Online Appendix for: Automation, Power, and Profit

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Abstract This document present the code solving the steady-state equilibrium in Section 4 of Automation, Power, and Profit.

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1 Introduction

This document presents all the computational steps required to replicate the results in Section 4 of Automation, Power, and Profit. Here, I also present additional data and robustness results, showing that the key conclusions of the paper do not vary with variations on the measures of automation, normal rate of unemployment, or welfare policy.

2 Code Related to Section 4

Download the required packages. Use import Pkg; Pkg.add(["Distributions","XLSX", "CairoMakie", "LaTeXStrings", "Makie", "CSV","FileIO"]). To download HPFilter, use Pkg.add(url = "https://github.com/sdBrinkmann/HPFilter.jl").

using CairoMakie,LaTeXStrings,NLboxsolve,Distributions,HPFilter,XLSX,ReadStat,DataFrames,CSV

The following code presents the definition of the parameters as in Table 1 of the main text.

2.1 Calibrated Parameters

```
## Calibrated (static) parameters
\alpha = 1.64 \# labor augmenting parameter
\sigma=0.6 # elasticity of substitution
Ak=0.02 # capital auugmenting parameter
        # Hicks neutral parameters
pm=(1+0.26)^{(1/12)-1} # this is obtained from Andreoni and Sprenger (2012)
gm = (1+0.02)^{(1/12)-1} # this is the average of labor productivity growth
\delta m = (1+0.068)^{(1/12)-1} # this is the average of the depreciation rate
# Beveridge curve
\lambda \theta = 0.025 # Separation rate
\dot{m} = 0.0000 # Equilibrium value
\dot{M} = qm/\alpha # derived from the steady-state growth equation.
          # Same as Petrosky-Nadeu (2018)
\rho = \rho m # subjective discount rate
yf = 0.45 # Response time of capitalists
\xi = 8.2 # calibrated to be about 2 times the average productivity of labor
\delta = \delta m # Standard
\varphi = 0.3 # Relative price of capital
```

```
0.3
```

The following code maps the equations in Definition 1 in the main text, with T^w as an endogenous variable. This is the first step to deduce the OLS estimators of

$$\label{eq:total_two_tensor} \mathrm{ln} T_t^w = \beta_0^w + \beta_1^w \mathrm{ln} \mathcal{W}_t + \beta_2^w \mathrm{ln} (Y_t/L_t) + \nu_t.$$

Keep in mind that, as noted in the Table 1 in the main text, $q(\theta) = (1 + \theta^{\iota})^{-\iota}$. Each line of the code is accompanied with a brief description.

2.2 Nonlinear Solver of Steady-State

```
# Code for solving the steady-state (with Tw as an endogenous variable)
function sys2! (FF,x,m,\alpha,\sigma,\lambda0, \iota,\rho,\dot{m},\dot{M},\gammaf,b_y,\xi,\delta,L,Pr,A,Ak,\phi)
     w=x[1]; wu=x[2]; wn=x[3]; k=x[4]; ku=x[5]; kn=x[6];
     \mu = x[7]; \theta = x[8]; \theta u = x[9]; \theta n = x[10]; \theta = x[11]; \theta = x[12];
     f\theta u = x[13]; q\theta u = x[14]; f\theta n = x[15]; q\theta n = x[16]; Tw = x[17];
     Lu=x[18]; Ln=x[19]; Fna = x[20]; Fnb = x[21]; \Psina = x[22];
     \Psi nb=x[23]; \Psi n=x[24]; y=x[25]; \partial yL=x[26]; \partial yk=x[27];
     yu = x[28]; \partial yLu = x[29]; yn = x[30]; \partial yLn = x[31]; \partial ykn = x[32]; \partial yku = x[33];
      \mu u = x[34]; \ \mu n = x[35]; \ \Psi u = x[36]; \ UAL = x[37]; \ g = x[38]; \ \lambda = x[39];
b=x[40]
     FF[1] = q\theta - (1+\theta^{(1)})^{(-1/1)}
                                            # probability of filling a vacancy
     FF[2] = f\theta - q\theta * \theta
                                                     # job finding probability
     FF[3] = L - f\theta/(\lambda + f\theta)
                                                     # steady-state employment
```

```
FF[4] = q\theta u - (1+\theta u^{(1)})^{(-1/1)} # probability of filling a vacancy in
 collective bargaining
                 FF[5] = f\theta u - q\theta u * \theta u
                                                                                                                                                                         # job finding probability in collective
bargaining
                FF[6] = Lu - f\theta u/(\lambda + f\theta u) # steady-state employment in collective
bargaining
                   FF[7] = q\theta n - (1+\theta n^{(1)})^{(-1/1)} # probability of filling a vacancy in
 individual bargaining
                FF[8] = f\theta n - g\theta n*\theta n
                                                                                                                                                                           # job finding probability in individual
 bargaining
                                                    FF[9] = UAL - (1-exp(\alpha^*(\sigma-1)^*(\dot{M}-\dot{m}))^*(exp(\alpha^*(\sigma-1)^*(\dot{m}+\dot{m}))-1)/
 (\exp(\alpha^*(\sigma-1)^*m)-1)) # marginal technological unemployment
                 FF[10] = \lambda - \lambda 0 - UAL
                                                                                                                                                                           # separation rate
                 FF[11] = q - \alpha * \dot{M}
                                                                                                                                                                              # growth rate
                FF[12] = Ln - f\theta n/(\lambda + f\theta n)
                                                                                                                                                                         # steady-state employment in individual
 bargaining
                 FF[13] = \Gamma na - \gamma f/(1+\gamma f) # Intrinsic bargaining power (case a)
               FF[14] = \Gamma nb - \gamma f^*(1-q\theta n)/(1+\gamma f+q\theta n^*(1-\gamma f)) # Intrinsic bargaining power (case
                 FF[15] = \Psi na - \Gamma na^*(\rho - g + \lambda + f\theta n)/(\rho - g + \lambda + \Gamma na^*f\theta n) # Actual bargaining power
 (case a)
                 FF[16] = \Psi nb - \Gamma nb^*(\rho - g + \lambda + f\theta n)/(\rho - g + \lambda + \Gamma nb^*f\theta n) # Actual bargaining power
 (case b)
                              FF[17] = \Psi n - ((Tw*\Gamma nb + \theta n*\Gamma na)/(\theta n+Tw))*(\rho-g+\lambda+f\theta n)/(\rho-g+\lambda+((Tw*\Gamma nb + \theta n*\Gamma na)/(\theta n+Tw))*(\rho-g+\lambda+f\theta n)/(\rho-g+\lambda+f\theta n)/(\rho-g+\lambda+f
 +θn*Γna)/(θn+Tw))*fθn) # Actual bargaining power (individual protocol)
                 FF[18] = \Psi u - \Gamma na*(\rho-g+\lambda+f\theta u)/(\rho-g+\lambda+ \Gamma na*f\theta u) # Actual bargaining power
 (collective protocol)
                               FF[19] = y -A*((1-m)^{(1/\sigma)} *(Ak*k)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-
 (\alpha^*(\sigma-1)))^(1/\sigma))^(\sigma/(\sigma-1)) # production function
                 FF[20] = \partial yk - (Ak*A)^{((\sigma-1)/\sigma)*(y/k)^{(1/\sigma)}*(1-m)^{(1/\sigma)}
                                                                                                                                                                                                                                                                                                     # Marginal
 prod. capital
                   FF[21] = \partial yL - (y - k*\partial yk)
                                                                                                                                                                                                                                                                                                          # Marginal
prod. labor
                         FF[22] = yu - A*((1-m)^{(1/\sigma)} *(Ak*ku)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/
 (\alpha^*(\sigma-1)))^(1/\sigma))^(\sigma/(\sigma-1)) # production function collective bargaining
                    FF[23] = \partial yku - (A*Ak)^{(\sigma-1)/\sigma} (yu/ku)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
Marginal prod. capital with collective bargaining
                   FF[24] = \partial yLu - (yu - ku*\partial yku)
Marginal prod. labor with collective bargaining
                         FF[25] = yn - A*((1-m)^{(1/\sigma)} *(Ak*kn)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/
 (\alpha^*(\sigma-1)))^(1/\sigma))^(\sigma/(\sigma-1)) # production function individual bargaining
                FF[26] = \partial y kn - (A*Ak)^{(\sigma-1)/\sigma} (yn/kn)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
                                                                                                                                                                                                                                                                                                                                                  #
Marginal prod. capital (equation (A1)) with individual bargaining
                   FF[27] = \partial y Ln - (yn - kn*\partial ykn)
                                                                                                                                                                                                                                                                                                                                                  #
Marginal prod. labor (equation (A1)) with individual bargaining
                   FF[28] = wn - (b + \Psi n*(\partial y Ln-b))
Hypothetical wage individual bargaining
                   FF[29] = wn - (\partial yLn - \xi^*(\rho - g + \lambda)/q\theta n)
```

```
Hypothetical labor demand with individual bargaining (these equations solve
\theta n.wn)
     FF[30] = wu - (b + \Psi u^*(\partial y L u - b + (\rho - q + \lambda)/(\rho - q) *(yu - \partial y L u)))
Hypothetical wage collective bargaining
     FF[31] = wu - (\partial_y Lu - \xi^*(\rho - g + \lambda)/q\theta u)
Hypothetical labor demand with collective bargaining (these equations solve
θu,wu)
     FF[32] = w - (Pr*wu + (1-Pr)*wn)
Aggregate wage
    FF[33] = w - (\partial yL - \xi^*(\rho - q + \lambda)/q\theta)
                                                                                           # Labor
demand equation
    FF[34] = \mu - ((\partial yL/w) - 1)
                                                                                         # markup
     FF[35] = \partial yk - \delta^*(1+\mu)/\phi
Capital market equilibrium
    FF[36] = \mu n - ((\partial y Ln/wn) - 1)
                                                                                         # markup
(individual bargaining)
     FF[37] = \mu u - ((\partial y Lu/wu) - 1)
                                                                                         # markup
(collective bargaining)
     FF[38] = \partial yku - \delta^*(1+\mu u)/\phi
Capital market equilibrium (collective bargaining)
     FF[39] = \partial y kn - \delta^*(1+\mu n)/\phi
Capital market equilibrium (individual bargaining)
     FF[40] = b - b y*y
                                                                                                  #
Steady-state unemployment benefits
end
```

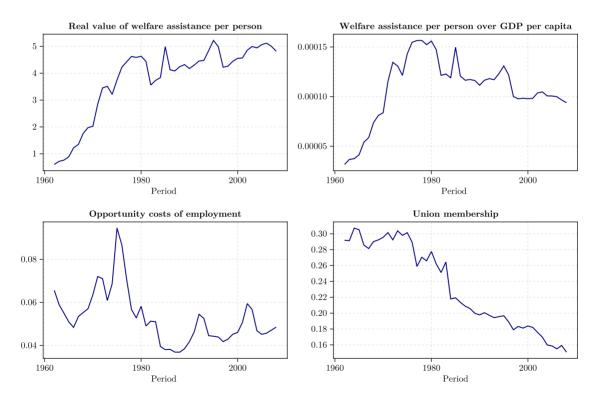
sys2! (generic function with 1 method)

2.3 Data

```
## Time-Varying Parameters
# Download the necessary data
data calibration = XLSX.readxlsx("/Users/juanjacobo/Documents/Documents/
JSCED_submission_2024/Data/data_in_calibrations.xlsx");
data_annual=data_calibration["annual!A1:AW83"];
data quarterly=data calibration["quarterly!A1:N290"]
data monthly=data calibration["monthly!A1:G962"]
## the data is annual from 1948 to 2008
time annual = convert(Array{Float64,1},data annual[12:end-11,1])
g penn = convert(Array{Float64,1},data_annual[12:end-11,5]) # growth rate penn
world data
unions = convert(Array{Float64,1},data_annual[12:end-11,2]) # union data
poor welfare = convert(Array{Float64,1},data annual[26:end-11,45]) # 1962-2010
poor_welfare_PTANF = convert(Array{Float64,1},data_annual[26:end-11,46])
1962-2010
poor welfare PTANFMEDICAID
```

```
convert(Array{Float64,1},data annual[26:end-11,47]) # 1962-2010
poor welfare ALL LTAXCREDITS
convert(Array{Float64,1},data annual[26:end-11,48]) # 1962-2010
automation_mann = convert(Array{Float64,1},data_annual[38:72,49]) # 1974-2008
## the data is quarterly from 1948 to 2008
time quarterly = collect(range(1948,length= 245, stop=2009))
b_chodorow_q =
                    convert(Array{Float64,1},data_quarterly[6:end-40,4])
Opportunity costs from Chodorow-Reich, & Karabarbounis
NRU q= convert(Array{Float64,1},data quarterly[10:end-40,5]) # Noncyclical
rate of unemployment
YL=convert(Array{Float64,1},data_quarterly[6:end-40,2])
                                                                     # GDP per
# Compute moving averages
b_chodorow =zeros(61)
NRU = [5.25; zeros(60)]
yl = zeros(61)
for i=1:61
    b\_chodorow[i]=mean(b\_chodorow\_q[1+(i-1)*4:i*4])
    yl[i]=mean(YL[1+(i-1)*4:i*4])
end
for i=1:60
    NRU[i+1] = mean(NRU q[1+(i-1)*4:i*4]) # Natural rate of unemployment
end
## the data is monthly from 1948 to 2009
time monthly = collect(range(1948,length= 733, stop=2009))
un civil m
                 convert(Array{Float64,1}, data monthly[110:842,5])
                                                                          civil
unemployment
vacancies m = convert(Array{Float64,1},data monthly[110:842,7]) # monthly
un c, vac=zeros(61), zeros(61), zeros(61)
for i=1:61
    un c[i]=mean(un civil m[1+(i-1)*12:i*12])
    vac[i]=mean(vacancies m[1+(i-1)*12:i*12])
\theta s = vac./un c # Labor market tightness
bcho_HP = HP(b_chodorow,6) # unemployment benefts (b)
unions HP = HP(unions, 6) # Union data
G_{hp} = HP(g_{penn,6}) # Penn world Table growth data
g ms = (G hp.+1).^(1/12).-1 # monthly
\dot{M}s = 1.0 * g_ms./\alpha; # Growth in the creation of new tasks
with_theme(theme_latexfonts()) do
    f = Figure(size = (900, 600))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
```

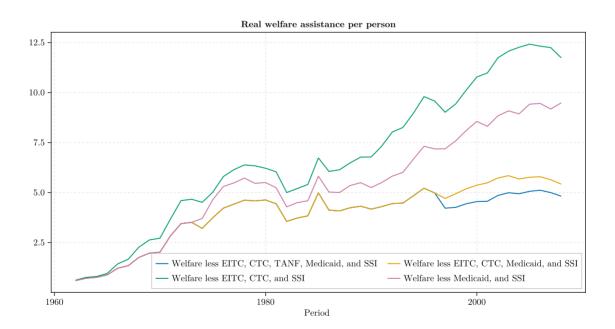
```
title = "Real value of welfare assistance per person",
    )
    lines!(ax, time_annual[15:end], poor_welfare, color = :navy)
    ax = Axis(f[1, 2],
    xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
    title = "Welfare assistance per person over GDP per capita",
)
 lines!(ax, time_annual[15:end], poor_welfare./yl[15:end], color = :navy)
  ax = Axis(f[2, 1],
  xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
  title = "Opportunity costs of employment",
lines!(ax, time annual[15:end], b chodorow[15:end], color = :navy)
ax = Axis(f[2, 2],
xlabel = "Period",xgridstyle = :dash, ygridstyle = :dash,
title = "Union membership",
lines!(ax, time annual[15:end], unions[15:end], color = :navy)
    end
```



The real value of welfare assistance per person is retrived from https://federalsafetynet.com/poverty-and-spending-over-the-years-2/. In particular, I compute Total welfare spending-Refundable tax credits (EITC and CTC) - SSI - Medicaid -TANF.

The differences generated by omitting refundable tax credits and Medicaid is presented in the following graph. This illustrates the transition of the welfare state in the United States from a need-based to a work-based system (Moffitt (2015); Parolin et al. (2023); Noble (1997)).

```
poor_measures=[poor_welfare
                               poor welfare PTANF
                                                    poor_welfare_PTANFMEDICAID
poor welfare ALL LTAXCREDITS]
with_theme(theme_latexfonts()) do
   f = Figure(size = (900, 500))
   ax = Axis(f[1, 1],
       xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Real welfare assistance per person",
     lines!(ax, time_annual[15:end],poor_measures[:,1], label = "Welfare less
EITC, CTC, TANF, Medicaid, and SSI")
     lines!(ax, time_annual[15:end],poor_measures[:,2], label = "Welfare less
EITC, CTC, Medicaid, and SSI")
     lines!(ax, time annual[15:end],poor measures[:,3], label = "Welfare less
EITC, CTC, and SSI")
     lines!(ax, time annual[15:end],poor measures[:,4], label = "Welfare less
Medicaid, and SSI")
   axislegend(; position = :rb, nbanks = 2, framecolor = (:grey, 0.5))
   f
   end
```



2.3.a Data on Productive Sectors

Following Basu & Foley (2013), I create a database of the labor share, markup, and capital-output ratio for sectors without questionable imputations of value-added. These sectors—which exclude agriculture and mining—are summarized in the following table.

BEA Industry Category	BLS Industry Category	
Utilities	Utilities	
Construction	Construction	
Manufacturing		
	Wood products	
	Nonmetallic mineral products	
	Primary metals	
	Fabricated metal products	
	Machinery	
	Computer and electronic products	
	Electrical equipment, appliances, and components	
	Motor vehicles, bodies and trailers, and parts	
	Other transportation equipment	
	Furniture and related products	
	Miscellaneous manufacturing	
	Food and beverage and tobacco products	
	Textile mills and textile product mills	
	Apparel and leather and allied products	
	Paper products	
	Printing and related support activities	
	Petroleum and coal products	
	Chemical products	
	Plastics and rubber products	
Wholesale trade	Wholesale trade	
Retail trade	Retail trade	
Transporting and warehousing		
	Air transportation	
	Rail transportation	

BEA	Industry	Category
-----	----------	----------

BLS Industry Category

Water transportation

Truck transportation

Transit and ground passenger transportation

Pipeline transportation

Other transportation and support activities

Warehousing and storage

Information

Publishing industries, except internet

Motion picture and sound recording industries

Broadcasting and telecommunications

Data processing and

The following code uses data from Eldridge et al. (2020) and BEA Fixed Assets Accounts Tables to construct the relevant variables in the paper.

```
#bea bls data is the data from Eldridge et al. (2020)
     = XLSX.readxlsx("/Users/juanjacobo/Documents/Documents/
data
JSCED_submission_2024/Data/bea_bls_data.xlsx")
data depre = XLSX.readxlsx("/Users/juanjacobo/Documents/Documents/
JSCED_submission_2024/Data/current_dep_assets.xlsx")
curr c cap
                       XLSX.readxlsx("/Users/juanjacobo/Documents/Documents/
               =
JSCED submission 2024/Data/cost assets.xlsx")
data_1947_1963=data["1947-1963!A2:W750"]
data_1963_2016=data["1963-2016!A2:W3404"]
full_sample=[data_1947_1963;data_1963_2016] # merges the time periods
data D=data depre["Sheet2!A1:U72"] # depreciation data
cost_assets=curr_c_cap["Sheet2!A1:U72"] # value of assets
# The following computes the empirical variables in the text using the
experimental BEA-BLS data
function economy lab shares(full sample,data D,cost assets)
   VA_t=zeros(17);
                          VA_t2=zeros(54); VA_t3=zeros(71);
                          VA_tz=zeros(54); la_c_t3=zeros(71); la_nc_t3=zeros(71);
   la_c_t=zeros(17);
                                                     la c t3=zeros(71);
   la_nc_t=zeros(17); la_nc_t2=zeros(54);
                           MA_t2=zeros(54); MA_t3=zeros(71)
KA_t2=zeros(54); KA_t3=zeros(71)
   MA t=zeros(17);
   KA t=zeros(17);
   rVA t=zeros(17);
                           rVA t2=zeros(54);
                                                   rVA t3=zeros(71);
   L t = zeros(17);
                                                   L t3=zeros(71);
                           L t2=zeros(54);
   h t=zeros(17);
                           h_t2=zeros(54);
                                                   h_t3=zeros(71);
   depret=sum(data D[2:end-1,i]./1 for i \in [5,6,7,8,9,10,11,16,19,20,21]).*1000
                      Kts=sum(cost_assets[2:end-1,i]./1
```

```
[5,6,7,8,9,10,11,16,19,20,21]).*1000
                                                                               i
=[6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,27,28,59,60,61]
        agr_VA=findall(x -> x ==i, full_sample[:,2])
        VA=full sample[agr VA,4].-full sample[agr VA,5]
        rVA=full_sample[agr_VA, 13].-full_sample[agr_VA, 14]
                                          LL
                                                        (full sample[agr VA, 20].
+full_sample[agr_VA,21]).*full_sample[agr_VA,22]
        VA t3=VA t3.+VA
        rVA t3=rVA t3.+rVA
        MA t3=MA t3.+full sample[agr VA,5]
        la_c=full_sample[agr_VA,11]
        la c t3=la c t3+la c
        la nc=full sample[agr VA, 12]
        h_nc=full_sample[agr_VA,22]
        la nc t3=la nc t3+la nc
        h t3=h nc+h t3
        L t3 = L t3 + LL
    for i=[2936,3740,5152,5758]
        agr_VA=findall(x -> x ==i, full_sample[:,2])
        VA=full sample[agr VA,4].-full sample[agr VA,5]
        rVA=full_sample[agr_VA, 13].-full_sample[agr_VA, 14]
        VA_t=VA_t.+VA
        rVA t=rVA t.+rVA
                                                        (full_sample[agr_VA, 20].
+full sample[agr VA,21]).*full sample[agr VA,22]
        MA_t=MA_t.+full_sample[agr_VA,5]
        la_c=full_sample[agr_VA,11]
        la c t=la c t+la c
        la nc=full sample[agr VA, 12]
        la_nc_t=la_nc_t+la_nc
        h_nc=full_sample[agr_VA,22]
        h t=h nc+h t
        L_t = L_t + LL
    for i=[29,30,31,32,33,34,35,36,37,38,39,40,51,52,57,58]
        agr VA=findall(x -> x ==i, full sample[:,2])
        VA=full_sample[agr_VA,4].-full_sample[agr_VA,5]
        rVA=full_sample[agr_VA, 13].-full_sample[agr_VA, 14]
                                          LL
                                                        (full_sample[agr_VA,20].
+full sample[agr VA,21]).*full sample[agr VA,22]
        VA t2=VA t2.+VA
        rVA_t2=rVA_t2.+rVA
        MA_t2=MA_t2.+full_sample[agr_VA,5]
        la c=full sample[agr VA, 11]
        la c t2=la c t2+la c
        la_nc=full_sample[agr_VA, 12]
```

```
la nc t2=la nc t2+la nc
       h nc=full sample[agr VA,22]
       h t2=h nc+h t2
       L_t2 = L_t2 + LL
   end
   la_c=[la_c_t;la_c_t2].+la_c_t3;
   la nc=[la nc t;la nc t2].+la nc t3;
   L_total =[L_t;L_t2].+L_t3
   h = [h t; h t2].+h t3;
   VA=[VA t; VA t2].+VA t3
    rVA= [rVA t;rVA t2].+rVA t3
   YL = VA./L_total
   PL = rVA./(h.*(la c.+la nc))
   MA=[MA t; MA t2].+MA t3
   KA = [KA_t; KA_t2].+KA_t3
   Cap=la nc[2:end].+la c[2:end].+depret.+MA[2:end]
   Cap2 = la nc[2:end].+la c[2:end].+depret
   Prof=(VA[2:end].-depret.-la nc[2:end].-la c[2:end])
   VA N=VA[2:end].-depret
         [(la nc)./VA (la nc.+la c)./VA
                                          [0; Prof./Cap2] [0; (la nc[2:end].
                       [0; Prof./(Kts.+depret)]
                                                 [0; (Kts.+depret)./VA[2:end]]
+la_c[2:end])./VA_N]
[0;(Prof.+depret.+la nc[2:end].+la c[2:end])./(VA[2:end])] [0;depret./(Kts.
+depret)]]
end
economy LS=economy lab shares(full sample,data D,cost assets)
LS NCP =economy LS[:,1] # labor share (unskilled labor)
LS C = economy LS[:,2].-LS NCP # labor share (skilled labor)
w_share = economy_LS[1:end,2] # labor share
\mu_{data} = economy_{LS[2:end,3]} # rate of return
r_data = economy_LS[2:end,5] # rate of profit
KY = economy LS[2:end,6] ; # capital-output ratio
dep_cap=economy_LS[2:end,end]; # depreciation of capital
```

2.4 Construction of Automation measure

Now. I use

$$1 - m_t^* = \left(\frac{K_t}{\varphi Y_t}\right)^{\text{BEA}} A^k \varphi^{1-\sigma} \left(\delta \left(1 + \mu_t^{\text{BEA-BLS}}\right)\right)^{\!\!\sigma},$$

to obtain the theoretical measure of automation.

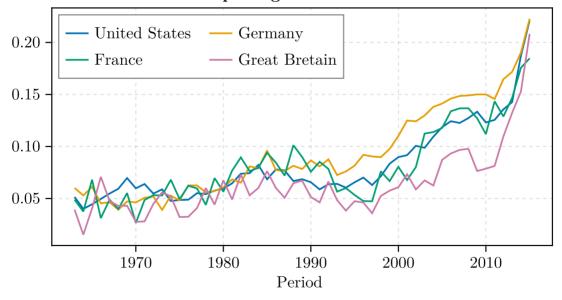
```
KYm=KY.*12 # remember that the calibration is based on monthly data dep_capm = (dep_cap.+1).^(1/12).-1 m_star =-((mean(dep_capm).*(\mu_data.+1)).^(\sigma)* (Ak*\phi)^(1-\sigma).*(KYm)).+1 mm=-m_star.+1;
```

Next, I construct the time series data in Hémous, Olsen, Zanella, & Dechezleprêtre (2025). Note that this is the same as Figure 2 in their paper. Here it is interesting to note that all countries have similar trajectories on the behavior of automation, yet only the Anglo-Saxon contries experienced rapid income inequality following the 1980s.

```
#automation_hemous.csv is obtained from hemous_2025.jl
merged_ctry=CSV.read("/Users/juanjacobo/Documents/Documents/
JSCED_submission_2024/Code/automation_hemous.csv", DataFrame)

with_theme(theme_latexfonts()) do
    f = Figure(size = (500, 300))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Task-displacing effect of automation",
    )
    lines!(ax, merged_ctry.Year,merged_ctry.Auto95_USA, label = "United States")
    lines!(ax, merged_ctry.Year,merged_ctry.Auto_95_Germany, label = "Germany")
    lines!(ax, merged_ctry.Year,merged_ctry.Auto_95_France, label = "France")
    lines!(ax, merged_ctry.Year,merged_ctry.Auto_95_GB, label = "Great Bretain")
    axislegend(; position = :lt, nbanks = 2, framecolor = (:grey, 0.95))
    f
end
```

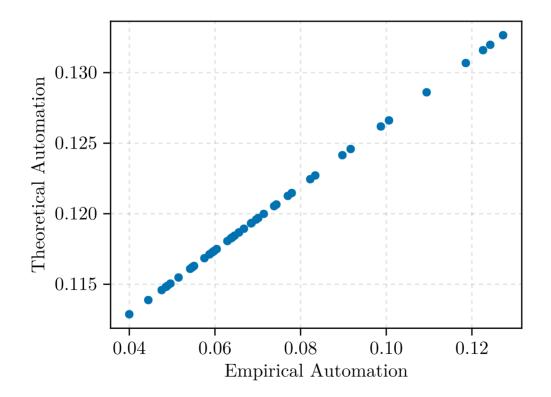
Task-displacing effect of automation



With this result, I now make the theoretical and empirical measures of automation comparable.

```
## Automation from Hemous 2025. Auto95 US
Mech=merged_ctry.Auto95_USA # data 1963:2015
Xmech=[ones(46) Mech[1:end-7]]

M1 = Xmech*(inv(Xmech'Xmech)*(Xmech'mm[16:end-9]))
mM2=-M1.+1;
f = with_theme(theme_latexfonts()) do
    fig = Figure(size = (400, 300))
    ax = Axis(fig[1, 1],
        xlabel = "Empirical Automation",
        xgridstyle = :dash,
        ygridstyle = :dash,
        ylabel = "Theoretical Automation"
    )
    scatter!(ax, Mech[1:end-7], M1)
    fig # <-- return the figure explicitly!
end
display(f)</pre>
```



```
CairoMakie.Screen{IMAGE}
```

2.5 Model Calibration

Now that we have all the data we need. We proceed to solve the OLS estimators in equation (25) in the main text. For this purpose, I first solve the steady-state assuming that T^w perfectly tracks the noncyclical rate of unemployment. This is presented in the following code.

```
# Set the initial values using
### This code sets the initial values.
function init_v(m,\alpha,\sigma,\lambda0,\iota,\rho,\dot{m},\dot{M},\gammaf,b_y,\xi,\delta,Tw,Pr,A,Ak)
                         k0=10.95; ku0=11.3; kn0=10.65; \theta0=0.7; \thetau0=0.016; \thetan0=0.72; g=\alpha*M;
= (1 - \exp(\alpha^*(\sigma - 1)^*(\dot{M} - \dot{m}))^*(\exp(\alpha^*(\sigma - 1)^*(m + \dot{m})) - 1)/(\exp(\alpha^*(\sigma - 1)^*m) - 1));
                                                                                                                                                                                                                                                                                                                                                                                         \lambda = \lambda 0 +
UAL:
                              q\theta\theta = (1+\theta\theta^{(1)})^{(-1/1)}; f\theta\theta = q\theta\theta * \theta\theta ;
                                                                                                                                                                                                                                                         q\theta u\theta = (1+\theta u\theta^{(1)})^{(-1/1)}; f\theta u\theta =
q\theta u0*\theta u0; q\theta n0=(1+\theta n0^{(1)})^{-1/1}; f\theta n0=q\theta n0*\theta n0; L0=f\theta 0/(f\theta 0+\lambda); Lu0=f\theta u0/(f\theta 0+\lambda); Lu0=f\theta 
(f\theta u \theta + \lambda);
                 Ln0=f0n0/(f0n0+\lambda); \Gamma na0 = \gamma f/(1+\gamma f); \Gamma nb0 = \gamma f^*(1-q0n0)/(1+\gamma f+q0n0^*(1-\gamma f));
                     Ψna0=Γna0*(ρ-g+λ+fθn0)/(ρ-g+λ+ Γna0*fθn0);
                     \Psi nb0 = \Gamma nb0*(\rho - q + \lambda + f\theta n0)/(\rho - q + \lambda + \Gamma nb0*f\theta n0);
                     \Psi 0 = ((\Gamma na0*\theta 0 + \Gamma nb0*Tw)/(Tw+\theta 0))*(\rho - g + \lambda + f \theta n0)/(\rho - g + \lambda + ((\Gamma na0*\theta 0 + \Gamma nb0*Tw)/(Tw+\theta 0))*(\rho - g + \lambda + f \theta n0)/(F -
(Tw+\theta0))*f\thetan0);
                     \Psi u0 = \Gamma na0*(\rho - g + \lambda + f\theta u0)/(\rho - g + \lambda + \Gamma na0*f\theta u0);
                    y\theta = A*((1-m)^{(1/\sigma)} *(Ak*k\theta)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/(\alpha*(\sigma-1)))^{(1/\sigma)}
\sigma))^(\sigma/(\sigma-1))
                     b = b y*y0
                     \partial y k \theta = (Ak*A)^{((\sigma-1)/\sigma)*(y \theta/k \theta)^{(1/\sigma)}*(1-m)^{(1/\sigma)}
                     \partial yL0 = y0 - k0*\partial yk0
                    yu\theta = A*((1-m)^{(1/\sigma)} *(Ak*ku\theta)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/(\alpha*(\sigma-1)))^{(1/\sigma)}
\sigma))^(\sigma/(\sigma-1))
                    yn\theta = A^*((1-m)^{(1/\sigma)} *(Ak^*kn\theta)^{((\sigma-1)/\sigma)} + ((exp(\alpha^*(\sigma-1)^*m)^{-1})/(\alpha^*(\sigma-1)))^{(1/\sigma)}
\sigma))^(\sigma/(\sigma-1))
                     \partial y ku0 = (Ak*A)^{(\sigma-1)/\sigma} (yu0/ku0)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
                     \partial y kn0 = (Ak*A)^{((\sigma-1)/\sigma)*}(yn0/kn0)^{(1/\sigma)}*(1-m)^{(1/\sigma)}
                     \partial y Lu0 = yu0 - ku0*\partial y ku0
                     \partial y Ln0 = yn0 - kn0*\partial y kn0
                     wu0=\partial yLu0- \xi*(\rho-q+\lambda)/q\theta u0
                     wn0=\partial yLn0- \xi^*(\rho-g+\lambda)/q\thetan0
                     w\theta = \partial y L\theta - \xi^* (\rho - g + \lambda) / q\theta\theta
                     \mu u\theta = (\partial y Lu\theta / wu\theta) - 1
                     \mun0=(\partialyLn0/wn0)-1
                     \mu 0 = (\partial y L 0 / w 0) - 1
                     return [w0, wu0, wn0, k0, ku0, kn0, μ0, θ0, θu0, θn0, fθ0, qθ0, fθu0,
                     qθu0, fθn0, qθn0, L0, Lu0, Ln0, Γna0, Γnb0, Ψna0, Ψnb0, Ψ0, y0, ayL0,
                     \partial y k0, y u0, \partial y L u0, y n0, \partial y L n0, \partial y k n0, \partial y k u0, \mu u0, \mu n0, \Psi u0, UAL, q, \lambda, b
                     end
                     # upper bounds
```

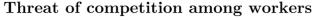
```
ubt=[50,50,50,50,50,50,50,50,50,50,
    1,1,1,1.0001,1,1,6.5,1,1,1,1,1,1,1,1,
    ## Calibrate steady-state values assuming you know the NRU
function inverse calibration(Pr,m,b y,L,M,γf,λ0)
    x0=init v(m,\alpha,\sigma,\lambda 0,\iota,\rho,\dot{m},\dot{M},\gamma f,b,\gamma,\xi,\delta,\frac{1.5}{1.5},Pr,A,Ak)
    x0[17]=1.75 # this is just an initial guess
                                                                             ->sys2!
                                                   nlboxsolve((FF,x)
                               rlb
(FF,x,m,\alpha,\sigma,\lambda 0,\iota,\rho,\dot{m},\dot{M},\gamma f,b,y,\xi,\delta,L,Pr,A,Ak,\phi),
  x0, lbt, ubt, xtol=1e-4, ftol=1e-4)
  sol =rlb.zero
 # aggregate wage; capital; rate of exploitation; labor-market tightness;
# rel. mobility of labor; output; worker power
  w=sol[1]; k=sol[4]; \mu = sol[7]; \theta = sol[8]; Tw = sol[17]; y = sol[25]; \Psi n
=sol[24];b=sol[40]
    return [w;k;μ;θ;Tw;y;Ψn;b]
L NRU=0.01*(-NRU.+100) # natural rate of unemployment
results 5H=zeros(8,46)
## Hypothesis: Changes in labor institutions and technical change with NRU given
for i=1:46
 results 5H[:,i]=inverse calibration(unions HP[i+15], mM2[i], bcho HP[i+15],
L_NRU[i+15], \dot{M}s[i+15], \gamma f, \lambda 0)
end
# Results
Ωs5H=results 5H[1,:]./results 5H[6,:] # Labor share
kys5H= results_5H[2,:]./results_5H[6,:] * (1/\varphi) # capital-output
Vs5H = results_5H[4,:].*NRU[16:end]./100 # vacancy rate
                              # Threat of competition
tsw5H = results 5H[5,:]
\mus5H = results 5H[3,:]
                                        # markup
r5H = (μs5H./(μs5H.+1))./kys5H
Ψn5H = results 5H[7,:]
                                      # rate of profit
\Psin5H = results 5H[7,:]
                                        # Worker power
\theta5sH = results 5H[4,:];
                                        # labor market tightness
```

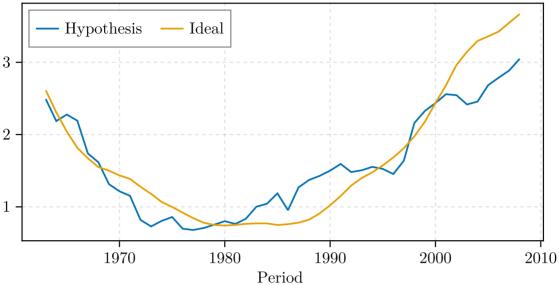
2.5.a Threat of Competition Among Workers

Given the ``ideal'' value of the threat of competition among workers obtained above, I now check the hypothesis that the threat of competition is largely determined by what I referred to as the allowed for by civil society.

```
\Psi nb = x[23]; \Psi n = x[24]; y = x[25]; \partial yL = x[26]; \partial yk = x[27];
                    yu = x[28]; \partial yLu = x[29]; yn = x[30]; \partial yLn = x[31]; \partial ykn = x[32]; \partial yku = x[33];
                         \mu u = x[34]; \ \mu n = x[35]; \ \Psi u = x[36]; \ UAL = x[37]; \ g = x[38]; \ \lambda = x[39];
b=x[40]
                    FF[1] = q\theta - (1+\theta^{(1)})^{(-1/1)}
                    FF[2] = f\theta - q\theta * \theta
                    FF[3] = L - f\theta/(\lambda + f\theta)
                    FF[4] = q\theta u - (1+\theta u^{(1)})^{(-1/\iota)}
                    FF[5] = f\theta u - g\theta u * \theta u
                    FF[6] = Lu - f\theta u/(\lambda + f\theta u)
                    FF[7] = q\theta n - (1+\theta n^{(1)})^{(-1/1)}
                    FF[8] = f\theta n - q\theta n*\theta n
                FF[9] = UAL - (1 - \exp(\alpha^*(\sigma - 1)^*(\dot{M} - \dot{m}))^*(\exp(\alpha^*(\sigma - 1)^*(\dot{m} + \dot{m})) - 1) / (\exp(\alpha^*(\sigma - 1)^*m) - 1))
                    FF[10] = \lambda - \lambda 0 - UAL
                    FF[11] = g - \alpha * \dot{M}
                    FF[12] = Ln - f\theta n/(\lambda + f\theta n)
                    FF[13] = \Gamma na - \gamma f/(1+\gamma f)
                    FF[14] = \Gamma nb - \gamma f^*(1-q\theta n) / (1+\gamma f+q\theta n^*(1-\gamma f))
                    FF[15] = \Psi na - \Gamma na*(\rho - g + \lambda + f\theta n)/(\rho - g + \lambda + \Gamma na*f\theta n)
                    FF[16] = \Psi nb - \Gamma nb^*(\rho - g + \lambda + f\theta n) / (\rho - g + \lambda + \Gamma nb^* f\theta n)
                                    FF[17] = \Psi n - ((Tw*\Gamma nb + \theta n*\Gamma na)/(\theta n+Tw))*(\rho - g + \lambda + f\theta n)/(\rho - g + \lambda + ((Tw*\Gamma nb + \theta n+Tw)))*(\rho - g + \lambda + f\theta n)/(\rho - 
+\theta n*\Gamma na)/(\theta n+Tw))*f\theta n)
                    FF[18] = \Psi u - \Gamma na*(\rho - q + \lambda + f\theta u)/(\rho - q + \lambda + f\theta u)
                                                                                                                                                                                                                                Γna*fθu)
                                    FF[19] = y -A*((1-m)^{(1/\sigma)} *(Ak*k)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/
(\alpha^*(\sigma-1))^{(1/\sigma)}^{(\sigma-1)}
                    FF[20] = \partial yk - (Ak*A)^{((\sigma-1)/\sigma)*}(y/k)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
                    FF[21] = \partial yL - (y - k*\partial yk)
                            FF[22] = yu - A*((1-m)^{(1/\sigma)} *(Ak*ku)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/
(\alpha^*(\sigma-1))^{(1/\sigma)}^{(\sigma/(\sigma-1))}
                    FF[23] = \partial y ku - (A*Ak)^{(\sigma-1)/\sigma} (yu/ku)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
                    FF[24] = \partial yLu - (yu - ku*\partial yku)
                            FF[25] = yn - A*((1-m)^{(1/\sigma)} *(Ak*kn)^{((\sigma-1)/\sigma)} + ((exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*m)-1)/(exp(\alpha*(\sigma-1)*
(\alpha^*(\sigma-1))^{(1/\sigma)}^{(\sigma/(\sigma-1))}
                    FF[26] = \partial ykn - (A*Ak)^{(\sigma-1)/\sigma} * (yn/kn)^{(1/\sigma)} * (1-m)^{(1/\sigma)}
                    FF[27] = \partial y Ln - (yn - kn*\partial ykn)
                    FF[28] = wn - (b + \Psi n^*(\partial y Ln - b))
                    FF[29] = wn - (\partial yLn - \xi^*(\rho - g + \lambda)/q\theta n)
                    FF[30] = wu - (b + \Psi u^*(\partial y Lu - b + (\rho - g + \lambda)/(\rho - g) *(yu - \partial y Lu)))
                    FF[31] = wu - (\partial yLu - \xi^*(\rho - g + \lambda)/q\theta u)
                    FF[32] = w - (Pr*wu + (1-Pr)*wn)
                    FF[33] = w - (\partial yL - \xi^*(\rho - g + \lambda)/q\theta)
                    FF[34] = \mu - ((\partial yL/w) - 1)
                    FF[35] = \partial yk - \delta^*(1+\mu)/\phi
                    FF[36] = \mu n - ((\partial y Ln/wn) - 1)
                    FF[37] = \mu u - ((\partial y Lu/wu) - 1)
                    FF[38] = \partial yku - \delta^*(1+\mu u)/\phi
                    FF[39] = \partial ykn - \delta^*(1+\mu n)/\phi
                    FF[40] = b - b_y*y
```

```
end
# lower bounds
# upper bounds
ubd=[50,50,50,50,50,50,50,50,50,50,
1,1,1,1.0001,1,1,1,1,1,1,1,1,1,1,1,1,
function inverse calibrationd(Pr,m,b y,Tw,\dot{M},\gamma f,\lambda \theta,\phi)
x0d=init_v(m,\alpha,\sigma,\lambda0,\iota,\rho,\dot{m},\dot{M},\gamma f,b_y,\xi,\delta,Tw,Pr,A,Ak)
rlb
                                                                       ->sys2d!
                                     nlboxsolve((FF,x)
(FF,x,m,\alpha,\sigma,\lambda 0,\iota,\rho,\dot{m},\dot{M},\gamma f,b,y,\xi,\delta,Tw,Pr,A,Ak,\phi),
x0d, lbd, ubd, xtol=1e-4, ftol=1e-4)
sol =rlb.zero
w=sol[1]; k=sol[4]; \mu = sol[7]; \theta = sol[8]; L = sol[17]; y = sol[25]; \Psi n = sol[24];
b=sol[40]
return [w;k;\mu;\theta;L;y;\Psin;b]
# Estimate equation (25)
X_{tw}=[ones(46) log.(((poor_welfare[1:end-1]))) log.(yl[15:end-1])]
\beta tw=inv(X tw'X tw)*(X tw'log.(tsw5H))
tsw_indiriect=X_tw*β_tw# sol[1].*cdf(Normal(0,1), X_tw*β_b)
with theme(theme latexfonts()) do
    f = Figure(size = (500, 300))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Threat of competition among workers",
    lines!(ax,time annual[16:end],exp.(tsw indiriect), label = "Hypothesis")
    lines!(ax, time_annual[16:end],tsw5H, label = "Ideal")
    axislegend(; position = :lt, nbanks = 2, framecolor = (:grey, 0.95))
    f
    end
```



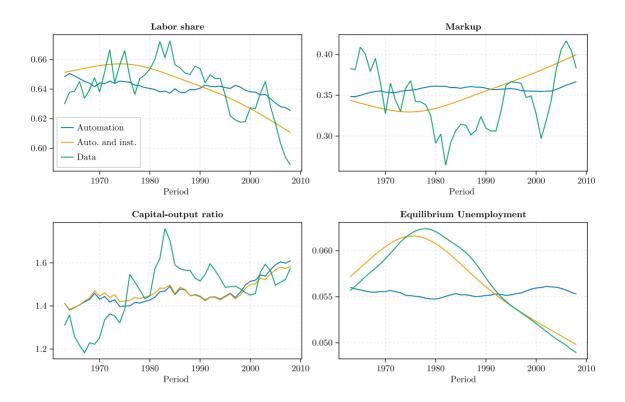


2.5.b Calibration Details and Results

With this result, I now present the code generating the results of the automation and institutions and automation hypotheses in the main text.

```
# Automation alone: Task-displacing and labor-augmenting technical change
results 1dH=zeros(8,46)
for i=1:46
    results 1dH[:,i]=inverse calibrationd(mean(unions HP[16:end]),mM2[i],
    mean(bcho_HP[16:end]), mean(tsw5H), \dot{M}s[i+15], \gammaf, \lambda0, \phi)
end
# Automation and labor augmneting technical change
OsdH=results_1dH[1,:]./results_1dH[6,:]
kysdH= results_1dH[^2,:]./results_1dH[^6,:] * (^1/^\phi)
VsdH = results_1dH[4,:].*(-results_1dH[5,:].+1)
UsdH = -results 1dH[5,:].+1
μsdH = results_1dH[3,:]
θsdH= results_1dH[4,:]
rsdH = (12*\mu sdH./(\mu sdH.+1))./kysdH
YndH= results_1dH[7,:];
results_2dH=zeros(8,46)
# Institutions and automation
for i=1:46
   results_2dH[:,i]=inverse_calibrationd(unions[i+15],mM^2[i],b_chodorow[i+15],
    exp.(tsw_indiriect)[i],\dot{M}s[i+15],\gammaf,\lambda0,\phi)
end
```

```
\Omegasd2H=results 2dH[1,:]./results 2dH[6,:]
kysd2H= results 2dH[2,:]./results 2dH[6,:] * (1/\phi)
Vsd2H = results_2dH[4,:].*(-results_2dH[5,:].+1)
Usd2H = -results_2dH[5,:].+1
\mu sd2H = results 2dH[3,:]
\thetasd2H= results 2dH[4,:]
rsd2H = (12*\mu sd2H./(\mu sd2H.+1))./kysd2H
Ψnd2H= results_2dH[7,:];
# Graphs
with_theme(theme_latexfonts()) do
    f = Figure(size = (900, 600))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Labor share",
    lines!(ax, time annual[16:end], ΩsdH, label="Automation")
       lines!(ax, time annual[16:end], HP(\Omega sd 2H, 1000), label="Auto. and inst.")
          lines!(ax, time annual[16:end], w share[16:end-10], label="Data")
           axislegend(; position = :lb, nbanks = 1, framecolor = (:gray, 0.5))
    ax = Axis(f[1, 2],
    xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
    title = "Markup",
lines!(ax, time annual[16:end], µsdH)
       lines!(ax, time annual[16:end], HP(\u03bcsd2H,1000))
          lines!(ax, time_annual[16:end], μ_data[17:end-8])
  ax = Axis(f[2, 1],
 xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
 title = "Capital-output ratio",
lines!(ax, time annual[16:end], kysdH./12)
       lines!(ax, time annual[16:end], kysd2H./12)
          lines!(ax, time_annual[16:end],KY[16:end-9])
ax = Axis(f[2, 2],
xlabel = "Period",xgridstyle = :dash, ygridstyle = :dash,
title = "Equilibrium Unemployment",
lines!(ax, time annual[16:end], UsdH)
       lines!(ax, time_annual[16:end], HP(Usd2H,1000))
          lines!(ax, time annual[16:end], NRU[16:end]./100)
    f
    end
```



3 Robustness Results

In this section, I use the 90th percentile data in Hémous, Olsen, Zanella, & Dechezleprêtre (2025), the automation measure in Mann & Püttmann (2023), and different measures of welfare policy as alternatives to the automation and institutions hypothesis in the main text. Here, I only contrast the baseline results with the alternatives explored below.

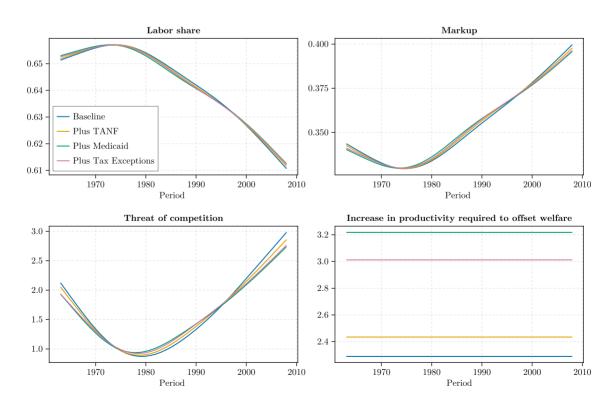
3.1 Alternative Measures of Welfare

The following graph compares the baseline results of the main paper with the different alternatives of welfare. The key results of the paper remain unchanged. The only critical variation is that —as expected—the increase in productivity required to offset the effect of welfare on labor supply is lower in the baseline measure. This result is reasonable because the baseline measure only computes welfare assistance that primarily targets the poor, making it easier to induce people to work when there is less help available to lift them out of poverty.

```
# Instead of using
poor_measures
function
alternative_measures(unions,mM2,b_chodorow,poor_measure,yl,Ms,γf,λ0,φ,tsw)
X_tw=[ones(46) log.(((poor_measure[1:end-1]))) log.(yl[15:end-1])]
β_tw=inv(X_tw'X_tw)*(X_tw'log.(tsw))
tsw_indiriect=X_tw*β_tw
results_alt=zeros(8,46)
```

```
# Institutions and automation
for i=1:46
    results alt[:,i]=inverse calibrationd(unions[i+15],mM2[i],b chodorow[i+15],
    exp.(tsw_indiriect)[i],\dot{M}s[i+15],\gammaf,\lambda0,\phi)
end
Ω=results alt[1,:]./results alt[6,:]
ky= (results alt[2,:]./results alt[6,:] * (1/\varphi))./12
V = results_alt[4,:].*(-results_alt[5,:].+1)
U = -results_alt[5,:].+1
\mu = results alt[3,:]
\theta= results alt[4,:]
return \Omega, \mu, ky, U, exp. (tsw indiriect), \beta tw[3]/\beta tw[2]
end
sol plus TANF=alternative measures(unions,mM2,b chodorow,poor measures[:,2],
yl,\dot{M}s,\gammaf,\lambda0,\phi,tsw5H)
sol plus Medicaid=alternative measures(unions,mM2,b chodorow,poor measures[:,3],
yl,\dot{M}s,\gammaf,\lambda0,\phi,tsw5H)
sol_plus_tax=alternative_measures(unions,mM2,b_chodorow,poor_measures[:,4],
yl,\dot{M}s,\gammaf,\lambda0,\phi,tsw5H);
with_theme(theme_latexfonts()) do
    f = Figure(size = (900, 600))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Labor share",
       lines!(ax, time annual[16:end], HP(\Omega sd2H,1000), label="Baseline")
         lines!(ax, time annual[16:end], HP(sol plus TANF[1],1000), label="Plus
TANF")
                 lines!(ax, time annual[16:end], HP(sol plus Medicaid[1],1000),
label="Plus Medicaid")
          lines!(ax, time_annual[16:end], HP(sol_plus_tax[1],1000), label="Plus
Tax Exceptions")
           axislegend(; position = :lb, nbanks = 1, framecolor = (:grey, 0.95))
    ax = Axis(f[1, 2],
    xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
    title = "Markup",
)
       lines!(ax, time annual[16:end], HP(\musd2H,1000))
          lines!(ax, time annual[16:end], HP(sol plus TANF[2],1000), label="Plus
TANF")
                 lines!(ax, time_annual[16:end], HP(sol_plus_Medicaid[2],1000),
label="Plus Medicaid")
          lines!(ax, time annual[16:end], HP(sol plus tax[2],1000), label="Plus
Tax Exceptions")
```

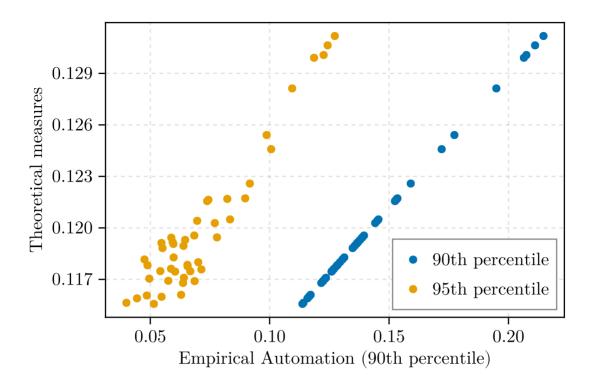
```
ax = Axis(f[2, 1],
  xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
  title = "Threat of competition",
)
       lines!(ax, time annual[16:end], HP(exp.(tsw indiriect),1000))
         lines!(ax, time_annual[16:end], HP(sol_plus_TANF[5],1000), label="Plus
TANF")
                lines!(ax, time_annual[16:end], HP(sol_plus_Medicaid[5],1000),
label="Plus Medicaid")
         lines!(ax, time annual[16:end], HP(sol plus tax[5],1000), label="Plus
Tax Exceptions")
ax = Axis(f[2, 2],
xlabel = "Period",xgridstyle = :dash, ygridstyle = :dash,
title = "Increase in productivity required to offset welfare",
       lines!(ax, time_annual[16:end], -ones(46).*(\beta_tw[3]/\beta_tw[2]))
                  lines!(ax, time annual[16:end], -ones(46).*sol plus TANF[6],
label="Plus TANF")
             lines!(ax, time_annual[16:end], -ones(46).*sol_plus_Medicaid[6],
label="Plus Medicaid")
         lines!(ax, time_annual[16:end], -ones(46).*sol_plus_tax[6],label="Plus
Tax Exceptions")
    f
    end
```



3.2 90th percentile automation data in Hémous, Olsen, Zanella, & Dechezleprêtre (2025)

The following plot repeats the same code of the main text, replacing the automation measure using the 95th percentile for the 90th percentile measure in Hémous, Olsen, Zanella, & Dechezleprêtre (2025). The code and results are depicted in the following graph.

```
merged ctry=CSV.read("/Users/juanjacobo/Documents/Documents/
JSCED_submission_2024/Code/automation_hemous90.csv", DataFrame)
## Automation from Hemous 2025. Auto95 US
Mech90=merged ctry.Auto95 USA # data 1963:2015
Xmech=[ones(46) Mech90[1:end-7]]
\hat{M}90 = Xmech*(inv(Xmech'Xmech)*(Xmech'mm[16:end-9]))
m\hat{M}90 = -\hat{M}90.+1;
f = with_theme(theme_latexfonts()) do
    fig = Figure(size = (450, 300))
    ax = Axis(fig[1, 1],
        xlabel = "Empirical Automation (90th percentile)",
        xgridstyle = :dash,
        ygridstyle = :dash,
        ylabel = "Theoretical measures"
    scatter!(ax, Mech90[1:end-7], M90, label="90th percentile")
    scatter!(ax, Mech[1:end-7], M90, label="95th percentile")
    axislegend(; position = :rb, nbanks = 1, framecolor = (:grey, 0.95))
    fig # <-- return the figure explicitly!</pre>
end
display(f)
```

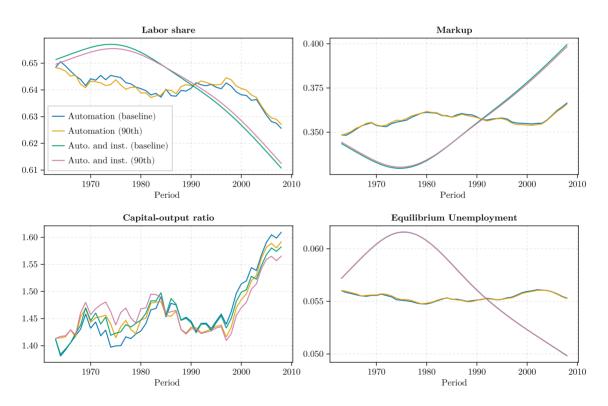


CairoMakie.Screen{IMAGE}

```
# Step 1: Estimate ideal Tw with new measure of automation
results H90=zeros(8,46)
## Hypothesis: Changes in labor institutions and technical change with NRU given
for i=1:46
 results_H90[:,i]=inverse_calibration(unions_HP[i+15],mM90[i],bcho_HP[i+15],
 L NRU[i+15], \dot{M}s[i+15], \gammaf, \lambda0)
end
# Results
ΩsH90=results_H90[1,:]./results_H90[6,:] # Labor share
kysH90= results_H90[2,:]./results_H90[6,:] * (1/\varphi) # capital-output
tswH90 = results H90[5,:]
                                             # Threat of competition
                                             # markup
\musH90 = results_H90[3,:]
# Steap 2: Use OLS estimators of welfare policy
# Estimate equation (25)
X_{tw90=[ones(46) log.(((poor_welfare[1:end-1]))) log.(yl[15:end-1])]
\beta_{\text{tw}}=\text{inv}(X_{\text{tw}}X_{\text{tw}})*(X_{\text{tw}}\log.(tswH90))
tsw_indiriect90=X_tw90*β_tw90
# Automation alone: Task-displacing and labor-augmenting technical change
```

```
results 1dH90=zeros(8,46)
for i=1:46
    results 1dH90[:,i]=inverse calibrationd(mean(unions HP[16:end]),mM90[i],
    mean(bcho_HP[16:end]), mean(tswH90), Ms[i+15], \gamma f, \lambda 0, \phi)
end
# Automation and labor augmneting technical change
ΩsdH90=results 1dH90[1,:]./results 1dH90[6,:]
kysdH90= results_1dH90[2,:]./results_1dH90[6,:] * (1/\phi)
UsdH90 = -results 1dH90[5,:].+1
\mu sdH90 = results 1dH90[3,:]
results_2dH90=zeros(8,46)
# Institutions and automation
for i=1:46
results 2dH90[:,i]=inverse calibrationd(unions[i+15],mM90[i],b chodorow[i+15],
    exp.(tsw indiriect90)[i],\dot{M}s[i+15],\gammaf,\lambda0,\varphi)
Ωsd2H90=results_2dH90[1,:]./results_2dH90[6,:]
kysd2H90= results 2dH90[2,:]./results 2dH90[6,:] * (1/<math>\phi)
Usd2H90 = -results_2dH90[5,:].+1
\mu sd2H90 = results 2dH90[3,:]
# Graphs
with theme(theme latexfonts()) do
    f = Figure(size = (900, 600))
    ax = Axis(f[1, 1],
        xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
        title = "Labor share",
    lines!(ax, time_annual[16:end], ΩsdH, label="Automation (baseline)")
          lines!(ax, time annual[16:end], ΩsdH90, label="Automation (90th)")
        lines!(ax, time annual[16:end], HP(\Omega sd2H,1000), label="Auto. and inst.
(baseline)")
       lines!(ax, time annual[16:end], HP(\Omegasd2H90,1000), label="Auto. and inst.
(90th)")
           axislegend(; position = :lb, nbanks = 1, framecolor = (:gray, 0.5))
    ax = Axis(f[1, 2],
    xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
    title = "Markup",
lines!(ax, time annual[16:end], µsdH, label="Automation (baseline)")
          lines!(ax, time_annual[16:end], µsdH90, label="Automation (90th)")
        lines!(ax, time_annual[16:end], HP(\musd2H,1000), label="Auto. and inst.
(90th)")
       lines!(ax, time annual[16:end], HP(\musd2H90,1000), label="Auto. and inst.
(90th)")
```

```
ax = Axis(f[2, 1],
 xlabel = "Period ",xgridstyle = :dash, ygridstyle = :dash,
  title = "Capital-output ratio",
lines!(ax, time annual[16:end], kysdH./12)
lines!(ax, time annual[16:end], kysdH90./12)
       lines!(ax, time annual[16:end], kysd2H./12)
           lines!(ax, time_annual[16:end], kysd2H90./12)
ax = Axis(f[2, 2],
xlabel = "Period",xgridstyle = :dash, ygridstyle = :dash,
title = "Equilibrium Unemployment",
)
lines!(ax, time annual[16:end], UsdH)
 lines!(ax, time annual[16:end], UsdH90)
       lines!(ax, time_annual[16:end], HP(Usd2H,1000))
         lines!(ax, time annual[16:end], HP(Usd2H90,1000))
    f
    end
```

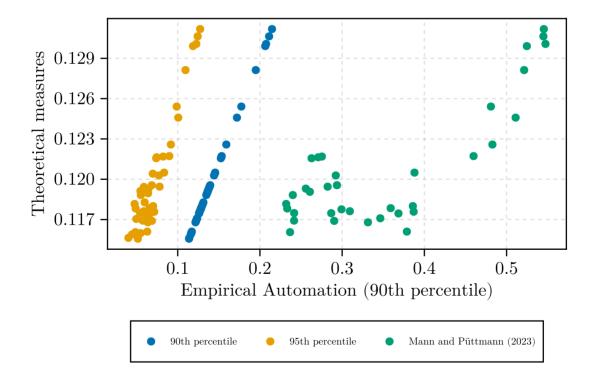


3.3 Automation data in Mann & Püttmann (2023)

I complete the Online Appendix with the data of the automation measure in Mann & Püttmann (2023). The results in the figure below show that all automation variables are strongly correlated,

though the measure in Mann & Püttmann (2023) has a smaller slope, meaning that automation in this case will be less significant than before.

```
MechMann=automation mann # data 1974-2008
Xmech=[ones(35) MechMann]
MMann = Xmech*(inv(Xmech'Xmech)*(Xmech'mm[27:end-9]))
m\hat{M}Mann = -\hat{M}Mann + 1;
M90[11:end]
f = with_theme(theme_latexfonts()) do
    fig = Figure(size = (450, 300))
    ax = Axis(fig[1, 1],
        xlabel = "Empirical Automation (90th percentile)",
        xgridstyle = :dash,
        ygridstyle = :dash,
        ylabel = "Theoretical measures"
    scatter!(ax, Mech90[1:end-7], M90, label="90th percentile")
    scatter!(ax, Mech[1:end-7], M90, label="95th percentile")
        scatter!(ax, MechMann, M90[12:end], label="Mann and Püttmann (2023)")
        Legend(fig[2, 1], ax; orientation = :horizontal, labelsize = 8)
    fig # <-- return the figure explicitly!</pre>
end
display(f)
```



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