

Portland State University
Electrical & Computer Engineering
ECE 311 Feedback & Control

-Homework #7-

Text Problems: **B-8-6**

Problem 1:

A linearized model of the relationship between a wind turbine's blade pitch and speed is given by the following plant transfer function:

$$G(s) = \frac{7200}{5s + 1}$$

Using the Matlab SISO tool, design a PI controller, $D(s)$, to control the speed of the turbine blades.

$$D(s) = K_p + \frac{K_I}{s} = K_p \left(\frac{s + \tau_c}{s} \right)$$

where $\tau_c = K_I/K_p$.

Design Specifications:

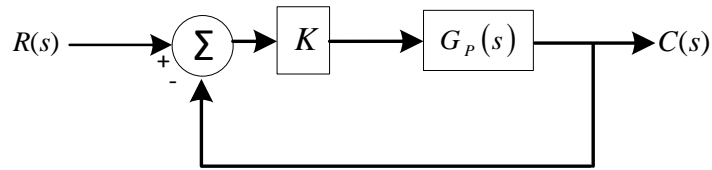
- Zero steady-state error to a step input
- $M_p < 25\%$ to a step input
- $t_s < 4$ seconds to a step input ($\pm 2\%$ criterion)
- $t_r < 1$ second to a step input (0.1 to 0.9 criterion)
- $t_p < 3$ seconds to a step input

Deliverables:

- (a) State the values of K_p, τ_c . NOTE: Every student should have unique answers.
There are many thousands of possible solutions
- (b) On an s -plane, plot overlay of the root loci and zone of allowable poles along with your designed closed-loop poles (this is shown in the SISO tool)
- (c) Show the step response
- (d) Note compliance with specs.

Problem 2:

For a system with plant $G_p(s)$ and $K = 1.64$, determine the gain crossover frequency, phase margin, plant Type i and the appropriate error coefficient, K_i .



$$G_p(s) = \frac{s+8}{(s+1)(s+2)(s+6)}$$

Fundamentals of Engineering Exam Problem 1 (Afternoon – 4 minutes) (Angus, et al):

A control system has a phase angle of -150° at the frequency where its open-loop gain is 0 dB. The phase margin is most nearly:

- (A) 180°
- (B) 30°
- (C) 20°
- (D) 10°

Fundamentals of Engineering Exam Problem 2 (Afternoon – 4 minutes) (Angus, et al):

A control system has a phase angle of -180° when its open-loop gain is -20 dB. The gain margin is most nearly:

- (A) 40 dB
- (B) 30 dB
- (C) 20 dB
- (D) 10 dB