## **Datos**

Faros_de_Xenon	Alarma	Techo_Solar	Navegador	Bluetooth	Control_de_Velocidad
1	0	0	1	1	1
1	0	1	0	1	1
1	0	0	1	0	1
1	0	1	1	1	0
1	0	0	0	1	1
0	0	0	1	0	0
1	0	0	0	1	1
0	1	1	0	0	0

Soporte >= 0.5 Confianza >= 0.8

## Resultados obtenidos

```
[OK] {Control_de_Velocidad} => {Bluetooth}
[OK] {Bluetooth} => {Control_de_Velocidad}
[OK] {Control_de_Velocidad}=> {Faros_de_Xenon}
[OK] {Faros_de_Xenon}=> {Control_de_Velocidad}
[OK] {Bluetooth}=> {Faros_de_Xenon}
[OK] {Faros_de_Xenon}=> {Bluetooth}
[OK] {Bluetooth,Control_de_Velocidad} => {Faros_de_Xenon}
[OK] {Faros_de_Xenon,Control_de_Velocidad} => {Bluetooth}
[OK] {Faros_de_Xenon,Bluetooth} => {Control_de_Velocidad}
[NO] {Control_de_Velocidad} => {Faros_de_Xenon,Bluetooth}
```

[NO] {Bluetooth} =>{Faros\_de\_Xenon,Control\_de\_Velocidad}

Los datos con [OK] fueron obtenidos por apriori, por mi implementación y a mano, los datos con NO solo por mi implementación y a mano.

## Replicar resultados

```
source("calapriori.R")
source("f_apriori.R")
toTable(f_apriori(readAprioriFile("datos2.txt"),0.5,0.8))
calapriori(readAprioriFile("datos2.txt"),0.5,0.8)
```

```
F= Fares de Xeon
                                S(<F>)=6/8 /
  A=Alarman
                                 8/1 = ((A>) 2
  T: Techo solar
                                 5 (<7>)= 3/8
  N = Nonegador
                                 S (<N>)= 4/8 V
  B= Blue tooth
                                 s ((B)=5/8 /
  (= control che velocidad
                                                              s(N) 20/5
                                 5((()):5/8/
L KF, N, B, c>
                                 5 (< F,N>) = 3/8
7 < F, T, B, C>
                                  s((F,B)) = 5/8 V
3 (F, N,C)
                                  S(<F, (>) = 5/8 V
4 (F, T, N, B)
                                  S((N, B>) = 2/8
5 (F, B, C>
                                  S(KN,C)=2/8
                                  S((B, ()) = 4/8 V
6 (N>
7 (F, B, C>
                                  S((F,B,(>)=4/8√
8 (A,T)
                                  5 ( ( F, B, N) =
                                  5(CB,C,W)=
                                ((<F>→ < B, <>)=4/6
  C((F) → (N))= 3/6
                                ((⟨B,C>→ ⟨F>)= 4/4 √
  c(<N>→<F>)=3/4
                                                               C(N) 20'8
                                (((N) -> <F, B>)= 2/4
  c(<F>→<B>)=5/6√
                                 ((<F,B>→<N>)=2/5
  ((⟨B>→⟨F>|=5/5 V
                                 ((<N> → <F,(>)=2/4
  ((<F>→<c>)=5/6 √
                                 (((F, () → (N))=2/5
  ((<(>→<F>)=5/5 ✓
                                  (\langle N \rangle \rightarrow \langle B, c \rangle) = 1/4
  ((<N>→<B>)=2/4
                                  c((B, c) → LNy)= 1/4
   c((B>→<N>)=2/s
                                  c((B) → (F, c))=4/5 V .
   ((<N>→L(>)=2/4
                                  (((F,C) → (B)) = 4/5 V
   <((<(>→<N>)=2/5
                                  ((() - (F, B))=4/5 V .
   c((B)→(())=4/5 V
   ((<c>→<B>)=4/5 ✓
                                  (((F,13) + (1))=4/5V
```

Figure 1: Manual\_apriori