

Closed-form DSM method for the free vibration of orthotropic rectangular thin plates

Four SOV-type eigenvalue equations

$$\alpha_1 = \chi \sqrt{\sqrt{\left(\frac{D_{12}l_2}{D_{11}l_1} - 2\frac{D_{66}l_3}{D_{11}l_1}\right)^2 - \frac{D_{22}l_4}{D_{11}l_1} + b^4\Omega_x^4} + \frac{D_{12}l_2}{D_{11}l_1} - 2\frac{D_{66}l_3}{D_{11}l_1}}$$

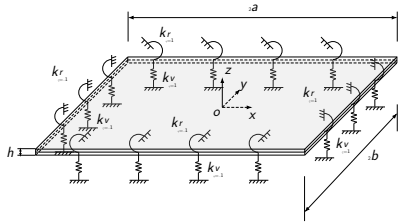
$$\beta_1 = \chi \sqrt{\sqrt{\left(\frac{D_{12}l_2}{D_{11}l_1} - 2\frac{D_{66}l_3}{D_{11}l_1}\right)^2 - \frac{D_{22}l_4}{D_{11}l_1} + b^4\Omega_x^4} - \frac{D_{12}l_2}{D_{11}l_1} + 2\frac{D_{66}l_3}{D_{11}l_1}}$$

$$\alpha_2 = \frac{1}{\chi} \sqrt{\sqrt{\left(\frac{D_{12}J_2}{D_{22}J_1} - 2\frac{D_{66}J_3}{D_{22}J_1}\right)^2 - \frac{D_{11}J_4}{D_{22}J_1} + \frac{a^4D_{11}}{D_{22}}\Omega_y^4} + \frac{D_{12}J_2}{D_{22}J_1} - 2\frac{D_{66}J_3}{D_{22}J_1}}$$

$$\beta_2 = \frac{1}{\chi} \sqrt{\sqrt{\left(\frac{D_{12}J_2}{D_{22}J_1} - 2\frac{D_{66}J_3}{D_{22}J_1}\right)^2 - \frac{D_{11}J_4}{D_{22}J_1} + \frac{a^4D_{11}}{D_{22}}\Omega_y^4} - \frac{D_{12}J_2}{D_{22}J_1} + 2\frac{D_{66}J_3}{D_{22}J_1}}$$

+

Two eigenvalue equations from boundary condition



The orthotropic rectangular plate with all edges elastically restrained.

$$\det(\mathbf{R}_x) = 0$$

$$\det(\mathbf{R}_y) = 0$$

SOV-DSM formulation and solution

Traditional SOV methods

- ▶ Six unknown variables: $\alpha_1, \beta_1, \Omega_x, \alpha_2, \beta_2, \Omega_y$.
- ▶ Four nonlinear and two **highly nonlinear transcendental** equations.
- ▶ Expensive computational cost and convergence difficulties.

Construct SOV-DS matrices

$$\mathbf{K}_x = \mathbf{R}_x \mathbf{Q}_x^{-1}$$

$$\mathbf{K}_y = \mathbf{R}_y \mathbf{Q}_y^{-1}$$

- ▶ Two unknown variables: Ω_x, Ω_y .
- ▶ Two **highly complex** SOV-DS matrices: $\mathbf{K}_x(\Omega_x)$ and $\mathbf{K}_y(\Omega_y)$.

Enhanced Wittrick-Williams algorithm to solve SOV-DS matrices:

$$J(p) = J(\bar{p}_1) - J_k(\bar{p}_1) + J_k(p, \omega^*)$$

The problem of solving $J_0(p_1)$ is transformed into solving $J(\bar{p}_1)$.

If $\bar{p}_1 = S-S$ boundary condition, **closed-form** expression to find $J(\bar{p}_1)$:

$$b\Omega_{x,n_x}^4 = \left[\left(\frac{n_x \pi}{2\chi} \right)^2 - \frac{D_{12}S_2}{D_{11}S_1} + 2\frac{D_{66}S_3}{D_{11}S_1} \right]^2 - \left(\frac{D_{12}S_2}{D_{11}S_1} - 2\frac{D_{66}S_3}{D_{11}S_1} \right)^2 + \frac{D_{22}S_4}{D_{11}S_1}$$

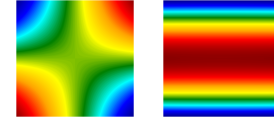
$$a\Omega_{y,n_y}^4 = \frac{D_{22}}{D_{11}} \left\{ \left[\left(\frac{n_y \pi \chi}{2} \right)^2 - \frac{D_{12}T_2}{D_{22}T_1} + 2\frac{D_{66}T_3}{D_{22}T_1} \right]^2 - \left(\frac{D_{12}T_2}{D_{22}T_1} - 2\frac{D_{66}T_3}{D_{22}T_1} \right)^2 + \frac{D_{11}T_4}{D_{22}T_1} \right\}$$

Other specific

boundary condition:

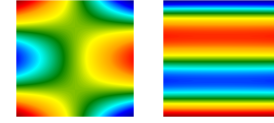
- ▶ $\bar{p}_1 = S-G$.
- ▶ $\bar{p}_1 = G-G$.
- ▶ $J(\bar{p}_1)$ available.

The square orthotropic plate with FFFF boundary conditions:



(a)

(b)



(c)

(d)

(a) the first mode; (b) the second mode; (c) the third mode; (d) the fourth mode.

Advantages:

- ▶ General solution for arbitrary boundary conditions.
- ▶ Closed-form DSM.
- ▶ Explicit closed-form expression for the J_0 term.
- ▶ Avoids solving highly nonlinear equations.

Mode shape computation for arbitrary boundary conditions

First-order Taylor series:

$$\mathbf{R}_{x,k}(\omega_k) \mathbf{A}_k = \mathbf{R}_{x,a} \mathbf{A}_k + (\omega_k - \omega_a) \mathbf{R}'_{x,a} \mathbf{A}_k + O((\omega_k - \omega_a)^2) = 0$$

Inverse iteration procedure:

$$\bar{\mathbf{A}}^{(i+1)} = \mathbf{R}_{x,a}^{-1} \mathbf{R}'_{x,a} \mathbf{A}^{(i)}$$

Mode shape:

$$\phi(\xi) = A_1 \sin(\alpha_1 \xi) + A_2 \cos(\alpha_1 \xi) + A_3 \sinh(\beta_1 \xi) + A_4 \cosh(\beta_1 \xi)$$

$$\psi(\eta) = B_1 \sin(\alpha_2 \eta) + B_2 \cos(\alpha_2 \eta) + B_3 \sinh(\beta_2 \eta) + B_4 \cosh(\beta_2 \eta)$$