### JOSHUA P. KEARNEY

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#### **Education**

# **Bachelor of Mechanical Engineering (Co-op)**

Sep. 2014 - Apr. 2019

**Memorial University of Newfoundland** 

GPA(CGPA): 4/4 (3.56/4)

### **Employment**

### **Vehicle Software Research and Development Engineering Intern**

#### **General Dynamics Mission Systems**

Ottawa, ON

Sep. 2018 – Dec. 2018

- Developed and implemented a military networking software for next-gen vehicle smart display computers
- Created and tested embedded Linux software, developing a system database (Xilinx/Yocto, Embedded C)
- Collaborated through an Agile development cycle using tools such as Git, Bitbucket, Jira, and Docker

### **Electromechanical Systems - Engineering Intern**

Jan. 2018 - May 2018

**DuXion Motors Inc.** 

St. John's, NL

- Designed an electric aircraft motor cooling system that reduced the system temperature by 50%
- Developed FEA/CFD/CAD models to optimize thermal performance of a high-power density electric motor

## **Robotic Vehicle Mechanical Team - Engineering Intern**

May 2017 - Aug. 2017

**Kraken Robotics Inc.** 

St. John's, NL

- Designed and manufactured a proprietary underwater electronic packaging system for an AUV vehicle
- Reduced cost on AUV vehicle fins by 90% through implementing an in-house injection molding process

## **Armored Vehicle Testing Team - Engineering Intern**

Sep. 2016 - Dec. 2016

**Rheinmetall Landsysteme Defence GmbH** 

Unterlüß, Germany

- Developed the electronic packaging system that protects the Puma IFV battle tanks communication network
- Environmentally tested military systems to military standard guidelines (MIL-STD-810)

## **Electronic Systems - Engineering Intern**

Jan. 2016 - May 2016

May 2015 – Aug. 2015

Bell Canada St. John's, NL

Designed and manufactured ruggedized electronic enclosures, installed and repaired radio board modules

#### **Achievements**

### **Electromechanical Systems Design**

Jan. 2017 - Present

Eastern Edge Robotics

- Developed distributed system control software and embedded system software for an underwater robot
- Designed and manufactured an underwater robotic vehicle chassis
- Competed in 2017 & 2018 International MATE ROV Competitions (CA, WA), placing 5<sup>th</sup> & 8<sup>th</sup> overall

#### **SKILLS**

Programming: Embedded C | Python | C++ | Embedded Linux | Bash | MATLAB | Arduino | ARM/Mbed Software: Git | Docker | Xilinx/Yocto | Jira/Bitbucket | Unigraphics | Ansys | PCB Design Software Oscilloscope | Multimeter | 3D Printing | Laser Cutting | CNC | Hand/Power Tools Red Cross First Aid | Mental Health First Aid | Canadian Driver's License

#### **EXTRACURRICULAR ACTIVITIES**

Projects: Portfolio Website | Hackathon Chrome Extension | Magnetically Controlled Lamp | Custom 3D printer

**Volunteering:** Head Coach of Competitive Swim Team | Resident Assistant & Engineering Tutor

Interests: Robotics | Embedded Systems | Web Dev | Reading | Swimming | Travel Recent Reads: When Breath Becomes Air | Gödel, Escher, Bach | Mindset | Snow Crash