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# Image Convolution

Introducción a métodos de Machine Learning para ciencias  
2023

# What is a digital image?

$$f : \mathbb{N}^d \rightarrow \mathbb{R}^B$$
$$m, n, \dots \mapsto f(m, n, \dots) = \{i_1, \dots, i_B\}.$$

- For example, a [grayscale image](#) corresponds to  $d = 2$  (the image has two dimensions) and  $B = 1$  (there is only one value per location  $(m, n)$ : the grayscale intensity).
- A common color image corresponds to  $d = 2$  and  $B = 3$  bands, typically red, green, and blue.
- An [MRI image](#) corresponds to  $d = 3$  (the image is three-dimensional) and  $B = 1$ .

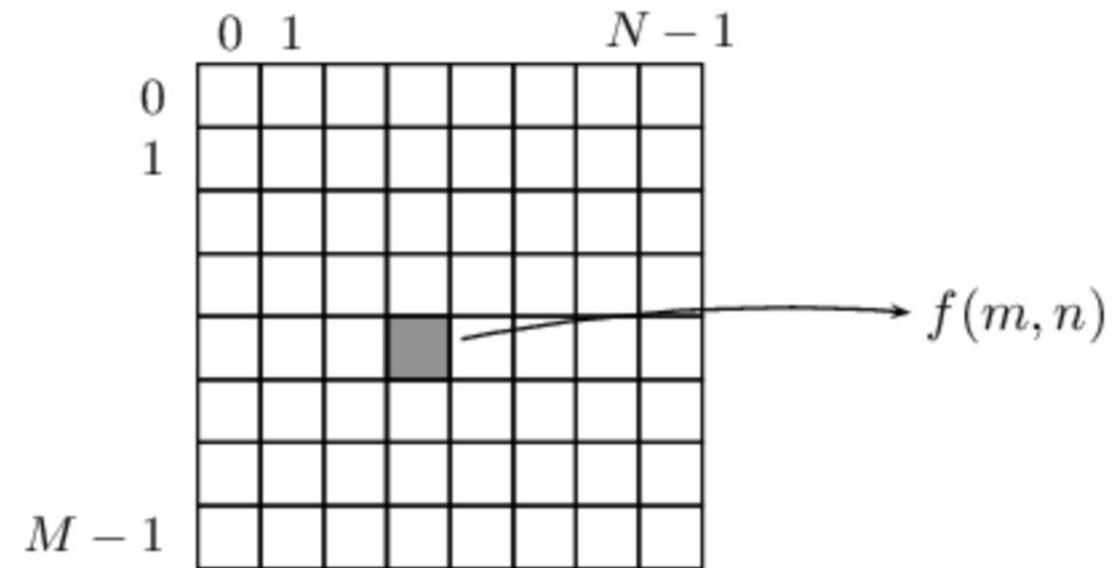
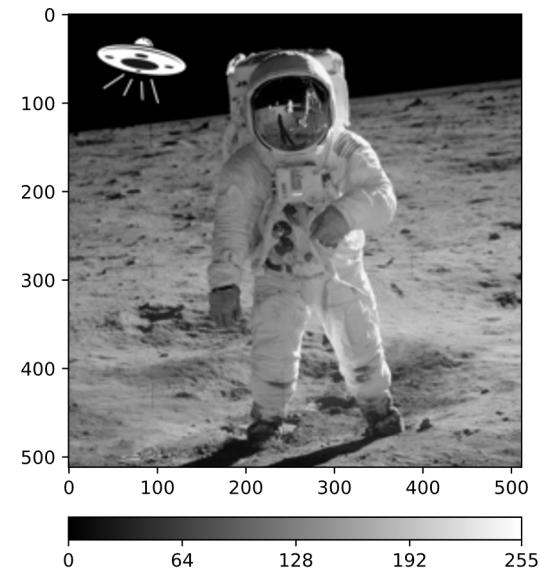
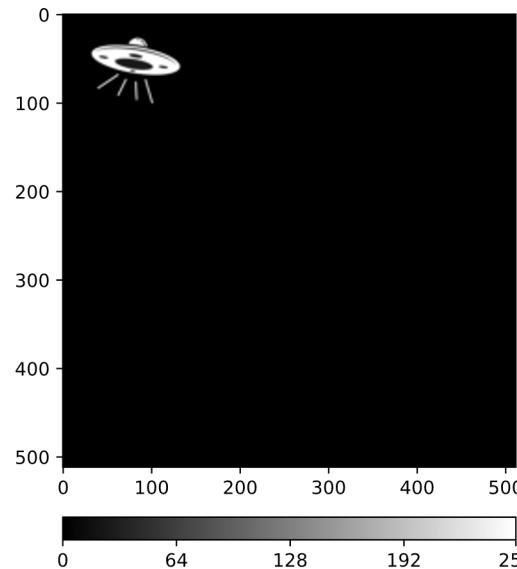
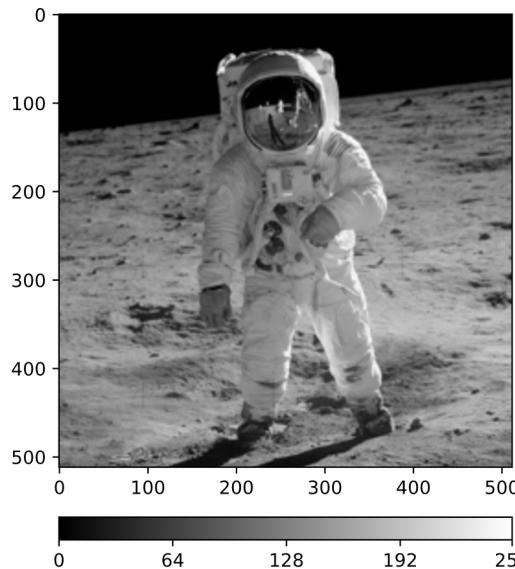


Fig. 1 Coordinate system generally used in image processing.

# Arithmetic operations of images

## Addition

$$\forall m, n, \quad h(m, n) = f(m, n) + g(m, n).$$



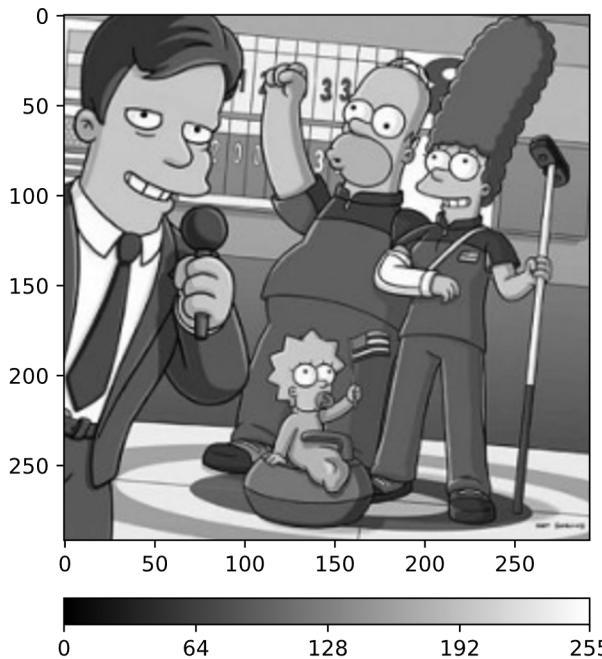
# Arithmetic operations of images

**substraction**

or

$$\forall m, n, \quad h(m, n) = f(m, n) - g(m, n)$$

$$\forall m, n, \quad h(m, n) = |f(m, n) - g(m, n)|$$



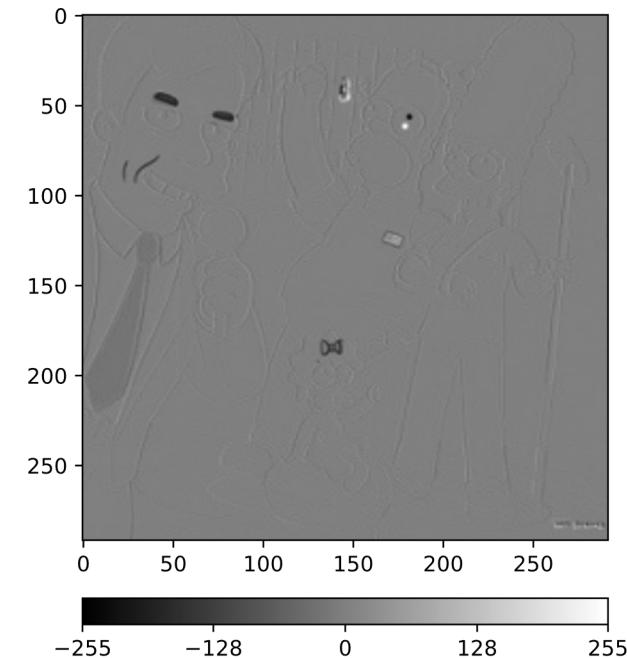
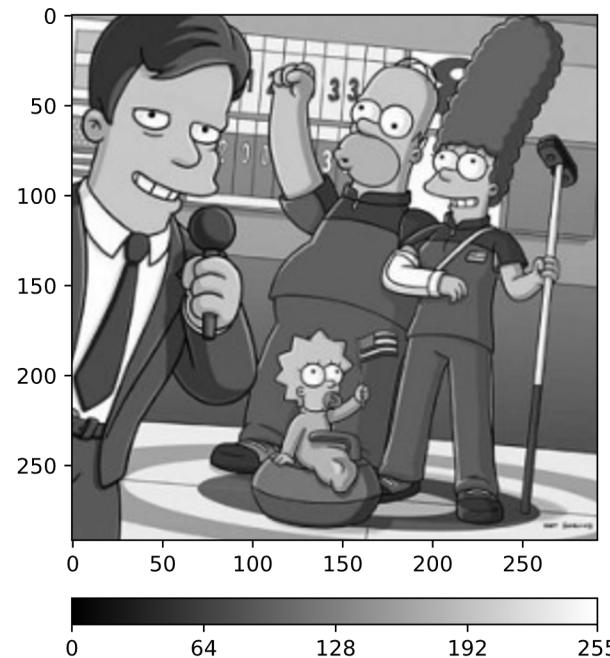
# Arithmetic operations of images

**substraction**

or

$$\forall m, n, \quad h(m, n) = f(m, n) - g(m, n)$$

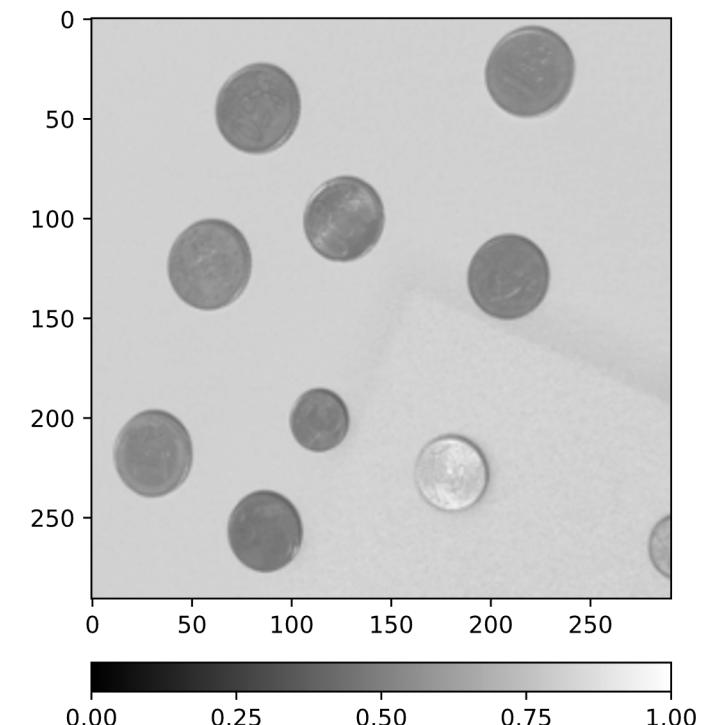
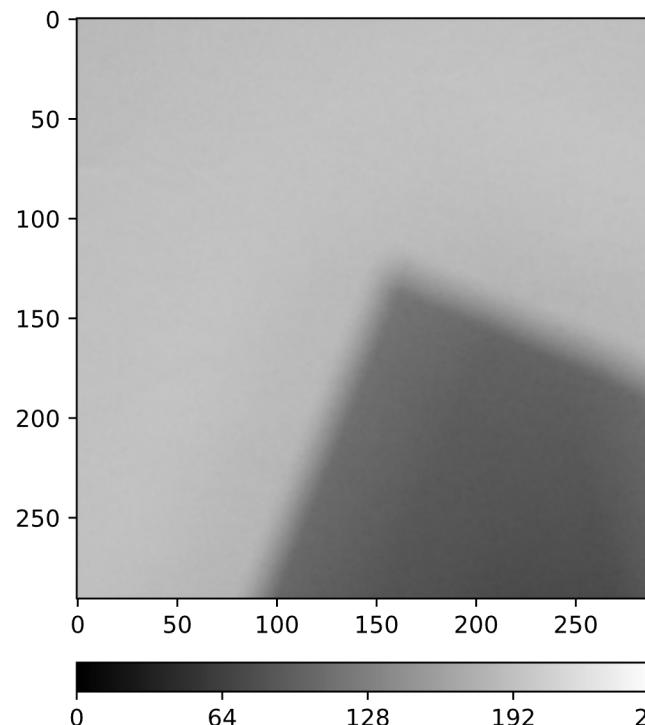
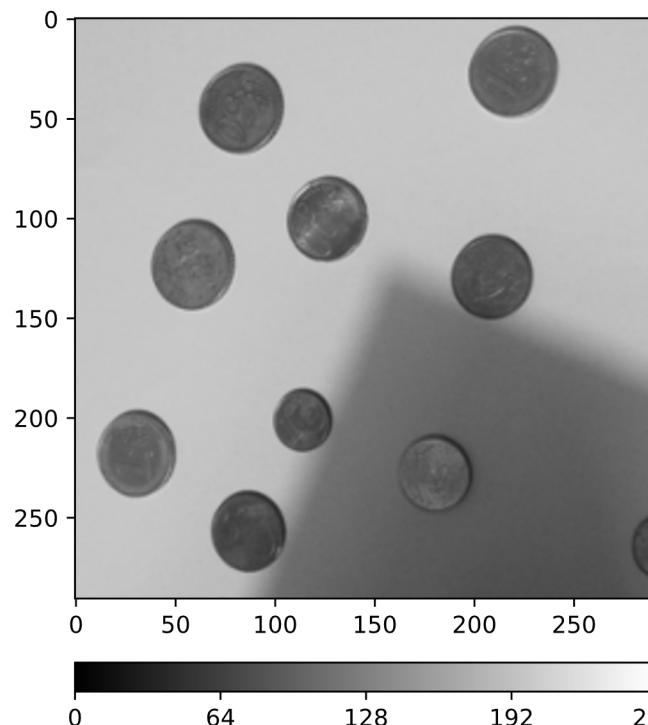
$$\forall m, n, \quad h(m, n) = |f(m, n) - g(m, n)|$$



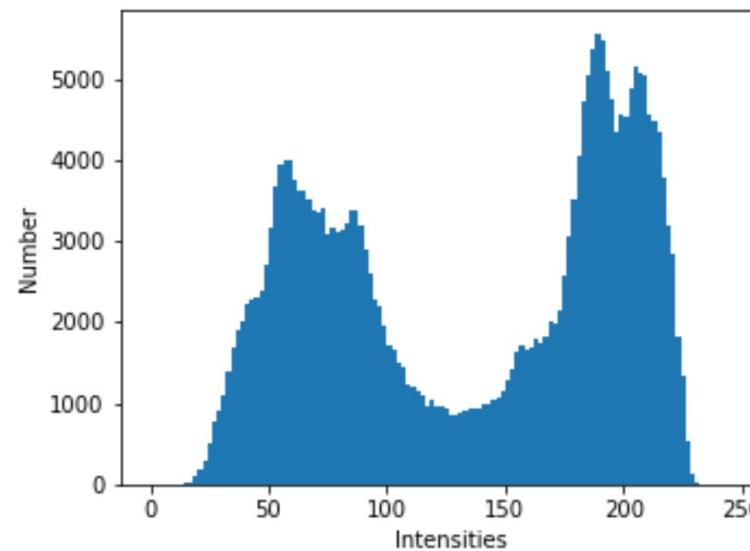
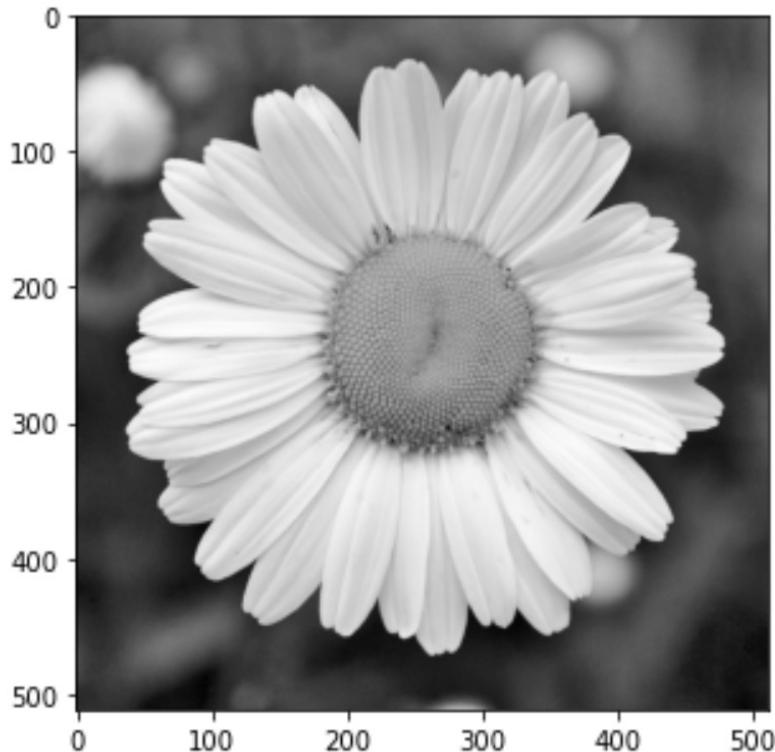
# Arithmetic operations of images

## Division

$$\forall m, n, \quad h(m, n) = \frac{f(m, n)}{g(m, n)}.$$



# Image histogram



# Histogram Transformation

An histogram transformation consists in applying a mathematical function to the intensity distribution.

Generally, the transformations are useful to improve the visual quality of an image, but are rarely needed inside an automatic processing.

$$j = T(i)$$

we suppose the pixel intensities to lie in  $[0, 1]$

Some common transformations:

- Negative image
- Gamma correction
- Histogram spreading
- Histogram equalization

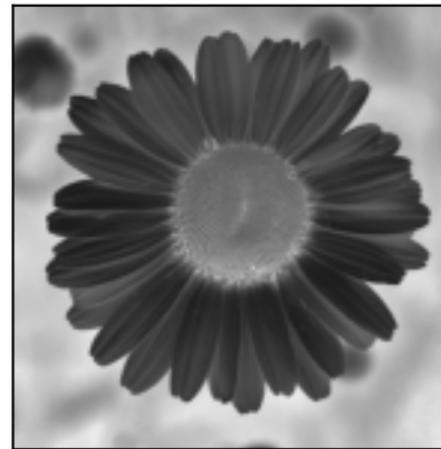


# Negative image

Original image



Transformed image

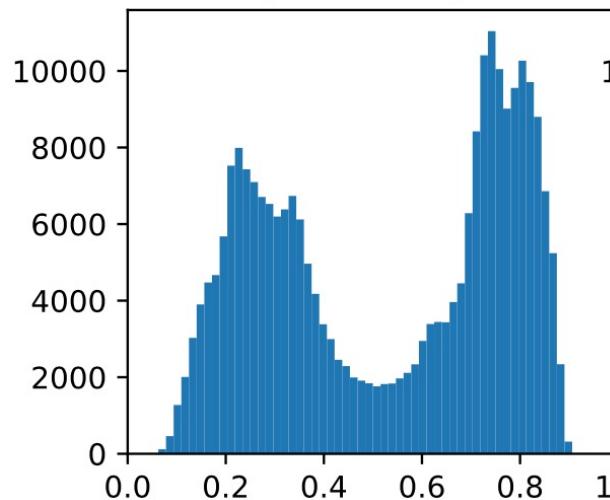


we suppose the pixel intensities to lie in  $[0, 1]$

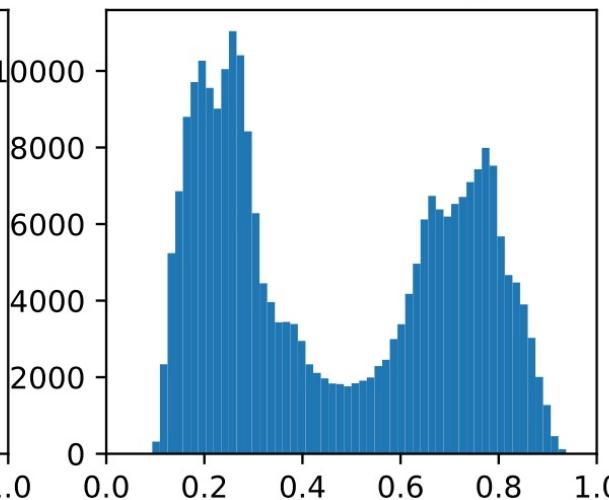
$$T(i) = 1 - i$$

Negative image: the gray levels are reversed

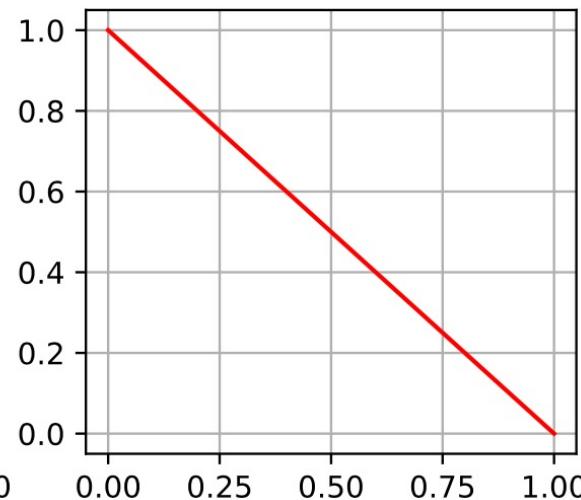
Original histogram



Transformed histogram



Transformation



# Gamma correction

Original image



Transformed image



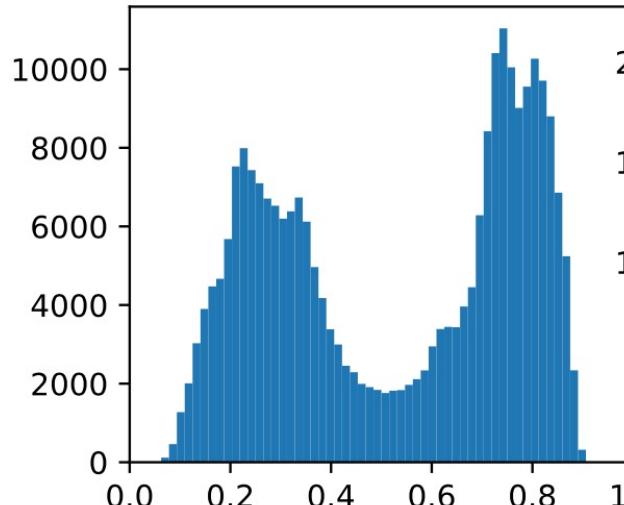
we suppose the pixel intensities to lie in  $[0, 1]$

$$T(i) = i^\gamma$$

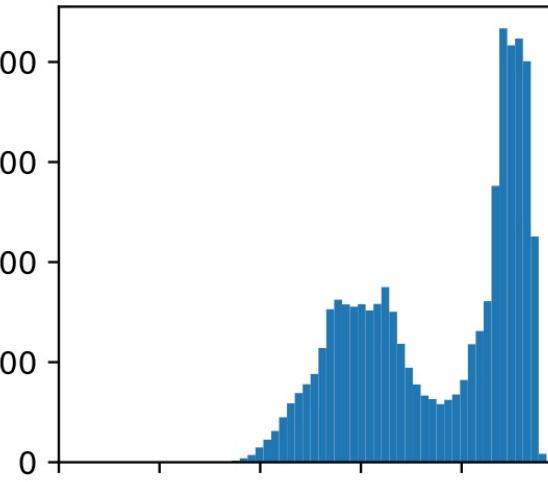
Gamma correction modifies the colors of an image acquired by an electronic system.

It is used to consider the non-linear sensibility of human eyes to the light. Here,  $\gamma=0.4$

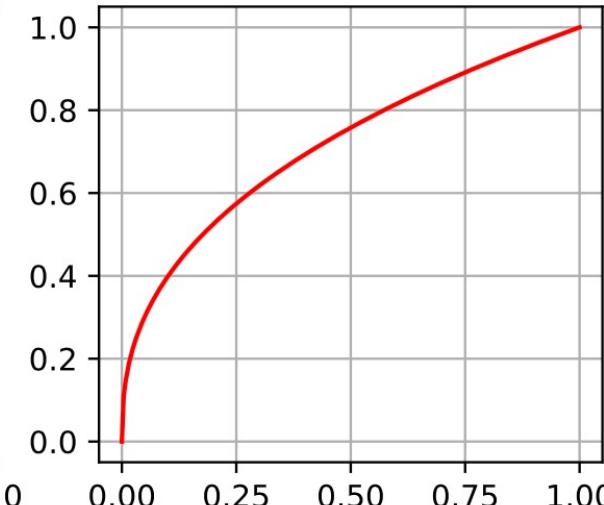
Original histogram



Transformed histogram



Transformation



# Histogram spreading

we suppose the pixel intensities to lie in  $[0, 1]$

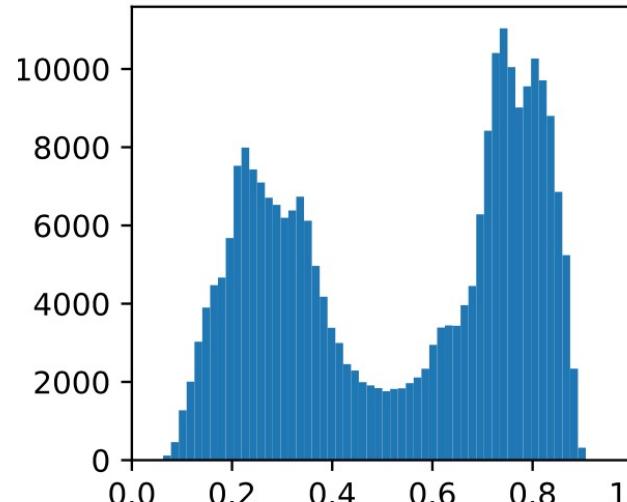
Original image



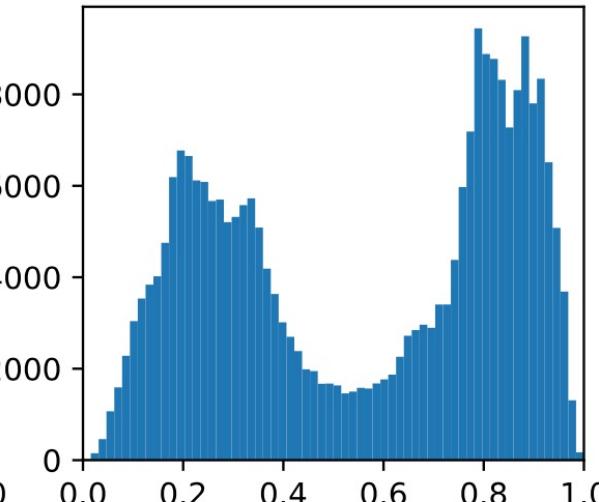
Transformed image



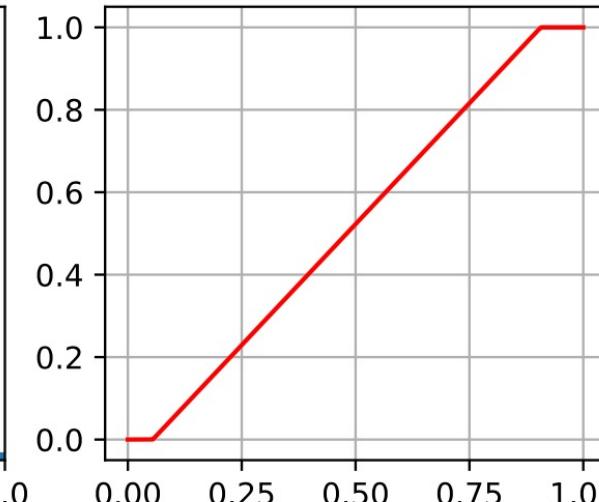
Original histogram



Transformed histogram



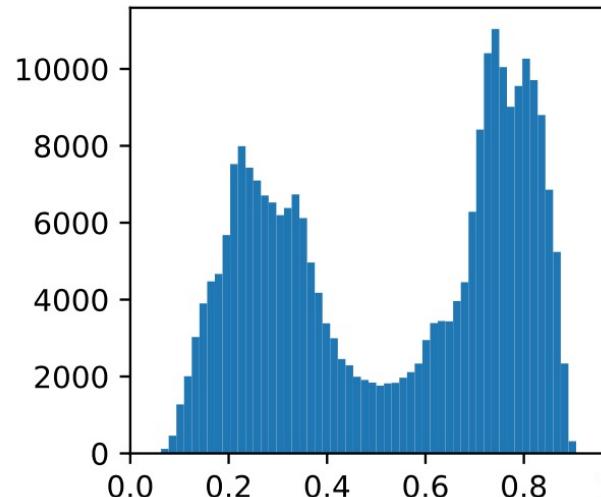
Transformation



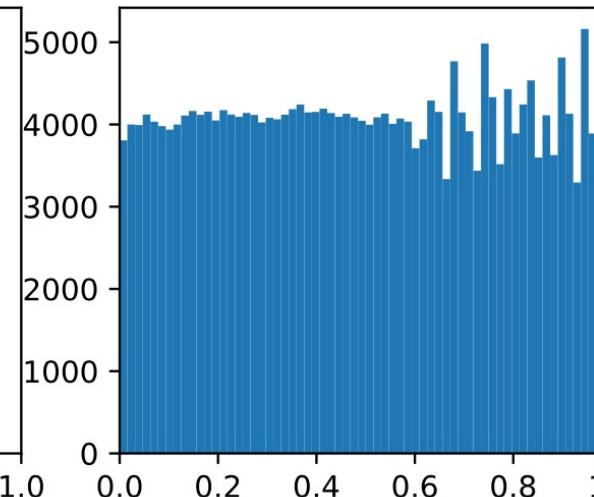
# Equalization Histogram



Original histogram



Transformed histogram

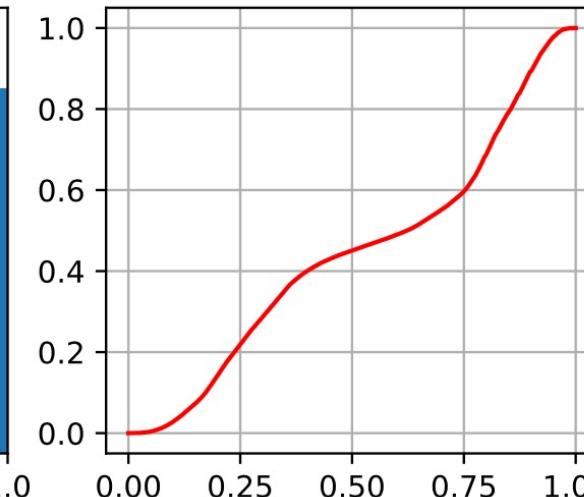


we suppose the pixel intensities to lie in  $[0, 1]$

$$T(i) = \frac{1}{MN} \sum_{k=0}^i n_k$$

- where  $M$  and  $N$  are the image size and  $n_k$  is the number of pixels with intensity  $i_k$ .
- This transformation aims to spread the histogram over the entire intensity range, and to make the histogram as flat as possible.
- A consequence is an increasing of the image contrast

Transformation

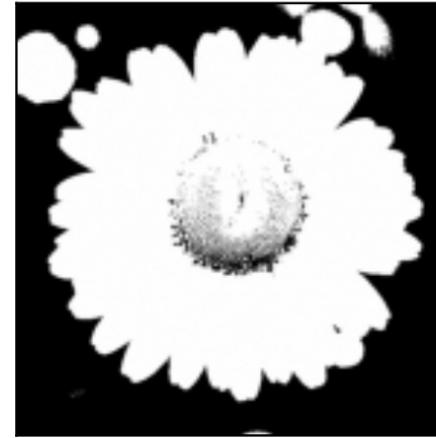


# Thresholding

Original image

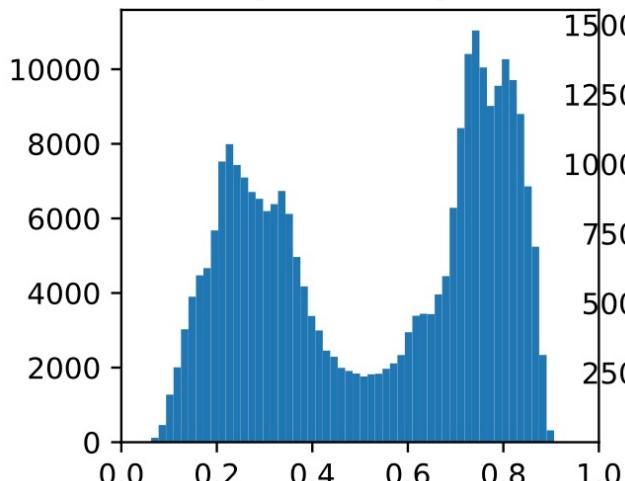


Transformed image

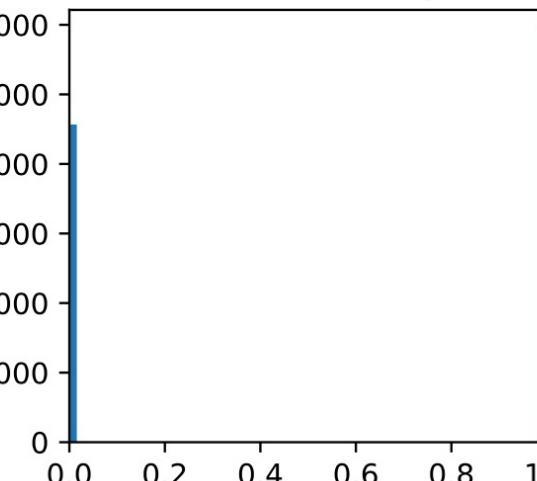


Threshold with a threshold set to 0.45

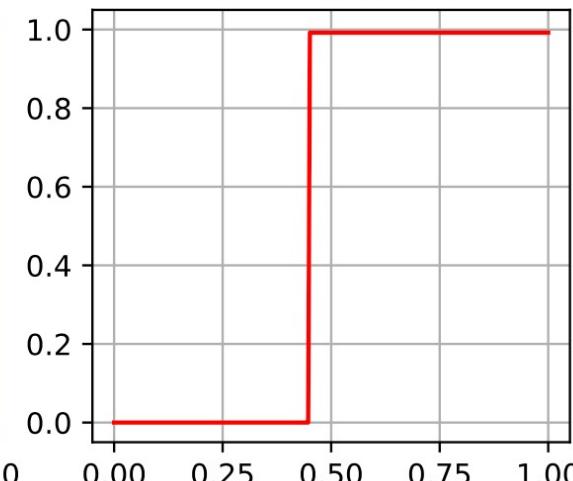
Original histogram



Transformed histogram



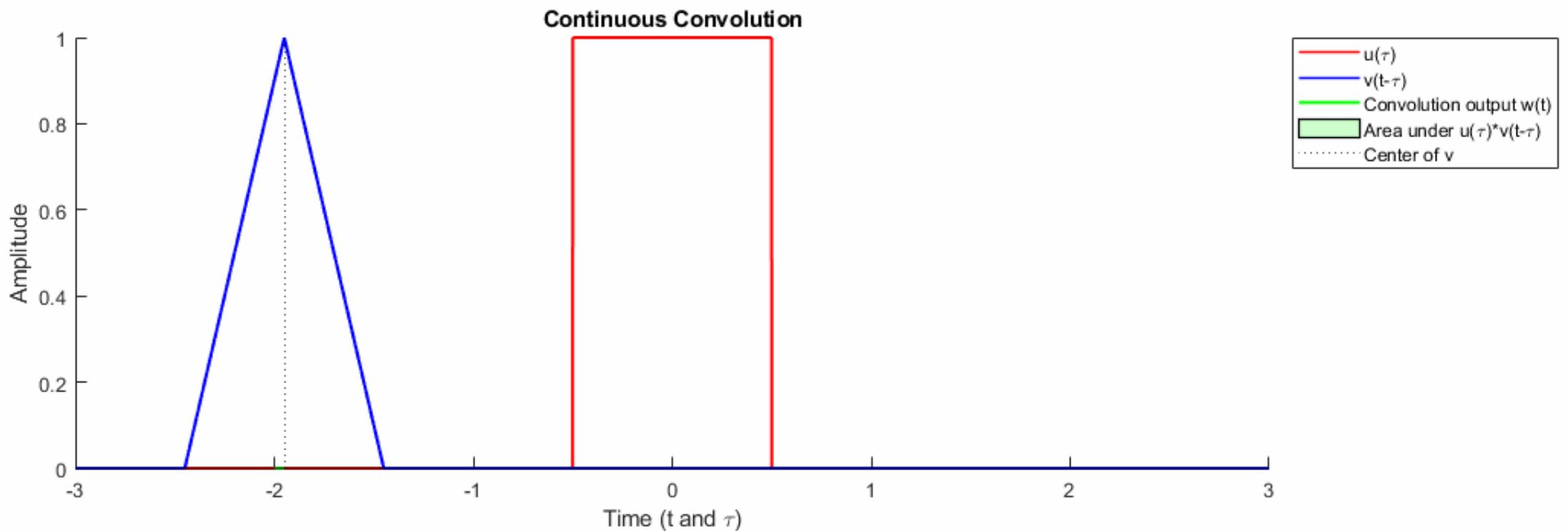
Transformation

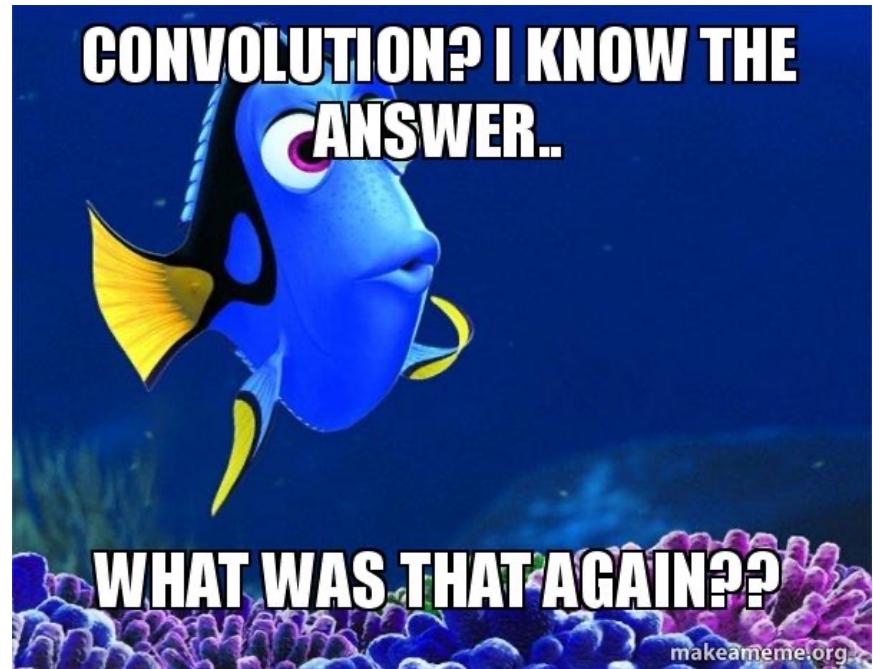


# Convolution

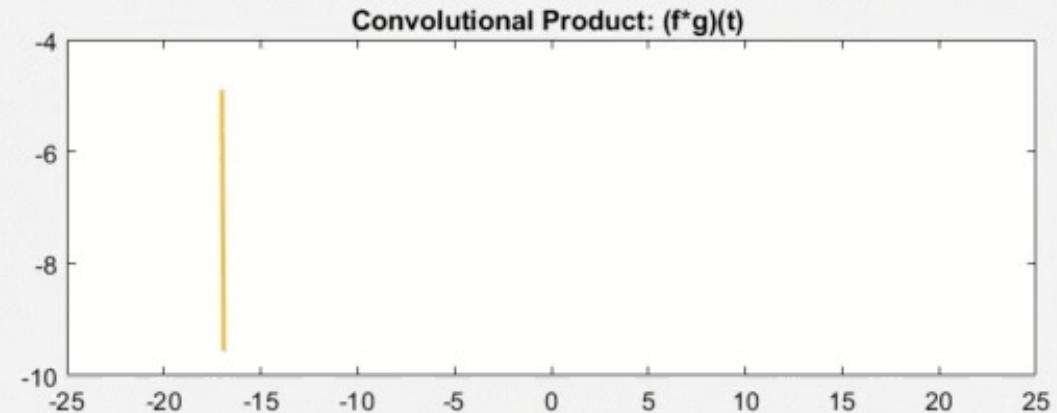
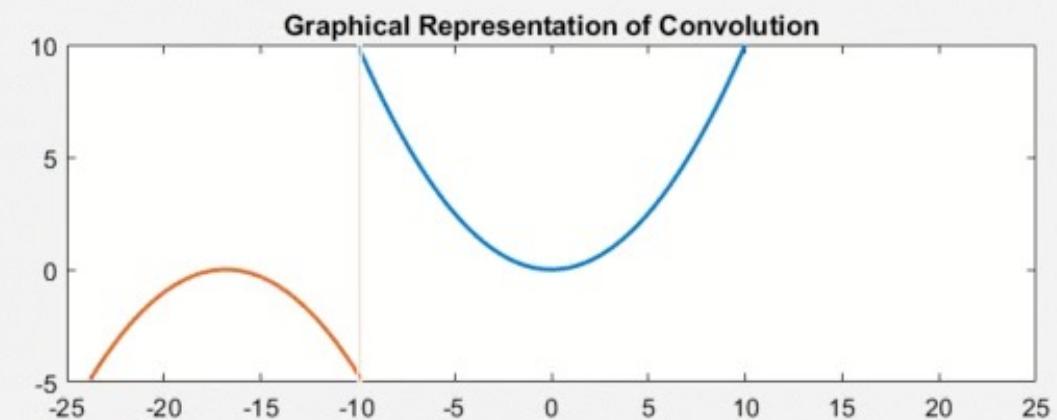
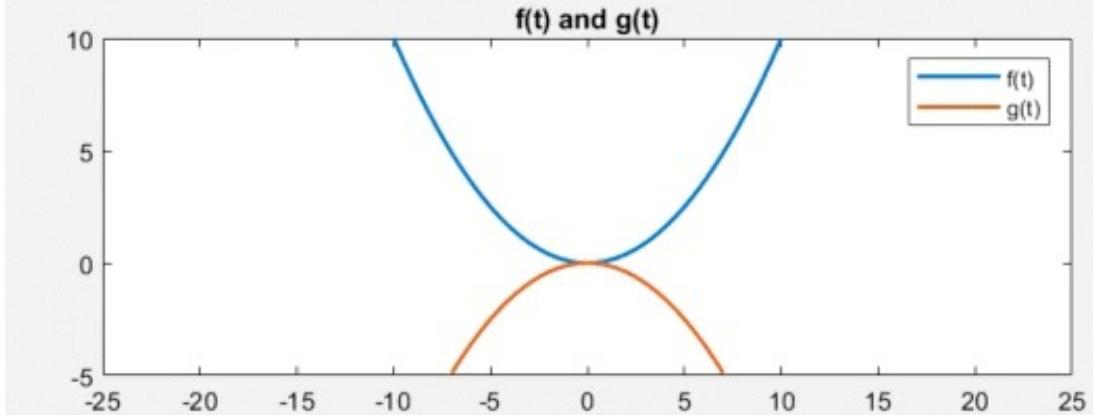
Formally, convolution is an integral that expresses the amount of overlap of one function,  $f(t)$ , as it is shifted over function  $g(t)$ , expressed as:

$$(f * g)(t) \approx^{\text{def}} \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau$$





- Convolution is a mathematical operation that combines two functions to describe the overlap between them.
- Convolution takes two functions and “slides” one of them over the other, multiplying the function values at each point where they overlap, and adding up the products to create a new function.
- This process creates a new function that represents how the two original functions interact with each other

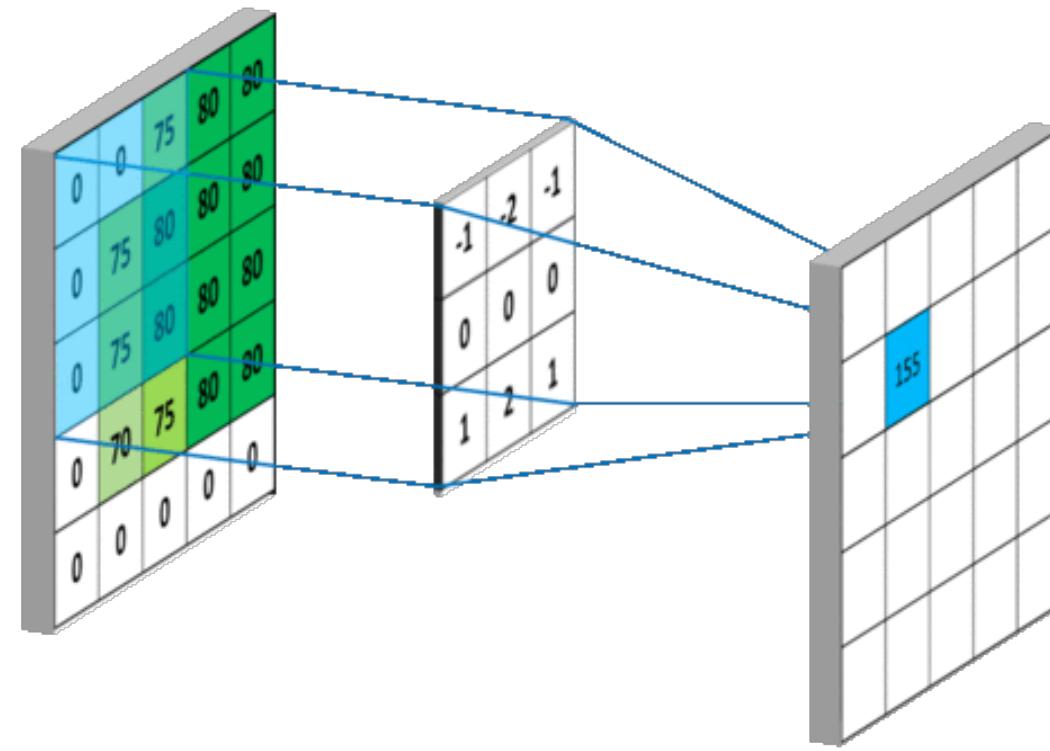


# Convolution in Image Processing

In image processing, convolutional filtering can be used to implement algorithms such as:

1. edge detection,
2. image sharpening, and
3. image blurring.

This is done by selecting the appropriate kernel (convolution matrix).



Sharpening Filter Kernel

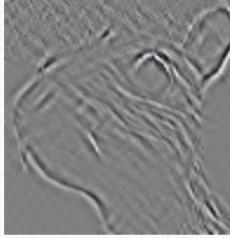
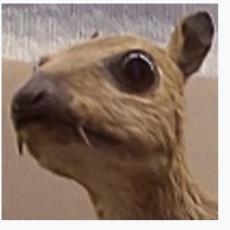
0	-1	0
-1	5	-1
0	-1	0

Input

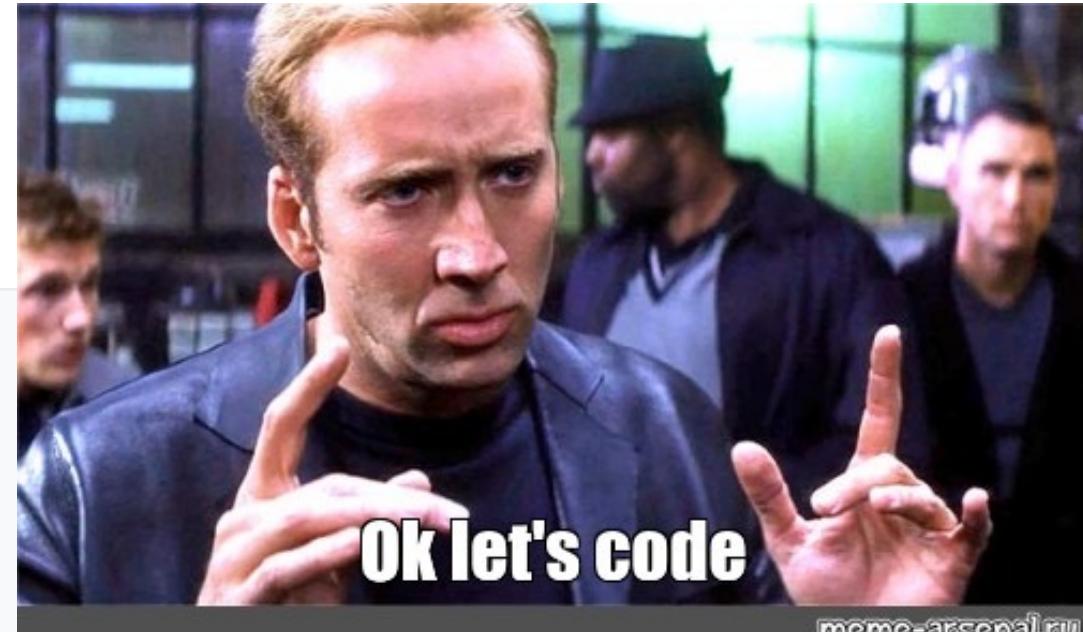
0	0	0	0	0	0	0
0	1	2	2	1	0	0
0	1	2	1	2	1	0
0	0	2	3	2	0	0
0	0	5	2	2	0	0
0	0	7	2	1	1	0
0	0	0	0	0	0	0

Sharpened Output

2	5	6	1	-2
2	4	-4	5	3
-3	0	8	3	-3
-5	14	-2	5	-3
-7	28	0	0	4

Operation	Kernel $\omega$	Image result $g(x,y)$		
Identity	$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$			
Ridge or edge detection	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$		<b>Box blur (normalized)</b>	$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ 
	$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$		<b>Gaussian blur <math>3 \times 3</math> (approximation)</b>	$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$ 
Sharpen	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$		<b>Gaussian blur <math>5 \times 5</math> (approximation)</b>	$\frac{1}{256} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \\ 4 & 16 & 24 & 16 & 4 \\ 6 & 24 & 36 & 24 & 6 \\ 4 & 16 & 24 & 16 & 4 \\ 1 & 4 & 6 & 4 & 1 \end{bmatrix}$ 
			<b>Unsharp masking <math>5 \times 5</math></b> Based on Gaussian blur with amount as 1 and threshold as 0 (with no image mask)	$\frac{-1}{256} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \\ 4 & 16 & 24 & 16 & 4 \\ 6 & 24 & -476 & 24 & 6 \\ 4 & 16 & 24 & 16 & 4 \\ 1 & 4 & 6 & 4 & 1 \end{bmatrix}$ 

```
for each image row in input image:  
    for each pixel in image row:  
        set accumulator to zero  
        for each kernel row in kernel:  
            for each element in kernel row:  
                if element position corresponding* to pixel position then  
                    multiply element value corresponding* to pixel value  
                    add result to accumulator  
                endif  
            set output image pixel to accumulator
```



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# Tarea:

## Parte 1:

- A una imagen, aplicar todos los métodos de transformación de histogramas vistos en clase.

## Parte 2:

- Implemente el algoritmo de convolución de una imagen mostrado en clase.

