```
.program trigger
.side_set 1 opt
start:
    pull block
                      side 0
    mov x, osr
    jmp x-- trigger
; if the input is zero, just send an update without waiting
update:
    jmp start
                       side 1 [7]
trigger:
   wait 1 pin 0
                     side 1 [3]
    out pins, 4
                      side 0
    out pins, 4
    push
.program timer
.side set 1
start:
    pull block
                  side 0
                           ; pull the instruction from FIFO
   mov x, osr
                   side 0
                               ; move from osr to scratch register
    jmp !x hwstart side 0
                              ; if instuciton is 0 that means hwstart
   nop
                   side 1 [5]; if not hwstart, hit the trigger pin
loop:
    jmp x-− loop
                   side 0
                               ; count down to next trigger
.wrap
hwstart:
                              ; wait for the trigger pin
   wait 1 gpio 8 side 0
    jmp start
                   side 0
% c-sdk {
    static inline void trigger_program_init(PIO pio, uint sm, uint offset,
       uint trigger pin,
       uint p_pin,
       uint update pin
    ) {
       // profile pins
       pio_gpio_init(pio, p_pin + 0);
       pio_gpio_init(pio, p_pin + 1);
       pio gpio init(pio, p pin + 2);
        pio_gpio_init(pio, p_pin + 3);
```

```
// IO_UPDATE to AD9959
    pio_gpio_init(pio, update_pin);
    // External Trigger Pin
    pio_gpio_init(pio, trigger_pin);
    pio sm set pindirs with mask(pio, sm,
        (0xf << p pin) | (1u << update pin) | (0u << trigger pin),
        (0xf << p_pin) | (1u << update_pin) | (1u << trigger_pin)</pre>
    );
    pio_sm_config c = trigger_program_get_default_config(offset);
    sm_config_set_sideset_pins(&c, update_pin);
    sm_config_set_out_pins(&c, p_pin, 4);
    sm_config_set_in_pins(&c, trigger_pin);
    sm_config_set_out_shift(&c, true, false, 1);
    sm_config_set_in_shift(&c, true, true, 1);
    sm config set clkdiv(&c, 1.f);
    pio_sm_init(pio, sm, offset, &c);
    pio_sm_set_enabled(pio, sm, true);
}
static inline void timer program init(PIO pio, uint sm, uint offset,
    uint trigger pin
) {
    pio sm config c = timer program get default config(offset);
    pio gpio init(pio, trigger pin);
    pio sm set pindirs with mask(pio, sm,
        (1u << trigger_pin),</pre>
        (1u << trigger pin)</pre>
    );
    sm config set sideset pins(&c, trigger pin);
    sm_config_set_out_shift(&c, true, false, 1);
    sm config set in shift(&c, true, true, 1);
    sm_config_set_clkdiv(&c, 1.f);
    pio_sm_init(pio, sm, offset, &c);
    pio sm set enabled(pio, sm, true);
}
```