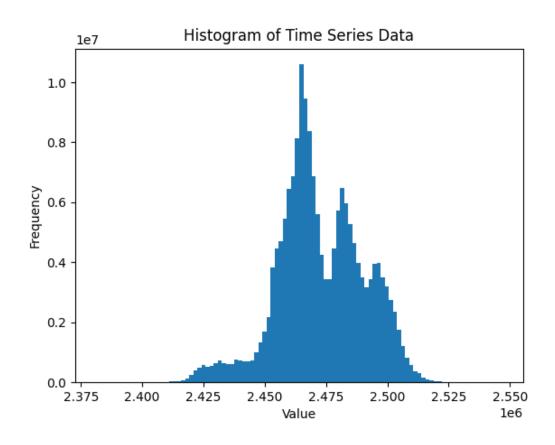
# Photoplethysmography Challenge

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DATA ANALYSIS

#### Distribution of the dataset

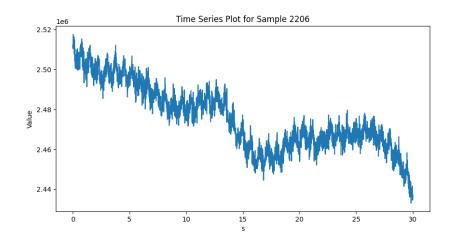


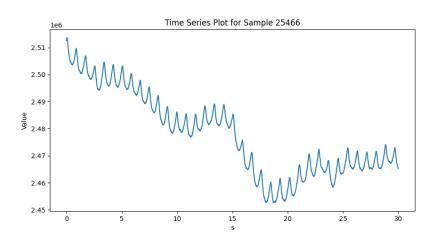
Several populations with certain overlap which could be related to:

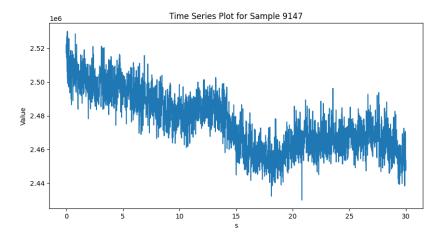
- Data artifacts
- Human modes (running/rest, age)

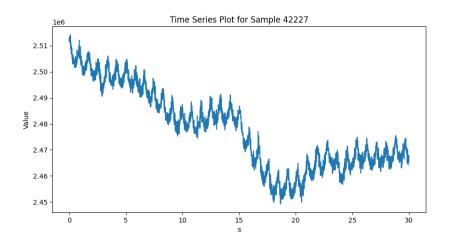
Different levels of onise

## Examples of different signals

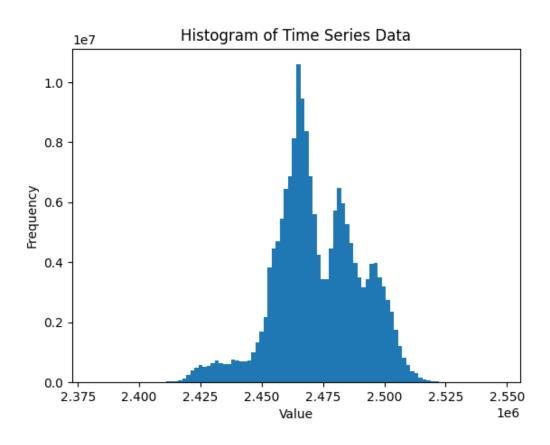






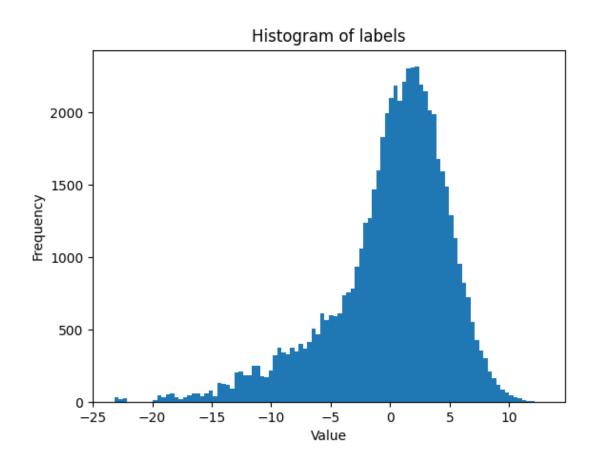


#### Distribution of the dataset



- At first, we observe several populations with certain overlap which could be related to:
  - Data artifacts
  - Human modes (running/rest, age)
- Different levels of noise:
  - Collection of datasets
  - Different sensors
  - Preprocessed signals
- Signals drifting down.
- Duplicated signals.

#### Distribution of the labels

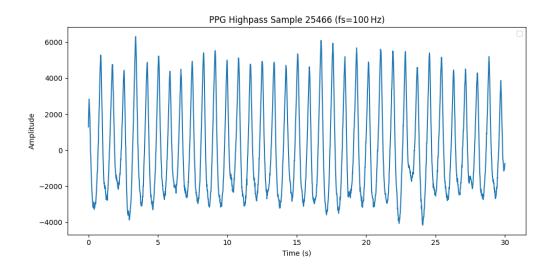


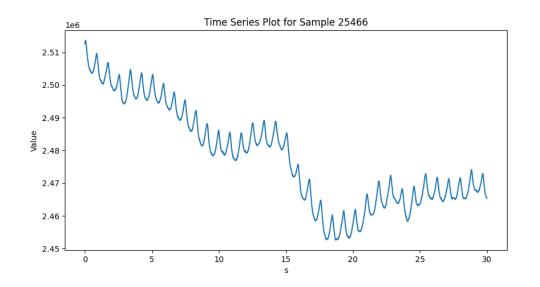
Labels follow a skew normal distribution, which is good for our purpose

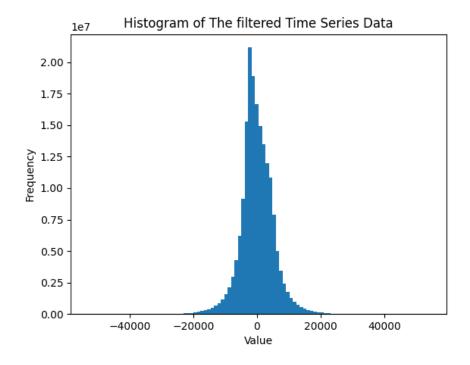
Likewise, the additional features are normally distributed as well:

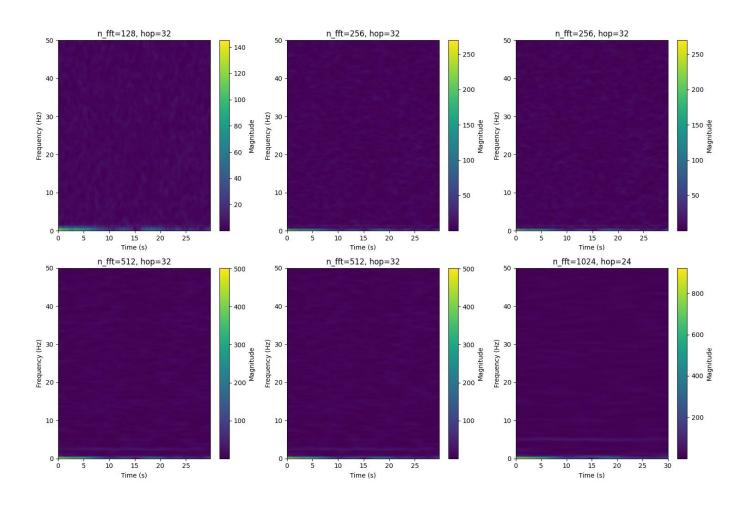
 Data sourced from real world without balancing of any kind.

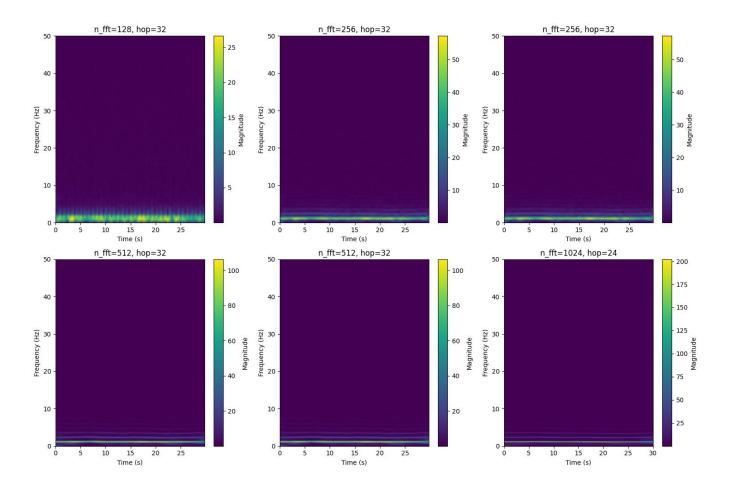
Why labels follow a normal distribution but not the data?











## Model Architecture, Training

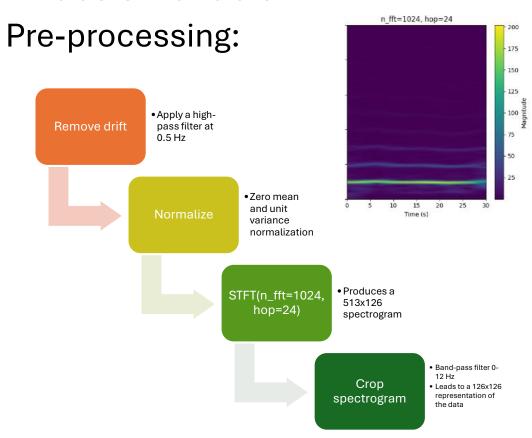
```
class Model(nn.Module)
def init (self)
    super().__init__()
    self.n_fft, self.hop = 1024, 24
    window: Tensor = torch.hamming window(window length=self.n fft)
    self.register_buffer(name="window", tensor=window)
    self.block1: Sequential = conv block(in channels=1, out channels=64, kernel size=7, activation=nn.ReLU(), pooling=nn.MaxPool2d(kernel...2))
    self.block2: Sequential = conv_block(in_channels=64, out_channels=128, kernel_size=7, activation=nn.ReLU(), pooling=nn.MaxPool2d(kernel...2))
    self.block3: Sequential = conv block(in channels=128, out channels=128, kernel size=3, activation=nn.ReLU(), pooling=nn.MaxPool2d(kernel...2)
    self.block4: Sequential = conv_block(in_channels=128, out_channels=256, kernel_size=3, activation=nn.ReLU(), pooling=nn.MaxPool2d(kernel...2))
    self.block5: Sequential = conv block(
        activation=nn.ReLU();
        pooling=nn.AdaptiveMaxPool2d(output_size=1),
    self.fc ts = nn.Sequential(nn.Linear(in features=256, out features=128), nn.ReLU())
    self.feats encoder = nn.Sequential(
        nn.Linear(in features=5, out features=64),
        nn.Linear(in features=64, out features=128),
        nn.ReLU(),
    self.fc1 = nn.Sequential(nn.Linear(in features=256, out features=128), nn.ReLU())
    self.fc2 = nn.Sequential(nn.Linear(in_features=128, out_features=64), nn.ReLU())
    self.fc regression = nn.Linear(in features=64, out features=1)
def forward(self, ts, feats):
    sp: Tensor = (
        torch.stft(
            input=ts.
            n_fft=self.n_fft,
            hop_length=self.hop
            window=self.window,
         .unsqueeze(dim=1)
    sp: Tensor = sp[:, :, :126] # Crop frequencies ~0-12 Hz
    x: Any = self.block1(sp)
    x: Any = self.block2(x)
    x: Any = self.block3(x)
    x: Any = self.block4(x)
    x: Any = self.block5(x).squeeze()
    ts_{emb}: Any = self.fc_{ts}(x)
    feats emb: Any = self.feats encoder(feats)
    shared: Tensor = torch.cat(tensors=(ts_emb, feats_emb), dim=1)
    shared: Any = self.fc1(shared)
    shared: Any = self.fc2(shared)
    out: Any = self.fc_regression(shared)
    return out[:, 0]
```

#### Network inputs:

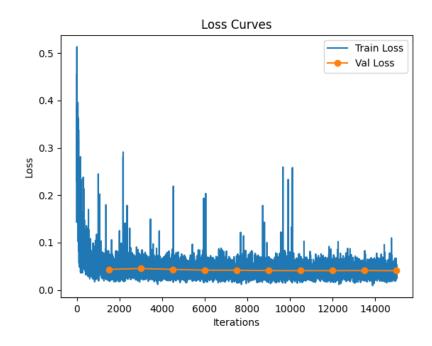
- PPG as spectrograms\*
- Features as they are

#### **Predicts:**

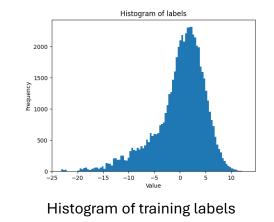
 Regression of z-score "labels" variable

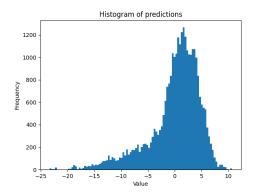


- Optimizer: SGD
- 80/20 train/val split
- 10 epochs
- Smooth L1 loss
- Scheduler: reducing lr 20% ever/epoch



#### Sanity check: Comparing train label vs test pred distribution





Histogram of predictions for the testset

	Mean Abs.Error
No PPG, only features	2.3
Only PPG, No features	3.05
PPG + Features	1.08

Best mean absolute error for the validation set achieved during training.