:

$$\nabla^2 p(x) = -s(x),$$

for 
$$x \in \Omega = [a, b] = [0, 1]$$
.

The source term function is defined as

$$s(x) = \frac{\lambda^2 \exp(\lambda x)}{\exp(\lambda) - 1}$$

where  $\lambda = -1$  is a parameter.

We consider Robin's boundary conditions of the form:

$$\alpha p(a) - \beta p'(a) = \omega$$
,

$$\alpha p(b) + \beta p'(b) = \varepsilon$$
.

The analytical solution for this problem is given by

$$p(x) = \frac{\exp(\lambda x) - 1}{\exp(\lambda) - 1}.$$

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Raul Vargas-Navarro - vargasna at rohan dot sdsu dot edu

Definition in file poisson\_1d.cc.

### 17.3.2 Function Documentation

```
17.3.2.1 int main ( )
```

Definition at line 261 of file poisson\_1d.cc.

# 17.4 poisson\_1d.cc

```
00001 00042 /\star 00043 Copyright (C) 2015, Computational Science Research Center, San Diego State 00044 University. All rights reserved. 00045
```

```
00046 Redistribution and use in source and binary forms, with or without modification,
00047 are permitted provided that the following conditions are met:
00048
00049 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00050 and a copy of the modified files should be reported once modifications are
00051 completed. Documentation related to said modifications should be included.
00052
00053 2. Redistributions of source code must be done through direct
00054 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00056 3. Redistributions of source code must retain the above copyright notice, this
00057 list of conditions and the following disclaimer.
00058
00059 4. Redistributions in binary form must reproduce the above copyright notice,
00060 this list of conditions and the following disclaimer in the documentation and/or
00061 other materials provided with the distribution.
00063 5. Usage of the binary form on proprietary applications shall require explicit
00064 prior written permission from the the copyright holders.
00066 6. Neither the name of the copyright holder nor the names of its contributors
00067 may be used to endorse or promote products derived from this software without
00068 specific prior written permission.
00069
00070 The copyright holders provide no reassurances that the source code provided does
00071 not infringe any patent, copyright, or any other intellectual property rights of
00072 third parties. The copyright holders disclaim any liability to any recipient for
00073 claims brought against recipient by any third party for infringement of that
00074 parties intellectual property rights.
00075
00076 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00077 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00078 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00079 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00080 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00081 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00082 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00083 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00084 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00085 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00086 */
00087
00088 #if __cplusplus == 201103L
00089
00090 #include <iostream>
00091 #include <fstream>
00092 #include <cmath>
00093
00094 #include <vector>
00095
00096 #include "mtk.h"
00097
00098 mtk::Real Source(mtk::Real xx) {
00099
00100
       mtk::Real lambda = -1.0;
00101
        return lambda*lambda*exp(lambda*xx)/(exp(lambda) - 1.0);
00102
00103 }
00104
00105 mtk::Real KnownSolution(mtk::Real xx) {
00106
00107
        mtk::Real lambda = -1.0;
00108
00109
        return (exp(lambda*xx) - 1.0)/(exp(lambda) - 1.0);
00110 }
00111
00112 int main () {
00113
00114
        std::cout << "Example: Poisson Equation on a 1D Uniform Staggered Grid ";
        std::cout << "with Robin BCs." << std::endl;
00115
00116
00118
00119
       mtk::Real lambda = -1.0;
       mtk::Real alpha = -exp(lambda);
00120
       mtk::Real beta = (exp(lambda) - 1.0)/lambda;
00121
00122
        mtk::Real omega = -1.0;
       mtk::Real epsilon = 0.0;
00123
00124
00126
00127
       mtk::Real west bndv x = 0.0;
00128
       mtk::Real east_bndy_x = 1.0;
```

17.4 poisson\_1d.cc 175

```
00129
        int num_cells_x = 5;
00130
00131
        mtk::UniStgGrid1D comp_sol(west_bndy_x, east_bndy_x, num_cells_x);
00132
00134
        int order_of_accuracy{2}; // Desired order of accuracy for approximation.
00135
00136
00137
        mtk::Grad1D grad; // Mimetic gradient operator.
00138
00139
        mtk::Lap1D lap; // Mimetic Laplacian operator.
00140
00141
        if (!lap.ConstructLap1D(order_of_accuracy)) {
00142
          std::cerr << "Mimetic lap could not be built." << std::endl;</pre>
00143
          return EXIT_FAILURE;
00144
00145
00146
        mtk::DenseMatrix lapm(lap.ReturnAsDenseMatrix(comp_sol));
00147
00148
        std::cout << "Mimetic Laplacian operator: " << std::endl;</pre>
00149
        std::cout << lapm << std::endl;
00150
00151
        if (!grad.ConstructGrad1D(order_of_accuracy)) {
00152
          std::cerr << "Mimetic grad could not be built." << std::endl;</pre>
00153
          return EXIT_FAILURE;
00154
00155
00156
        mtk::DenseMatrix gradm(grad.ReturnAsDenseMatrix(comp sol));
00157
00158
        std::cout << "Mimetic gradient operator: " << std::endl;</pre>
00159
        std::cout << gradm << std::endl;
00160
00162
00163
        mtk::UniStgGrid1D source(west_bndy_x, east_bndy_x, num_cells_x);
00164
00165
        source.BindScalarField(Source);
00166
00167
        std::cout << source << std::endl;
00168
00170
00171
        // Since we need to approximate the first derivative times beta, we must use
00172
        // the approximation of the gradient at the boundary. We could extract them
00173
        // from the gradient operator as packed in the grad object. BUT, since we have
00174
        // generated at matrix containing this operator, we can extract these from the
00175
        // matrix.
00176
00177
        // Array containing the coefficients for the west boundary condition.
00178
        std::vector<mtk::Real> west_coeffs;
00179
00180
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00181
         west_coeffs.push_back(-beta*gradm.GetValue(0, ii));
00182
00183
00184
        // Array containing the coefficients for the east boundary condition.
00185
        std::vector<mtk::Real> east_coeffs;
00186
00187
        for (auto ii = 0; ii < grad.num_bndy_coeffs(); ++ii) {</pre>
00188
         east_coeffs.push_back(beta*gradm.GetValue(gradm.num_rows() - 1,
00189
                                                     gradm.num_cols() - 1 - ii));
00190
00191
00192
        // To impose the Dirichlet condition, we simple add its coefficient to the
00193
        // first entry of the west, and the last entry of the east array.
00194
00195
        west coeffs[0] += alpha;
00196
00197
        east_coeffs[0] += alpha;
00198
00199
        // Now that we have the coefficients that should be in the operator, we create
00200
        // a boundary condition descriptor object, which will encapsulate the
00201
        // complexity of assigning them in the matrix, to complete the construction of
00202
        // the mimetic operator.
00203
00204
        mtk::BCDesc1D::ImposeOnOperator(lapm, west_coeffs, east_coeffs);
00205
00206
        std::cout << "Mimetic Laplacian with Robin conditions:" << std::endl;</pre>
00207
        std::cout << lapm << std::endl;</pre>
00208
00209
        mtk::BCDesc1D::ImposeOnGrid(source, omega, epsilon);
00210
        std::cout << "Source term with imposed BCs:" << std::endl;</pre>
00211
00212
        std::cout << source << std::endl;
```

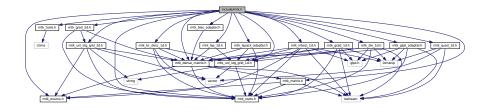
```
00213
00214
        source.WriteToFile("poisson_1d_source.dat", "x", "s(x)");
00215
00217
00218
        int info{mtk::LAPACKAdapter::SolveDenseSystem(lapm, source)};
00219
00220
00221
         std::cout << "System solved! Problem solved!" << std::endl;</pre>
00222
         std::cout << std::endl;
00223
00224
       else {
00225
         std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
00226
          std::cerr << "Exiting..." << std::endl;
00227
          return EXIT_FAILURE;
00228
00229
00230
        std::cout << "Computed solution:" << std::endl;</pre>
00231
        std::cout << source << std::endl;
00232
00233
        source.WriteToFile("poisson_ld_comp_sol.dat", "x", "~u(x)");
00234
00236
00237
        mtk::UniStgGrid1D known_sol(west_bndy_x, east_bndy_x, num_cells_x);
00238
00239
        known_sol.BindScalarField(KnownSolution);
00240
00241
        std::cout << "known_sol =" << std::endl;
00242
        std::cout << known_sol << std::endl;
00243
00244
        known_sol.WriteToFile("poisson_ld_known_sol.dat", "x", "u(x)");
00245
00246
       mtk::Real relative_norm_2_error{}; // Relative norm 2 of the error.
00247
00248
        relative_norm_2_error =
         mtk::BLASAdapter::RelNorm2Error(source.discrete_field_u(),
00249
00250
                                           known_sol.discrete_field_u(),
00251
                                           known_sol.num_cells_x());
00252
        std::cout << "relative_norm_2_error = ";</pre>
00253
00254
        std::cout << relative_norm_2_error << std::endl;</pre>
00255 }
00256
00257 #else
00258 #include <iostream>
00259 using std::cout;
00260 using std::endl;
00261 int main () {
00262 cout << "This code HAS to be compiled with support for C++11." << endl;
00263 cout << "Exiting..." << endl;
00264
       return EXIT_SUCCESS;
00265 }
00266 #endif
```

## 17.5 include/mtk.h File Reference

Includes the entire API.

17.6 mtk.h 177

```
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_tools.h"
#include "mtk_matrix.h"
#include "mtk_dense_matrix.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_uni_stg_grid_1d.h"
#include "mtk_uni_stg_grid_2d.h"
#include "mtk_grad_1d.h"
#include "mtk_div_1d.h"
#include "mtk_lap_1d.h"
#include "mtk_interp_1d.h"
#include "mtk_quad_1d.h"
#include "mtk_bc_desc_1d.h"
#include "mtk_grad_2d.h"
Include dependency graph for mtk.h:
```



### 17.5.1 Detailed Description

This file contains every required header file, thus containing the entire API. In this way, client codes only have to instruct #include "mtk.h".

#### Warning

IT IS EXTREMELY IMPORTANT THAT THE HEADERS ARE ADDED TO THIS FILE IN A SPECIFIC ORDER; THAT IS, CONSIDERING THE DEPENDENCE BETWEEN THE CLASSES THESE CONTAIN!

#### Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk.h.

### 17.6 mtk.h

```
00001 00015 /\star 00016 Copyright (C) 2015, Computational Science Research Center, San Diego State 00017 University. All rights reserved. 00018 00018 00019 Redistribution and use in source and binary forms, with or without modification, 00020 are permitted provided that the following conditions are met:
```

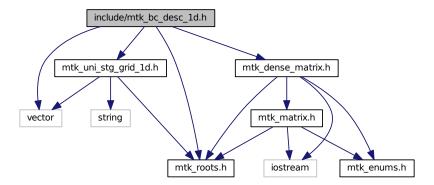
```
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed. Documentation related to said modifications should be included.
00026 2. Redistributions of source code must be done through direct
00027 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00029 3. Redistributions of source code must retain the above copyright notice, this
00030 list of conditions and the following disclaimer.
00032 4. Redistributions in binary form must reproduce the above copyright notice,
00033 this list of conditions and the following disclaimer in the documentation and/or
00034 other materials provided with the distribution.
00036 5. Usage of the binary form on proprietary applications shall require explicit
00037 prior written permission from the the copyright holders.
00039 6. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE 00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00362 #ifndef MTK_INCLUDE_MTK_H_
00363 #define MTK_INCLUDE_MTK_H_
00364
00372 #include "mtk_roots.h"
00373
00381 #include "mtk_enums.h"
00382
00390 #include "mtk_tools.h"
00391
00399 #include "mtk_matrix.h"
00400 #include "mtk_dense_matrix.h"
00401
00409 #include "mtk_blas_adapter.h"
00410 #include "mtk_lapack_adapter.h"
00411 #include "mtk_glpk_adapter.h"
00412
00420 #include "mtk_uni_stg_grid_ld.h"
00421 #include "mtk_uni_stq_grid_2d.h"
00430 #include "mtk_grad_1d.h"
00431 #include "mtk_div_1d.h"
00432 #include "mtk_lap_1d.h"
00433 #include "mtk_interp_1d.h"
00434 #include "mtk_quad_1d.h"
00435 #include "mtk_bc_desc_1d.h"
00437 #include "mtk_grad_2d.h"
00439 #endif // End of: MTK_INCLUDE_MTK_H_
```

# 17.7 include/mtk\_bc\_desc\_1d.h File Reference

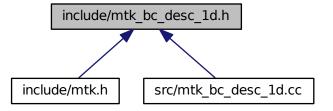
```
#include <vector>
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_1d.h"
```

17.8 mtk\_bc\_desc\_1d.h 179

Include dependency graph for mtk\_bc\_desc\_1d.h:



This graph shows which files directly or indirectly include this file:



#### Classes

• class mtk::BCDesc1D

### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

# 17.8 mtk\_bc\_desc\_1d.h

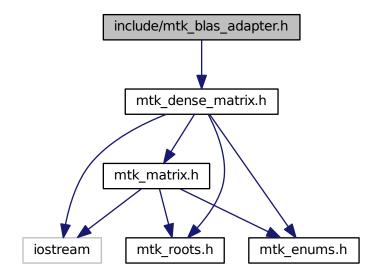
```
00001 #include <vector>
00002
00003 #include "mtk_roots.h"
00004 #include "mtk_dense_matrix.h"
00005 #include "mtk_uni_stg_grid_ld.h"
```

```
00006
00007 namespace mtk {
80000
00009 class BCDesc1D {
00010 public:
00011
       static void ImposeOnOperator(DenseMatrix &matrix,
00012
                                     const std::vector<Real> &west,
00013
                                     const std::vector<Real> &east);
00014
00015 static void ImposeOnGrid(UniStgGrid1D &grid,
00016
                                 const Real &omega,
00017
                                 const Real &epsilon);
00018 };
00019 }
```

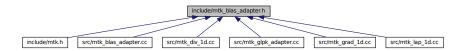
# 17.9 include/mtk\_blas\_adapter.h File Reference

Adapter class for the BLAS API.

```
#include "mtk_dense_matrix.h"
Include dependency graph for mtk_blas_adapter.h:
```



This graph shows which files directly or indirectly include this file:



#### Classes

class mtk::BLASAdapter

Adapter class for the BLAS API.

#### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

### 17.9.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the BLAS.

The **BLAS** (**Basic Linear Algebra Subprograms**) are routines that provide standard building blocks for performing basic vector and matrix operations. The Level 1 BLAS perform scalar, vector and vector-vector operations, the Level 2 BLAS perform matrix-vector operations, and the Level 3 BLAS perform matrix operations.

The BLAS can be installed from links given in the See Also section of this page.

#### See Also

```
http://www.netlib.org/blas/
https://software.intel.com/en-us/non-commercial-software-development
```

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_blas\_adapter.h.

# 17.10 mtk\_blas\_adapter.h

```
00001
00025 Copyright (C) 2015, Computational Science Research Center, San Diego State
00026 University. All rights reserved.
00028 Redistribution and use in source and binary forms, with or without modification,
00029 are permitted provided that the following conditions are met:
00031 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00032 and a copy of the modified files should be reported once modifications are
00033 completed. Documentation related to said modifications should be included.
00035 2. Redistributions of source code must be done through direct
00036 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00038 3. Redistributions of source code must retain the above copyright notice, this
00039 list of conditions and the following disclaimer.
00040
00041 4. Redistributions in binary form must reproduce the above copyright notice,
00042 this list of conditions and the following disclaimer in the documentation and/or
00043 other materials provided with the distribution.
00044
00045 5. Usage of the binary form on proprietary applications shall require explicit
00046 \ \mathrm{prior} \ \mathrm{written} \ \mathrm{permission} \ \mathrm{from} \ \mathrm{the} \ \mathrm{copyright} \ \mathrm{holders}.
00047
00048 6. Neither the name of the copyright holder nor the names of its contributors
```

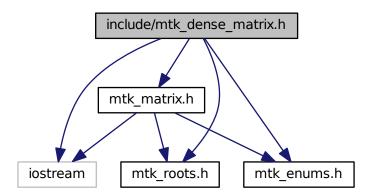
```
00049 may be used to endorse or promote products derived from this software without
00050 specific prior written permission.
00052 The copyright holders provide no reassurances that the source code provided does
00053 not infringe any patent, copyright, or any other intellectual property rights of
00054 third parties. The copyright holders disclaim any liability to any recipient for
00055 claims brought against recipient by any third party for infringement of that
00056 parties intellectual property rights.
00058 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00059 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00060 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00061 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00062 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00063 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00064 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00065 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00066 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00067 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00068 */
00069
00070 #ifndef MTK_INCLUDE_BLAS_ADAPTER_H_
00071 #define MTK_INCLUDE_BLAS_ADAPTER_H_
00072
00073 #include "mtk_dense_matrix.h"
00074
00075 namespace mtk {
00076
00096 class BLASAdapter {
00097 public:
00106
       static Real RealNRM2 (Real *in, int &in length);
00107
       static void RealAXPY(Real alpha, Real *xx, Real *yy, int &in_length);
00124
00125
       static Real RelNorm2Error(Real *computed, Real *known, int length);
00140
00141
00159
       static void RealDenseMV(Real &alpha,
00160
                                DenseMatrix &aa,
00161
                                Real *xx,
00162
                                Real &beta.
00163
                                Real *yy);
00164
00179
       static DenseMatrix RealDenseMM(DenseMatrix &aa,
     DenseMatrix &bb);
00180 };
00181
00182 #endif // End of: MTK_INCLUDE_BLAS_ADAPTER_H_
```

## 17.11 include/mtk\_dense\_matrix.h File Reference

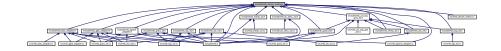
Defines a common dense matrix, using a 1D array.

```
#include <iostream>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_matrix.h"
```

Include dependency graph for mtk\_dense\_matrix.h:



This graph shows which files directly or indirectly include this file:



#### Classes

· class mtk::DenseMatrix

Defines a common dense matrix, using a 1D array.

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

## 17.11.1 Detailed Description

For developing purposes, it is better to have a not-so-intrincated data structure implementing matrices. This is the purpose of this class: to be used for prototypes of new code for small test cases. In every other instance, this should be replaced by the most appropriate sparse matrix.

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Note

We prefer composition to inheritance [Reedy, 2011]. The main reason for this preference is that inheritance produces a more tightly coupled design. When a class inherits from another type be it public, protected, or private inheritance the subclass gains access to all public and protected members of the base class, whereas with composition, the class is only coupled to the public members of the other class. Furthermore, if you only hold a pointer to the other object, then your interface can use a forward declaration of the class rather than #include its full definition. This results in greater compile-time insulation and improves the time it takes to compile your code.

Definition in file mtk dense matrix.h.

# 17.12 mtk\_dense\_matrix.h

```
00001
00023 /*
00024 Copyright (C) 2015, Computational Science Research Center, San Diego State
00025 University. All rights reserved.
00026
00027 Redistribution and use in source and binary forms, with or without modification,
00028 are permitted provided that the following conditions are met:
00029
00030 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00031 and a copy of the modified files should be reported once modifications are
00032 completed. Documentation related to said modifications should be included.
00033
00034 2. Redistributions of source code must be done through direct
00035 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00036
00037 3. Redistributions of source code must retain the above copyright notice, this
00038 list of conditions and the following disclaimer.
00039
00040 4. Redistributions in binary form must reproduce the above copyright notice,
00041 this list of conditions and the following disclaimer in the documentation and/or
00042 other materials provided with the distribution.
00043
00044 5. Usage of the binary form on proprietary applications shall require explicit
00045 prior written permission from the the copyright holders.
00046
00047 6. Neither the name of the copyright holder nor the names of its contributors
00048 may be used to endorse or promote products derived from this software without
00049 specific prior written permission.
00050
00051 The copyright holders provide no reassurances that the source code provided does
00052 not infringe any patent, copyright, or any other intellectual property rights of
00053 third parties. The copyright holders disclaim any liability to any recipient for
00054 claims brought against recipient by any third party for infringement of that
00055 parties intellectual property rights.
00057 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00058 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00059 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00060 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00061 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00062 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00063 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00064 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00065 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00066 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00067 */
00068
00069 #ifndef MTK_INCLUDE_DENSE_MATRIX_H_
00070 #define MTK_INCLUDE_DENSE_MATRIX_H_
00071
00072 #include <iostream>
00073
00074 #include "mtk_roots.h"
00075 #include "mtk enums.h"
00076 #include "mtk matrix.h"
00077
00078 namespace mtk {
00079
00092 class DenseMatrix {
00093 public:
```

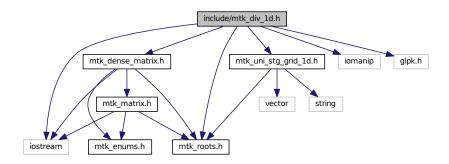
```
00095
        friend std::ostream& operator <<(std::ostream &stream, DenseMatrix &in);
00096
00098
        DenseMatrix& operator =(const DenseMatrix &in);
00099
00101
        DenseMatrix();
00102
00108
        DenseMatrix(const DenseMatrix &in);
00109
00118
        DenseMatrix(const int &num_rows, const int &num_cols);
00119
00145
        DenseMatrix(const int &rank, const bool &padded, const bool &transpose);
00146
00180
       DenseMatrix(const Real *gen,
00181
                    const int &gen_length,
00182
                    const int &pro_length,
00183
                    const bool &transpose);
00184
00186
       ~DenseMatrix();
00187
00193
       Matrix matrix_properties() const;
00194
00200
        int num rows() const;
00201
00207
       int num_cols() const;
00208
00214
        Real* data() const;
00215
00223
       void SetOrdering(mtk::MatrixOrdering oo);
00224
00233
        Real GetValue(const int &row_coord, const int &col_coord) const;
00234
00242
        void SetValue(const int &row_coord,
00243
                      const int &col_coord,
00244
                      const Real &val);
00245
00247
       void Transpose();
00248
00250
        void OrderRowMajor();
00251
00253
       void OrderColMajor();
00254
00265
       static DenseMatrix Kron(const DenseMatrix &aa, const
     DenseMatrix &bb);
00266
00267 private:
00268
        Matrix matrix_properties_;
00269
00270
       Real *data_;
00271 };
00272
00273 #endif // End of: MTK_INCLUDE_MTK_DENSE_MATRIX_H_
```

# 17.13 include/mtk div 1d.h File Reference

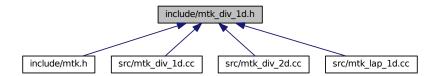
#### Includes the definition of the class Div1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
```

Include dependency graph for mtk\_div\_1d.h:



This graph shows which files directly or indirectly include this file:



### Classes

• class mtk::Div1D

Implements a 1D mimetic divergence operator.

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

# 17.13.1 Detailed Description

This class implements a 1D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_div\_1d.h.

17.14 mtk div 1d.h 187

# 17.14 mtk div 1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice, 00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_DIV_1D_H_
00058 #define MTK_INCLUDE_DIV_1D_H_
00059
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "glpk.h"
00064
00065 #include "mtk roots.h"
00066 #include "mtk_dense_matrix.h"
00067 #include "mtk_uni_stg_grid_1d.h"
00068
00069 namespace mtk {
00070
00081 class Div1D {
00082 public:
        friend std::ostream& operator <<(std::ostream& stream, Div1D &in);</pre>
00085
00087
        Div1D();
00088
00094
        Div1D(const Div1D &div);
00095
00097
        ~Div1D();
00098
00104
        bool ConstructDivlD(int order accuracy = kDefaultOrderAccuracy,
00105
                             Real mimetic threshold = kDefaultMimeticThreshold);
00106
00112
        int num bndy coeffs() const;
00113
00119
        Real *coeffs interior() const:
00120
```

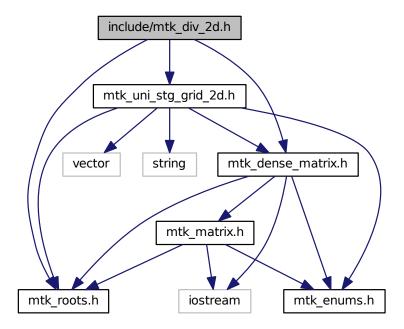
```
00126
        Real *weights_crs(void) const;
00127
00133
        Real *weights_cbs(void) const;
00134
00140
        DenseMatrix mim_bndy() const;
00141
00147
        DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid);
00148
00149 private:
00155
        bool ComputeStencilInteriorGrid(void);
00156
00163
        bool ComputeRationalBasisNullSpace(void);
00164
00170
       bool ComputePreliminaryApproximations(void);
00171
00177
        bool ComputeWeights (void);
00178
00184
       bool ComputeStencilBoundaryGrid(void);
00185
00191
       bool AssembleOperator(void);
00192
00193
        int order_accuracy_;
       int dim_null_;
00194
00195
        int num_bndy_coeffs_;
00196
        int divergence_length_;
00197
        int minrow_;
00198
        int row_;
00199
00200
        DenseMatrix rat_basis_null_space_;
00201
00202
        Real *coeffs_interior_;
00203
        Real *prem_apps_;
00204
        Real *weights_crs_;
00205
        Real *weights_cbs_;
00206
       Real *mim_bndy_;
00207
       Real *divergence_;
00208
00209 F
00210 };
       Real mimetic_threshold_;
00211 }
00212 #endif // End of: MTK_INCLUDE_DIV_1D_H_
```

# 17.15 include/mtk\_div\_2d.h File Reference

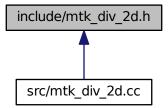
#### Includes the definition of the class Div2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk\_div\_2d.h:



This graph shows which files directly or indirectly include this file:



# Classes

class mtk::Div2D

# **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### 17.15.1 Detailed Description

This class implements a 2D divergence operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_div\_2d.h.

### 17.16 mtk div 2d.h

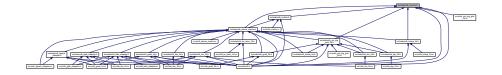
```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00021
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_MTK_DIV_2D_H_
00058 #define MTK_INCLUDE_MTK_DIV_2D_H_
00059
00060 #include "mtk roots.h"
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
```

```
00065
00066 class Div2D {
00067 public:
00069
       Div2D();
00070
00076
       Div2D (const Div2D &div);
00077
00079
        ~Div2D();
00080
00086
       DenseMatrix ConstructDiv2D(const UniStgGrid2D &grid,
00087
                                   int order_accuracy = kDefaultOrderAccuracy,
                                   Real mimetic_threshold =
00088
      kDefaultMimeticThreshold);
00089
00095
       DenseMatrix ReturnAsDenseMatrix();
00096
00097 private:
00098
       DenseMatrix divergence_;
00099
        int order_accuracy_;
00100
       Real mimetic_threshold_;
00101 };
00102 }
00103 #endif // End of: MTK_INCLUDE_MTK_DIV_2D_H_
```

# 17.17 include/mtk\_enums.h File Reference

Considered enumeration types in the MTK.

This graph shows which files directly or indirectly include this file:



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### **Enumerations**

- enum mtk::MatrixStorage { mtk::DENSE, mtk::BANDED, mtk::CRS }
  - Considered matrix storage schemes to implement sparse matrices.
- enum mtk::MatrixOrdering { mtk::ROW\_MAJOR, mtk::COL\_MAJOR }
  - Considered matrix ordering (for Fortran purposes).
- enum mtk::FieldNature { mtk::SCALAR, mtk::VECTOR }
  - Nature of the field discretized in a given grid.
- enum mtk::DirInterp { mtk::SCALAR\_TO\_VECTOR, mtk::VECTOR\_TO\_SCALAR }

1D interpolation operator.

#### 17.17.1 Detailed Description

Enumeration types are used throughout the MTK to differentiate instances of derived classes, as well as for mnemonic purposes. In this file, the enumeration types are listed alphabetically.

#### Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk enums.h.

### 17.18 mtk enums.h

```
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 \ \mathrm{prior} \ \mathrm{written} \ \mathrm{permission} \ \mathrm{from} \ \mathrm{the} \ \mathrm{copyright} \ \mathrm{holders}.
00035
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_ENUMS_H_
00059 #define MTK_INCLUDE_ENUMS_H_
00060
00061 namespace mtk {
00062
00077 enum MatrixStorage {
00078
       DENSE,
00079
        BANDED,
00080
       CRS
00081 };
00082
00095 enum MatrixOrdering {
00096 ROW_MAJOR,
00097
       COL MAJOR
00098 };
00099
00113 enum FieldNature {
00114 SCALAR,
00115
       VECTOR
00116 };
00117
```

# 17.19 include/mtk\_glpk\_adapter.h File Reference

Adapter class for the GLPK API.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
Include dependency graph for mtk_glpk_adapter.h:
```

include/mtk\_glpk\_adapter.h

mtk\_dense\_matrix.h

iomanip

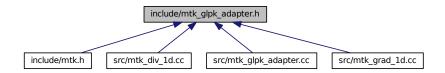
glpk.h

mtk\_roots.h

This graph shows which files directly or indirectly include this file:

mtk\_enums.h

iostream



#### Classes

class mtk::GLPKAdapter

Adapter class for the GLPK API.

### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### 17.19.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

#### See Also

```
http://www.gnu.org/software/glpk/
```

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk glpk adapter.h.

# 17.20 mtk\_glpk\_adapter.h

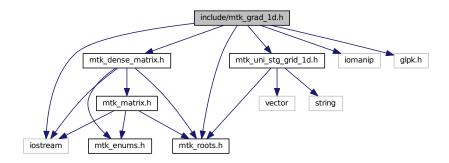
```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00022
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00025
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed. Documentation related to said modifications should be included.
00030 2. Redistributions of source code must be done through direct
00031 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00033 3. Redistributions of source code must retain the above copyright notice, this
00034 list of conditions and the following disclaimer.
00036 4. Redistributions in binary form must reproduce the above copyright notice,
00037 this list of conditions and the following disclaimer in the documentation and/or
00038 other materials provided with the distribution.
00040 5. Usage of the binary form on proprietary applications shall require explicit
00041 prior written permission from the the copyright holders.
00043 6. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00052
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED 00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
```

```
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00064
00065 #ifndef MTK_INCLUDE_GLPK_ADAPTER_H_
00066 #define MTK_INCLUDE_GLPK_ADAPTER_H_
00068 #include <iostream>
00069 #include <iomanip>
00070
00071 #include "glpk.h"
00072
00073 #include "mtk_roots.h"
00074 #include "mtk_dense_matrix.h"
00075
00076 namespace mtk {
00077
00101 class GLPKAdapter {
00102 public:
00123
       static mtk::Real SolveSimplexAndCompare(
     mtk::Real *A,
00124
                                                int nrows,
00125
                                                int ncols.
00126
                                                int kk,
00127
                                                mtk::Real *hh,
00128
                                                mtk::Real *qq,
00129
                                                int robjective,
00130
                                                mtk::Real mimetic_tol,
00131
                                                int copy);
00132 };
00133
00134 #endif // End of: MTK_INCLUDE_MTK_GLPK_ADAPTER_H_
```

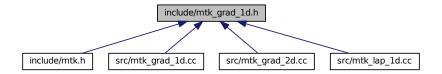
# 17.21 include/mtk\_grad\_1d.h File Reference

Includes the definition of the class Grad1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_grad_1d.h:
```



This graph shows which files directly or indirectly include this file:



#### Classes

· class mtk::Grad1D

Implements a 1D mimetic gradient operator.

### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### 17.21.1 Detailed Description

This class implements a 1D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CB-SA).

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_grad\_1d.h.

# 17.22 mtk\_grad\_1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice, 00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
```

17.22 mtk grad\_1d.h 197

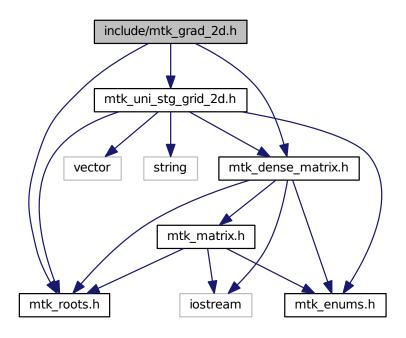
```
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_GRAD_1D_H_
00058 #define MTK_INCLUDE_GRAD_1D_H_
00059
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "glpk.h"
00064
00065 #include "mtk_roots.h"
00066 #include "mtk_dense_matrix.h"
00067 #include "mtk_uni_stg_grid_1d.h"
00068
00069 namespace mtk {
00070
00081 class Grad1D {
      public:
00082
00084
        friend std::ostream& operator <<(std::ostream& stream, Grad1D &in);</pre>
00085
00087
        Grad1D();
00088
00094
       Grad1D(const Grad1D &grad);
00095
        ~Grad1D();
00097
00098
00104
        bool ConstructGrad1D(int order_accuracy = kDefaultOrderAccuracy,
00105
                             Real mimetic_threshold = kDefaultMimeticThreshold);
00106
00112
        int num_bndy_coeffs() const;
00113
00119
        Real *coeffs_interior() const;
00120
00126
        Real *weights_crs(void) const;
00127
00133
        Real *weights_cbs(void) const;
00134
00140
        DenseMatrix mim_bndy() const;
00141
00147
        DenseMatrix ReturnAsDenseMatrix(Real west,
      Real east, int num_cells_x);
00148
00154
        DenseMatrix ReturnAsDenseMatrix(const
      UniStgGrid1D &grid);
00155
00156
      private:
00162
       bool ComputeStencilInteriorGrid(void);
00163
00170
       bool ComputeRationalBasisNullSpace(void);
00171
00177
        bool ComputePreliminaryApproximations(void);
00178
00184
        bool ComputeWeights(void);
00185
00191
        bool ComputeStencilBoundaryGrid(void);
00192
       bool AssembleOperator(void);
00198
```

```
00199
00200
       int order_accuracy_;
00201
        int dim_null_;
       int num_bndy_approxs_;
00202
00203
       int num_bndy_coeffs_;
00204
      int gradient_length_;
00205
       int minrow_;
00206
       int row_;
00207
       DenseMatrix rat_basis_null_space_;
00209
00210
       Real *coeffs_interior_;
00211
       Real *prem_apps_;
       Real *weights_crs_;
00213
       Real *weights_cbs_;
00214
       Real *mim_bndy_;
00215
       Real *gradient_;
00216
00217
       Real mimetic_threshold_;
00218 };
00219 }
00220 #endif // End of: MTK_INCLUDE_GRAD_1D_H_
```

## 17.23 include/mtk\_grad\_2d.h File Reference

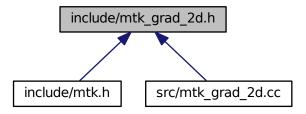
Includes the definition of the class Grad2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
Include dependency graph for mtk_grad_2d.h:
```



17.24 mtk grad 2d.h 199

This graph shows which files directly or indirectly include this file:



#### **Classes**

class mtk::Grad2D

### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### 17.23.1 Detailed Description

This class implements a 2D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CB-SA).

#### Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_grad\_2d.h.

## 17.24 mtk\_grad\_2d.h

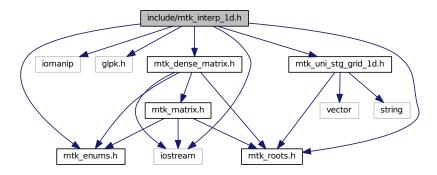
```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00021
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
```

```
00026 list of conditions and the following disclaimer.
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED 00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; 00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK INCLUDE MTK GRAD 2D H
00058 #define MTK_INCLUDE_MTK_GRAD_2D_H_
00059
00060 #include "mtk roots.h"
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
00065
00066 class Grad2D {
00067 public:
00069
        Grad2D();
00070
00076
        Grad2D(const Grad2D &grad);
00077
00079
        ~Grad2D();
00080
00086
        DenseMatrix ConstructGrad2D(const UniStgGrid2D &grid,
00087
                                      int order_accuracy = kDefaultOrderAccuracy,
00088
                                     Real mimetic_threshold =
      kDefaultMimeticThreshold);
00089
00095
        DenseMatrix ReturnAsDenseMatrix();
00096
00097 private:
00098
       DenseMatrix gradient_;
00099
        int order_accuracy_;
00100
       Real mimetic_threshold_;
00101 };
00103 #endif // End of: MTK_INCLUDE_MTK_GRAD_2D_H_
```

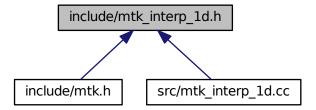
### 17.25 include/mtk\_interp\_1d.h File Reference

Includes the definition of the class Interp1D.

```
#include <iostream>
#include <iomanip>
#include "glpk.h"
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_interp_1d.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

· class mtk::Interp1D

Implements a 1D interpolation operator.

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### 17.25.1 Detailed Description

This class implements a 1D interpolation operator.

#### **Author**

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Johnny Corbino jcorbino at mail dot sdsu dot edu

Definition in file mtk interp 1d.h.

### 17.26 mtk\_interp\_1d.h

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00015
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are \text{met}:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00032
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders.
00035
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_INTERP_1D_H_
00059 #define MTK_INCLUDE_INTERP_1D_H_
00061 #include <iostream>
00062 #include <iomanip>
00063
00064 #include "glpk.h"
00065
00066 #include "mtk roots.h"
00067 #include "mtk_enums.h"
00068 #include "mtk_dense_matrix.h"
00069 #include "mtk_uni_stg_grid_1d.h"
00070
```

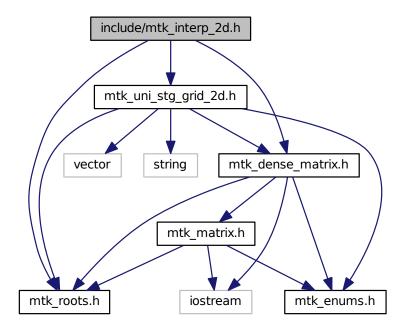
```
00071 namespace mtk {
00072
00082 class Interp1D {
00083 public:
00085
       friend std::ostream& operator <<(std::ostream& stream, InterplD &in);
88000
       Interp1D();
00089
00095
       InterplD(const InterplD &interp);
00096
00098
       ~Interp1D();
00099
00105
       bool ConstructInterplD(int order_accuracy =
     kDefaultOrderAccuracy,
00106
                              mtk::DirInterp dir = SCALAR_TO_VECTOR);
00107
00113
       Real *coeffs_interior() const;
00114
00120
       DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid);
00121
00122 private:
       DirInterp dir_interp_;
00123
00124
00125
       int order_accuracy_;
00126
       Real *coeffs_interior_;
00127
00128 };
00129 }
00130 #endif // End of: MTK_INCLUDE_INTERP_1D_H_
```

# 17.27 include/mtk\_interp\_2d.h File Reference

### Includes the definition of the class Interp2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk\_interp\_2d.h:



### **Classes**

· class mtk::Interp2D

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### 17.27.1 Detailed Description

This class implements a 2D interpolation operator.

### **Author**

- : Eduardo J. Sanchez (ejspeiro) esanchez at mail dot sdsu dot edu
- : Johnny Corbino jcorbino at mail dot sdsu dot edu

Definition in file mtk\_interp\_2d.h.

17.28 mtk interp 2d.h 205

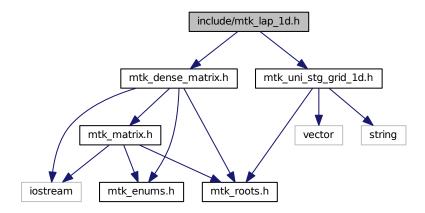
## 17.28 mtk\_interp\_2d.h

```
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00032
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders.
00035
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00057
00058 #ifndef MTK_INCLUDE_MTK_INTERP_2D_H_
00059 #define MTK_INCLUDE_MTK_INTERP_2D_H_
00061 #include "mtk_roots.h"
00062 #include "mtk_dense_matrix.h"
00063 #include "mtk_uni_stg_grid_2d.h"
00064
00065 namespace mtk{
00066
00067 class Interp2D {
00068 public:
       Interp2D();
00069
00070
        Interp2D (const Interp2D &interp);
00071
       ~Interp2D();
00072
       DenseMatrix ConstructInterp2D(const UniStgGrid2D &grid,
                                      int order_accuracy = kDefaultOrderAccuracy,
00073
00074
                                   Real mimetic_threshold =
     kDefaultMimeticThreshold);
00075
       DenseMatrix ReturnAsDenseMatrix();
00076
00077 private:
00078
       DenseMatrix interpolator_;
00079
       int order_accuracy_;
00080
       Real mimetic_threshold_;
00081 };
00082 }
00083 #endif // End of: MTK_INCLUDE_MTK_INTERP_2D_H_
```

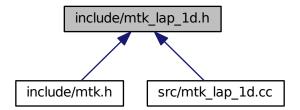
# 17.29 include/mtk\_lap\_1d.h File Reference

Includes the definition of the class Lap1D.

```
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
Include dependency graph for mtk_lap_1d.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

· class mtk::Lap1D

Implements a 1D mimetic Laplacian operator.

### Namespaces

mtk

17.30 mtk lap 1d.h 207

Mimetic Methods Toolkit namespace.

#### 17.29.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_lap\_1d.h.

## 17.30 mtk\_lap\_1d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00021
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_LAP_1D_H_
00058 #define MTK_INCLUDE_LAP_1D_H_
00059
00060 #include "mtk dense matrix.h"
00061
00062 #include "mtk_uni_stg_grid_1d.h"
00063
00064 namespace mtk {
```

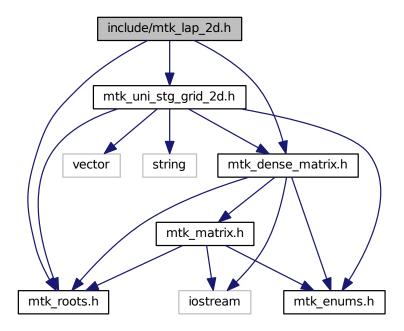
```
00065
00076 class Lap1D {
00077 public:
       friend std::ostream& operator <<(std::ostream& stream, Lap1D &in);
00079
08000
00082
00083
00089
       Lap1D (const Lap1D &lap);
00090
00092
       ~Lap1D();
00093
00099
       bool ConstructLap1D(int order_accuracy = kDefaultOrderAccuracy,
00100
                           Real mimetic_threshold = kDefaultMimeticThreshold);
00101
00107
       DenseMatrix ReturnAsDenseMatrix(const
     UniStgGrid1D &grid);
00108
00114
       mtk::Real* Data(const UniStgGrid1D &grid);
00115
00116 private:
00117
        int order_accuracy_;
00118
       int laplacian_length_;
00119
00120
       Real *laplacian_;
00121
00122
       Real mimetic_threshold_;
00123 };
00124 }
00125 #endif // End of: MTK_INCLUDE_LAP_1D_H_
```

# 17.31 include/mtk\_lap\_2d.h File Reference

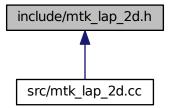
Includes the implementation of the class Lap2D.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk\_lap\_2d.h:



This graph shows which files directly or indirectly include this file:



### Classes

· class mtk::Lap2D

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### 17.31.1 Detailed Description

This class implements a 2D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_lap\_2d.h.

## 17.32 mtk\_lap\_2d.h

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00021
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #ifndef MTK_INCLUDE_MTK_LAP_2D_H_
00058 #define MTK_INCLUDE_MTK_LAP_2D_H_
00059
00060 #include "mtk roots.h"
00061 #include "mtk_dense_matrix.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk{
```

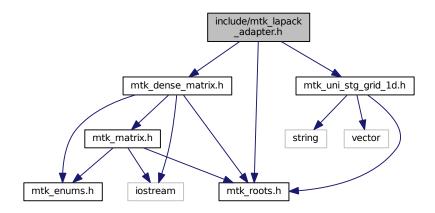
```
00065
00066 class Lap2D {
00067 public:
00068
       Lap2D();
00069
       Lap2D (const Lap2D &lap);
00070
00071
       DenseMatrix ConstructLap2D(const UniStgGrid2D &grid,
00072
                                   int order_accuracy = kDefaultOrderAccuracy,
00073
                                  Real mimetic_threshold =
     kDefaultMimeticThreshold);
00074
       DenseMatrix ReturnAsDenseMatrix();
00075
00076 private:
       DenseMatrix laplacian_;
00078
       int order_accuracy_;
      Real mimetic_threshold_;
00080 };
00081 }
00082 #endif // End of: MTK_INCLUDE_MTK_LAP_2D_H_
```

## 17.33 include/mtk\_lapack\_adapter.h File Reference

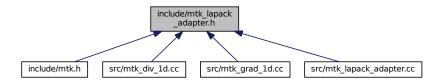
Adapter class for the LAPACK API.

```
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_uni_stg_grid_ld.h"
#include "mtk_uni_stg_grid_ld.h"
```

Include dependency graph for mtk lapack adapter.h:



This graph shows which files directly or indirectly include this file:



#### Classes

class mtk::LAPACKAdapter

Adapter class for the LAPACK API.

#### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### 17.33.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

#### See Also

```
http://www.netlib.org/lapack/
```

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_lapack\_adapter.h.

### 17.34 mtk\_lapack\_adapter.h

```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed. Documentation related to said modifications should be included.
00030 2. Redistributions of source code must be done through direct
00031 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00033 3. Redistributions of source code must retain the above copyright notice, this
00034 list of conditions and the following disclaimer.
00036 4. Redistributions in binary form must reproduce the above copyright notice,
00037 this list of conditions and the following disclaimer in the documentation and/or
00038 other materials provided with the distribution.
00039
00040 5. Usage of the binary form on proprietary applications shall require explicit
00041 prior written permission from the the copyright holders.
00042
00043 6. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00046
00047 The copyright holders provide no reassurances that the source code provided does
```

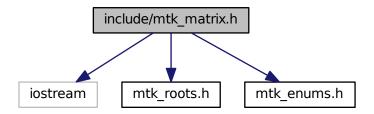
```
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00064
00065 #ifndef MTK_INCLUDE_LAPACK_ADAPTER_H_
00066 #define MTK_INCLUDE_LAPACK_ADAPTER_H_
00067
00068 #include "mtk_roots.h"
00069 #include "mtk_dense_matrix.h"
00070 #include "mtk_uni_stg_grid_1d.h"
00071
00072 namespace mtk {
00073
00092 class LAPACKAdapter {
00093 public:
00104
       static int SolveDenseSystem(mtk::DenseMatrix &mm,
00105
                                    mtk::Real *rhs);
00106
00117
       static int SolveDenseSystem(mtk::DenseMatrix &mm,
00118
                                   mtk::DenseMatrix &rr);
00119
       static int SolveDenseSystem(mtk::DenseMatrix &mm,
00130
00131
                                    mtk::UniStgGrid1D &rhs);
00132
00144
       static int SolveRectangularDenseSystem(const
     mtk::DenseMatrix &aa,
00145
                                               mtk::Real *ob_,
00146
                                               int ob_ld_);
00147
00159
       static mtk::DenseMatrix QRFactorDenseMatrix(
     DenseMatrix &matrix);
00160 };
00161
00162 #endif // End of: MTK_INCLUDE_LAPACK_ADAPTER_H_
```

### 17.35 include/mtk matrix.h File Reference

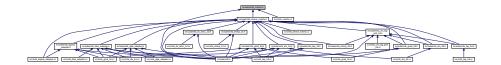
Definition of the representation of a matrix in the MTK.

```
#include <iostream>
#include "mtk_roots.h"
#include "mtk enums.h"
```

Include dependency graph for mtk\_matrix.h:



This graph shows which files directly or indirectly include this file:



### **Classes**

class mtk::Matrix

Definition of the representation of a matrix in the MTK.

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### 17.35.1 Detailed Description

Definition of the representation for the matrices implemented in the MTK.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_matrix.h.

# 17.36 mtk\_matrix.h

00001 00010 /\* 17.36 mtk matrix.h 215

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00033
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #ifndef MTK_INCLUDE_MATRIX_H_
00057 #define MTK_INCLUDE_MATRIX_H_
00058
00059 #include <iostream>
00060
00061 #include "mtk_roots.h"
00062 #include "mtk_enums.h"
00063
00064 namespace mtk {
00065
00075 class Matrix {
00076 public:
00078
       Matrix();
00079
00085
       Matrix(const Matrix &in);
00086
00088
        ~Matrix();
00089
00095
       MatrixStorage storage() const;
00096
00102
       MatrixOrdering ordering() const;
00103
00109
       int num_rows() const;
00110
00116
        int num_cols() const;
00117
00123
       int num values() const;
00124
00134
       int 1d() const;
00135
00141
        int num zero() const;
00142
00148
        int num non zero() const;
00149
00157
        int num null() const;
00158
```

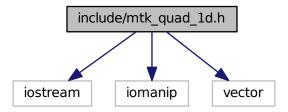
```
00166
        int num_non_null() const;
00167
00173
        int kl() const;
00174
00180
        int ku() const;
00181
00187
        int bandwidth() const;
00188
00196
        Real abs_density() const;
00197
00205
        Real rel_density() const;
00206
00214
        Real abs_sparsity() const;
00215
00223
       Real rel_sparsity() const;
00224
00232
        void set_storage(const MatrixStorage &tt);
00233
00241
        void set_ordering(const MatrixOrdering &oo);
00242
00248
       void set_num_rows(int num_rows);
00249
00255
       void set_num_cols(int num_cols);
00256
00262
       void set_num_zero(int in);
00263
00269
       void set_num_null(int in);
00270
00272
       void IncreaseNumZero();
00273
00275
       void IncreaseNumNull();
00276
00277 private:
00278
        MatrixStorage storage_;
00279
00280
       MatrixOrdering ordering_;
00281
00282
        int num_rows_;
00283
        int num_cols_;
00284
        int num_values_;
00285
       int ld_;
00286
00287
        int num_zero_;
00288
        int num_non_zero_;
00289
        int num_null_;
00290
        int num_non_null_;
00291
00292
        int kl_;
00293
       int ku_;
00294
        int bandwidth_;
00295
00296
        Real abs_density_;
00297
       Real rel_density_;
00298
        Real abs_sparsity_;
00299
       Real rel_sparsity_;
00300 };
00302 #endif // End of: MTK_INCLUDE_MATRIX_H_
```

# 17.37 include/mtk\_quad\_1d.h File Reference

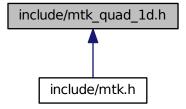
Includes the definition of the class Quad1D.

```
#include <iostream>
#include <iomanip>
#include <vector>
```

Include dependency graph for mtk\_quad\_1d.h:



This graph shows which files directly or indirectly include this file:



#### Classes

· class mtk::Quad1D

Implements a 1D mimetic quadrature.

### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### 17.37.1 Detailed Description

This class implements a 1D quadrature solver based on the mimetic discretization of the gradient operator.

See Also

mtk::Grad1D

#### Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Implement this class.

Definition in file mtk\_quad\_1d.h.

### 17.38 mtk quad 1d.h

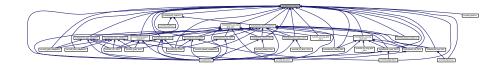
```
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00021
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed. Documentation related to said modifications should be included.
00025
00026 2. Redistributions of source code must be done through direct
00027 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00028
00029 3. Redistributions of source code must retain the above copyright notice, this
00030 list of conditions and the following disclaimer.
00031
00032 4. Redistributions in binary form must reproduce the above copyright notice,
00033 this list of conditions and the following disclaimer in the documentation and/or
00034 other materials provided with the distribution.
00035
00036 5. Usage of the binary form on proprietary applications shall require explicit
00037 prior written permission from the the copyright holders.
00038
00039 6. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00060
00061 #ifndef MTK_INCLUDE_QUAD_1D_H_
00062 #define MTK_INCLUDE_QUAD_1D_H_
00064 #include <iostream>
00065 #include <iomanip>
00066
00067 #include <vector>
00068
00069 namespace mtk {
00070
00081 class Quad1D {
00082
      public:
00084
        friend std::ostream& operator <<(std::ostream& stream, Quad1D &in);
00085
00087
       Quad1D();
00088
00094
        Quad1D (const Quad1D &quad);
00095
```

```
00097
        ~Quad1D();
00098
00104
        int degree_approximation() const;
00105
00111
        Real *weights() const;
00112
00121
        Real Integrate(Real (*Integrand)(Real xx), UniStgGrid1D grid);
00122
00123
00124
        int degree_approximation_;
00125
00126
        std::vector<Real> weights_;
00127 };
00129 #endif // End of: MTK_INCLUDE_QUAD_1D_H_
```

### 17.39 include/mtk\_roots.h File Reference

Fundamental definitions to be used across all classes of the MTK.

This graph shows which files directly or indirectly include this file:



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### **Typedefs**

typedef float mtk::Real

Users can simply change this to build a double- or single-precision MTK.

#### **Variables**

const float mtk::kZero {0.0f}

MTK's zero defined according to selective compilation.

const float mtk::kOne {1.0f}

MTK's one defined according to selective compilation.

const float mtk::kDefaultTolerance {1e-7f}

Considered tolerance for comparisons in numerical methods.

const int mtk::kDefaultOrderAccuracy {2}

Default order of accuracy for mimetic operators.

const float mtk::kDefaultMimeticThreshold {1e-6f}

Default tolerance for higher-order mimetic operators.

const int mtk::kCriticalOrderAccuracyDiv {8}

At this order (and higher) we must use the CBSA to construct.

const int mtk::kCriticalOrderAccuracyGrad {10}

At this order (and higher) we must use the CBSA to construct.

#### 17.39.1 Detailed Description

This file contains the fundamental definitions that classes of the MTK rely on to be implemented. Examples of these definitions are the definition of fundamental data types, and global variables affecting the construction of mimetic operators, among others.

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at sciences dot sdsu dot edu

**Todo** Documentation should (better?) capture effects from selective compilation.

**Todo** Test selective precision mechanism.

Definition in file mtk roots.h.

### 17.40 mtk roots.h

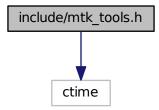
```
00001
00017 /*
00018 Copyright (C) 2015, Computational Science Research Center, San Diego State
00019 University. All rights reserved.
00020
00021 Redistribution and use in source and binary forms, with or without modification,
00022 are permitted provided that the following conditions are met:
00023
00024 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00025 and a copy of the modified files should be reported once modifications are
00026 completed. Documentation related to said modifications should be included.
00027
00028 2. Redistributions of source code must be done through direct
00029 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00030
00031 3. Redistributions of source code must retain the above copyright notice, this
00032 list of conditions and the following disclaimer.
00033
00034 4. Redistributions in binary form must reproduce the above copyright notice,
00035 this list of conditions and the following disclaimer in the documentation and/or
00036 other materials provided with the distribution.
00037
00038 5.
        Usage of the binary form on proprietary applications shall require explicit
00039 prior written permission from the the copyright holders.
00040
00041 6. Neither the name of the copyright holder nor the names of its contributors
00042 may be used to endorse or promote products derived from this software without
00043 specific prior written permission.
00044
00045 The copyright holders provide no reassurances that the source code provided does
00046 not infringe any patent, copyright, or any other intellectual property rights of
00047 third parties. The copyright holders disclaim any liability to any recipient for
00048 claims brought against recipient by any third party for infringement of that
00049 parties intellectual property rights.
00051 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00052 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00053 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00054 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00055 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00056 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00057 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00058 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00059 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00060 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00061 */
00062
00063 #ifndef MTK INCLUDE ROOTS H
00064 #define MTK_INCLUDE_ROOTS_H_
00065
00071 namespace mtk {
```

```
00072
00080 #ifdef MTK_PRECISION_DOUBLE
00081 typedef double Real;
00082 #else
00083 typedef float Real;
00084 #endif
00085
00103 #ifdef MTK_PRECISION_DOUBLE
00104 const double kZero{0.0};
00105 const double kOne{1.0};
00106 #else
00107 const float kZero{0.0f};
00108 const float kOne{1.0f};
00109 #endif
00110
00118 #ifdef MTK_PRECISION_DOUBLE
00119 const double kDefaultTolerance{1e-7};
00120 #else
00121 const float kDefaultTolerance{1e-7f};
00122 #endif
00123
00133 const int kDefaultOrderAccuracy{2};
00134
00144 #ifdef MTK_PRECISION_DOUBLE
00145 const double kDefaultMimeticThreshold{1e-6};
00146 #else
00147 const float kDefaultMimeticThreshold{1e-6f};
00148 #endif
00149
00157 const int kCriticalOrderAccuracyDiv{8};
00158
00166 const int kCriticalOrderAccuracyGrad{10};
00167 }
00168 #endif // End of: MTK_INCLUDE_ROOTS_H_
```

## 17.41 include/mtk\_tools.h File Reference

Tool manager class.

#include <ctime>
Include dependency graph for mtk\_tools.h:



This graph shows which files directly or indirectly include this file:



#### Classes

class mtk::Tools

Tool manager class.

#### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

### 17.41.1 Detailed Description

Basic tools to ensure execution correctness.

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_tools.h.

### 17.42 mtk tools.h

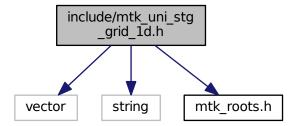
```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED 00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; 00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
```

```
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055
00056 #ifndef MTK_INCLUDE_TOOLS_H_
00057 #define MTK_INCLUDE_TOOLS_H_
00058
00059 #include <ctime>
00060
00061 namespace mtk {
00062
00072 class Tools {
00073 public:
00084 static void Prevent(const bool condition,
00085
                            const char *fname,
                            int lineno,
00087
                            const char *fxname);
00088
00094
       static void BeginTestNo(const int &nn);
00095
00101
       static void EndTestNo(const int &nn);
00102
00103 private:
00104
       static int test_number_;
00105
00106
       static clock t begin time ;
00107 };
00108 }
00109 #endif // End of: MTK_INCLUDE_TOOLS_H_
```

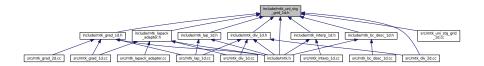
# 17.43 include/mtk\_uni\_stg\_grid\_1d.h File Reference

Definition of an 1D uniform staggered grid.

```
#include <vector>
#include <string>
#include "mtk_roots.h"
Include dependency graph for mtk_uni_stg_grid_1d.h:
```



This graph shows which files directly or indirectly include this file:



### Classes

class mtk::UniStgGrid1D
 Uniform 1D Staggered Grid.

#### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### 17.43.1 Detailed Description

Definition of an 1D uniform staggered grid.

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

**Todo** Create overloaded binding routines that read data from files.

Definition in file mtk\_uni\_stg\_grid\_1d.h.

# 17.44 mtk\_uni\_stg\_grid\_1d.h

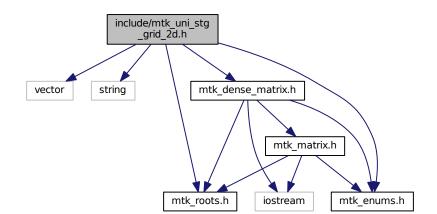
```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00032
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders.
```

```
00035
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #ifndef MTK_INCLUDE_UNI_STG_GRID_1D_H_
00059 #define MTK_INCLUDE_UNI_STG_GRID_1D_H_
00060
00061 #include <vector>
00062 #include <string>
00063
00064 #include "mtk_roots.h"
00065
00066 namespace mtk {
00067
00077 class UniStgGrid1D {
00078 public:
        friend std::ostream& operator << (std::ostream& stream, UniStgGrid1D &in);
00080
00081
00083
       UniStqGrid1D();
00084
       UniStgGrid1D(const UniStgGrid1D &grid);
00090
00091
00102
        UniStgGrid1D(const Real &west_bndy_x,
00103
                     const Real &east_bndy_x,
00104
                     const int &num cells x,
00105
                     const mtk::FieldNature &nature = mtk::SCALAR);
00106
00108
        ~UniStgGrid1D();
00109
00115
        Real west_bndy_x() const;
00116
00122
        Real east_bndy_x() const;
00123
00129
        Real delta x() const;
00130
00136
        Real *discrete_domain_x();
00137
00143
        Real *discrete_field_u();
00144
00150
        int num_cells_x() const;
00151
00157
        void BindScalarField(Real (*ScalarField)(Real xx));
00158
00170
       void BindVectorField(Real (*VectorField)(Real xx));
00171
00183
       bool WriteToFile(std::string filename,
00184
                         std::string space_name,
                         std::string field_name);
00185
00186
      private:
00187
00188
        FieldNature nature_;
00189
00190
        std::vector<Real> discrete domain x ;
00191
        std::vector<Real> discrete_field_u_;
00192
00193
        Real west bndv x :
00194
        Real east_bndy_x_;
00195
        Real num cells x ;
00196
        Real delta_x_;
00197 };
00198 }
00199 #endif // End of: MTK INCLUDE UNI STG GRID 1D H
```

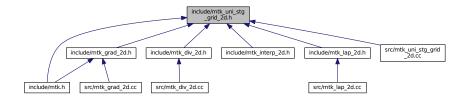
# 17.45 include/mtk\_uni\_stg\_grid\_2d.h File Reference

Definition of an 2D uniform staggered grid.

```
#include <vector>
#include <string>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_dense_matrix.h"
Include dependency graph for mtk_uni_stg_grid_2d.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

class mtk::UniStgGrid2D
 Uniform 2D Staggered Grid.

#### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### 17.45.1 Detailed Description

Definition of an 1D uniform staggered grid.

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Create overloaded binding routines that read data from files.

Definition in file mtk uni stg grid 2d.h.

### 17.46 mtk\_uni\_stg\_grid\_2d.h

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00015
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00032
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders.
00035
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00039
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00045
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00057
00058 #ifndef MTK_INCLUDE_UNI_STG_GRID_2D_H_
00059 #define MTK_INCLUDE_UNI_STG_GRID_2D_H_
00060
00061 #include <vector>
00062 #include <string>
00063
00064 #include "mtk roots.h'
00065 #include "mtk_enums.h"
00066 #include "mtk_dense_matrix.h"
00067
00068 namespace mtk {
```

```
00069
00079 class UniStgGrid2D {
00080 public:
00082
        friend std::ostream& operator <<(std::ostream& stream, UniStgGrid2D &in);</pre>
00083
00085
00086
00092
        UniStgGrid2D(const UniStgGrid2D &grid);
00093
00107
        UniStgGrid2D(const Real &west_bndy_x,
00108
                     const Real &east_bndy_x,
00109
                     const int &num_cells_x,
00110
                     const Real &south_bndy_y,
00111
                     const Real &north_bndy_y,
00112
                     const int &num_cells_y,
00113
                     const mtk::FieldNature &nature = mtk::SCALAR);
00114
00116
        ~UniStgGrid2D();
00117
00123
        Real west_bndy_x() const;
00124
00130
        Real east bndv x() const:
00131
00137
        Real south bndv v() const;
00138
00144
        Real north bndy v() const;
00145
00151
        Real delta_x() const;
00152
00158
        Real delta_y() const;
00159
00165
        Real *discrete_domain_x();
00166
00172
        Real *discrete_domain_y();
00173
00179
        Real *discrete_field_u();
00180
00186
        int num_cells_x() const;
00187
00193
        int num_cells_y() const;
00194
00200
        void BindScalarField(Real (*ScalarField)(Real xx, Real yy));
00201
00213
        void BindVectorFieldPComponent(Real (*VectorField)(
      Real xx, Real yy));
00214
00226
        void BindVectorFieldQComponent(Real (*VectorField)(
      Real xx, Real yy));
00227
00239
        bool WriteToFile(std::string filename,
00240
                          std::string space_name,
00241
                          std::string field_name);
00242
00243 private:
00244
       FieldNature nature_;
00245
00246
        std::vector<Real> discrete_domain_x_;
00247
        std::vector<Real> discrete_domain_y_;
00248
       std::vector<Real> discrete_field_u_;
00249
00250
        Real west_bndy_x_;
00251
        Real east_bndy_x_;
00252
        Real num_cells_x_;
00253
        Real delta_x_;
00254
00255
        Real south_bndy_y_;
00256
        Real north_bndy_y_;
00257
        Real num_cells_y_;
       Real delta_y_;
00258
00259 };
00260 }
00261 #endif // End of: MTK_INCLUDE_UNI_STG_GRID_2D_H_
```

### 17.47 Makefile.inc File Reference

17.48 Makefile.inc 229

#### 17.48 Makefile.inc

```
00001 # Makefile setup file for MTK.
00002
00003 SHELL := /bin/bash
00004
00005 # Please set the following variables up:
00006
00007 #
          1. Absolute path to base directory of the MTK... where is the MTK?
00008 #
00009
00010 BASE = /home/ejspeiro/Dropbox/MTK
00011
00012 #
         2. The machine (platform) identifier and required precision.
00013 #
00014
00015 # Options are:
00016 # - LINUX: A LINUX box installation.
00017 # - OSX: Uses OS X optimized solvers.
00018
00019 PLAT = LINUX
00020
00021 # Options are:
00022 # - SINGLE: Use 4 B floating point numbers.
00023 # - DOUBLE: Use 8 B floating point numbers.
00024
00025 PRECISION = DOUBLE
00026
00027 #
          3. Optimized solvers and operations by means of ATLAS in Linux?
00028 #
00029
00030 # If you have selected OSX in step 1, then you don't need to worry about this.
00031
00032 # Options are ON xor OFF:
00033
00034 ATL_OPT = OFF
00035
00036 #
         4. Paths to dependencies (header files for compiling).
00037 #
00038
00039 # GLPK include path (soon to go):
00040
00041 GLPK_INC = $(HOME)/Libraries/glpk-4.55/include
00042
00043 # Linux: If ATLAS optimization is ON, users should only provide the path to
00044 # ATLAS:
00045
00046 ATLAS_INC = $(HOME)/Libraries/ATLAS_3.8.4-CORE/include
00047
00048 # OS X: Do nothing.
00049
00050 #
          5. Paths to dependencies (archive files for (static) linking).
00051 #
00052
00053 # GLPK linking path (soon to go):
00054
00055 GLPK_LIB = $(HOME)/Libraries/qlpk-4.55/lib/libqlpk.a
00056
00057 # If optimization is OFF, then provide the paths for:
00058
00059 BLAS_LIB = $(HOME)/Libraries/BLAS/libblas.a
00060 LAPACK_LIB = $(HOME)/Libraries/lapack-3.4.1/liblapack.a
00062 # WARNING: Vendor libraries should be used whenever they are available.
00063
00064 # However, if optimization is ON, please provide the path the ATLAS' archive:
00065
00066 ATLAS_LIB = $(HOME)/Libraries/ATLAS_3.8.4-CORE/ATLAS_3.8.4-BUILD-Citadel/lib
00067
00068 #
          6. Compiler and its flags.
00069 #
00070
00071 CC = colorgcc
00072
00073 # Debug Level. Options are:
00074 # 0. NO debug at all NOR any run-time checks... be cautious!
00075 # 1. Verbose (execution messages) AND run-time checks.
00076 # 2. Level 1 plus intermediate scalar-valued results.
00077 \# 3. Level 2 plus intermediate array-valued results.
00078
```

```
00079 DEBUG_LEVEL = 3
08000
00081 # Flags recommended for release code:
00082
00083 CCFLAGS = -Wall -02
00084
00085 # Flags recommended for debugging code:
00086
00087 CCFLAGS = -Wall -g
00089 #
         7. Archiver, its flags, and ranlib:
00090 #
00091
00092 ARCH
               = ar
00093 ARCHFLAGS = cr
00095 # If your system does not have "ranlib" then set: "RANLIB = echo":
00096
00097 RANLIB = echo
00098
00099 # But, if possible:
00100
00101 RANLIB = ranlib
00102
00103 #
         8. Valgrind's memcheck options:
00104 #
00105
00106 MEMCHECK_OPTS = -v --tool=memcheck --leak-check=full --show-leak-kinds=all \
00107 --track-origins=yes --freelist-vol=20000000
00108
00109 # Done!
00110
00111 #
00112 #
00113 #
00114
00115 #
         MTK-related.
00116 #
00117
00118 SRC
               = $(BASE)/src
00119 INCLUDE = $(BASE)/include
00120 LIB
               = $(BASE)/lib
00121 MTK_LIB = \$(LIB)/libmtk.a
00122 TESTS
               = $(BASE)/tests
00123 EXAMPLES = $(BASE)/examples
00124
00125 #
         Compiling-related.
00126 #
00127
00128 CCFLAGS += -std=c++11 -fPIC -DMTK_DEBUG_LEVEL=$ (DEBUG_LEVEL) -I$ (INCLUDE) -c
00129
00130 ifeq ($(PRECISION),DOUBLE)
00131 CCFLAGS += -DMTK_PRECISION_DOUBLE
00132 else
00133
       CCFLAGS += -DMTK_PRECISION_SINGLE
00134 endif
00135
00136 \# Only the GLPK is included because the other dependencies are coded in Fortran.
00137
00138 ifeq ($(ATL_OPT),ON)
00139 CCFLAGS += -I$(GLPK_INC) $(ATLAS_INC)
00140 else
00141 CCFLAGS += -I$(GLPK_INC)
00142 endif
00143
00144 #
         Linking-related.
00145 #
00146
00147 NOOPT_LIBS = $(LAPACK_LIB) $(BLAS_LIB) -lm $(GLPK_LIB) -lstdc++
00148
00149 OPT_LIBS = -L$(ATLAS_LIB) -latlas -llapack -lblas -lm -latlas -lstdc++
00150
00151 ifeq ($(PLAT),OSX)
       LINKER = g++
00152
       LINKER += -framework Accelerate $(GLPK_LIB) $(MTK_LIB)
00153
00154 else
      ifeq ($(ATL_OPT),ON)
00155
00156
         LINKER = q++
         LIBS = $ (MTK_LIB)
00157
00158
         LIBS += $(OPT_LIBS)
00159
       else
```

```
00160
         LINKER = gfortran
00161
         LIBS = $ (MTK_LIB)
00162
         LIBS += $(NOOPT_LIBS)
00163
       endif
00164 endif
00165
00166 #
         Documentation-related.
00167 #
00168
00169 DOCGEN
                 = doxygen
00170 DOCFILENAME = doc_config.dxcf
               = $(BASE)/doc
00171 DOC
00172 DOCFILE
                 = $(BASE)/$(DOCFILENAME)
```

#### 17.49 README.md File Reference

#### 17.50 README.md

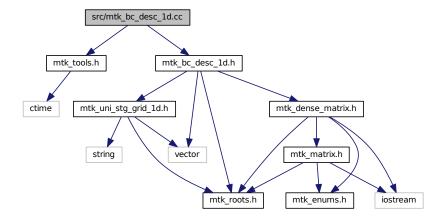
```
00001 # The Mimetic Methods Toolkit (MTK)
00003 By: **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu**
00004
00005
00006 ## 1. Description
00007
00008 We define numerical methods that are based on discretizations preserving the
00009 properties of their continuum counterparts to be **mimetic**.
00010
00011 The **Mimetic Methods Toolkit (MTK) ** is a C++ library for mimetic numerical
00012 methods. It is arranged as a set of classes for **mimetic quadratures**,
00013 **mimetic interpolation**, and **mimetic discretization** methods for the
00014 numerical solution of ordinary and partial differential equations.
00015
00016 An older version of this library is available outside of GitHub... just email me
00017 about it, and you can have it... it is ugly, yet functional and more complete.
00018
00019
00020 ## 2. Dependencies
00021
00022 This README assumes all of these dependencies are installed in the following
00023 folder:
00024
00025 ***
00026 $(HOME)/Libraries/
00027 ***
00028
00029 In this version, the MTK optionally uses ATLAS-optimized BLAS and LAPACK
00030 routines for the internal computation on some of the layers. However, ATLAS
00031 requires both BLAS and LAPACK in order to create their optimized distributions.
00032 Therefore, the following dependencies tree arises:
00033
00034 ### For Linux:
00035
00036 1. LAPACK - Available from: http://www.netlib.org/lapack/
        1. BLAS - Available from: http://www.netlib.org/blas/
00038
00039 2. GLPK - Available from: https://www.gnu.org/software/glpk/
00041 3. (Optional) ATLAS - Available from: http://math-atlas.sourceforge.net/
      1. BLAS - Available from: http://www.netlib.org/blas/
00043
       2. LAPACK - Available from: http://www.netlib.org/lapack/
00044
00045 4. (Optional) Valgrind - Available from: http://valgrind.org/
00046
00047 5. (Optional) Doxygen - Available from http://www.stack.nl/~dimitri/doxygen/
00048
00049 ### For OS X:
00050
00051 1. GLPK - Available from: https://www.gnu.org/software/glpk/
00052
00053
00054 ## 3. Installation
00055
00056 ### PART 1. CONFIGURATION OF THE MAKEFILE.
00057
```

```
00058 The following steps are required the build and test the MTK. Please use the
00059 accompanying 'Makefile.inc' file, which should provide a solid template to
00060 start with. The following command provides help on the options for make:
00061
00062 ***
00063 $ make help
00064 -
00065 Makefile for the MTK.
00066
00067 Options are:
00068 - make: builds only the library and the examples.
00069 - all: builds the library, the examples and the documentation.
00070 - mtklib: builds the library, i.e. generates the archive files.
00071 - tests: generates the tests.
00072 - examples: generates the examples.
00073 - gendoc: generates the documentation for the library.
00074 - checkheaders: checks syntax of the header files.
00076 - clean: cleans ALL the generated files.
00077 - cleanlib: cleans the generated archive and object files.
00078 - cleantests: cleans the generated tests executables.
00079 - cleanexamples: cleans the generated examples executables.
00080 -
00081 '''
00082
00083 ### PART 2. BUILD THE LIBRARY.
00084
00085 ***
00086 $ make
00087
00088
00089 If successful you'll read (before building the tests and examples):
00090
00091 '''
00092 ---- Library created! Check in /home/ejspeiro/Dropbox/MTK/lib
00093 ***
00094
00095 Examples and tests will also be built.
00096
00097
00098 ## 4. Frequently Asked Questions
00099
00100 Q: Why haven't you guys implemented GBS to build the library?
00101 A: I'm on it as we speak! ;)
00102
00103 Q: When will the other flavors be ready?
00104 A: Soon! I'm working on getting help on developing those.
00105
00106 Q: Is there any main reference when it comes to the theory on Mimetic Methods?
00107 A: Yes! Check: http://www.csrc.sdsu.edu/mimetic-book
00108
00109 Q: Do I need to generate the documentation myself?
00110 A: You can if you want to... but if you DO NOT want to, just go to our website.
00111
00112
00113 ## 5. Contact, Support, and Credits
00114
00115 The MTK is developed by researchers and adjuncts to the
00116 [Computational Science Research Center (CSRC)](http://www.csrc.sdsu.edu/)
00117 at [San Diego State University (SDSU)] (http://www.sdsu.edu/).
00118
00119 Developers are members of:
00120
00121 1. Mimetic Numerical Methods Research and Development Group.
00122 2. Computational Geoscience Research and Development Group.
00123 3. Ocean Modeling Research and Development Group.
00125 Currently the developers are:
00126
00127 - **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu** - @ejspeiro
00128 - Jose E. Castillo, Ph.D. - jcastillo at mail dot sdsu dot edu
00129 - Guillermo F. Miranda, Ph.D. - unigrav at hotmail dot com
00130 - Christopher P. Paolini, Ph.D. - paolini at engineering dot sdsu dot edu
00131 - Angel Boada.
00132 - Johnny Corbino.
00133 - Raul Vargas-Navarro.
00134
00135 Finally, please feel free to contact me with suggestions or corrections:
00136
00137 **Eduardo J. Sanchez, Ph.D. - esanchez at mail dot sdsu dot edu** - @ejspeiro
00138
```

00139 Thanks and happy coding!

## 17.51 src/mtk\_bc\_desc\_1d.cc File Reference

```
#include "mtk_tools.h"
#include "mtk_bc_desc_1d.h"
Include dependency graph for mtk_bc_desc_1d.cc:
```



## 17.52 mtk\_bc\_desc\_1d.cc

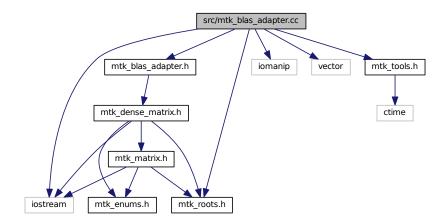
```
00001 #include "mtk_tools.h"
00002
00003 #include "mtk_bc_desc_1d.h"
00005 void mtk::BCDesc1D::ImposeOnOperator(
      mtk::DenseMatrix &matrix,
00006
                                             const std::vector<mtk::Real> &west,
00007
                                             const std::vector<mtk::Real> &east) {
00008
00009
       mtk::Tools::Prevent(matrix.num_rows() == 0, __FILE__, __LINE__, __func__);
00010
       mtk::Tools::Prevent(west.size() > (unsigned int) matrix.
      num_cols(),
00011
                               _FILE__, __LINE__, __func__);
       mtk::Tools::Prevent(east.size() > (unsigned int) matrix.
00012
                             __FILE__, __LINE__, __func__);
00013
00014
00016
00017
        for (unsigned int ii = 0; ii < west.size(); ++ii) {</pre>
         matrix.SetValue(0, ii, west[ii]);
00018
00019
00020
00022
        for (unsigned int ii = 0; ii < east.size(); ++ii) {</pre>
00023
        matrix.SetValue(matrix.num_rows() - 1,
matrix.num_cols() - 1 - ii,
00024
00025
00026
                           east[ii]);
00027
00028 }
00029
00030 void mtk::BCDesc1D::ImposeOnGrid(mtk::UniStgGrid1D &grid,
00031
                                         const mtk::Real &omega,
00032
                                         const mtk::Real &epsilon) {
```

```
00033
00034
       mtk::Tools::Prevent(grid.num_cells_x() == 0, __FILE__, __LINE__, __func__);
00035
00037
00038
       grid.discrete_field_u()[0] = omega;
00039
00041
00042
       grid.discrete_field_u()[grid.num_cells_x() + 2 - 1] = epsilon;
00043 }
```

#### 17.53 src/mtk\_blas\_adapter.cc File Reference

```
#include <iostream>
#include <iomanip>
#include <vector>
#include "mtk_roots.h"
#include "mtk tools.h"
#include "mtk_blas_adapter.h"
```

Include dependency graph for mtk blas adapter.cc:



### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### **Functions**

- float mtk::snrm2\_ (int \*n, float \*x, int \*incx)
- void mtk::saxpy\_ (int \*n, float \*sa, float \*sx, int \*incx, float \*sy, int \*incy)
- void mtk::sgemv (char \*trans, int \*m, int \*n, float \*alpha, float \*a, int \*lda, float \*x, int \*incx, float \*beta, float \*y, int \*incy)
- void mtk::sgemm\_ (char \*transa, char \*transb, int \*m, int \*n, int \*k, double \*alpha, double \*a, int \*lda, double \*b, aamm int \*ldb, double \*beta, double \*c, int \*ldc)

# 17.54 mtk\_blas\_adapter.cc

```
00001
00024 /*
00025 Copyright (C) 2015, Computational Science Research Center, San Diego State
00026 University. All rights reserved.
00028 Redistribution and use in source and binary forms, with or without modification,
00029 are permitted provided that the following conditions are met:
00031 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00032 and a copy of the modified files should be reported once modifications are
00033 completed. Documentation related to said modifications should be included.
00035 2. Redistributions of source code must be done through direct
00036 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00038 3. Redistributions of source code must retain the above copyright notice, this
00039 list of conditions and the following disclaimer.
00040
00041 4. Redistributions in binary form must reproduce the above copyright notice, 00042 this list of conditions and the following disclaimer in the documentation and/or
00043 other materials provided with the distribution.
00045 5. Usage of the binary form on proprietary applications shall require explicit
00046 \ \mathrm{prior} written permission from the the copyright holders.
00047
00048 6. Neither the name of the copyright holder nor the names of its contributors
00049 may be used to endorse or promote products derived from this software without
00050 specific prior written permission.
00051
00052 The copyright holders provide no reassurances that the source code provided does
00053 not infringe any patent, copyright, or any other intellectual property rights of
00054 third parties. The copyright holders disclaim any liability to any recipient for
00055 claims brought against recipient by any third party for infringement of that
00056 parties intellectual property rights.
00057
00058 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00059 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00060 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00061 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00062 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00063 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00064 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00065 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00066 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00067 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00068 */
00069
00070 #include <iostream>
00071 #include <iomanip>
00072
00073 #include <vector>
00074
00075 #include "mtk_roots.h"
00076 #include "mtk_tools.h"
00077 #include "mtk_blas_adapter.h"
00078
00079 namespace mtk {
08000
00081 extern "C" {
00083 #ifdef MTK_PRECISION_DOUBLE
00097 double dnrm2_(int *n, double *x, int *incx);
00098 #else
00112 float snrm2_(int *n, float *x, int *incx);
00113 #endif
00115 #ifdef MTK_PRECISION_DOUBLE
00116
00135 void daxpy_(int *n, double *da, double *dx, int *incx, double *dy, int *incy);
00136 #else
00137
00156 void saxpy_(int *n, float *sa, float *sx, int *incx, float *sy, int *incy);
00157 #endif
00158
00159 #ifdef MTK PRECISION DOUBLE
00160
```

```
00188 void dgemv_(char *trans,
00189
                  int *m,
00190
                   int *n,
                  double *alpha,
00191
00192
                  double *a,
00193
                  int *lda,
00194
                  double *x,
00195
                  int *incx,
00196
                  double *beta,
00197
                  double *y,
00198
                  int *incy);
00199 #else
00200
00228 void sgemv_(char *trans,
00229
                  int *m,
00230
                   int *n,
00231
                   float *alpha,
                  float *a,
00232
                  int *lda,
00233
00234
                  float *x,
00235
                   int *incx,
00236
                  float *beta,
00237
                   float *v,
00238
                  int *incy);
00239 #endif
00240
00241 #ifdef MTK_PRECISION_DOUBLE
00242
00267 void dgemm_(char *transa, 00268 char* transb,
00269
                   int *m,
00270
                  int *n,
00271
                  int *k,
00272
                  double *alpha,
00273
                  double *a.
00274
                  int *lda,
00275
                  double *b,
00276
                  int *ldb.
00277
                  double *beta,
00278
                  double *c,
00279
                  int *ldc);
00280 }
00281 #else
00282
00307 void sgemm_(char *transa,
00308
                  char* transb,
00309
                   int *m,
00310
                  int *n,
00311
                  int *k,
00312
                  double *alpha,
00313
                  double *a,
00314
                  int *lda,
00315
                  double *b, aamm
00316
                  int *ldb,
00317
                  double *beta,
00318
                  double *c,
00319
                  int *ldc);
00320 }
00321 #endif
00322 }
00324 mtk::Real mtk::BLASAdapter::RealNRM2(Real *in, int &in_length) {
00325
00326
        #if MTK_DEBUG_LEVEL > 0
00327
        mtk::Tools::Prevent(in_length <= 0, __FILE__, __LINE__, __func__);</pre>
00328
        #endif
00329
00330
        int incx\{1\}; // Increment for the elements of xx. ix >= 0.
00331
        #ifdef MTK_PRECISION_DOUBLE
00332
00333
        return dnrm2_(&in_length, in, &incx);
00334
        #else
00335
        return snrm2_(&in_length, in, &incx);
00336
        #endif
00337 }
00338
00339 void mtk::BLASAdapter::RealAXPY(mtk::Real alpha,
00340
                                             mtk::Real *xx,
mtk::Real *yy,
00341
00342
                                             int &in_length) {
00343
```

```
00344
        #if MTK_DEBUG_LEVEL > 0
00345
        mtk::Tools::Prevent(xx == nullptr, __FILE__, __LINE__, __func__);
00346
        mtk::Tools::Prevent(yy == nullptr, __FILE__, __LINE__, __func__);
00347
00348
00349
        int incx\{1\}; // Increment for the elements of xx. ix >= 0.
00350
00351
        #ifdef MTK_PRECISION_DOUBLE
00352
        daxpy_(&in_length, &alpha, xx, &incx, yy, &incx);
00353
        #else
00354
        saxpy_(&in_length, &alpha, xx, &incx, yy, &incx);
00355
        #endif
00356 }
00357
00358 mtk::Real mtk::BLASAdapter::RelNorm2Error(
     mtk::Real *computed,
00359
                                                  mtk::Real *known,
00360
                                                  int length) {
00361
00362
        #if MTK_DEBUG_LEVEL > 0
       mtk::Tools::Prevent(computed == nullptr, __FILE__, __LINE__, __func_
mtk::Tools::Prevent(known == nullptr, __FILE__, __LINE__, __func__);
00363
                                                               __LINE__, ___func___);
00364
00365
        #endif
00366
        mtk::Real norm_2_computed{mtk::BLASAdapter::RealNRM2(known, length)};
00367
00368
00369
        mtk::Real alpha{-mtk::kOne};
00370
00371
       mtk::BLASAdapter::RealAXPY(alpha, known, computed, length);
00372
00373
       mtk::Real norm 2 difference(mtk::BLASAdapter::RealNRM2 (computed,
     length) };
00374
00375
        return norm_2_difference/norm_2_computed;
00376 }
00377
00378 void mtk::BLASAdapter::RealDenseMV(mtk::Real &alpha,
00379
                                           mtk::DenseMatrix &aa,
00380
                                           mtk::Real *xx,
00381
                                           mtk::Real &beta.
00382
                                          mtk::Real *yy) {
00383
00384
        // Make sure input matrices are row-major ordered.
00385
00386
        if (aa.matrix_properties().ordering() ==
     mtk::COL MAJOR) {
00387
         aa.OrderRowMajor();
00388
00389
00390
        char transa{'T'}; // State that now, the input WILL be in row-major ordering.
00391
00392
                                                  // Rows of aa.
        int mm{aa.num_rows()};
00393
        int nn{aa.num_cols()};
                                                  // Columns of aa.
00394
        int lda{(aa.matrix_properties()).ld()}; // Leading dimension.
00395
        int incx{1};
                                                  // Increment of values in x.
00396
                                                  // Increment of values in y.
        int incy{1};
00397
00398
        std::swap(mm,nn);
00399
        #ifdef MTK_PRECISION_DOUBLE
00400
        dgemv_(&transa, &mm, &nn, &alpha, aa.data(), &lda,
00401
              xx, &incx, &beta, yy, &incy);
00402
00403
        sgemv_(&transa, &mm, &nn, &alpha, aa.data(), &lda,
              xx, &incx, &beta, yy, &incy);
00404
        #endif
00405
00406
        std::swap(mm,nn);
00407 }
00408
00409 mtk::DenseMatrix mtk::BLASAdapter::RealDenseMM(
     mtk::DenseMatrix &aa,
00410
                                                       mtk::DenseMatrix &bb) {
00411
00412
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(aa.num_cols() != bb.num_rows(),
00413
00414
                             __FILE__, __LINE__, __func__);
00415
        #endif
00416
00417
        // Make sure input matrices are row-major ordered.
00418
00419
        if (aa.matrix_properties().ordering() ==
      mtk::COL_MAJOR) {
```

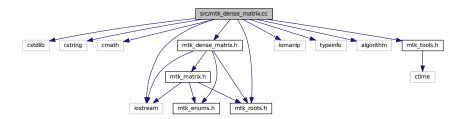
```
00420
            aa.OrderRowMajor();
00421
00422
          if (bb.matrix_properties().ordering() ==
      mtk::COL_MAJOR) {
00423
           bb.OrderRowMajor();
00424
00425
00426
         char ta\{'T'\}; // State that input matrix aa is in row-wise ordering.
00427
         char tb{'T'}; // State that input matrix bb is in row-wise ordering.
         int mm{aa.num_rows()};  // Rows of aa and rows of cc.
int nn{bb.num_cols()};  // Cols of bb and cols of cc.
int kk{aa.num_cols()};  // Cols of aa and rows of bb.
00430
00431
         int cc_num_rows{mm}; // Rows of cc.
int cc_num_cols{nn}; // Columns of cc.
00433
00434
00435
         int lda{std::max(1,kk)}; // Leading dimension of the aa matrix. int ldb{std::max(1,nn)}; // Leading dimension of the bb matrix. int ldc{std::max(1,mm)}; // Leading dimension of the cc matrix.
00436
00437
00438
00439
00440
         mtk::Real alpha{1.0}; // First scalar coefficient.
00441
         mtk::Real beta{0.0}; // Second scalar coefficient.
00442
00443
         mtk::DenseMatrix cc_col_maj_ord(cc_num_rows,cc_num_cols); // Output matrix.
00444
00445
         cc_col_maj_ord.SetOrdering(mtk::COL_MAJOR);
00446
         #ifdef MTK_PRECISION_DOUBLE
00447
00448
         dgemm_(&ta, &tb, &mm, &nn, &kk, &alpha, aa.data(), &lda,
00449
                  bb.data(), &ldb, &beta, cc_col_maj_ord.data(), &ldc);
00450
00451
         sgemm_(&ta, &tb, &mm, &nn, &kk, &alpha, aa.data(), &lda,
00452
                  bb.data(), &ldb, &beta, cc_col_maj_ord.data(), &ldc);
          #endif
00453
00454
         #if MTK_DEBUG_LEVEL > 0
std::cout << "cc_col_maj_ord =" << std::endl;</pre>
00455
00456
00457
          std::cout << cc_col_maj_ord << std::endl;
         #endif
00458
00459
00460
          cc_col_maj_ord.OrderRowMajor();
00461
00462
         return cc_col_maj_ord;
00463 }
```

# 17.55 src/mtk\_dense\_matrix.cc File Reference

### Implements a common dense matrix, using a 1D array.

```
#include <cstdlib>
#include <cstring>
#include <cmath>
#include <iostream>
#include <iomanip>
#include <typeinfo>
#include <algorithm>
#include "mtk_roots.h"
#include "mtk_dense_matrix.h"
#include "mtk_tools.h"
```

Include dependency graph for mtk\_dense\_matrix.cc:



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::DenseMatrix &in)</li>

### 17.55.1 Detailed Description

For developing purposes, it is better to have a not-so-intrincated data structure implementing matrices. This is the purpose of this class: to be used for prototypes of new code for small test cases. In every other instance, this should be replaced by the most appropriate sparse matrix.

### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk dense matrix.cc.

## 17.56 mtk dense matrix.cc

```
00013 /*
00014 Copyright (C) 2015, Computational Science Research Center, San Diego State
00015 University. All rights reserved.
00017 Redistribution and use in source and binary forms, with or without modification,
00018 are permitted provided that the following conditions are met:
00019
00020 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00021 and a copy of the modified files should be reported once modifications are
00022 completed. Documentation related to said modifications should be included.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00026
00027 3. Redistributions of source code must retain the above copyright notice, this
00028 list of conditions and the following disclaimer.
00029
00030 4. Redistributions in binary form must reproduce the above copyright notice,
00031 this list of conditions and the following disclaimer in the documentation and/or
```

```
00032 other materials provided with the distribution.
00034 5. Usage of the binary form on proprietary applications shall require explicit
00035 prior written permission from the the copyright holders.
00037 6. Neither the name of the copyright holder nor the names of its contributors
00038 may be used to endorse or promote products derived from this software without
00039 specific prior written permission.
00041 The copyright holders provide no reassurances that the source code provided does
00042 not infringe any patent, copyright, or any other intellectual property rights of
00043 third parties. The copyright holders disclaim any liability to any recipient for
00044 claims brought against recipient by any third party for infringement of that
00045 parties intellectual property rights.
00047 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00048 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00049 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00050 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00051 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00052 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00053 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00054 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00055 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00056 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00057 */
00058
00059 #include <cstdlib>
00060 #include <cstring>
00061 #include <cmath>
00062
00063 #include <iostream>
00064 #include <iomanip>
00065 #include <typeinfo>
00066
00067 #include <algorithm>
00068
00069 #include "mtk_roots.h"
00070 #include "mtk_dense_matrix.h"
00071 #include "mtk_tools.h"
00072
00073 namespace mtk {
00074
00075 std::ostream& operator <<(std::ostream &stream, mtk::DenseMatrix &in) {
00076
00077
        int mm{in.matrix_properties_.num_rows()}; // Auxiliary.
00078
       int nn{in.matrix_properties_.num_cols()}; // Auxiliary.
00079
08000
       if (in.matrix_properties_.ordering() ==
     mtk::COL_MAJOR) {
00081
         std::swap(mm, nn);
00082
00083
       for (auto ii = 0; ii < mm; ii++) {</pre>
00084
        for (auto jj = 0; jj < nn; jj++) {</pre>
00085
          mtk::Real value = in.data_[ii*nn + jj];
00086
           stream << std::setw(13) << value;
00087
00088
         stream << std::endl;
00089
        if (in.matrix_properties_.ordering() ==
00090
     mtk::COL_MAJOR) {
00091
         std::swap(mm, nn);
00092
00093
        return stream;
00094 }
00095 }
00097 mtk::DenseMatrix& mtk::DenseMatrix::operator = (const
     mtk::DenseMatrix &in) {
00098
00099
        if(this == &in) {
00100
         return *this;
00101
00102
       matrix_properties_.set_storage(in.
00103
     matrix_properties_.storage());
00104
00105
       matrix_properties_.set_ordering(in.
     matrix_properties_.ordering());
00106
00107
       auto aux = in.matrix_properties_.num_rows();
```

```
00108
        matrix_properties_.set_num_rows(aux);
00109
00110
        aux = in.matrix_properties().num_cols();
        matrix_properties_.set_num_cols(aux);
00111
00112
00113
        aux = in.matrix_properties().num_zero();
00114
        matrix_properties_.set_num_zero(aux);
00115
00116
        aux = in.matrix_properties().num_null();
00117
        matrix_properties_.set_num_null(aux);
00118
00119
        auto num_rows = matrix_properties_.num_rows();
00120
        auto num_cols = matrix_properties_.num_cols();
00121
00122
        delete [] data ;
00123
00124
        trv {
00125
         data_ = new mtk::Real[num_rows*num_cols];
00126
        } catch (std::bad_alloc &memory_allocation_exception) {
00127
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00128
            std::endl;
00129
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00130
00131
       memset(data_, mtk::kZero, sizeof(data_[0])*num_rows*
      num_cols);
00132
00133
        std::copy(in.data_, in.data_ + num_rows*num_cols, data_);
00134
00135
        return *this;
00136 }
00137
00138 mtk::DenseMatrix::DenseMatrix(): data_(nullptr) {
00139
        matrix_properties_.set_storage(mtk::DENSE);
0.0140
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00141
00142 }
00143
00144 mtk::DenseMatrix::DenseMatrix(const
      mtk::DenseMatrix &in) {
00145
00146
        matrix_properties_.set_storage(in.matrix_properties_.storage());
00147
00148
       matrix_properties_.set_ordering(in.matrix_properties_.
      ordering());
00149
00150
        auto aux = in.matrix_properties_.num_rows();
00151
        matrix_properties_.set_num_rows(aux);
00152
00153
        aux = in.matrix_properties().num_cols();
        matrix_properties_.set_num_cols(aux);
00154
00155
00156
        aux = in.matrix_properties().num_zero();
00157
        matrix_properties_.set_num_zero(aux);
00158
00159
        aux = in.matrix_properties().num_null();
00160
        matrix_properties_.set_num_null(aux);
00161
00162
        auto num_rows = in.matrix_properties_.num_rows();
00163
        auto num_cols = in.matrix_properties_.num_cols();
00164
00165
        try {
00166
          data_ = new mtk::Real[num_rows*num_cols];
00167
        } catch (std::bad_alloc &memory_allocation_exception) {
00168
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00169
            std::endl;
00170
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00171
00172
        memset(data_, mtk::kZero, sizeof(data_[0])*num_rows*num_cols);
00173
00174
        std::copy(in.data_,in.data_ + num_rows*num_cols,data_);
00175 }
00176
00177 mtk::DenseMatrix::DenseMatrix(const int &num_rows, const int &num_cols) {
00178
00179
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(num_rows < 1, __FILE__, __LINE__, __func__);</pre>
00180
00181
        mtk::Tools::Prevent(num_cols < 1, __FILE__, __LINE__, __func__);</pre>
00182
        #endif
00183
00184
        matrix_properties_.set_storage(mtk::DENSE);
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00185
```

```
00186
        matrix_properties_.set_num_rows(num_rows);
00187
        matrix_properties_.set_num_cols(num_cols);
00188
00189
00190
          data_ = new mtk::Real[num_rows*num_cols];
00191
        } catch (std::bad_alloc &memory_allocation_exception) {
00192
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00193
            std::endl;
00194
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00195
00196
        memset(data_, mtk::kZero, sizeof(data_[0])*num_rows*num_cols);
00197 }
00198
00199 mtk::DenseMatrix::DenseMatrix(const int &rank,
00200
                                       const bool &padded,
00201
                                       const bool &transpose) {
00202
00203
        #if MTK_DEBUG_LEVEL > 0
00204
        mtk::Tools::Prevent(rank < 1, __FILE__, __LINE__, __func__);</pre>
00205
        #endif
00206
00207
        int aux{}; // Used to control the padding.
00208
00209
        if (padded) {
00210
         aux = 1;
00211
00212
00213
        matrix_properties_.set_storage(mtk::DENSE);
00214
        \verb|matrix_properties_.set_ordering(mtk::ROW_MAJOR)|;
00215
        matrix_properties_.set_num_rows(aux + rank + aux);
00216
        matrix_properties_.set_num_cols(rank);
00217
00218
          data_ = new mtk::Real[matrix_properties_.num_values()];
00219
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << _</pre>
00220
                                                                         LINE - 3 <<
00221
00222
             std::endl;
00223
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00224
        memset(data_,
00225
00226
                mtk::kZero,
00227
                sizeof(data_[0])*(matrix_properties_.num_values()));
00228
00229
        for (auto ii =0; ii < matrix_properties_.num_rows(); ++ii) {</pre>
00230
         for (auto jj = 0; jj < matrix_properties_.num_cols(); ++jj) {</pre>
00231
             data_[ii*matrix_properties_.num_cols() + jj] =
00232
               (ii == jj + aux)? mtk::kOne: mtk::kZero;
00233
00234
00235 }
00236
00237 mtk::DenseMatrix::DenseMatrix(const mtk::Real *gen,
00238
                                       const int &gen_length,
00239
                                        const int &pro_length,
00240
                                        const bool &transpose) {
00241
00242
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(gen == nullptr, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(gen_length < 1, __FILE__, __LINE__, __func__);</pre>
00243
00244
        mtk::Tools::Prevent(pro_length < 1, __FILE__, __LINE__, __func__);</pre>
00245
00246
00247
00248
        matrix_properties_.set_storage(mtk::DENSE);
00249
        matrix_properties_.set_ordering(mtk::ROW_MAJOR);
00250
        if (!transpose) {
00251
          matrix_properties_.set_num_rows(gen_length);
00252
          matrix_properties_.set_num_cols(pro_length);
00253
        } else {
00254
          matrix_properties_.set_num_rows(pro_length);
00255
          matrix_properties_.set_num_cols(gen_length);
00256
00257
00258
        int rr = matrix_properties_.num_rows(); // Used to construct this matrix.
        int cc = matrix_properties_.num_cols(); // Used to construct this matrix.
00259
00260
00261
        trv {
          data_ = new mtk::Real[rr*cc];
00262
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00263
00264
00265
             std::endl:
00266
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
```

```
00267
00268
        memset(data_, mtk::kZero, sizeof(data_[0])*rr*cc);
00269
00270
        if (!transpose) {
00271
         for (auto ii = 0; ii < rr; ii++) {</pre>
00272
           for (auto jj = 0; jj < cc; jj++) {</pre>
00273
              data_[ii*cc + jj] = pow(gen[ii], (double) jj);
00274
00275
00276
       } else {
00277
          for (auto ii = 0; ii < rr; ii++) {</pre>
00278
           for (auto jj = 0; jj < cc; jj++) {</pre>
00279
              data_[ii*cc + jj] = pow(gen[jj], (double) ii);
00281
          }
00282
00283 }
00284
00285 mtk::DenseMatrix::~DenseMatrix() {
00286
00287
        delete[] data ;
00288
       data_ = nullptr;
00289 }
00290
00291 mtk::Matrix mtk::DenseMatrix::matrix_properties() const {
00292
00293
        return matrix_properties_;
00294 }
00295
00296 void mtk::DenseMatrix::SetOrdering(
      mtk::MatrixOrdering oo) {
00297
00298
       #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(!(oo == mtk::ROW_MAJOR || oo ==
00299
     mtk::COL_MAJOR),
00300
                               _FILE__, __LINE__, __func__);
00301
        #endif
00302
00303
       matrix_properties_.set_ordering(oo);
00304 }
00305
00306 int mtk::DenseMatrix::num_rows() const {
00307
00308
        return matrix_properties_.num_rows();
00309 }
00310
00311 int mtk::DenseMatrix::num_cols() const {
00312
00313
        return matrix_properties_.num_cols();
00314 }
00315
00316 mtk::Real* mtk::DenseMatrix::data() const {
00317
00318
        return data_;
00319 }
00320
00321 mtk::Real mtk::DenseMatrix::GetValue(
00322
         const int &rr,
00323
          const int &cc) const {
00324
00325
       #if MTK_DEBUG_LEVEL > 0
       mtk::Tools::Prevent(rr < 0, _FILE_, _LINE_, _func_);
mtk::Tools::Prevent(cc < 0, _FILE_, _LINE_, _func_);</pre>
00326
        #endif
00328
00329
00330
        return data_[rr*matrix_properties_.num_cols() + cc];
00331 }
00332
00333 void mtk::DenseMatrix::SetValue(
00334
          const int &rr,
00335
          const int &cc,
00336
          const mtk::Real &val) {
00337
00338
        #if MTK DEBUG LEVEL > 0
00339
       mtk::Tools::Prevent(rr < 0, __FILE__, __LINE__, __func__);</pre>
00340
       mtk::Tools::Prevent(cc < 0, __FILE__, __LINE__, __func__);</pre>
00341
        #endif
00342
00343
        data_[rr*matrix_properties_.num_cols() + cc] = val;
00344 }
00345
```

```
00346 void mtk::DenseMatrix::Transpose() {
00347
00349
        mtk::Real *data_transposed{}; // Buffer.
00350
00351
00352
        int rr = matrix_properties_.num_rows(); // Used to construct this matrix.
00353
        int cc = matrix_properties_.num_cols(); // Used to construct this matrix.
00354
00355
        try {
00356
         data_transposed = new mtk::Real[rr*cc];
        } catch (std::bad_alloc &memory_allocation_exception) {
00357
00358
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00359
            std::endl;
00360
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00361
00362
        memset (data_transposed,
00363
               mtk::kZero,
00364
               sizeof(data_transposed[0]) *rr*cc);
00365
00366
        // Assign the values to their transposed position.
00367
        for (auto ii = 0; ii < rr; ++ii) {</pre>
00368
         for (auto jj = 0; jj < cc; ++jj) {</pre>
            data_transposed[jj*rr + ii] = data_[ii*cc + jj];
00369
00370
          }
00371
        }
00372
00373
        // Swap pointers.
00374
        auto tmp = data_; // Temporal holder.
00375
        data_ = data_transposed;
00376
        delete [] tmp;
00377
        tmp = nullptr;
00378
00379
        matrix_properties_.set_num_rows(cc);
00380
        matrix_properties_.set_num_cols(rr);
00381 }
00382
00383 void mtk::DenseMatrix::OrderRowMajor() {
00384
00385
        if (matrix_properties_.ordering() == mtk::COL_MAJOR) {
00386
00388
00389
          mtk::Real *data_transposed{}; // Buffer.
00390
          int rr = matrix_properties_.num_rows(); // Used to construct this matrix.
00391
00392
          int cc = matrix_properties_.num_cols(); // Used to construct this matrix.
00393
00394
00395
            data_transposed = new mtk::Real[rr*cc];
          } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<</pre>
00396
00397
00398
              std::endl;
00399
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00400
          memset(data_transposed,
00401
00402
               mtk::kZero,
00403
                 sizeof(data_transposed[0])*rr*cc);
00404
00405
          // Assign the values to their transposed position.
00406
          std::swap(rr, cc);
00407
          for (auto ii = 0; ii < rr; ++ii) {</pre>
           for (auto jj = 0; jj < cc; ++jj) {</pre>
00408
00409
              data_transposed[jj*rr + ii] = data_[ii*cc + jj];
00410
            }
00411
00412
          std::swap(rr, cc);
00413
00414
          // Swap pointers.
00415
          auto tmp = data_; // Temporal holder.
00416
          data_ = data_transposed;
00417
          delete [] tmp;
00418
          tmp = nullptr;
00419
00420
          matrix properties .set ordering(mtk::ROW MAJOR);
00421
       }
00422 }
00423
00424 void mtk::DenseMatrix::OrderColMajor() {
00425
00426
        if (matrix_properties_.ordering() == ROW_MAJOR) {
00427
00429
```

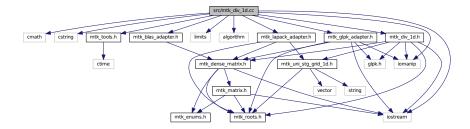
```
00430
          mtk::Real *data_transposed{}; // Buffer.
00431
00432
          int rr = matrix_properties_.num_rows(); // Used to construct this matrix.
00433
          int cc = matrix_properties_.num_cols(); // Used to construct this matrix.
00434
00435
00436
            data_transposed = new mtk::Real[rr*cc];
00437
          } catch (std::bad_alloc &memory_allocation_exception) {
00438
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00439
              std::endl;
00440
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00441
00442
          memset (data_transposed,
00443
                mtk::kZero,
00444
                sizeof(data_transposed[0]) *rr*cc);
00445
00446
          // Assign the values to their transposed position.
00447
          for (auto ii = 0; ii < rr; ++ii) {</pre>
           for (auto jj = 0; jj < cc; ++jj) {
   data_transposed[jj*rr + ii] = data_[ii*cc + jj];</pre>
00448
00449
00450
            }
00451
00452
00453
          // Swap pointers.
          auto tmp = data_; // Temporal holder.
00454
          data_ = data_transposed;
00455
          delete [] tmp;
00456
00457
          tmp = nullptr;
00458
00459
          matrix_properties_.set_ordering(mtk::COL_MAJOR);
00460
       }
00461 }
00462
00463 mtk::DenseMatrix mtk::DenseMatrix::Kron(const
     mtk::DenseMatrix &aa.
00464
                                                const mtk::DenseMatrix &bb) {
00465
        int row_offset{}; // Offset for rows.
00466
       int col_offset{}; // Offset for rows.
00467
00468
00469
       mtk::Real aa_factor{}; // Used in computation.
00470
00471
        // Auxiliary variables:
00472
        auto aux1 = aa.matrix_properties_.num_rows()*bb.
      matrix_properties_.num_rows();
00473
       auto aux2 = aa.matrix_properties_.num_cols()*bb.
      matrix_properties_.num_cols();
00474
00475
        mtk::DenseMatrix output(aux1,aux2); // Output matrix.
00476
00477
        int kk_num_cols{output.matrix_properties_.num_cols()}; // Aux.
00478
00479
        auto mm = aa.matrix_properties_.num_rows(); // Rows of aa.
00480
        auto nn = aa.matrix_properties_.num_cols(); // Cols of aa.
00481
        auto pp = bb.matrix_properties_.num_rows(); // Rows of bb.
00482
        auto qq = bb.matrix_properties_.num_cols(); // Cols of bb.
00483
00484
        for (auto ii = 0; ii < mm; ++ii) {</pre>
00485
         row_offset = ii*pp;
00486
         for (auto jj = 0; jj < nn; ++jj) {</pre>
           col_offset = jj*qq;
00487
00488
            aa_factor = aa.data_[ii*nn + jj];
00489
            for (auto 11 = 0; 11 < pp; ++11) {
00490
             for (auto oo = 0; oo < qq; ++oo) {
               auto index = (ll + row_offset)*kk_num_cols + (oo + col_offset);
00491
00492
                output.data_[index] = aa_factor*bb.data_[ll*qq + oo];
00493
00494
            }
00495
         }
00496
00497
00498
        output.matrix_properties_.set_storage(mtk::DENSE);
00499
        output.matrix_properties_.set_ordering(
     mtk::ROW_MAJOR);
00501
        return output;
00502 }
00503
```

## 17.57 src/mtk\_div\_1d.cc File Reference

### Implements the class Div1D.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_div_ld.h"
```

Include dependency graph for mtk\_div\_1d.cc:



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Div1D &in)</li>

### 17.57.1 Detailed Description

This class implements a 1D divergence matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Overload ostream operator as in mtk::Lap1D.

**Todo** Implement creation of **■** w. mtk::BLASAdapter.

Definition in file mtk\_div\_1d.cc.

17.58 mtk div 1d.cc 247

## 17.58 mtk\_div\_1d.cc

```
00001
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed. Documentation related to said modifications should be included.
00026 2. Redistributions of source code must be done through direct
00027 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00029 3. Redistributions of source code must retain the above copyright notice, this
00030 list of conditions and the following disclaimer.
00031
00032 4. Redistributions in binary form must reproduce the above copyright notice, 00033 this list of conditions and the following disclaimer in the documentation and/or
00034 other materials provided with the distribution.
00035
00036 5. Usage of the binary form on proprietary applications shall require explicit
00037 prior written permission from the the copyright holders.
00038
00039 6. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00060
00061 #include <cmath>
00062 #include <cstring>
00063
00064 #include <iostream>
00065 #include <iomanip>
00066 #include <limits>
00067 #include <algorithm>
00068
00069 #include "mtk_tools.h"
00070
00071 #include "mtk_blas_adapter.h"
00072 #include "mtk_lapack_adapter.h"
00073 #include "mtk_glpk_adapter.h"
00075 #include "mtk_div_1d.h"
00076
00077 namespace mtk {
00078
00079 std::ostream& operator <<(std::ostream &stream, mtk::Div1D &in) {
00080
00082
00083
       stream << "divergence_[0] = " << std::setw(9) << in.divergence_[0] <<
00084
         std::endl;
00085
00087
        stream << "divergence_[1:" << in.order_accuracy_ << "] = ";</pre>
00088
        for (auto ii = 1; ii <= in.order_accuracy_; ++ii) {</pre>
00089
         stream << std::setw(9) << in.divergence_[ii] << " ";
00090
00091
00092
        stream << std::endl;
00093
```

```
if (in.order_accuracy_ > 2) {
00094
00095
00097
00098
          stream << "divergence_[" << in.order_accuracy_ + 1 << ":" <<
00099
           2*in.order_accuracy_ << "] = ";
          for (auto ii = in.order_accuracy_ + 1; ii <= 2*in.</pre>
     order_accuracy_; ++ii) {
00101
           stream << std::setw(9) << in.divergence_[ii] << " ";</pre>
00102
00103
          stream << std::endl;
00104
00106
00107
          auto offset = (2*in.order_accuracy_ + 1);
          int mm{};
00109
          for (auto ii = 0; ii < in.dim_null_; ++ii) {</pre>
           stream << "divergence_[" << offset + mm << ":" <<
             offset + mm + in.num_bndy_coeffs_ - 1 << "] = ";
00111
            for (auto jj = 0; jj < in.num_bndy_coeffs_; ++jj) {</pre>
00112
             auto value = in.divergence_[offset + mm];
00113
              stream << std::setw(9) << value << " ";
00114
00115
             ++mm;
00116
00117
            stream << std::endl;
00118
00119
       }
00120
00121
        return stream;
00122 }
00123 }
00124
00125 mtk::Div1D::Div1D():
       order_accuracy_(mtk::kDefaultOrderAccuracy),
00126
       dim_null_(),
00127
00128
       num_bndy_coeffs_(),
00129
       divergence_length_(),
00130
       minrow_(),
00131
       row_(),
00132
       coeffs_interior_(),
00133
        prem_apps_(),
00134
        weights_crs_(),
00135
        weights_cbs_(),
00136
       mim_bndy_(),
00137
       divergence_(),
00138
       mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00139
00140 mtk::Div1D::Div1D(const Div1D &div):
00141
        order_accuracy_(div.order_accuracy_),
00142
       dim_null_(div.dim_null_),
00143
        num_bndy_coeffs_(div.num_bndy_coeffs_),
00144
        divergence_length_(div.divergence_length_),
       minrow_(div.minrow_),
00145
00146
        row_(div.row_),
00147
        coeffs_interior_(div.coeffs_interior_),
00148
       prem_apps_(div.prem_apps_),
00149
        weights_crs_(div.weights_crs_),
00150
        weights_cbs_(div.weights_cbs_),
00151
        mim_bndy_(div.mim_bndy_),
00152
        divergence_(div.divergence_),
00153
       mimetic_threshold_(div.mimetic_threshold_) {}
00154
00155 mtk::Div1D::~Div1D() {
00156
00157
       delete[] coeffs_interior_;
00158
       coeffs_interior_ = nullptr;
00159
00160
       delete[] prem_apps_;
00161
       prem_apps_ = nullptr;
00162
00163
        delete[] weights_crs_;
00164
        weights_crs_ = nullptr;
00165
00166
       delete[] weights cbs ;
00167
       weights cbs = nullptr;
00168
00169
       delete[] mim_bndy_;
00170
       mim_bndy_ = nullptr;
00171
00172
       delete[] divergence ;
00173
       divergence_ = nullptr;
00174 }
00175
```

17.58 mtk div 1d.cc 249

```
00176 bool mtk::Div1D::ConstructDiv1D(int order_accuracy,
00177
                                        mtk::Real mimetic threshold) {
00178
00179
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(order_accuracy < 2, __FILE_, __LINE_, __func__);
mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE_, __LINE__, __func__);</pre>
00180
00181
00182
        mtk::Tools::Prevent(mimetic_threshold <= mtk::kZero,</pre>
00183
                             __FILE__, __LINE__, __func__);
00184
        if (order_accuracy >= mtk::kCriticalOrderAccuracyDiv) {
00185
          std::cout << "WARNING: Numerical accuracy is critical." << std::endl;
00186
00187
00188
00189
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;</pre>
00190
        std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;</pre>
00191
00192
00193
        order_accuracy_ = order_accuracy;
00194
        mimetic_threshold_ = mimetic_threshold;
00195
00197
00198
        bool abort_construction = ComputeStencilInteriorGrid();
00199
00200
        #if MTK_DEBUG_LEVEL > 0
00201
        if (!abort construction) {
          std::cerr << "Could NOT complete stage 1." << std::endl;
00202
          std::cerr << "Exiting..." << std::endl;
00203
00204
          return false;
00205
00206
        #endif
00207
00208
        // At this point, we already have the values for the interior stencil stored
00209
        // in the coeffs_interior_ array.
00210
00211
        \ensuremath{//} It is noteworthy, that the 2nd-order-accurate divergence operator has NO
00212
        // approximation at the boundary, thus it has no weights. For this case, the
00213
        // dimension of the null-space of the Vandermonde matrices used to compute the
00214
        \ensuremath{//} approximating coefficients at the boundary is 0. Ergo, we compute this
        \ensuremath{//} number first and then decide if we must compute anything at the boundary.
00215
00216
00217
        dim_null_ = order_accuracy_/2 - 1;
00218
00219
        if (dim_null_ > 0) {
00220
00221
          #ifdef MTK_PRECISION_DOUBLE
00222
          num_bndy_coeffs_ = (int) (3.0*((mtk::Real) order_accuracy_)/2.0);
00223
00224
          num_bndy_coeffs_ = (int) (3.0f*((mtk::Real) order_accuracy_)/2.0f);
00225
          #endif
00226
00228
00229
          \ensuremath{//} For this we will follow recommendations given in:
00230
00231
          // http://icl.cs.utk.edu/lapack-forum/viewtopic.php?f=5&t=4506
00232
00233
          // We will compute the QR Factorization of the transpose, as in the
00234
          // following (MATLAB) pseudo-code:
00235
00236
          // [Q,R] = qr(V'); % Full QR as defined in
00237
          // % http://www.stanford.edu/class/ee263/notes/qr_matlab.pdf
00238
00239
          // null-space = Q(:, last (order_accuracy_/2 - 1) columns of Q );
00240
00241
          // However, given the nature of the Vandermonde matrices we've just
          // computed, they all posses the same null-space. Therefore, we impose the
00242
00243
          // convention of computing the null-space of the first Vandermonde matrix
00244
          // (west boundary).
00245
00246
          abort_construction = ComputeRationalBasisNullSpace();
00247
00248
          #if MTK_DEBUG_LEVEL > 0
00249
          if (!abort construction) {
00250
            std::cerr << "Could NOT complete stage 2.1." << std::endl;
00251
            std::cerr << "Exiting..." << std::endl;</pre>
00252
            return false:
00253
00254
          #endif
00255
00257
00258
          abort construction = ComputePreliminaryApproximations();
00259
```

```
00260
          #if MTK_DEBUG_LEVEL > 0
00261
          if (!abort_construction) {
00262
           std::cerr << "Could NOT complete stage 2.2." << std::endl;</pre>
            std::cerr << "Exiting..." << std::endl;
00263
00264
            return false;
00265
00266
          #endif
00267
00269
00270
          abort_construction = ComputeWeights();
00271
          #if MTK_DEBUG_LEVEL > 0
00272
00273
          if (!abort_construction) {
00274
           std::cerr << "Could NOT complete stage 2.3." << std::endl;
00275
            std::cerr << "Exiting..." << std::endl;
00276
            return false;
00277
00278
          #endif
00279
00281
00282
          abort_construction = ComputeStencilBoundaryGrid();
00283
00284
          #if MTK DEBUG LEVEL > 0
00285
          if (!abort_construction) {
00286
            std::cerr << "Could NOT complete stage 2.4." << std::endl;
            std::cerr << "Exiting..." << std::endl;
00287
00288
            return false:
00289
00290
          #endif
00291
00292
        } // End of: if (dim_null_ > 0);
00293
00295
00296
        \ensuremath{//} Once we have the following three collections of data:
       // (a) the coefficients for the interior,
// (b) the coefficients for the boundary (if it applies),
00297
00298
00299
        // (c) and the weights (if it applies),
00300
        // we will store everything in the output array:
00301
00302
        abort_construction = AssembleOperator();
00303
00304
        \#if MTK_DEBUG_LEVEL > 0
00305
       if (!abort_construction) {
00306
         std::cerr << "Could NOT complete stage 3." << std::endl;</pre>
         std::cerr << "Exiting..." << std::endl;
00307
00308
          return false;
00309
00310
       #endif
00311
00312
       return true;
00313 }
00314
00315 int mtk::Div1D::num_bndy_coeffs() const {
00316
00317
        return num_bndy_coeffs_;
00318 }
00319
00320 mtk::Real *mtk::Div1D::coeffs_interior() const {
00321
00322
       return coeffs_interior_;
00323 }
00324
00325 mtk::Real *mtk::Div1D::weights_crs() const {
00327
        return weights_crs_;
00328 }
00330 mtk::Real *mtk::Div1D::weights_cbs() const {
00331
00332
00333
       return weights cbs ;
00334 }
00335
00336 mtk::DenseMatrix mtk::Div1D::mim_bndy() const {
00337
00338
       mtk::DenseMatrix xx(dim_null_, 3*order_accuracy_/2);
00339
00340
        auto counter = 0;
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00341
         for(auto jj = 0; jj < 3*order_accuracy_/2; ++jj) {</pre>
00342
            xx.SetValue(ii,jj, divergence_[2*order_accuracy_ + 1 + counter]);
00343
```

17.58 mtk\_div\_1d.cc 251

```
00344
            counter++;
00345
00346
00347
00348
        return xx;
00349 }
00350
00351 mtk::DenseMatrix mtk::Div1D::ReturnAsDenseMatrix(const
      UniStgGrid1D &grid) {
00352
00353
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00354
00355
        #if MTK_DEBUG_LEVEL > 0
00356
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00357
        mtk::Tools::Prevent(nn < 3*order_accuracy_ - 1, __FILE__, __LINE__, __func__);</pre>
00358
        #endif
00359
00360
        mtk::Real inv_delta_x{mtk::kOne/grid.delta_x()};
00361
00362
        int dd_num_rows = nn + 2;
00363
        int dd num cols = nn + 1;
00364
        int elements_per_row = num_bndy_coeffs_;
00365
        int num_extra_rows = dim_null_;
00366
00367
        // Output matrix featuring sizes for divergence operators.
00368
        mtk::DenseMatrix out(dd num rows, dd num cols);
00369
00371
00372
        auto ee_index = 0;
00373
        for (auto ii = 1; ii < num_extra_rows + 1; ii++) {</pre>
00374
          auto cc = 0;
          for(auto jj = 0 ; jj < dd_num_rows; jj++) {</pre>
00375
00376
            if( cc >= elements_per_row) {
00377
              out.SetValue(ii, jj, mtk::kZero);
00378
            } else {
00379
              out.SetValue(ii,jj, mim_bndy_[ee_index++]*inv_delta_x);
00380
              cc++;
00381
            }
00382
          }
        }
00383
00384
00386
00387
        for (auto ii = num_extra_rows + 1;
00388
             ii < dd_num_rows - num_extra_rows - 1; ii++) {</pre>
          auto jj = ii - num_extra_rows - 1;
for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {</pre>
00389
00390
00391
            out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00392
00393
        }
00394
00396
00397
        ee_index = 0;
00398
        for (auto ii = dd_num_rows - 2; ii >= dd_num_rows - num_extra_rows - 1; ii--) {
00399
00400
          for (auto jj = dd_num_cols - 1; jj >= 0; jj--) {
00401
            if( cc >= elements_per_row) {
              out.SetValue(ii,jj,0.0);
00402
00403
            } else {
00404
              out.SetValue(ii, jj, -mim_bndy_[ee_index++] *inv_delta_x);
00405
              cc++;
00406
00407
           }
00408
00409
00410
        return out;
00411 }
00412
00413 bool mtk::Div1D::ComputeStencilInteriorGrid() {
00414
00416
00417
        mtk::Real* pp{}; // Spatial coordinates to create interior stencil.
00418
00419
        trv {
         pp = new mtk::Real[order_accuracy_];
00420
        } catch (std::bad_alloc &memory_allocation_exception) {
00421
00422
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00423
            std::endl;
00424
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00425
00426
        memset(pp, mtk::kZero, sizeof(pp[0])*order_accuracy_);
00427
```

```
00428
        #ifdef MTK_PRECISION_DOUBLE
00429
        pp[0] = 1.0/2.0 - ((mtk::Real) order_accuracy_)/2.0;
00430
        pp[0] = 1.0f/2.0f - ((mtk::Real) order_accuracy_)/2.0f;
00431
00432
        #endif
00433
00434
        for (auto ii = 1; ii < order_accuracy_; ++ii) {</pre>
00435
         pp[ii] = pp[ii - 1] + mtk::kOne;
00436
00437
00438
        #if MTK_DEBUG_LEVEL > 0
00439
        std::cout << "pp =" << std::endl;
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00440
          std::cout << std::setw(12) << pp[ii];
00441
00442
00443
        std::cout << std::endl << std::endl;</pre>
00444
        #endif
00445
00447
00448
       bool transpose(false);
00449
00450
        mtk::DenseMatrix vander matrix(pp.
00451
                                          order accuracy ,
00452
                                          order_accuracy_,
00453
                                          transpose);
00454
        #if MTK_DEBUG_LEVEL > 0
00455
        std::cout << "vander_matrix = " << std::endl;
00456
        std::cout << vander_matrix << std::endl;</pre>
00457
00458
        #endif
00459
00461
00462
        trv {
          coeffs_interior_ = new mtk::Real[order_accuracy_];
00463
        } catch (std::bad_alloc &memory_allocation_exception) {
00464
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00465
00466
            std::endl;
00467
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00468
00469
        memset(coeffs_interior_, mtk::kZero, sizeof(coeffs_interior_[0])*order_accuracy_);
00470
00471
        coeffs_interior_[1] = mtk::kOne;
00472
00473
        #if MTK DEBUG LEVEL > 0
00474
        std::cout << "oo =" << std::endl;
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00475
00476
          std::cout << std::setw(12) << coeffs_interior_[ii] << std::endl;</pre>
00477
00478
        std::cout << std::endl;
00479
        #endif
00480
00482
00483
        int info{mtk::LAPACKAdapter::SolveDenseSystem(vander_matrix,
00484
                                                          coeffs_interior_) };
00485
00486
        #if MTK_DEBUG_LEVEL > 0
00487
        if (!info) {
00488
          std::cout << "System solved! Interior stencil attained!" << std::endl;</pre>
00489
          std::cout << std::endl;
00490
00491
        else {
00492
          std::cerr << "Something wrong solving system! info = " << info << std::endl;</pre>
00493
          std::cerr << "Exiting..." << std::endl;
00494
          return false;
00495
00496
        #endif
00497
00498
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "coeffs_interior_ =" << std::endl;
for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00499
00500
00501
          std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
00502
00503
        std::cout << std::endl << std::endl;
00504
        #endif
00505
00506
        delete [] pp;
00507
       pp = nullptr;
00508
00509
        return true;
00510 }
00511
```

17.58 mtk div 1d.cc 253

```
00512 bool mtk::Div1D::ComputeRationalBasisNullSpace(void) {
00513
00514
        mtk::Real* gg{}; // Generator vector for the first Vandermonde matrix.
00515
00517
00518
       trv (
00519
         gg = new mtk::Real[num_bndy_coeffs_];
00520
        } catch (std::bad_alloc &memory_allocation_exception) {
00521
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00522
            std::endl;
00523
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00524
00525
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00526
00527
        #ifdef MTK_PRECISION_DOUBLE
00528
        gg[0] = -1.0/2.0;
00529
        #else
00530
        gg[0] = -1.0f/2.0f;
00531
        #endif
00532
        for (auto ii = 1; ii < num_bndy_coeffs_; ++ii) {</pre>
00533
         gg[ii] = gg[ii - 1] + mtk::kOne;
00534
00535
00536
        #if MTK_DEBUG_LEVEL > 0
00537
        std::cout << "gg =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00538
00539
         std::cout << std::setw(12) << gg[ii];
00540
00541
        std::cout << std::endl << std::endl;
00542
        #endif
00543
00545
00546
        bool tran{true}; // Should I transpose the Vandermonde matrix.
00547
00548
        mtk::DenseMatrix vv_west_t(qq, num_bndy_coeffs_, order_accuracy_ + 1, tran);
00549
00550
        #if MTK_DEBUG_LEVEL > 0
std::cout << "vv_west_t =" << std::endl;</pre>
00551
        std::cout << vv_west_t << std::endl;
00552
00553
        #endif
00554
00556
00557
       mtk::DenseMatrix qq_t(mtk::LAPACKAdapter::QRFactorDenseMatrix
      (vv_west_t));
00558
00559
        \#if MTK_DEBUG_LEVEL > 0
        std::cout << "QQ^T = " << std::endl;
00560
00561
        std::cout << qq_t << std::endl;
00562
00563
00565
00566
        int KK_num_rows_{num_bndy_coeffs_};
00567
        int KK_num_cols_{dim_null_};
00568
00569
        mtk::DenseMatrix KK(KK_num_rows_, KK_num_cols_);
00570
00571
        for (auto ii = num_bndy_coeffs_ - dim_null_; ii < num_bndy_coeffs_; ++ii) {</pre>
00572
         for (auto jj = 0; jj < num_bndy_coeffs_; ++jj) {</pre>
00573
            KK.data()[jj*dim_null_ + (ii - (num_bndy_coeffs_ - dim_null_))] =
00574
                qq_t.data()[ii*num_bndy_coeffs_ + jj];
00575
         }
00576
00577
00578
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "KK =" << std::endl;
00579
        std::cout << KK << std::endl;
        std::cout << "KK.num_rows() = " << KK.num_rows() << std::endl;
        std::cout << "KK.num_cols() = " << KK.num_cols() << std::endl;
00582
00583
        std::cout << std::endl;
00584
        #endif
00585
00587
00588
        // Scale thus requesting that the last entries of the attained basis for the
00589
        // null-space, adopt the pattern we require.
00590
        // Essentially we will implement the following MATLAB pseudo-code:
00591
        // scalers = KK(num_bndy_approxs - (dim_null - 1):num_bndy_approxs,:) \B
        // SK = KK*scalers
00592
00593
        // where SK is the scaled null-space.
00594
00595
        // In this point, we almost have all the data we need correctly allocated
        // in memory. We will create the matrix II_, and elements we wish to scale in
00596
```

```
00597
        // the KK array. Using the concept of the leading dimension, we could just
00598
        // use KK, with the correct leading dimension and that is it. BUT I DO NOT
00599
        \ensuremath{//} GET how does it work. So I will just create a matrix with the content of
00600
        // this array that we need, solve for the scalers and then scale the
00601
        // whole KK:
00602
        // We will then create memory for that sub-matrix of KK (SUBK).
00603
00604
00605
        mtk::DenseMatrix SUBK(dim_null_,dim_null_);
00607
        for (auto ii = num_bndy_coeffs_ - dim_null_; ii < num_bndy_coeffs_; ++ii) {</pre>
         for (auto jj = 0; jj < dim_null_; ++jj) {
   SUBK.data()[(ii - (num_bndy_coeffs_ - dim_null_))*dim_null_ + jj] =</pre>
00608
00609
00610
                 KK.data()[ii*dim_null_ + jj];
00611
          }
00612
00613
00614
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "SUBK =" << std::endl;
00615
        std::cout << SUBK << std::endl;
00616
00617
        #endif
00618
00619
        SUBK. Transpose();
00620
00621
        #if MTK DEBUG LEVEL > 0
        std::cout << "SUBK^T =" << std::endl;
00622
        std::cout << SUBK << std::endl;
00623
00624
        #endif
00625
00626
        bool padded{false};
00627
        tran = false;
00628
00629
        mtk::DenseMatrix II(dim_null_, padded, tran);
00630
        #if MTK_DEBUG_LEVEL > 0
std::cout << "II =" << std::endl;</pre>
00631
00632
00633
        std::cout << II << std::endl;
00634
        #endif
00635
00636
        // Solve the system to compute the scalers.
00637
        // An example of the system to solve, for k = 8, is:
00638
        11
        // SUBK*scalers = II_ or
00639
00640
        //
        // | 0.386018 -0.0339244 -0.129478 | | 1 0 0 | | // | -0.119774 0.0199423 0.0558632 |*scalers = | 0 1 0 |
00641
00642
00643
        // | 0.0155708 -0.00349546 -0.00853182 |
                                                               | 0 0 1 |
00644
        11
        // Notice this is a nrhs = 3 system.
00645
00646
        // Noteworthy: we do NOT ACTUALLY ALLOCATE space for the scalers... they
00647
        // will be stored in the created identity matrix.
00648
        // Let us first transpose SUBK (because of LAPACK):
00649
00650
        int info{mtk::LAPACKAdapter::SolveDenseSystem(SUBK, II)};
00651
00652
        #if MTK_DEBUG_LEVEL > 0
        if (!info) {
00653
00654
         std::cout << "System successfully solved!" <<
00655
00656
        } else {
00657
         std::cerr << "Something went wrong solving system! info = " << info <<
00658
00659
          std::cerr << "Exiting..." << std::endl;</pre>
00660
          return false;
00661
00662
        std::cout << std::endl;
00663
        #endif
00664
00665
        #if MTK_DEBUG_LEVEL > 0
00666
        std::cout << "Computed scalers:" << std::endl;</pre>
00667
        std::cout << II << std::endl;
00668
00669
00670
        // Multiply the two matrices to attain a scaled basis for null-space.
00671
00672
        rat_basis_null_space_ = mtk::BLASAdapter::RealDenseMM(KK, II);
00673
00674
        #if MTK DEBUG LEVEL > 0
00675
        std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00676
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00677
        #endif
```

17.58 mtk div 1d.cc 255

```
00678
00679
        // At this point, we have a rational basis for the null-space, with the
00680
        // pattern we need! :)
00681
00682
        delete [] gg;
00683
        gg = nullptr;
00684
00685
        return true;
00686 }
00688 bool mtk::Div1D::ComputePreliminaryApproximations(void) {
00689
00691
00692
        mtk::Real *gg{}; // Generator vector for the first approximation.
00693
00694
        try {
          gg = new mtk::Real[num_bndy_coeffs_];
00695
        } catch (std::bad_alloc &memory_allocation_exception) {
00696
00697
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00698 std::endl;
00699
         std::cerr << memory allocation exception.what() << std::endl;</pre>
00700
00701
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00702
00703
        #ifdef MTK PRECISION DOUBLE
00704
        qq[0] = -1.0/2.0;
00705
        #else
00706
        gg[0] = -1.0f/2.0f;
00707
        #endif
00708
        for (auto ii = 1; ii < num_bndy_coeffs_; ++ii) {</pre>
00709
          gg[ii] = gg[ii - 1] + mtk::kOne;
00710
00711
00712
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "gg0 =" << std::endl;
00713
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00714
00715
          std::cout << std::setw(12) << gg[ii];
00716
00717
        std::cout << std::endl << std::endl;
00718
        #endif
00719
00720
        // Allocate 2D array to store the collection of preliminary approximations.
00721
00722
          prem_apps_ = new mtk::Real[num_bndy_coeffs_*dim_null_];
        } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00723
00724
00725 std::endl;
00726
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00727
00728
        memset (prem_apps_,
00729
                mtk::kZero,
00730
                sizeof(prem_apps_[0])*num_bndy_coeffs_*dim_null_);
00731
00733
00734
        for (auto 11 = 0; 11 < dim_null_; ++11) {</pre>
00735
00736
          // Re-check new generator vector for every iteration except for the first.
00737
          #if MTK_DEBUG_LEVEL > 0
00738
          if (11 > 0) {
00739
             std::cout << "gg" << 11 << " =" << std::endl;
00740
             for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00741
              std::cout << std::setw(12) << gg[ii];
00742
00743
            std::cout << std::endl << std::endl;
00744
00745
          #endif
00746
00748
00749
          bool transpose(false);
00750
00751
          mtk::DenseMatrix AA_(gg,
00752
                                 num_bndy_coeffs_, order_accuracy_ + 1,
00753
                                 transpose):
00754
00755
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "AA_" << 11 << " =" << std::endl; std::cout << AA_ << std::endl;
00756
00757
00758
          #endif
00759
00761
00762
          mtk::Real *ob{};
```

```
00763
00764
          auto ob_ld = num_bndy_coeffs_;
00765
00766
          trv {
00767
           ob = new mtk::Real[ob_ld];
00768
          } catch (std::bad_alloc &memory_allocation_exception) {
00769
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00770
              std::endl;
00771
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00772
00773
          memset(ob, mtk::kZero, sizeof(ob[0])*ob_ld);
00774
00775
          ob[1] = mtk::kOne;
00776
00777
          #if MTK_DEBUG_LEVEL > 0
00778
          std::cout << "ob = " << std::endl << std::endl;
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
00779
00780
           std::cout << std::setw(12) << ob[ii] << std::endl;
00781
00782
          std::cout << std::endl;
00783
          #endif
00784
00786
00787
          // However, this is an under-determined system of equations. So we can not
00788
          // use the same LAPACK routine (dgesv_). We will instead use dgels_, through
          // our LAPACKAdapter class.
00789
00790
00791
          int info {
00792
           mtk::LAPACKAdapter::SolveRectangularDenseSystem(AA_,
     ob, ob_ld)};
00793
00794
          #if MTK DEBUG LEVEL > 0
00795
          if (!info ) {
           std::cout << "System successfully solved!" << std::endl << std::endl;
00796
00797
          } else {
00798
           std::cerr << "Error solving system! info = " << info_ << std::endl;
00799
00800
          #endif
00801
          #if MTK_DEBUG_LEVEL > 0
00802
          std::cout << "ob =" << std::endl;
00803
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
00804
00805
           std::cout << std::setw(12) << ob[ii] << std::endl;
00806
00807
          std::cout << std::endl;</pre>
00808
          #endif
00809
00811
00812
          // This implies a DAXPY operation. However, we must construct the arguments
00813
          // for this operation.
00814
00816
          // Save them into the ob_bottom array:
00817
00818
          Real *ob_bottom{}; // Bottom part of the attained kernel used to scale it.
00819
00820
00821
           ob_bottom = new mtk::Real[dim_null_];
00822
          } catch (std::bad_alloc &memory_allocation_exception) {
00823
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00824
00825
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00826
00827
          memset(ob_bottom, mtk::kZero, sizeof(ob_bottom[0])*dim_null_);
00828
00829
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
           ob_bottom[(dim_null_ - 1) - ii] = ob[num_bndy_coeffs_ - ii - 1];
00830
00831
00832
00833
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "ob_bottom =" << std::endl;</pre>
00834
00835
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00836
           std::cout << std::setw(12) << ob_bottom[ii] << std::endl;</pre>
00837
00838
          std::cout << std::endl;
00839
          #endif
00840
00842
00843
          // We must computed an scaled ob, sob, using the scaled null-space in
00844
          // rat_basis_null_space_.
00845
          // Such operation is: sob = ob - rat_basis_null_space_*ob_bottom
00846
                                  ob = -1.0*rat_basis_null_space_*ob_bottom + 1.0*ob
          // or:
```

17.58 mtk\_div\_1d.cc 257

```
00847
          // thus:
                                    Y =
                                          a*A
                                                        + b*Y (DAXPY).
00848
00849
          #if MTK_DEBUG_LEVEL > 0
00850
          std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00851
          std::cout << rat_basis_null_space_ << std::endl;</pre>
00852
00853
00854
          mtk::Real alpha{-mtk::kOne};
00855
          mtk::Real beta{mtk::kOne};
00856
00857
          mtk::BLASAdapter::RealDenseMV(alpha, rat_basis_null_space_,
00858
                                          ob_bottom, beta, ob);
00859
00860
          #if MTK_DEBUG_LEVEL > 0
00861
          std::cout << "scaled ob:" << std::endl;
00862
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00863
            std::cout << std::setw(12) << ob[ii] << std::endl;
00864
00865
          std::cout << std::endl;
00866
          #endif
00867
00868
          // We save the recently scaled solution, into an array containing these.
          // We can NOT start building the pi matrix, simply because I want that part
00869
00870
          // to be separated since its construction depends on the algorithm we want
00871
          // to implement.
00872
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {
  prem_apps_[ii*dim_null_ + 11] = ob[ii];</pre>
00873
00874
00875
00876
00877
          // After the first iteration, simply shift the entries of the last
00878
          // generator vector used:
00879
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00880
            gg[ii]--;
00881
00882
00883
          // Garbage collection for this loop:
00884
          delete[] ob;
00885
          ob = nullptr;
00886
00887
          delete[] ob_bottom;
00888
          ob_bottom = nullptr;
        } // End of: for (ll = 0; ll < dim_null; ll++);
00889
00890
00891
        #if MTK_DEBUG_LEVEL > 0
00892
        std::cout << "Matrix post-scaled preliminary apps: " << std::endl;</pre>
00893
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00894
          for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
00895
            std::cout << std::setw(12) << prem_apps_[ii*dim_null_ + jj];</pre>
00896
00897
          std::cout << std::endl;</pre>
00898
00899
        std::cout << std::endl;
00900
        #endif
00901
00902
        delete[] gg;
00903
        gg = nullptr;
00904
00905
        return true;
00906 }
00907
00908 bool mtk::Div1D::ComputeWeights(void) {
00909
00910
        // Matrix to copmpute the weights as in the CRSA.
00911
        mtk::DenseMatrix pi(num_bndy_coeffs_, num_bndy_coeffs_ - 1);
00912
00914
00915
        // Assemble the pi matrix using:
00916
        // 1. The collection of scaled preliminary approximations.
00917
        // 2. The collection of coefficients approximating at the interior.
00918
        // 3. The scaled basis for the null-space.
00919
00920
        // 1.1. Process array of scaled preliminary approximations.
00921
00922
        // These are queued in scaled_solutions. Each one of these, will be a column
00923
        // of the pi matrix:
00924
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00925
          for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
00926
            pi.data()[ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj] =
00927
              prem_apps_[ii*dim_null_ + jj];
00928
```

```
00929
00930
00931
        // 1.2. Add columns from known stencil approximating at the interior.
00932
00933
        // However, these must be padded by zeros, according to their position in the
00934
        // final pi matrix:
00935
        auto mm = 0;
00936
        for (auto jj = dim_null_; jj < order_accuracy_; ++jj) {</pre>
00937
          for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
            pi.data()[(ii + mm)*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj] =
00938
00939
               coeffs_interior_[ii];
00940
00941
          ++mm;
        }
00942
00943
00944
        rat_basis_null_space_.OrderColMajor();
00945
00946
        #if MTK_DEBUG_LEVEL > 0
00947
        std::cout << "Rational basis for the null-space (col. major):" << std::endl;</pre>
00948
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00949
        #endif
00950
00951
        // 1.3. Add final set of columns: rational basis for null-space.
00952
        for (auto jj = dim_null_ + (order_accuracy_/2 + 1); jj < num_bndy_coeffs_ - 1; ++jj) {</pre>
00953
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00954
            auto og =
            (jj - (dim_null_ + (order_accuracy_/2 + 1)))*num_bndy_coeffs_ + ii;
auto de = ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj;
00955
00956
00957
            pi.data()[de] = rat_basis_null_space_.data()[og];
00958
00959
        }
00960
        #if MTK_DEBUG_LEVEL >0
std::cout << "coeffs_interior_ =" << std::endl;</pre>
00961
00962
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00963
00964
          std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
00965
00966
        std::cout << std::endl << std::endl;
00967
        #endif
00968
00969
        #if MTK_DEBUG_LEVEL >0
        std::cout << "Constructed pi matrix for CRS Algorithm: " << std::endl;</pre>
00970
00971
        std::cout << pi << std::endl;
00972
        #endif
00973
00975
00976
        // This imposes the mimetic condition.
00977
00978
        mtk::Real *hh{}; // Right-hand side to compute weights in the C{R,B}SA.
00979
00980
00981
          hh = new mtk::Real[num_bndy_coeffs_];
00982
        } catch (std::bad_alloc &memory_allocation_exception) {
00983
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00984
            std::endl;
00985
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00986
00987
        memset(hh, mtk::kZero, sizeof(hh[0])*num_bndy_coeffs_);
00988
00989
        hh[0] = -mtk::kOne;
00990
        for (auto ii = (order_accuracy_/2 + 2 - 1); ii < num_bndy_coeffs_; ++ii) {</pre>
00991
          auto aux_xx = mtk::kZero;
00992
          for (auto jj = 0; jj < ((ii - (order_accuracy_/2 - 1)) - 1); ++jj) {</pre>
00993
            aux_xx += coeffs_interior_[jj];
00994
00995
          hh[ii] = -mtk::kOne*aux_xx;
00996
00997
00999
01000
        // That is, we construct a system, to solve for the weights.
01001
01002
        // Once again we face the challenge of solving with LAPACK. However, for the
01003
        // CRSA, this matrix PI is over-determined, since it has more rows than
        // unknowns. However, according to the theory, the solution to this system is
01004
01005
        // unique. We will use dgels_.
01006
01007
          weights_cbs_ = new mtk::Real[num_bndy_coeffs_];
01008
01009
        } catch (std::bad_alloc &memory_allocation_exception) {
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01010
01011
            std::endl:
```

17.58 mtk div\_1d.cc 259

```
01012
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01013
01014
        memset(weights_cbs_, mtk::kZero, sizeof(weights_cbs_[0])*num_bndy_coeffs_);
01015
01016
        int weights_ld{pi.num_cols() + 1};
01017
01018
        // Preserve hh.
01019
        std::copy(hh, hh + weights_ld, weights_cbs_);
01020
01021
        pi.Transpose();
01022
01023
        int info{mtk::LAPACKAdapter::SolveRectangularDenseSystem(
     pi, weights_cbs_, weights_ld)};
01024
01025
        #if MTK_DEBUG_LEVEL > 0
01026
        if (!info) {
01027
         std::cout << "System successfully solved!" << std::endl << std::endl;</pre>
01028
        } else {
01029
          std::cerr << "Error solving system! info = " << info << std::endl;</pre>
01030
01031
        #endif
01032
01033
        #if MTK DEBUG LEVEL > 0
01034
        std::cout << "hh =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01035
01036
          std::cout << std::setw(11) << hh[ii] << std::endl;
01037
01038
        std::cout << std::endl;
01039
        #endif
01040
01041
        // Preserve the original weights for research.
01042
01043
        trv (
          weights_crs_ = new mtk::Real[num_bndy_coeffs_];
01044
        } catch (std::bad_alloc &memory_allocation_exception) {
01045
          std::cerr << "Memory allocation exception on line " << \_LINE\_ - 3 <<
01046
01047
            std::endl;
01048
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01049
01050
        memset(weights_crs_, mtk::kZero, sizeof(weights_crs_[0])*num_bndy_coeffs_);
01051
01052
        std::copy(weights_cbs_, weights_cbs_ + (weights_ld - 1), weights_crs_);
01053
01054
        #if MTK DEBUG LEVEL > 0
01055
        std::cout << "weights_CRSA + lambda =" << std::endl;</pre>
01056
        for (auto ii = 0; ii < weights_ld - 1; ++ii) +</pre>
01057
          std::cout << std::setw(12) << weights_crs_[ii] << std::endl;</pre>
01058
01059
        std::cout << std::endl;
01060
        #endif
01061
01063
01064
        if (order_accuracy_ >= mtk::kCriticalOrderAccuracyDiv) {
01065
01066
          int minrow_{std::numeric_limits<int>::infinity()};
01067
01068
          mtk::Real norm_{mtk::BLASAdapter::RealNRM2(weights_cbs_,
      order_accuracy_) };
01069
          mtk::Real minnorm_{std::numeric_limits<mtk::Real>::infinity()};
01070
01072
01073
          mtk::DenseMatrix phi(order_accuracy_ + 1, order_accuracy_);
01074
01075
          for (auto ii = 0; ii < order_accuracy_ + 1; ++ii) {</pre>
01076
            for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01077
              phi.data()[ii*(order_accuracy_) + jj] = prem_apps_[ii*dim_null_ + jj];
01078
01079
          }
01080
01081
          int aux{}; // Auxiliary variable.
01082
          for (auto jj = dim_null_; jj < dim_null_ + 2; ++jj) {</pre>
            for (auto ii = 0; ii < order_accuracy_; ++ii) {
   phi.data()[(ii + aux)*order_accuracy_ + jj] = coeffs_interior_[ii];</pre>
01083
01084
01085
01086
            ++aux;
          }
01087
01088
          for(auto jj=order_accuracy_ - 1; jj >=order_accuracy_ - dim_null_; jj--) {
01089
01090
            for (auto ii=0; ii<order_accuracy_ + 1; ++ii) {</pre>
01091
              phi.data()[ii*order_accuracy_+jj] = mtk::kZero;
01092
```

```
01093
01094
01095
           for (auto jj = 0; jj < order_accuracy_ + 1; ++jj) {</pre>
01096
            for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
               phi.data()[(ii + order_accuracy_ - dim_null_ + jj*order_accuracy_)] =
    -prem_apps_[(dim_null_ - ii - 1 + jj*dim_null_)];
01097
01098
01099
01100
01101
01102
           for(auto ii = 0; ii < order_accuracy_/2; ++ii) {</pre>
             for (auto jj = dim_null_ + 2; jj < order_accuracy_; ++jj) {
  auto swap = phi.data()[ii*order_accuracy_+jj];</pre>
01103
01104
01105
                phi.data()[ii*order_accuracy_ + jj] =
                 phi.data()[(order_accuracy_-ii)*order_accuracy_+jj];
01106
01107
                phi.data()[(order_accuracy_-ii)*order_accuracy_+jj] = swap;
01108
01109
01110
01111
           #if MTK_DEBUG_LEVEL > 0
           std::cout << "Constructed PHI matrix for CBS Algorithm: " << std::endl;
01112
01113
           std::cout << phi << std::endl;
01114
           #endif
01115
01117
           mtk::Real *lamed{}; // Used to build big lambda.
01118
01119
01120
           trv {
01121
             lamed = new mtk::Real[dim null ];
           } catch (std::bad_alloc &memory_allocation_exception) {
   std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
01122
01123
01124
               std::endl:
01125
             std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01126
01127
           memset(lamed, mtk::kZero, sizeof(lamed[0])*dim_null_);
01128
           for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01129
01130
            lamed[ii] = hh[ii + order_accuracy_ + 1] ;
01131
01132
           #if MTK_DEBUG_LEVEL > 0
01133
           std::cout << "lamed =" << std::endl;
01134
           for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01135
01136
            std::cout << std::setw(12) << lamed[ii] << std::endl;
01137
01138
           std::cout << std::endl;</pre>
01139
           #endif
01140
01141
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01142
            mtk::Real temp = mtk::kZero;
01143
             for(auto jj = 0; jj < dim_null_; ++jj) {</pre>
01144
                temp = temp +
01145
                  lamed[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01146
01147
             hh[ii] = hh[ii] - temp;
01148
01149
01150
           #if MTK_DEBUG_LEVEL > 0
01151
           std::cout << "big_lambda =" << std::endl;</pre>
01152
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01153
             std::cout << std::setw(12) << hh[ii] << std::endl;
01154
           std::cout << std::endl;
01155
01156
           #endif
01157
01158
           int copy_result{};
01159
01160
           mtk::Real normerr_; // Norm of the error for the solution on each row.
01161
01163
01164
           for(auto row_= 0; row_ < order_accuracy_ + 1; ++row_) {</pre>
01165
            normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
      data(),
01166
                                                                        order_accuracy_ + 1,
01167
                                                                        order accuracy ,
01168
                                                                        order accuracy .
01169
                                                                        hh.
01170
                                                                        weights_cbs_,
01171
                                                                        row_,
01172
                                                                        mimetic_threshold_,
01173
                                                                        copy_result);
01174
             mtk::Real aux{normerr /norm };
```

17.58 mtk\_div\_1d.cc 261

```
01175
01176
            #if MTK_DEBUG_LEVEL>0
01177
            std::cout << "Relative norm: " << aux << " " << std::endl;
01178
            std::cout << std::endl;
01179
01180
01181
            if (aux < minnorm_) {</pre>
01182
             minnorm_ = aux;
01183
              minrow_= row_;
01184
01185
01186
01187
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "weights_CBSA + lambda (after brute force search):" <<</pre>
01188
01189
            std::endl;
01190
          for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01191
            std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01192
01193
          std::cout << std::endl;
01194
          #endif
01195
01197
01198
          // After we know which row yields the smallest relative norm that row is
01199
          // chosen to be the objective function and the result of the optimizer is
01200
          // chosen to be the new weights_.
01201
          #if MTK_DEBUG_LEVEL > 0
01202
          std::cout << "Minimum Relative Norm " << minnorm_ << " found at row " <<
01203
           minrow_ + 1 << std::endl;
01204
01205
          std::cout << std::endl;</pre>
01206
          #endif
01207
01208
          copy_result = 1;
          normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
01209
     data(),
01210
                                                                 order_accuracy_ + 1,
01211
                                                                 order_accuracy_,
01212
                                                                 order_accuracy_,
01213
                                                                 hh,
01214
                                                                 weights_cbs_,
01215
                                                                 minrow_,
                                                                 mimetic_threshold_,
01216
01217
                                                                 copy_result);
01218
          mtk::Real aux_{normerr_/norm_};
01219
          #if MTK_DEBUG_LEVEL > 0
01220
          std::cout << "Relative norm: " << aux_ << std::endl;</pre>
01221
          std::cout << std::endl;</pre>
01222
          #endif
01223
01224
          delete [] lamed;
01225
          lamed = nullptr;
01226
01227
01228
        delete [] hh;
01229
       hh = nullptr;
01230
01231
        return true;
01232 }
01233
01234 bool mtk::Div1D::ComputeStencilBoundaryGrid(void) {
01235
01236
        #if MTK_DEBUG_LEVEL > 0
01237
        std::cout << "weights_CBSA + lambda =" << std::endl;</pre>
        for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01238
          std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;
01239
01240
01241
        std::cout << std::endl;</pre>
01242
        #endif
01243
01245
01246
        mtk::Real *lambda{}; // Collection of bottom values from weights_.
01247
01248
01249
          lambda = new mtk::Real[dim null ];
01250
        } catch (std::bad_alloc &memory_allocation_exception) {
01251
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01252
            std::endl;
01253
          std::cerr << memory allocation exception.what() << std::endl;</pre>
01254
01255
        memset(lambda, mtk::kZero, sizeof(lambda[0])*dim_null_);
01256
```

```
01257
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01258
         lambda[ii] = weights_cbs_[order_accuracy_ + ii];
01259
01260
        #if MTK_DEBUG_LEVEL > 0
01261
01262
        std::cout << "lambda =" << std::endl;
01263
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01264
         std::cout << std::setw(12) << lambda[ii] << std::endl;</pre>
01265
01266
        std::cout << std::endl;
01267
01268
01270
01271
        mtk::Real *alpha{}; // Collection of alpha values.
01272
01273
01274
         alpha = new mtk::Real[dim_null_];
01275
        } catch (std::bad_alloc &memory_allocation_exception) {
01276
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01277
            std::endl;
01278
         std::cerr << memory allocation exception.what() << std::endl;</pre>
01279
01280
        memset(alpha, mtk::kZero, sizeof(alpha[0])*dim null );
01281
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01282
         alpha[ii] = lambda[ii]/weights_cbs_[ii] ;
01283
01284
01285
        #if MTK_DEBUG_LEVEL > 0
std::cout << "alpha =" << std::endl;</pre>
01286
01287
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01288
01289
         std::cout << std::setw(12) << alpha[ii] << std::endl;</pre>
01290
01291
        std::cout << std::endl;
01292
        #endif
01293
01295
01296
01297
         mim_bndy_ = new mtk::Real[num_bndy_coeffs_*dim_null_];
01298
        } catch (std::bad_alloc &memory_allocation_exception) {
01299
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01300
            std::endl:
01301
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01302
01303
        memset(mim_bndy_, mtk::kZero, sizeof(mim_bndy_[0])*num_bndy_coeffs_*dim_null_);
01304
01305
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01306
          for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01307
            mim_bndy_[ii*dim_null_ + jj] =
01308
              prem_apps_[ii*dim_null_ + jj] +
01309
              alpha[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01310
01311
01312
01313
        #if MTK_DEBUG_LEVEL >0
01314
        std::cout << "Collection of mimetic approximations:" << std::endl;</pre>
01315
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01316
         for (auto jj = 0; jj < dim_null_; ++jj) {</pre>
01317
            std::cout << std::setw(13) << mim_bndy_[ii*dim_null_ + jj];</pre>
01318
01319
          std::cout << std::endl;
01320
01321
        std::cout << std::endl;
        #endif
01322
01323
01324
        delete[] lambda;
01325
        lambda = nullptr;
01326
01327
        delete[] alpha;
01328
        alpha = nullptr;
01329
01330
        return true;
01331 }
01332
01333 bool mtk::Div1D::AssembleOperator(void) {
01334
01335
        // The output array will have this form:
01336
        // 1. The first entry of the array will contain the used order order_accuracy_.
        // 2. The second entry of the array will contain the collection of
01337
01338
        \ensuremath{//} approximating coefficients for the interior of the grid.
        // 3. IF order_accuracy_ > 2, then the third entry will contain a collection of weights.
01339
```

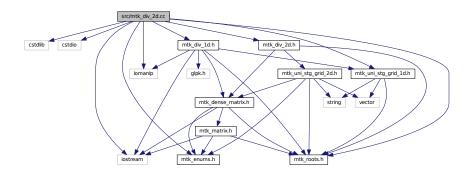
```
01340
        // 4. IF order_accuracy_ > 2, the next dim_null_ entries will contain the collections of
01341
        // approximating coefficients for the west boundary of the grid.
01342
01343
       if (order_accuracy_ > mtk::kDefaultOrderAccuracy) {
         divergence_length_ =
01345
           1 + order_accuracy_ + order_accuracy_ + dim_null_*num_bndy_coeffs_;
01346
01347
         divergence_length_ = 1 + order_accuracy_;
01348
01349
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "divergence_length_ = " << divergence_length_ << std::endl;</pre>
01351
01352
        #endif
01353
01354
01355
         divergence_ = new double[divergence_length_];
01356
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01357
01358
            std::endl;
01359
         std::cerr << memory allocation exception.what() << std::endl;</pre>
01360
01361
        memset(divergence_, mtk::kZero, sizeof(divergence_[0])*divergence_length_);
01362
01364
01365
       divergence_[0] = order_accuracy_;
01366
01368
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01369
01370
        divergence_[ii + 1] = coeffs_interior_[ii];
01371
01372
01374
01375
        if (order_accuracy_ > 2) {
01376
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
            divergence_[(1 + order_accuracy_) + ii] = weights_cbs_[ii];
01377
01378
01379
       }
01380
01383
01384
       if (order_accuracy_ > 2) {
01385
         auto offset = (2*order_accuracy_ + 1);
01386
          int mm{};
01387
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01388
            for (auto jj = 0; jj < num_bndy_coeffs_; ++jj) {</pre>
01389
              divergence_[offset + (mm)] = mim_bndy_[jj*dim_null_ + ii];
01390
01391
01392
         }
01393
01394
01395
        #if MTK_DEBUG_LEVEL > 0
01396
        std::cout << "1D " << order_accuracy_ << "-order div built!" << std::endl;
01397
        std::cout << std::endl;
01398
01399
01400
        return true;
01401 }
```

## 17.59 src/mtk div 2d.cc File Reference

## Implements the class Div2D.

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_uni_stg_grid_ld.h"
#include "mtk_div_ld.h"
#include "mtk_div_ld.h"
```

Include dependency graph for mtk\_div\_2d.cc:



### 17.59.1 Detailed Description

This class implements a 2D divergence matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_div\_2d.cc.

## 17.60 mtk div 2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00031
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
```

17.60 mtk div 2d.cc 265

```
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00060 #include <iostream>
00061 #include <iomanip>
00062
00063 #include "mtk_roots.h"
00064 #include "mtk_enums.h"
00065 #include "mtk_uni_stg_grid_1d.h"
00066 #include "mtk_div_1d.h"
00067 #include "mtk_div_2d.h"
00068
00069 mtk::Div2D::Div2D():
00070 order_accuracy_(),
00071 mimetic_threshold_() {}
00072
00073 mtk::Div2D::Div2D(const Div2D &div):
00074 order_accuracy_(div.order_accuracy_),
00075
       mimetic_threshold_(div.mimetic_threshold_) {}
00076
00077 mtk::Div2D::~Div2D() {}
00078
00079 mtk::DenseMatrix mtk::Div2D::ConstructDiv2D(const
     mtk::UniStgGrid2D &grid,
08000
                                                      int order_accuracy,
00081
                                                      mtk::Real mimetic_threshold) {
00082
        int NumCellsX = grid.num_cells_x();
int NumCellsY = grid.num_cells_y();
00083
00084
00085
00086
        int mx = NumCellsX + 2; // Gx vertical dimension
        int nx = NumCellsX + 1; // Gx horizontal dimension int my = NumCellsY + 2; // Gy vertical dimension int ny = NumCellsY + 1; // Gy horizontal dimension
00087
00088
00089
00090
00091
        mtk::Div1D div;
00092
00093
        bool info = div.ConstructDiv1D(order_accuracy, mimetic_threshold);
00094
00095
        if (!info) {
         std::cerr << "Mimetic div could not be built." << std::endl;</pre>
00096
00097
        }
00098
00099
        auto West = grid.west_bndy_x();
        auto East = grid.east_bndy_x();
00100
00101
        auto South = grid.south_bndy_y();
00102
        auto North = grid.east_bndy_x();
00103
        mtk::UniStgGrid1D grid_x(West, East, NumCellsX);
00104
00105
        mtk::UniStgGrid1D grid_y(South, North, NumCellsY);
00106
00107
        mtk::DenseMatrix Dx(div.ReturnAsDenseMatrix(grid_x));
00108
        mtk::DenseMatrix Dy(div.ReturnAsDenseMatrix(grid_y));
00109
00110
        bool padded{true};
00111
        bool transpose{false};
00112
00113
        mtk::DenseMatrix Ix(NumCellsX, padded, transpose);
00114
        mtk::DenseMatrix Iy(NumCellsY, padded, transpose);
00115
00116
        mtk::DenseMatrix Dxy(mtk::DenseMatrix::Kron(Iv, Dx));
00117
        mtk::DenseMatrix Dyx(mtk::DenseMatrix::Kron(Dy, Ix));
00118
00119 #if MTK DEBUG LEVEL > 0
        std::cout << "Gx :" << mx << "by " << nx << std::endl;
00120
        std::cout << "Transpose Iy : " << NumCellsY<< " by " << ny << std::endl;
00121
        std::cout << "Gy :" << my << "by " << ny << std::endl; std::cout << "Transpose Ix : " << NumCellsX<< " by " << nx << std::endl;
00122
00123
```

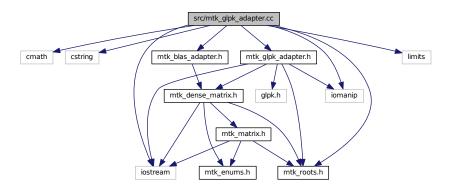
```
std::cout << "Kronecker dimensions Grad 2D" <<</pre>
00125
        mx*NumCellsY + my*NumCellsX << " by " << nx*ny <<std::endl;</pre>
00126 #endif
00127
00128
        mtk::DenseMatrix D2D(mx*my,nx*NumCellsY + ny*NumCellsX);
00129
00130
        for (auto ii = 0; ii < mx*my; ii++) {</pre>
00131
         for (auto jj = 0; jj < nx*NumCellsY; jj++) {</pre>
00132
            D2D.SetValue(ii, jj, Dxy.GetValue(ii,jj));
00133
00134
         for (auto kk=0; kk<ny*NumCellsX; kk++)</pre>
00135
            D2D.SetValue(ii, kk + nx*NumCellsY, Dyx.GetValue(ii, kk));
00136
00137
00138
00139
        divergence_ = D2D;
00140
00141
        return divergence ;
00142 }
00143
00144 mtk::DenseMatrix mtk::Div2D::ReturnAsDenseMatrix() {
00145
00146
        return divergence_;
00147 }
```

# 17.61 src/mtk\_glpk\_adapter.cc File Reference

### Adapter class for the GLPK API.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include "mtk_roots.h"
#include "mtk_blas_adapter.h"
#include "mtk_glpk_adapter.h"
```

Include dependency graph for mtk\_glpk\_adapter.cc:



### 17.61.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the GLPK.

The **GLPK (GNU Linear Programming Kit)** package is intended for solving large-scale linear programming (LP), mixed integer programming (MIP), and other related problems. It is a set of routines written in ANSI C and organized in the form of a callable library.

#### See Also

```
http://www.gnu.org/software/glpk/
```

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_glpk\_adapter.cc.

## 17.62 mtk\_glpk\_adapter.cc

```
00001
00019 /*
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00025
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed. Documentation related to said modifications should be included.
00029
00030 2. Redistributions of source code must be done through direct
00031 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00032
00033 3. Redistributions of source code must retain the above copyright notice, this
00034 list of conditions and the following disclaimer.
00035
00036 4. Redistributions in binary form must reproduce the above copyright notice,
00037 this list of conditions and the following disclaimer in the documentation and/or
00038 other materials provided with the distribution.
00039
00040 5. Usage of the binary form on proprietary applications shall require explicit
00041 prior written permission from the the copyright holders.
00042
00043 6. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00046
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00064
00065 #include <cmath>
00066 #include <cstring>
00067
00068 #include <iostream>
00069 #include <iomanip>
00070 #include <limits>
00071
00072 #include "mtk roots.h"
```

```
00073 #include "mtk_blas_adapter.h"
00074 #include "mtk_glpk_adapter.h"
00075
00076 mtk::Real mtk::GLPKAdapter::SolveSimplexAndCompare(
     mtk::Real *A,
00077
00078
                                                            int ncols,
00079
                                                            int kk,
00080
                                                            mtk::Real *hh,
                                                            mtk::Real *qq,
00082
                                                            int robjective,
00083
                                                            mtk::Real mimetic_threshold,
00084
                                                            int copy) {
00085
00086
        #if MTK_DEBUG_LEVEL > 0
00087
        char mps_file_name[18]; // File name for the MPS files.
00088
        #endif
00089
        char rname[5];
                                  // Row name.
00090
        char cname[5];
                                 // Column name.
00091
00092
        glp_prob *lp; // Linear programming problem.
00093
        int *ia; // Array for the problem.
int *ja; // Array for the problem.
00094
00095
00096
        int problem_size; // Size of the problem.
00097
                           // Number of rows.
00098
        int lp_nrows;
                           // Number of columns.
00099
        int lp_ncols;
                           // Size of the matrix.
00100
        int matsize;
        int glp_index{1}; // Index of the objective function.
00101
00102
        int ii;
                           // Iterator.
00103
                           // Iterator.
        int jj;
00104
                                    \ensuremath{//} Array for the problem.
00105
        mtk::Real *ar;
        mtk::Real *objective;
                                   \ensuremath{//} Array containing the objective function.
00106
                                   // Array containing the rhs.
        mtk::Real *rhs;
00107
00108
        mtk::Real *err;
                                   // Array of errors.
00109
                                   // Norm-2 of the error.
00110
        mtk::Real x1;
00111
00112
        #if MTK_DEBUG_LEVEL > 0
                                   // Value of the objective function.
00113
        mtk::Real obj_value;
00114
        #endif
00115
00116
        lp\_nrows = kk;
00117
        lp_ncols = kk;
00118
00119
        matsize = lp_nrows*lp_ncols;
00120
00122
00124
        problem_size = lp_nrows*lp_ncols + 1;
00125
00126
00127
          ia = new int[problem_size];
00128
        } catch (std::bad_alloc &memory_allocation_exception) {
00129
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00130
            std::endl;
00131
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00132
00133
        memset(ia, 0, sizeof(ia[0])*problem_size);
00134
00135
00136
          ja = new int[problem_size];
00137
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00138
00139
            std::endl;
00140
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00141
00142
        memset(ja, 0, sizeof(ja[0])*problem_size);
00143
00144
00145
          ar = new mtk::Real[problem size];
00146
        } catch (std::bad_alloc &memory_allocation_exception) {
00147
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00148
            std::endl;
00149
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00150
00151
        memset(ar, mtk::kZero, sizeof(ar[0])*problem_size);
00152
00153
00154
          objective = new mtk::Real[lp_ncols + 1];
```

```
} catch (std::bad_alloc &memory_allocation_exception) {
00156
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00157
            std::endl;
00158
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00159
00160
       memset(objective, mtk::kZero, sizeof(objective[0])*(lp_ncols + 1));
00161
00162
00163
         rhs = new mtk::Real[lp_nrows + 1];
        } catch (std::bad_alloc &memory_allocation_exception) {
00164
00165
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00166
            std::endl;
00167
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00168
00169
       memset(rhs, mtk::kZero, sizeof(rhs[0])*(lp_nrows + 1));
00170
00171
        trv {
         err = new mtk::Real[lp_nrows];
00172
00173
        } catch (std::bad_alloc &memory_allocation_exception) {
00174
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00175
            std::endl;
00176
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00177
00178
       memset(err, mtk::kZero, sizeof(err[0])*(lp_nrows));
00179
00180
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "Problem size: " << problem_size << std::endl;
00181
        std::cout << "lp_nrows = " << lp_nrows << std::endl;
00182
        std::cout << "lp_ncols = " << lp_ncols << std::endl;
00183
00184
        std::cout << std::endl;
00185
        #endif
00186
00187
        lp = glp_create_prob();
00188
        glp_set_prob_name (lp, "mtk::GLPKAdapter::Simplex");
00189
00190
00191
        glp_set_obj_dir (lp, GLP_MIN);
00192
00194
00195
        glp_add_rows(lp, lp_nrows);
00196
00197
        for (ii = 1; ii <= lp_nrows; ++ii) {</pre>
          sprintf(rname, "R%02d",ii);
00198
00199
          glp_set_row_name(lp, ii, rname);
00200
00201
00202
        glp_add_cols(lp, lp_ncols);
00203
00204
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00205
          sprintf(cname, "Q%02d",ii);
00206
         glp_set_col_name (lp, ii, cname);
00207
00208
00210
00211
        #if MTK_DEBUG_LEVEL>0
00212
        std::cout << "Using row " << robjective + 1 << " as objective." << std::endl;
00213
00214
        for (jj = 0; jj < kk; ++jj) {
00215
         objective[glp_index] = A[jj + robjective * ncols];
00216
         glp_index++;
00217
00218
        #if MTK_DEBUG_LEVEL >0
00219
        std::cout << std::endl;</pre>
00220
        #endif
00221
00223
        glp_index = 1;
00225
        rhs[0] = mtk::kZero;
00226
        for (ii = 0; ii <= lp_nrows; ++ii) {</pre>
         if (ii != robjective) {
00227
00228
           rhs[glp_index] = hh[ii];
00229
            glp_set_row_bnds(lp, glp_index, GLP_UP, 0.0, rhs[glp_index]);
00230
            glp_index++;
00231
         }
00232
00233
        #if MTK DEBUG LEVEL > 0
00234
        std::cout << "rhs =" << std::endl;
00235
        for (auto ii = 0; ii < lp_nrows; ++ii) {</pre>
00236
00237
         std::cout << std::setw(15) << rhs[ii] << std::endl;
00238
```

```
00239
        std::cout << std::endl;</pre>
00240
00241
00243
00244
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00245
         glp_set_obj_coef (lp, ii, objective[ii]);
00246
00247
00249
00250
        for (ii = 1; ii <= lp_ncols; ++ii) {</pre>
00251
          glp_set_col_bnds (lp, ii, GLP_LO, mimetic_threshold, 0.0);
00252
00253
00255
00256
        glp\_index = 1;
00257
        for (ii = 0; ii <= kk; ++ii) {
00258
          for (jj = 0; jj < kk; ++jj) {</pre>
            if (ii != robjective) {
00259
00260
              ar[glp_index] = A[jj + ii * ncols];
00261
               glp_index++;
00262
            }
00263
          }
00264
        }
00265
00266
        qlp\_index = 0;
00267
        for (ii = 1; ii < problem_size; ++ii) {
  if (((ii - 1) % lp_ncols) == 0) {</pre>
00268
00269
00270
            glp_index++;
00271
          ia[ii] = glp_index;
ja[ii] = (ii - 1) % lp_ncols + 1;
00272
00273
00274
00275
00276
        glp_load_matrix (lp, matsize, ia, ja, ar);
00277
        #if MTK_DEBUG_LEVEL > 0
sprintf(mps_file_name, "LP_MPS_row_%02d.mps", robjective);
00278
00279
        glp_write_mps(lp, GLP_MPS_FILE, nullptr, mps_file_name);
00280
00281
00282
00284
00285
        glp_simplex (lp, nullptr);
00286
00287
        // Check status of the solution.
00288
00289
        if (glp_get_status(lp) == GLP_OPT) {
00290
00291
          for(ii = 1; ii <= lp_ncols; ++ii) {</pre>
00292
            err[ii - 1] = qq[ii - 1] - glp_get_col_prim(lp,ii);
00293
00294
00295
           #if MTK_DEBUG_LEVEL > 0
00296
           obj_value = glp_get_obj_val (lp);
00297
           std::cout << std::setw(12) << "CBS" << std::setw(12) << "CRS" << std::endl;
00298
           for (ii = 0; ii < lp_ncols; ++ii) {</pre>
            std::cout << "q_" << ii + 1 << " = " << std::setw(12) <<
00299
00300
               glp_get_col_prim(lp,ii + 1) << std::setw(12) << qq[ii] << std::endl;</pre>
00301
00302
          std::cout << "Objective function value (row " << robjective + 1 << ") = " <<
00303
            obj_value << std::endl;
00304
           #endif
00305
00306
          if (copy) {
            for (ii = 0; ii < lp_ncols; ++ii) {</pre>
00307
00308
              qq[ii] = glp_get_col_prim(lp,ii + 1);
00309
00310
             // Preserve the bottom values of qq.
00311
00312
00313
          x1 = mtk::BLASAdapter::RealNRM2(err,lp_ncols);
00314
00315
        } else {
00316
          x1 = std::numeric limits<mtk::Real>::infinity();
00317
00318
00319
        glp delete prob (lp);
00320
        glp_free_env ();
00321
00322
        delete [] ia;
delete [] ja;
00323
```

```
00324 delete [] ar;

00325 delete [] objective;

00326 delete [] rhs;

00327 delete [] err;

00328

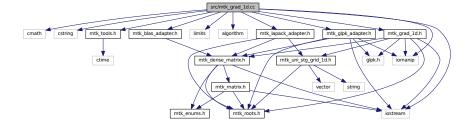
00329 return x1;

00330 }
```

# 17.63 src/mtk\_grad\_1d.cc File Reference

### Implements the class Grad1D.

```
#include <cmath>
#include <cstring>
#include <iostream>
#include <iomanip>
#include <limits>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
#include "mtk_lapack_adapter.h"
#include "mtk_glpk_adapter.h"
#include "mtk_grad_ld.h"
Include dependency graph for mtk_grad_ld.cc:
```



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

## **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Grad1D &in)</li>

### 17.63.1 Detailed Description

This class implements a 1D gradient matrix operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm.

#### Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

**Todo** Overload ostream operator as in mtk::Lap1D.

**Todo** Implement creation of ■ w. mtk::BLASAdapter.

Definition in file mtk\_grad\_1d.cc.

## 17.64 mtk\_grad\_1d.cc

```
00001
00015 /*
00016 Copyright (C) 2015, Computational Science Research Center, San Diego State
00017 University. All rights reserved.
00019 Redistribution and use in source and binary forms, with or without modification,
00020 are permitted provided that the following conditions are met:
00021
00022 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00023 and a copy of the modified files should be reported once modifications are
00024 completed. Documentation related to said modifications should be included.
00025
00026 2. Redistributions of source code must be done through direct
00027 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00028
00029 3. Redistributions of source code must retain the above copyright notice, this
00030 list of conditions and the following disclaimer.
00031
00032 4. Redistributions in binary form must reproduce the above copyright notice,
00033 this list of conditions and the following disclaimer in the documentation and/or
00034 other materials provided with the distribution.
00035
00036 5. Usage of the binary form on proprietary applications shall require explicit
00037 prior written permission from the the copyright holders.
00038
00039 6. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00042
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00048
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00061 #include <cmath>
00062 #include <cstring>
00064 #include <iostream>
00065 #include <iomanip>
00066 #include <limits>
00067 #include <algorithm>
00068
00069 #include "mtk tools.h"
00070
00071 #include "mtk_blas_adapter.h"
00072 #include "mtk_lapack_adapter.h"
00073 #include "mtk_glpk_adapter.h'
00074
```

```
00075 #include "mtk_grad_1d.h"
00076
00077 namespace mtk {
00078
00079 std::ostream& operator <<(std::ostream &stream, mtk::Grad1D &in) {
08000
00082
00083
        stream << "gradient_[0] = " << std::setw(9) << in.gradient_[0] << std::endl;</pre>
00084
        stream << "gradient_[1:" << in.order_accuracy_ << "] = ";
00087
        for (auto ii = 1; ii <= in.order_accuracy_; ++ii)</pre>
00088
00089
          stream << std::setw(9) << in.gradient_[ii] << " ";
00090
00091
        stream << std::endl;
00092
00094
00095
        stream << "gradient_[" << in.order_accuracy_ + 1 << ":" <<
          2*in.order_accuracy_ << "] = ";
00096
        for (auto ii = in.order_accuracy_ + 1; ii <= 2*in.</pre>
00097
      order accuracy; ++ii) {
00098
         stream << std::setw(9) << in.gradient_[ii] << " ";
00099
00100
        stream << std::endl;
00101
00103
        int offset{2*in.order_accuracy_ + 1};
00104
00105
        int mm {};
00106
        stream << "gradient_[" << offset + mm << ":" <<
00107
          offset + mm + in.num_bndy_coeffs_ - 1 << "] = ";
00108
00109
        if (in.order_accuracy_ > mtk::kDefaultOrderAccuracy) {
   for (auto ii = 0; ii < in.num_bndy_approxs_; ++ii)</pre>
00110
00111
            for (auto jj = 0; jj < in.num_bndy_coeffs_; jj++) {
  auto value = in.gradient_[offset + (mm)];</pre>
00112
00113
00114
               stream << std::setw(9) << value << " ";
00115
               mm++;
00116
            }
00117
00118
        } else {
           stream << std::setw(9) << in.gradient_[offset + 0] << ' ';
00119
           stream << std::setw(9) << in.gradient_[offset + 1] << ' ';
00120
           stream << std::setw(9) << in.gradient_[offset + 2] << ' ';</pre>
00121
00122
00123
        stream << std::endl;
00124
00125
        return stream;
00126 }
00127 }
00128
00129 mtk::Grad1D::Grad1D():
00130 order_accuracy_(mtk::kDefaultOrderAccuracy),
        dim_null_(),
00131
00132
        num_bndy_approxs_(),
00133
        num_bndy_coeffs_(),
00134
        gradient_length_(),
        minrow_(),
00135
00136
       row_(),
00137
        coeffs_interior_(),
00138
        prem_apps_(),
00139
        weights_crs_(),
00140
        weights_cbs_(),
00141
        mim_bndy_(),
00142
        gradient_(),
00143
        mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00144
00145 mtk::Grad1D::Grad1D(const Grad1D &grad):
00146
       order_accuracy_(grad.order_accuracy_),
00147
        dim_null_(grad.dim_null_),
00148
        num_bndy_approxs_(grad.num_bndy_approxs_),
        num_bndy_coeffs_(grad.num_bndy_coeffs_),
gradient_length_(grad.gradient_length_),
00149
00150
00151
        minrow_(grad.minrow_),
00152
        row (grad.row ),
00153
        coeffs_interior_(grad.coeffs_interior_),
00154
        prem_apps_(grad.prem_apps_),
00155
        weights_crs_(grad.weights_crs_),
00156
        weights_cbs_(grad.weights_cbs_),
00157
        mim_bndy_(grad.mim_bndy_),
00158
        gradient_(grad.gradient_),
```

```
00159
        mimetic_threshold_(grad.mimetic_threshold_) {}
00160
00161 mtk::Grad1D::~Grad1D() {
00162
00163
        delete[] coeffs_interior_;
00164
        coeffs_interior_ = nullptr;
00165
00166
        delete[] prem_apps_;
00167
        prem_apps_ = nullptr;
00168
00169
        delete[] weights_crs_;
00170
        weights_crs_ = nullptr;
00171
00172
        delete[] weights_cbs_;
00173
        weights_cbs_ = nullptr;
00174
00175
        delete[] mim_bndy_;
        mim_bndy_ = nullptr;
00176
00177
00178
        delete[] gradient_;
00179
        gradient_ = nullptr;
00180 }
00181
00182 bool mtk::Grad1D::ConstructGrad1D(int order_accuracy,
      Real mimetic_threshold) {
00183
00184
        #if MTK_DEBUG_LEVEL > 0
00185
        mtk::Tools::Prevent(order_accuracy < 2, __FILE__,</pre>
                                                               __LINE__,
                                                                          __func__);
        mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(mimetic_threshold <= mtk::kZero,</pre>
00186
00187
00188
                                _FILE__, __LINE__, __func__);
00189
        if (order_accuracy >= mtk::kCriticalOrderAccuracyGrad) {
00190
         std::cout << "WARNING: Numerical accuracy is high." << std::endl;</pre>
0.0191
        }
00192
00193
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;
std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;</pre>
00194
00195
00196
        #endif
00197
00198
        order_accuracy_ = order_accuracy;
00199
        mimetic_threshold_ = mimetic_threshold;
00200
00202
00203
        bool abort_construction = ComputeStencilInteriorGrid();
00204
00205
        #if MTK_DEBUG_LEVEL > 0
00206
        if (!abort_construction) {
00207
         std::cerr << "Could NOT complete stage 1." << std::endl;</pre>
00208
          std::cerr << "Exiting..." << std::endl;</pre>
00209
          return false;
00210
00211
        #endif
00212
00213
         // At this point, we already have the values for the interior stencil stored
00214
        // in the coeffs_interior_ array.
00215
00216
        dim_null_ = order_accuracy_/2 - 1;
00217
00218
        num_bndy_approxs_ = dim_null_ + 1;
00219
00220
        #ifdef MTK_PRECISION_DOUBLE
00221
        num\_bndy\_coeffs\_ = (int) (3.0*((mtk::Real) order\_accuracy\_)/2.0);
        #else
00222
00223
        num_bndy_coeffs_ = (int) (3.0f*((mtk::Real) order_accuracy_)/2.0f);
00224
         #endif
00225
00227
00228
        // For this we will follow recommendations given in:
00229
00230
        // http://icl.cs.utk.edu/lapack-forum/viewtopic.php?f=5&t=4506
00231
00232
        // We will compute the QR Factorization of the transpose, as in the
00233
        // following (MATLAB) pseudo-code:
00234
00235
        // [Q,R] = qr(V'); % Full QR as defined in
00236
        // % http://www.stanford.edu/class/ee263/notes/qr_matlab.pdf
00237
00238
        // null-space = Q(:, last (order_accuracy_/2 - 1) columns of Q );
00239
00240
        // However, given the nature of the Vandermonde matrices we've just
```

```
00241
        // computed, they all posses the same null-space. Therefore, we impose the
00242
        // convention of computing the null-space of the first Vandermonde matrix
00243
        // (west boundary).
00244
00245
        // In the case of the gradient, the first Vandermonde system has a unique
00246
        // solution for the case of second-order-accuracy. Ergo, the Vandermonde
00247
        // matrix used to assemble said system, will have an empty null-space.
00248
00249
        // Therefore, we only compute a rational basis for the case of order higher
00250
        // than second.
00251
00252
        if (dim_null_ > 0) {
00253
00254
          abort_construction = ComputeRationalBasisNullSpace();
00255
00256
          #if MTK_DEBUG_LEVEL > 0
00257
          if (!abort_construction) {
00258
            std::cerr << "Could NOT complete stage 2.1." << std::endl;
00259
            std::cerr << "Exiting..." << std::endl;
00260
            return false;
00261
00262
          #endif
00263
        }
00264
00266
00267
        abort_construction = ComputePreliminaryApproximations();
00268
00269
        #if MTK DEBUG LEVEL > 0
00270
        if (!abort_construction) {
00271
          std::cerr << "Could NOT complete stage 2.2." << std::endl;
          std::cerr << "Exiting..." << std::endl;
00272
00273
          return false;
00274
00275
        #endif
00276
00278
00279
        abort_construction = ComputeWeights();
00280
00281
        #if MTK DEBUG LEVEL > 0
00282
        if (!abort_construction) {
         std::cerr << "Could NOT complete stage 2.3." << std::endl;
std::cerr << "Exiting..." << std::endl;</pre>
00283
00284
00285
         return false;
00286
00287
        #endif
00288
00290
00291
        if (dim_null_ > 0) {
00292
00293
          abort_construction = ComputeStencilBoundaryGrid();
00294
00295
          #if MTK_DEBUG_LEVEL > 0
00296
          if (!abort_construction) {
00297
            std::cerr << "Could NOT complete stage 2.4." << std::endl;</pre>
            std::cerr << "Exiting..." << std::endl;
00298
00299
            return false;
00300
00301
          #endif
00302
00303
00305
00306
        // Once we have the following three collections of data:
        // (a) the coefficients for the interior,
00308
             (b) the coefficients for the boundary (if it applies),
             (c) and the weights (if it applies),
00309
00310
        // we will store everything in the output array:
00311
00312
        abort_construction = AssembleOperator();
00313
00314
        #if MTK_DEBUG_LEVEL > 0
00315
        if (!abort_construction) {
          std::cerr << "Could NOT complete stage 3." << std::endl;
std::cerr << "Exiting..." << std::endl;</pre>
00316
00317
00318
          return false;
00319
00320
        #endif
00321
00322
        return true:
00323 }
00324
00325 int mtk::Grad1D::num_bndy_coeffs() const {
```

```
00326
00327
        return num_bndy_coeffs_;
00328 }
00329
00330 mtk::Real *mtk::Grad1D::coeffs_interior() const {
00331
00332
        return coeffs_interior_;
00333 }
00334
00335 mtk::Real *mtk::Grad1D::weights_crs() const {
00337
        return weights_crs_;
00338 }
00339
00340 mtk::Real *mtk::Grad1D::weights_cbs() const {
00341
00342
        return weights cbs ;
00343 }
00344
00345 mtk::DenseMatrix mtk::Grad1D::mim_bndy() const {
00346
00347
        mtk::DenseMatrix xx(dim null , 3*order accuracy /2);
00348
00349
        auto counter = 0;
00350
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
         for(auto jj = 0; jj < 3*order_accuracy_/2; ++jj) {</pre>
00351
            xx.SetValue(ii,jj, gradient_[2*order_accuracy_ + 1 + counter]);
00352
00353
       }
             counter++;
00354
00355
00356
00357
        return xx;
00358 }
00359
00360 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix(
     mtk::Real west,
00361
                                                           mtk::Real east,
00362
                                                           int num_cells_x) {
00363
        int nn{num_cells_x}; // Number of cells on the grid.
00364
00365
00366
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(east < west, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(nn < 3*order_accuracy_ - 2, __FILE__, __LINE__, __func__);</pre>
00367
00368
00369
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00370
00371
00372
        mtk::Real delta_x = (east - west)/((mtk::Real) num_cells_x);
00373
00374
        mtk::Real inv_delta_x{mtk::kOne/delta_x};
00375
        int gg_num_rows = nn + 1;
00376
00377
        int gg_num_cols = nn + 2;
00378
         int elements_per_row = num_bndy_coeffs_;
00379
        int num_extra_rows = order_accuracy_/2;
00380
00381
        // Output matrix featuring sizes for gradient operators.
00382
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00383
00385
00386
        auto ee_index = 0;
00387
        for (auto ii = 0; ii < num_extra_rows; ii++) {</pre>
         auto cc = 0;
00388
          for(auto jj = 0; jj < gg_num_cols; jj++) {</pre>
00389
00390
            if(cc >= elements_per_row) {
00391
              out.SetValue(ii, jj, mtk::kZero);
00392
             } else {
00393
              out.SetValue(ii, jj,
00394
                            gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00395
              cc++;
00396
            }
00397
          }
00398
        }
00399
00401
        for (auto ii = num_extra_rows; ii < gg_num_rows - num_extra_rows; ii++) {</pre>
00402
          auto jj = ii - num_extra_rows + 1;
00403
          for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {
00404
00405
             out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00406
        }
00407
```

```
00408
00410
00411
        ee_index = 0;
00412
        for (auto ii = gg_num_rows - 1; ii >= gg_num_rows - num_extra_rows; ii--) {
00413
00414
          for (auto jj = gg_num_cols - 1; jj >= 0; jj--) {
00415
            if(cc >= elements_per_row) {
00416
              out.SetValue(ii, jj, mtk::kZero);
00417
            } else {
00418
             out.SetValue(ii,jj,
00419
                            -gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00420
              cc++;
00421
            }
00422
00423
        }
00424
00425
        return out;
00426 }
00427
00428 mtk::DenseMatrix mtk::Grad1D::ReturnAsDenseMatrix(const
      UniStgGrid1D &grid) {
00430
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00431
00432
        #if MTK DEBUG LEVEL > 0
00433
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00434
        mtk::Tools::Prevent(nn < 3*order_accuracy_ - 2, __FILE__, __LINE__, __func__);</pre>
00435
00436
        #endif
00437
00438
        mtk::Real inv_delta_x{mtk::kOne/grid.delta_x()};
00439
        int gg_num_rows = nn + 1;
int gg_num_cols = nn + 2;
00440
00441
00442
        int elements_per_row = num_bndy_coeffs_;
00443
        int num_extra_rows = order_accuracy_/2;
00444
00445
        \ensuremath{//} Output matrix featuring sizes for gradient operators.
00446
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00447
00449
00450
        auto ee_index = 0;
00451
        for (auto ii = 0; ii < num_extra_rows; ii++) {</pre>
00452
          auto cc = 0;
00453
          for(auto jj = 0; jj < gg_num_cols; jj++) {</pre>
00454
            if(cc >= elements_per_row) {
00455
              out.SetValue(ii, jj, mtk::kZero);
00456
            } else {
00457
              out.SetValue(ii,jj,
00458
                            gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00459
00460
00461
         }
00462
00463
00465
00466
        for (auto ii = num_extra_rows; ii < gg_num_rows - num_extra_rows; ii++) {</pre>
00467
          auto jj = ii - num_extra_rows + 1;
         for (auto cc = 0; cc < order_accuracy_; cc++, jj++) {
00468
00469
            out.SetValue(ii, jj, coeffs_interior_[cc]*inv_delta_x);
00470
00471
00472
00474
00475
        ee_index = 0;
        for (auto ii = gg_num_rows - 1; ii >= gg_num_rows - num_extra_rows; ii--) {
00477
         auto cc = 0;
00478
          for (auto jj = gg_num_cols - 1; jj >= 0; jj--) {
           if(cc >= elements_per_row) {
00479
              out.SetValue(ii, jj, mtk::kZero);
00480
00481
            } else {
00482
              out.SetValue(ii, jj,
00483
                            -gradient_[2*order_accuracy_ + 1 + ee_index++]*inv_delta_x);
00484
              cc++;
00485
            }
00486
           }
00487
        }
00488
00489
        return out;
00490 }
00491
```

```
00492 bool mtk::Grad1D::ComputeStencilInteriorGrid() {
00493
00495
00496
        mtk::Real* pp{}; // Spatial coordinates to create interior stencil.
00497
00498
00499
          pp = new mtk::Real[order_accuracy_];
00500
        } catch (std::bad_alloc &memory_allocation_exception) {
00501
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00502
             std::endl;
00503
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00504
00505
        memset(pp, mtk::kZero, sizeof(pp[0])*order_accuracy_);
00506
00507
        #ifdef MTK_PRECISION_DOUBLE
00508
        pp[0] = 1.0/2.0 - ((mtk::Real) order_accuracy_)/2.0;
00509
         #else
00510
        pp[0] = 1.0f/2.0f - ((mtk::Real) order_accuracy_)/2.0f;
00511
         #endif
00512
        for (auto ii = 1; ii < order_accuracy_; ++ii) {
    pp[ii] = pp[ii - 1] + mtk::kOne;
}</pre>
00513
00514
00515
00516
00517
        #if MTK DEBUG LEVEL > 0
        std::cout << "pp =" << std::endl;
00518
        for (auto ii = 0; ii < order_accuracy_; ++ii) {
  std::cout << std::setw(12) << pp[ii];</pre>
00519
00520
00521
        std::cout << std::endl << std::endl;</pre>
00522
00523
        #endif
00524
00526
00527
        bool transpose {false};
00528
00529
        mtk::DenseMatrix vander_matrix(pp,order_accuracy_,order_accuracy_,transpose);
00530
00531
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "vander_matrix = " << std::endl;</pre>
00532
        std::cout << vander_matrix << std::endl << std::endl;</pre>
00533
00534
        #endif
00535
00537
00538
00539
          coeffs_interior_ = new mtk::Real[order_accuracy_];
00540
        } catch (std::bad_alloc &memory_allocation_exception)
00541
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00542
            std::endl;
00543
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00544
00545
        memset(coeffs_interior_, mtk::kZero, sizeof(coeffs_interior_[0])*order_accuracy_);
00546
00547
        coeffs_interior_[1] = mtk::kOne;
00548
00549
        \#if MTK_DEBUG_LEVEL > 0
00550
         std::cout << "oo =" << std::endl;
00551
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00552
          std::cout << std::setw(12) << coeffs_interior_[ii] << std::endl;</pre>
00553
00554
        std::cout << std::endl;
00555
        #endif
00556
00558
00559
        int info{mtk::LAPACKAdapter::SolveDenseSystem(vander_matrix,
00560
                                                           coeffs_interior_) };
00561
00562
        #if MTK_DEBUG_LEVEL > 0
00563
        if (!info) {
00564
         std::cout << "System solved! Interior stencil attained!" << std::endl;</pre>
00565
          std::cout << std::endl;
00566
00567
        else {
00568
         std::cerr << "Something wrong solving system! info = " << info << std::endl;
00569
           std::cerr << "Exiting..." << std::endl;</pre>
00570
          return false:
00571
00572
        #endif
00573
00574
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "coeffs_interior_ =" << std::endl;
for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
00575
00576
```

17.64 mtk grad 1d.cc 279

```
00577
          std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
00578
00579
        std::cout << std::endl << std::endl;</pre>
00580
00581
00582
        delete [] pp;
00583
        pp = nullptr;
00584
00585
        return true;
00586 }
00587
00588 bool mtk::Grad1D::ComputeRationalBasisNullSpace(void) {
00589
00591
00592
        mtk::Real* gg{}; // Generator vector for the first Vandermonde matrix.
00593
00594
        trv {
          gg = new mtk::Real[num_bndy_coeffs_];
00595
00596
        } catch (std::bad_alloc &memory_allocation_exception) {
00597
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00598
            std::endl;
00599
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00600
00601
        memset(qq, mtk::kZero, sizeof(qq[0])*num_bndy_coeffs_);
00602
00603
        #ifdef MTK PRECISION DOUBLE
00604
        gg[1] = 1.0/2.0;
00605
        #else
00606
        gg[1] = 1.0f/2.0f;
00607
        #endif
        for (auto ii = 2; ii < num_bndy_coeffs_; ++ii) {
   gg[ii] = gg[ii - 1] + mtk::kOne;</pre>
00608
00609
00610
00611
        #if MTK_DEBUG_LEVEL > 0
00612
        std::cout << "gg =" << std::endl;
00613
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00614
00615
          std::cout << std::setw(12) << gg[ii];
00616
        std::cout << std::endl << std::endl;</pre>
00617
        #endif
00618
00619
00621
00622
        bool tran{true}; // Should I transpose the Vandermonde matrix.
00623
00624
        mtk::DenseMatrix aa_west_t(gg, num_bndy_coeffs_, order_accuracy_ + 1, tran);
00625
00626
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "aa_west_t =" << std::endl;
00627
00628
        std::cout << aa_west_t << std::endl;
00629
00630
00632
00633
       mtk::DenseMatrix qq_t (mtk::LAPACKAdapter::QRFactorDenseMatrix
      (aa_west_t));
00634
00635
        #if MTK_DEBUG_LEVEL > 0
00636
        std::cout << "qq_t = " << std::endl;
00637
        std::cout << qq_t << std::endl;
00638
        #endif
00639
00641
00642
        int kk_num_rows{num_bndy_coeffs_};
00643
        int kk_num_cols{dim_null_};
00644
00645
        mtk::DenseMatrix kk(kk_num_rows, kk_num_cols);
00646
00647
        // In the case of the gradient, even though we must solve for a null-space
        // of dimension 2, we must only extract ONE basis for the kernel.
00648
00649
        // We perform this extraction here:
00650
00651
        int aux {kk num rows - kk num cols};
00652
        for (auto ii = kk_num_rows - kk_num_cols; ii < kk_num_rows; ii++) {</pre>
00653
          aux_--;
00654
          for (auto jj = 0; jj < kk_num_rows; jj++) {</pre>
            kk.data()[jj*kk_num_cols + (kk_num_rows - kk_num_cols - aux_ - 1)] =
qq_t.data()[ii*num_bndy_coeffs_ + jj];
00655
00656
00657
00658
00659
        #if MTK_DEBUG_LEVEL > 0
00660
```

```
std::cout << "kk =" << std::endl;
        std::cout << kk << std::endl;
        std::cout << "kk.num_rows() = " << kk.num_rows() << std::endl;
00663
        std::cout << "kk.num_cols() = " << kk.num_cols() << std::endl;
00664
00665
        std::cout << std::endl;
00666
00667
00669
00670
        // Scale thus requesting that the last entries of the attained basis for the
00671
        // null-space, adopt the pattern we require.
        // Essentially we will implement the following MATLAB pseudo-code:
00672
00673
        // scalers = kk(num_bndy_approxs - (dim_null - 1):num_bndy_approxs,:)\B
        // SK = kk*scalers
00674
00675
        // where SK is the scaled null-space.
00676
00677
        // In this point, we almost have all the data we need correctly allocated
00678
        // in memory. We will create the matrix iden_, and elements we wish to scale in
        // the kk array. Using the concept of the leading dimension, we could just
00679
00680
        // use kk, with the correct leading dimension and that is it. BUT I DO NOT
00681
        // GET how does it work. So I will just create a matrix with the content of
00682
        // this array that we need, solve for the scalers and then scale the
00683
        // whole kk:
00684
00685
        // We will then create memory for that sub-matrix of kk (subk).
00686
00687
        mtk::DenseMatrix subk(dim null , dim null );
00688
00689
        auto zz = 0;
00690
        for (auto ii = order_accuracy_ + 1; ii < num_bndy_coeffs_; ii++) {</pre>
00691
         for (auto jj = 0; jj < dim_null_; jj++) {</pre>
00692
           subk.data()[zz*(dim_null_) + jj] = kk.data()[ii*(dim_null_) + jj];
00693
00694
         zz++;
00695
00696
00697
        #if MTK DEBUG LEVEL > 0
        std::cout << "subk =" << std::endl;
00698
        std::cout << subk << std::endl;
00699
00700
        #endif
00701
00702
        subk.Transpose();
00703
        #if MTK_DEBUG_LEVEL > 0
std::cout << "subk_t =" << std::endl;</pre>
00704
00705
00706
        std::cout << subk << std::endl;</pre>
00707
        #endif
00708
00709
        bool padded{false};
00710
       tran = false;
00711
00712
        mtk::DenseMatrix iden(dim_null_, padded, tran);
00713
        #if MTK_DEBUG_LEVEL > 0
std::cout << "iden =" << std::endl;</pre>
00714
00715
00716
        std::cout << iden << std::endl;
00717
00718
00719
        // Solve the system to compute the scalers.
00720
        // An example of the system to solve, for k = 8, is:
00721
00722
       // subk*scalers = iden or
00723
        // | 0.386018 -0.0339244 -0.129478 | | 1 0 0 |
// | -0.119774 0.0199423 0.0558632 |*scalers = | 0 1 0 |
00724
00725
        // | 0.0155708 -0.00349546 -0.00853182 |
00726
00727
        // Notice this is a nrhs = 3 system.
00728
00729
        // Noteworthy: we do NOT ACTUALLY ALLOCATE space for the scalers... they
00730
        // will be stored in the created identity matrix.
00731
        // Let us first transpose subk (because of LAPACK):
00732
00733
        int info{mtk::LAPACKAdapter::SolveDenseSystem(subk, iden)};
00734
00735
        #if MTK_DEBUG_LEVEL > 0
00736
        if (!info) {
00737
        std::cout << "System successfully solved!" <<
00738
            std::endl;
00739
        } else {
00740
         std::cerr << "Something went wrong solving system! info = " << info <<
00741
            std::endl;
         std::cerr << "Exiting..." << std::endl;
00742
```

```
00743
          return false;
00744
00745
        std::cout << std::endl;
00746
00747
00748
        #if MTK_DEBUG_LEVEL > 0
00749
        std::cout << "Computed scalers:" << std::endl;
00750
        std::cout << iden << std::endl;
00751
00752
00753
        // Multiply the two matrices to attain a scaled basis for null-space.
00754
00755
        rat_basis_null_space_ = mtk::BLASAdapter::RealDenseMM(kk, iden);
00756
00757
        #if MTK_DEBUG_LEVEL > 0
00758
        std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00759
        std::cout << rat_basis_null_space_ << std::endl;</pre>
00760
        #endif
00761
00762
        // At this point, we have a rational basis for the null-space, with the
00763
        // pattern we need! :)
00764
00765
        delete [] qq;
00766
        gg = nullptr;
00767
00768
        return true;
00769 }
00770
00771 bool mtk::Grad1D::ComputePreliminaryApproximations() {
00772
00774
00775
        mtk::Real *gg{}; // Generator vector for the first approximation.
00776
00777
00778
          gg = new mtk::Real[num_bndy_coeffs_];
00779
        } catch (std::bad_alloc &memory_allocation_exception) {
00780
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00781
            std::endl:
00782
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00783
00784
        memset(gg, mtk::kZero, sizeof(gg[0])*num_bndy_coeffs_);
00785
        #ifdef MTK_PRECISION_DOUBLE
00786
00787
        gg[1] = 1.0/2.0;
00788
        #else
00789
        gg[1] = 1.0f/2.0f;
00790
        #endif
00791
        for (auto ii = 2; ii < num_bndy_coeffs_; ++ii) {</pre>
00792
         gg[ii] = gg[ii - 1] + mtk::kOne;
00793
00794
00795
        #if MTK_DEBUG_LEVEL > 0
00796
        std::cout << "gg0 =" << std::endl;
00797
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00798
          std::cout << std::setw(12) << gg[ii];
00799
00800
        std::cout << std::endl << std::endl;
00801
        #endif
00802
00803
        // Allocate 2D array to store the collection of preliminary approximations.
00804
00805
         prem_apps_ = new mtk::Real[num_bndy_coeffs_*num_bndy_approxs_];
00806
        } catch (std::bad_alloc &memory_allocation_exception) {
00807
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00808 std::endl;
00809
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00810
00811
        memset (prem_apps_,
00812
               mtk::kZero,
00813
               sizeof(prem_apps_[0])*num_bndy_coeffs_*num_bndy_approxs_);
00814
00816
00817
        for (auto 11 = 0; 11 < num_bndy_approxs_; ++11) {</pre>
00818
00819
          // Re-check new generator vector for every iteration except for the first.
          #if MTK_DEBUG_LEVEL > 0
00820
00821
          if (11 > 0) {
            std::cout << "gg" << 11 << " =" << std::endl;
00822
            for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00823
00824
              std::cout << std::setw(12) << gg[ii];
00825
```

```
00826
            std::cout << std::endl << std::endl;</pre>
00827
00828
          #endif
00829
00831
00832
          bool transpose{false};
00833
00834
          mtk::DenseMatrix aa(gg,
00835
                                num_bndy_coeffs_, order_accuracy_ + 1,
00836
                                transpose);
00837
00838
          #if MTK_DEBUG_LEVEL > 0
00839
          std::cout << "aa_" << 11 << " =" << std::endl;
          std::cout << aa << std::endl;
00840
00841
          #endif
00842
00844
00845
          mtk::Real *ob{};
00846
00847
          auto ob_ld = num_bndy_coeffs_;
00848
00849
00850
            ob = new mtk::Real[ob_ld];
00851
          } catch (std::bad_alloc &memory_allocation_exception) {
00852
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00853
              std::endl;
00854
            std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00855
00856
          memset(ob, mtk::kZero, sizeof(ob[0])*ob_ld);
00857
00858
          ob[1] = mtk::kOne;
00859
          #if MTK_DEBUG_LEVEL > 0
std::cout << "ob = " << std::endl << std::endl;</pre>
00860
00861
          for (auto ii = 0; ii < ob_ld; ++ii) {
00862
00863
            std::cout << std::setw(12) << ob[ii] << std::endl;
00864
00865
          std::cout << std::endl;
00866
          #endif
00867
00869
00870
          // However, this is an under-determined system of equations. So we can not
00871
          // use the same LAPACK routine (dgesv_). We will instead use dgels_, through
00872
          // our LAPACKAdapter class.
00873
00874
          int info_{
00875
            mtk::LAPACKAdapter::SolveRectangularDenseSystem(aa, ob
      , ob_ld)};
00876
00877
          #if MTK_DEBUG_LEVEL > 0
00878
          if (!info_) +
00879
            std::cout << "System successfully solved!" << std::endl << std::endl;</pre>
00880
00881
            std::cerr << "Error solving system! info = " << info_ << std::endl;</pre>
00882
00883
          #endif
00884
00885
          #if MTK_DEBUG_LEVEL > 0
00886
          std::cout << "ob =" << std::endl;
00887
          for (auto ii = 0; ii < ob_ld; ++ii) {</pre>
           std::cout << std::setw(12) << ob[ii] << std::endl;
00888
00889
00890
          std::cout << std::endl;
00891
          #endif
00892
00894
00895
          // This implies a DAXPY operation. However, we must construct the arguments
00896
          // for this operation.
00897
00899
          // Save them into the ob_bottom array:
00900
00901
          Real *ob bottom{}; // Bottom part of the attained kernel used to scale it.
00902
00903
          trv {
00904
            ob_bottom = new mtk::Real[dim_null_];
00905
          } catch (std::bad_alloc &memory_allocation_exception) {
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00906
00907
              std::endl;
00908
            std::cerr << memory allocation exception.what() << std::endl;</pre>
00909
00910
          memset(ob_bottom, mtk::kZero, sizeof(ob_bottom[0])*dim_null_);
```

```
00911
00912
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00913
            ob_bottom[(dim_null_ - 1) - ii] = ob[num_bndy_coeffs_ - ii - 1];
00914
00915
00916
          #if MTK_DEBUG_LEVEL > 0
00917
          std::cout << "ob_bottom =" << std::endl;</pre>
00918
          for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
00919
            std::cout << std::setw(12) << ob_bottom[ii] << std::endl;</pre>
00920
00921
          std::cout << std::endl;</pre>
00922
          #endif
00923
00925
00926
          // We must computed an scaled ob, sob, using the scaled null-space in
00927
          // rat_basis_null_space_.
00928
          // Such operation is: sob = ob - rat_basis_null_space_*ob_bottom
00929
          // or:
                                  ob = -1.0*rat_basis_null_space_*ob_bottom + 1.0*ob
00930
          // thus:
                                           a*A
                                                  * X
00931
00932
          #if MTK DEBUG LEVEL > 0
00933
          std::cout << "Rational basis for the null-space:" << std::endl;</pre>
00934
          std::cout << rat_basis_null_space_ << std::endl;</pre>
00935
          #endif
00936
00937
          mtk::Real alpha{-mtk::kOne};
00938
          mtk::Real beta{mtk::kOne};
00939
          mtk::BLASAdapter::RealDenseMV(alpha, rat_basis_null_space_,
00940
00941
                                          ob_bottom, beta, ob);
00942
00943
          #if MTK_DEBUG_LEVEL > 0
          std::cout << "scaled ob:" << std::endl;
00944
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00945
00946
            std::cout << std::setw(12) << ob[ii] << std::endl;
00947
00948
          std::cout << std::endl;
00949
          #endif
00950
00951
          \ensuremath{//} We save the recently scaled solution, into an array containing these.
00952
          // We can NOT start building the pi matrix, simply because I want that part
00953
          // to be separated since its construction depends on the algorithm we want
00954
          \ensuremath{//} to implement.
00955
00956
          prem_apps_[ii*num_bndy_approxs_ + 11] = ob[ii];
}
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00957
00958
00959
00960
          // After the first iteration, simply shift the entries of the last
00961
          // generator vector used:
00962
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00963
            gg[ii]--;
00964
00965
00966
          // Garbage collection for this loop:
00967
          delete[] ob;
00968
          ob = nullptr;
00969
          delete[] ob_bottom;
00970
00971
          ob_bottom = nullptr;
00972
        } // End of: for (ll = 0; ll < dim_null; ll++);
00973
00974
        \#if MTK_DEBUG_LEVEL > 0
00975
        std::cout << "Matrix post-scaled preliminary apps: " << std::endl;</pre>
00976
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
00977
         for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {</pre>
00978
            std::cout << std::setw(12) << prem_apps_[ii*num_bndy_approxs_ + jj];
00979
00980
          std::cout << std::endl;
00981
00982
        std::cout << std::endl;
00983
        #endif
00984
00985
        delete[] gg;
        gg = nullptr;
00986
00987
00988
        return true;
00989 1
00990
00991 bool mtk::Grad1D::ComputeWeights() {
00992
```

```
00993
         // Matrix to copmpute the weights as in the CRSA.
00994
        mtk::DenseMatrix pi(num_bndy_coeffs_, num_bndy_coeffs_ - 1);
00995
00997
00998
         // Assemble the pi matrix using:
00999
        // 1. The collection of scaled preliminary approximations.
01000
        // 2. The collection of coefficients approximating at the interior.
01001
        // 3. The scaled basis for the null-space.
01002
01003
        // 1.1. Process array of scaled preliminary approximations.
01004
01005
        // These are queued in scaled_solutions. Each one of these, will be a column
01006
         // of the pi matrix:
01007
         for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
          for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {
   pi.data()[ii*(2*(num_bndy_approxs_ - 1) + (order_accuracy_/2 + 1)) + jj] =</pre>
01008
01009
01010
               prem_apps_[ii*num_bndy_approxs_ + jj];
01011
          }
01012
        }
01013
01014
        // 1.2. Add columns from known stencil approximating at the interior.
01015
01016
         // However, these must be padded by zeros, according to their position in the
01017
        // final pi matrix:
01018
         auto mm = 1:
01019
         for (auto jj = num_bndy_approxs_; jj < order_accuracy_; ++jj) {</pre>
          for (auto ii = 0; ii < order_accuracy_; ++ii) {
    auto de = (ii + mm) * (2*(num_bndy_approxs_ - 1) +
01020
01021
               (order_accuracy_/2 + 1)) + jj;
01022
01023
             pi.data()[de] = coeffs_interior_[ii];
01024
01025
          ++mm;
01026
        }
01027
01028
        rat_basis_null_space_.OrderColMajor();
01029
01030
        #if MTK_DEBUG_LEVEL > 0
std::cout << "Rational basis for the null-space (col. major):" << std::endl;</pre>
01031
01032
         std::cout << rat_basis_null_space_ << std::endl;</pre>
01033
         #endif
01034
01035
         \ensuremath{//} 1.3. Add final set of columns: rational basis for null-space.
01036
01037
         for (auto jj = dim_null_ + (order_accuracy_/2 + 1);
01038
              jj < num_bndy_coeffs_ - 1; ++jj)</pre>
01039
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01040
           auto og =
01041
               (jj - (dim_null_ + (order_accuracy_/2 + 1)))*num_bndy_coeffs_ + ii;
01042
             auto de = ii*(2*dim_null_ + (order_accuracy_/2 + 1)) + jj;
01043
             pi.data()[de] = rat_basis_null_space_.data()[og];
01044
01045
01046
01047
         #if MTK_DEBUG_LEVEL >0
01048
         std::cout << "coeffs_interior_ =" << std::endl;
01049
         for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01050
          std::cout << std::setw(12) << coeffs_interior_[ii];</pre>
01051
01052
        std::cout << std::endl << std::endl;</pre>
01053
        #endif
01054
         #if MTK_DEBUG_LEVEL >0
01055
01056
         std::cout << "Constructed pi matrix for CRS Algorithm: " << std::endl;</pre>
01057
         std::cout << pi << std::endl;
01058
         #endif
01059
01061
01062
        // This imposes the mimetic condition.
01063
01064
        mtk::Real *hh{}; // Right-hand side to compute weights in the C{R,B}SA.
01065
01066
01067
          hh = new mtk::Real[num_bndy_coeffs_];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
01068
01069
01070
             std::endl;
01071
          std::cerr << memory allocation exception.what() << std::endl;</pre>
01072
01073
        memset(hh, mtk::kZero, sizeof(hh[0])*num_bndy_coeffs_);
01074
01075
       hh[0] = -mtk::kOne;
```

17.64 mtk grad\_1d.cc 285

```
for (auto ii = (order_accuracy_/2 + 2 - 1); ii < num_bndy_coeffs_; ++ii) {</pre>
01077
         auto aux_xx = mtk::kZero;
01078
          for (auto jj = 0; jj < ((ii - (order_accuracy_/2 - 1)) - 1); ++jj) {
           aux_xx += coeffs_interior_[jj];
01079
01080
01081
          hh[ii] = -mtk::kOne*aux_xx;
01082
01083
01085
01086
        // That is, we construct a system, to solve for the weights.
01087
01088
        // Once again we face the challenge of solving with LAPACK. However, for the
01089
        // CRSA, this matrix PI is over-determined, since it has more rows than
01090
        // unknowns. However, according to the theory, the solution to this system is
01091
        // unique. We will use dgels_.
01092
01093
        try {
         weights_cbs_ = new mtk::Real[num_bndy_coeffs_];
01094
01095
        } catch (std::bad_alloc &memory_allocation_exception) {
01096
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01097
            std::endl;
01098
          std::cerr << memory allocation exception.what() << std::endl;</pre>
01099
01100
        memset (weights cbs , mtk::kZero, sizeof (weights cbs [0]) *num bndy coeffs );
01101
        int weights_ld{pi.num_cols() + 1};
01102
01103
01104
        // Preserve hh.
        std::copy(hh, hh + weights_ld, weights_cbs_);
01105
01106
01107
        pi.Transpose();
01108
01109
        int info{
01110
         mtk::LAPACKAdapter::SolveRectangularDenseSystem(pi,
                                                            weights_cbs_, weights_ld)
01111
01112
01113
01114
        #if MTK_DEBUG_LEVEL > 0
01115
        if (!info) {
         std::cout << "System successfully solved!" << std::endl << std::endl;</pre>
01116
01117
        } else {
          std::cerr << "Error solving system! info = " << info << std::endl;</pre>
01118
01119
01120
        #endif
01121
01122
        #if MTK_DEBUG_LEVEL > 0
01123
        std::cout << "hh =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01124
01125
         std::cout << std::setw(11) << hh[ii] << std::endl;
01126
01127
        std::cout << std::endl;
01128
01129
01130
        // Preserve the original weights for research.
01131
01132
01133
         weights_crs_ = new mtk::Real[num_bndy_coeffs_];
01134
        } catch (std::bad_alloc &memory_allocation_exception) {
01135
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01136
            std::endl;
01137
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01138
01139
        memset(weights_crs_, mtk::kZero, sizeof(weights_crs_[0])*num_bndy_coeffs_);
01140
01141
        std::copy(weights_cbs_, weights_cbs_ + (weights_ld - 1), weights_crs_);
01142
01143
        #if MTK_DEBUG_LEVEL > 0
01144
        std::cout << "weights_CRSA + lambda =" << std::endl;
        for (auto ii = 0; ii < weights_ld - 1; ++ii) {</pre>
01145
01146
         std::cout << std::setw(12) << weights_crs_[ii] << std::endl;</pre>
01147
01148
        std::cout << std::endl;
01149
        #endif
01150
01152
        if (order_accuracy_ >= mtk::kCriticalOrderAccuracyGrad) {
01153
01154
01155
          int minrow {std::numeric limits<int>::infinity() };
01156
         mtk::Real norm{mtk::BLASAdapter::RealNRM2(weights cbs ,
01157
      order_accuracy_) };
```

```
01158
           mtk::Real minnorm{std::numeric_limits<mtk::Real>::infinity()};
01159
01161
01162
           mtk::DenseMatrix phi(order_accuracy_ + 1, order_accuracy_);
01163
01164
           // 6.1. Insert preliminary approximations to first set of columns.
01165
01166
           for (auto ii = 0; ii < order_accuracy_ + 1; ++ii) {</pre>
01167
             for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {</pre>
               phi.data()[ii*(order_accuracy_) + jj] =
01168
                 prem_apps_[ii*num_bndy_approxs_ + jj];
01170
01171
           }
01172
01173
           // 6.2. Skip a column and negate preliminary approximations.
01174
01175
           for (auto jj = 0; jj < order_accuracy_ + 1; jj++) {</pre>
01176
             for (auto ii = 1; ii < num_bndy_approxs_; ii++) {</pre>
               auto de = (ii+ order_accuracy_ - num_bndy_approxs_+ jj*order_accuracy_);
auto og = (num_bndy_approxs_ - ii + (jj)*num_bndy_approxs_);
01177
01178
01179
               phi.data()[de] = -prem_apps_[og];
01180
01181
01182
           // 6.3. Flip negative columns up-down.
01183
01184
           for (auto ii = 0; ii < order_accuracy_/2; ii++) {</pre>
01185
             for (auto jj = num_bndy_approxs_ + 1; jj < order_accuracy_; jj++) {</pre>
01186
               auto aux = phi.data()[ii*order_accuracy_ + jj];
01187
               phi.data()[ii*order_accuracy_ + jj] =
   phi.data()[(order_accuracy_ - ii)*order_accuracy_ + jj];
phi.data()[(order_accuracy_ - ii)*order_accuracy_ + jj] = aux;
01188
01189
01190
01191
01192
01193
           // 6.4. Insert stencil.
01194
01195
01196
           auto mm = 0:
01197
           for (auto jj = num_bndy_approxs_; jj < num_bndy_approxs_ + 1; jj++) {</pre>
01198
             for (auto ii = 0; ii < order_accuracy_ + 1; ii++) {</pre>
01199
               if (ii == 0) {
01200
                 phi.data()[jj] = 0.0;
               } else {
01201
01202
                  phi.data()[(ii + mm)*order_accuracy_ + jj] = coeffs_interior_[ii - 1];
01203
01204
             }
01205
             mm++;
01206
           }
01207
01208
           #if MTK_DEBUG_LEVEL > 0
01209
           std::cout << "phi =" << std::endl;
01210
           std::cout << phi << std::endl;
01211
01212
01214
01215
           mtk::Real *lamed{}; // Used to build big lambda.
01216
01217
           try {
01218
             lamed = new mtk::Real[num_bndy_approxs_ - 1];
           } catch (std::bad_alloc &memory_allocation_exception) {
01219
            std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01220
01221
01222
             std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01223
01224
           memset(lamed, mtk::kZero, sizeof(lamed[0])*(num_bndy_approxs_ - 1));
01225
01226
           for (auto ii = 0; ii < num_bndy_approxs_ - 1; ++ii) {</pre>
01227
             lamed[ii] = hh[ii + order_accuracy_ + 1] ;
01228
01229
01230
           #if MTK_DEBUG_LEVEL > 0
           std::cout << "lamed =" << std::endl;</pre>
01231
           for (auto ii = 0; ii < num_bndy_approxs_ - 1; ++ii) {
  std::cout << std::setw(12) << lamed[ii] << std::endl;</pre>
01232
01233
01234
01235
           std::cout << std::endl;
01236
           #endif
01237
           for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01238
             mtk::Real temp = mtk::kZero;
01239
01240
             for(auto jj = 0; jj < num_bndy_approxs_ - 1; ++jj) {</pre>
```

17.64 mtk grad 1d.cc 287

```
01241
              temp = temp +
01242
                lamed[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01243
01244
            hh[ii] = hh[ii] - temp;
01245
01246
01247
          #if MTK_DEBUG_LEVEL > 0
01248
          std::cout << "big_lambda =" << std::endl;</pre>
01249
          for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01250
            std::cout << std::setw(12) << hh[ii] << std::endl;
01251
01252
          std::cout << std::endl;</pre>
01253
          #endif
01254
01256
01257
          int copy_result{}; // Should I replace the solution... not for now.
01258
01259
          mtk::Real normerr_; // Norm of the error for the solution on each row.
01260
01261
          for(auto row_= 0; row_ < order_accuracy_ + 1; ++row_) {</pre>
            normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
01262
      data(),
01263
                                                                    order_accuracy_ + 1,
01264
                                                                   order accuracy .
01265
                                                                    order_accuracy_,
01266
                                                                   hh,
01267
                                                                    weights_cbs_,
01268
                                                                    row_,
                                                                   mimetic_threshold_,
01269
01270
                                                                   copy_result);
01271
            mtk::Real aux{normerr /norm};
01272
01273
            #if MTK DEBUG LEVEL>0
            std::cout << "Relative norm: " << aux << " " << std::endl;
01274
01275
            std::cout << std::endl;
01276
            #endif
01277
01278
            if (aux < minnorm) {</pre>
01279
              minnorm = aux;
01280
              minrow_= row_;
01281
01282
01283
01284
          #if MTK_DEBUG_LEVEL > 0
01285
          std::cout << "weights_CBSA + lambda (after brute force search):" <<</pre>
01286
            std::endl:
01287
          for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01288
            std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01289
01290
          std::cout << std::endl;
01291
          #endif
01292
01294
01295
          \ensuremath{//} After we know which row yields the smallest relative norm that row is
01296
          // chosen to be the objective function and the result of the optimizer is
01297
          // chosen to be the new weights_.
01298
01299
          \#if MTK_DEBUG_LEVEL > 0
01300
          std::cout << "Minimum Relative Norm " << minnorm << " found at row " <<
01301
            minrow_ + 1 << std::endl;
01302
          std::cout << std::endl;
01303
          #endif
01304
01305
          copy_result = 1;
          normerr_ = mtk::GLPKAdapter::SolveSimplexAndCompare(phi.
01306
      data(),
01307
                                                                 order_accuracy_ + 1,
01308
                                                                 order_accuracy_,
01309
                                                                 order accuracy ,
01310
                                                                 hh,
01311
                                                                 weights_cbs_,
01312
                                                                 minrow_,
01313
                                                                 mimetic_threshold_,
01314
                                                                 copy_result);
01315
          mtk::Real aux_{normerr_/norm};
          #if MTK_DEBUG_LEVEL > 0
01316
          std::cout << "Relative norm: " << aux << std::endl;
01317
01318
          std::cout << std::endl;
01319
          #endif
01320
01321
          delete [] lamed;
```

```
01322
         lamed = nullptr;
01323
       }
01324
01325
        delete [] hh;
01326
        hh = nullptr;
01327
01328
        return true;
01329 }
01330
01331 bool mtk::Grad1D::ComputeStencilBoundaryGrid(void) {
01333
        #if MTK_DEBUG_LEVEL > 0
01334
        std::cout << "weights_* + lambda =" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_ - 1; ++ii) {</pre>
01335
01336
          std::cout << std::setw(12) << weights_cbs_[ii] << std::endl;</pre>
01337
01338
        std::cout << std::endl;
01339
        #endif
01340
01342
01343
        mtk::Real *lambda{}; // Collection of bottom values from weights .
01344
01345
        trv {
01346
          lambda = new mtk::Real[dim_null_];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<</pre>
01347
01348
            std::endl:
01349
01350
          std::cerr << memory allocation exception.what() << std::endl;</pre>
01351
01352
        memset(lambda, mtk::kZero, sizeof(lambda[0])*dim_null_);
01353
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01354
01355
          lambda[ii] = weights_cbs_[order_accuracy_ + ii];
01356
01357
01358
        #if MTK DEBUG LEVEL > 0
        std::cout << "lambda =" << std::endl;
01359
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01360
01361
          std::cout << std::setw(12) << lambda[ii] << std::endl;
01362
01363
        std::cout << std::endl;
01364
        #endif
01365
01367
01368
        mtk::Real *alpha{}; // Collection of alpha values.
01369
01370
01371
          alpha = new mtk::Real[dim_null_];
01372
        } catch (std::bad_alloc &memory_allocation_exception) {
01373
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01374
             std::endl;
01375
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01376
01377
        memset(alpha, mtk::kZero, sizeof(alpha[0])*dim_null_);
01378
01379
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01380
         alpha[ii] = lambda[ii]/weights_cbs_[ii] ;
01381
01382
        #if MTK_DEBUG_LEVEL > 0
01383
        std::cout << "alpha =" << std::endl;</pre>
01384
01385
        for (auto ii = 0; ii < dim_null_; ++ii) {</pre>
01386
          std::cout << std::setw(12) << alpha[ii] << std::endl;</pre>
01387
01388
        std::cout << std::endl;
01389
        #endif
01390
01392
        try {
01393
01394
          mim_bndy_ = new mtk::Real[num_bndy_coeffs_*num_bndy_approxs_];
01395
        } catch (std::bad_alloc &memory_allocation_exception) {
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01396
01397
            std::endl;
01398
          std::cerr << memory allocation exception.what() << std::endl;
01399
01400
        memset (mim_bndy_,
01401
               mtk::kZero,
01402
                sizeof(mim_bndy_[0])*num_bndy_coeffs_*num_bndy_approxs_);
01403
01404
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01405
          for (auto jj = 0; jj < (num_bndy_approxs_ - 1); ++jj) {</pre>
```

17.64 mtk\_grad\_1d.cc 289

```
01406
            mim_bndy_[ii*num_bndy_approxs_ + jj] =
01407
              prem_apps_[ii*num_bndy_approxs_ + jj] +
01408
              alpha[jj]*rat_basis_null_space_.data()[jj*num_bndy_coeffs_ + ii];
01409
01410
01411
01412
        for(auto ii = 0; ii < num_bndy_coeffs_; ++ii) {</pre>
01413
         mim_bndy_[ii*num_bndy_approxs_ + (num_bndy_approxs_ - 1)] =
01414
            prem_apps_[ii*num_bndy_approxs_ + (num_bndy_approxs_ - 1)];
01415
01416
01417
        \#if MTK_DEBUG_LEVEL > 0
01418
        std::cout << "Collection of mimetic approximations:" << std::endl;
        for (auto ii = 0; ii < num_bndy_coeffs_; ++ii) +</pre>
01420
          for (auto jj = 0; jj < num_bndy_approxs_; ++jj) {</pre>
01421
           std::cout << std::setw(13) << mim_bndy_[ii*num_bndy_approxs_ + jj];
01422
01423
          std::cout << std::endl;
01424
01425
        std::cout << std::endl;
01426
        #endif
01427
        delete[] lambda;
01428
01429
        lambda = nullptr:
01430
01431
        delete[] alpha;
01432
        alpha = nullptr;
01433
01434
       return true;
01435 }
01436
01437 bool mtk::Grad1D::AssembleOperator(void) {
01438
01439
        // The output array will have this form:
01440
        // 1. The first entry of the array will contain the used order kk.
        //\ \mbox{2.} The second entry of the array will contain the collection of
01441
01442
        // approximating coefficients for the interior of the grid.
01443
        \ensuremath{//} 3. The third entry will contain a collection of weights.
01444
        // 4. The next dim_null - 1 entries will contain the collections of
01445
        \ensuremath{//} approximating coefficients for the west boundary of the grid.
01446
01447
        gradient_length_ = 1 + order_accuracy_ + order_accuracy_ +
01448
          num_bndy_approxs_*num_bndy_coeffs_;
01449
01450
        \#if MTK_DEBUG_LEVEL > 0
01451
        std::cout << "gradient_length_ = " << gradient_length_ << std::endl;</pre>
01452
        #endif
01453
01454
01455
          gradient_ = new mtk::Real[gradient_length_];
01456
        } catch (std::bad_alloc &memory_allocation_exception) {
01457
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
01458
            std::endl;
01459
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
01460
01461
        memset(gradient_, mtk::kZero, sizeof(gradient_[0])*gradient_length_);
01462
01464
01465
        gradient_[0] = order_accuracy_;
01466
01469
01470
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
01471
         gradient_[ii + 1] = coeffs_interior_[ii];
01472
01473
01475
01476
        for (auto ii = 0; ii < order_accuracy_; ++ii) {</pre>
         gradient_[(order_accuracy_ + 1) + ii] = weights_cbs_[ii];
01477
01478
01479
01482
        int offset{2*order_accuracy_ + 1};
01483
01484
01485
        int aux {}; // Auxiliary variable.
01486
        if (order_accuracy_ > mtk::kDefaultOrderAccuracy) {
01487
          for (auto ii = 0; ii < num_bndy_approxs_ ; ii++) {</pre>
01488
            for (auto jj = 0; jj < num_bndy_coeffs_; jj++) {</pre>
01489
01490
              gradient_[offset + aux] = mim_bndy_[jj*num_bndy_approxs_ + ii];
01491
              aux++;
01492
```

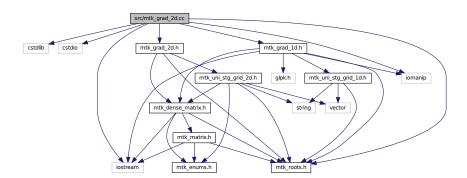
```
01493
01494
        } else {
01495
          gradient_[offset + 0] = prem_apps_[0];
01496
          gradient_[offset + 1] = prem_apps_[1];
01497
         gradient_[offset + 2] = prem_apps_[2];
01498
01499
01500
       #if MTK_DEBUG_LEVEL > 0
01501
        std::cout << "1D " << order_accuracy_ << "-order grad built!" << std::endl;
01502
        std::cout << std::endl;
01503
01504
01505
        return true;
01506 }
```

# 17.65 src/mtk\_grad\_2d.cc File Reference

Implements the class Grad2D.

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_grad_ld.h"
#include "mtk_grad_2d.h"
```

Include dependency graph for mtk\_grad\_2d.cc:



### 17.65.1 Detailed Description

This class implements a 2D gradient operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CB-SA).

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_grad\_2d.cc.

17.66 mtk grad 2d.cc 291

## 17.66 mtk\_grad\_2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice, 00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059
00060 #include <iostream>
00061 #include <iomanip>
00063 #include "mtk roots.h"
00064 #include "mtk_grad_1d.h"
00065 #include "mtk_grad_2d.h"
00067 mtk::Grad2D::Grad2D():
00068
       order_accuracy_(),
        mimetic_threshold_() {}
00069
00071 mtk::Grad2D::Grad2D(const Grad2D &grad):
00072
       order_accuracy_(grad.order_accuracy_),
00073
        mimetic_threshold_(grad.mimetic_threshold_) {}
00074
00075 mtk::Grad2D::~Grad2D() {}
00076
00077 mtk::DenseMatrix mtk::Grad2D::ConstructGrad2D(const
      mtk::UniStgGrid2D &grid,
00078
                                                       int order accuracy,
00079
                                                       mtk::Real mimetic_threshold) {
00080
        int NumCellsX = grid.num_cells_x();
00081
        int NumCellsY = grid.num_cells_y();
00082
00083
        int mx = NumCellsX + 1; // Gx vertical dimension int nx = NumCellsX + 2; // Gx horizontal dimension int my = NumCellsY + 1; // Gy vertical dimension
00084
00085
00086
```

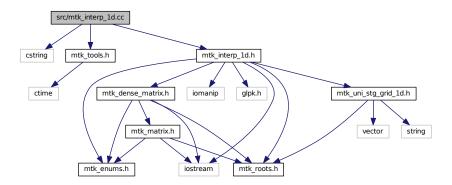
```
00087
        int ny = NumCellsY + 2; // Gy horizontal dimension
00088
00089
        mtk::Grad1D grad;
00090
00091
        bool info = grad.ConstructGrad1D(order_accuracy, mimetic_threshold);
00092
00093
00094
          std::cerr << "Mimetic grad could not be built." << std::endl;
00095
00096
00097
        auto West = grid.west_bndy_x();
00098
        auto East = grid.east_bndy_x();
00099
        auto South = grid.south_bndy_y();
        auto North = grid.east_bndy_x();
00101
00102
        mtk::UniStgGrid1D grid_x(West, East, NumCellsX);
00103
        mtk::UniStgGrid1D grid_y (South, North, NumCellsY);
00104
00105
        mtk::DenseMatrix Gx(grad.ReturnAsDenseMatrix(grid_x));
00106
        mtk::DenseMatrix Gy(grad.ReturnAsDenseMatrix(grid_y));
00107
00108
        bool padded{true};
00109
        bool transpose{true};
00110
00111
        mtk::DenseMatrix TIx(NumCellsX, padded, transpose);
00112
        mtk::DenseMatrix TIy (NumCellsY, padded, transpose);
00113
        mtk::DenseMatrix Gxy (mtk::DenseMatrix::Kron(TIy, Gx));
00114
0.0115
        mtk::DenseMatrix Gyx(mtk::DenseMatrix::Kron(Gy, TIx));
00116
       #if MTK_DEBUG_LEVEL > 0
std::cout << "Gx :" << mx << "by " << nx << std::endl;</pre>
00117
00118
        std::cout << "Transpose Iy : " << NumCellsY<< " by " << ny << std::endl; std::cout << "Gy :" << my << "by " << ny << std::endl;
00119
00120
        std::cout << "Transpose Ix : " << NumCellsX<< " by " << nx << std::endl;
00121
        std::cout << "Kronecker dimensions Grad 2D" <<</pre>
00122
00123
        mx*NumCellsY + my*NumCellsX << " by " << nx*ny <<std::endl;</pre>
00124
00125
00126
        mtk::DenseMatrix G2D(mx*NumCellsY + my*NumCellsX, nx*ny);
00127
00128
        for(auto ii = 0; ii < nx*ny; ii++)</pre>
         for(auto jj = 0; jj < mx*NumCellsY; jj++) {</pre>
00129
00130
            G2D.SetValue(jj,ii, Gxy.GetValue(jj,ii));
00131
00132
          for(auto kk = 0; kk < my*NumCellsX; kk++) {</pre>
00133
             G2D.SetValue(kk + mx*NumCellsY, ii, Gyx.GetValue(kk,ii));
00134
00135
00136
00137
        gradient_ = G2D;
00138
00139
        return gradient_;
00140 }
00141
00142 mtk::DenseMatrix mtk::Grad2D::ReturnAsDenseMatrix() {
00143
00144
        return gradient_;
00145 }
```

# 17.67 src/mtk interp 1d.cc File Reference

Includes the implementation of the class Interp1D.

```
#include <cstring>
#include "mtk_tools.h"
#include "mtk_interp_1d.h"
```

Include dependency graph for mtk\_interp\_1d.cc:



### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Interp1D &in)</li>

## 17.67.1 Detailed Description

This class implements a 1D interpolation operator.

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

: Johnny Corbino - jcorbino at mail dot sdsu dot edu

Definition in file mtk\_interp\_1d.cc.

# 17.68 mtk\_interp\_1d.cc

```
00001
00012 /*
00013 Copyright (C) 2015, Computational Science Research Center, San Diego State
00014 University. All rights reserved.
00015
00016 Redistribution and use in source and binary forms, with or without modification,
00017 are permitted provided that the following conditions are met:
00018
00019 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00020 and a copy of the modified files should be reported once modifications are
00021 completed. Documentation related to said modifications should be included.
00022
00023 2. Redistributions of source code must be done through direct
00024 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
```

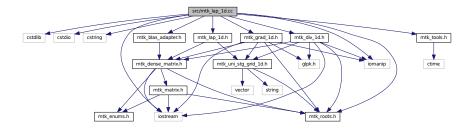
```
00026 3. Redistributions of source code must retain the above copyright notice, this
00027 list of conditions and the following disclaimer.
00028
00029 4. Redistributions in binary form must reproduce the above copyright notice,
00030 this list of conditions and the following disclaimer in the documentation and/or
00031 other materials provided with the distribution.
00033 5. Usage of the binary form on proprietary applications shall require explicit
00034 prior written permission from the the copyright holders.
00036 6. Neither the name of the copyright holder nor the names of its contributors
00037 may be used to endorse or promote products derived from this software without
00038 specific prior written permission.
00040 The copyright holders provide no reassurances that the source code provided does
00041 not infringe any patent, copyright, or any other intellectual property rights of
00042 third parties. The copyright holders disclaim any liability to any recipient for
00043 claims brought against recipient by any third party for infringement of that
00044 parties intellectual property rights.
00046 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00047 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00048 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00049 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00050 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00051 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00052 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00053 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00054 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00055 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00056 */
00057
00058 #include <cstring>
00059
00060 #include "mtk tools.h"
00061
00062 #include "mtk interp 1d.h"
00063
00064 namespace mtk {
00065
00066 std::ostream& operator <<(std::ostream &stream, mtk::Interp1D &in) {
00067
00069
00070
        stream << "coeffs_interior_[1:" << in.order_accuracy_ << "] = ";
00071
        for (auto ii = 0; ii < in.order_accuracy_; ++ii) {</pre>
00072
          stream << std::setw(9) << in.coeffs_interior_[ii] << " ";</pre>
00073
00074
        stream << std::endl;
00075
00076
        return stream;
00077 }
00078 }
00079
00080 mtk::Interp1D::Interp1D():
00081 dir_interp_(mtk::SCALAR_TO_VECTOR),
        order_accuracy_(mtk::kDefaultOrderAccuracy),
00082
00083
        coeffs_interior_(nullptr) {}
00084
00085 mtk::Interp1D::Interp1D(const Interp1D &interp):
00086
       dir_interp_(interp.dir_interp_),
        order_accuracy_(interp.order_accuracy_),
00088
        coeffs_interior_(interp.coeffs_interior_) {}
00089
00090 mtk::Interp1D::~Interp1D() {
00091
        delete[] coeffs_interior_;
00093
       coeffs_interior_ = nullptr;
00094 }
00095
00096 bool mtk::Interp1D::ConstructInterp1D(int order_accuracy,
     mtk::DirInterp dir) {
00097
00098
        #if MTK_DEBUG_LEVEL > 0
       mtk::Tools::Prevent(order_accuracy < 2, __FILE_, __LINE_, __func__);
mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE_, __LINE_, __func__);</pre>
00099
00100
       mtk::Tools::Prevent(dir < mtk::SCALAR_TO_VECTOR &&
00101
                            dir > mtk::VECTOR_TO_SCALAR,
00102
00103
                             __FILE__, __LINE__, __func__);
00104
        std::cout << "order_accuracy_ = " << order_accuracy << std::endl;</pre>
00105
00106
        #endif
```

```
00107
00108
        order_accuracy_ = order_accuracy;
00109
00111
00112
        try {
00113
         coeffs_interior_ = new mtk::Real[order_accuracy_];
00114
       } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00115
00116
            std::endl;
00117
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00118
00119
       memset(coeffs_interior_,
00120
               mtk::kZero,
               sizeof(coeffs_interior_[0])*order_accuracy_);
00122
00123
       for (int ii = 0; ii < order_accuracy_; ++ii) {</pre>
00124
         coeffs_interior_[ii] = mtk::kOne;
00125
00126
00127
        return true;
00128 }
00129
00130 mtk::Real *mtk::Interp1D::coeffs interior() const {
00131
00132
        return coeffs_interior_;
00133 }
00134
00135 mtk::DenseMatrix mtk::InterplD::ReturnAsDenseMatrix(const
       UniStgGrid1D &grid) {
00136
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00137
00138
        #if MTK_DEBUG_LEVEL > 0
00139
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
0.0140
00141
        #endif
00142
        int gg_num_rows{}; // Number of rows.
int gg_num_cols{}; // Number of columns.
00143
00144
00145
        if (dir_interp_ == mtk::SCALAR_TO_VECTOR) {
00146
00147
         gg_num_rows = nn + 1;
00148
          gg_num_cols = nn + 2;
00149
        } else {
00150
          gg_num_rows = nn + 2;
00151
          gg_num_cols = nn + 1;
00152
00153
00154
        // Output matrix featuring sizes for gradient operators.
00155
        mtk::DenseMatrix out(gg_num_rows, gg_num_cols);
00156
00158
00159
        out.SetValue(0, 0, mtk::kOne);
00160
00162
00163
        for (auto ii = 1; ii < gg_num_rows - 1; ++ii) {</pre>
00164
         for(auto jj = ii ; jj < order_accuracy_ + ii; ++jj) {</pre>
00165
            out.SetValue(ii, jj, mtk::kOne/order_accuracy_);
00166
00167
00168
00170
00171
        out.SetValue(gg_num_rows - 1, gg_num_cols - 1, mtk::kOne);
00173
        return out;
00174 }
```

# 17.69 src/mtk\_lap\_1d.cc File Reference

Includes the implementation of the class Lap1D.

```
#include <cstdlib>
#include <cstdio>
#include <cstring>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_tools.h"
#include "mtk_blas_adapter.h"
#include "mtk_grad_ld.h"
#include "mtk_div_ld.h"
#include "mtk_lap_ld.h"
Include dependency graph for mtk_lap_ld.cc:
```



### **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::Lap1D &in)</li>

### 17.69.1 Detailed Description

This class implements a 1D Laplacian operator, constructed using the Castillo-Blomgren-Sanchez (CBS) Algorithm (CBSA).

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_lap\_1d.cc.

# 17.70 mtk\_lap\_1d.cc

```
00001 00011 /\star 00012 Copyright (C) 2015, Computational Science Research Center, San Diego State 00013 University. All rights reserved. 00014
```

17.70 mtk lap 1d.cc 297

```
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are met:
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00034
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00038
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00044
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059 #include <cstring>
00060
00061 #include <iostream>
00062 #include <iomanip>
00063
00064 #include "mtk_roots.h"
00065 #include "mtk_tools.h"
00066 #include "mtk_blas_adapter.h"
00067 #include "mtk_grad_1d.h"
00068 #include "mtk_div_1d.h"
00069 #include "mtk_lap_1d.h"
00070
00071 namespace mtk {
00072
00073 std::ostream& operator <<(std::ostream &stream, mtk::Lap1D &in) {
00074
00076
00077
       stream << "laplacian_[0] = " << in.laplacian_[0] << std::endl << std::endl;</pre>
00078
00080
        stream << "laplacian_[1:" << 2*in.order_accuracy_ - 1 << "] = " <<
         std::endl << std::endl;
        for (auto ii = 1; ii <= (2*in.order_accuracy_ - 1); ++ii) {</pre>
00083
         stream << std::setw(13) << in.laplacian_[ii] << '
00084
00085
00086
        stream << std::endl << std::endl;</pre>
00087
00089
00090
        auto offset = 1 + (2*in.order_accuracy_ - 1);
00091
00092
        stream << "laplacian_[" << offset << ":" << offset +
          (in.order_accuracy_ - 1)*(2*in.order_accuracy_) - 1 << "] = " <<</pre>
00093
          std::endl << std::endl;
00094
00095
00096
        for (auto ii = 0; ii < in.order_accuracy_ - 1; ++ii) {</pre>
00097
         for (auto jj = 0; jj < 2*in.order_accuracy_; ++jj) {</pre>
00098
            stream << std::setw(13) <<
```

```
00099
               in.laplacian_[offset + ii*(2*in.order_accuracy_) + jj];
00100
00101
           stream << std::endl;</pre>
00102
00103
00104
        return stream;
00105 }
00106 }
00107
00108 mtk::Lap1D::Lap1D():
        order_accuracy_(mtk::kDefaultOrderAccuracy),
00110
        laplacian_length_(),
00111
        mimetic_threshold_(mtk::kDefaultMimeticThreshold) {}
00112
00113 mtk::Lap1D::~Lap1D() {
00114
00115
        delete [] laplacian ;
00116
        laplacian_ = nullptr;
00117 }
00118
00119 bool mtk::Lap1D::ConstructLap1D(int order_accuracy,
00120
                                          mtk::Real mimetic threshold) {
00121
00122
        #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(order_accuracy < 2, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent((order_accuracy%2) != 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(mimetic_threshold <= mtk::kZero,</pre>
00123
00124
00125
00126
                               __FILE__, __LINE__, __func__);
00127
00128
         if (order accuracy >= mtk::kCriticalOrderAccuracyDiv) {
00129
          std::cout << "WARNING: Numerical accuracy is high." << std::endl;</pre>
00130
00131
         std::cout << "order_accuracy_ = " << order_accuracy << std::endl;
std::cout << "mimetic_threshold_ = " << mimetic_threshold << std::endl;</pre>
00132
00133
00134
         #endif
00135
00136
         order_accuracy_ = order_accuracy;
        mimetic_threshold_ = mimetic_threshold;
00137
00138
00140
00141
        mtk::Grad1D grad; // Mimetic gradient.
00142
00143
        bool info = grad.ConstructGrad1D(order_accuracy_, mimetic_threshold_);
00144
00145
         if (!info) {
00146
          std::cerr << "Mimetic grad could not be built." << std::endl;</pre>
00147
           return false;
00148
00149
00151
00152
        mtk::Div1D div; // Mimetic divergence.
00153
         info = div.ConstructDiv1D(order_accuracy_, mimetic_threshold_);
00154
00155
00156
         if (!info) {
00157
          std::cerr << "Mimetic div could not be built." << std::endl;
00158
          return false;
00159
00160
00162
00163
         // Since these are mimetic operator, we must multiply the matrices arising
00164
         // from both the divergence and the Laplacian, in order to get the
00165
         // approximating coefficients for the Laplacian operator.
00166
00167
         // However, we must choose a grid that implied a step size of 1, so to get
         // the approximating coefficients, without being affected from the
00168
00169
         // normalization with respect to the grid.
00170
00171
         // Also, the grid must be of the minimum size to support the requested order
00172
        // of accuracy. We must please the divergence.
00173
00174
        mtk::UniStgGrid1D aux(mtk::kZero,
00175
                                 (mtk::Real) 3*order_accuracy_ - 1,
00176
                                 3*order_accuracy_ - 1);
00177
00178
         #if MTK DEBUG LEVEL > 0
00179
         std::cout << "aux =" << std::endl;
00180
        std::cout << aux << std::endl;
         std::cout <<"aux.delta_x() = " << aux.delta_x() << std::endl;
00181
00182
        std::cout << std::endl;
```

17.70 mtk lap 1d.cc 299

```
00183
        #endif
00184
00185
        mtk::DenseMatrix grad_m(grad.ReturnAsDenseMatrix(aux));
00186
00187
         #if MTK_DEBUG_LEVEL > 0
00188
        std::cout << "grad_m =" << std::endl;</pre>
00189
        std::cout << grad_m << std::endl;
00190
00191
00192
        mtk::DenseMatrix div_m(div.ReturnAsDenseMatrix(aux));
00193
00194
        \#if MTK_DEBUG_LEVEL > 0
00195
        std::cout << "div_m =" << std::endl;
        std::cout << div_m << std::endl;
00196
00197
         #endif
00198
00202
00203
        mtk::DenseMatrix lap; // Laplacian matrix to hold to computed coefficients.
00204
00205
        lap = mtk::BLASAdapter::RealDenseMM(div_m, grad_m);
00206
00207
        #if MTK_DEBUG_LEVEL > 0
00208
        std::cout << "lap =" << std::endl;
        std::cout << lap << std::endl;
00209
00210
        #endif
00211
00213
00215
00216
        // The output array will have this form:
00217
        // 1. The first entry of the array will contain the used order kk.
00218
        // 2. The second entry of the array will contain the collection of
00219
        \ensuremath{//} approximating coefficients for the interior of the grid.
        // 3. The next entries will contain the collections of approximating
00220
00221
         // coefficients for the west boundary of the grid.
00222
        laplacian_length_ = 1 + (2*order_accuracy_ - 1) +
00223
00224
          (order_accuracy_ - 1) * (2*order_accuracy_);
00225
        #if MTK_DEBUG_LEVEL > 0
std::cout << "laplacian_length_ = " << laplacian_length_ << std::endl;</pre>
00226
00227
00228
        std::cout << std::endl;</pre>
00229
        #endif
00230
00231
00232
          laplacian_ = new mtk::Real[laplacian_length_];
00233
         } catch (std::bad_alloc &memory_allocation_exception) {
00234
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00235
             std::endl;
00236
           std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00237
00238
        memset(laplacian_, mtk::kZero, sizeof(laplacian_[0])*laplacian_length_);
00239
00241
00242
        laplacian_[0] = order_accuracy_;
00243
00246
00247
        for (auto ii = 0; ii < 2*order_accuracy_ - 1; ++ii) {</pre>
00248
          laplacian_[ii + 1] = lap.GetValue(1 + (order_accuracy_ - 1), ii + 1);
00249
00250
00252
00253
        auto offset = 1 + (2*order_accuracy_ - 1);
00254
00255
        for (auto ii = 0; ii < order_accuracy_ - 1; ++ii) {</pre>
          for (auto jj = 0; jj < 2*order_accuracy_; ++jj) {
   laplacian_[offset + ii*(2*order_accuracy_) + jj] =
00256
00257
               lap.GetValue(1 + ii, jj);
00258
00259
          }
00260
        }
00261
00262
        return true;
00263 }
00264
00265 mtk::DenseMatrix mtk::Lap1D::ReturnAsDenseMatrix(const
      UniStaGrid1D & grid) {
00266
00267
        int nn{grid.num_cells_x()}; // Number of cells on the grid.
00268
00269
        #if MTK DEBUG LEVEL > 0
        mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(nn < 3*order_accuracy_ - 1, __FILE__, __LINE__, __func__);</pre>
00270
00271
```

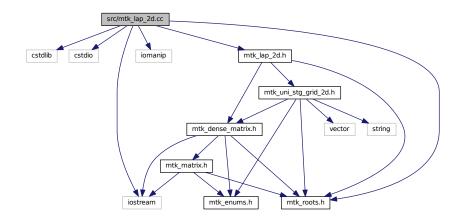
```
00272
00273
00274
        mtk::DenseMatrix lap(nn + 2, nn + 2); // Laplacian matrix to be returned.
00275
00276
        mtk::Real idx{mtk::kOne/(grid.delta_x()*grid.delta_x())}; // Inverse of
00277
00279
00280
        auto offset = (1 + 2*order_accuracy_ - 1);
00281
        for (auto ii = 0; ii < order_accuracy_ - 1; ++ii)</pre>
00283
         for (auto jj = 0; jj < 2*order_accuracy_; ++jj) {</pre>
00284
            lap.SetValue(1 + ii,
00285
                         jj,
00286
                          idx*laplacian_[offset + ii*2*order_accuracy_ + jj]);
00287
00288
        }
00289
00291
00292
        offset = 1 + (order_accuracy_ - 1);
00293
00294
        int kk{1};
00295
        for (auto ii = order_accuracy_; ii <= nn - (order_accuracy_ - 1); ++ii) {</pre>
00296
         int mm{1};
00297
          for (auto jj = 0; jj < 2*order_accuracy_ - 1; ++jj) {</pre>
            lap.SetValue(ii, jj + kk, idx*laplacian_[mm]);
00298
00299
           mm = mm + 1;
00300
00301
         kk = kk + 1;
00302
00303
00305
00306
        offset = (1 + 2*order_accuracy_ - 1);
00307
00308
        auto aux = order_accuracy_ + (nn - 2*(order_accuracy_ - 1));
00309
00310
        auto 11 = 1;
auto rr = 1;
00311
00312
        for (auto ii = nn; ii > aux - 1; --ii) {
00313
          auto cc = 0;
00314
          for (auto jj = nn + 2 - 1; jj >= (nn + 2) - 2*order_accuracy_; --jj) {
00315
            lap.SetValue(ii, jj, lap.GetValue(rr,cc));
00316
            ++11;
00317
            ++cc;
00318
00319
          rr++;
00320
00321
00328
00329
        return lap;
00330 }
00331
00332 mtk::Real* mtk::Lap1D::Data(const UniStgGrid1D &grid) {
00333
00334
       mtk::DenseMatrix tmp;
00335
00336
       tmp = ReturnAsDenseMatrix(grid);
00337
00338
        return tmp.data();
00339 }
```

# 17.71 src/mtk\_lap\_2d.cc File Reference

```
#include <cstdlib>
#include <cstdio>
#include <iostream>
#include <iomanip>
#include "mtk_roots.h"
#include "mtk_lap_2d.h"
```

17.72 mtk lap 2d.cc 301

Include dependency graph for mtk\_lap\_2d.cc:



# 17.72 mtk\_lap\_2d.cc

```
00001
00011 /*
00012 Copyright (C) 2015, Computational Science Research Center, San Diego State
00013 University. All rights reserved.
00014
00015 Redistribution and use in source and binary forms, with or without modification,
00016 are permitted provided that the following conditions are \text{met}:
00017
00018 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00019 and a copy of the modified files should be reported once modifications are
00020 completed. Documentation related to said modifications should be included.
00021
00022 2. Redistributions of source code must be done through direct
00023 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024
00025 3. Redistributions of source code must retain the above copyright notice, this
00026 list of conditions and the following disclaimer.
00027
00028 4. Redistributions in binary form must reproduce the above copyright notice,
00029 this list of conditions and the following disclaimer in the documentation and/or
00030 other materials provided with the distribution.
00032 5. Usage of the binary form on proprietary applications shall require explicit
00033 prior written permission from the the copyright holders.
00035 6. Neither the name of the copyright holder nor the names of its contributors
00036 may be used to endorse or promote products derived from this software without
00037 specific prior written permission.
00039 The copyright holders provide no reassurances that the source code provided does
00040 not infringe any patent, copyright, or any other intellectual property rights of
00041 third parties. The copyright holders disclaim any liability to any recipient for
00042 claims brought against recipient by any third party for infringement of that
00043 parties intellectual property rights.
00045 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00046 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00047 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00048 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00049 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00050 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00051 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00052 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00053 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00054 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00055 */
```

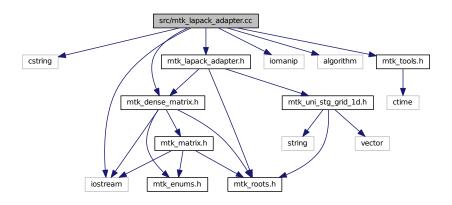
```
00056
00057 #include <cstdlib>
00058 #include <cstdio>
00059
00060 #include <iostream>
00061 #include <iomanip>
00063 #include "mtk_roots.h"
00064 #include "mtk_lap_2d.h"
00066 mtk::Lap2D::Lap2D():
00067
      order_accuracy_(),
00068
       mimetic_threshold_() {}
00070 mtk::Lap2D::Lap2D(const Lap2D &lap):
00071 order_accuracy_(lap.order_accuracy_),
00072
       mimetic_threshold_(lap.mimetic_threshold_) {}
00073
00074 mtk::Lap2D::~Lap2D() {}
00075
00076 mtk::DenseMatrix mtk::Lap2D::ConstructLap2D(const
     mtk::UniStgGrid2D &grid,
00077
                                                      int order_accuracy,
mtk::Real mimetic_threshold) {
00078
00079
08000
       return laplacian_;
00081 }
```

# 17.73 src/mtk\_lapack\_adapter.cc File Reference

### Adapter class for the LAPACK API.

```
#include <cstring>
#include <iostream>
#include <iomanip>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_dense_matrix.h"
#include "mtk_lapack_adapter.h"
```

Include dependency graph for mtk\_lapack\_adapter.cc:



#### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### **Functions**

- void mtk::sgesv\_ (int \*n, int \*nrhs, Real \*a, int \*Ida, int \*ipiv, Real \*b, int \*Idb, int \*info)
- void mtk::sgels\_ (char \*trans, int \*m, int \*n, int \*nrhs, Real \*a, int \*lda, Real \*b, int \*ldb, Real \*work, int \*lwork, int \*info)

Single-precision GEneral matrix Least Squares solver.

- void mtk::sgeqrf\_ (int \*m, int \*n, Real \*a, int \*lda, Real \*tau, Real \*work, int \*lwork, int \*info)
  - Single-precision GEneral matrix QR Factorization.
- void mtk::sormqr\_ (char \*side, char \*trans, int \*m, int \*n, int \*k, Real \*a, int \*lda, Real \*tau, Real \*c, int \*ldc, Real \*work, int \*lwork, int \*info)

Single-precision Orthogonal Matrix from QR factorization.

#### 17.73.1 Detailed Description

This class contains a collection of static classes, that posses direct access to the underlying structure of the matrices, thus allowing programmers to exploit some of the numerical methods implemented in the LAPACK.

The **LAPACK** (**Linear Algebra PACKage**) is written in Fortran 90 and provides routines for solving systems of simultaneous linear equations, least-squares solutions of linear systems of equations, eigenvalue problems, and singular value problems.

#### See Also

```
http://www.netlib.org/lapack/
```

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_lapack\_adapter.cc.

## 17.74 mtk lapack adapter.cc

```
00020 Copyright (C) 2015, Computational Science Research Center, San Diego State
00021 University. All rights reserved.
00023 Redistribution and use in source and binary forms, with or without modification,
00024 are permitted provided that the following conditions are met:
00026 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00027 and a copy of the modified files should be reported once modifications are
00028 completed. Documentation related to said modifications should be included.
00029
00030 2. Redistributions of source code must be done through direct
00031 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00032
00033 3. Redistributions of source code must retain the above copyright notice, this
00034 list of conditions and the following disclaimer.
00035
00036 4. Redistributions in binary form must reproduce the above copyright notice,
00037 this list of conditions and the following disclaimer in the documentation and/or
00038 other materials provided with the distribution.
00039
00040 5. Usage of the binary form on proprietary applications shall require explicit
```

```
00041 prior written permission from the the copyright holders.
00043 6. Neither the name of the copyright holder nor the names of its contributors
00044 may be used to endorse or promote products derived from this software without
00045 specific prior written permission.
00047 The copyright holders provide no reassurances that the source code provided does
00048 not infringe any patent, copyright, or any other intellectual property rights of
00049 third parties. The copyright holders disclaim any liability to any recipient for
00050 claims brought against recipient by any third party for infringement of that
00051 parties intellectual property rights.
00053 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00054 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00055 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00056 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00057 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00058 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00059 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00060 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00061 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00062 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00063 */
00064
00065 #include <cstring>
00066
00067 #include <iostream>
00068 #include <iomanip>
00069
00070 #include <algorithm>
00071
00072 #include "mtk_tools.h"
00073 #include "mtk_dense_matrix.h"
00074 #include "mtk_lapack_adapter.h"
00075
00076 namespace mtk {
00077
00078 extern "C" {
00079
00080 #ifdef MTK_PRECISION_DOUBLE
00081
00100 void dgesv_(int* n,
00101
                  int* nrhs,
00102
                  Real* a,
00103
                  int* lda,
00104
                  int* ipiv,
00105
                  Real* b.
00106
                  int* ldb.
00107
                  int* info);
00108 #else
00109
00128 void sgesv_(int* n,
00129
                int* nrhs,
00130
                  Real* a,
00131
                  int* lda,
00132
                  int* ipiv,
00133
                  Real* b,
00134
                  int* ldb,
00135
                  int* info);
00136 #endif
00138 #ifdef MTK_PRECISION_DOUBLE
00139
00182 void dgels_(char* trans,
                 int* m,
                  int* n,
00185
                  int* nrhs,
00186
                  Real* a,
00187
                  int* lda,
00188
                  Real* b,
00189
                  int* ldb,
00190
                  Real* work,
00191
                  int* lwork,
00192
                  int* info);
00193 #else
00194
00237 void sgels_(char* trans,
00238
                  int* m.
00239
                  int* n,
00240
                  int* nrhs,
00241
                  Real* a,
```

```
00242
                  int* lda,
00243
                  Real* b,
00244
                  int* ldb,
00245
                  Real* work,
00246
                  int* lwork,
00247
                  int* info);
00248 #endif
00249
00250 #ifdef MTK_PRECISION_DOUBLE
00280 void dgeqrf_(int *m,
                   int *n,
00282
                   Real *a,
                   int *lda,
00284
                   Real *tau,
                   Real *work,
00286
                   int *lwork,
00287
                   int *info);
00288 #else
00289
00318 void sgeqrf_(int *m,
00319
                   int *n.
00320
                   Real *a,
00321
                   int *lda,
00322
                   Real *tau,
00323
                   Real *work,
                   int *lwork,
00324
00325
                   int *info);
00326 #endif
00327
00328 #ifdef MTK_PRECISION_DOUBLE
00329
00363 void dormqr_(char *side,
                  char *trans,
00364
00365
                   int *m.
00366
                   int *n,
00367
                   int *k,
00368
                   Real *a,
                   int *lda,
00369
00370
                   Real *tau,
00371
                   Real *c,
00372
                   int *ldc,
00373
                   Real *work,
00374
                   int *lwork,
00375
                   int *info);
00376 #else
00377
00411 void sormqr_(char *side,
       char *trans,
00412
00413
                   int *m,
                  int *n,
00414
00415
                   int *k,
00416
                  Real *a,
00417
                   int *lda,
00418
                  Real *tau,
00419
                   Real *c,
00420
                   int *ldc,
00421
                   Real *work,
00422
                   int *lwork,
00423
                   int *info);
00424 #endif
00425 }
00426 }
00427
00428 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
00429
                                                mtk::Real *rhs) {
00430
00431
       #if MTK_DEBUG_LEVEL > 0
       mtk::Tools::Prevent(rhs == nullptr, __FILE__, __LINE__, __func__);
00432
00433
       #endif
00434
00435
        int *ipiv{};
                                     // Array for pivoting information.
00436
                                     // Number of right-hand sides.
        int nrhs{1};
                                     // Status of the solution.
00437
        int info{};
00438
        int mm_rank{mm.num_rows()}; // Rank of the matrix.
00439
00440
        try {
         ipiv = new int[mm_rank];
00441
       } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00442
00443
```

```
00444
            std::endl;
00445
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00446
00447
       memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00448
        int ldbb = mm_rank;
00449
00450
        int mm_ld = mm_rank;
00451
00452
        #ifdef MTK_PRECISION_DOUBLE
00453
        dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, rhs, &ldbb, &info);
00454
00455
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, rhs, &ldbb, &info);
00456
        #endif
00457
00458
       delete [] ipiv;
00459
00460
       return info:
00461 }
00462
00463 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
                                               mtk::DenseMatrix &bb) {
00465
00466
       int nrhs{bb.num_rows()}; // Number of right-hand sides.
00467
00468
        #if MTK DEBUG LEVEL > 0
       mtk::Tools::Prevent(nrhs <= 0, __FILE__, __LINE__, __func__);</pre>
00469
00470
        #endif
00471
00472
                                    // Array for pivoting information.
        int *ipiv{};
00473
        int info{}:
                                     // Status of the solution.
        int mm_rank{mm.num_rows()}; // Rank of the matrix.
00474
00475
00476
          ipiv = new int[mm_rank];
00477
00478
       } catch (std::bad_alloc &memory_allocation_exception) {
00479
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00480
           std::endl;
00481
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00482
00483
       memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00484
00485
        int ldbb = mm_rank;
00486
        int mm_ld = mm_rank;
00487
00488
        #ifdef MTK_PRECISION_DOUBLE
00489
        dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, bb.data(), &ldbb, &info);
00490
00491
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv, bb.data(), &ldbb, &info);
00492
        #endif
00493
00494
        delete [] ipiv;
00495
00496
        // After output, the data in the matrix will be column-major ordered.
00497
00498
       bb.SetOrdering(mtk::COL_MAJOR);
00499
00500
        #if MTK_DEBUG_LEVEL > 0
00501
        std::cout << "bb_col_maj_ord =" << std::endl;</pre>
00502
        std::cout << bb << std::endl;
00503
        #endif
00504
00505
       bb.OrderRowMajor();
00506
00507
        #if MTK_DEBUG_LEVEL > 0
        std::cout << "bb_row_maj_ord =" << std::endl;
00508
       std::cout << bb << std::endl;
00509
00510
        #endif
00511
00512
        return info;
00513 }
00514
00515 int mtk::LAPACKAdapter::SolveDenseSystem(
     mtk::DenseMatrix &mm,
00516
                                                mtk::UniStgGrid1D &rhs) {
00517
00518
        int nrhs{1}; // Number of right-hand sides.
00519
00520
        int *ipiv{};
                                     // Array for pivoting information.
00521
                                     // Status of the solution.
        int info{}:
        int mm_rank{mm.num_rows()}; // Rank of the matrix.
00522
```

```
00523
00524
00525
          ipiv = new int[mm_rank];
        } catch (std::bad_alloc &memory_allocation_exception) {
00526
00527
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00528
            std::endl;
00529
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00530
00531
       memset(ipiv, 0, sizeof(ipiv[0])*mm_rank);
00532
00533
        int ldbb = mm_rank;
00534
       int mm_ld = mm_rank;
00535
00536
       mm.OrderColMajor();
00537
00538
       #ifdef MTK_PRECISION_DOUBLE
       dgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv,
00539
00540
               rhs.discrete_field_u(), &ldbb, &info);
00541
00542
        fgesv_(&mm_rank, &nrhs, mm.data(), &mm_ld, ipiv,
00543
              rhs.discrete_field_u(), &ldbb, &info);
00544
00545
00546
       mm.OrderRowMajor();
00547
00548
       delete [] ipiv;
00549
00550
       return info;
00551 }
00552
00553 mtk::DenseMatrix mtk::LAPACKAdapter::ORFactorDenseMatrix
      (mtk::DenseMatrix &aa) {
00554
       mtk::Real *work{}; // Working array.
00555
       mtk::Real *tau{}; // Array for the Householder scalars.
00556
00557
00558
        // Prepare to factorize: allocate and inquire for the value of lwork.
00559
00560
          work = new mtk::Real[1];
00561
        } catch (std::bad_alloc &memory_allocation_exception) {
00562
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00563
           std::endl;
00564
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00565
00566
       memset(work, mtk::kZero, sizeof(aa.data()[0])*1);
00567
00568
        int lwork{-1};
00569
        int info{};
00570
        int aa_num_cols = aa.num_cols();
00571
00572
        int aaT_num_rows = aa.num_cols();
00573
        int aaT_num_cols = aa.num_rows();
00574
00575
        #if MTK_DEBUG_LEVEL > 0
00576
        std::cout << "Input matrix BEFORE QR factorization:" << std::endl;</pre>
00577
        std::cout << aa << std::endl;
00578
00579
00580
        #ifdef MTK_PRECISION_DOUBLE
00581
       dgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00582
                tau,
00583
                work, &lwork, &info);
00584
       #else
00585
        fgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00586
                tau,
00587
                work, &lwork, &info);
00588
       #endif
00589
00590
       #if MTK_DEBUG_LEVEL > 0
00591
        if (info == 0) {
00592
         lwork = (int) work[0];
00593
       } else {
00594
         std::cerr << "Could not get value for lwork on line " << __LINE__ - 5 <<
00595
            std::endl;
00596
         std::cerr << "Exiting..." << std::endl;
00597
00598
        #endif
00599
00600
        #if MTK DEBUG LEVEL>0
        std::cout << "lwork = " << std::endl << std::setw(12) << lwork << std::endl
00601
00602
         << std::endl;
```

```
00603
        #endif
00604
00605
        delete [] work;
        work = nullptr;
00606
00607
00608
        // Once we know lwork, we can actually invoke the factorization:
00609
        try {
00610
         work = new mtk::Real [lwork];
00611
        } catch (std::bad_alloc &memory_allocation_exception) {
         std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00612
00613
            std::endl:
00614
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00615
00616
        memset(work, mtk::kZero, sizeof(work[0])*lwork);
00617
00618
        int ltau = std::min(aaT_num_rows,aaT_num_cols);
00619
00620
00621
          tau = new mtk::Real [ltau];
00622
        } catch (std::bad_alloc &memory_allocation_exception) {
00623
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00624
           std::endl;
00625
          std::cerr << memory allocation exception.what() << std::endl;</pre>
00626
00627
        memset(tau, mtk::kZero, sizeof(0.0)*ltau);
00628
00629
        #ifdef MTK PRECISION DOUBLE
        dgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00630
00631
                tau, work, &lwork, &info);
00632
        #else
00633
        fgeqrf_(&aaT_num_rows, &aaT_num_cols, aa.data(), &aaT_num_rows,
00634
                tau, work, &lwork, &info);
00635
        #endif
00636
        if (!info) {
00637
         #if MTK_DEBUG_LEVEL > 0
00638
          std::cout << "QR factorization completed!" << std::endl << std::endl;</pre>
00639
00640
          #endif
00641
       } else {
         std::cerr << "Error solving system! info = " << info << std::endl;
00642
         std::cerr << "Exiting..." << std::endl;
00643
00644
00645
00646
        #if MTK DEBUG LEVEL > 0
00647
        std::cout << "Input matrix AFTER QR factorization:" << std::endl;</pre>
00648
        std::cout << aa << std::endl;
00649
        #endif
00650
00651
        // We now generate the real matrix Q with orthonormal columns. This has to
00652
        // be done separately since the actual output of dgeqrf_ (AA_) represents
00653
        // the orthogonal matrix Q as a product of min(aa_num_rows,aa_num_cols)
00654
        // elementary Householder reflectors. Notice that we must re-inquire the new
00655
        // value for lwork that is used.
00656
00657
        bool padded{false};
00658
00659
       bool transpose {false};
00660
00661
        mtk::DenseMatrix QQ_(aa.num_cols(), padded, transpose);
00662
00663
        #if MTK_DEBUG_LEVEL > 0
00664
        std::cout << "Initialized QQ_T: " << std::endl;</pre>
00665
        std::cout << QQ_ << std::endl;
00666
        #endif
00667
00668
        // Assemble the QQ_ matrix:
00669
        lwork = -1;
00670
00671
        delete[] work;
00672
        work = nullptr;
00673
00674
        trv {
00675
         work = new mtk::Real[1];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <</pre>
00676
00677
00678
            std::endl;
00679
          std::cerr << memory allocation exception.what() <<
00680
            std::endl:
00681
00682
        memset(work, mtk::kZero, sizeof(work[0])*1);
00683
```

```
00684
        char side_{'L'};
00685
        char trans_{'N'};
00686
00687
        int aux = QQ_.num_rows();
00688
00689
        #ifdef MTK_PRECISION_DOUBLE
00690
        dormqr_(&side_, &trans_,
00691
                 &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00692
                QQ_.data(), &aux, work, &lwork, &info);
00693
00694
        formqr_(&side_, &trans_,
00695
                &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00696
                QQ_.data(), &aux, work, &lwork, &info);
00697
00698
00699
        #if MTK_DEBUG_LEVEL > 0
00700
        if (info == 0) {
00701
          lwork = (int) work[0];
00702
        } else {
         std::cerr << "Could not get lwork on line " << __LINE__ - 5 << std::endl;
00703
          std::cerr << "Exiting..." << std::endl;
00704
00705
00706
        #endif
00707
00708
        #if MTK DEBUG LEVEL > 0
        std::cout << "lwork = " << std::endl << std::setw(12) << lwork <<
00709
00710
          std::endl << std::endl;
00711
        #endif
00712
00713
        delete[] work;
00714
        work = nullptr;
00715
00716
        try {
00717
          work = new mtk::Real[lwork];
00718
        } catch (std::bad_alloc &memory_allocation_exception) {
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 <<
00719
            std::endl;
00721
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00722
00723
        memset(work, mtk::kZero, sizeof(work[0])*lwork);
00724
00725
        #ifdef MTK_PRECISION_DOUBLE
00726
        dormqr_(&side_, &trans_,
00727
                 &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00728
                 QQ_.data(), &aux, work, &lwork, &info);
00729
        #else
00730
        formqr_(&side_, &trans_,
00731
                 &aa_num_cols, &aa_num_cols, &ltau, aa.data(), &aaT_num_rows, tau,
00732
                 QQ_.data(), &aux, work, &lwork, &info);
00733
        #endif
00734
00735
        if (!info) {
00736
          #if MTK_DEBUG_LEVEL>0
00737
          std::cout << "Q matrix successfully assembled!" << std::endl << std::endl;</pre>
00738
00739
        } else {
00740
          std::cerr << "Something went wrong solving system! info = " << info <<
00741
00742
          std::cerr << "Exiting..." << std::endl;</pre>
00743
00744
00745
        delete[] work;
00746
       work = nullptr;
00747
00748
        delete[] tau;
00749
        tau = nullptr;
00750
00751
        return QQ_;
00752 }
00753
00754 int mtk::LAPACKAdapter::SolveRectangularDenseSystem(const
     mtk::DenseMatrix &aa,
00755
                                                             mtk::Real *ob_,
00756
                                                             int ob ld ) {
00757
00758
        // We first invoke the solver to guery for the value of lwork. For this,
00759
        // we must at least allocate enough space to allow access to \mathtt{WORK}(1)\,\text{, or}
00760
        // work[01:
00761
        // If LWORK = -1\mbox{,} then a workspace query is assumed; the routine only // calculates the optimal size of the WORK array, returns this value as
00762
00763
```

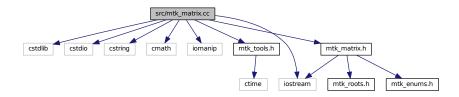
```
00764
        // the first entry of the WORK array, and no error message related to
00765
        // LWORK is issued by XERBLA.
00766
        mtk::Real *work{}; // Work array.
00767
00768
00769
00770
          work = new mtk::Real[1];
00771
        } catch (std::bad_alloc &memory_allocation_exception) {
00772
          std::cerr << "Memory allocation exception on line " << __LINE__ - 3 << std::endl;
00773
          std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00774
00775
        memset(work, mtk::kZero, sizeof(work[0])*1);
00776
00777
        char trans_{'N'};
00778
        int nrhs_{1};
00779
        int info{0};
00780
        int lwork{-1};
00781
00782
        int AA_num_rows_ = aa.num_cols();
int AA_num_cols_ = aa.num_rows();
00783
        int AA_ld_ = std::max(1,aa.num_cols());
00784
00785
00786
        #ifdef MTK_PRECISION_DOUBLE
00787
        dgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00788
                ob_, &ob_ld_,
00789
                work, &lwork, &info);
00790
        #else
00791
        sgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00792
               ob_, &ob_ld_,
00793
               work, &lwork, &info);
00794
        #endif
00795
00796
        if (info == 0) {
00797
         lwork = (int) work[0];
00798
       } else {
          std::cerr << "Could not get value for lwork on line " << __LINE__ - 2 <<
00799
            std::endl;
00800
          std::cerr << "Exiting..." << std::endl;
00801
00802
          return info;
00803
00804
        #if MTK_DEBUG_LEVEL > 0
std::cout << "lwork = " << std::endl << std::setw(12) << lwork <<</pre>
00805
00806
00807
          std::endl << std::endl;
00808
00809
00810
        // We then use lwork's new value to create the work array:
00811
        delete[] work;
00812
        work = nullptr;
00813
00814
00815
          work = new mtk::Real[lwork];
        } catch (std::bad_alloc &memory_allocation_exception) {
  std::cerr << "Memory allocation exception on line " << __LINE__ - 3 << std::endl;</pre>
00816
00817
00818
         std::cerr << memory_allocation_exception.what() << std::endl;</pre>
00819
00820
        memset(work, 0.0, sizeof(work[0])*lwork);
00821
        // We now invoke the solver again:
00822
00823
        #ifdef MTK_PRECISION_DOUBLE
00824
        dgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00825
                ob_, &ob_ld_,
00826
                work, &lwork, &info);
00827
        #else
00828
        sgels_(&trans_, &AA_num_rows_, &AA_num_cols_, &nrhs_, aa.data(), &AA_ld_,
00829
               ob_, &ob_ld_,
                work, &lwork, &info);
00831
       #endif
00832
00833
       delete [] work;
00834
       work = nullptr;
00835
00836
       return info;
00837 }
```

## src/mtk\_matrix.cc File Reference

Implementing the representation of a matrix in the MTK.

```
#include <cstdlib>
#include <cstdio>
#include <cstring>
#include <cmath>
#include <iomanip>
#include <iostream>
#include "mtk_tools.h"
#include "mtk_matrix.h"
```

Include dependency graph for mtk\_matrix.cc:



#### 17.75.1 Detailed Description

Implementation of the representation for the matrices implemented in the MTK.

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk matrix.cc.

#### 17.76 mtk matrix.cc

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to the source code should be reported to:
00018
00019 esanchez at mail dot sdsu dot edu
00020
00021 A copy of the modified files should be reported once modifications are
00022 completed. Documentation related to said modifications should be included.
00023
00024 2. Redistributions of source code must be done through direct
00025 downloads from the project's GitHub page:
00026
00027 http://www.csrc.sdsu.edu/mtk
00028
00029 3. Redistributions of source code must retain the above copyright notice, this
00030 list of conditions and the following disclaimer.
00031
```

```
00032 4. Redistributions in binary form must reproduce the above copyright notice,
00033 this list of conditions and the following disclaimer in the documentation and/or
00034 other materials provided with the distribution.
00036 5. Usage of the binary form on proprietary applications shall require explicit
00037 prior written permission from the the copyright holders.
00039 6. Neither the name of the copyright holder nor the names of its contributors
00040 may be used to endorse or promote products derived from this software without
00041 specific prior written permission.
00043 The copyright holders provide no reassurances that the source code provided does
00044 not infringe any patent, copyright, or any other intellectual property rights of
00045 third parties. The copyright holders disclaim any liability to any recipient for
00046 claims brought against recipient by any third party for infringement of that
00047 parties intellectual property rights.
00049 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00050 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00051 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00052 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00053 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00054 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00055 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00056 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT 00057 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00058 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00059 */
00060
00061 #include <cstdlib>
00062 #include <cstdio>
00063 #include <cstring>
00064 #include <cmath>
00065
00066 #include <iomanip>
00067 #include <iostream>
00068
00069 #include "mtk tools.h"
00070 #include "mtk_matrix.h"
00071
00072 mtk::Matrix::Matrix():
00073 storage_(mtk::DENSE)
00074
       ordering_(mtk::ROW_MAJOR),
00075
       num_rows_(),
00076
       num_cols_(),
00077
        num_values_(),
00078
       ld_(),
00079
        num_zero_(),
        num_non_zero_(),
00080
00081
        num_null_(),
00082
        num_non_null_(),
00083
        kl_(),
00084
        ku (),
00085
        bandwidth_(),
00086
        abs_density_(),
00087
        rel_density_(),
00088
        abs_sparsity_(),
00089
        rel_sparsity_() {}
00090
00091 mtk::Matrix::Matrix(const Matrix &in):
00092 storage_(in.storage_),
00093
        ordering_(in.ordering_),
00094
       num_rows_(in.num_rows_),
00095
        num_cols_(in.num_cols_),
00096
        num_values_(in.num_values_),
00097
        ld_(in.ld_),
00098
       num_zero_(in.num_zero_),
00099
        num_non_zero_(in.num_non_zero_),
00100
       num_null_(in.num_null_),
00101
        num_non_null_(in.num_non_null_),
00102
        kl_(in.kl_),
00103
        ku (in.ku ),
00104
        bandwidth (in.bandwidth ),
00105
        abs_density_(in.abs_density_),
00106
        rel density (in.rel density ),
00107
        abs_sparsity_(in.abs_sparsity_),
00108
        rel_sparsity_(in.rel_sparsity_) {}
00109
00110 mtk::Matrix::~Matrix() {}
00111
00112 mtk::MatrixStorage mtk::Matrix::storage() const {
```

17.76 mtk matrix.cc 313

```
00113
00114
       return storage_;
00115 }
00116
00117 mtk::MatrixOrdering mtk::Matrix::ordering() const {
00118
00119
        return ordering_;
00120 }
00121
00122 int mtk::Matrix::num_rows() const {
00123
00124
       return num_rows_;
00125 }
00126
00127 int mtk::Matrix::num_cols() const {
00128
00129
       return num cols ;
00130 }
00131
00132 int mtk::Matrix::num_values() const {
00133
00134
       return num values :
00135 }
00136
00137 int mtk::Matrix::ld() const {
00138
00139
       return ld :
00140 }
00141
00142 int mtk::Matrix::num_zero() const {
00143
00144
       return num_zero_;
00145 }
00146
00147 int mtk::Matrix::num_non_zero() const {
00148
00149
       return num_non_zero_;
00150 }
00151
00152 int mtk::Matrix::num_null() const {
00153
00154
        return num_null_;
00155 }
00156
00157 int mtk::Matrix::num_non_null() const {
00158
00159
        return num_non_null_;
00160 }
00161
00162 int mtk::Matrix::kl() const {
00163
00164
       return kl_;
00165 }
00166
00167 int mtk::Matrix::ku() const {
00168
00169
       return ku_;
00170 }
00171
00172 int mtk::Matrix::bandwidth() const {
00173
00174
       return bandwidth_;
00175 }
00176
00177 mtk::Real mtk::Matrix::rel_density() const {
00178
00179
        return rel_density_;
00180 }
00181
00182 mtk::Real mtk::Matrix::abs_sparsity() const {
00183
00184
       return abs_sparsity_;
00185 }
00186
00187 mtk::Real mtk::Matrix::rel_sparsity() const {
00188
00189
        return rel sparsity;
00190 }
00191
00192 void mtk::Matrix::set_storage(const mtk::MatrixStorage &ss) {
00193
```

```
00194
        #if MTK_DEBUG_LEVEL > 0
00195
        mtk::Tools::Prevent(!(ss == mtk::DENSE ||
00196
                              ss == mtk::BANDED ||
00197
                               ss == mtk::CRS),
00198
                             __FILE__, __LINE__, __func__);
00199
        #endif
00200
00201
        storage_ = ss;
00202 }
00203
00204 void mtk::Matrix::set_ordering(const
     mtk::MatrixOrdering &oo) {
00205
00206
        #if MTK_DEBUG_LEVEL > 0
00207
       mtk::Tools::Prevent(!(oo == mtk::ROW_MAJOR || oo ==
     mtk::COL_MAJOR),
00208
                             __FILE__, __LINE__, __func__);
00209
        #endif
00210
00211
       ordering_ = oo;
00212
00213
       ld_ = (ordering_ == mtk::ROW_MAJOR)?
00214
          std::max(1,num_cols_): std::max(1,num_rows_);
00215 }
00216
00217 void mtk::Matrix::set num rows(int in) {
00218
00219
        #if MTK DEBUG LEVEL > 0
00220
       mtk::Tools::Prevent(in < 1, __FILE__, __LINE__, __func__);</pre>
00221
        #endif
00222
00223
        num_rows_ = in;
00224
        num_values_ = num_rows_*num_cols_;
        ld_ = (ordering_ == mtk::ROW_MAJOR)?
00225
          std::max(1,num_cols_): std::max(1,num_rows_);
00226
00227 }
00228
00229 void mtk::Matrix::set_num_cols(int in) {
00230
        #if MTK DEBUG LEVEL > 0
00231
00232
       mtk::Tools::Prevent(in < 1, __FILE__, __LINE__, __func__);</pre>
00233
        #endif
00234
00235
        num_cols_ = in;
        num_values_ = num_rows_*num_cols_;
00236
00237
        ld_ = (ordering_ == mtk::ROW_MAJOR)?
00238
          std::max(1,num_cols_): std::max(1,num_rows_);
00239 }
00240
00241 void mtk::Matrix::set_num_zero(int in) {
00242
00243
        #if MTK_DEBUG_LEVEL > 0
00244
        mtk::Tools::Prevent(in < 0, __FILE__, __LINE__, __func__);</pre>
00245
        #endif
00246
00247
        num_zero_ = in;
00248
       num_non_zero_ = num_values_ - num_zero_;
00249
00251
        rel_density_ = (mtk::Real) num_non_zero_/num_values_;
00252
       rel_sparsity_ = 1.0 - rel_density_;
00253 }
00254
00255 void mtk::Matrix::set_num_null(int in) {
00256
00257
        #if MTK_DEBUG_LEVEL > 0
00258
        mtk::Tools::Prevent(in < 0, __FILE__, __LINE__, __func__);</pre>
00259
        #endif
00260
00261
        num_null_ = in;
00262
        num_non_null_ = num_values_ - num_null_;
00263
       abs_density_ = (mtk::Real) num_non_null_/num_values_;
abs_sparsity_ = 1.0 - abs_density_;
00265
00266
00267 }
00268
00269 void mtk::Matrix::IncreaseNumZero() {
00270
00272
00273
       num zero ++;
00274
       num_non_zero_ = num_values_ - num_zero_;
00275
       rel_density_ = (mtk::Real) num_non_zero_/num_values_;
```

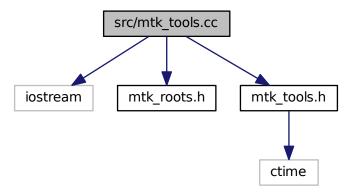
```
00276    rel_sparsity_ = 1.0 - rel_density_;
00277 }
00278
00279 void mtk::Matrix::IncreaseNumNull() {
00280
00282
00283    num_null_++;
00284    num_non_null_ = num_values_ - num_null_;
00285    abs_density_ = (mtk::Real) num_non_null_/num_values_;
00286    abs_sparsity_ = 1.0 - abs_density_;
00287 }
```

## 17.77 src/mtk\_tools.cc File Reference

Implements a execution tool manager class.

```
#include <iostream>
#include "mtk_roots.h"
#include "mtk_tools.h"
```

Include dependency graph for mtk\_tools.cc:



#### 17.77.1 Detailed Description

Basic tools to ensure execution correctness.

Author

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_tools.cc.

## 17.78 mtk\_tools.cc

```
00001
00010 /*
```

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00033
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED 00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <iostream>
00057
00058 #include "mtk_roots.h"
00059 #include "mtk_tools.h"
00060
00061 void mtk::Tools::Prevent(const bool condition,
00062
                                const char *fname,
00063
                                int lineno,
00064
                                const char *fxname) {
00065
00067
        #if MTK_DEBUG_LEVEL > 0
00068
        if (lineno < 1) {</pre>
00069
         std::cerr << __FILE__ << ": " << "Incorrect parameter at line " << __LINE__ - 2 << " (" << __func__ << ")" << std::endl;
00070
00071
00072
          exit(EXIT_FAILURE);
00073
00074
        #endif
00075
00076
        if (condition) {
          std::cerr << fname << ": " << "Incorrect parameter at line " <<
00077
          lineno << " (" << fxname << ")" << std::endl;
00078
00079
          exit(EXIT_FAILURE);
08000
00081 }
00082
00084
00085 int mtk::Tools::test_number_; // Used to control the correctness of the test.
00086
00087 clock_t mtk::Tools::begin_time_; // Used to time tests.
00088
00089 void mtk::Tools::BeginTestNo(const int &nn) {
00090
00091
        #if MTK_DEBUG_LEVEL > 0
00092
       mtk::Tools::Prevent(nn <= 0, __FILE__, __LINE__, __func__);</pre>
00093
       #endif
```

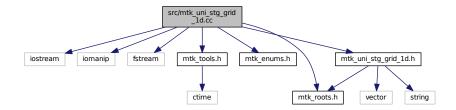
```
00094
00095
          test_number_ = nn;
00096
00097
          std::cout << "Test " << nn << "..." << std::endl << std::endl;
00098
          begin_time_ = clock();
00099 }
00100
00101 void mtk::Tools::EndTestNo(const int &nn) {
00102
00103
          #if MTK_DEBUG_LEVEL > 0
00104
          mtk::Tools::Prevent(test_number_ != nn, __FILE__, __LINE__, __func__);
00105
00106
          auto duration = mtk::Real(clock() - begin_time_)/CLOCKS_PER_SEC;
std::cout << "Test " << test_number_ << " complete! ";
std::cout << "Elapsed: " << duration << " seconds." << std::endl;</pre>
00107
00108
00110 }
```

## 17.79 src/mtk\_uni\_stg\_grid\_1d.cc File Reference

Implementation of an 1D uniform staggered grid.

```
#include <iostream>
#include <iomanip>
#include <fstream>
#include "mtk_roots.h"
#include "mtk_enums.h"
#include "mtk_tools.h"
#include "mtk_uni_stg_grid_ld.h"
```

Include dependency graph for mtk\_uni\_stg\_grid\_1d.cc:



#### **Namespaces**

mtk

Mimetic Methods Toolkit namespace.

#### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::UniStgGrid1D &in)</li>

#### 17.79.1 Detailed Description

Implementation of an 1D uniform staggered grid.

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_uni\_stg\_grid\_1d.cc.

## 17.80 mtk\_uni\_stg\_grid\_1d.cc

```
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00026
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
0.0030
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 \ \mathrm{prior} \ \mathrm{written} \ \mathrm{permission} \ \mathrm{from} \ \mathrm{the} \ \mathrm{copyright} \ \mathrm{holders}.
00033
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #include <iostream>
00057 #include <iomanip>
00058 #include <fstream>
00060 #include "mtk_roots.h"
00061 #include "mtk_enums.h"
00062 #include "mtk_tools.h'
00063
00064 #include "mtk_uni_stg_grid_ld.h"
00065
00066 namespace mtk {
00067
00068 std::ostream& operator <<(std::ostream &stream, mtk::UniStgGridlD &in) {
00069
        stream << '[' << in.west_bndy_x_ << ':' << in.num_cells_x_ << ':' << in.east_bndy_x_ << "] = " << std::endl << std::endl;
00070
00071
00072
00074
00075
        stream << "x:":
        for (unsigned int ii = 0; ii < in.discrete_domain_x_.size(); ++ii) {</pre>
00076
00077
          stream << std::setw(10) << in.discrete_domain_x_[ii];</pre>
```

```
00078
00079
        stream << std::endl;
00080
00082
00083
        if (in.nature_ == mtk::SCALAR) {
00084
         stream << "u:";
00085
00086
       else {
00087
         stream << "v:";
00088
00089
        for (unsigned int ii = 0; ii < in.discrete_field_u_.size(); ++ii) {</pre>
00090
         stream << std::setw(10) << in.discrete_field_u_[ii];</pre>
00091
00092
00093
        stream << std::endl;
00094
00095
       return stream;
00096 }
00097 }
00098
00099 mtk::UniStgGrid1D::UniStgGrid1D():
00100
          nature ().
00101
          discrete_domain_x_(),
00102
          discrete_field_u_(),
00103
          west_bndy_x_(),
          east_bndy_x_(),
00104
00105
          num_cells_x_(),
00106
          delta_x_() {}
00107
00108 mtk::UniStgGrid1D::UniStgGrid1D(const
     UniStgGrid1D &grid):
00109
         nature_(grid.nature_),
00110
          west_bndy_x_(grid.west_bndy_x_),
00111
          east_bndy_x_(grid.east_bndy_x_),
00112
          num_cells_x_(grid.num_cells_x_),
00113
          delta_x_(grid.delta_x_) {
00114
00115
          std::copy(grid.discrete_domain_x_.begin(),
00116
                    grid.discrete_domain_x_.begin() + grid.
     discrete_domain_x_.size(),
00117
                   discrete_domain_x_.begin());
00118
00119
          std::copy(grid.discrete_field_u_.begin(),
00120
                    grid.discrete_field_u_.begin() + grid.
     discrete_field_u_.size(),
00121
                    discrete_field_u_.begin());
00122 }
00123
00124 mtk::UniStgGrid1D::UniStgGrid1D(const Real &west_bndy_x,
00125
                                       const Real &east_bndy_x,
00126
                                       const int &num_cells_x,
00127
                                       const mtk::FieldNature &nature) {
00128
00129
        #if MTK_DEBUG_LEVEL > 0
00130
       mtk::Tools::Prevent(west_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00131
        mtk::Tools::Prevent(east_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00132
       mtk::Tools::Prevent(east_bndy_x <= west_bndy_x, __FILE__, __LINE__, __func__);</pre>
00133
       mtk::Tools::Prevent(num_cells_x < 0, __FILE__, __LINE__, __func__);</pre>
00134
00135
00136
       nature_ = nature;
00137
        west_bndy_x_ = west_bndy_x;
00138
        east_bndy_x_ = east_bndy_x;
00139
       num_cells_x_ = num_cells_x;
00140
00141
       delta_x_ = (east_bndy_x - west_bndy_x)/((mtk::Real) num_cells_x);
00142 }
00143
00144 mtk::UniStgGrid1D::~UniStgGrid1D() {}
00145
00146 mtk::Real mtk::UniStgGrid1D::west_bndy_x() const {
00147
00148
        return west bndv x :
00149 }
00150
00151 mtk::Real mtk::UniStgGrid1D::east bndv x() const {
00152
00153
        return east_bndy_x_;
00154 }
0.0155
00156 mtk::Real mtk::UniStgGrid1D::delta_x() const {
```

```
00157
00158
        return delta_x_;
00159 }
00160
00161 mtk::Real *mtk::UniStgGrid1D::discrete_domain_x() {
00162
00163
        return discrete_domain_x_.data();
00164 }
00165
00166 mtk::Real *mtk::UniStgGrid1D::discrete_field_u() {
00168
        return discrete_field_u_.data();
00169 }
00170
00171 int mtk::UniStgGrid1D::num_cells_x() const {
00172
00173
        return num cells x :
00174 }
00175
00176 void mtk::UniStgGrid1D::BindScalarField(
00177
          mtk::Real (*ScalarField) (mtk::Real xx)) {
00178
00179
        #if MTK DEBUG LEVEL > 0
00180
       mtk::Tools::Prevent(nature_ == mtk::VECTOR, __FILE__, __LINE__, __func__);
00181
        #endif
00182
00184
00185
        discrete_domain_x_.reserve(num_cells_x_ + 2);
00186
00187
        discrete_domain_x_.push_back(west_bndy_x_);
00188
        #ifdef MTK_PRECISION_DOUBLE
00189
        auto first_center = west_bndy_x_ + delta_x_/2.0;
00190
        #else
00191
        auto first_center = west_bndy_x_ + delta_x_/2.0f;
00192
        #endif
00193
        {\tt discrete\_domain\_x\_.push\_back\,(first\_center)\,;}
00194
        for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00195
          discrete_domain_x_.push_back(first_center + ii*delta_x_);
00196
00197
        discrete_domain_x_.push_back(east_bndy_x_);
00198
00200
00201
        discrete_field_u_.reserve(num_cells_x_ + 2);
00202
00203
        discrete_field_u_.push_back(ScalarField(west_bndy_x_));
00204
00205
        {\tt discrete\_field\_u\_.push\_back\,(ScalarField\,(first\_center)\,)\,;}
00206
        for (auto ii = 1; ii < num_cells_x_; ++ii)</pre>
00207
          \label{linear_content} \\ \texttt{discrete\_field\_u\_.push\_back(ScalarField(first\_center + ii * delta\_x\_));} \\
00208
00209
        \tt discrete\_field\_u\_.push\_back\,(ScalarField\,(east\_bndy\_x\_)\,)\,;
00210 }
00211
00212 void mtk::UniStgGrid1D::BindVectorField(
00213
         mtk::Real (*VectorField) (mtk::Real xx)) {
00214
00215
        #if MTK_DEBUG_LEVEL > 0
00216
        mtk::Tools::Prevent(nature_ == mtk::SCALAR, __FILE__, __LINE__, __func__);
00217
00218
00220
00221
        discrete_domain_x_.reserve(num_cells_x_ + 1);
00222
00223
        discrete_domain_x_.push_back(west_bndy_x_);
        for (auto ii = 1; ii < num_cells_x_; ++ii) {</pre>
00224
00225
          discrete_domain_x_.push_back(west_bndy_x_ + ii*delta_x_);
00226
00227
        discrete_domain_x_.push_back(east_bndy_x_);
00228
00230
00231
        discrete_field_u_.reserve(num_cells_x_ + 1);
00232
        discrete_field_u_.push_back(VectorField(west_bndy_x_));
00233
00234
        for (auto ii = 1; ii < num cells x ; ++ii) {</pre>
00235
          discrete_field_u_.push_back(VectorField(west_bndy_x_ + ii*delta_x_));
00236
00237
        discrete field u .push back(VectorField(east bndy x ));
00238 }
00239
00240 bool mtk::UniStgGrid1D::WriteToFile(std::string filename,
00241
                                             std::string space_name,
```

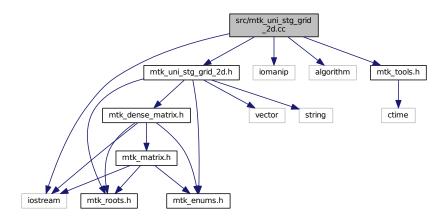
```
00242
                                                 std::string field_name) {
00243
00244
         std::ofstream output_dat_file; // Output file.
00245
00246
         output_dat_file.open(filename);
00247
00248
         if (!output_dat_file.is_open()) {
00249
           return false;
00250
00251
00252
         output_dat_file << "# " << space_name << ' ' << field_name << std::endl;</pre>
        for (unsigned int ii = 0; ii < discrete_domain_x_.size(); ++ii) {
  output_dat_file << discrete_domain_x_[ii] << ' ' << discrete_field_u_[ii] <</pre>
00253
00254
00255
             std::endl;
00256
00257
00258
        output_dat_file.close();
00259
00260
        return true;
00261 }
```

## 17.81 src/mtk\_uni\_stg\_grid\_2d.cc File Reference

Implementation of a 2D uniform staggered grid.

```
#include <iostream>
#include <iomanip>
#include <algorithm>
#include "mtk_tools.h"
#include "mtk_uni_stg_grid_2d.h"
```

Include dependency graph for mtk\_uni\_stg\_grid\_2d.cc:



## **Namespaces**

• mtk

Mimetic Methods Toolkit namespace.

#### **Functions**

std::ostream & mtk::operator<< (std::ostream &stream, mtk::UniStgGrid2D &in)</li>

#### 17.81.1 Detailed Description

Implementation of a 2D uniform staggered grid.

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk uni stg grid 2d.cc.

## 17.82 mtk\_uni\_stg\_grid\_2d.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00026
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00033
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00043
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00056 #include <iostream>
00057 #include <iomanip>
00058
00059 #include <algorithm>
00060
00061 #include "mtk tools.h"
00062 #include "mtk_uni_stg_grid_2d.h"
00063
00064 namespace mtk {
00065
00066 std::ostream& operator <<(std::ostream &stream, mtk::UniStgGrid2D &in) {
00067
        stream << '[' << in.west_bndy_x_ << ':' << in.num_cells_x_ << ':' <<
00068
       in.east_bndy_x_ << "] x ";
00069
```

```
00070
00071
         stream << '[' << in.south_bndy_y_ << ':' << in.num_cells_y_ << ':' <<
00072
         in.north_bndy_y_ << "] = " << std::endl << std::endl;
00073
00075
00076
         stream << "x:";
00077
         for (unsigned int ii = 0; ii < in.discrete_domain_x_.size(); ++ii) {</pre>
00078
         stream << std::setw(10) << in.discrete_domain_x_[ii];</pre>
00079
00080
        stream << std::endl;
00081
00082
        stream << "v:";
00083
        for (unsigned int ii = 0; ii < in.discrete_domain_y_.size(); ++ii) {</pre>
         stream << std::setw(10) << in.discrete_domain_y_[ii];</pre>
00085
00086
        stream << std::endl;</pre>
00087
00089
00090
        if (in.nature_ == mtk::SCALAR) {
         stream << "u:";
00091
00092
00093
        else {
00094
          stream << "v:";
00095
00096
        if (in.discrete_field_u_.size() > 0) {
  for (unsigned int ii = 0; ii < in.num_cells_x_ + 2; ++ii) {</pre>
00097
            for (unsigned int jj = 0; jj < in.num_cells_y_ + 2; ++jj) {
   stream << std::setw(10) << in.discrete_field_u_[ii*in.
00098
00099
      num_cells_y_ + jj];
00100
00101
             stream << std::endl;
00102
00103
00104
00105
        stream << std::endl;
00106
00107
       return stream;
00108 }
00109 }
00110
00111 mtk::UniStgGrid2D::UniStgGrid2D():
00112
          nature_(),
00113
          discrete_domain_x_(),
00114
          discrete_domain_y_(),
00115
          discrete_field_u_(),
00116
          west\_bndy\_x\_(),
00117
          east_bndy_x_(),
00118
          num_cells_x_(),
00119
          delta_x_(),
00120
          south_bndy_y_(),
          north_bndy_y_(),
00121
          num_cells_y_(),
00122
00123
          delta_y_() {}
00124
00125 mtk::UniStgGrid2D::UniStgGrid2D(const
      UniStgGrid2D &grid):
00126
          nature_(grid.nature_),
00127
          west_bndy_x_(grid.west_bndy_x_),
00128
          east_bndy_x_(grid.east_bndy_x_),
00129
          num_cells_x_(grid.num_cells_x_),
00130
          delta_x_(grid.delta_x_),
00131
          south_bndy_y_(grid.south_bndy_y_),
00132
          north_bndy_y_(grid.north_bndy_y_),
00133
          num_cells_y_(grid.num_cells_y_),
          delta_y_(grid.delta_y_) {
00134
00135
00136
          std::copy(grid.discrete_domain_x_.begin(),
00137
                     grid.discrete_domain_x_.begin() + grid.
     discrete_domain_x_.size(),
00138
                     discrete_domain_x_.begin());
00139
          std::copy(grid.discrete_domain_y_.begin(),
00140
00141
                     grid.discrete_domain_y_.begin() + grid.
      discrete_domain_y_.size(),
00142
                     discrete_domain_y_.begin());
00143
          std::copy(grid.discrete_field_u_.begin(),
00144
00145
                     grid.discrete_field_u_.begin() + grid.
      discrete_field_u_.size(),
00146
                     discrete_field_u_.begin());
00147 }
```

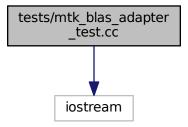
```
00148
00149 mtk::UniStgGrid2D::UniStgGrid2D(const Real &west_bndy_x,
                                            const Real &east_bndy_x,
                                            const int &num_cells_x,
00151
00152
                                            const Real &south_bndy_y,
00153
                                            const Real &north_bndy_y,
00154
                                            const int &num_cells_y,
00155
                                            const mtk::FieldNature &nature) {
00156
00157
         #if MTK_DEBUG_LEVEL > 0
        mtk::Tools::Prevent(west_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(east_bndy_x < mtk::kZero, __FILE__, __LINE__, __func__);</pre>
00159
        mtk::Tools::Prevent(east_bndy_x <= west_bndy_x, __FILE__, __LINE__, _func__);
mtk::Tools::Prevent(num_cells_x < 0, __FILE__, __LINE__, _func__);</pre>
00160
00161
        mtk::Tools::Prevent(south_bndy_y < mtk::kZero, __FILE__, __LINE__, __func__)
00162
00163
        mtk::Tools::Prevent(north_bndy_y < mtk::kZero, __FILE__, __LINE__, __func__)</pre>
00164
        mtk::Tools::Prevent(north_bndy_y <= south_bndy_y,</pre>
         __FILE__, __LINE__, __func__);
mtk::Tools::Prevent(num_cells_y < 0, __FILE__, __LINE__, __func__);
00165
00166
00167
         #endif
00168
00169
         nature_ = nature;
00170
00171
         west_bndy_x_ = west_bndy_x;
        east_bndy_x_ = east_bndy_x;
num_cells_x_ = num_cells_x;
00172
00173
00174
00175
         south_bndy_y_ = south_bndy_y;
         north_bndy_y_ = north_bndy_y;
num_cells_y_ = num_cells_y;
00176
00177
00178
         delta_x_ = (east_bndy_x - west_bndy_x)/((mtk::Real) num_cells_x);
00179
00180
         delta_y_ = (north_bndy_y - south_bndy_y)/((mtk::Real) num_cells_y);
00181 }
00182
00183 mtk::UniStgGrid2D::~UniStgGrid2D() {}
00184
00185 mtk::Real mtk::UniStgGrid2D::west_bndy_x() const {
00186
00187
         return west_bndy_x_;
00188 }
00189
00190 mtk::Real mtk::UniStgGrid2D::east_bndy_x() const {
00191
00192
         return east_bndy_x_;
00193 }
00194
00195 mtk::Real mtk::UniStgGrid2D::south_bndy_y() const {
00196
00197
         return south_bndy_y_;
00198 }
00199
00200 mtk::Real mtk::UniStgGrid2D::north_bndy_y() const {
00201
00202
         return north_bndy_y_;
00203 }
```

## 17.83 tests/mtk\_blas\_adapter\_test.cc File Reference

Test file for the mtk::BLASAdapter class.

#include <iostream>

Include dependency graph for mtk\_blas\_adapter\_test.cc:



#### **Functions**

• int main ()

### 17.83.1 Detailed Description

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_blas\_adapter\_test.cc.

#### 17.83.2 Function Documentation

```
17.83.2.1 int main ( )
```

Definition at line 107 of file mtk\_blas\_adapter\_test.cc.

## 17.84 mtk\_blas\_adapter\_test.cc

```
00001  
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State  
00010 University. All rights reserved.  
00011  
00012 Redistribution and use in source and binary forms, with or without modification,  
00013 are permitted provided that the following conditions are met:  
00014  
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu  
00016 and a copy of the modified files should be reported once modifications are  
00017 completed. Documentation related to said modifications should be included.  
00018  
00019 2. Redistributions of source code must be done through direct  
00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk  
00021  
00022 3. Redistributions of source code must retain the above copyright notice, this  
00023 list of conditions and the following disclaimer.
```

```
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00031
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void Test1() {
00061
00062
       mtk::Tools::BeginTestNo(1);
00063
00064
       int rr = 2;
00065
       int cc = 3;
00066
00067
       mtk::DenseMatrix aa(rr,cc);
00068
00069
        aa.SetValue(0,0,1.0);
00070
        aa.SetValue(0,1,2.0);
00071
        aa.SetValue(0,2,3.0);
00072
        aa.SetValue(1,0,4.0);
00073
        aa.SetValue(1,1,5.0);
00074
       aa.SetValue(1,2,6.0);
00075
00076
        std::cout << aa << std::endl;
00077
00078
       mtk::DenseMatrix bb(cc,rr);
00079
08000
       bb.SetValue(0,0,7.0);
        bb.SetValue(0,1,8.0);
00081
00082
        bb.SetValue(1,0,9.0);
00083
        bb.SetValue(1,1,10.0);
        bb.SetValue(2,0,11.0);
00084
00085
        bb.SetValue(2,1,12.0);
00086
00087
        std::cout << bb << std::endl;
00088
00089
       mtk::DenseMatrix pp = mtk::BLASAdapter::RealDenseMM(aa,bb);
00090
00091
       std::cout << pp << std::endl;
00092
00093
       mtk::Tools::EndTestNo(1);
00094 }
00095
00096 int main () {
00097
00098
        std::cout << "Testing mtk::BLASAdapter class." << std::endl;</pre>
00099
00100
        Test1();
00101 }
00102
00103 #else
00104 #include <iostream>
```

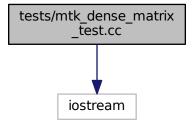
```
00105 using std::cout;
00106 using std::endl;
00107 int main () {
00108    cout << "This code HAS to be compiled with support for C++11." << endl;
00109    cout << "Exiting..." << endl;
00110 }
00111 #endif</pre>
```

## 17.85 tests/mtk\_dense\_matrix\_test.cc File Reference

Test file for the mtk::DenseMatrix class.

```
#include <iostream>
```

Include dependency graph for mtk\_dense\_matrix\_test.cc:



#### **Functions**

• int main ()

#### 17.85.1 Detailed Description

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_dense\_matrix\_test.cc.

#### 17.85.2 Function Documentation

```
17.85.2.1 int main ( )
```

Definition at line 285 of file mtk\_dense\_matrix\_test.cc.

## 17.86 mtk\_dense\_matrix\_test.cc

00001

```
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed. Documentation related to said modifications should be included.
00019 2. Redistributions of source code must be done through direct
00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00022 3. Redistributions of source code must retain the above copyright notice, this
00023 list of conditions and the following disclaimer.
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00028
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00031
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00041
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057 #include <ctime>
00058
00059 #include "mtk.h"
00060
00061 void Test1() {
00062
00063
       mtk::Tools::BeginTestNo(1);
00064
00065
       mtk::DenseMatrix ml;
00066
00067
       std::cout << m1 << std::endl;
00068
00069
       mtk::Tools::EndTestNo(1);
00070 }
00071
00072 void Test2() {
00073
00074
       mtk::Tools::BeginTestNo(2);
00075
00076
        int rr = 4;
00077
        int cc = 7;
00078
00079
       mtk::DenseMatrix m2(rr,cc);
00080
00081
        std::cout << m2 << std::endl;
00082
00083
       mtk::Tools::EndTestNo(2);
00084 }
00085
00086 void Test3() {
00087
00088
       mtk::Tools::BeginTestNo(3);
```

```
00089
00090
        int rank = 5;
00091
        bool padded = true;
00092
        bool transpose = false;
00093
00094
        mtk::DenseMatrix m3(rank,padded,transpose);
00095
00096
        std::cout << m3 << std::endl;
00097
00098
        mtk::Tools::EndTestNo(3);
00099 }
00100
00101 void Test4() {
00102
00103
        mtk::Tools::BeginTestNo(4);
00104
00105
        int rank = 5:
        bool padded = false;
00106
00107
        bool transpose = false;
00108
00109
        mtk::DenseMatrix m4(rank,padded,transpose);
00110
00111
        std::cout << m4 << std::endl;
00112
00113
       mtk::Tools::EndTestNo(4);
00114 }
00115
00116 void Test5() {
00117
00118
        mtk::Tools::BeginTestNo(5);
00119
00120
        int rr = 4:
00121
        int cc = 7;
00122
        mtk::DenseMatrix m5(rr,cc);
00123
00124
00125
        for (auto ii = 0; ii < rr; ++ii) {</pre>
00126
          for (auto jj = 0; jj < cc; ++jj) {</pre>
            m5.SetValue(ii,jj,(mtk::Real) ii + jj);
00127
00128
00129
        }
00130
00131
        std::cout << m5 << std::endl;
00132
00133
        mtk::Real *vals = m5.data();
00134
00135
         for (auto ii = 0; ii < rr; ++ii) {</pre>
          for (auto jj = 0; jj < cc; ++jj) {
  std::cout << " " << vals[ii*cc + jj];</pre>
00136
00137
00138
00139
          std::cout << std::endl;
00140
00141
        std::cout << std::endl;</pre>
00142
00143
         for (auto ii = 0; ii < rr; ++ii) {</pre>
          for (auto jj = 0; jj < cc; ++jj) {
  std::cout << " " << m5.GetValue(ii,jj);</pre>
00144
00145
00146
00147
          std::cout << std::endl;
00148
00149
        std::cout << std::endl;</pre>
00150
00151
        mtk::Tools::EndTestNo(5);
00152 }
00153
00154 void Test6() {
00155
00156
        mtk::Tools::BeginTestNo(6);
00157
00158
        bool transpose = false;
00159
        int generator_length = 3;
00160
        int progression_length = 4;
00161
00162
        mtk::Real generator[] = \{-0.5, 0.5, 1.5\};
00163
00164
        mtk::DenseMatrix m6(generator, generator_length, progression_length, transpose);
00165
00166
        std::cout << m6 << std::endl;
00167
00168
        transpose = true;
00169
```

```
00170
        mtk::DenseMatrix m7(generator,generator_length,progression_length,transpose);
00171
00172
        std::cout << m7 << std::endl;
00173
00174
00175
       mtk::Tools::EndTestNo(6);
00176 }
00177
00178 void Test7() {
00179
00180
       mtk::Tools::BeginTestNo(7);
00181
00182
        bool padded = false;
00183
        bool transpose = false;
00184
        int lots_of_rows = 2;
00185
        int lots_of_cols = 5;
00186
        mtk::DenseMatrix m8(lots_of_rows, padded, transpose);
00187
00188
        std::cout << m8 << std::endl;
00189
00190
       mtk::DenseMatrix m9(lots of rows, lots of cols);
00191
00192
        for (auto ii = 0; ii < lots_of_rows; ++ii) {</pre>
00193
         for (auto jj = 0; jj < lots_of_cols; ++jj) {</pre>
00194
           m9.SetValue(ii,jj,(mtk::Real) ii*lots_of_cols + jj + 1);
00195
        }
00196
00197
00198
        std::cout << m9 << std::endl;
00199
00200
       mtk::DenseMatrix m10 = mtk::DenseMatrix::Kron(m8.m9);
00201
00202
        std::cout << m10 << std::endl;
00203
00204
       mtk::Tools::EndTestNo(7);
00205 }
00206
00207 void Test8() {
00208
00209
        mtk::Tools::BeginTestNo(8);
00210
00211
        int lots_of_rows = 4;
        int lots_of_cols = 3;
00212
00213
        mtk::DenseMatrix m11(lots_of_rows,lots_of_cols);
00214
00215
        for (auto ii = 0; ii < lots_of_rows; ++ii) {</pre>
00216
         for (auto jj = 0; jj < lots_of_cols; ++jj) {</pre>
00217
            m11.SetValue(ii, jj, (mtk::Real) ii*lots_of_cols + jj + 1);
00218
00219
00220
00221
        std::cout << m11 << std::endl;
00222
00223
        m11.Transpose();
00224
00225
        std::cout << m11 << std::endl;
00226
00227
        mtk::DenseMatrix m12;
00228
00229
       m12 = m11;
00230
00231
        std::cout << m12 << std::endl;
00232
00233
       mtk::Tools::EndTestNo(8);
00234 }
00235
00236 void Test9() {
00237
00238
       mtk::Tools::BeginTestNo(9);
00239
00240
        bool transpose = false;
00241
        int qq 1 = 3;
        int progression_length = 4;
00242
00243
        mtk::Real gg[] = {-0.5, 0.5, 1.5};
00244
00245
       mtk::DenseMatrix m13(gg, gg_l ,progression_length, transpose);
00246
00247
        std::cout << m13 << std::endl;
00248
00249
        mtk::DenseMatrix m14;
00250
```

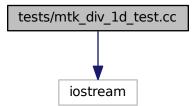
```
00251
        m14 = m13;
00252
00253
        std::cout << m14 << std::endl;
00254
00255
        m13.Transpose();
00256
00257
        std::cout << m13 << std::endl;
00258
00259
00260
        std::cout << m14 << std::endl;
00262
00263
       mtk::Tools::EndTestNo(9);
00264 }
00265
00266 int main () {
00267
        std::cout << "Testing mtk::DenseMatrix class." << std::endl;</pre>
00268
00269
00270
        Test1();
00271
        Test2();
00272
        Test3();
00273
        Test4();
00274
        Test5();
00275
        Test6():
00276
        Test7();
00277
        Test8():
00278
        Test9();
00279 }
00280
00281 #else
00282 #include <iostream>
00283 using std::cout;
00284 using std::endl;
00285 int main () {    00286 cout << "This code HAS to be compiled with support for C++11." << endl;
00287
       cout << "Exiting..." << endl;</pre>
00288 1
00289 #endif
```

## 17.87 tests/mtk\_div\_1d\_test.cc File Reference

Testing the mimetic 1D divergence, constructed with the CBS algorithm.

```
#include <iostream>
```

Include dependency graph for mtk\_div\_1d\_test.cc:



## **Functions**

• int main ()

#### 17.87.1 Detailed Description

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_div\_1d\_test.cc.

#### 17.87.2 Function Documentation

```
17.87.2.1 int main ( )
```

Definition at line 248 of file mtk\_div\_1d\_test.cc.

### 17.88 mtk div 1d test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00011
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed. Documentation related to said modifications should be included.
00018
00019 2. Redistributions of source code must be done through direct
00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00021
00022 3. Redistributions of source code must retain the above copyright notice, this
00023 list of conditions and the following disclaimer.
00024
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void Test1() {
```

```
00061
00062
       mtk::Tools::BeginTestNo(1);
00063
00064
       mtk::Div1D div2;
00065
00066
       bool info = div2.ConstructDiv1D();
00067
00068
        if (!info) {
00069
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00070
00071
00072
       std::cout << div2 << std::endl;
00073
00074
       mtk::Tools::EndTestNo(1);
00075 }
00076
00077 void Test2() {
00078
00079
       mtk::Tools::BeginTestNo(2);
00080
00081
       mtk::Div1D div4;
00082
00083
       bool info = div4.ConstructDiv1D(4);
00084
00085
        if (!info) {
         std::cerr << "Mimetic div (4th order) could not be built." << std::endl;
00086
        }
00087
00088
00089
        std::cout << div4 << std::endl;
00090
00091
       mtk::Tools::EndTestNo(2);
00092 }
00093
00094 void Test3() {
00095
00096
       mtk::Tools::BeginTestNo(3);
00097
       mtk::Div1D div6;
00098
00099
00100
       bool info = div6.ConstructDiv1D(6);
00101
00102
        if (!info) {
         std::cerr << "Mimetic div (6th order) could not be built." << std::endl;</pre>
00103
00104
00105
00106
        std::cout << div6 << std::endl;
00107
00108
       mtk::Tools::EndTestNo(3);
00109 }
00110
00111 void Test4() {
00112
00113
       mtk::Tools::BeginTestNo(4);
00114
00115
       mtk::Div1D div8;
00116
00117
        bool info = div8.ConstructDiv1D(8);
00118
00119
        if (!info) {
00120
         std::cerr << "Mimetic div (8th order) could not be built." << std::endl;
00121
00122
00123
       std::cout << div8 << std::endl;
00124
00125
       mtk::Tools::EndTestNo(4);
00126 }
00127
00128 void Test5() {
00129
00130
       mtk::Tools::BeginTestNo(5);
00131
00132
       mtk::Div1D div10;
00133
00134
       bool info = div10.ConstructDiv1D(10);
00135
00136
        if (!info) {
         std::cerr << "Mimetic div (10th order) could not be built." << std::endl;
00137
00138
00139
00140
        std::cout << div10 << std::endl:
00141
```

```
00142 mtk::Tools::EndTestNo(5);
00143 }
00144
00145 void Test6() {
00146
00147
       mtk::Tools::BeginTestNo(6);
00148
00149
       mtk::Div1D div12;
00150
00151
       bool info = div12.ConstructDiv1D(12);
00152
00153
        if (!info) {
00154
         std::cerr << "Mimetic div (12th order) could not be built." << std::endl;
00155
00156
00157
        std::cout << div12 << std::endl;
00158
00159
       mtk::Tools::EndTestNo(6);
00160 }
00161
00162 void Test7() {
00163
00164
       mtk::Tools::BeginTestNo(7);
00165
00166
       mtk::Div1D div14;
00167
00168
        bool info = div14.ConstructDiv1D(14);
00169
00170
        if (!info) {
         std::cerr << "Mimetic div (14th order) could not be built." << std::endl;
00171
        }
00172
00173
00174
        std::cout << div14 << std::endl;
00175
00176
       mtk::Tools::EndTestNo(7);
00177 }
00178
00179 void Test8() {
00180
        mtk::Tools::BeginTestNo(8);
00181
00182
00183
       mtk::Div1D div2;
00184
00185
       bool info = div2.ConstructDiv1D();
00186
00187
        if (!info) {
00188
         std::cerr << "Mimetic div (2nd order) could not be built." << std::endl;
00189
00190
00191
        std::cout << div2 << std::endl;
00192
00193
       mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00194
00195
        std::cout << grid << std::endl;
00196
00197
        mtk::DenseMatrix div2m(div2.ReturnAsDenseMatrix(grid));
00198
00199
        std::cout << div2m << std::endl;
00200
00201
       mtk::Tools::EndTestNo(8);
00202 }
00203
00204 void Test9() {
00205
00206
       mtk::Tools::BeginTestNo(9);
00207
00208
       mtk::Div1D div4;
00209
00210
        bool info = div4.ConstructDiv1D(4);
00211
00212
        if (!info) {
00213
         std::cerr << "Mimetic div (4th order) could not be built." << std::endl;</pre>
00214
00215
00216
        std::cout << div4 << std::endl;
00217
00218
       mtk::UniStgGrid1D grid(0.0, 1.0, 11);
00219
00220
        std::cout << grid << std::endl;
00221
       mtk::DenseMatrix div4m(div4.ReturnAsDenseMatrix(grid));
00222
```

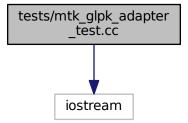
```
00223
00224
         std::cout << div4m << std::endl;
00225
00226
        mtk::Tools::EndTestNo(9);
00227 }
00228
00229 int main () {
00230
00231
         std::cout << "Testing mtk::Div1D class." << std::endl;</pre>
00232
00234
        Test2();
00235
         Test3();
00236
        Test4();
00237
         Test5();
00238
        Test6();
00239
         Test7();
00240
        Test8();
00241
        Test9();
00242 }
00243
00244 #else
00245 #include <iostream>
00246 using std::cout;
00247 using std::endl;
00248 int main () {
00249 cout << "This code HAS to be compiled with support for C++11." << endl;
00250 cout << "Exiting..." << endl;
00251 }
00252 #endif
```

## 17.89 tests/mtk\_glpk\_adapter\_test.cc File Reference

Test file for the mtk::GLPKAdapter class.

```
#include <iostream>
```

Include dependency graph for mtk glpk adapter test.cc:



#### **Functions**

• int main ()

#### 17.89.1 Detailed Description

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Test the mtk::GLPKAdapter class.

Definition in file mtk\_glpk\_adapter\_test.cc.

#### 17.89.2 Function Documentation

```
17.89.2.1 int main ( )
```

Definition at line 81 of file mtk\_glpk\_adapter\_test.cc.

## 17.90 mtk\_glpk\_adapter\_test.cc

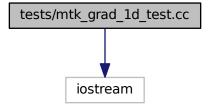
```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00026
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00033
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059 #include <ctime>
00060
00061 #include "mtk.h"
00062
```

```
00063 void Test1() {
00064
        mtk::Tools::BeginTestNo(1);
00066
00067
       mtk::Tools::EndTestNo(1);
00068 }
00069
00070 int main () {
00071
00072
        std::cout << "Testing mtk::GLPKAdapter class." << std::endl;</pre>
00073
00074
       Test1();
00075 }
00076
00077 #else
00078 #include <iostream>
00079 using std::cout;
00080 using std::endl;
00081 int main () {
00082 cout << "This code HAS to be compiled with support for C++11." << end;
       cout << "Exiting..." << endl;
00083
00084 }
00085 #endif
```

## 17.91 tests/mtk\_grad\_1d\_test.cc File Reference

Testing the mimetic 1D gradient, constructed with the CBS algorithm.

```
#include <iostream>
Include dependency graph for mtk_grad_1d_test.cc:
```



#### **Functions**

• int main ()

### 17.91.1 Detailed Description

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_grad\_1d\_test.cc.

#### 17.91.2 Function Documentation

```
17.91.2.1 int main ( )
```

Definition at line 186 of file mtk grad 1d test.cc.

## 17.92 mtk\_grad\_1d\_test.cc

```
00001
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State
00010 University. All rights reserved.
00012 Redistribution and use in source and binary forms, with or without modification,
00013 are permitted provided that the following conditions are met:
00014
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00016 and a copy of the modified files should be reported once modifications are
00017 completed. Documentation related to said modifications should be included.
00018
00019 2. Redistributions of source code must be done through direct
00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00021
00022 3. Redistributions of source code must retain the above copyright notice, this
00023 list of conditions and the following disclaimer.
00024
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00028
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00031
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00035
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057
00058 #include "mtk.h"
00059
00060 void Test1() {
00061
00062
       mtk::Tools::BeginTestNo(1);
00063
00064
       mtk::Grad1D grad2;
00065
00066
        bool info = grad2.ConstructGrad1D();
00067
00068
        if (!info) {
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00069
00070
00071
00072
        std::cout << grad2 << std::endl;
00073
```

```
00074 mtk::Tools::EndTestNo(1);
00075 }
00076
00077 void Test2() {
00078
00079
       mtk::Tools::BeginTestNo(2);
08000
00081
       mtk::Grad1D grad4;
00082
00083
       bool info = grad4.ConstructGrad1D(4);
00084
00085
        if (!info) {
00086
         std::cerr << "Mimetic grad (4th order) could not be built." << std::endl;
00087
00088
00089
        std::cout << grad4 << std::endl;
00090
00091
       mtk::Tools::EndTestNo(2);
00092 }
00093
00094 void Test3() {
00095
00096
       mtk::Tools::BeginTestNo(3);
00097
00098
       mtk::Grad1D grad6;
00099
00100
       bool info = grad6.ConstructGrad1D(6);
00101
00102
        if (!info) {
         std::cerr << "Mimetic grad (6th order) could not be built." << std::endl;
00103
        }
00104
00105
00106
        std::cout << grad6 << std::endl;
00107
00108
       mtk::Tools::EndTestNo(3);
00109 }
00110
00111 void Test4() {
00112
       mtk::Tools::BeginTestNo(4);
00113
00114
00115
       mtk::Grad1D grad8;
00116
00117
       bool info = grad8.ConstructGrad1D(8);
00118
00119
        if (!info) {
00120
         std::cerr << "Mimetic grad (8th order) could not be built." << std::endl;
00121
00122
00123
        std::cout << grad8 << std::endl;
00124
00125
       mtk::Tools::EndTestNo(4);
00126 }
00127
00128 void Test5() {
00129
00130
       mtk::Tools::BeginTestNo(5);
00131
00132
       mtk::Grad1D grad10;
00133
00134
       bool info = grad10.ConstructGrad1D(10);
00135
00136
00137
         std::cerr << "Mimetic grad (10th order) could not be built." << std::endl;
00138
00139
00140
        std::cout << grad10 << std::endl;
00141
00142
       mtk::Tools::EndTestNo(5);
00143 }
00144
00145 void Test6() {
00146
00147
       mtk::Tools::BeginTestNo(6);
00148
00149
       mtk::Grad1D grad2;
00150
00151
        bool info = grad2.ConstructGrad1D();
00152
00153
        if (!info) {
          std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00154
```

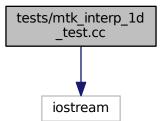
```
00155
00156
00157
        std::cout << grad2 << std::endl;
00158
00159
        mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00160
00161
        std::cout << grid << std::endl;</pre>
00162
00163
        mtk::DenseMatrix grad2m(grad2.ReturnAsDenseMatrix(grid));
00164
        std::cout << grad2m << std::endl;
00166
00167
        mtk::Tools::EndTestNo(6);
00168 }
00169
00170 int main () {
00171
00172
        std::cout << "Testing mtk::Grad1D class." << std::endl;</pre>
00173
00174
        Test1();
00175
        Test2();
00176
        Test3();
00177
        Test4();
00178
        Test5();
00179
        Test6();
00180 }
00181
00182 #else
00183 #include <iostream>
00184 using std::cout;
00185 using std::endl;
00186 int main () {
00187 cout << "This code HAS to be compiled with support for C++11." << endl;
00189 }
00190 #endif
```

# 17.93 tests/mtk\_interp\_1d\_test.cc File Reference

Testing the 1D interpolation.

#include <iostream>

Include dependency graph for mtk\_interp\_1d\_test.cc:



#### **Functions**

• int main ()

### 17.93.1 Detailed Description

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu : Johnny Corbino - jcorbino at mail dot sdsu dot edu

Definition in file mtk\_interp\_1d\_test.cc.

#### 17.93.2 Function Documentation

```
17.93.2.1 int main ( )
```

Definition at line 116 of file mtk\_interp\_1d\_test.cc.

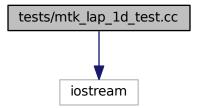
## 17.94 mtk\_interp\_1d\_test.cc

```
00001
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00023
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00026
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00030
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00037
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059
00060 #include "mtk.h"
```

```
00061
00062 void Test1() {
00063
00064
       mtk::Tools::BeginTestNo(1);
00065
00066
       mtk::Interp1D inter;
00067
00068
       bool info = inter.ConstructInterplD();
00069
00070
00071
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00072
00073
00074
        std::cout << inter << std::endl;</pre>
00075
00076
       mtk::Tools::EndTestNo(1);
00077 }
00078
00079 void Test2() {
08000
00081
       mtk::Tools::BeginTestNo(2);
00082
00083
       mtk::InterplD inter;
00084
00085
        bool info = inter.ConstructInterplD();
00086
00087
        if (!info) {
         std::cerr << "Mimetic grad (2nd order) could not be built." << std::endl;
00088
00089
00090
00091
        std::cout << inter << std::endl;
00092
00093
       mtk::UniStgGrid1D grid(0.0, 1.0, 5);
00094
00095
        std::cout << grid << std::endl;
00096
00097
       mtk::DenseMatrix interpm(inter.ReturnAsDenseMatrix(grid));
00098
00099
        std::cout << interpm << std::endl;</pre>
00100
00101
       mtk::Tools::EndTestNo(2);
00102 }
00103
00104 int main () {
00105
00106
        std::cout << "Testing mtk::Interp1D class." << std::endl;</pre>
00107
00108
       Test1();
00109
       Test2();
00110 }
00111
00112 #else
00113 #include <iostream>
00114 using std::cout;
00115 using std::endl;
00116 int main () {
00117 cout << "This code HAS to be compiled with support for C++11." << endl;
00118
       cout << "Exiting..." << endl;</pre>
00119 }
00120 #endif
```

# 17.95 tests/mtk\_lap\_1d\_test.cc File Reference

#include <iostream>
Include dependency graph for mtk\_lap\_1d\_test.cc:



## **Functions**

• int main ()

## 17.95.1 Function Documentation

17.95.1.1 int main ( )

Definition at line 156 of file mtk\_lap\_1d\_test.cc.

## 17.96 mtk\_lap\_1d\_test.cc

```
00001 #if __cplusplus == 201103L
00002
00003 #include <iostream>
00004
00005 #include "mtk.h"
00007 void Test1() {
00009
       mtk::Tools::BeginTestNo(1);
00011
       mtk::Lap1D lap2;
00012
00013
       bool info = lap2.ConstructLap1D();
00014
00015
        if (!info) {
00016
         std::cerr << "Mimetic lap (2nd order) could not be built." << std::endl;
00017
00018
00019
       mtk::Tools::EndTestNo(1);
00020 }
00021
00022 void Test2() {
00023
       mtk::Tools::BeginTestNo(2);
00024
00025
00026
       mtk::Lap1D lap4;
00027
```

```
00028
        bool info = lap4.ConstructLap1D(4);
00029
00030
        if (!info) {
00031
         std::cerr << "Mimetic lap (4th order) could not be built." << std::endl;
00032
00033
00034
       mtk::Tools::EndTestNo(2);
00035 }
00036
00037 void Test3() {
00038
00039
       mtk::Tools::BeginTestNo(3);
00040
00041
       mtk::Lap1D lap6;
00042
00043
       bool info = lap6.ConstructLap1D(6);
00044
00045
        if (!info) {
00046
         std::cerr << "Mimetic lap (6th order) could not be built." << std::endl;</pre>
00047
00048
00049
       mtk::Tools::EndTestNo(3);
00050 }
00051
00052 void Test4() {
00053
00054
       mtk::Tools::BeginTestNo(4);
00055
00056
       mtk::Lap1D lap8;
00057
00058
       bool info = lap8.ConstructLap1D(8);
00059
00060
        if (!info) {
         std::cerr << "Mimetic lap (8th order) could not be built." << std::endl;</pre>
00061
        }
00062
00063
00064
       mtk::Tools::EndTestNo(4);
00065 }
00066
00067 void Test5() {
00068
       mtk::Tools::BeginTestNo(5);
00069
00070
00071
       mtk::Lap1D lap10;
00072
00073
        bool info = lap10.ConstructLap1D(10);
00074
00075
        if (!info) {
00076
         std::cerr << "Mimetic lap (10th order) could not be built." << std::endl;
00077
00078
00079
       mtk::Tools::EndTestNo(5);
00080 }
00081
00082 void Test6() {
00083
00084
       mtk::Tools::BeginTestNo(6);
00085
00086
       mtk::Lap1D lap12;
00087
00088
       bool info = lap12.ConstructLap1D(12);
00089
00090
00091
         std::cerr << "Mimetic lap (12th order) could not be built." << std::endl;
00092
00093
00094
       mtk::Tools::EndTestNo(6);
00095 }
00096
00097 void Test7() {
00098
00099
       mtk::Tools::BeginTestNo(7);
00100
00101
       mtk::Lap1D lap4;
00102
00103
       bool info = lap4.ConstructLap1D(4);
00104
00105
        if (!info) {
00106
         std::cerr << "Mimetic lap (4th order) could not be built." << std::endl;
        }
00107
00108
```

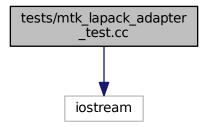
```
00109
        std::cout << lap4 << std::endl;
00110
       std::cout << std::endl;
00111
       mtk::Tools::EndTestNo(7);
00112
00113 }
00114
00115 void Test8() {
00116
00117
       mtk::Tools::BeginTestNo(8);
00118
       mtk::Lap1D lap4;
00120
00121
       bool info = lap4.ConstructLap1D(4);
00122
00123
        if (!info) {
00124
         std::cerr << "Mimetic lap (4th order) could not be built." << std::endl;
00125
00126
00127
        std::cout << lap4 << std::endl;
00128
       std::cout << std::endl;
00129
00130
       mtk::UniStgGrid1D aux(0.0, 1.0, 11);
00131
00132
       mtk::DenseMatrix lap4_m(lap4.ReturnAsDenseMatrix(aux));
00133
00134
        std::cout << lap4_m << std::endl;
00135
        std::cout << std::endl;
00136
00137
       mtk::Tools::EndTestNo(8);
00138 }
00139
00140 int main () {
00141
       std::cout << "Testing MTK 1D Laplacian" << std::endl;</pre>
00142
00143
00144
       Test1();
00145
        Test2();
00146
        Test3();
00147
        Test4();
00148
        Test5();
00149
        Test6();
00150
        Test7();
00151
       Test8();
00152 }
00153
00154 #else
00155 #include <iostream>
00156 int main () {
      std::cout << "This code HAS to be compiled to support C++11." << std::endl;
00157
00158
       std::cout << "Exiting..." << std::endl;</pre>
00159 }
00160 #endif
```

## 17.97 tests/mtk\_lapack\_adapter\_test.cc File Reference

Test file for the mtk::LAPACKAdapter class.

#include <iostream>

Include dependency graph for mtk\_lapack\_adapter\_test.cc:



#### **Functions**

• int main ()

## 17.97.1 Detailed Description

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Todo Test the mtk::LAPACKAdapter class.

Definition in file mtk\_lapack\_adapter\_test.cc.

### 17.97.2 Function Documentation

```
17.97.2.1 int main ( )
```

Definition at line 81 of file mtk\_lapack\_adapter\_test.cc.

## 17.98 mtk\_lapack\_adapter\_test.cc

```
00001
00010 /*
00010 /*
00011 Copyright (C) 2015, Computational Science Research Center, San Diego State
00012 University. All rights reserved.
00013
00014 Redistribution and use in source and binary forms, with or without modification,
00015 are permitted provided that the following conditions are met:
00016
00017 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu
00018 and a copy of the modified files should be reported once modifications are
00019 completed. Documentation related to said modifications should be included.
00020
00021 2. Redistributions of source code must be done through direct
```

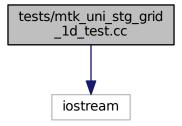
```
00022 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk
00024 3. Redistributions of source code must retain the above copyright notice, this
00025 list of conditions and the following disclaimer.
00027 4. Redistributions in binary form must reproduce the above copyright notice,
00028 this list of conditions and the following disclaimer in the documentation and/or
00029 other materials provided with the distribution.
00031 5. Usage of the binary form on proprietary applications shall require explicit
00032 prior written permission from the the copyright holders.
00034 6. Neither the name of the copyright holder nor the names of its contributors
00035 may be used to endorse or promote products derived from this software without
00036 specific prior written permission.
00038 The copyright holders provide no reassurances that the source code provided does
00039 not infringe any patent, copyright, or any other intellectual property rights of
00040 third parties. The copyright holders disclaim any liability to any recipient for
00041 claims brought against recipient by any third party for infringement of that
00042 parties intellectual property rights.
00044 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00045 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00046 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00047 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00048 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00049 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00050 LOSS OF USE, DATA, OR PROFITS: OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00051 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00052 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00053 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00054 */
00055
00056 #if __cplusplus == 201103L
00057
00058 #include <iostream>
00059 #include <ctime>
00060
00061 #include "mtk.h"
00062
00063 void Test1() {
00064
00065
       mtk::Tools::BeginTestNo(1);
00066
00067
       mtk::Tools::EndTestNo(1);
00068 }
00069
00070 int main () {
00071
00072
        std::cout << "Testing mtk::LAPACKAdapter class." << std::endl;</pre>
00073
00074
00075 }
00076
00077 #else
00078 #include <iostream>
00079 using std::cout;
00080 using std::endl;
00081 int main () {
00082 cout << "This code HAS to be compiled with support for C++11." << endl;
00083
       cout << "Exiting..." << endl;</pre>
00084 }
00085 #endif
```

## 17.99 tests/mtk\_uni\_stg\_grid\_1d\_test.cc File Reference

Test file for the mtk::UniStgGrid1D class.

#include <iostream>

Include dependency graph for mtk\_uni\_stg\_grid\_1d\_test.cc:



#### **Functions**

• int main ()

## 17.99.1 Detailed Description

**Author** 

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_uni\_stg\_grid\_1d\_test.cc.

#### 17.99.2 Function Documentation

```
17.99.2.1 int main ( )
```

Definition at line 164 of file mtk\_uni\_stg\_grid\_1d\_test.cc.

## 17.100 mtk\_uni\_stg\_grid\_1d\_test.cc

```
00001 00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State 00010 University. All rights reserved.
00011 00012 Redistribution and use in source and binary forms, with or without modification, 00013 are permitted provided that the following conditions are met:
00014 00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu 00016 and a copy of the modified files should be reported once modifications are 00017 completed. Documentation related to said modifications should be included.
00018 00019 2. Redistributions of source code must be done through direct 00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk 00021 00022 3. Redistributions of source code must retain the above copyright notice, this 00023 list of conditions and the following disclaimer.
```

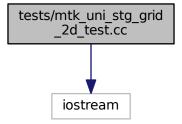
```
00024
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00031
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES
00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057 #include <ctime>
00058
00059 #include "mtk.h"
00060
00061 void Test1() {
00062
       mtk::Tools::BeginTestNo(1);
00063
00064
00065
       mtk::UniStgGrid1D gg;
00066
00067
       std::cout << gg << std::endl;
00068
00069
       mtk::Tools::EndTestNo(1);
00070 }
00071
00072 mtk::Real ScalarFieldOne(mtk::Real xx) {
00073
00074
        return 2.0*xx;
00075 }
00076
00077 void Test2() {
00078
00079
       mtk::Tools::BeginTestNo(2);
08000
00081
       mtk::Real aa = 0.0;
00082
       mtk::Real bb = 1.0;
00083
00084
        int nn = 5;
00085
00086
       mtk::UniStgGrid1D gg(aa, bb, nn);
00087
00088
       std::cout << gg << std::endl;
00089
00090
       gg.BindScalarField(ScalarFieldOne);
00091
00092
        std::cout << gg << std::endl;
00093
00094
       mtk::Tools::EndTestNo(2);
00095 }
00096
00097 void Test3() {
00098
00099
       mtk::Tools::BeginTestNo(3);
00100
00101
       mtk::Real aa = 0.0;
00102
       mtk::Real bb = 1.0;
00103
00104
        int nn = 5;
```

```
00105
00106
        mtk::UniStgGrid1D gg(aa, bb, nn);
00107
00108
        std::cout << gg << std::endl;
00109
00110
        gg.BindScalarField(ScalarFieldOne);
00111
00112
        std::cout << gg << std::endl;
00113
00114
        if(!gg.WriteToFile("mtk_uni_stg_grid_1d_test_03.dat", "x", "u(x)")) {
00115
         std::cerr << "Error writing to file." << std::endl;
00116
00117
00118
       mtk::Tools::EndTestNo(3);
00119 }
00121 mtk::Real VectorFieldXComponentOne(mtk::Real xx) {
00122
00123
        return xx*xx;
00124 }
00125
00126 void Test4() {
00127
00128
       mtk::Tools::BeginTestNo(4);
00129
00130
       mtk::Real aa = 0.0;
       mtk::Real bb = 1.0;
00131
00132
00133
        int nn = 20;
00134
00135
        mtk::UniStgGrid1D gg(aa, bb, nn, mtk::VECTOR);
00136
00137
        std::cout << gg << std::endl;
00138
00139
        gg.BindVectorField(VectorFieldXComponentOne);
00140
00141
        std::cout << gg << std::endl;
00142
        if(!gg.WriteToFile("mtk_uni_stg_grid_ld_test_04.dat", "x", "v(x)")) {
   std::cerr << "Error writing to file." << std::endl;</pre>
00143
00144
00145
00146
00147
        mtk::Tools::EndTestNo(4);
00148 }
00149
00150 int main () {
00151
        std::cout << "Testing mtk::UniStgGrid1D class." << std::endl;</pre>
00152
00153
00154
        Test1();
00155
        Test2();
00156
        Test3();
00157
       Test4();
00158 }
00159
00160 #else
00161 #include <iostream>
00162 using std::cout;
00163 using std::endl;
00164 int main () {
00165 cout << "This code HAS to be compiled with support for C++11." << endl;
       cout << "Exiting..." << endl;
00167 }
00168 #endif
```

## 17.101 tests/mtk\_uni\_stg\_grid\_2d\_test.cc File Reference

Test file for the mtk::UniStgGrid2D class.

#include <iostream>
Include dependency graph for mtk uni stg grid 2d test.cc:



## **Functions**

• int main ()

## 17.101.1 Detailed Description

#### **Author**

: Eduardo J. Sanchez (ejspeiro) - esanchez at mail dot sdsu dot edu

Definition in file mtk\_uni\_stg\_grid\_2d\_test.cc.

#### 17.101.2 Function Documentation

```
17.101.2.1 int main ( )
```

Definition at line 102 of file mtk\_uni\_stg\_grid\_2d\_test.cc.

## 17.102 mtk\_uni\_stg\_grid\_2d\_test.cc

```
00001  
00008 /*
00009 Copyright (C) 2015, Computational Science Research Center, San Diego State  
00010 University. All rights reserved.  
00011  
00012 Redistribution and use in source and binary forms, with or without modification,  
00013 are permitted provided that the following conditions are met:  
00014  
00015 1. Modifications to source code should be reported to: esanchez@mail.sdsu.edu  
00016 and a copy of the modified files should be reported once modifications are  
00017 completed. Documentation related to said modifications should be included.  
00018  
00019 2. Redistributions of source code must be done through direct  
00020 downloads from the project's GitHub page: http://www.csrc.sdsu.edu/mtk  
00021  
00022 3. Redistributions of source code must retain the above copyright notice, this  
00023 list of conditions and the following disclaimer.
```

```
00025 4. Redistributions in binary form must reproduce the above copyright notice,
00026 this list of conditions and the following disclaimer in the documentation and/or
00027 other materials provided with the distribution.
00029 5. Usage of the binary form on proprietary applications shall require explicit
00030 prior written permission from the the copyright holders.
00031
00032 6. Neither the name of the copyright holder nor the names of its contributors
00033 may be used to endorse or promote products derived from this software without
00034 specific prior written permission.
00036 The copyright holders provide no reassurances that the source code provided does
00037 not infringe any patent, copyright, or any other intellectual property rights of
00038 third parties. The copyright holders disclaim any liability to any recipient for
00039 claims brought against recipient by any third party for infringement of that
00040 parties intellectual property rights.
00042 THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND
00043 ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED
00044 WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE
00045 DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR
00046 ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES 00047 (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES;
00048 LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON
00049 ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT
00050 (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS
00051 SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.
00052 */
00053
00054 #if __cplusplus == 201103L
00055
00056 #include <iostream>
00057 #include <ctime>
00058
00059 #include "mtk.h"
00060
00061 void Test1() {
00062
       mtk::Tools::BeginTestNo(1);
00063
00064
00065
       mtk::UniStgGrid2D gg;
00066
00067
       std::cout << gg << std::endl;
00068
00069
       mtk::Tools::EndTestNo(1);
00070 }
00071
00072 void Test2() {
00073
00074
       mtk::Tools::BeginTestNo(2);
00075
00076
       mtk::Real aa = 0.0;
00077
        mtk::Real bb = 1.0;
00078
       mtk::Real cc = 0.0;
00079
        mtk::Real dd = 1.0;
08000
00081
        int nn = 5;
00082
00083
00084
        mtk::UniStgGrid2D gg(aa, bb, nn, cc, dd, mm);
00085
00086
       std::cout << gg << std::endl;
00087
00088
       mtk::Tools::EndTestNo(2);
00089 }
00090 int main () {
00091
00092
       std::cout << "Testing mtk::UniStgGrid2D class." << std::endl;</pre>
00093
00094
       Test1();
00095
        Test2();
00096 }
00097
00098 #else
00099 #include <iostream>
00100 using std::cout;
00101 using std::endl;
00102 int main () {
       cout << "This code HAS to be compiled with support for C++11." << endl;
0.0103
       cout << "Exiting..." << endl;</pre>
00104
```

00105 } 00106 #endif

# Index

$\sim$ DenseMatrix	mtk::Tools, 148
mtk::DenseMatrix, 65	BeginTestNo
$\sim$ Div1D	mtk::Tools, 146
mtk::Div1D, 78	BindScalarField
~Div2D	mtk::UniStgGrid1D, 153
mtk::Div2D, 89	mtk::UniStgGrid2D, 161
~Grad1D	BindVectorField
mtk::Grad1D, 97	mtk::UniStgGrid1D, 153
~Grad2D	BindVectorFieldPComponent
mtk::Grad2D, 107	mtk::UniStgGrid2D, 161
~Interp1D	BindVectorFieldQComponent
mtk::Interp1D, 110	mtk::UniStgGrid2D, 162
~Interp2D	mikomotgandzb, roz
•	COL MAJOR
mtk::Interp2D, 114	Enumerations., 34
~Lap1D	CRS
mtk::Lap1D, 116	Enumerations., 34
~Lap2D	coeffs_interior
mtk::Lap2D, 121	mtk::Div1D, 79
~Matrix	mtk::Grad1D, 97
mtk::Matrix, 132	mtk::Interp1D, 110
∼Quad1D	
mtk::Quad1D, 144	coeffs_interior_
$\sim$ UniStgGrid1D	mtk::Div1D, 85
mtk::UniStgGrid1D, 152	mtk::Grad1D, 104
$\sim$ UniStgGrid2D	mtk::Interp1D, 112
mtk::UniStgGrid2D, 161	ComputePreliminaryApproximations
	mtk::Div1D, 79
abs_density	mtk::Grad1D, 97
mtk::Matrix, 132	ComputeRationalBasisNullSpace
abs_density_	mtk::Div1D, 80
mtk::Matrix, 141	mtk::Grad1D, 98
abs_sparsity	ComputeStencilBoundaryGrid
mtk::Matrix, 132	mtk::Div1D, 81
abs_sparsity_	mtk::Grad1D, 99
mtk::Matrix, 141	ComputeStencilInteriorGrid
AssembleOperator	mtk::Div1D, 81
mtk::Div1D, 79	mtk::Grad1D, 99
mtk::Grad1D, 97	ComputeWeights
	mtk::Div1D, 82
BANDED	mtk::Grad1D, 100
Enumerations., 34	ConstructDiv1D
bandwidth	mtk::Div1D, 82
mtk::Matrix, 132	ConstructDiv2D
bandwidth_	mtk::Div2D, 89
mtk::Matrix, 141	ConstructGrad1D
begin_time_	mtk::Grad1D, 100

ConstructGrad2D	mtk::UniStgGrid1D, 154
mtk::Grad2D, 107	mtk::UniStgGrid2D, 162
ConstructInterp1D	discrete_field_u_
mtk::Interp1D, 110	mtk::UniStgGrid1D, 156
ConstructInterp2D	mtk::UniStgGrid2D, 166
mtk::Interp2D, 114	Div1D
ConstructLap1D	mtk::Div1D, 78
mtk::Lap1D, 116	Div2D
ConstructLap2D	mtk::Div2D, 89
mtk::Lap2D, 121	divergence_
	mtk::Div1D, 86
DENSE	mtk::Div2D, 90
Enumerations., 34	divergence_length_
Data	mtk::Div1D, 86
mtk::Lap1D, 117	
data	east_bndy_x
mtk::DenseMatrix, 65	mtk::UniStgGrid1D, 154
Data structures., 36	mtk::UniStgGrid2D, 162
data_	east_bndy_x_
mtk::DenseMatrix, 75	mtk::UniStgGrid1D, 156
degree_approximation	mtk::UniStgGrid2D, 166
mtk::Quad1D, 145	EndTestNo
degree_approximation_	mtk::Tools, 147
mtk::Quad1D, 145	Enumerations., 33
delta x	BANDED, 34
mtk::UniStgGrid1D, 154	COL_MAJOR, 34
mtk::UniStgGrid2D, 162	CRS, 34
delta_x_	DENSE, 34
mtk::UniStgGrid1D, 156	DirInterp, 33
mtk::UniStgGrid2D, 165	FieldNature, 33
delta_y	MatrixOrdering, 33
mtk::UniStgGrid2D, 162	MatrixStorage, 34
delta y	ROW_MAJOR, 34
mtk::UniStgGrid2D, 165	SCALAR, 33
DenseMatrix	SCALAR_TO_VECTOR, 33
mtk::DenseMatrix, 62–64	VECTOR, 33
	VECTOR_TO_SCALAR, 33
dim_null_ mtk::Div1D, 85	examples/minimalistic_poisson_1d/minimalistic_poisson-
mtk::Grad1D, 104	_1d.cc, 169, 170
	examples/poisson_1d/poisson_1d.cc, 172, 173
dir_interp_ mtk::Interp1D, 112	Execution tools., 35
•	
DirInterp	FieldNature
Enumerations., 33	Enumerations., 33
discrete_domain_x	0.044
mtk::UniStgGrid1D, 154	GetValue
mtk::UniStgGrid2D, 162	mtk::DenseMatrix, 66
discrete_domain_x_	Grad1D
mtk::UniStgGrid1D, 156	mtk::Grad1D, 96
mtk::UniStgGrid2D, 166	Grad2D
discrete_domain_y	mtk::Grad2D, 107
mtk::UniStgGrid2D, 162	gradient_
discrete_domain_y_	mtk::Grad1D, 104
mtk::UniStgGrid2D, 166	mtk::Grad2D, 108
discrete_field_u	gradient_length_

mtk::Grad1D, 104	kl
Grids., 38	mtk::Matrix, 133
	kl_
ImposeOnGrid	mtk::Matrix, 141
mtk::BCDesc1D, 51	Kron
ImposeOnOperator	mtk::DenseMatrix, 67
mtk::BCDesc1D, 52	ku
include/mtk.h, 176, 177	mtk::Matrix, 133
include/mtk_bc_desc_1d.h, 178, 179	ku_
include/mtk_blas_adapter.h, 180, 181	mtk::Matrix, 141
include/mtk_dense_matrix.h, 182, 184	
include/mtk_div_1d.h, 185, 187	Lap1D
include/mtk_div_2d.h, 188, 190	mtk::Lap1D, 116
include/mtk_enums.h, 191, 192	Lap2D
include/mtk_glpk_adapter.h, 193, 194	mtk::Lap2D, 121
include/mtk_grad_1d.h, 195, 196	laplacian_
include/mtk_grad_2d.h, 198, 199	mtk::Lap1D, 119
include/mtk_interp_1d.h, 200, 202	mtk::Lap2D, 121
include/mtk_interp_2d.h, 203, 205	laplacian_length_
include/mtk_lap_1d.h, 206, 207	mtk::Lap1D, 119
include/mtk_lap_2d.h, 208, 210	ld
include/mtk_lapack_adapter.h, 211, 212	mtk::Matrix, 133
include/mtk_matrix.h, 213, 214	ld_
include/mtk_quad_1d.h, 216, 218	mtk::Matrix, 141
include/mtk_roots.h, 219, 220	
include/mtk_tools.h, 221, 222	main
include/mtk_uni_stg_grid_1d.h, 223, 224	minimalistic_poisson_1d.cc, 170
include/mtk_uni_stg_grid_2d.h, 226, 227	mtk_blas_adapter_test.cc, 325
IncreaseNumNull	mtk_dense_matrix_test.cc, 327
mtk::Matrix, 132	mtk_div_1d_test.cc, 332
IncreaseNumZero	mtk_glpk_adapter_test.cc, 336
mtk::Matrix, 132	mtk_grad_1d_test.cc, 338
Integrate	mtk_interp_1d_test.cc, 341
mtk::Quad1D, 145	mtk_lap_1d_test.cc, 343
Interp1D	mtk_lapack_adapter_test.cc, 346
mtk::Interp1D, 110	mtk_uni_stg_grid_1d_test.cc, 348
Interp2D	mtk_uni_stg_grid_2d_test.cc, 351
mtk::Interp2D, 114	poisson_1d.cc, 173
interpolator_	Makefile.inc, 228
mtk::Interp2D, 114	Matrix
	mtk::Matrix, 130
kCriticalOrderAccuracyDiv	matrix_properties
Roots., 32	mtk::DenseMatrix, 68
kCriticalOrderAccuracyGrad	matrix_properties_
Roots., 32	mtk::DenseMatrix, 75
kDefaultMimeticThreshold	MatrixOrdering
Roots., 32	Enumerations., 33
kDefaultOrderAccuracy	MatrixStorage
Roots., 32	Enumerations., 34
kDefaultTolerance	mim_bndy
Roots., 32	mtk::Div1D, 83
kOne	mtk::Grad1D, 101
Roots., 32	mim_bndy_
kZero	mtk::Div1D, 86
Roots., 32	mtk::Grad1D, 104

Mimetic operators., 39	coeffs_interior, 79
mimetic_threshold_	coeffs_interior_, 85
mtk::Div1D, 86	ComputePreliminaryApproximations, 79
mtk::Div2D, 90	ComputeRationalBasisNullSpace, 80
mtk::Grad1D, 104	ComputeStencilBoundaryGrid, 81
mtk::Grad2D, 108	ComputeStencilInteriorGrid, 81
mtk::Interp2D, 114	ComputeWeights, 82
mtk::Lap1D, 119	ConstructDiv1D, 82
mtk::Lap2D, 121	dim_null_, 85
minimalistic_poisson_1d.cc	Div1D, 78
main, 170	divergence_, 86
minrow	divergence_length_, 86
mtk::Div1D, 86	mim_bndy, 83
mtk::Grad1D, 104	mim_bndy_, 86
	_ ·
mtk, 41	mimetic_threshold_, 86
operator<<, 43, 44	minrow_, 86
saxpy_, 44	num_bndy_coeffs, 84
sgels_, 45	num_bndy_coeffs_, 86
sgemm_, 46	operator<<, 85
sgemv_, 46	order_accuracy_, 86
sgeqrf_, 47	prem_apps_, <mark>86</mark>
sgesv_, 47	rat_basis_null_space_, 86
snrm2_, 47	ReturnAsDenseMatrix, 84
sormqr_, 48	row_, 86
mtk::BCDesc1D, 51	weights_cbs, 85
ImposeOnGrid, 51	weights_cbs_, 86
ImposeOnOperator, 52	weights_crs, 85
mtk::BLASAdapter, 53	weights_crs_, 87
RealAXPY, 54	mtk::Div2D, 87
RealDenseMM, 54	$\sim$ Div2D, 89
RealDenseMV, 56	ConstructDiv2D, 89
RealNRM2, 58	Div2D, 89
RelNorm2Error, 59	divergence , 90
mtk::DenseMatrix, 59	mimetic_threshold_, 90
$\sim$ DenseMatrix, 65	order_accuracy_, 90
data, 65	ReturnAsDenseMatrix, 90
data_, 75	mtk::GLPKAdapter, 91
DenseMatrix, 62–64	SolveSimplexAndCompare, 92
GetValue, 66	mtk::Grad1D, 93
Kron, 67	~Grad1D, 97
matrix_properties, 68	AssembleOperator, 97
matrix_properties_, 75	coeffs_interior, 97
num_cols, 69	coeffs_interior_, 104
num_rows, 69	Compute Preliminary Approximations, 97
operator 70	ComputeRationalBasisNullSpace, 98
operator=, 70	ComputeStencilBoundaryGrid, 99
OrderColMajor, 71	ComputeStencilInteriorGrid, 99
OrderRowMajor, 72	ComputeWeights, 100
SetOrdering, 72	ConstructGrad1D, 100
SetValue, 73	dim_null_, 104
Transpose, 74	Grad1D, 96
mtk::Div1D, 75	gradient_, 104
$\sim$ Div1D, 78	gradient_length_, 104
AssembleOperator, 79	mim_bndy, 101

mim_bndy_, 104	operator<<, 119
mimetic_threshold_, 104	order_accuracy_, 119
minrow_, 104	ReturnAsDenseMatrix, 118
num_bndy_approxs_, 105	mtk::Lap2D, 119
num_bndy_coeffs, 102	$\sim$ Lap2D, 121
num_bndy_coeffs_, 105	ConstructLap2D, 121
operator<<, 104	Lap2D, 121
order_accuracy_, 105	laplacian_, 121
prem_apps_, 105	mimetic_threshold_, 121
rat_basis_null_space_, 105	order_accuracy_, 121
ReturnAsDenseMatrix, 102, 103	ReturnAsDenseMatrix, 121
row_, 105	mtk::Matrix, 127
weights_cbs, 103	∼Matrix, 132
weights_cbs_, 105	abs_density, 132
weights_crs, 103	abs_density_, 141
weights_crs_, 105	abs_sparsity, 132
mtk::Grad2D, 105	abs_sparsity_, 141
$\sim$ Grad2D, 107	bandwidth, 132
ConstructGrad2D, 107	bandwidth_, 141
Grad2D, 107	IncreaseNumNull, 132
gradient_, 108	IncreaseNumZero, 132
mimetic_threshold_, 108	kl, 133
order_accuracy_, 108	kl_, 141
ReturnAsDenseMatrix, 108	ku, 133
mtk::Interp1D, 109	ku_, 141
~Interp1D, 110	ld, 133
coeffs_interior, 110	ld_, 141
coeffs_interior_, 112	Matrix, 130
ConstructInterp1D, 110	num_cols, 133
dir_interp_, 112	num_cols_, 141
Interp1D, 110	 num_non_null, 134
operator<<, 111	num_non_null_, 141
order_accuracy_, 112	num_non_zero, 134
ReturnAsDenseMatrix, 111	num_non_zero_, 142
mtk::Interp2D, 112	num_null, 1 <mark>34</mark>
∼Interp2D, 114	 numnull, 142
ConstructInterp2D, 114	num rows, 134
Interp2D, 114	num rows , 142
interpolator , 114	num values, 135
mimetic threshold , 114	num values , 142
order accuracy , 114	num zero, 135
ReturnAsDenseMatrix, 114	num zero , 142
mtk::LAPACKAdapter, 122	ordering, 135
QRFactorDenseMatrix, 123	ordering , 142
SolveDenseSystem, 124–126	rel density, 136
SolveRectangularDenseSystem, 126	rel density, 142
mtk::Lap1D, 115	rel sparsity, 136
~Lap1D, 116	rel_sparsity_, 142
ConstructLap1D, 116	set num cols, 136
Data, 117	set num null, 137
Lap1D, 116	set_num_rows, 138
laplacian , 119	set num zero, 138
laplacian length , 119	set ordering, 139
mimetic_threshold_, 119	set_storage, 140
	233.3.430, 1.10

storage, 140	nature_, 166
storage_, 142	north_bndy_y, 163
mtk::Quad1D, 143	north_bndy_y_, 166
$\sim$ Quad1D, 144	num_cells_x, 163
degree_approximation, 145	num_cells_x_, 166
degree_approximation_, 145	num_cells_y, 163
Integrate, 145	num_cells_y_, 166
operator<<, 145	operator<<, 165
Quad1D, 144	south_bndy_y, 164
weights, 145	south_bndy_y_, 166
weights_, 145	UniStgGrid2D, 160
mtk::Tools, 145	west_bndy_x, 164
begin_time_, 148	west_bndy_x_, 166
BeginTestNo, 146	WriteToFile, 165
EndTestNo, 147	mtk_blas_adapter_test.cc
Prevent, 147	main, 325
test_number_, 149	mtk_dense_matrix_test.cc
mtk::UniStgGrid1D, 149	main, 327
$\sim$ UniStgGrid1D, 152	mtk_div_1d_test.cc
BindScalarField, 153	main, 332
BindVectorField, 153	mtk_glpk_adapter_test.cc
delta_x, 154	main, 336
delta_x_, 156	mtk_grad_1d_test.cc
discrete_domain_x, 154	main, 338
discrete_domain_x_, 156	mtk_interp_1d_test.cc
discrete_field_u, 154	main, 341
discrete_field_u_, 156	mtk_lap_1d_test.cc
east_bndy_x, 154	main, 343
east_bndy_x_, 156	mtk_lapack_adapter_test.cc
nature_, 156	main, 346
num_cells_x, 155	mtk_uni_stg_grid_1d_test.cc
num_cells_x_, 156	main, 348
operator<<, 156	mtk_uni_stg_grid_2d_test.cc
UniStgGrid1D, 152	main, 351
west_bndy_x, 155	
west_bndy_x_, 156	nature_
WriteToFile, 155	mtk::UniStgGrid1D, 156
mtk::UniStgGrid2D, 157	mtk::UniStgGrid2D, 166
~UniStgGrid2D, 161	north_bndy_y
BindScalarField, 161	mtk::UniStgGrid2D, 163
BindVectorFieldPComponent, 161	north_bndy_y_
BindVectorFieldQComponent, 162	mtk::UniStgGrid2D, 166
delta_x, 162	num_bndy_approxs_
delta_x_, 165	mtk::Grad1D, 105
delta_y, 162 delta_y , 165	num_bndy_coeffs mtk::Div1D, 84
—	mtk::Grad1D, 102
discrete_domain_x, 162	
discrete_domain_x_, 166 discrete_domain_y, 162	num_bndy_coeffs_ mtk::Div1D, 86
discrete_domain_y, 162 discrete_domain_y_, 166	mtk::Grad1D, 105
discrete_domain_y_, 166 discrete_field_u, 162	num_cells_x
discrete_field_u_, 166	mtk::UniStgGrid1D, 155
east_bndy_x, 162	mtk::UniStgGrid2D, 163
east_bndy_x, 166	num_cells_x_
545 <u>1</u> 5114 <u>y_</u> ^_, 100	110111_00110_A_

mtk::UniStgGrid1D, 156	mtk::Grad2D, 108
mtk::UniStgGrid2D, 166	mtk::Interp1D, 112
num_cells_y	mtk::Interp2D, 114
mtk::UniStgGrid2D, 163	mtk::Lap1D, 119
num_cells_y_	mtk::Lap2D, 121
mtk::UniStgGrid2D, 166	OrderColMajor
num_cols	mtk::DenseMatrix, 71
mtk::DenseMatrix, 69	OrderRowMajor
mtk::Matrix, 133	mtk::DenseMatrix, 72
num_cols_	ordering
mtk::Matrix, 141	mtk::Matrix, 135
num_non_null	ordering_
mtk::Matrix, 134	mtk::Matrix, 142
num_non_null_	
mtk::Matrix, 141	poisson_1d.cc
num_non_zero	main, 173
mtk::Matrix, 134	prem_apps_
num non zero	mtk::Div1D, 86
mtk::Matrix, 142	mtk::Grad1D, 105
num null	Prevent
mtk::Matrix, 134	mtk::Tools, 147
num_null_	
mtk::Matrix, 142	QRFactorDenseMatrix
num_rows	mtk::LAPACKAdapter, 123
mtk::DenseMatrix, 69	Quad1D
mtk::Matrix, 134	mtk::Quad1D, 144
num rows	DOW MA IOD
mtk::Matrix, 142	ROW_MAJOR
num_values	Enumerations., 34
mtk::Matrix, 135	README.md, 231
num_values_	rat_basis_null_space_
mtk::Matrix, 142	mtk::Div1D, 86
num zero	mtk::Grad1D, 105
mtk::Matrix, 135	Real
	Roots., 32
num_zero_ mtk::Matrix, 142	RealAXPY
	mtk::BLASAdapter, 54
Numerical methods., 37	RealDenseMM
operator<<	mtk::BLASAdapter, 54
·	RealDenseMV
mtk, 43, 44	mtk::BLASAdapter, 56
mtk::DenseMatrix, 74	RealNRM2
mtk::Div1D, 85	mtk::BLASAdapter, 58
mtk::Grad1D, 104	rel_density
mtk::Interp1D, 111	mtk::Matrix, 136
mtk::Lap1D, 119	rel_density_
mtk::Quad1D, 145	mtk::Matrix, 142
mtk::UniStgGrid1D, 156	rel_sparsity
mtk::UniStgGrid2D, 165	mtk::Matrix, 136
operator=	rel_sparsity_
mtk::DenseMatrix, 70	mtk::Matrix, 142
order_accuracy_	RelNorm2Error
mtk::Div1D, 86	mtk::BLASAdapter, 59
mtk::Div2D, 90	ReturnAsDenseMatrix
mtk::Grad1D, 105	mtk::Div1D, 84

mtk::Div2D, 90	SolveDenseSystem
mtk::Grad1D, 102, 103	mtk::LAPACKAdapter, 124-126
mtk::Grad2D, 108	SolveRectangularDenseSystem
mtk::Interp1D, 111	mtk::LAPACKAdapter, 126
mtk::Interp2D, 114	SolveSimplexAndCompare
mtk::Lap1D, 118	mtk::GLPKAdapter, 92
mtk::Lap2D, 121	sormqr_
Roots., 31	mtk, 48
kCriticalOrderAccuracyDiv, 32	south_bndy_y
kCriticalOrderAccuracyGrad, 32	mtk::UniStgGrid2D, 164
kDefaultMimeticThreshold, 32	south_bndy_y_
kDefaultOrderAccuracy, 32	mtk::UniStgGrid2D, 166
kDefaultTolerance, 32	src/mtk_bc_desc_1d.cc, 233
	src/mtk_blas_adapter.cc, 234, 235
kOne, 32	src/mtk_dense_matrix.cc, 238, 239
kZero, 32	src/mtk_div_1d.cc, 246, 247
Real, 32	src/mtk_div_2d.cc, 263, 264
row_	src/mtk_div_zd.cc, 265, 264 src/mtk_glpk_adapter.cc, 266, 267
mtk::Div1D, 86	
mtk::Grad1D, 105	src/mtk_grad_1d.cc, 271, 272
	src/mtk_grad_2d.cc, 290, 291
SCALAR	src/mtk_interp_1d.cc, 292, 293
Enumerations., 33	src/mtk_lap_1d.cc, 295, 296
SCALAR_TO_VECTOR	src/mtk_lap_2d.cc, 300, 301
Enumerations., 33	src/mtk_lapack_adapter.cc, 302, 303
saxpy_	src/mtk_matrix.cc, 311
mtk, 44	src/mtk_tools.cc, 315
set_num_cols	src/mtk_uni_stg_grid_1d.cc, 317, 318
mtk::Matrix, 136	src/mtk_uni_stg_grid_2d.cc, 321, 322
set_num_null	storage
mtk::Matrix, 137	mtk::Matrix, 140
set num rows	storage_
mtk::Matrix, 138	mtk::Matrix, 142
set num zero	
mtk::Matrix, 138	test_number_
set_ordering	mtk::Tools, 149
mtk::Matrix, 139	tests/mtk_blas_adapter_test.cc, 324, 325
	tests/mtk_dense_matrix_test.cc, 327
set_storage	tests/mtk_div_1d_test.cc, 331, 332
mtk::Matrix, 140	tests/mtk_glpk_adapter_test.cc, 335, 336
SetOrdering	tests/mtk_grad_1d_test.cc, 337, 338
mtk::DenseMatrix, 72	tests/mtk_interp_1d_test.cc, 340, 341
SetValue	tests/mtk_lap_1d_test.cc, 343
mtk::DenseMatrix, 73	tests/mtk_lapack_adapter_test.cc, 345, 346
sgels_	tests/mtk_uni_stg_grid_1d_test.cc, 347, 348
mtk, 45	tests/mtk_uni_stg_grid_2d_test.cc, 350, 351
sgemm_	Transpose
mtk, 46	mtk::DenseMatrix, 74
sgemv_	,
mtk, 46	UniStgGrid1D
sgeqrf_	mtk::UniStgGrid1D, 152
mtk, 47	UniStgGrid2D
sgesv_	mtk::UniStgGrid2D, 160
mtk, 47	<del> </del>
snrm2	VECTOR
mtk, 47	Enumerations., 33
· · · · · · · · · · · · · · · · · · ·	,

VECTOR_TO_SCALAR
Enumerations., 33
weights
mtk::Quad1D, 145
weights_
mtk::Quad1D, 145
weights_cbs
mtk::Div1D, 85
mtk::Grad1D, 103
weights_cbs_
mtk::Div1D, 86
mtk::Grad1D, 105
weights crs
mtk::Div1D, 85
mtk::Grad1D, 103
weights_crs_
mtk::Div1D, 87
mtk::Grad1D, 105
west bndy x
mtk::UniStgGrid1D, 155
mtk::UniStgGrid2D, 164
west_bndy_x_
mtk::UniStgGrid1D, 156
mtk::UniStgGrid2D, 166
WriteToFile
mtk::UniStgGrid1D, 155
mtk::UniStgGrid2D, 165