### Operating systems and concurrency B05

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#### Introduction

- Multi-tasking program from previous lecture is very simple:
  - No need for communication between tasks
  - No shared resources
  - No need for synchronisation
- Most multi-tasking programs are not so simple:
  - Communication: shared variables; message-passing
  - Shared resources: interference or race conditions
  - Synchronisation: critical sections; mutual exclusion

### Multi-tasking program with sharing

- Let's look at a slightly more (artificially) complicated version of the example from last week (main.c)
- Notice there is a boolean variable flashing that is initially false and must become true in order for the lights to start flashing
- There are 3 shared uint32\_t variables: total, count1 and count2
- There are 2 new tasks: appTaskCount1 and appTaskCount2
- The tasks increment their count variables and the total and check that count1 + count2 is equal to total: if not start flashing.

### appTaskCount1 behaviour

```
static void appTaskCount1(void *pdata) {
   while (true) {
      count1 += 1;
      display(1, count1);
      total += 1;
      if ((count1 + count2) != total) {
        flashing = true;
      }
      OSTimeDlyHMSM(0,0,0,20);
   }
}
```

 appTaskCount2 is similar: it increments and displays count2 (not count1)

#### **QUESTION**

# Will the lights start flashing?

### Working towards an answer

 Look at the crucial parts of appTaskCount1 and appTaskCount2

```
appTaskCount1

A.1 count1 += 1;

A.2 display(1, count1);

A.3 total += 1;

A.4 if ...

appTaskCount2

B.1 count2 += 1;

B.2 display(2, count2);

B.3 total += 1;

B.4 if ...
```

- What is the value of total at A.4 and B.4 in each case below (assume all values initially 0):
  - A.1, A.2, A.3, A4, B.1, B.2, B.3, B4

### Working towards an answer

 Look at the crucial parts of appTaskCount1 and appTaskCount2

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A.1 count1 += 1;

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A.4 if ...

appTaskCount2

B.1 count2 += 1;

B.2 display(2, count2);

B.3 total += 1;

B.4 if ...
```

- What is the value of total at A.4 and B.4 in each case below (assume all values initially 0):
  - A.1, A.2, A.3, A4, B.1, B.2, B.3, B4
  - B.1, B.2, A.1, A.2, A3, A4, B3, B4

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Answer: MAYBE

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- Question: Will the lights start flashing?
- Answer: MAYBE
- It depends on the scheduler and when tasks become ready to run.
- Can appTaskCount2 ever interfere with appTaskCount1?
  - No it's a lower priority task; appTaskCount1 never blocks in its critical section, so appTaskCount2 never has a chance to interfere with it.

### Interference - summary

- What is the problem?
  - Interference
  - One or more tasks is prevented from generating a correct result because of interference from another task
  - Sometimes known as a race condition
- Why is it caused?
  - Arbitrary interleaving of task instructions
  - created by the scheduler
- How can it be prevented?
  - Avoid shared variables, or
  - Enforce mutual exclusion of critical sections

#### How to enforce mutual exclusion of critical sections

- Memory interlock
- Mutual exclusion algorithms: Dekker, Peterson, Lamport
- Disable interrupts
  - OS\_ENTER\_CRITICAL(), OS\_EXIT\_CRITICAL()
  - Use with extreme caution preferably not at all.
- Semaphores
- Monitors

#### Mutual exclusion of critical sections

- A critical section is part of a program in which a shared resource is accessed: global variable, file, etc.
- Mutual exclusion is the requirement that no more than one process is executing its critical section at the same time
- An acceptable solution to the mutual exclusion problem requires several properties:
  - Mutual exclusion is enforced
  - No deadlock
  - No livelock (starvation)
  - No requirement for strict alternation (if other process doesn't need access to c.s. then a process should be able to enter its c.s. immediately)

#### Peterson's algorithm for mutual exclusion

- Difficult to get a correct solution to mutual exclusion problem
- Many incorrect attempts
  - Perhaps instructive to look at some of them later.
- Peterson proposed a correct algorithm (main.c)

```
static void appTaskCount1(void *pdata) {
  while (true) {
   need1 = true;
    turn = 2;
    while (need2 && (turn == 2)) {
      // OSTimeDlyHMSM(0,0,0,1);
    count1 += 1;
    display(1, count1);
    total += 1:
   need1 = false:
    if ((count1 + count2) != total) {
      flashing = true;
   OSTimeDlyHMSM(0,0,0,20);
```

```
static void appTaskCount1(void *pdata) {
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```

#### **ENTRY PROTOCOL**

```
static void appTaskCount1(void *pdata) {
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   need1 = true;
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    count1 += 1;
    display(1, count1);
    total += 1:
   need1 = false:
    if ((count1 + count2) != total) {
      flashing = true;
   OSTimeDlyHMSM(0,0,0,20);
```

#### **ENTRY PROTOCOL**

CRITICAL SECTION

```
static void appTaskCount1(void *pdata) {
 while (true) {
   need1 = true;
                                            ENTRY PROTOCOL
   turn = 2;
   while (need2 && (turn == 2)) {
      // OSTimeDlyHMSM(0.0.0.1);
                                            CRITICAL SECTION
   count1 += 1;
   display(1, count1);
    total += 1:
   need1 = false:
                                            EXIT PROTOCOL
    if ((count1 + count2) != total) {
      flashing = true;
   OSTimeDlyHMSM(0,0,0,20);
```

### A problem with Peterson's algorithm

## **BUSY WAITING**