

Motor_control_state
::enter

Motor_control_state
::update

Dual_LED::turn_red

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stateDiagram-v2\n    state Motor_control_state\n        state enter\n        state update\n    end\n    state Dual_LED\n        state turn_red\n    end\n    Motor_control_state --> Dual_LED : enter\n    Motor_control_state --> Dual_LED : update
```

The diagram illustrates a state machine with two source states on the left and one target state on the right. The source states are 'Motor_control_state::enter' and 'Motor_control_state::update', both contained within a white rectangular box. The target state is 'Dual_LED::turn_red', contained within a gray rectangular box. Two blue arrows originate from the right side of the white box: one arrow points from 'Motor_control_state::enter' to 'Dual_LED::turn_red', and the other points from 'Motor_control_state::update' to 'Dual_LED::turn_red'.