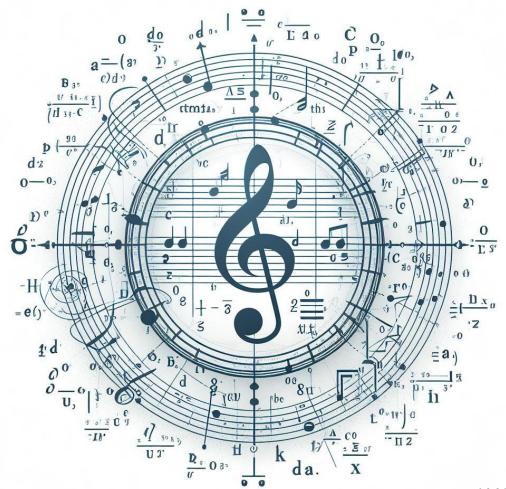
Chaos-ic: tune the chaos, create the symphony!

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AM1 1° MUSE Curso 2023/24







- 1.Introduction
- 2.GUI
- 3.Algorithm
- 4.MIDI file
- 5.Examples
- 6.Conclusions



- Automatic-generated music:
 - Literature, algorithms, ...
- Fractals
- Academic interest: a different way of studying the behaviour of the chaotic dynamic systems



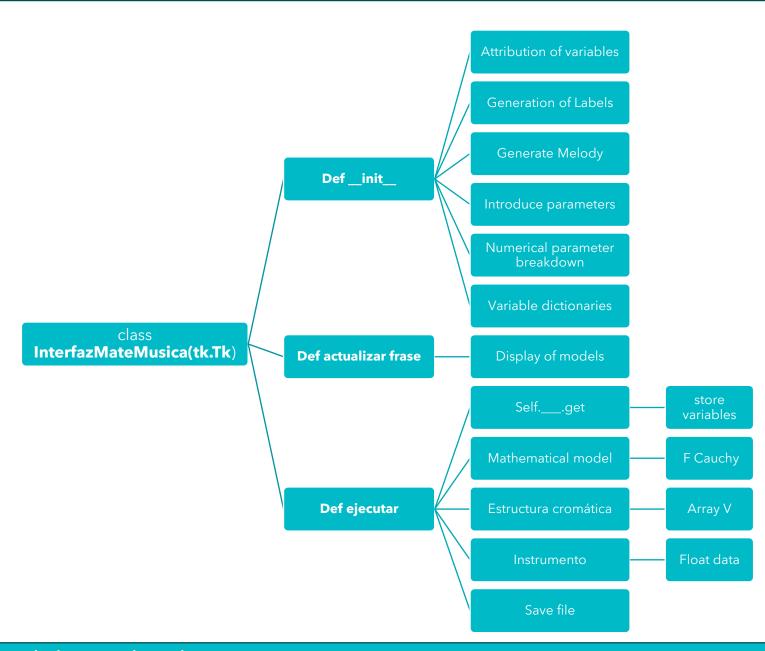
- Library to develop GUI: Thinker
- Objetives:
 - **Define variables** to be stored.
 - Create **labels** for each block.
 - Use a combobox to choose options.
 - Define parameters to be choosen.
 - Define to enter" data.
 - Create dictionaries"float to store variables.
 - Use variable "self.__" to assign variables.
- Code Secuence:



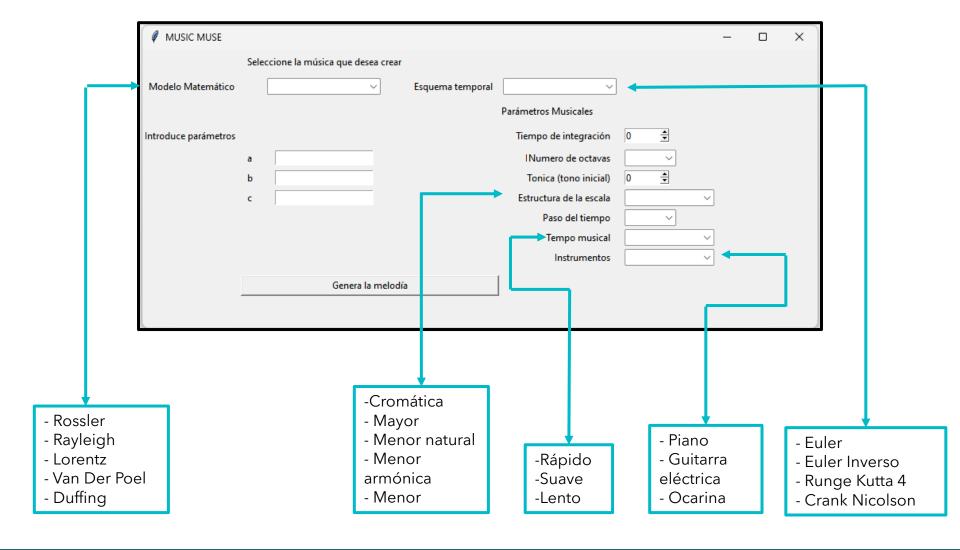
tk.Label

Tk.Combobox

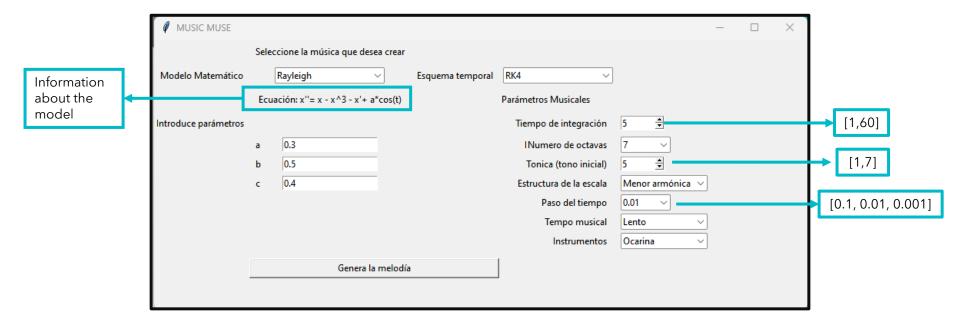
tk.Entry



Combobox



Grafical User Interface (GUI)



• Main idea:

Transformation

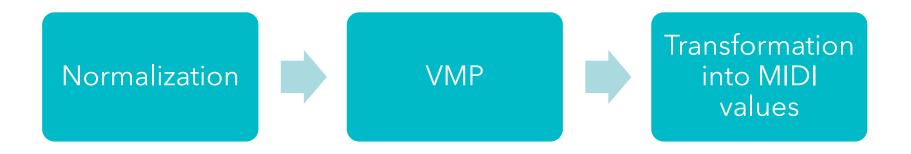
Mathematical Method Solution

$$\bullet$$
 $Y = ()$

•
$$Z = ()$$

Musical values

- Frequency
- Rhythm
- Dynamic



```
'''Normalizacion de la variable'''
alpha = (2**k-1)/(max(x)-min(x))
beta = -alpha*min(x)+1

for i in range(0,len(x)):
   x1[i] = alpha*x[i]+beta
```

ALGORITHM: Rhythm

Normalization



Round



Transformation into MIDI values

```
'''Normalizacion de la variable'''
alpha = (max(R)-min(R))/(max(y)-min(y))
beta = -alpha*min(y)+min(R)
y1 = zeros(len(y))

for i in range(0,len(y)):
    y1[i] = alpha*y[i]+beta
```

```
'''Redondeo a valor proximo'''
y2=[]
for i in range(0,len(y)):
    y2.append(round(y1[i]))
```

```
'''Conversion a MIDI'''
Y=[]
for i in range(0,len(y2)):
    Y.append(60/tp*2**y2[i]/2**4)
```

```
R=[0,1,2,3,4,5,6]

0 - semifusa
1 - fusa
2 - semichorchea
3 - corchea
4 - negra
5 - blanca
6 - redonda
```

ALGORITHM: Dynamic

Normalization



VMP



Transformation into MIDI values

```
'''Normalizacion de la variable'''
alpha = (max(U)-min(U))/(max(z)-min(z))
beta = -alpha*min(z)+min(U)
z1 = zeros(len(z))

for i in range(0,len(z)):
    z1[i] = alpha*z[i]+beta
```

```
Z=[]
for i in range(0,len(L)):
    if max(L) != 0:
        Z.append(L[i]/max(L))
    else:
        Z.append(100)
```

```
U=[10, 30, 45, 60, 75, 92, 108, 127]
0-10 ppp
11-30 pp
31-45 p
46-60 mp
61-75 mf
76-92 f
93-108 ff
109-127 ffff
```

get_save_path

From tkinter: Creates a file dialog for choosing the location and name of the MIDI file

```
idef get_save_path():
    root = tk.Tk()
    root.withdraw() # Ocultar la ventana principal

# Mostrar el diálogo para elegir la ubicación y el nombre del archivo
    file_path = filedialog.asksaveasfilename(defaultextension=".mid", filetypes=[("MIDI files", "*.mid")])
    return file_path
```

Called from GUI
def ejecutar(self)

Output file: the path where the MIDI file will be saved

- X: Frequencies notes [0..127]
- Y: Note Duration-rhythm (seg or beats->BPM)
- Z: Speed / intensity and musical **dynamic** [0..127] Instrument: MIDI code

```
# Crear un archivo MIDI
midi = MidiFile()

# Agregar una pista al archivo MIDI
track = MidiTrack()
midi.tracks.append(track)

# Configurar el canal y el instrumento (opcional)
track.append(Message('program_change', program=Instrumento)) # Cambiar el instrumento

# Agregar mensajes MIDI a la pista (secuencia de notas)
for nota, velocidad, bpm in zip(vector_nota, vector_velocidad, vector_bpm):
tiempo_en_segundos = bpm # Calcular el tiempo en segundos a partir de bpm
tiempo_en_tics = int(tiempo_en_segundos * midi.ticks_per_beat) # Convertir a tics de tiempo MIDI
track.append(Message('note_on', note=nota, velocity=velocidad, time=0)) # Encender la nota
track.append(Message('note_off', note=nota, velocity=velocidad, time=tiempo_en_tics)) # Apagar la nota
# Guardar el archivo MIDI
```



create_midi_file

From mido:

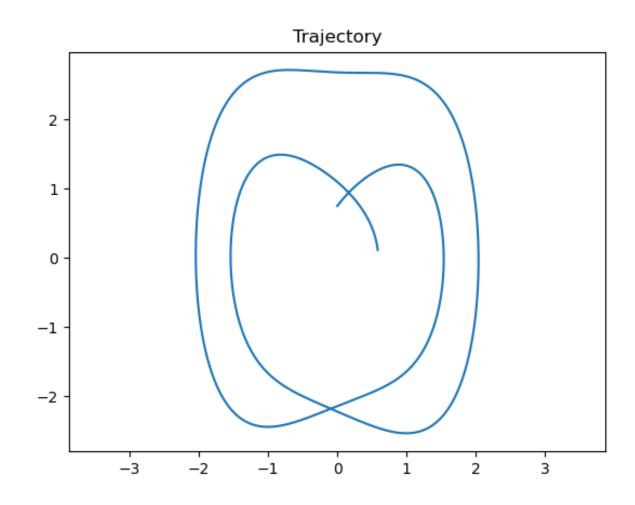
- Creates a Midifile
- Adds a track to the file
- 3. Configures the instrument
- 4. Add the notes with its duration and speed to the track based on input vectors (X, Y, Z)

midi.save(output_file)

- Integrated with Euler method
- Initial Conditions: (0, 0.75)

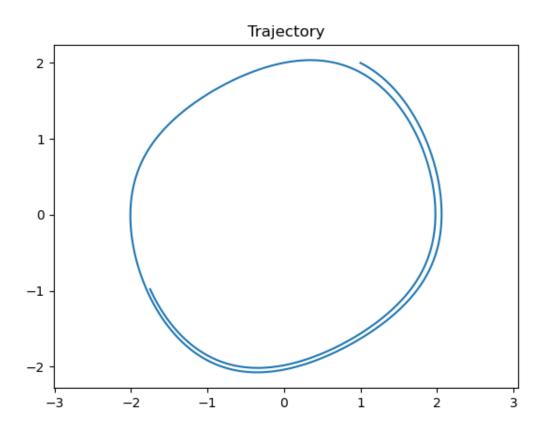
• <u>K parameter</u>: 0





- Integrated with Inverse Euler method
- Initial Conditions: (1, 2)
- μ Parameter = 0.2

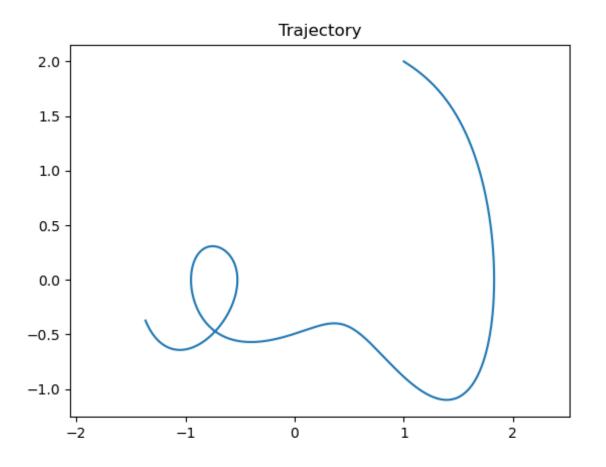




- Integrated with Runge-Kutta order 4 method
- <u>Initial Conditions</u>: (1,2)

• <u>F₀ parameter</u>: 0.75





- Integrated with Crank-Nicolson method
- Initial Conditions: (1,2,3)
- Parameters:

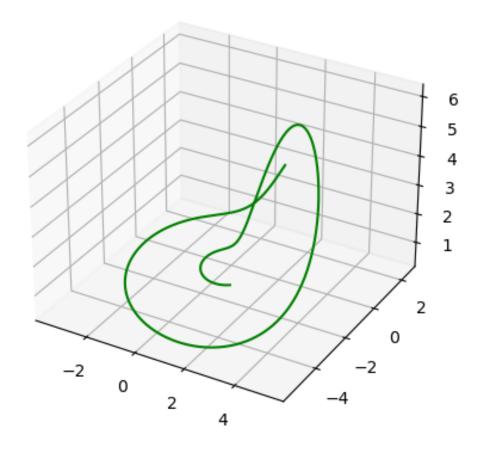
$$\circ A = 0.398$$

$$\circ B = 2$$

$$\circ$$
C = 4



Trajectory



- Integrated with Crank-Nicolson method
- Initial Conditions: (1,2)
- Parameters:

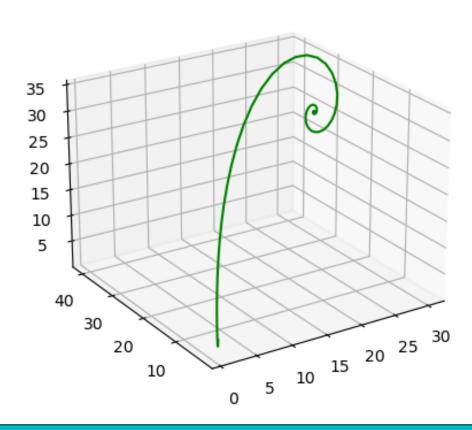
$$\circ R = 28$$

$$\circ B = 8/3$$

$$\circ$$
C = 10

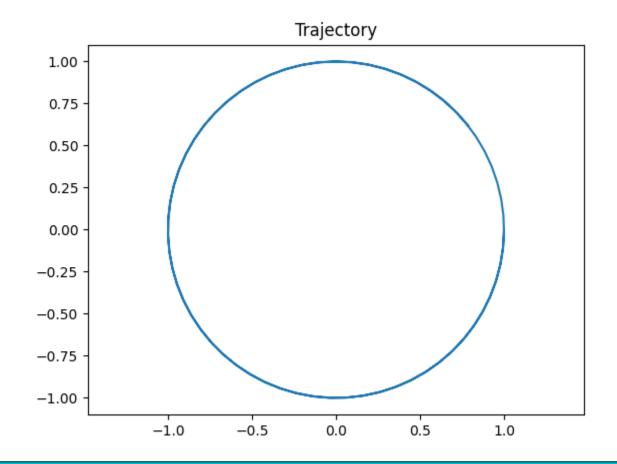


Trajectory



- Integrated with Runge-Kutta order 4 method
- Initial Conditions: (1,0)
- <u>Parameters</u>: n/a

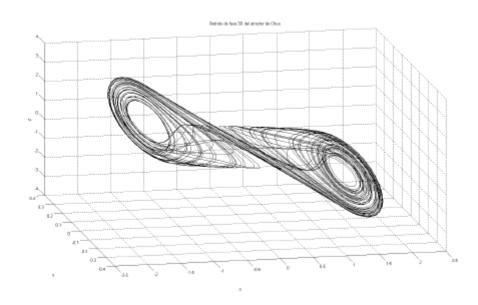




Equation:

$$\ddot{\mathbf{x}} + \mathbf{x} = \mathbf{0}$$

- The results match the concepts studied in the course's classes.
- Future work:
 - Modify the MIDI module (more than 1 instrument in the same MIDI file)
 - Implement AI to add drum and bass (https://magenta.tensorflow.org/drumbot)
 - Add other dynamic systems to study their evolution (e.g.: Chua model)



ANY QUESTIONS?

