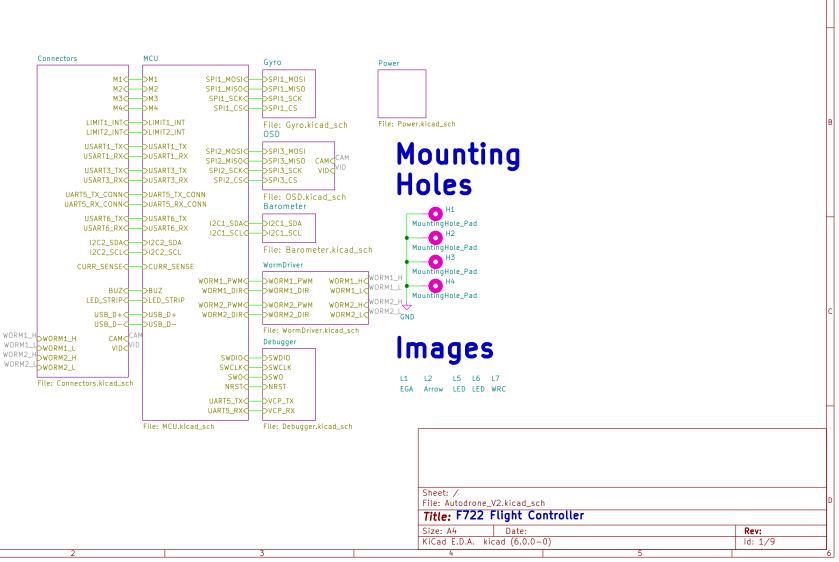
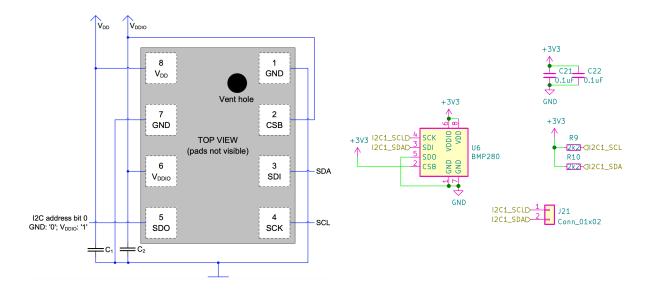
Main



Barometer



Connectors

JST 8 Pin Conn JST 6 Pin Conn

USB Conn









D+ 3-QUSB_D+ 2-QUSB_D-

D- 4X

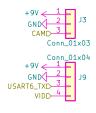
D- 4X

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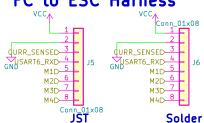
D- 4X



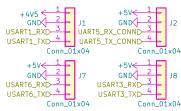
CAMERA







UARTS USB J4_USB_B_Micro 5V_USB



Other









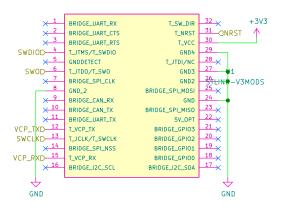
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Size: A4 Date: KiCad E.D.A. kicad (6.0.0-0)Id: 3/9

Debugger

Side	Pin#	Pin description	Туре
	1	Bridge UART RX ⁽¹⁾	ı
LEFT	2	Bridge UART CTS	I
	3	Bridge UART RTS	0
	4	T_JTMS/T_SWDIO	0
	5	GNDDetect ⁽²⁾	I
	6	T_JTDO/T_SWO ⁽³⁾	I
	7	Bridge SPI CLK	I/O
	8	GND	s
	9	Bridge CAN RX ⁽¹⁾	I
	10	Bridge CAN TX ⁽⁴⁾	0
	11	Bridge UART TX ⁽⁴⁾	0
	12	T_VCP_TX	I
	13	T_JCLK/T_SWCLK	0
	14	Bridge SPI NSS	I/O
	15	T_VCP_RX	0
	16	Bridge I2C SCL	0
	17	Bridge I2C SDA	I/O
	18	Bridge GPIO0	I/O
	19	Bridge GPIO1	I/O
	20	Bridge GPIO2	I/O
	21	Bridge GPIO3	I/O
	22	Reserved ⁽⁵⁾	-
	23	Bridge SPI MISO	I/O
DIOLIT	24	GND	s
RIGHT	25	Bridge SPI MOSI	I/O
	26	GND	s
	27	GND	s
	28	T_JTDI/NC ⁽⁶⁾	0
	29	GND	S
	30	T_VCC ⁽⁷⁾	I
	31	T_NRST	0
	32	T_SW_DIR	0



Sheet: /Debugger/ File: Debugger.kicad_sch

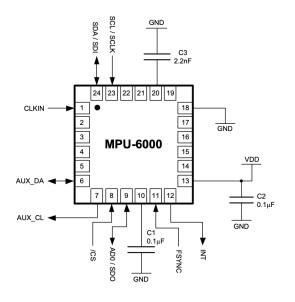
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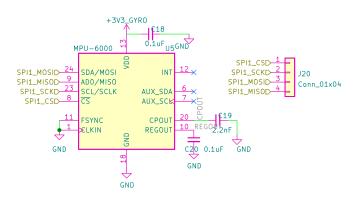
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 Rev:

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 Id: 4/9

Gyro

7.2 Typical Operating Circuit



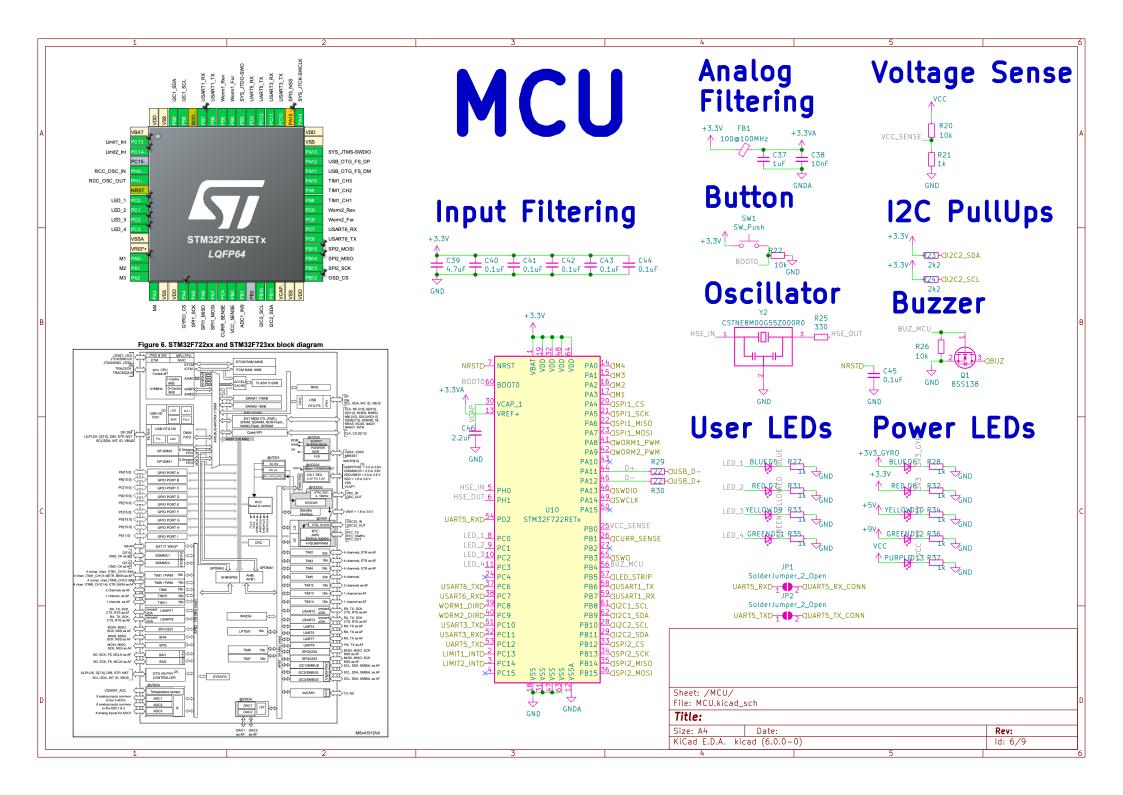


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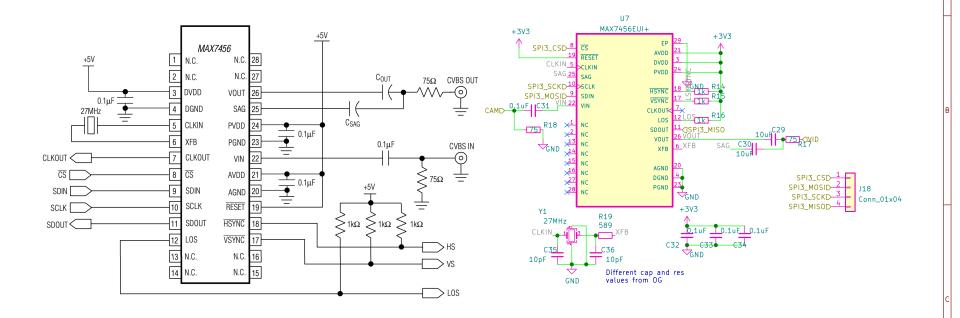
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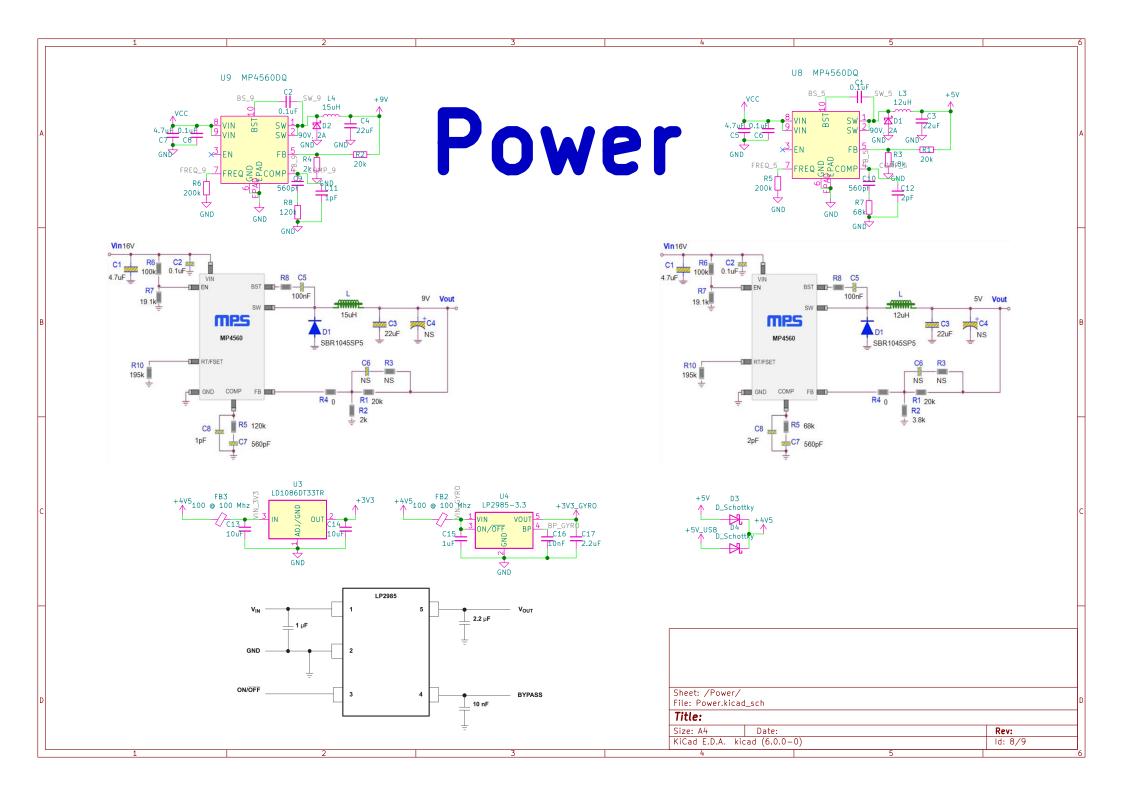
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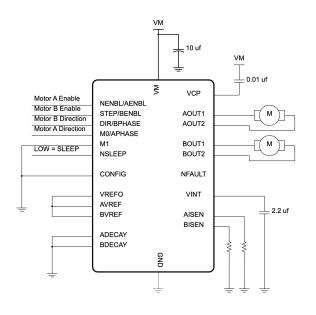
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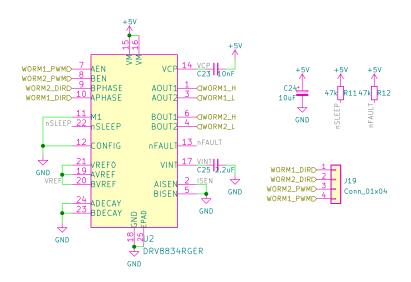


2 3



Worm Motor Driver





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