

Problem 1)

Problem 1:

A linearized model of the relationship between a wind turbine's blade pitch and speed is given by the following plant transfer function:

$$G(s) = \frac{7200}{5s + 1}$$

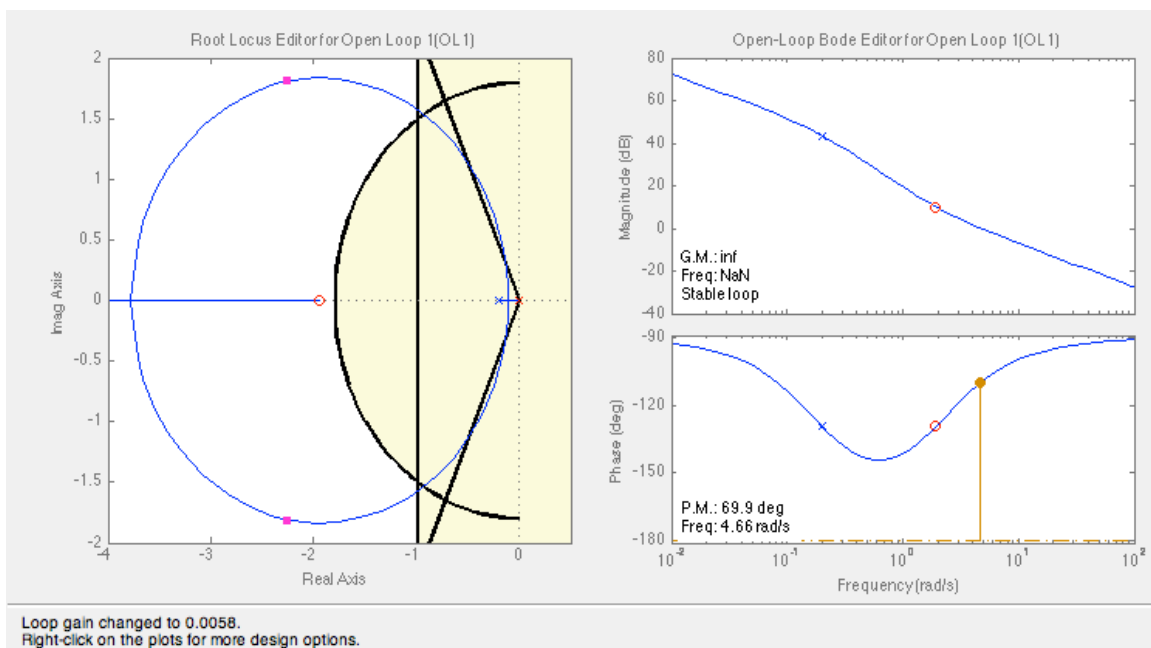
Using the Matlab SISO tool, design a PI controller, $D(s)$, to control the speed of the turbine blades.

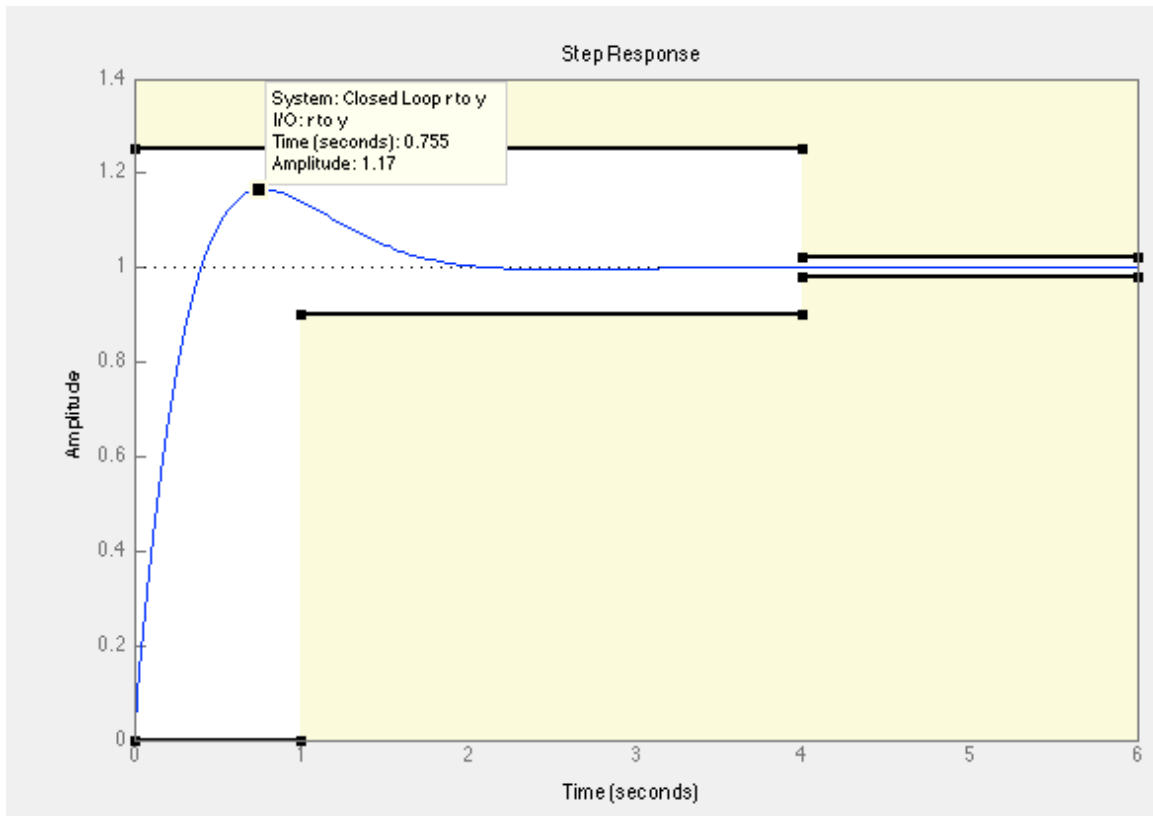
$$D(s) = K_P + \frac{K_I}{s} = K_P \left(\frac{s + \tau_C}{s} \right)$$

where $\tau_C = K_I/K_P$.

$$D(s) = .0058 \left(\frac{s + 1.94}{s} \right)$$

$$K_P = .0058, \tau_C = 1.94$$





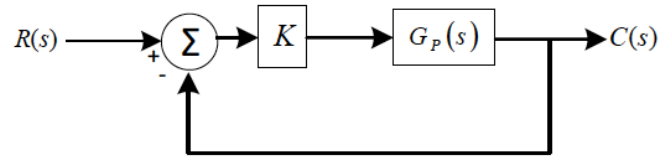
as can seen in the step plot above, the system meets all constraints

$M_p = 17\%$
 $t_p = 0.755$ seconds
 $t_r = 0.323$ seconds
 $t_s = 1.75$ seconds
 $ess = 0$

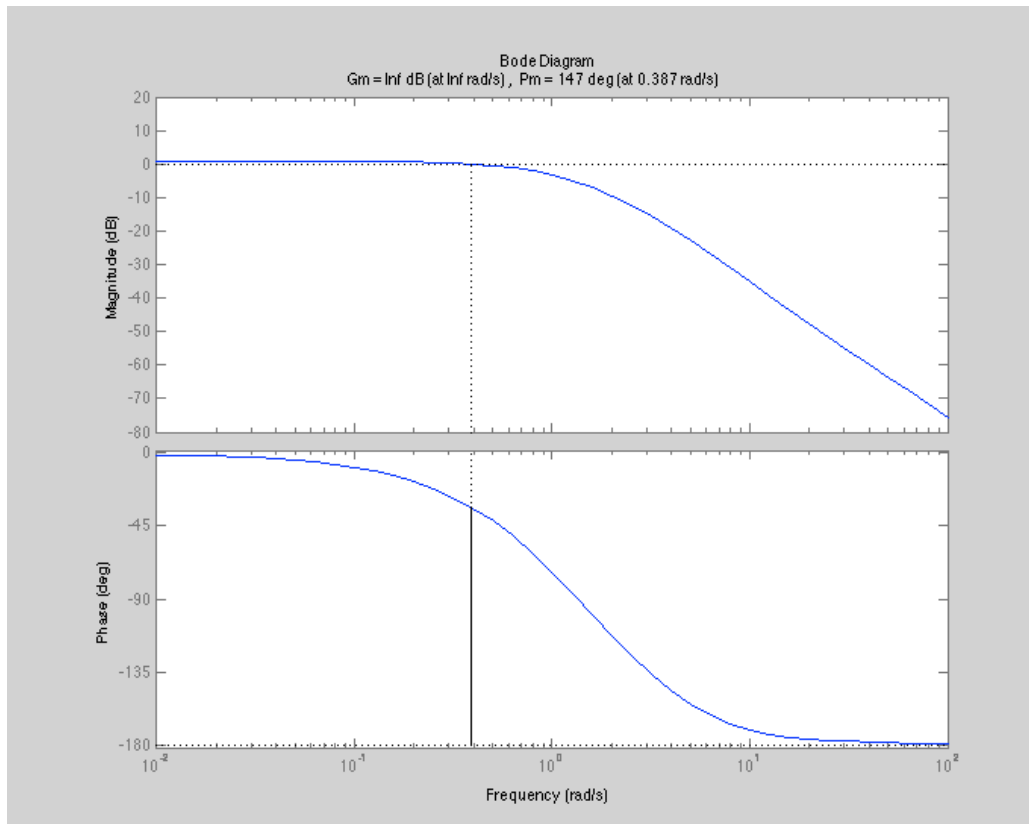
Problem 2)

Problem 2:

For a system with plant $G_p(s)$ and $K = 1.64$, determine the gain crossover frequency, phase margin, plant Type i and the appropriate error coefficient, K_i .



$$G_p(s) = \frac{s+8}{(s+1)(s+2)(s+6)}$$



Phase Margin = 147 degrees

Gain Crossover Frequency

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wc= getGainCrossover(sys,1)
wc=0.3874
  
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