# Signal and System

Assignment

Group Members: Enrollment Number:

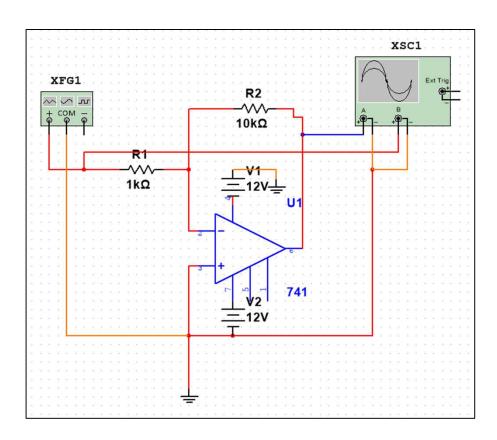
1.Sayak Rana. 510519108

2.Abhiroop Mukherjee. 510519109

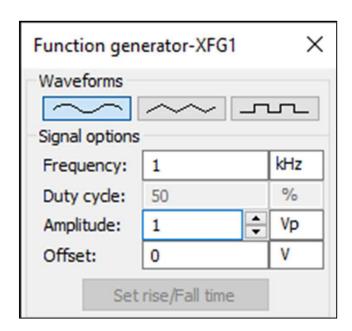
3. Hritick Sharma. 510519114

1) First of all, implement a simple inverting amplifier. Check whether the gain (V\_out/V\_in) remains linear over a range of input voltage. Try to plot the gain against a swing of input voltage for this.

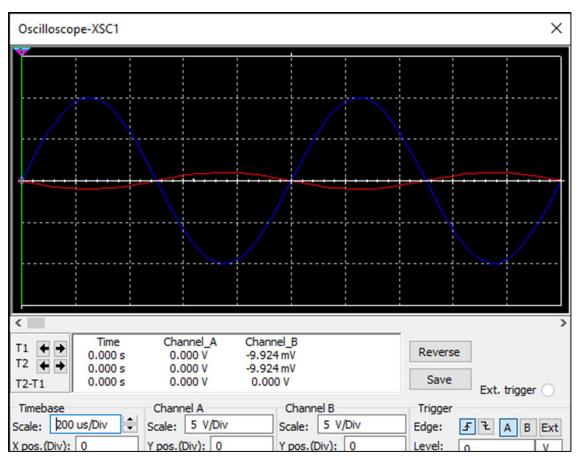
#### • Circuit:



#### • Input:1



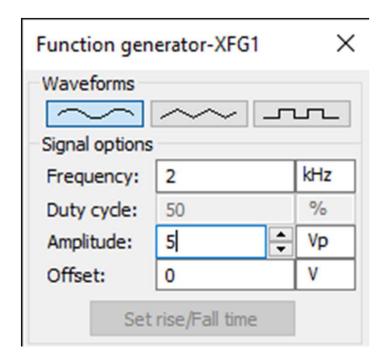
#### • Output:1



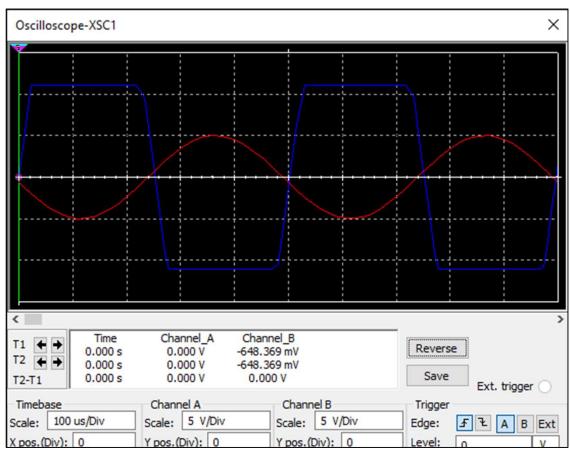
### **Explanation to Output**

- As R1 = 1kOhm and R2 = 10kOhm
- Proportionality Factor = -10/1 = -10
- Hence the output will be inverted and scaled 10 time

#### • Input :2



#### • Output:2

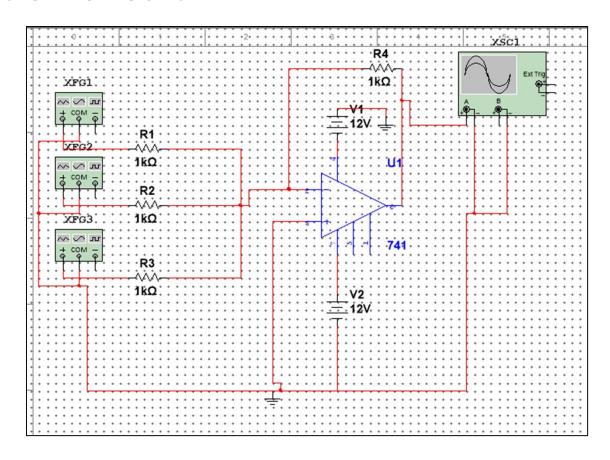


### **Explanation to Output**

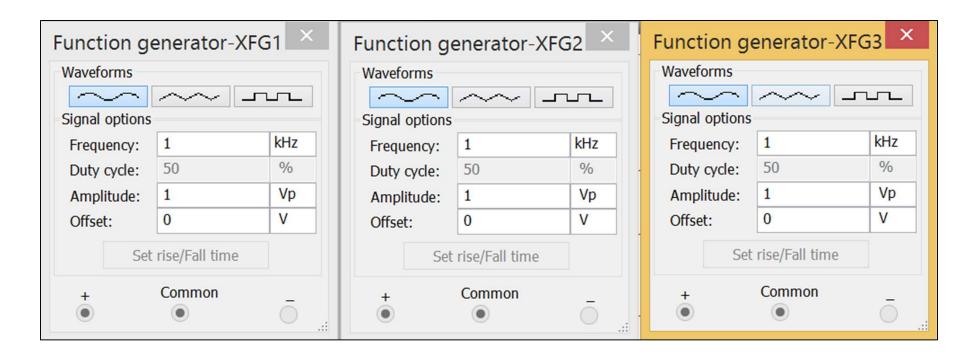
- Proportionality Factor = -10
- But as V\_in has Amplitude 5, V\_out will have Amplitude 50
- But the opamp cant amplify past 12V
- So any value above 12V will be displayed as 12V only

2) Then implement few designer opamps that produce a linear combination of two input voltages at the output. Check different alternatives like sum and differences.

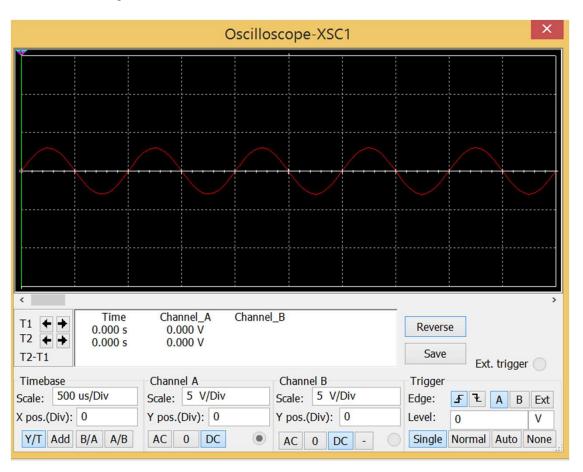
#### Addition circuit:



#### Addition input:



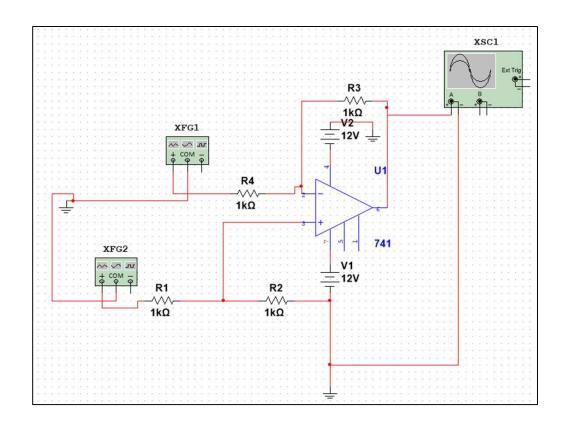
#### • Addition output:



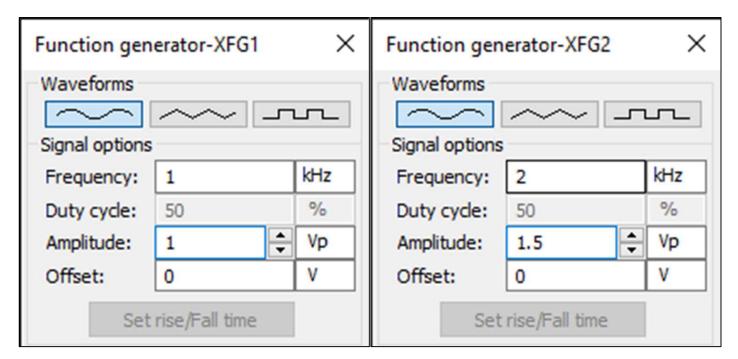
### **Explanation to Output**

 As all of the three inputs have amplitude 1 and frequent 1kHz, The Output will have Amplitude 3 and same frequency

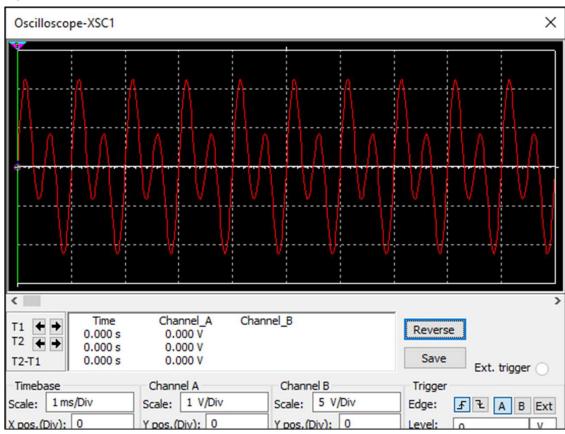
#### • Subtraction circuit:



#### • Subtractor input:



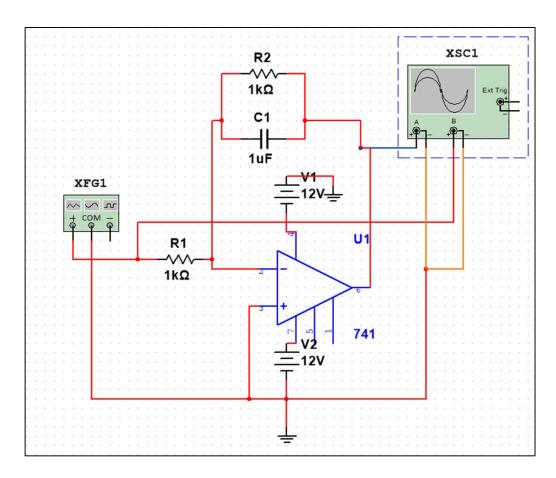
#### • Output:



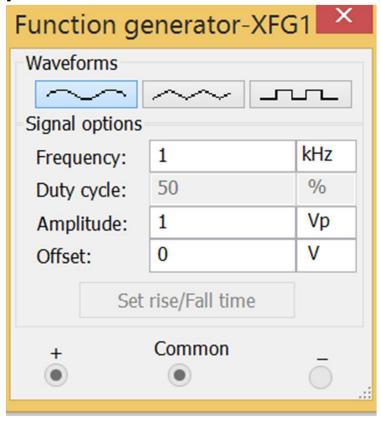
### **Explanation to Output**

 As both of the input has different frequency and Amplitude, The output will be superposition of their graphs 3) Now implement the integrator circuit and also the PI circuit. Check the output for different input voltage profiles.

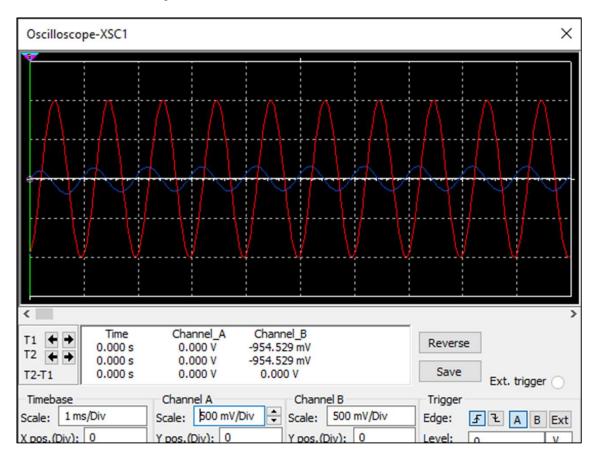
#### • Integrator circuit:



Integrator Input:



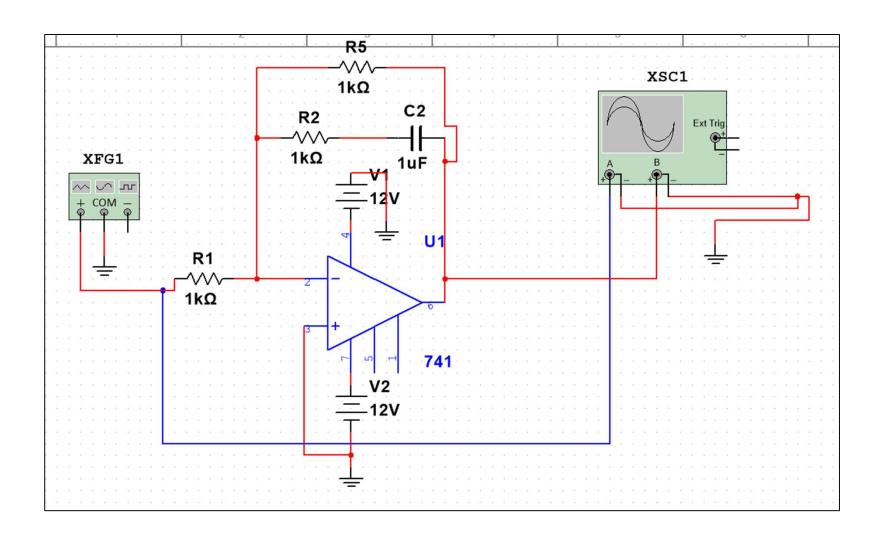
#### • Integrator Output:



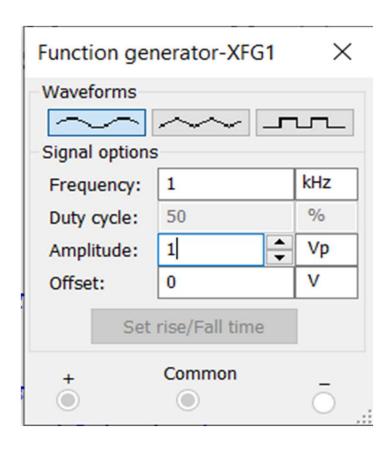
### **Explanation of Output**

- As  $\int \sin(2\pi f t) = \cos(2\pi f t) / 2\pi f$
- The output graph will be a cos function, but scaled down by a factor of  $2\pi f$
- It means when input is in its peak / valley, the output will be zero

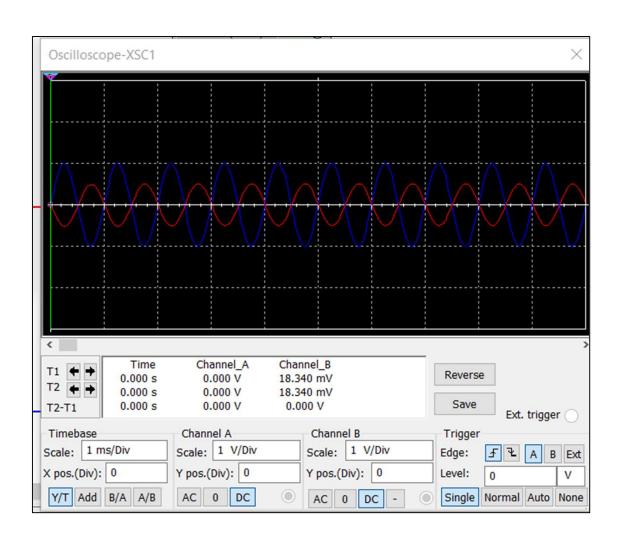
### • PI Circuit:



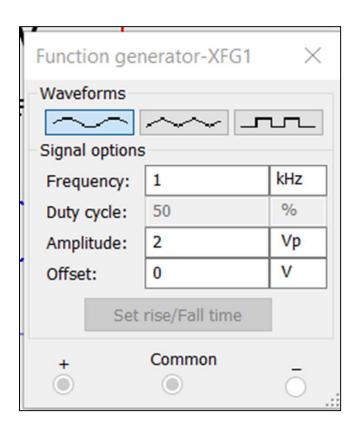
### • Pl Input 1:



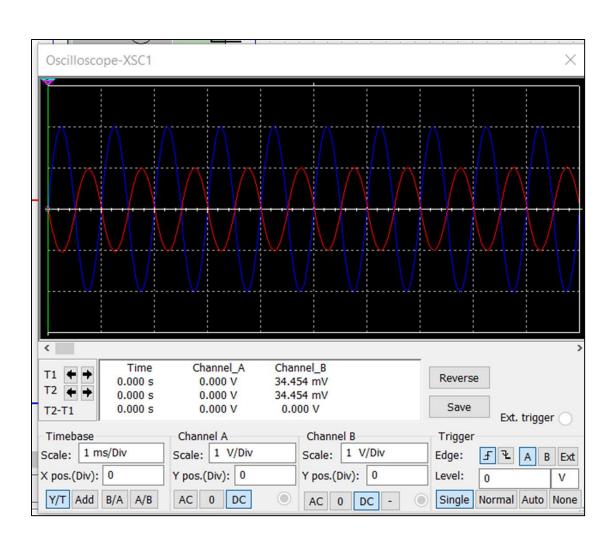
# • PI Output 1:



## • PI Input 2:

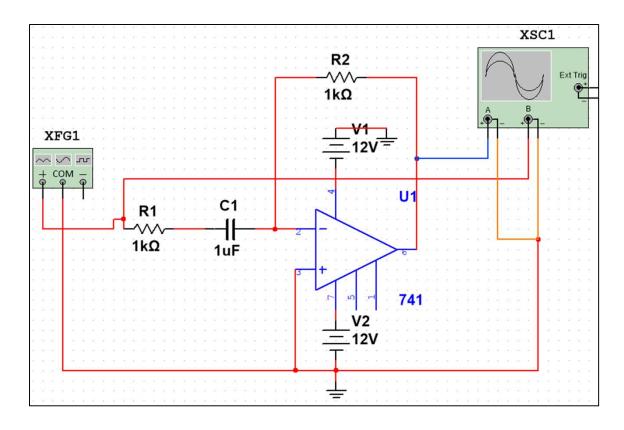


### • PI Output 2:

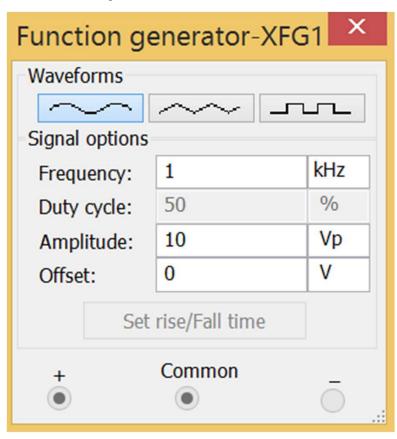


4) Now implement the differentiator circuit and the PD circuit. Check the output for different input voltage profiles.

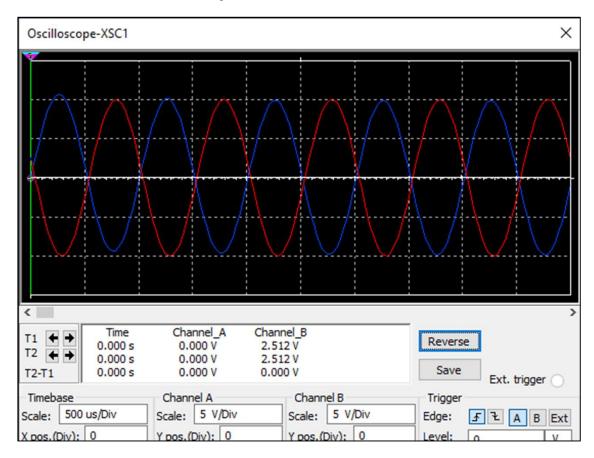
#### • Differentiator circuit:



• Differentiator input:



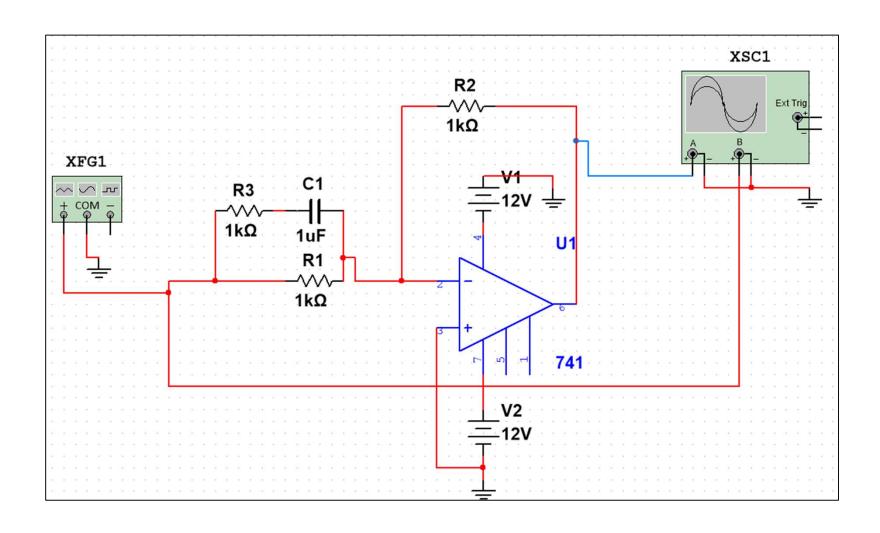
#### • Differentiator output:



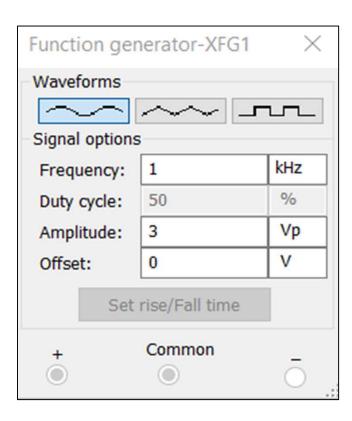
### **Explanation of Output**

- As  $\frac{d}{dt}\sin(2\pi ft) = 2\pi f\cos(2\pi ft)$
- The output will be a cos function, scaled up by the value  $2\pi f$
- But due to the values of Resistance and Capacitance of the circuit, the factor cancels, giving exact same amplitude as Input

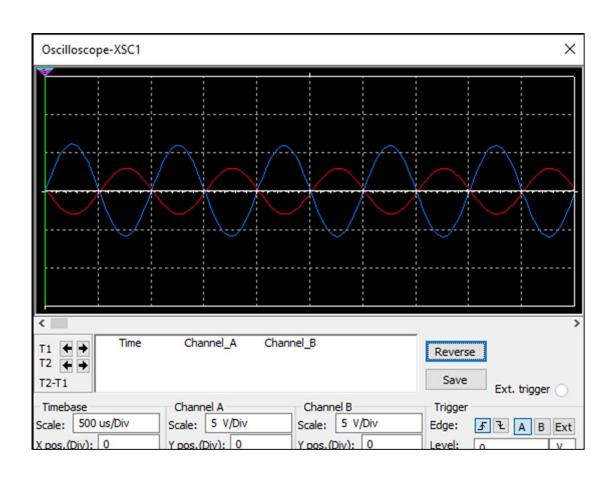
### • PD Circuit:



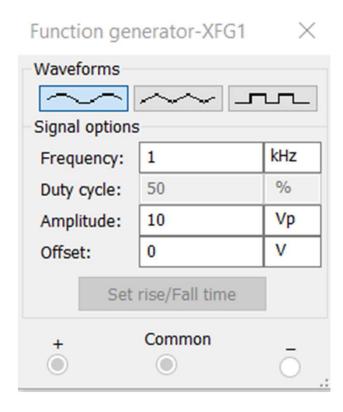
## • PD Input 1:



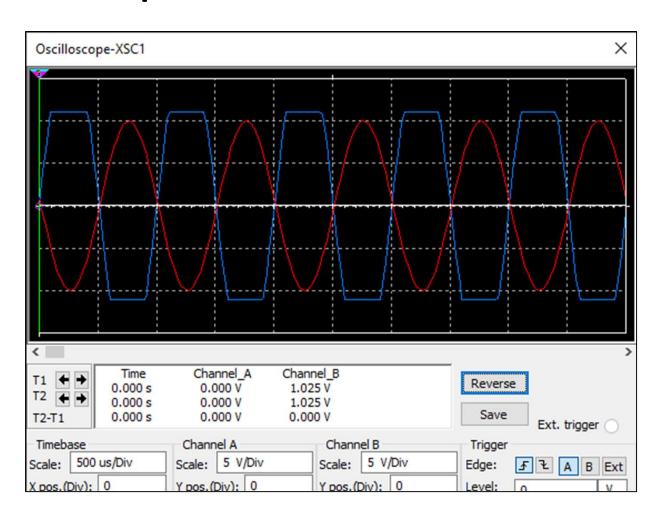
## • PD Output 1:



### • PD Input 2:

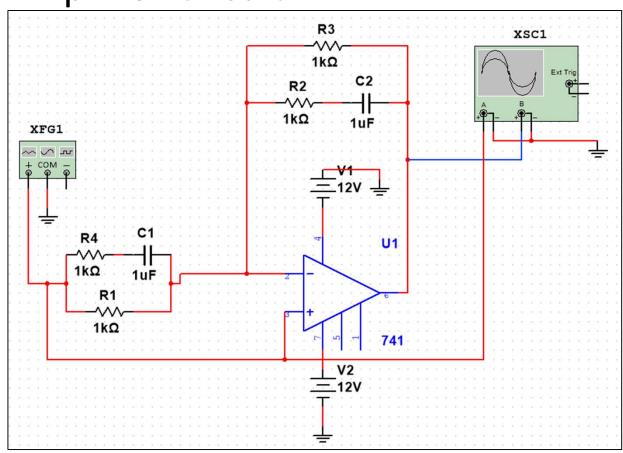


### • PD Output 2:

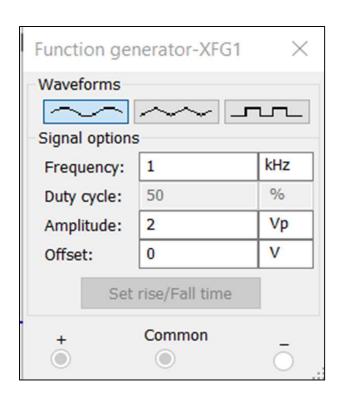


5) Finally implement the PID amplifier and show its performance in time domain for various input signal profiles.

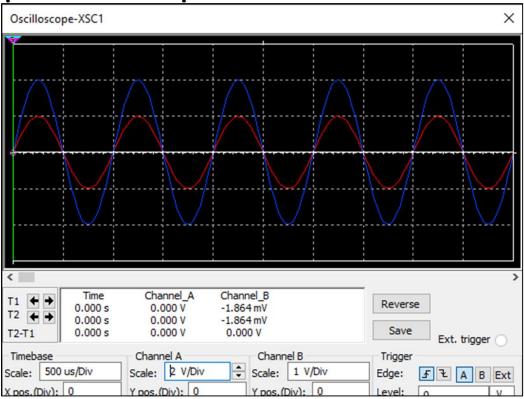
#### • PID Amplifier Circuit:



#### • PID Amplifier Input 1:



PID Amplifier Output 1:

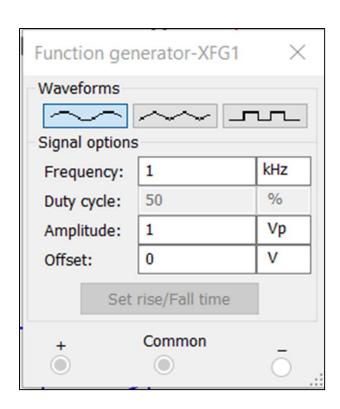


Here Scales of the two plots have been changed as they are equal

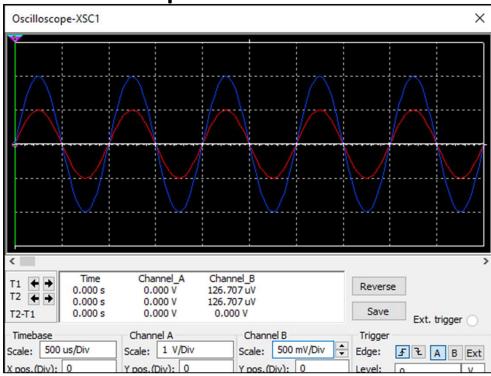
### **Explanation of Output**

- Proportionality of sine function is sine
- Integral of sine function is –cosine
- Differentiation of sine function is cosine
- Hence when P, I, D of this input will be added, only sine will remain, giving the exact same output as the input

#### • PID Amplifier Input 2:



PID Amplifier Output 2:



Here Scales of the two plots have been changed as they are equal

# Thank You