Convex Hull:

Time and Space Complexity overview sudo code for actual report go to the bottom.

```
Space Complexity O(n logn) Time Complexity: O(n/agins)
                                                                                                                                                                                                                                                                                                                                                                                                2T =+D(30) A= 2 8=2 D=1
Complainty
 (n) - def compute_hull(points: list[tuple[float, float]]) -> list[tuple[float, float]]:
                                                                                 points = sorted(points, key=lambda x: (x[0], x[1])) - n/a, (n)
                                                                                   convex_hull = div_hull(points)
                                                                                  return convex hull
         of def div_hull(points):
                                                                                  points
                                                                                  if len(points) <= 2: - C
                                                                                               return points - C
                0 \stackrel{\text{(i)}}{\longrightarrow} = \min = \text{len(points)} //2 - \alpha = 2
2 \stackrel{\text{(i)}}{\longrightarrow} 0 \stackrel{\text{(n+n+n)}}{\longrightarrow} 0 \stackrel{\text{(ii)}}{\longrightarrow} 0 \stackrel{\text{(iii)}}{\longrightarrow} 0 \stackrel{\text{(iiii)}}{\longrightarrow} 0 \stackrel{\text{(iii)}}{\longrightarrow} 0 \stackrel{\text{(iiii)}}{\longrightarrow} 0 \stackrel{\text{(iii)}}{\longrightarrow} 0 \stackrel{\text{(iiii)}}{\longrightarrow} 0 \stackrel{\text{(iii)}}{\longrightarrow} 0 \stackrel
                 left = points[:mid]
right = points[mid:]
                 o(a_n) (eftHull = div_hull(right) > b = 2, <math>o(a_n)
                                                                                               return combine_hull(leftHull, rightHull) - Q(n)
               (n) - def combine_hull(left, right):
                                                                                 return [left[0], right[0]]
                                                                                  else:
                                                                                                 rightmost_left_index = max(range(len(left)), key=lambda i: left[i][0])
                                                                                               leftmost_right_index = max(range(len(left)), key=lambda i: right[i][0])

Find : leftmost_right_index = min(range(len(right)), key=lambda i: right[i][0])

O(n)
                                                                                               upper_tangent = find_upper_tangent(left, right, rightmost_left_index, - 0 (n)
                                                                    leftmost_right_index)
                                                                     | lower_tangent = find_lower_tangent(left, right, rightmost_left_index, _ O (N) | leftmost_right_index)
```

```
upper_right = upper_tangent[1]
                                                   O(): Set points for combination
                lower_right = lower_tangent[1]
                upper_left = upper_tangent[0]
                lower_left = lower_tangent[0]
                 combined hull = []
                 currentPoint = upper left
                combined_hull.append(left[currentPoint]) - Add all points o(1)
                                                                   Add all points at worst from upper not o(n)
                 currentPoint = upper_right
                 combined_hull.append(right[currentPoint])
While
                                                                   from upper right
                 while currentPoint != lower_right:
Cambining
                   currentPoint = (currentPoint + 1) % len(right)
 the Space
                   combined_hull.append(right[currentPoint])
 Complexity
 is at with
                 if upper_left != lower_left:
 O(1) beaute
                   currentPoint = (lower_left) % len(left)
every point
 is add
                   while currentPoint != upper_left:
                                                                       lover left
until end of
                     combined_hull.append(left[currentPoint])
                     currentPoint = (currentPoint + 1) % len(left)
                                                                        left or upper
                return combined hull
Space Complainty
  o(a) _ def find_upper_tangent(left, right, left_index, right_index): ->
              xl, yl = left[left_index]
                                             } Get x,g in
              xr, yr = right[right_index]
              if x! == xr:
                                         Don't divide by 0
                start_slope = float('inf')
```

start_slope = (yr - yl) / (xr - xl) get Sboe

```
changed = True
while changed: - o(n)
/ left_visited = set()
  right_visited = set()
                                           at worst o (lagas)
  changed = False
  while True: _
     left_visited.add(left_index) Q(/)
     next_left_index = (left_index - 1) % len(left) O(\iota)
     if next_left_index in left_visited: o(1)
       break
                                                              checking if slope
is <= ifidis
     left_visited.add(next_left_index) Q(I)
     lx, ly = left[next_left_index]
                                      0(1)
                                     0(1)
     new\_slope = (yr - ly) / (xr - lx)
     if new_slope <= start_slope:
                                     0(1)
       start_slope = new_slope
                                   0(1)
       xI, yI = Ix, Iy
                                   0(1)
       left_index = next_left_index Q(1)
       changed = True
     else:
       break
  while True:
     right_visited.add(right_index)
     next_right_index = (right_index + 1) % len(right)
     if next_right_index in right_visited:
       break
     right_visited.add(next_right_index)
                                                           > other side
O(/gn)
     rx, ry = right[next_right_index]
```

```
new\_slope = (ry - yl) / (rx - xl)
        if new_slope >= start_slope:
          start_slope = new_slope
          xr, yr = rx, ry
          right_index = next_right_index
          changed = True
        else:
          break
  return left_index, right_index
                                                                     000)
def find lower tangent(left, right, left index, right index):
  xl, yl = left[left_index]
  xr, yr = right[right_index]
  if x == xr:
     start_slope = float('-inf')
  else:
     start_slope = (yr - yl) / (xr - xl)
  changed = True
  while changed:
     left_visited = set()
     right_visited = set()
                                                                      repeate for laws
     changed = False
     while True:
        left_visited.add(left_index)
        next_left_index = (left_index + 1) % len(left)
        if next_left_index in left_visited:
```

break

This allow the state of the sta

```
left_visited.add(next_left_index)
  lx, ly = left[next_left_index]
  new_slope = (yr - ly) / (xr - lx)
  if new_slope >= start_slope:
     start_slope = new_slope
     xI, yI = Ix, Iy
     left_index = next_left_index
     changed = True
  else:
     break
while True:
  right_visited.add(right_index)
  next_right_index = (right_index - 1) % len(right)
  if next_right_index in right_visited:
     break
  right_visited.add(next_right_index)
  rx, ry = right[next_right_index]
  new\_slope = (ry - yl) / (rx - xl)
  if new_slope <= start_slope:
     start_slope = new_slope
     xr, yr = rx, ry
     right_index = next_right_index
     changed = True
  else:
     break
```

return left_index, right_index

The algorithm's total time complexity is $O(n \log n)$.

The initial sorting operation in compute_hull takes $O(n \log n)$ time. After sorting, the algorithm follows a divide-and-conquer pattern, where we recursively divide the points into left and right halves until we reach base case. Due to the Master Theorem where we have a = 2, b = 2, and d = 1 giving us $O(n\log(n))$.

For the recursive process:

- Each division splits the input into two equal halves
- The combination step, which includes finding and merging hulls, takes O(n) time
- 1. Division Phase O(1):
 - Splitting points into left and right halves uses simple array slicing
 - The midpoint calculation is constant time
- 2. Finding Tangents O(n):
 - Both find_upper_tangent and find_lower_tangent scan points in left and right hulls
 - While loops may iterate multiple times, but each point is visited at most once
 - Total operations remain linear in the size of input
- 3. Combining Hulls O(n):
 - Iterating around the hulls to create the combined result
 - Each point is visited at most once during the merge

Space Complexity Analysis:

The total space complexity is O(n log n), determined by:

- 1. Recursive Space:
 - At each recursion level, we create new left and right subarrays
 - The recursion depth is log n
 - At each level, we need O(n) space for:
 - Divided point arrays

- Temporary storage in combination operations
- Visited sets while finding tangents

2. Additional Storage:

Initial sorted array: O(n)

- Combined hull arrays at each level: O(n)

- Sets for tracking visited points: O(n)

The space accumulates across recursion levels since we maintain arrays at each level before combining results. With log n levels each requiring O(n) space, this gives us a total space complexity of $O(n \log n)$.

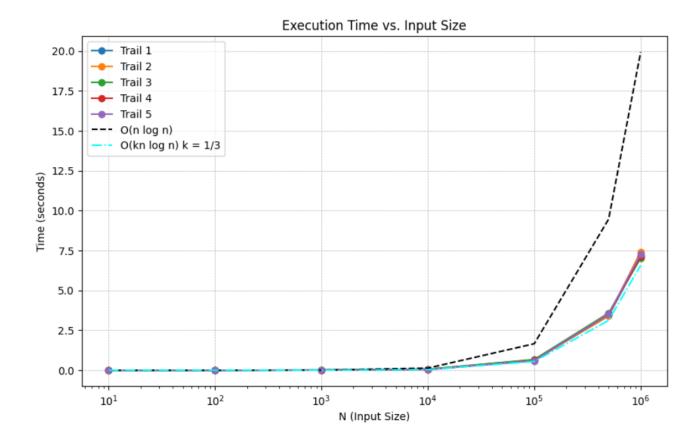
Analyzing Differences

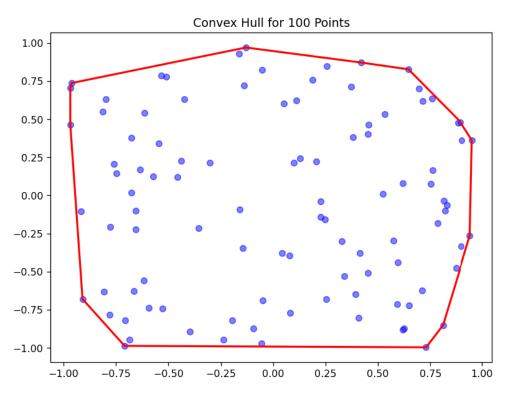
The measured execution times generally follow the expected O(n log n), but there are some deviations at larger input sizes (see below). While the empirical data aligns with the theoretical complexity, the actual runtime appears to be scaled down by a constant factor.

One notable observation is that the measured times are consistently about k = 1/3 or O($1/3n \log(n)$). This suggests that while the algorithm's growth rate matches the theoretical prediction, the actual execution time is lower.

- Hidden Constants The theoretical analysis does not account for constant-time operations like function calls, memory allocation, which could impact the performance.
- **Hardware Optimizations** Modern CPUs, caching, and parallelism may contribute to a lower observed runtime than expected.

N =	10	100	1000	10000	100000	500000	1000000
Trail 1 time	0.0	0.0	0.008411	0.062716	0.652557	3.400225	7.186492
Trail 2 time	0.0	0.0	0.007681	0.065222	0.620895	3.415905	7.4317
Trail 3 time	0.0	0.0	0.008272	0.061779	0.673041	3.584279	7.024147
Trail 4 time	0.0	0.0	0.008129	0.050271	0.606982	3.51028	7.114009
Trail 5 time	0.0	0.0	0.010193	0.040866	0.597968	3.525613	7.28373





Convex Hull for 1000 Points

