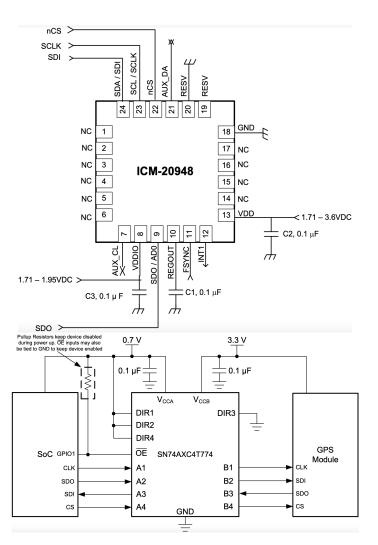
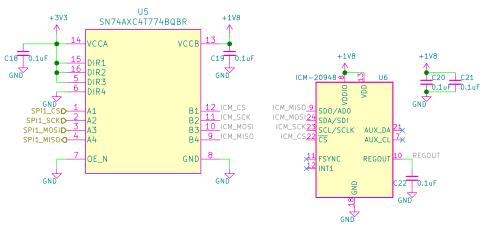


Gyro

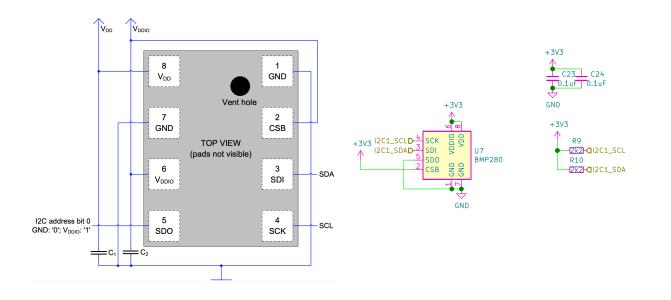




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 Id: 3/9

Barometer



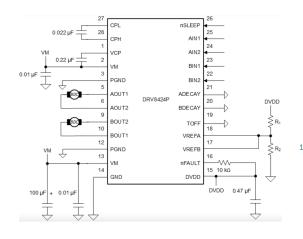
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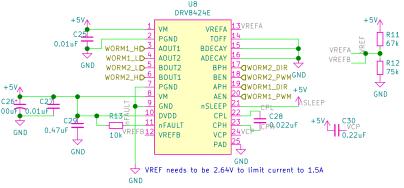
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 Id: 4/9

Worm Motor Driver



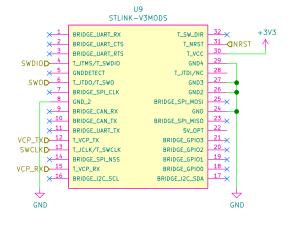


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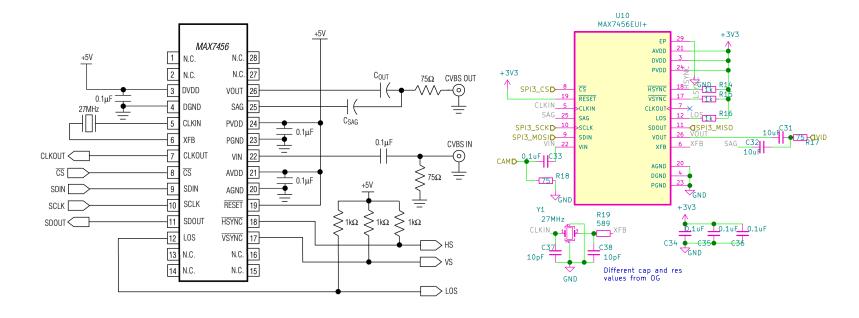
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 Id: 5/9

Debugger

Side	Pin#	Pin description	Туре
	1	Bridge UART RX ⁽¹⁾	I
	2	Bridge UART CTS	I
	3	Bridge UART RTS	0
	4	T_JTMS/T_SWDIO	0
	5	GNDDetect ⁽²⁾	I
	6	T_JTDO/T_SWO ⁽³⁾	I
	7	Bridge SPI CLK	I/O
EFT	8	GND	s
-EF I	9	Bridge CAN RX ⁽¹⁾	1
	10	Bridge CAN TX ⁽⁴⁾	0
	11	Bridge UART TX ⁽⁴⁾	0
	12	T_VCP_TX	I
	13	T_JCLK/T_SWCLK	0
	14	Bridge SPI NSS	I/O
	15	T_VCP_RX	0
	16	Bridge I2C SCL	0
	17	Bridge I2C SDA	I/O
	18	Bridge GPI00	I/O
	19	Bridge GPIO1	I/O
	20	Bridge GPIO2	I/O
	21	Bridge GPIO3	I/O
	22	Reserved ⁽⁵⁾	-
	23	Bridge SPI MISO	I/O
RIGHT	24	GND	s
RIGHT	25	Bridge SPI MOSI	I/O
	26	GND	s
	27	GND	s
	28	T_JTDI/NC ⁽⁶⁾	0
	29	GND	s
	30	T_VCC ⁽⁷⁾	I
	31	T_NRST	0
	32	T_SW_DIR	0



OSD



Connectors

JST 8 Pin Conn JST 6 Pin Conn

USB Conn



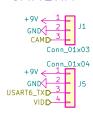




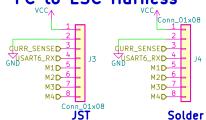




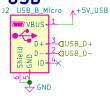
CAMERA



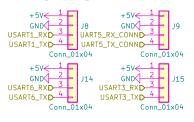




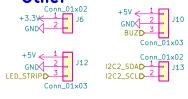
USB



UARTS



Other





Conn_01x02		
WORM1_HD 1 WORM1_LD 2		J7

WURMZ_LD	
LIMIT1_INTD 1	J16
LIMIT1_INT <mark>D=1</mark> LIMIT2_INT D= 1	117

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