## decture: Eigenvalues and Eigenvectors

### 1. Introduction:

To explain eigenvalues, we first explain eigen vectors. det, A be a square matrix. Almost all the vectors change direction when they are multiplied by A.

Certain exceptional vectors & wie in the same direction as Ax. Those special type of vectors are called eigen vectors.

Multiply an eigenvector by A, and the rector Ax is a number & times the original x.

The Basic basic equation Ax=1x. The number 1 cs an eigenvalue of A.

The eigen value & tells whether the special vector x is streched or shrunk or reversed or left unchanged - when it is multiplied by A. we may find 1=2 or 1 or () The eigenvalue & could be zero! Then Ax = 0x means the eigen rector 2 es in the nullspace.

## 2. Definition:

det A be a square matrix. A number it is called an eigenvalue of A if there exists a non-zero rector & such that Ax = 1x.

In the above definition, the vector & is called eigen rector associated to the eigen value s.

#### Remarks:

- (1) \$\frac{1}{2} \times \pm 2 \times 2 is crucial, since \(\mu = 2\) always satisfy equation ().
- If x is an eigenvectors for A, then so is ex for (2) any constant c.
- (3) Geometrically, in 3D, eigen vectors of A are those whose whose directions are unchanged under linear transformation A.

3. Characteristic Equation:

We observe from equation (1), that  $\lambda$  is an eigen value iff  $(A-\lambda I) = 0$  has a nontrivial solution. By the inverse matrix theorem,  $\det(A-\lambda I) = 0$ .

If  $A = (aij)_{n \times n}$  then,  $det (A - \lambda I) = 0$  gives

 $|A-\lambda I| = \begin{vmatrix} a_{11}-\lambda & a_{12} & a_{1n} \\ a_{21} & a_{22}-\lambda & a_{2n} \end{vmatrix} = 0$ 

This is called the characteristic equation of A. On expanding the determinant, the characteristic equation takes the form -

 $(-)^n \lambda^n + K_1 \lambda^{n-1} + K_2 \lambda^{n-2} + \dots + K_n = 0$ , where each  $K_i$  (i=1,2,...,n) are expressible interms of  $A_i$ .

The roots of this equation is called the eigenvalues or characteristic roots of the matrix A.

For each eigenvalue  $\lambda$ , we need to find a basis for the eigenspace i.e, Null  $(A-\lambda I)$  for finding eigen vectors. ie, we have to solve:  $(A-\lambda I) x = 0$ , for fixed  $\lambda$ .

# Summary: To solve eigen value problem for an nxn matrix

- 1. compute the determinant of A-AI, which is a polynomial of degree n.
- 2. Find the roots of this polynomial.
- 3. For each eigen value  $\lambda$ , solve  $(A-\lambda I) \chi = Q$  to find an eigen vector  $\chi$ .

Find the eigen values and eigen vectors of the matrix A = [3 1 4]

Solution: The characteristic equation is

$$|A-\lambda I| = 0$$
 $|3-\lambda I| = 0$ 
 $|0 2-\lambda 6| = 0$ 
 $|0 5-\lambda| = 0$ 

Thus the eigen values of A are 2,3,5.

If x = [x, y, z] be the eigen vector corresponds to the eigenvalued then we have

alue 
$$\lambda$$
 then we have
$$\begin{bmatrix}
A - \lambda I \end{bmatrix} \dot{\chi} = \begin{bmatrix} 3 - \lambda & 1 & 4 \\
0 & 2 - \lambda & 6 \\
0 & 0 & 5 - \lambda
\end{bmatrix}
\begin{bmatrix}
\chi \\
\chi \\
Z
\end{bmatrix} = 0 = \begin{bmatrix} 0 \\
0 \\
0 \end{bmatrix}$$

Putting, 1=2, we have 1+1+42=0 and, 67=0 and 32=0

Hence, the eigenvectors corresponding the eigen value  $\lambda = 2$ , We have K, (1,-1,0).

Pulling 1=3, we have 1+4=0,-1+6==0 and 2==0. is, 4=0, 7=0.

$$\frac{\chi}{1} = \frac{y}{0} = \frac{z}{0} = 162 \text{ (Say)}$$

Hence, the eigen rectors corresponding to the eigen value

Similarly, the eigen rectors corresponding to 1=5 are K3 (3,2,1).

4. Cayley-Hamilton theorem and its applications:

Ne now introduce a very important theorem in matrix theory; i.e., Cayley-Hamilton theorem.

Statement: Every square matrix satisfies its own Characteristic equation.

If Anxn be a square matrix, then its characteristic equation is det (A-) In) = 0. Let us denote det (A-) In) as b(A). Then according to Cayley-Hamilton theorem b(A)=0.

Applications:

verify Cayley-Hamilton theorem for  $A = \begin{bmatrix} 1 & 1 \end{bmatrix}$ . Find  $A^{\dagger}$ . Example 2

Solution:

We know that 
$$det(A-\lambda I)=0$$

$$\left|\begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right|=0$$

$$\left|\begin{bmatrix} 1-\lambda & 4 \\ 2 & 3-\lambda \end{bmatrix}\right|=0$$

$$\Rightarrow \lambda^2 - 4\lambda - 5 = 0$$

The characteristic equation is  $\lambda^2 - 4\lambda - 5 = 0$ NOW,  $A^2 = \begin{bmatrix} 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 4 \end{bmatrix} = \begin{bmatrix} 9 & 16 \end{bmatrix}$ 

NOW, 
$$A^2 = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 9 & 16 \\ 8 & 17 \end{bmatrix}$$

$$A^{2}-4A-5I = \begin{bmatrix} 9 & 11 \\ 8 & 17 \end{bmatrix} - 4 \begin{bmatrix} 1 & 24 \\ 2 & 3 \end{bmatrix} - 5 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$$

p (A) = 0 and cayley. Hamiton theorem is verified. Hence

NOW we have

Multiplying both side by A

$$\Rightarrow A^{-1} = \frac{1}{5} (A - 4I)$$

$$= \frac{1}{5} \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix} - 4 \begin{bmatrix} 0 & 0 \end{bmatrix}$$

$$= \frac{1}{5} \begin{bmatrix} -3 & 4 \\ 2 & -1 \end{bmatrix}$$

Without calculating we can find inverse of A Note Using Cayley-Hamilton theorem.

Example 2:

ample 2:  

$$det$$
,  $A = \begin{bmatrix} 3 - 1 \\ 2 - 1 \end{bmatrix}$ . Find  $A^6$ .

p(x) = characteristic polynomial of A Solutim:

$$= \det (A - \lambda I)$$

$$= \lambda^2 - 2\lambda - 1 \quad \text{(check!)}$$

By Cayley-Hamilton theorem, P(A) = 0 ig A2-2A-I=0

$$A^2 = 2A + I$$
  
 $A^3 = 2A^2 + A = 2(2A + I) + A = 5A + 2I$ 

$$A^3 = 2A^2 + A = 2$$
  
 $A^4 = 5A^2 + 2A = 5(2A + I) + 2A = 12A + 5I$ 

$$A^{9} = 5A + 2H$$

$$A^{5} = 12A^{2} + 5A = 12(2A+1) + 5A = 29A + 12I$$

$$A^6 = 29A^2 + 12A = 29(2A+I) + 12A = 70A + 29I$$

= 70 [3 -1] +29 [10] Note: The Cayley-Hamilton theorem is useful for calculating An for any square matrix.

5. Properties of Eigen values Theorem 1: Any square matrix A and its transpose AT have the same eigen values. Proofor we have, (A-AI) = AT-AIT = AT-AI  $|(A-\lambda I)^T| = |A^T-\lambda I|$ > |A-AI| = |AT-AI| [ .: |BT|= |B] ie, i is am eigen value of A iff it is an eigen value of AT. · | A-XI | = 0 iff | AT-XI | = 0 . Theorem 2: The eigen values of a triangular o matrix are just the diagonal elements of the manix. Proof: det A = [an an an be a triangular matrix o o -- ann of order n. Then, |A-AI| = (a11-1) (a22-1) -- (ann-1) Roots of |A-AI|=0 are an, azz,.., ann Hence the eigen values of A are the diagonal elements of A, ie, Corollary: The eigen values of a diagonal matrix are just the diagonal elements. Theorem 3: The eigen values of an idempotent matrix are either zero or one. Proof or det A be an idempotent matrix so that A=A. If I be an eigen value of A, then there exists a non-zero vector X such that AX = XX. - A(AX) = A(XX) ie,  $A^2X = \lambda(AX) = \lambda(XX) = \lambda^2X$ ie, AX = 12X in XX=XX り(入一人) X=0 X +0 > \lambda - \lambda^2 = 0 > \lambda (\lambda - 1) = 0 > \lambda = 0 or 1. Hence the result

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Theorem 4: The sum of the eigen values of a matrix is the sum of the elements of the principal diagonal. Proof: consider the square matrix A = Tan anz ans [a31 a32 a33] So that |A-AI| = |an-1 a12 a13 a21 a22-1 a23 a31 a32 a33-x = - 13 + 12 (an+ a22 + a33) - 2 (----) + ----If  $\lambda_1, \lambda_2, \lambda_3$  are eigen values of A, then  $|A-\lambda I| = (-1)^3 (\lambda - \lambda_1) (\lambda - \lambda_2) (\lambda - \lambda_3)$  $= -\lambda^3 + \lambda^2 (\lambda_1 + \lambda_2 + \lambda_3) - \lambda (\lambda_1 \lambda_2 + \lambda_2 \lambda_3 + \lambda_3 \lambda_1) + \lambda_1 \lambda_2 \lambda_3$ Equating (i) & (ii) we get 11+12+13= a11+a22+a33. Hence the result. This property is proved for a matrix of order 3, but method will be capable of easy extension to matrices of any order The product of the eigen values of a matrix is equal to Theorem 5% its determinant Proof on butting 1=0 in (ii) we get the desired result. If I is an eigen value of a matrix A, is then 1/2 is Theorem 6: the eigenvalue of A-1. Proof or If X be the eigenvector corresponding to A, premultiplying both side by AT  $A^{+}(AX) = A^{-}(XX) \Rightarrow (A^{+}A) \times = \lambda (A^{+}X)$ 

RAShis proves that 1/2 is an eigen value of AT. Theorem 78 If it is an eigen value of a matrix A an orthogonal matrix. A, then Yx is an eigen value of A. Proof : We know that if I is an eigen value of a matrix A then 1/2 is an eigen value of A-1 (5h. 16). Since A is an orthogonal matrix, AT is same as its transpesse AT. But A and AT has same set of eigenvalues. · /x is also an eigen value of A. Theorem 8: If  $\lambda_1, \lambda_2, ..., \lambda_n$  are the eigen values of a matrix A, then Am has the eigen values  $\lambda_1^m, \lambda_2^m, ..., \lambda_n^m$ . (m being possitive integer). Proof: « det Ai be the eigenvalue and Xi be the corresponding eigen vector of A (i=1,2,...,n). Then, Axi=\iXi  $A^2Xi = \lambda i(AiXi) = \lambda i(\lambda iXi) = \lambda i Xi$ Similarly, A3xi = \lambdai^2 (Axi) = \lambdai (\lambdai Xi) = \lambdai \lambdai \times i Proceeding similarly we get,

Am Xi = Ai Xi

which tells us him is an eigen value of Am and Xi is the eigenvector corresponding to si.

If is an eigen value of a non-singular matrix, show that IAI/x is an eigen value of adjA.

> we know that, if it is an eigen value of the matrix A, is an eigen value of A-1. Then I an eigen rector X1 such that,

$$\overrightarrow{A}X_1 = \frac{1}{\lambda}X_1$$
 $\Rightarrow \underbrace{AdjA}_{AAl} = \underbrace{X_1}_{AAl} = \underbrace{AAl}_{AAl} = \underbrace{AAl}_{AAl}$ 
 $\Rightarrow \underbrace{AdjA}_{AAl} = \underbrace{AAl}_{AAl} = \underbrace{A$ 

This implies IAI is an eigenvalue of adj A.

Example 50

Find eigen values of adj'A and of AZZA+I, Where  $A = \begin{bmatrix} 2 & 3 & 4 \end{bmatrix}$ .

Loo 0 3.

First we find the eigenvalues of A.

$$|A-\lambda I| = 0 \text{ gives } |2-\lambda 3 4| = 0$$

$$|A-\lambda I| = 0 \text{ gives } |2-\lambda 3 4| = 0$$

$$|A-\lambda I| = 0 \text{ gives } |3-\lambda| = 0$$

$$|A-\lambda I| = 0 \text{ gives } |3-\lambda| = 0$$

det A = product of eigen values = 2.4.3 = 24

: Eigen values of adj A are 24, 24, 24 is, 12,6,8.

If is an eigen value of A, 12-21+1 is eigen value of A-2A+I.

Eigen values of A2-2A+I are 22-2.2+1, 42-2.4+1, 32-2.3+1 1,9,4.

Find all of the eigenvalues and eigenvectors of A= [5 12 -6]

Compute the characteristic polynomial -(1-2)2(1+1). -(1-2)2(1+1)=0 gires 1=2,2,-1

### Definition

If A is a matrix with characteristic equation p(N=0, the multiplicity of a root & of is called the algebric multiplicity of the eigen value & Here in the above example,  $\chi=2$  has algebric multiplicity 2, while 1=-1 has algebric multiplicity 1.

The eigenvalue  $\lambda = 2$  gives us two linearly independent eigen rectors (-4,1,0) and (2,0,1) and  $\lambda = -1$ , we obtain the single eigen rector (-1, 1, 1)

The number of linearly independent eigenvectors Definition corresponding to a single eigenvalue is its geometric multiplicity

In the above example,  $\lambda=2$  has geometric multiplicity 2, while  $\lambda=-1$  has geometric multiplicity 1.

#### Theorem:

The geometric multiplicity of an eigenvalue is less than or equal to its algebric muliplicity

A square matrix A is said to be diagonalizable iff there exists a diagonal matrix D such that A is A=PTDP for some non singular matrix P. similar to D. is,

If a square matrix of order n has n linearly independent eigen such that PIAP is a vectors, then a matrix. I this result will be proved for a square matrix of order 3 but method will be capable of easy extension to matrices of any order Proof: Let A be a square matrix of order 3. Let 11, 12, 13 be its eigen values and  $X_1 = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ ,  $X_2 = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ ,  $X_3 = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ Denoting the square matrix [X1 X L X3] = [X1 XL X2] by P, we have AP = A[X1 X2 X3] = [AX1 AX2 AX3] [X14 X2X1] \[ [X14 X2 X3] \] LX3 X3' X3" [0 & X3 0 : PTAP = D, D is diagonal matrix and this proves the theorem.

Similarly,