

Emory University

MATH 212 Differential Equations Learning Notes

Jiuru Lyu

September 29, 2023

Contents

1	First Order ODEs	2
1.1	Introduction	2
1.2	Linear First Order ODEs	4
1.3	Separable Equations	9
1.4	Exact Equations	14
1.5	Autonomous ODEs	20
2	Second Order ODEs	22
2.1	Linear Algebra	22
3	System of ODEs	26

1 First Order ODEs

1.1 Introduction

Definition 1.1.1 (Ordinary Differential Equations/ODEs). An *ordinary differential equation* is an equation that contains one or more derivatives of an unknown function $y = y(x)$.

Definition 1.1.2 (Order of ODEs). The *order* of an ODE is the maximum order of the derivatives appearing in the equation.

Definition 1.1.3 (Solution to ODEs). The *solution* to an ODE is a function y that satisfies the equation.

Example 1.1.4 Solve $y'' = 3x + 1$.

Solution 1.

$$y' = \int 3x + 1 \, dx = \frac{3}{2}x^2 + x + C$$
$$y = \int y' \, dx = \int \left(\frac{3}{2}x^2 + x + C \right) dx = \frac{1}{2}x^3 + \frac{1}{2}x^2 + Cx + D.$$

□

Definition 1.1.5 (Linear ODEs/Non-Linear ODEs). A first order ODE is *linear* if it can be written as

$$y' + p(x)y = f(x).$$

Otherwise, it is *non-linear*.

Definition 1.1.6 (Homogenous/Non-Homogenous Linear ODEs). If $f(x) = 0$, then the linear ODE is *homogenous*. That is,

$$y' + p(x)y = 0.$$

Otherwise, it is *non-homogenous*.

Definition 1.1.7 (Trivial/Non-Trivial Solution). $y = 0$ is a *trivial solution* to a homogenous ODE. Any other solutions are *non-trivial*.

Definition 1.1.8 (One-Parameter Family of Solutions). We call C a *parameter* and the equation, therefore solution, defines a *one-parameter family* of solutions.

Example 1.1.9 For the ODE $y' = 1$, $y_1 = x + C_1$ is a solution to it, and it is a one-parameter family of solutions. Similarly, for $y' = \frac{1}{x^2}$, the one-parameter families of solutions are defined by $y_2 = -\frac{1}{x} + C_2$ on the interval $(-\infty, 0) \cup (0, \infty)$.

Definition 1.1.10 (General Solution). Given the general form of the linear ODE $y' + p(x)y = f(x)$ if p and f are continuous on some open interval (a, b) and there is a unique formula $y = y(x, c)$ and we have the following properties:

- for each fixed c , the resulting function of x is a solution of the ODE on (a, b) , and
- if y is a solution of the ODE, then y can be obtained by choosing the value of c appropriately.

The function $y = y(x, c)$ is called a *general solution*.

More generally, we can write an ODE as

$$P_0(x)y' + P_1(x)y = F(x).$$

In this case, the ODE has a general solution on any open interval in which P_0 , P_1 , and F are continuous and $P_0 \neq 0$.

Definition 1.1.11 (Initial Value Problem (IVP)). A differential equation with an initial condition.

Example 1.1.12 Let a be a constant. Find the general solution of $y' - ay = 0$ and solve

the IVP $\begin{cases} y' - ay = 0 \\ y(x_0) = y_0. \end{cases}$

Solution 2.

Classification: First order, Linear, Homogeneous.

Trivial Solution: $y = 0$.

General solution:

$$\begin{aligned} \frac{dy}{dx} &= ay \\ \int \frac{1}{y} dy &= \int a dx \\ \ln |y| &= ax + c \\ y &= e^{ax+c} = Ae^{ax}. \end{aligned}$$

This general solution includes the trivial solution.

IVP: Substitute $x = x_0$ and $y = y_0$:

$$y_0 = Ae^{ax_0} \longrightarrow A = y_0 e^{-ax_0}$$

So,

$$y^{\text{IVP}} = y_0 e^{-ax_0} e^{ax} = y_0 e^{a(x-x_0)}.$$

This IVP is a “generic initial condition.” We need more information on x_0, y_0 to get a more specific solution. □

1.2 Linear First Order ODEs

Theorem 1.2.1

If p is continuous on (a, b) , then the general solution of the homogeneous equation $y' + p(x)y = 0$ on (a, b) is given by

$$y = ce^{-\int p(x) dx}.$$

Proof 1.

(a). Substitute the solution formula to show that $y = ce^{-\int p(x) dx}$ is a solution for any choice of c .

$$y' = c \left(- \int p(x) dx \right)' e^{-\int p(x) dx} = -cp(x)e^{-\int p(x) dx}.$$

Then,

$$y' + p(x)y = -cp(x)e^{-\int p(x) dx} + cp(x)e^{-\int p(x) dx} = 0.$$

So, $y = ce^{-\int p(x) dx}$ is a solution for any choice of c . \square

(b). Want to show: any solution of $y' + p(x)y = 0$ can be written as $y = ce^{-\int p(x) dx}$. Note that $y = 0$ is a trivial solution, so we assume $y \neq 0$.

$$\begin{aligned} y' + p(x)y &= 0 \\ y' &= -p(x)y \\ \frac{y'}{y} &= -p(x) \\ \rightsquigarrow \int \frac{1}{y} dy &= \int -p(x) dx \\ \ln |y| &= -\int p(x) dx \\ y &= ce^{-\int p(x) dx}. \end{aligned}$$

Note that when $c = 0$, $y = 0$ is the trivial solution. So, any solution of $y' + p(x)y = 0$ can be written as $y = ce^{-\int p(x) dx}$. \blacksquare

Example 1.2.2 Solve the IVP

$$\begin{cases} xy' + y = 0 \\ y(1) = 3. \end{cases}$$

Solution 2.

Note that $P_0(x) = x$ and $P_1(x) = 1$, which are continuous on \mathbb{R} . Since we need $P_0(x) \neq 0$, $x \neq 0$. So the interval of validity is $\mathbb{R} \setminus \{0\}$.

Method 1: Separation of Variables

$$y' = -\frac{y}{x}.$$

Note that $y = 0$ is a solution. Assume $y \neq 0$.

$$\begin{aligned}\frac{y'}{y} = -\frac{1}{x} &\rightsquigarrow \int \frac{1}{y} dy = -\int \frac{1}{x} dx + k \\ \ln |y| &= -\ln |x| + k \\ |y| &= e^k \frac{1}{|x|} \\ y &= \frac{c}{x}\end{aligned}$$

Method 2: Solution Formula By Theorem 1.2.1,

$$y = ce^{-\int p(x) dx} = ce^{-\int \frac{1}{x} dx} = ce^{-\ln |x|} = \frac{c}{x}.$$

Solving the IVP Substitute $x = 1$ and $y = 3$:

$$3 = \frac{c}{1} \longrightarrow c = 3.$$

So, $y^{\text{IVP}} = \frac{3}{x}$.

□

Example 1.2.3 Given the equation $(4 + x^2)y' + 2xy = 4x$. Classify the equation and find the general solution $y = y(x, c)$.

Solution 3.

This is a first order, linear, non-homogeneous differential equation.

Note that $P_0(x) = 4 + x^2$, $P_1(x) = 2x$, $F(x) = 4x$, and $P_0 \neq 0 \forall x \in \mathbb{R}$, so the interval of validity is \mathbb{R} . Also note that $\frac{d}{dx}[4 + x^2] = 2x$, so the equation can be written as

$$(4 + x^2)\frac{dy}{dx} + \frac{d}{dx}[4 + x^2]y = 4x.$$

Using the product rule to re-write the LHS as

$$\begin{aligned}\frac{d}{dx}[(4 + x^2)y] &= 4x \\ \int \frac{d}{dx}[(4 + x^2)y] dx &= \int 4x dx + c \\ (4 + x^2)y &= 2x^2 + c \\ y &= \frac{2x^2 + c}{4 + x^2}.\end{aligned}$$

□

Example 1.2.4 Given the equation $y' - 2y = 4 - x$. Classify the equation and find the general solution $y = y(x, c)$.

Solution 4.

This is a first order, linear, non-homogeneous differential equation.

Since $P_0(x) = 1$, $P_1(x) = -2y$, $F(x) = 4 - x$, and $P_0(x) \neq 0 \forall x \in \mathbb{R}$, the interval of validity is \mathbb{R} . Consider $\mu = \mu(x) \neq 0$. Multiply both sides of the equation by $\mu(x)$:

$$\mu(x)y' - 2\mu(x)y = \mu(x)(4 - x) \quad (1)$$

To make the LHS a product rule, we need

$$\frac{d}{dx}[\mu(x)y(x)] = \mu'(x)y(x) + \mu(x)y'(x) = \mu(x)y'(x) - 2\mu(x)y.$$

So, we have $\mu' = -2\mu$, or $\mu' + 2\mu = 0$, a first order, linear, homogeneous ODE. Solving this ODE, we get $\mu(x) = ce^{-2x}$. Since we only want one specific μ that would work, take $c = 1$. So, $\mu(x) = e^{-2x}$. Substituting $\mu(x) = e^{-2x}$ to Eq. (1):

$$e^{-2x}y' - 2e^{-2x}y = e^{-2x}(4 - x), \quad \tilde{P}_0 = e^{-2x} \neq 0, \quad \tilde{P}_1 = -2e^{-2x}.$$

Using the product rule:

$$\begin{aligned} \frac{d}{dx}[e^{-2x}y] &= 4e^{-2x} - xe^{-2x} \\ \int \frac{d}{dx}[e^{-2x}y] dx &= \int 4e^{-2x} - xe^{-2x} dx + c \\ e^{-2x}y &= \frac{1}{2}xe^{-2x} - \frac{7}{4}e^{-2x} + c \\ y &= e^{2x} \left(\frac{1}{2}xe^{-2x} - \frac{7}{4}e^{-2x} + c \right) \\ &= \frac{1}{2}x - \frac{7}{4} + ce^{2x}. \end{aligned}$$

□

Theorem 1.2.5 Method of Integrating Factor

Given the first order linear differential equation $y' + p(x)y = f(x)$, with p and f both continuous on some interval (a, b) ,

$$y(x) = \frac{1}{\mu(x)} \left[\int \mu(x)f(x) \, dx + c \right]$$

is the general solution to the equation, with

$$\mu(x) = e^{\int p(x) \, dx}.$$

We call $\mu(x)$ the *integrating factor*.

Proof 5. Consider $\mu = \mu(x) \neq 0$. Multiplying the both sides of $y' + p(x)y = f(x)$ by μ :

$$\mu y' + p\mu y = \mu f. \quad (2)$$

Impose $\mu y' + p\mu y = \frac{d}{dx}[\mu y]$ to find $\mu = \mu(x)$:

$$\mu y' + p\mu y = \mu' y + \mu y'$$

$$\mu' - p\mu = 0,$$

first order, linear, homogeneous ODE

$$\mu(x) = e^{\int p(x) \, dx},$$

the integrating factor

Substitute $\mu(x) = e^{\int p(x) \, dx}$ into Eq. (2):

$$\begin{aligned} \frac{d}{dx}[\mu y] &= \mu f \\ \int \frac{d}{dx}[\mu y] \, dx &= \int \mu f \, dx + c \\ \mu y &= \int \mu f \, dx + c \\ y(x) &= \frac{1}{\mu(x)} \left[\int \mu(x)f(x) \, dx + c \right]. \end{aligned}$$

■

Example 1.2.6 Give the equation $y' + 2y = x^3 e^{-2x}$. Classify the equation and find the general solution $y = y(x, c)$.

Solution 6.

It is a first order, linear, non-homogeneous ODE, with $p = 2$ and $f = x^3 e^{-2x}$. Let $\mu(x)$ be the integrating factor. Then,

$$\mu(x) = e^{\int 2 \, dx} = e^{2x}.$$

So, by the method of integrating factor, we know

$$\begin{aligned}\frac{d}{dx} [\mu(x)y] &= \mu(x)f(x) \\ \int \frac{d}{dx} [e^{2x}y] dx &= \int e^{2x}x^3e^{-2x} dx + c \\ e^{2x}y &= \int x^3 dx + c \\ e^{2x}y &= \frac{1}{4}x^4 + c \\ y &= \frac{1}{4}x^4e^{-2x} + ce^{-2x}.\end{aligned}$$

□

Remark. Re-examine the formula we derived from the method of integrating factor:

$$y(x) = \frac{1}{\mu} \int f\mu dx + \boxed{\frac{c}{\mu}}.$$

The part being boxed, $\frac{c}{\mu}$, is independent from f and is exactly $ce^{-\int p dx}$ if we expand, which is the solution for a homogeneous differential equation.

Definition 1.2.7 (Complementary Equation). The *complementary equation* to a first order ODE $y' + py = f$ is the homogeneous part of it. i.e., $y' + py = 0$.

Theorem 1.2.8 Method of Variation of Parameters

Given the first order linear differential equation $y' + p(x)y = f(x)$, with p and f both continuous on some interval (a, b) ,

$$y(x) = y_1(x) \left[\int \frac{f(x)}{y_1(x)} dx + c \right]$$

is the general solution to the equation, where y_1 is a solution of the complementary equation $y' + py = 0$.

Proof 7. Call y_1 a solution of the complementary equation $y' + p(x)y = 0$. Then, we want to find $y(x) = u(x)y_1(x)$, the general solution of $y' + p(x)y = f(x)$, where u is an unknown function of f . Note that, by product rule, $y'(x) = u'y_1 + uy_1'$. Then, the equation becomes

$$\begin{aligned}(u'y_1 + uy_1') + p(x)(uy_1) &= f(x) \\ u'y_1 + uy_1' + puy_1 &= f \\ y_1u' + \underbrace{(y_1' + py_1)}_0 u &= f \\ y_1u' = f &\implies u(x) = \int \frac{f(x)}{y_1(x)} dx + c.\end{aligned}$$

Therefore, the formula to find y is given by

$$y = y_1 u = y_1(x) \left[\int \frac{f(x)}{y_1(x)} dx + c \right].$$

■

Remark. The method of variation of parameters will be more useful when solving second or higher order differential equations.

Example 1.2.9 Give the equation $y' + 2y = x^3 e^{-2x}$. Find the general solution $y = y(x, c)$ using the method of variation of parameters.

Solution 8.

It is a first order, linear, non-homogeneous ODE, with $p = 2$ and $f = x^3 e^{-2x}$. Let y_1 be the solution of the complementary equation $y' + 2y = 0$. Then, $y_1(x) = e^{-\int 2 dx} = e^{-2x}$. By the method of variation of parameters, suppose $y = u y_1$, where u is an unknown function of x . Then,

$$u(x) = \int \frac{f(x)}{y_1(x)} dx + c = \int \frac{x^3 e^{-2x}}{e^{-2x}} dx + c = \int x^3 dx + c = \frac{1}{4} x^4 + c.$$

So,

$$y = u y_1 = e^{-2x} \left(\frac{1}{4} x^4 + c \right) = \frac{1}{4} x^4 e^{-2x} + c e^{-2x}.$$

□

Theorem 1.2.10 Existence and Uniqueness Theorem

Suppose that $p = p(x)$ and $f = f(x)$ are continuous on (a, b) . Then, a general solution of $y' + p(x)y = f(x)$ on (a, b) is

$$y(x) = y_1(x) \left[\int \frac{f(x)}{y_1(x)} dx + c \right],$$

where $y_1(x)$ is a solution of the complementary equation (i.e., $y' + p(x)y = 0$).

If x_0 is an arbitrary point in (a, b) and y_0 is an arbitrary real number, then the initial value problem,

$$y' + p(x)y = f(x), \quad y(x_0) = y_0$$

has a unique solution on (a, b) .

1.3 Separable Equations

Definition 1.3.1 (General Forms). The general form of a non-linear first order ODE is given by

$$y' = f(x, y(x)).$$

If we take $M(x, y) = -f(x, y)$ and $N(x, y) = 1$, we can also re-write the equation into

$$M(x, y) + N(x, y)y' = 0, \quad \text{or} \quad M(x, y) dx + N(x, y) dy = 0.$$

Definition 1.3.2 (Separable Equations). If $M(x, y) = M(x)$ and $N(x, y) = N(y)$, then the ODE is called *separable*.

Theorem 1.3.3 Separation of Variables (SoV)

Consider the non-linear first order ODE $M(x, y) + N(x, y)y' = 0$, with $M(x, y) = M(x)$ and $N(x, y) = N(y)$. Then we can find an implicit solution of the ODE in the form of

$$F(x, y) = c,$$

where $F(x, y)$ is a function of x and y and

$$F(x, y) = \int M(x) dx + \int N(y) dy.$$

Proof 1. Let $H_1'(x) = M(x)$ and $H_2'(y) = N(y)$. Then, the equation becomes

$$\begin{aligned} H_1'(x) + H_2'(y)y' &= 0 \\ \frac{d}{dx} [H_1(x)] + \frac{d}{dy} [H_2(y)] \frac{dy}{dx} &= 0 \end{aligned}$$

By using the chain rule, $\frac{d}{dy} [H_2(y)] \frac{dy}{dx} = \frac{d}{dx} [H_2(y(x))]$. So, the equation becomes

$$\begin{aligned} \frac{d}{dx} [H_1(x)] + \frac{d}{dx} [H_2(y(x))] &= 0 \\ \frac{d}{dx} [H_1(x) + H_2(y)] &= 0 \\ H_1(x) + H_2(y) &= c \\ \int M(x) \frac{d}{dx} + \int N(y) dy &= c \\ F(x, y) &= c \end{aligned}$$

■

Example 1.3.4 Given the equation $y' = \frac{x^2}{1 - y^2}$. Classify the differential equation and find the general solution.

Solution 2.

It is a first order, non-linear ODE. Since $y' = \frac{x^2}{1 - y^2}$, so we have $1 - y^2 \neq 0$. That is,

$y^2 \neq 1$, or $y \neq \pm 1$. Using the separation of variables (SoV), we have

$$\begin{aligned}(1 - y^2)y' &= x^2 \\ \int (1 - y^2) dy &= \int x^2 dx \\ y - \frac{1}{3}y^3 &= \frac{1}{3}x^3 + c \\ y - \frac{1}{3}y^3 - \frac{1}{3}x^3 &= c \\ 3y - y^3 - x^3 &= c\end{aligned}$$

□

Example 1.3.5 Given the equation $y' = \frac{(y-3)\cos x}{1+2y^2}$. Classify the equation and find the general solution.

Solution 3.

It is a first order, non-linear ODE. Since $1 + 2y^2 \neq 0 \quad \forall y \in \mathbb{R}$. Note that if we take $y - 3 = 0$, we get $y = 3$, a constant solution to the differential equation. Now, assume $y \neq 3$. Then, use SoV:

$$\int \frac{1+2y^2}{y-3} dy = \int \cos x dx + c = \sin x + c.$$

Set $t = y - 3$, $dt = dy$. So, $y = t + 3$ and $y^2 = (t + 3)^2$. Then,

$$\begin{aligned}\int \frac{1+2y^2}{y-3} dy &= \int \frac{1+2(t+3)^2}{t} dt = \int \frac{1+2t^2+12t+18}{t} dt \\ &= \int \frac{19}{t} + 12 + 2t dt \\ &= 19 \ln |t| + 12t + t^2 \\ &= 19 \ln |y-3| + 12(y-3) + (y-3)^2 \\ &= 19 \ln |y-3| + 6y + y^2 - 27.\end{aligned}$$

So,

$$19 \ln |y-3| + y^2 + 6y - 27 - \sin x = c$$

□

Example 1.3.6 Give the equation $y' = \frac{1}{2}x(1-y^2)$. Classify the equation and find the general solution.

Solution 4.

It is a first order, non-linear ODE. Notice that we have the constant solutions when

we take $1 - y^2 = 0$, or $y = \pm 1$. Now, assume $y \neq \pm 1$. Using SoV:

$$\int \frac{2}{1 - y^2} dy = \int x dx + c = \frac{1}{2}x^2 + c.$$

Note that $\frac{2}{1 - y^2} = \frac{2}{(1 - y)(1 + y)}$. Use partial fractions. Assume

$$\frac{2}{(1 - y)(1 + y)} = \frac{A}{1 - y} + \frac{B}{1 + y}.$$

Then, we get $A(1 + y) + B(1 - y) = 2$. That is, $(A + B) + (A - B)y = 2$. Attempting to solve the system of equations $\begin{cases} A - B = 0 \\ A + B = 2 \end{cases}$, then we get $A = B = 1$. Therefore,

$$\frac{2}{1 - y^2} = \frac{1}{1 - y} + \frac{1}{1 + y}.$$

Then,

$$\begin{aligned} \int \frac{1}{1 - y} + \frac{1}{1 + y} dy &= \frac{1}{2}x^2 + c \\ -\ln |1 - y| + \ln |1 + y| &= \frac{1}{2}x^2 + c \\ \ln |1 - y| - \ln |1 + y| &= -\frac{1}{2}x^2 + c \\ \ln \left| \frac{1 - y}{1 + y} \right| &= -\frac{1}{2}x^2 + c \\ \left| \frac{y - 1}{y + 1} \right| &= e^{-\frac{1}{2}x^2 + c} = e^{-\frac{1}{2}x^2} e^c \\ \frac{y - 1}{y + 1} &= c_2 e^{-\frac{1}{2}x^2} \\ y - 1 &= (y + 1)c_2 e^{-\frac{1}{2}x^2} \\ (1 - c_2 e^{-\frac{1}{2}x^2})y &= 1 + c_2 e^{-\frac{1}{2}x^2} \\ y &= \frac{1 + c_2 e^{-\frac{1}{2}x^2}}{1 - c_2 e^{-\frac{1}{2}x^2}} \end{aligned}$$

The value of c_2 is chosen according to the sign of $\frac{y - 1}{y + 1}$. □

Example 1.3.7 Given the equation $y' = \frac{3x^2 + 4x + 2}{2(y - 1)}$, with $y(0) = 1$. Classify the equation, find the general solution, and solve the IVP.

Solution 5.

It is a first order, nonlinear, separable ODE. Note that $y - 1 \neq 0$, so $y \neq 1$. Assume

$y \neq 1$, use SoV:

$$\int 2(y-1) dy = \int 3x^2 + 4x + 2 dx + c$$

$$(y-1)^2 = x^3 + 2x^2 + 2x + c$$

$$y^2 - 2y + 1 = x^3 + 2x^2 + 2x + c$$

$$y^2 - 2y = x^3 + 2x^2 + 2x + c.$$

Substitute $y = -1$ when $x = 0$:

$$1 + 2 = c \implies c = 3.$$

So,

$$y^2 - 2y = x^3 + 2x^2 + 2x + 3, \quad y \neq 1$$

$$y^2 - 2y + 1 = x^3 + 2x^2 + 2x + 4$$

$$(y-1)^2 = x^3 + 2x^2 + 2x + 4$$

$$y-1 = \pm \sqrt{x^3 + 2x^2 + 2x + 4}$$

$$y = 1 \pm \sqrt{x^3 + 2x^2 + 2x + 4}.$$

If $y = -1$ and $x = 0$: $-1 = 1 \pm \sqrt{4} = 1 \pm 2$. So, it must be that $-1 = 1 - 2$. So,

$$y^{\text{IVP}} = 1 - \sqrt{x^3 + 2x^2 + 2x + 4}.$$

Note that now we have another condition for x :

$$x^3 + 2x^2 + 2x + 4 \geq 0$$

$$(x+2)(x^2+2) \geq 0$$

$$x+2 \geq 0$$

$$x \geq -2$$

So,

$$y^{\text{IVP}} = 1 - \sqrt{x^3 + 2x^2 + 2x + 4}, \text{ with } y \neq 1 \text{ and } x \geq -2.$$

□

Example 1.3.8 Solve the IVP $\begin{cases} y' = \sqrt[3]{y} = y^{\frac{1}{3}} \\ y(0) = 0 \end{cases}$.

Solution 6.

It is a first order, nonlinear, separable ODE. The initial interval of validity: $x \in \mathbb{R}$ and

$y \in \mathbb{R}$. Note that if $y = 0$, there is a constant solution. Assume $y \neq 0$, use SoV:

$$\begin{aligned}\int y^{-\frac{1}{3}} dy &= \int dx + c \\ \frac{3}{2} y^{\frac{2}{3}} &= x + c \\ y^{\frac{2}{3}} &= \frac{2}{3} x + c \\ y &= \pm \left(\frac{2}{3} x + c \right)^{\frac{3}{2}}\end{aligned}$$

Substitute $y(0) = 0$:

$$0 = 0 + c \implies c = 0.$$

So,

$$y^{\text{IVP}} = \pm \left(\frac{2}{3} x \right)^{\frac{3}{2}}.$$

□

Theorem 1.3.9 Existence and Uniqueness of Solutions to Nonlinear ODEs

Consider the IVP

$$y' = f(x, y(x)) \quad \text{with } y(x_0) = y_0.$$

- If f is continuous on an open rectangle $R\{a < x < b, c < y < d\}$ that contains (x_0, y_0) , then the IVP has *at least* one solution on some open subinterval of (a, b) that contains x_0 .
- If both f and $\frac{\partial f}{\partial y}$ are continuous on R , then the IVP has a *unique* solution on some open subinterval of (a, b) that contains x_0 .

Example 1.3.10 In the IVP above (Example 1.3.8), $f(x, y) = y^{\frac{1}{3}}$, and so $\frac{\partial f}{\partial y} = \frac{1}{3} y^{-\frac{2}{3}}$, which is not continuous at $y = 0$. So, the IVP \nexists a unique solution on the interval given: $R = \{x \in \mathbb{R}, y \in \mathbb{R}\}$.

1.4 Exact Equations

Theorem 1.4.1 Multivariable Chain Rule

Given $F(x, y) = c$, where $y = y(x)$. Then, the total derivative with respect to x is

$$\frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \frac{dy}{dx} = 0.$$

Example 1.4.2 Exact ODEs

$$M(x, y) dx + N(x, y) dy = 0$$

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad \text{if } y = y(x)$$

$$M(x, y) \frac{dx}{dy} + N(x, y) = 0 \quad \text{if } x = x(y).$$

Example 1.4.3 Show that $x^4y^3 + x^2y^5 + 2xy = c$ is an implicit solution of

$$(4x^3y^3 + 2xy^5 + 2y) dx + (3x^4y^2 + 5x^2y^4 + 2x) dy = 0.$$

Solution 1.

$$\frac{\partial F}{\partial x} = 4x^3y^3 + 2xy^5 + 2y; \quad \frac{\partial F}{\partial y} = 3x^4y^2 + 5x^2y^4 + 2x$$

If $y = y(x)$:

$$(4x^3y^3 + 2xy^5 + 2y) + (3x^4y^2 + 5x^2y^4 + 2x) \frac{dy}{dx} = 0.$$

If $x = x(y)$:

$$(4x^3y^3 + 2xy^5 + 2y) \frac{dx}{dy} + (3x^4y^2 + 5x^2y^4 + 2x) = 0.$$

So the implicit function is a solution to the differential equation. □

Theorem 1.4.4

Given an implicit function $F(x, y) = c$. It is a solution to the differential equation if

$$F_x dx + F_y dy = 0.$$

Definition 1.4.5 (Exact ODEs). We say that an ODE of the form $M(x, y) dx + N(x, y) dy = 0$ is *exact* if $\exists F(x, y) = c$, with F_x and F_y continuous, such that

$$M(x, y) = F_x(x, y) \quad \text{and} \quad N(x, y) = F_y(x, y).$$

Theorem 1.4.6 Characterization of Exact ODEs

Suppose that M and N are continuous on R and have continuous partial derivatives M_y, N_x on R . Then,

$$M(x, y) dx + N(x, y) dy = 0$$

is exact if and only if

$$M_y(x, y) = N_x(x, y)$$

on R .

Example 1.4.7 Show this ODE is exact:

$$(4x^3y^3 + 2xy^5 + 2y) dx + (3x^4y^2 + 5x^2y^4 + 2x) dy = 0.$$

Solution 2.

$$M(x, y) = 4x^3y^3 + 2xy^5 + 2y; \quad M_y(x, y) = 12x^3y^2 + 10xy^4 + 2$$

$$N(x, y) = 3x^4y^2 + 5x^2y^4 + 2x; \quad N_x(x, y) = 12x^3y^2 + 10xy^4 + 2$$

Since $M_y(x, y) = N_x(x, y)$, it is exact. □

Example 1.4.8 Find the general solution of

$$(4x^3y^3 + 3x^2) dx + (3x^4y^2 + 6y^2) dy = 0$$

Solution 3.

Note that $M(x, y) = 4x^3y^3 + 3x^2$ and $N(x, y) = 3x^4y^2 + 6y^2$, so

$$M_y(x, y) = 12x^3y^2; \quad N_x(x, y) = 12x^3y^2.$$

Since $M_y(x, y) = N_x(x, y)$, the ODE is exact. Then,

$$\begin{aligned} F(x, y) &= \int M(x, y) dx + \varphi(y) \\ &= \int (4x^3y^3 + 3x^2) dx + \varphi(y) \\ &= x^4y^4 + x^3 + \varphi(y). \end{aligned}$$

Since $F_y(x, y) = 3x^4y^2 + \varphi'(y) = 3x^4y^2 + 6y^2$, we have $\varphi'(y) = 6y^2$. That is,

$$\varphi(y) = \int 6y^2 dy + c = 2y^3 + c.$$

So, $F(x, y) = x^4 y^3 + x^3 + 2y^3 + c$. Then, the implicit solution is

$$x^4 y^3 + x^3 + 2y^3 = c.$$

Alternatively, we can use $F(x, y) = \int N(x, y) dy + \psi(x)$ to get the same result. \square

Theorem 1.4.9 Method of Integrating Factors for Exact ODEs

Given $M(x, y) dx + N(x, y) dy = 0$ is not exact. Consider $\mu = \mu(x, y) \neq 0$. Multiply

$$\mu(x) = e^{\int \frac{M_y - N_x}{N} dx} \quad \text{or} \quad \mu(y) = e^{\int \frac{N_x - M_y}{M} dy},$$

we could make the ODE exact and thus solvable.

Proof 4. Given $M(x, y) dx + N(x, y) dy = 0$ is not exact. Consider $\mu = \mu(x, y) \neq 0$. Multiply both sides by μ :

$$\mu M(x, y) dx + \mu N(x, y) dy = 0 \quad (3)$$

Then, we have

$$\widetilde{M}(x, y) = \mu M; \quad \text{and} \quad \widetilde{N}(x, y) = \mu N.$$

Thus, the condition for Eq. (3) to be exact is $\widetilde{M}_y = \widetilde{N}_x$, or $(\mu M)_y = (\mu N)_x$. By product rule,

$$\mu_y M + \mu M_y = \mu_x N + \mu N_x \quad (4)$$

Remark. Eq. (4) is a PDE, which we cannot solve. So, make the assumption that μ is a function of only x or only y .

- If $\mu = \mu(x)$, then $\mu_y = 0$. So, we have

$$\begin{aligned} \mu M_y &= \mu_x N + \mu N_x \\ N\mu_x + (N_x - M_y)\mu &= 0 \\ \mu(x) &= e^{\int \frac{M_y - N_x}{N} dx}. \end{aligned}$$

If $\mu = \mu(y)$, then $\mu_x = 0$. So, we have

$$\begin{aligned} \mu_y M + \mu M_y &= \mu N_x \\ M\mu_y + (M_y - N_x)\mu &= 0 \\ \mu(y) &= e^{\int \frac{N_x - M_y}{M} dy}. \end{aligned}$$

■

Remark. To decide on if we should use $\mu(x)$ or $\mu(y)$, test if $\frac{M_y - N_x}{N}$ is a function of x only and if $\frac{N_x - M_y}{M}$ is a function of y only.

Example 1.4.10 Given the equation $(3x + 2y^2) dx + 2xy dy = 0$. Find the integrating factor and solve the ODE.

Solution 5.

Note that $M(x, y) = 3x + 2y^2$ and $N(x, y) = 2xy$. So, $M_y = 4y$ and $N_x = 2y$. So, the ODE is not exact, and we should find an integrating factor. It is easier to divide by N since there is only 1 term:

$$\frac{M_y - N_x}{N} = \frac{4y - 2y}{2xy} = \frac{1}{x},$$

is a function of x only. So, by the Method of Integrating Factors, we know

$$\mu(x) = e^{\int \frac{1}{x} dx} = e^{\ln x} = x \quad (x \neq 0).$$

Now, multiply both sides of the original ODE by x :

$$(3x^2 + 2xy^2) dx + 2x^2y dy = 0,$$

where $\tilde{M}(x, y) = 3x^2 + 2xy^2$ and $\tilde{N}(x, y) = 2x^2y$. So,

$$\begin{aligned} F(x, y) &= \int \tilde{N}(x, y) dy + \psi(x) \\ &= \int 2x^2y dy + \psi(x) \\ &= x^2y^2 + \psi(x) \end{aligned}$$

Compute the partial derivative of F with respect to x , we get

$$\begin{aligned} \frac{\partial F(x, y)}{\partial x} &= 2xy^2 + \psi'(x) = 3x^2 + 2xy^2 \\ \psi'(x) &= 3x^2 \\ \psi(x) &= \int 3x^2 dx + c = x^3 + c \end{aligned}$$

So, the solution is

$$x^2y^2 + x^3 = c.$$

□

Example 1.4.11 Solve the equation $(2xy^3 - 2x^3y^3 - 4xy^2 + 2x) dx + (3x^2y^2 + 4y) dy = 0$.

Solution 6.

- Test if the equation is exact:

$$M(x, y) = 2xy^3 - 2x^3y^3 - 4xy^2 + 2x; \quad M_y = 6xy^2 - 6x^3y^2 - 8xy$$

$$N(x, y) = 3x^2y^2 + 4y; \quad N_x = 6xy^2$$

Since $M_y \neq N_x$, the equation is not exact.

- Find an integrating factor. Try:

$$\frac{M_y - N_x}{N} = \frac{6xy^2 - 6x^3y^2 - 8xy - 6xy^2}{3x^2y^2 + 4y} = \frac{-2x(3x^2y^2 + 4y)}{3x^2y^2 + 4y} = -2x,$$

which is a function of x only. So, the integrating factor $\mu = \mu(x) \neq 0$ is

$$\mu = e^{\int -2x \, dx} = e^{-x^2}.$$

- Multiply the equation by μ :

$$e^{-x^2}(2xy^3 - 2x^3y^3 - 4xy^2 + 2x) \, dx + e^{-x^2}(3x^2y^2 + 4y) \, dy = 0.$$

We can easily show that the equation is exact.

$$\begin{aligned} F(x, y) &= \int e^{-x^2}(3x^2y^2 + 4y) \, dy + \psi(x) \\ &= e^{-x^2}(x^2y^3 + 2y^2) + \psi(x). \end{aligned}$$

So,

$$\begin{aligned} F_x(x, y) &= -(2x)e^{-x^2}(x^2y^3 + 2y^2) + e^{-x^2}(2xy^3) + \psi'(x) \\ &= e^{-x^2}(2xy^3 - 2x^3y^3 - 4xy^2) + \psi'(x). \end{aligned}$$

Note that

$$\begin{aligned} e^{-x^2}(2xy^3 - 2x^3y^3 - 4xy^2) + \psi'(x) &= e^{-x^2}(2xy^3 - 2x^3y^3 - 4xy^2 + 2x) \\ \psi'(x) &= e^{-x^2}(2x) \\ \psi(x) &= \int (2x)e^{-x^2} \, dx + c = -e^{-x^2} + c. \end{aligned}$$

- So, the solution is

$$e^{-x^2}(x^2y^3 + 2y^2 - 1) = c.$$

□

1.5 Autonomous ODEs

Definition 1.5.1 (Autonomous ODEs). ODEs in the form $y' = f(y)$ is called *autonomous ODEs*. In other words, the dependent variable x does not appear explicitly in the equation.

Remark. *Autonomous ODEs are separable.*

Example 1.5.2 Exponential Growth

Let $y = \varphi(t)$ be the population of the given species at time t . Assume that the rate of change of the population is proportional to the current value of y , and the constant of proportionality is given by r , called the rate of growth ($r > 0$) or decline ($r < 0$).

A differential equation to model this situation is given by

$$\begin{cases} y' = ry \\ y(0) = y_0 \end{cases}$$

and the solution is

$$y = y_0 e^{rt}.$$

Example 1.5.3 Logistic Growth

The *logistic growth* is modeled by the differential equation

$$y' = r \left(1 - \frac{y}{K} \right) y,$$

where $r > 0$ represents the intrinsic growth rate in absence of limiting factors, and $K > 0$ is the environmental carrying capacity.

In this system, we have $y = 0$ and $y = K$ as the constant solutions/equilibria/critical points of the ODE. $y = 0$ is the *unstable equilibrium solution*, and $y = K$ is the *asymptotic stable solution*.

This model shows that when $0 < y < K$, the population will grow until K (that is, $\lim_{t \rightarrow \infty} y = K$) and when $y > K$, the population will decrease to K ($\lim_{t \rightarrow \infty} y = K$).

We can model the logistic growth using the following ODE as well

$$y' = -r \left(1 - \frac{y}{T} \right) y,$$

where r represents the intrinsic growth rate in absence of limiting factors and T is the threshold level.

In this system, we have $y = 0$ and $y = T$ as the equilibrium solutions, $y = T$ is the unstable solution and $y = 0$ is the asymptotic stable solution. That is, when $0 < y < T$, the population will decrease to 0 ($\lim_{t \rightarrow \infty} y = 0$) and when $y > T$, the population will grow forever ($\lim_{t \rightarrow \infty} y = \infty$).

A solution to the IVP

$$y' = -r\left(1 - \frac{y}{T}\right)y; \quad y(0) = y_0$$

is $y = \frac{y_0 T}{y_0 + (T - y_0)e^{rt}}$.

The solution also have a vertical asymptote $t = t^*$ such that $y \rightarrow \infty$. To find such an asymptote, we want $\lim_{t \rightarrow t^*} y^{\text{IVP}} = 0$. So, we set the denominator to 0, i.e., $y_0 + (T - y_0)e^{rt} = 0$, and we get $t = \frac{1}{r} \ln \left(\frac{y_0}{y_0 - T} \right)$ with $y_0 > T$ by solving the equation.

Combining the two models, we give a more accurate model of the population. We call it *Logistic Growth with a Threshold*.

$$y' = -r\left(1 - \frac{y}{T}\right)\left(1 - \frac{y}{K}\right),$$

where $r > 0$ is the intrinsic growth rate in the absence of limiting factors and $0 < T < K$, where T is the threshold level and K is the environmental carrying capacity.

In this system, $y = K$ and $y = 0$ are asymptotic stable solutions and $y = T$ is the unstable equilibrium solution. Given the IVP

$$y' = -r\left(1 - \frac{y}{T}\right)\left(1 - \frac{y}{K}\right); \quad y(0) = y_0.$$

The behavior of the IVP solution with respect to y_0 is given as the following:

- If $0 < y_0 < T$, then $y(t) \rightarrow 0$ as $t \rightarrow \infty$.
- If $y_0 = T$, then $y(t) = T$ for all t .
- If $T < y_0 < K$, then $y(t) \rightarrow K$ as $t \rightarrow \infty$.
- If $y_0 = K$, then $y(t) = K$ for all t .
- If $y_0 > K$, then $y(t) \rightarrow K$ as $t \rightarrow \infty$.

Example 1.5.4 Newton's Law of Cooling

Newton's law of cooling states that the rate of change of the temperature of an object is proportional to the difference between its own temperature and the ambient temperature (i.e., the temperature of its surroundings). This law is summarized using the following ODE

$$T' = -k(T - T_a),$$

where T represents the temperature of an object, T_a is the ambient temperature of the surrounding environment, and $k > 0$ is the cooling constant.

The equilibrium solution $T = T_a$ is asymptotic stable. Using either integrating factor or SoV, we find the general solution as $T = Ae^{-kt} + T_a$.

2 Second Order ODEs

2.1 Linear Algebra

Definition 2.1.1 (System of Linear Ordinary Differential Equations). A system of ODEs is in general given by

$$\begin{cases} y'_1 = f_1(t, y_1, y_2, \dots, y_n) \\ y'_2 = f_2(t, y_1, y_2, \dots, y_n) \\ \vdots \\ y'_n = f_n(t, y_1, y_2, \dots, y_n). \end{cases}$$

A system of ODEs is called *linear* if it can be written in the following form

$$y' = \mathbf{A}(t)y + f(t),$$

where

$$\mathbf{A}(t) = \begin{bmatrix} a_{11}(t) & a_{12}(t) & \cdots & a_{1n}(t) \\ a_{21}(t) & a_{22}(t) & \cdots & a_{2n}(t) \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1}(t) & a_{n2}(t) & \cdots & a_{nn}(t) \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}, \quad f(t) = \begin{bmatrix} f_1(t) \\ f_2(t) \\ \vdots \\ f_n(t) \end{bmatrix}.$$

The system can be

- *Homogeneous*, if $f(t) = \vec{0}$
- *Non-homogeneous*, if $f(t) \neq \vec{0}$

Definition 2.1.2 (Matrix Equality). Suppose \mathbf{A} and \mathbf{B} are matrices of the same size. We say $\mathbf{A} = \mathbf{B}$ if $A_{ij} = B_{ij}$ for all i and j . In other words, $\mathbf{A} = \mathbf{B}$ if they are equal componentwise.

Definition 2.1.3 (Null Matrix/Zero). The symbol $\mathbf{0}$ will be used to denote the matrix (or vector) each of whose elements is zero.

Definition 2.1.4 (Transpose). \mathbf{A}^T is the *transpose* of \mathbf{A} and it is obtained by interchanging the rows and columns of \mathbf{A} . If $\mathbf{A} = [A_{ij}]$, then $\mathbf{A}^T = [A_{ji}]$.

Definition 2.1.5 (Matrix Addition). Suppose \mathbf{A} and \mathbf{B} are matrices of the same size. Then, $\mathbf{A} + \mathbf{B} = [a_{ij} + b_{ij}]$ for all i and j .

Definition 2.1.6 (Product of a Matrix and a Scalar). Suppose $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $c \in \mathbb{R}$, then $c\mathbf{A} = [ca_{ij}]$.

Definition 2.1.7 (Dot Product/Scalar Product). Suppose $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^{2 \times 1}$ and $\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \in \mathbb{R}^{2 \times 1}$. Then, the *dot product* of \mathbf{x} and \mathbf{y} is defined to be

$$\mathbf{x} \cdot \mathbf{y} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \mathbf{x}^T \mathbf{y} = x_1 y_1 + x_2 y_2.$$

Definition 2.1.8 (Matrix Product). Suppose $\tilde{\mathbf{A}} \in \mathbb{R}^{m \times n}$ and $\tilde{\mathbf{B}} \in \mathbb{R}^{n \times p}$. Then, each c_{ij} of

$\tilde{\mathbf{C}} \in \mathbb{R}^{m \times p}$ such that $\tilde{\mathbf{C}} = \tilde{\mathbf{A}}\tilde{\mathbf{B}}$ is the dot product between row i of \mathbf{A} and column j of \mathbf{B} . That is,

$$c_{ij} = \sum_{k=1}^n a_{ik}b_{kj}.$$

Definition 2.1.9 (Identity Matrix). The $n \times n$ multiplicative identity is the *identity matrix*

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}.$$

From the definition of matrix multiplication, we have $\mathbf{AI} = \mathbf{IA} = \mathbf{A}$.

Definition 2.1.10 (Determinant). Given a matrix \mathbf{A} , we can always find the *determinant* of \mathbf{A} , which is a number associated to \mathbf{A} , denoted as $\det(\mathbf{A})$ or $|\mathbf{A}|$. Suppose $\mathbf{A} \in \mathbb{R}^{2 \times 2}$, then

$$\det(\mathbf{A}) = \det \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11}a_{22} - a_{12}a_{21}.$$

Definition 2.1.11 (Inverse). For $\mathbf{A} \in \mathbb{R}^{n \times n}$, if \mathbf{A} is invertible, then $\exists \mathbf{B} \in \mathbb{R}^{n \times m}$ such that $\mathbf{AB} = \mathbf{I}$. We denote \mathbf{B} as \mathbf{A}^{-1} , the *inverse* of \mathbf{A} .

Theorem 2.1.12 Determinant and Invertibility

If $\det(\mathbf{A}) \neq 0$, then the matrix \mathbf{A} is nonsingular and invertible. Conversely, if $\det(\mathbf{A}) = 0$, then the matrix is singular and not invertible.

If $\det(\mathbf{A}) \neq 0$, then the inverse is given by

$$\mathbf{A}^{-1} = \frac{1}{\det(\mathbf{A})} \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}.$$

Theorem 2.1.13 Determinants are Multiplicable

$$\det(\mathbf{AB}) = \det(\mathbf{BA}) = \det(\mathbf{A}) \det(\mathbf{B}).$$

Definition 2.1.14 (Linear Systems of Algebraic Equations). Given an $n \times n$ matrix \mathbf{A} , an $n \times 1$ vector b , and a vector of unknowns x , $\mathbf{Ax} = b$ is called *linear system of equations*. If $b = 0$, the system is called *homogeneous*. If $b \neq 0$, then the linear system is called *non-homogeneous*.

Theorem 2.1.15 Singularity of Systems

If the system is homogeneous, it is nonsingular if it exists a unique solution (which is the null vector); it is singular if it has infinitely many solutions.

If the system is non-homogeneous, then it is nonsingular if it has a unique solution ($x = \mathbf{A}^{-1}b$), and it is singular if it has either infinitely many solutions or no solutions.

Definition 2.1.16 (Eigenvector, Eigenvalue, Eigenpairs). Suppose that A is an $n \times n$ matrix. A nonzero vector v that satisfies the equation

$$Av = \lambda v$$

is called an *eigenvector* of matrix A . The scalar λ is the *eigenvalue* associated with this eigenvector. An *eigenpair* is the pair $\{\lambda_i, v_i\}$ with $i = 1, \dots, n$.

Theorem 2.1.17 Finding Eigenpairs

To find an eigenpair $\{\lambda_i, v_i\}$ with $i = 1, \dots, n$, we need to find the roots of the characteristics polynomial of A . That is, we need to solve the problem

$$\det(A - \lambda I) = 0.$$

Once we have the eigenvalues, we need to solve the linear systems

$$(A - \lambda_i I)v_i = 0 \quad \text{with } i = 1, \dots, n.$$

Proof 1.

$$\begin{aligned} Av = \lambda v &\implies Av - \lambda v = 0 \\ (A - \lambda I)v &= 0 \end{aligned}$$

To solve this homogeneous linear system, we cannot have $v = 0$ since v is defined to be nonzero. Therefore, the system has infinite many solutions. That is, $A - \lambda I$ is singular, or $\det(A - \lambda I) = 0$. ■

Remark. The matrix $A - \lambda I$ is singular, meaning the system has infinitely many solutions. Finding the eigenvector consists of identifying a direction (invariant under the action of A) and choose a representative of it.

Definition 2.1.18 (Similar Matrices). Two $n \times n$ matrices A and B are *similar* if there exists an invertible matrix T such that

$$B = T^{-1}AT \quad \text{and} \quad A = TBT^{-1}.$$

Definition 2.1.19 (Diagonalizable Matrix). A matrix A is said to be *diagonalizable* if it is similar to a diagonal matrix D . In this case, the entries of the diagonal matrix D are the eigenvalues of A .

Theorem 2.1.20 Characterization of Diagonalizability

A matrix is diagonalizable if and only if it has n linearly independent eigenvectors.

Proof 2. Consider the eigenpairs $\{\lambda_i, v_i\}$ with $i = 1, \dots, n$ of an $n \times n$ matrix A . Let V be

the matrix of the n linearly independent eigenvectors, namely $\mathbf{V} = \begin{bmatrix} v_1 & v_2 & \dots & v_n \end{bmatrix}$, then

$$\mathbf{D} = \mathbf{V}^{-1}\mathbf{A}\mathbf{V}.$$

■

3 System of ODEs