Balancing Search Trees

• Balancing Binary Search Trees

- Operations for Rebalancing
- Tree Rotation
- Insertion at Root
- Tree Partitioning
- Periodic Rebalancing
- Randomised BST Insertion
- An Application of BSTs: Sets

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https://www.cse.unsw.edu.au/~cs2521/20T2/lecs/trees2/slides.html

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Balancing Binary Search Trees

Observation: order of insertion into a tree affects its height

- worst case: keys inserted in ascending/descending order
 - (effectively have a linked list, so search cost is O(n))
- best case (for at-leaf insertion): keys inserted in preorder
 - (tree height \Rightarrow search cost is $O(\log n)$; tree is balanced)
- average case: keys inserted in random order
 (tree height ⇒ search cost is O(log n); but cost ≥ best case)

Goal: build binary search trees which have

minimum height ⇒ minimum worst case search cost

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... Balancing Binary Search Trees

Perfectly-balanced tree with N nodes has

- ▼ nodes, abs(#nodes(LeftSubtree) #nodes(RightSubtree))
 < 2
- height of $log_2N \Rightarrow$ worst case search O(log N)

Three strategies to improving worst case search in BSTs:

- randomise reduce chance of worst-case scenario occuring
- amortise do more work at insertion to make search faster
- optimise implement all operations with performance bounds

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To assist with rebalancing, we consider new operations:

Left rotation



 move right child to root; rearrange links to retain order

Right rotation



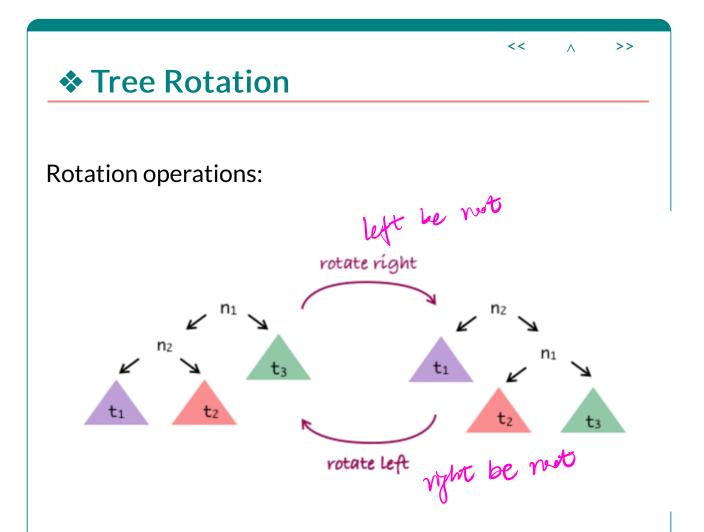
Insertion at root

each new item is added as the new root node

Partition &

rearrange tree around specified node (push it to root)

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Note: tree is ordered, $t_1 < n_2 < t_2 < n_1 < t_3$

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Method for rotating tree T right:

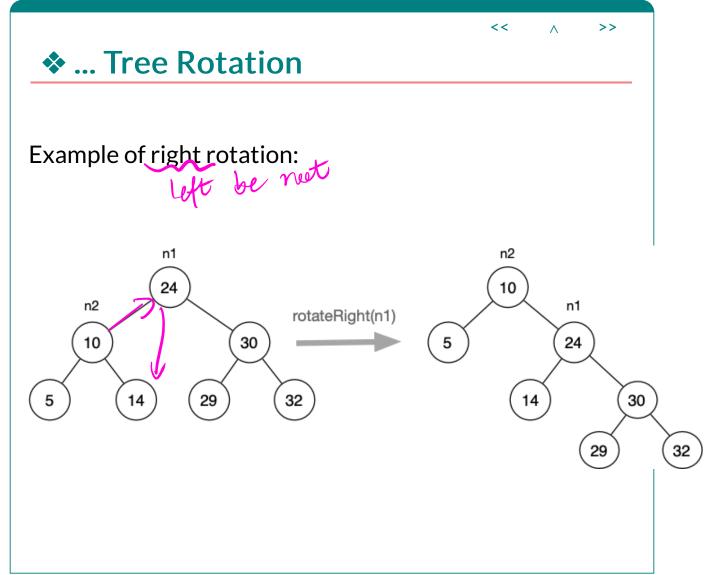
- n₁ is current root; n₂ is root of n₁'s left subtree
- n₁ gets new left subtree, which is n₂'s right subtree
- n₁ becomes root of n₂'s new right subtree
- n₂ becomes new root
- n₂'s left subtree is unchanged

Left rotation: swap left/right in the above.

Rotation requires simple, localised pointer rearrangemennts

Cost of tree rotation: O(1)

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Algorithm for right rotation:

```
rotateRight(n<sub>1</sub>):
    Input tree n<sub>1</sub>
    Output n<sub>1</sub> rotated to the right
    if n<sub>1</sub> is empty v left(n<sub>1</sub>) is empty then
        return (n<sub>1</sub>)
    end if
        n<sub>2</sub>=left(n<sub>1</sub>)
    left(n<sub>1</sub>)=right(n<sub>2</sub>)
    right(n<sub>2</sub>)=n<sub>1</sub>
    return n<sub>2</sub>
```

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Cost considerations for tree rotation

- the rotation operation is cheap *O(1)*
- if applied appropriately, will tend to improve tree balance

Sometimes rotation is applied from leaf to root, along one branch

- cost of this is O(height)
- payoff is improved balance which reduces height
- reduced height pushes search cost towards O(log n)

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Previous discussion of BSTs did insertion at leaves.

Different approach: insert new item at root.

Potential disadvantages:

• large-scale rearrangement of tree for each insert (apparently)

Potential advantages:

- recently-inserted items are close to root
- lower cost if recent items more likely to be searched

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Method for inserting at root:

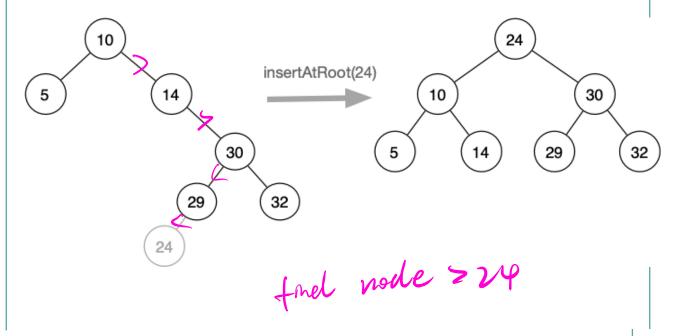
- base case:
 - o tree is empty; make new node and make it root
- recursive case:
 - insert new node as root of appropriate subtree
 - lift new node to root by rotation

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❖ ... Insertion at Root \varphi

Example of inserting at root:



Algorithm for inserting at root:

```
insertAtRoot(t, it):
```

```
Input tree t, item it to be inserted
Output modified tree with item at root

if t is empty tree then
    t = new node containing item

else if item < root(t) then
    left(t) = insertAtRoot(left(t), it)
    t = rotateRight(t)

else if it > root(t) then
    right(t) = insertAtRoot(right(t), it)
    t = rotateLeft(t)
end if
return t;
```

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Analysis of insertion-at-root:

- same complexity as for insertion-at-leaf: *O(height)*
 - o but cost is effectively doubled ... traverse down, rotate up
- tendency to be balanced, but no balance guarantee
- benefit comes in searching
 - for some applications, search favours recentlyadded items
 - insertion-at-root ensures these are close to root
- could even consider "move to root when found"
 - o effectively provides "self-tuning" search tree

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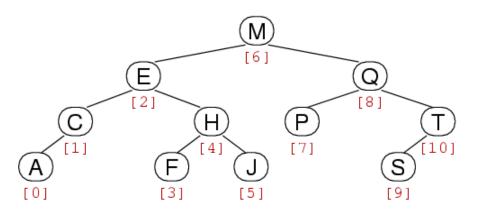
Tree Partitioning

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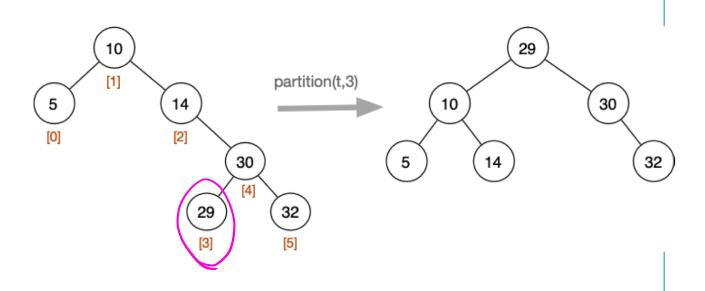
Tree partition operation partition (tree, i)

re-arranges tree so that element with index i becomes



For tree with N nodes, indices are 0.. N-1, in LNR order

Example of partition:



>> ... Tree Partitioning Implementation of partition operation: partition(tree, i): Input tree with n nodes, index i Output tree with item moved to the root m=#nodes(left(tree)) if i < m then left(tree)=partition(left(tree),i) tree=rotateRight(tree) else if i > m then $i \not\leftarrow w p \not \leftarrow \vec{y}$ right(tree)=partition(right(tree), i-m-1) tree=rotateLeft(tree)

if

with end if return tree Note: size(tree) = n, size(left(tree)) = m, size(right(tree)) = n-m- $COMP2521 20T1 \diamondsuit Balancing Search Trees \diamondsuit [17/30]$ when t=14 n=3 m=0 i=1when t=30 i=0 n=2 m=1when t=30 i=0 n=2 m=1where t=30 t=0 t=0 t=0



Analysis of tree partitioning

- no requirement for search (using element index instead)
- after each recursive partitioning step, one rotation
- overall cost similar to insert-at-root

Benefits

tends to improve balance ⇒ improves search cost

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Periodic Rebalancing

An approach to maintaining balance:

• insert at leaves as before; periodically, rebalance the tree

```
Input tree, item
Output tree with item randomly inserted

t=insertAtLeaf(tree,item)
if #nodes(t) mod k = 0 then
    t=rebalance(t)
end if
return t
```

When to rebalance? e.g. after every k insertions

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... Periodic Rebalancing

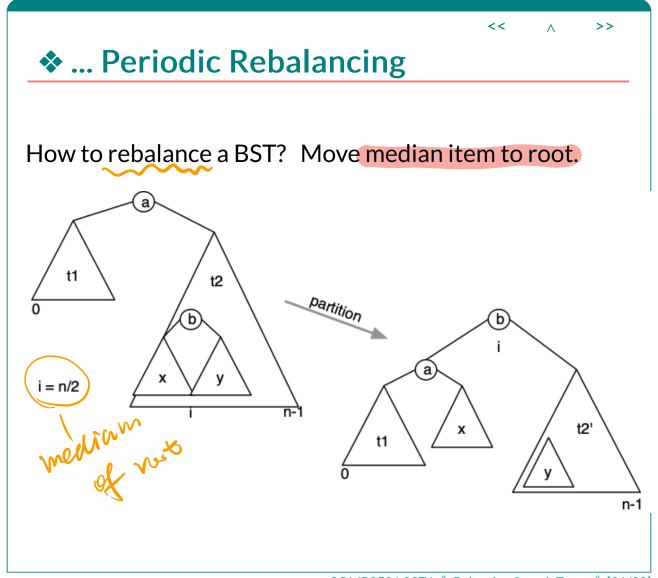
A problem with this approach ...

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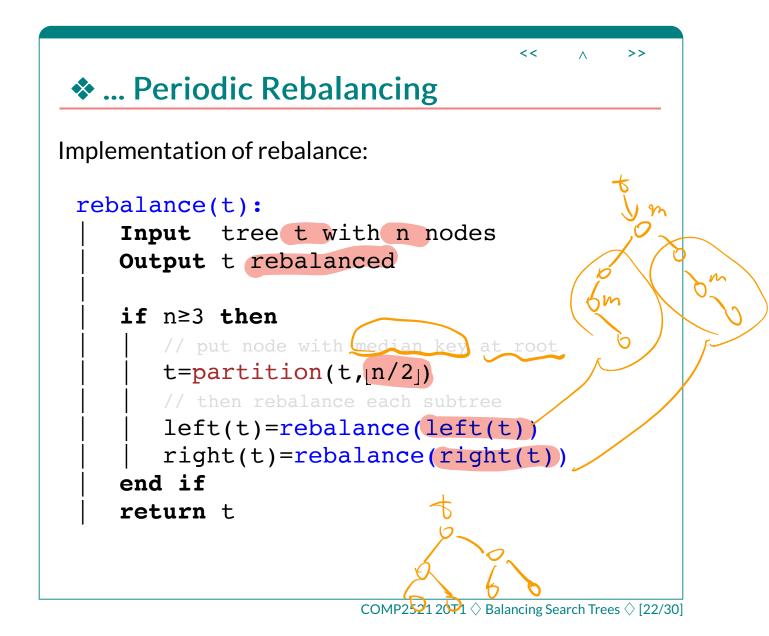
- operation #nodes() has to traverse whole (sub)tree
- to improve efficiency, change node structure

But maintaining nnodes requires extra work in other operations

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Analysis of rebalancing: visits every node $\Rightarrow O(N)$

Cost means not feasible to rebalance after each insertion.

When to rebalance? ... Some possibilities:

- after every k insertions
- whenever "imbalance" exceeds threshold

Either way, we tolerate worse search performance for periods of time.

Does it solve the problem?... Not completely ⇒ Solution: real balanced trees (next week)

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Randomised BST Insertion

Reminder: order of insertion can dramatically affect shape of tree

Tree ADT has no control over order that keys are supplied.

We know that inserting in random order gives $O(log_2n)$ search

Can the algorithm itself introduce some randomness?

In the hope that this randomness helps to balance the tree ...

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... Randomised BST Insertion

Approach: normally do leaf insert, randomly do root insert.

E.g. 30% chance \Rightarrow choose p=3, q=10

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... Randomised BST Insertion

Cost analysis:

- similar to cost for inserting keys in random order:
 O(log₂ n)
- does not rely on keys being supplied in random order

Approach can also be applied to deletion:

- standard method promotes inorder successor to root
- for the randomised method ...
 - o promote inorder successor from right subtree, OR
 - promote inorder predecessor from left subtree

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An Application of BSTs: Sets

Trees provide efficient search.

Sets require efficient search

- to find where to insert/delete
- to test for set membership

Logical to implement a set ADT via binary search tree.

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... An Application of BSTs: Sets

Assuming we have BST implementation with type Tree

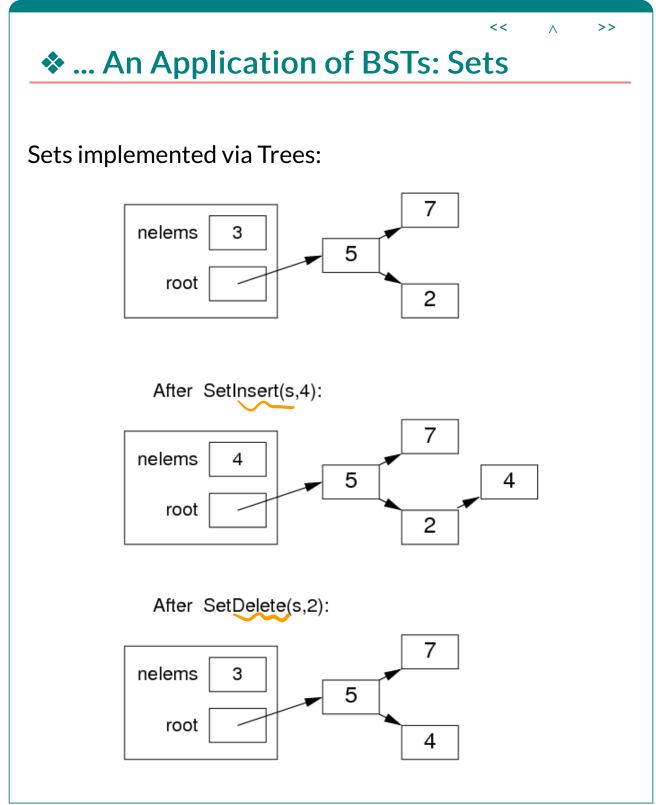
- which precludes duplicate key values
- which implements insertion, search, deletion

then **Set** implementation is

- SetInsert(Set,Item) =TreeInsert(Tree,Item)
- SetDelete(Set,Item) =TreeDelete(Tree,Item.Key)
- SetMember(Set,Item) =
 TreeSearch(Tree,Item.Key)

What about union? and intersection?

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... An Application of BSTs: Sets

Concrete representation:

```
#include <Tree.h>

typedef struct SetRep {
   int nelems;
   Tree root;
} SetRep;

Set newSet() {
   Set S = malloc(sizeof(SetRep));
   assert(S != NULL);
   S->nelems = 0;
   S->root = newTree();
   return S;
}
```

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