

SOLID principles

Program slicing:

- originally the program is like a bunch of lines of code executed sequentially
- extract functions and the program is like a composition of functions
- group functions into modules or classes and the program has structure, so you can find easily the function you are interested in

(years)
After a while of the program evolving, responsibilities settle and a kind of domain structure emerges.

- modular monolith architecture
 - ↳ (micro)services from each module
 - distributed architecture

distributed is always ^{way} more complex than monolith,

but sometimes this added complexity is worth for the (horizontal) scalability it gives to us.

Open for extension
but closed for modification

Liskov substitution
(design by contract)
(interface)

Single responsibility
for each function or module

SOC Separation of concerns

well-defined dependencies between functions / modules
(data transfers)

Interface segregation

Low coupling
High cohesion

Dependency inversion

Trade-off between complexity and benefits
(of slicing)

(maintainability)
(scalability)

Separation of concerns

- reduce duplication (DRY - Don't Repeat Yourself)

ideally → only one point to change for each responsibility

- flexibility to evolve ideally → you can change ^{inside} each part/module/class without affecting any other

- allows interface creation ideally → all dependencies are well stated

- reduces cognitive load when combined with good naming, you can focus at different levels of abstraction
(the names of functions/modules/parameters)
(convey clearly what each of them does)

monolith → all ^{modules/services} in one single binary → you ^{build} deploy all together

(micro)services → each service in it's own binary → you ^{build} deploy each one independently

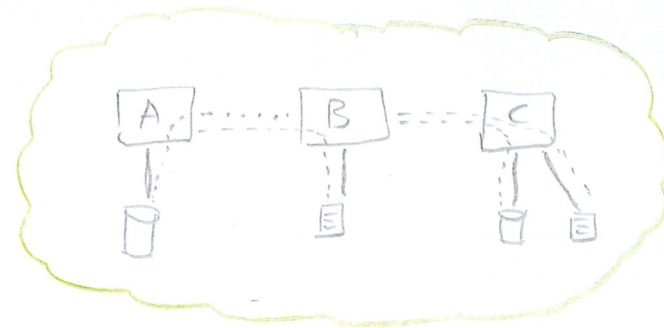
complexity and coordination needs
are bigger

↓
if you have realized each service right, you can deploy more of one or another service as you need to cope with the demand of each one.

you can also add redundancy to cope with failures in a system

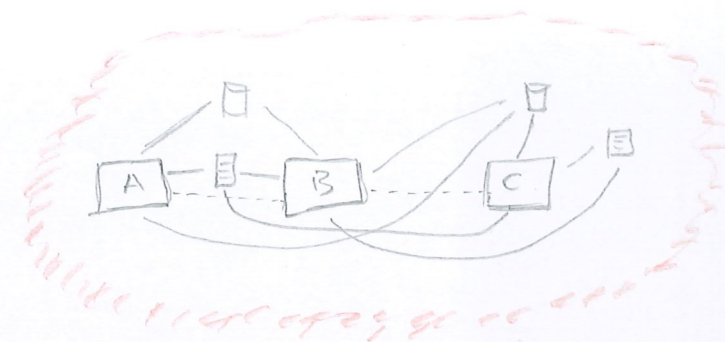
Decoupling

- In monoliths you must care about interfaces, but all modules share build, deployment, libraries and repositories (service)
- In microservices, each service has its own build, deployment, libraries, repositories (module)
(and you must care about relationships) (APIs) (contracts)



Hidden Coupling

There is a thing worse than a highly coupled monolith (Big Ball of Mud) and it is a distributed monolith! (highly coupled microservices)



Invocation Consequences

- pay attention to network invocation burden
 - (async / ^{latency} delays / errors / timeouts)
- pay attention to reliability or congestion issues

Addressing Consequences

- pay attention to DNS, (IP) hosts, ports, load balancers, proxies, ...

where is B?

is B alive?

more complicated as more services we have to coordinate

Dependency Isolation Consequences

- pay attention to versioning of each service (API)

8 Fallacies of Distributed Computing

observability is vital!