

Tarea 3

$$\begin{bmatrix} \ddot{d} \\ \dot{d} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{b}{m} \end{bmatrix} \begin{bmatrix} d \\ \dot{d} \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{a}{m} \end{bmatrix} p.$$

$$x_1 = d$$

$$x_2 = \dot{d}$$

$$x_2 = \dot{x}_1 \rightarrow \dot{d} = \dot{d}$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{pmatrix} d \\ \dot{d} \end{pmatrix} + 0 \cdot p.$$

$$\ddot{d} = -\frac{b}{m} \dot{d} - \frac{k}{m} d + \frac{a}{m} p.$$

Saco el punto de eq

$$0 = -\frac{0.4}{1} d + \frac{0.1}{1} p.$$

$$\dot{x}_2 = 0 \rightarrow \boxed{\dot{d}_e = 0.}$$

$$\frac{0.4}{1} d_e = \frac{0.1}{1} p \quad d_e = \frac{0.1}{0.4} p \rightarrow \boxed{d_e = \frac{p}{4}}$$

$$y = (1 \ 0) \begin{bmatrix} p/4 \\ 0 \end{bmatrix} \quad \boxed{y_e = \frac{p}{4}}$$

Tarea 1

$$\left. \begin{aligned} m\ddot{d} &= -b\dot{d} - kd + ap \\ \ddot{d} &= -\frac{b}{m}\dot{d} - \frac{k}{m}d + \frac{a}{m}p \end{aligned} \right\}$$

$$\begin{bmatrix} \ddot{d} \\ \dot{d} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{b}{m} \end{bmatrix} \begin{bmatrix} d \\ \dot{d} \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{a}{m} \end{bmatrix} p$$

Tarea 2

$$1) V_i = V_{R1} + V_{C1}$$

$$V_i = I_1 \cdot R_1 + V_{C1}$$

$$2) V_{C1} = V_{R2} + V_{C2}$$

$$V_{C1} = I_2 R_2 + V_{C2}$$

→ Sustituyo.

$$V_i = R_1 \cdot \dot{V}_{C1} \cdot C_1 + R_1 \cdot \dot{V}_{C2} \cdot C_2 + V_{C1}$$

$$V_{C1} = R_2 \cdot \dot{V}_{C2} \cdot C_2 + V_{C2}$$

Despejo la derivada más grande.

$$\dot{V}_{C1} = \frac{1}{R_1 C_1} V_i - \frac{R_1 \cdot C_2}{R_1 C_1} \dot{V}_{C2} - \frac{1}{R_1 C_1} V_{C1}$$

$$\dot{V}_{C2} = \frac{1}{R_2 C_2} \cdot V_{C1} - \frac{1}{R_2 C_2} \cdot V_{C2}$$

→ Metodo en \dot{V}_{C1} \dot{V}_{C2}

$$\dot{V}_{C1} = \frac{1}{R_1 C_1} V_i - \frac{R_1}{C_1 R_2 C_2} V_{C1} + \frac{R_1}{C_1 R_2 C_2} V_{C2} - \frac{1}{R_1 C_1} V_{C1}$$

$$A = \begin{bmatrix} -\frac{1}{C_1 R_2} - \frac{1}{R_1 C_1} & \frac{1}{C_1 R_2} \\ \frac{1}{R_2 C_2} & -\frac{1}{R_2 C_2} \end{bmatrix} \begin{bmatrix} V_{C1} \\ V_{C2} \end{bmatrix} B = \begin{bmatrix} \frac{1}{R_1 C_1} \\ 0 \end{bmatrix} V_i$$

$$C = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 \end{bmatrix}$$