

# COMP225: Algorithms and Data Structures

## Applications of Graphs (2)

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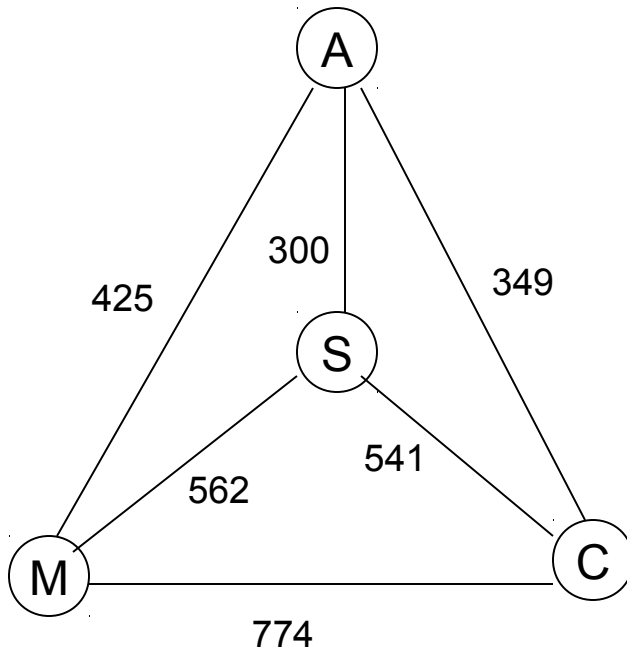
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E6A380

# Outline

- Euler circuits
- Shortest paths
- Miscellanea

# Aside: Travelling Salesman



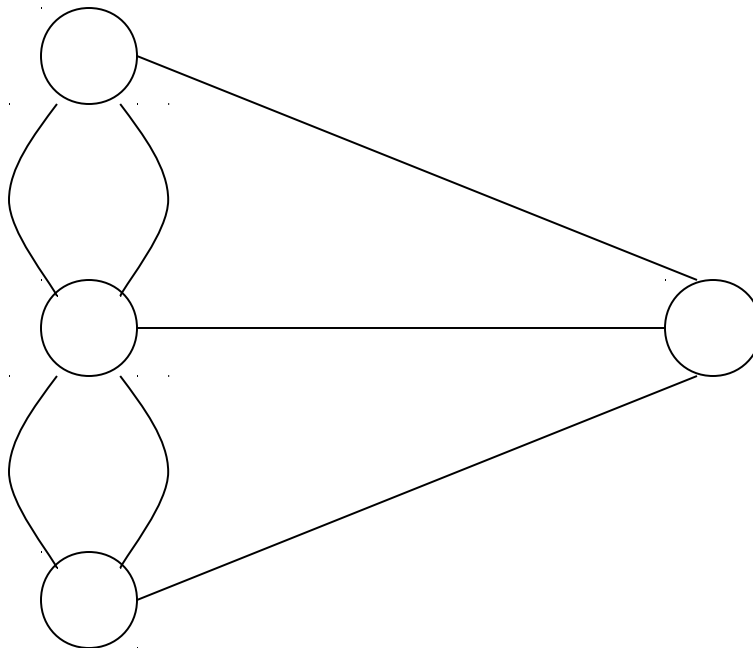
optimal: 1877 (A-C-S-M-A)

greedy: 2040 (A-S-C-M-A)

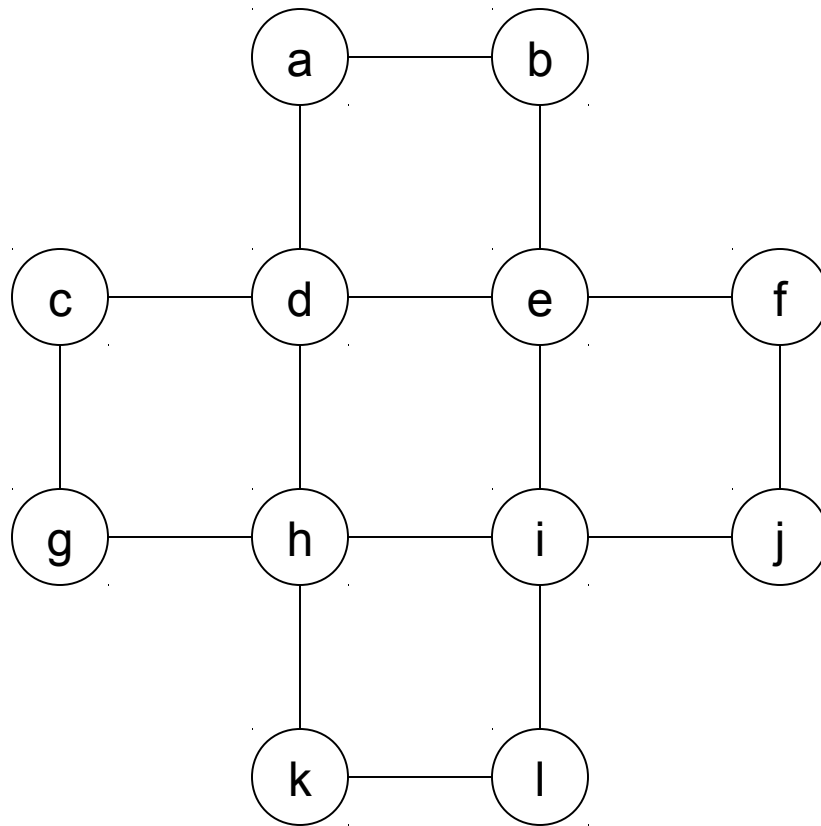
# Euler Circuit

- Original problem: Seven Bridges of Königsberg
- Aim is to traverse every edge exactly once
  - doesn't matter how many times a particular vertex is visited
  - must end at start vertex
  - an Euler path is where you traverse each edge once but don't end up at the same vertex

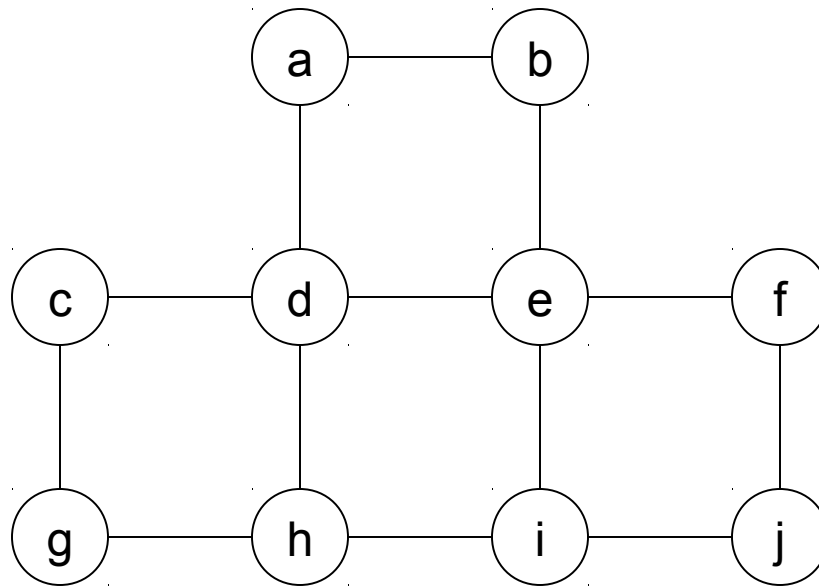
# Euler Circuit



# Euler Circuit



# Euler Circuit



# Euler Circuit

- Finding a cycle
  - an algorithm to find *whether* there is a cycle is easier
  - an Euler circuit is possible iff each node is of even degree
    - intuitively, this is because to traverse each edge you need to both enter and leave each node
  - an Euler path is possible iff
    - each node is of even degree, except for two of odd degree; or
    - an Euler circuit is possible



# Euler Circuit

```
bool hasEulerCircuit(int v)
```

```
// detects whether there is an Euler circuit starting from vertex v
```

```
    circuitSoFar = true
```

```
    mark v as visited
```

```
    if (degree(v) is odd)
```

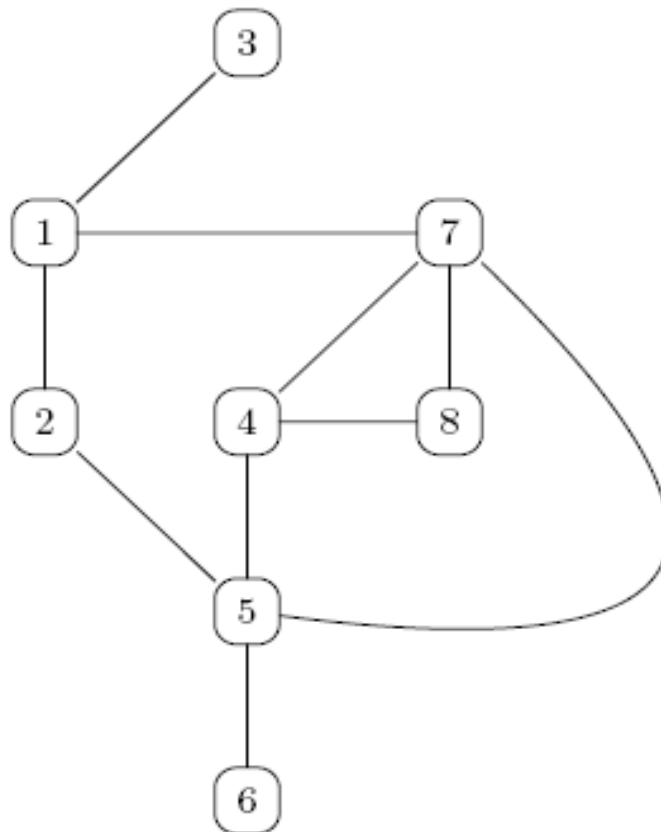
```
        return false
```

```
    for (each unvisited vertex u adjacent to v)
```

```
        circuitSoFar = circuitSoFar && isEulerCircuit(u)
```

```
    return circuitSoFar
```

# Euler Circuit: Exercise



# Euler Circuit

- So obviously problem is not too difficult
- How about a problem where every vertex is visited once?
  - Hamiltonian circuit

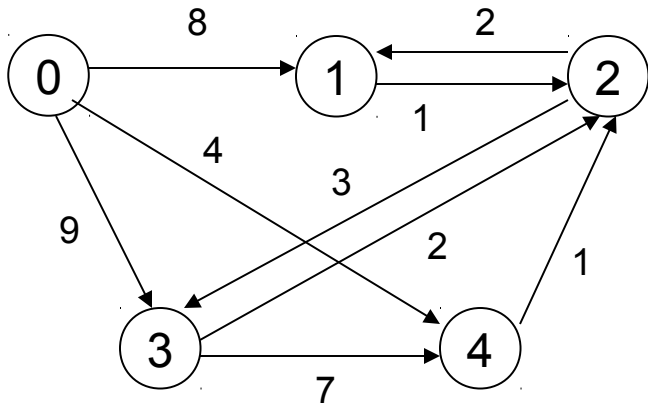
# Outline

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# Shortest Path

- Aim to get from one vertex  $v_1$  to another  $v_2$  by the least cost path
- Note this isn't the same as the minimal spanning tree problem
  - that tries to connect all the nodes into a single least-cost tree
  - here we only look for a single connection between nodes, which must be a path
  - consider shortest path from  $b$  to  $g$  in Prim's Algorithm example

# Shortest Path



|   | 0        | 1        | 2        | 3        | 4        |
|---|----------|----------|----------|----------|----------|
| 0 | $\infty$ | 8        | $\infty$ | 9        | 4        |
| 1 | $\infty$ | $\infty$ | 1        | $\infty$ | $\infty$ |
| 2 | $\infty$ | 2        | $\infty$ | 3        | $\infty$ |
| 3 | $\infty$ | $\infty$ | 2        | $\infty$ | 7        |
| 4 | $\infty$ | $\infty$ | 1        | $\infty$ | $\infty$ |

# Shortest Path

- Shortest path from vertex 0 to vertex 1 has cost 7
  - not the edge (0,1): cost is 8
  - shortest path is 0-4-2-1
- Can we get this via a greedy algorithm?
  - in this case yes: take greedy choice at each step from 0
  - however, not for the general case

# Shortest Path

- What's an alternative?
  - same as Travelling Salesman: enumerate every single possible path and evaluate weights
  - to find the shortest path from 0 to 1:
    - evaluate 0-1
    - evaluate 0-3-2-1
    - evaluate 0-3-4-2-1
    - evaluate 0-4-2-1
  - in general, computationally expensive



# Dijkstra's Algorithm

- Determines shortest path between origin and all other vertices
- Algorithm uses:
  - a set `vertexSet` of selected vertices
  - an array `weight`, where `weight[v]` is the weight of the shortest path from vertex 0 to vertex `v` that passes through vertices in `vertexSet`
- Initially, `vertexSet` contains just 0, `weight[v]` is just `adjMatrix[0][v]`

# Dijkstra's Algorithm

- Then
  - find a vertex  $v$  that is not in `vertexSet` that minimises `weight[v]`
  - add  $v$  to `vertexSet`
  - can you improve the cost to any other vertex  $u$  not in `vertexSet` by passing through  $v$ ?
    - to do this, break path from 0 to  $u$  into two pieces:
    - `weight[v]` = weight of shortest path from 0 to  $v$
    - `matrix[v][u]` = weight of edge from  $v$  to  $u$

# Dijkstra's Algorithm Example

| step | v | vertexSet | weight |     |          |     |     |
|------|---|-----------|--------|-----|----------|-----|-----|
|      |   |           | [0]    | [1] | [2]      | [3] | [4] |
| 1    | - | 0         | 0      | 8   | $\infty$ | 9   | 4   |
| 2    | 4 | 0,4       | 0      | 8   | 5        | 9   | 4   |
| 3    | 2 | 0,4,2     | 0      | 7   | 5        | 8   | 4   |
| 4    | 1 | 0,4,2,1   | 0      | 7   | 5        | 8   | 4   |
| 5    | 3 | 0,4,2,1,3 | 0      | 7   | 5        | 8   | 4   |

# Dijkstra's Algorithm Example

- Step 1
  - vertexSet contains 0, weight is first row of adjMatrix (with  $\text{weight}[0] = 0$ )
- Step 2
  - $\text{weight}[4]$  is smallest value in weight
  - add 4 to vertexSet
  - for each vertex not in vertexSet (i.e. 1, 2, 3), check if it's shorter to go via 4
  - shorter for 2 ( $\text{weight}[4] + \text{adjMatrix}[4][2] = 5$ )

# Dijkstra's Algorithm Example

- Step 3
  - $\text{weight}[2] = 5$  is the smallest value in  $\text{weight}$  (ignoring  $\text{weight}[0]$  and  $\text{weight}[4]$ )
  - add 2 to  $\text{vertexSet}$
  - shorter to go via 2 for both 1 and 3
  - $\text{weight}[1] = 7$ ,  $\text{weight}[3] = 8$

# Dijkstra's Algorithm Example

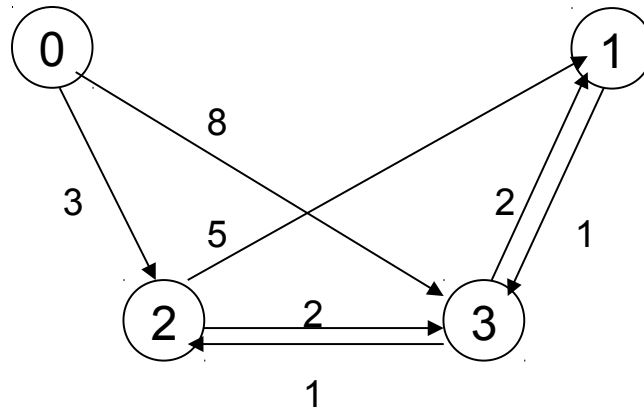
- Step 4
  - $\text{weight}[1] = 7$
  - add 1 to vertexSet
- Step 5
  - add only remaining vertex, 3, to vertexSet

# Dijkstra's Algorithm

```
shortestPath(in theGraph: Graph, in weight:WeightArray)
// finds the min-cost paths between an origin vertex and all other vertices
// in a weighted directed graph; theGraph's weights are non-negative

create a set vertexSet that contains only vertex 0
n = number of vertices in theGraph
for (v = 0 through n-1) weight[v] = matrix[0][v]
// invariant: weight[v] is the smallest weight to v from vertices in vertexSet
for (step = 2 through n) {
    find smallest weight[v] such that v is not in vertexSet
    add v to vertexSet
    for (all vertices u not in vertexSet)
        if (weight[u] > weight[v] + matrix[v][u])
            weight[u] = weight[v] + matrix[v][u]
}
```

# Dijkstra's Algorithm: Exercise





# Analysis

- In the form given, worst-case time complexity is  $O(V^2)$ 
  - outer for loop loops through all  $|V|$  vertices
  - inner for loop loops through all vertices not yet in vertexSet (on average  $|V|/2$ )

# A Better Variant

- Can improve by adding a global PQ, as with Prim's, storing vertices with distances
  - complexity is  $O(E.T_{dk} + V.T_{em})$ , where  $T_{dk}$  and  $T_{em}$  are the complexities of the decrease-key and extract-minimum operations in the PQ, respectively
  - where a minheap is used,  $T_{dk}$  and  $T_{em}$  are both  $O(\log n)$  for heap of size  $n$
  - overall complexity then is  $O(V \log V + E \log V)$

# Dijkstra's Algorithm

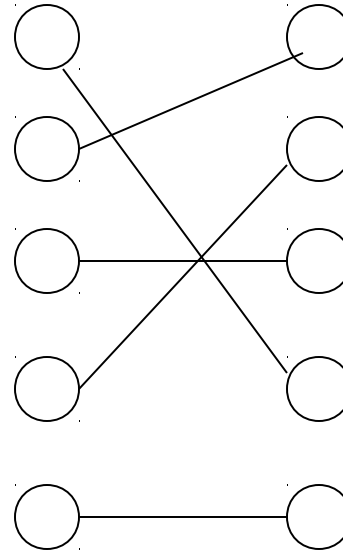
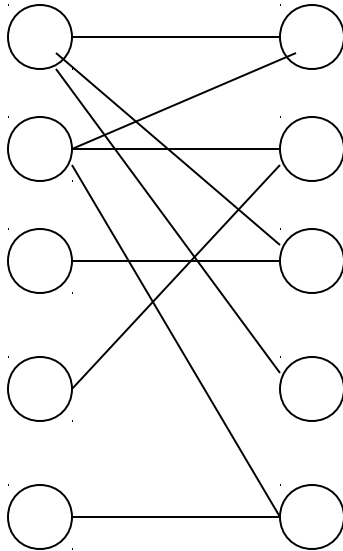
- Why don't we have to enumerate all solutions, as in Travelling Salesman?
  - the key is the loop invariant
  - we keep a record of the best solution so far:  
**optimal substructure**
  - this is a fundamental aspect of both greedy algorithms and dynamic programming
  - cf. divide-and-conquer

# Outline

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- **Miscellanea**

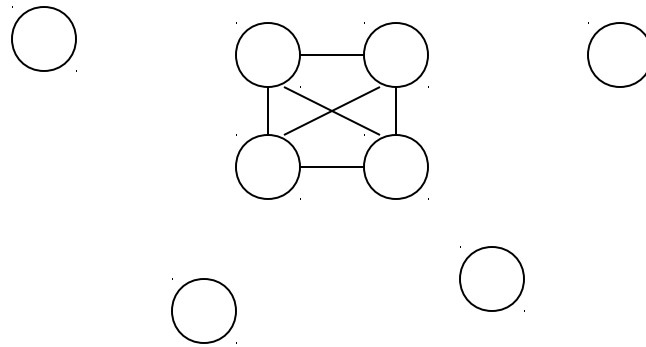
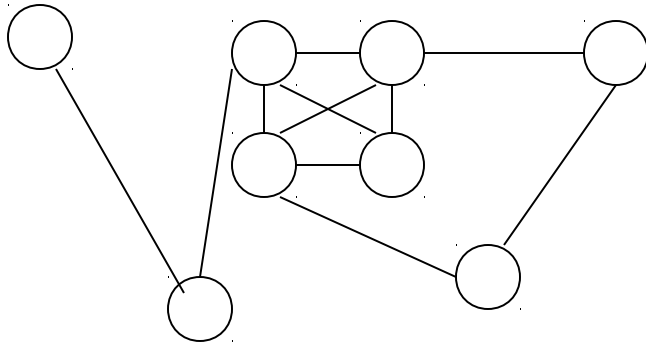
# Other Graph Applications

- Matching
  - subgraph s.t. each vertex is incident to at most one edge



# Other Graph Applications

- Clique detection



# Real-Life Graph Problems

- Already mentioned ones
  - find best configuration for phone network links: minimal spanning tree
  - find best route for postman: weighted version of Euler circuit
  - scheduling of tasks: topological sort
  - assignment of jobs: matching

# Real-Life Graph Problems

- In DNA sequencing: for a fragment  $f$ , some fragments are forced to go to the left of  $f$ , others to the right, others are free; need to find a consistent ordering
  - Create a directed graph with links between constrained fragments, then do topological sort



# Real-Life Graph Problems

- In porting code from Unix to DOS, filenames can only be 8 characters, but must be unique. Can't just truncate (e.g. *filename1* vs *filename2*)
  - Each original filename becomes a vertex, as does the set of acceptable renamings. Want  $n$  edges with no vertices in common: matching.

# Real-Life Graph Problems

- In organised tax fraud, fake tax returns are similar but not identical. How to detect clusters of similar forms?
  - Each form is a vertex, with an edge between them if they match some percentage of entries: then identify clique

# Real-Life Graph Problems

- In OCR, need a way to separate lines of text. Although there's some white space between lines, problems like noise and page tilt make it hard to find. How to do line segmentation?
  - Each pixel is a vertex, edges between neighbouring pixels. Weight is proportional to darkness: find shortest path.