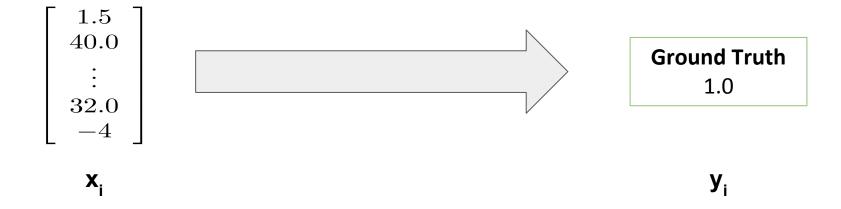
CS221 Section 2: Learning

Ajay Sohmshetty & Benoit Zhou

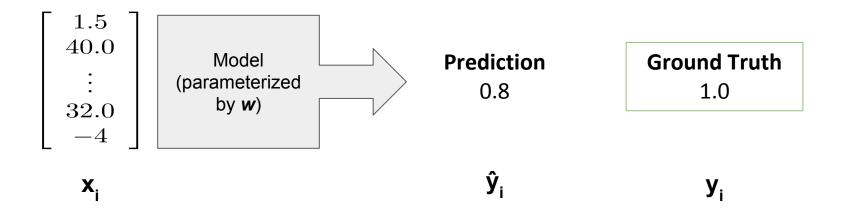
Topics

- Backpropagation
- SciKit Learn
 - *k*-nearest neighbors
 - Decision trees
 - Random forests
 - Hyperparameter search
 - Cross validation

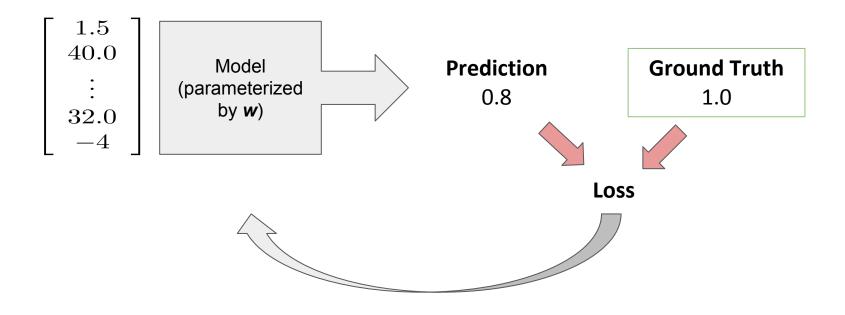
Datapoints



Model

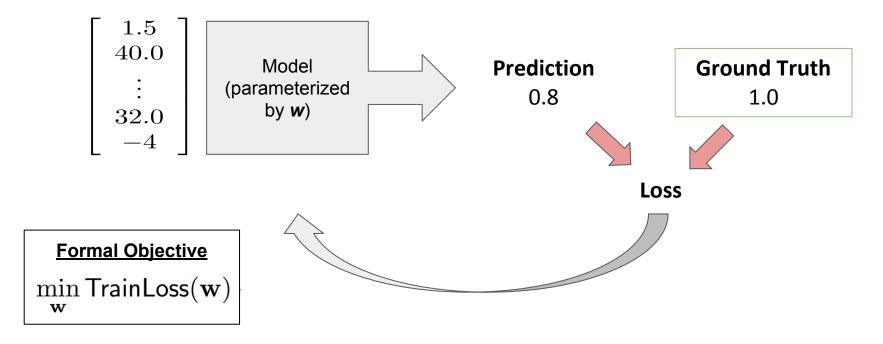


Loss



Key idea: Use loss to inform updates to weights.

Loss

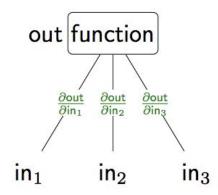


Key idea: Use loss to inform updates to weights.

Partial Derivatives / Gradients

We want to know how each weight affects the training loss.

→ exactly what derivative (gradient in the vector case) tells us!



Partial derivatives (gradients): how much does the output change if an input changes?

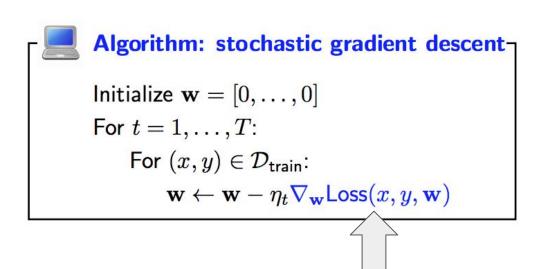
Gradient Descent

We want to know how each weight affects the training loss.

→ exactly what derivative (gradient in the vector case) tells us!



Stochastic Gradient Descent



Symbolic Gradient Computation - Two Layer NN

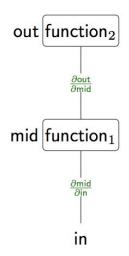
$$\begin{aligned} & \mathsf{TrainLoss}(\mathbf{V}, \mathbf{w}) = \frac{1}{|\mathcal{D}_{\mathsf{train}}|} \sum_{(x,y) \in \mathcal{D}_{\mathsf{train}}} \mathsf{Loss}(x,y,\mathbf{V},\mathbf{w}) \\ & \mathsf{Loss}(x,y,\mathbf{V},\mathbf{w}) = (y - f_{\mathbf{V},\mathbf{w}}(x))^2 \end{aligned}$$

$$f_{\mathbf{V},\mathbf{w}}(x) = \sum_{j=1}^{k} w_j \sigma(\mathbf{v}_j \cdot \phi(x))$$

<u>GOAL</u>

 $\nabla_{\mathbf{V},\mathbf{w}}\mathsf{TrainLoss}(\mathbf{V},\mathbf{w})$

Backpropagation



Chain rule: $\frac{\partial \text{out}}{\partial \text{in}} = \frac{\partial \text{out}}{\partial \text{mid}} \frac{\partial \text{mid}}{\partial \text{in}}$

Backprop Gradient Computation - Two Layer NN

$$\begin{aligned} & \mathsf{TrainLoss}(\mathbf{V}, \mathbf{w}) = \frac{1}{|\mathcal{D}_{\mathsf{train}}|} \sum_{(x,y) \in \mathcal{D}_{\mathsf{train}}} \mathsf{Loss}(x,y,\mathbf{V},\mathbf{w}) \\ & \mathsf{Loss}(x,y,\mathbf{V},\mathbf{w}) = (y - f_{\mathbf{V},\mathbf{w}}(x))^2 \end{aligned}$$

$$f_{\mathbf{V},\mathbf{w}}(x) = \sum_{j=1}^{k} w_j \sigma(\mathbf{v}_j \cdot \phi(x))$$

<u>GOAL</u>

 $\nabla_{\mathbf{V},\mathbf{w}}\mathsf{TrainLoss}(\mathbf{V},\mathbf{w})$

Why Backpropagate?

- Don't have to deal with the nastiness of the chain rule with deep neural networks
- Performance optimizations (can hold onto intermediary values, don't have to recompute)
- Translates into a modular framework, so packages like Tensorflow and PyTorch will auto-differentiate for you!

Backpropagation

Backprop: http://cs231n.github.io/optimization-2/

Vector, Matrix, and Tensor Derivatives: http://cs231n.stanford.edu/vecDerivs.pdf

scikit-learn

```
import sklearn
import numpy as np
```

Load a dataset

X is a $n \times d$ matrix where each row is $\phi(x_i) \in \mathbb{R}^d$

y is a *n*-dimensional vector where each entry y_i is the label of the i^{th} datapoint x_i

```
from sklearn.datasets import load_iris
X = load_iris().data
y = load_iris().target
```

```
X[0]
array([5.1, 3.5, 1.4, 0.2])
```

```
y[0]
```

0

Split into training and test sets

```
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.33, random_state=3)
```

Logistic Regression

```
from sklearn.linear_model import LogisticRegression
lr = LogisticRegression()
lr = lr.fit(X_train, y_train)
y_pred = lr.predict(X_test)
```

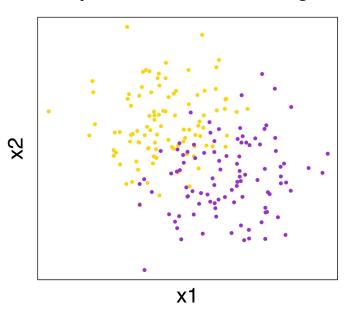
```
y_pred
```

```
array([0, 0, 0, 0, 0, 2, 1, 0, 2, 1, 1, 0, 1, 1, 2, 0, 2, 2, 2, 0, 2, 2, 2, 1, 0, 2, 2, 1, 1, 1, 0, 0, 2, 1, 0, 0, 2, 0, 2, 1, 2, 1, 0, 0, 2, 1, 0, 2, 2, 2])
```

```
np.mean(y_pred == y_test)
```

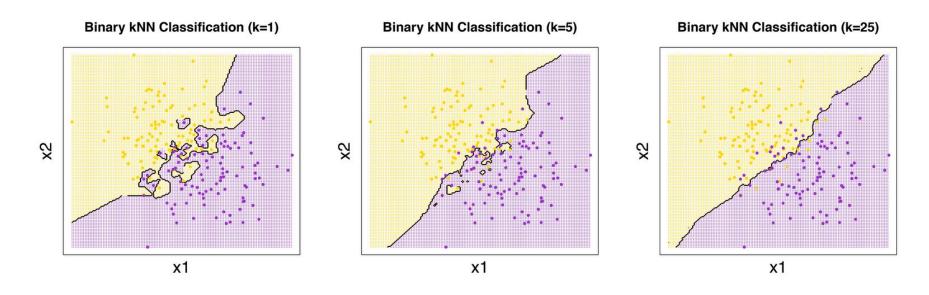
k-nearest neighbors

Binary kNN Classification Training Set



k-nearest neighbors

Effect of *k*:

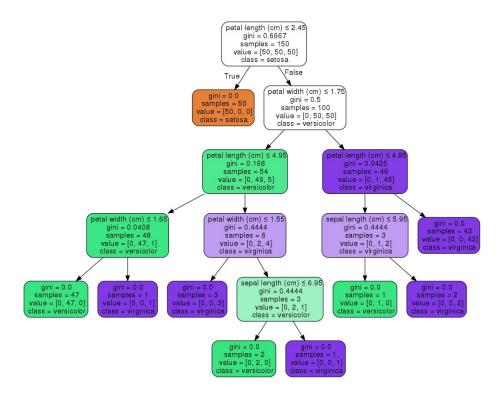


k-nearest neighbors

from sklearn.neighbors import KNeighborsClassifier

knn = KNeighborsClassifier()

Decision Tree



Decision Tree

```
from sklearn.tree import DecisionTreeClassifier
dt = DecisionTreeClassifier()
dt = dt.fit(X_train, y_train)
y_pred = dt.predict(X_test)
```

```
y_pred
```

```
array([0, 0, 1, 1, 0, 2, 1, 1, 0, 1, 2, 1, 1, 0, 0, 2, 1, 0, 0, 2, 1, 2, 0, 1, 0, 1, 2, 2, 1, 1, 0, 0, 2, 2, 1, 2, 0, 1, 2, 0, 0, 0, 2, 0, 1, 2, 0, 1, 1, 2, 0, 0, 2, 0, 0, 1, 2, 0])
```

```
np.mean(y_pred == y_test)
```

Random Forest

Decision trees have low bias but high variance

Random forests reduce the variance with bagging (bootstrap aggregating)

```
for b = 1, ..., B: # B is a parameter that you choose
    sample with replacement n training examples from (X, y); call these
(X_b, y_b)
    train a decision tree on (X_b, y_b), with a subset of the features
Take the average (for regression) or the majority vote (for classification) of the B decision trees
```

Random Forest

```
from sklearn.ensemble import RandomForestClassifier
rf = RandomForestClassifier()
rf = rf.fit(X_train, y_train)
y_pred = rf.predict(X_test)
```

```
y_pred
```

```
array([0, 0, 1, 1, 0, 2, 1, 1, 0, 1, 2, 1, 1, 0, 0, 2, 1, 0, 0, 2, 1, 2, 0, 1, 0, 1, 1, 2, 1, 1, 0, 0, 2, 1, 1, 2, 0, 1, 2, 0, 0, 0, 2, 0, 1, 2, 0, 1, 1, 2, 0, 0, 1, 0, 0, 1, 2, 0])
```

```
np.mean(y_pred == y_test)
```

Gradient Boosting

Random forests try to decrease the high variance of decision trees while keeping the low bias

Gradient boosting trees try to decrease a high bias while keeping a low variance

Start with a weak learner, i.e. a really simple tree

Each iteration, in order to minimize the loss, add a tree without modifying the existing trees

Gradient Boosting

```
from sklearn.ensemble import GradientBoostingClassifier
gb = GradientBoostingClassifier()
gb = gb.fit(X_train, y_train)
y_pred = gb.predict(X_test)
```

```
y_pred
```

```
array([0, 0, 1, 1, 0, 2, 1, 1, 0, 1, 2, 1, 1, 0, 0, 2, 1, 0, 0, 2, 1, 2, 0, 1, 0, 1, 2, 2, 1, 2, 1, 1, 0, 0, 2, 2, 1, 2, 0, 1, 2, 0, 0, 0, 2, 0, 1, 2, 0])
```

```
np.mean(y_pred == y_test)
```

Hyperparameters

Number of trees: usually, the more, the better

Max depth of trees: a deeper tree is more likely to overfit

Max number of features: sqrt(p) or log(p) as a rule of thumb

Hyperparameter search

Grid search: exhaustive, suffers from curse of dimensionality, parallelizable

Randomized search (recommended): faster, allows including prior knowledge by specifying distribution from which to sample, parallelizable, good performance

Bayesian optimization: builds a probabilistic model to find the best hyperparameters

Validation

Solution: randomly take out 10-50% of training data and use it instead of the test set to estimate test error.

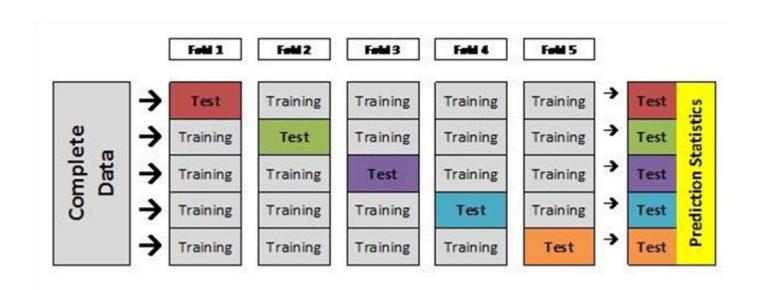




Definition: validation set-

A validation (development) set is taken out of the training data which acts as a surrogate for the test set.

k-fold cross-validation



k-fold cross-validation