

## CS375 HWS

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1. Prove or provide a counter-example for each of the following statements. You can use Matlab to find counter-examples. Assume  $A$  is a matrix and  $c$  is a scalar.

a)

$$\|cA\| = |c| \|A\|$$

$$\|A\| = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

because of vector norms we know

$$\|cA\| = \max_{x \neq 0} \frac{\|(cA)x\|}{\|x\|} = \max_{x \neq 0} \frac{\|Acx\|}{\|x\|}$$

$$\|\lambda x\| = |\lambda| \|x\| \text{ if } \lambda \in \mathbb{R}, x \in V$$

$$\therefore = \max_{x \neq 0} \frac{|c| \|Ax\|}{\|x\|}$$

$$= |c| \max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

$$\|A\|$$

$$\therefore \|cA\| = |c| \|A\|$$



b)  $\kappa(cA) = \kappa(A)$  for any nonzero constant  $c$

$$\text{let } \kappa(A) = \|A\| \|A^{-1}\|$$

$$\kappa(cA) = \|cA\| \|(cA)^{-1}\|$$

$$\kappa(cA) = |c| \|A\| \left| \frac{1}{c} \right| \|A^{-1}\|$$

$$\kappa(cA) = \cancel{|c|} \cancel{\left| \frac{1}{c} \right|} \cdot \underbrace{\|A\| \|A^{-1}\|}_{\kappa(A)}$$

c)  $\kappa(A)$  is the same for every matrix norm

$$\text{cond}(A) = \|A\|, \|A^{-1}\| \neq \|A\|_2 \|A^{-1}\|_2$$

false

see matlab attached for counter Example.

2.

$$A = \begin{bmatrix} 1 & k \\ 1 & 1 \end{bmatrix} \quad \text{where } k \neq 1$$

a) Find  $\|A\|_1$  in terms of  $k$ .

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}| = \begin{matrix} j=1 & j=2 \\ |1|+|1| & |1|+|k| \end{matrix}$$

$$\|A\|_1 = \begin{cases} 2 & \text{if } k \in (-1, 1) \\ |1|+|k| & \text{for } k > 1 \text{ or } k < -1 \end{cases}$$

b) find  $\|A^{-1}\|_1$  in terms of  $k$ . remember that

$$\|A^{-1}\|_1 = \left\| \frac{1}{\det(A)} \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix} \right\|_1$$

$$\|A^{-1}\|_1 = \left| \frac{1}{\det(A)} \right| \left\| \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix} \right\|_1$$

$$\left\| \begin{pmatrix} 1 & -k \\ -1 & 1 \end{pmatrix} \right\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}| = \begin{matrix} j=1 & j=2 \\ |1|+|1| & |1|+|k| \end{matrix}$$

$$\|A^{-1}\|_1 = \left| \frac{1}{1-k} \right| \cdot \begin{cases} 2 & \text{if } k \in (-1, 1) \\ |1|+|k| & \text{for } k > 1 \text{ or } k < -1 \end{cases}$$

c)



$$\kappa(A) = \|A\|_1 \|A^{-1}\|_1$$

recall

$$\|A\|_1 = \begin{cases} 2 & \text{for } k \in (-1, 1) \\ 1 + |k| & \text{for } k > 1 \text{ or } k < -1 \end{cases}$$

and

$$\|A^{-1}\|_1 = \begin{cases} \left| \frac{1}{1-k} \right|^2 & \text{for } k \in (-1, 1) \\ \left| \frac{1}{1-k} \right| (1 + |k|) & \text{for } k > 1 \text{ or } k < -1 \end{cases}$$

$$\therefore \kappa(A) = \left| \frac{1}{1-k} \right|^4 \text{ for } k \in (-1, 1)$$

&

$$\kappa(A) = \left| \frac{1}{1-k} \right|^2 (1 + |k|)^2 \text{ for } k > 1 \text{ or } k < -1$$

d) Explain geometrically why the condition number grows as  $k \rightarrow 1$

as  $k$  reaches one  $\kappa(A)$  for both conditions will approach infinity because of the

$$\left| \frac{1}{1-k} \right| \text{ term.}$$

e) If  $\kappa(A) = 10^k$  then you can expect to lose at least  $k$  digits of precision in solving the system  $Ax=b$ .  
 ∴ we have  $10^k = 10^6$  because we have 16 digits of accuracy and we want 10 digits accuracy



it follows that

$$K(A) = 10^6 = \left| \frac{1}{1-K} \right| 4$$

$$\frac{10^6}{4} = \left| \frac{1}{1-K} \right| = \frac{1}{\sqrt{(1-K)^2}}$$

$$\sqrt{(1-K)^2} = \frac{4}{10^6}$$

$$(1-K) = \sqrt{\frac{4^2}{10^{12}}}$$

$$-K = \sqrt{\frac{16}{10^{12}}} - 1$$

$$K = 1 - \sqrt{\frac{16}{10^{12}}}$$

3. Let

$$A = \begin{bmatrix} 1 & 1+e \\ 1-e & 1 \end{bmatrix}$$

a) Find the determinant of A

$$\det(A) = 1 - (1+e)(1-e) = 1 - (1-e^2)$$

b) Using double precision floating point arithmetic, for what values of  $e$  will  $\det(A)$  equal to 0?



recall

$$\det(A) = 1 - (1 - e^2)$$

$$\text{if } \det(A) = 0 \Rightarrow 1 - (1 - e^2) = 0$$

$$f(1 - e^2) = f(1)$$

$$f(1 - e^2) = 1$$

$$(1 - e^2)(1 + e) = 1$$

$$1 + e - e^2 - e^3 = 1$$

$$e - e^2 - e^3 \leq \epsilon_m$$

so that

$$1 + \underbrace{(e - e^2 - e^3)}_{\leq \epsilon_m} = 1$$

c) Find the LU factorization of A without pivoting

$$A = \begin{bmatrix} 1 & 1+e \\ 1-e & 1 \end{bmatrix} \Rightarrow R_2 - (1-e)R_1 \quad \begin{bmatrix} 1 & 1+e \\ 0 & 1-(1-e^2) \end{bmatrix}$$

$$A = \underbrace{\begin{bmatrix} 1 & 0 \\ (1-e) & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 1 & 1+e \\ 0 & 1-(1-e^2) \end{bmatrix}}_U$$



4. Let  $\epsilon$  be some small positive number less than half machine epsilon and

$$A = \begin{bmatrix} \epsilon & 1 \\ 1 & 1 \end{bmatrix}$$

a) compute  $1 - \frac{1}{\epsilon}$  using floating-point arithmetic.

We know

$$1 + \epsilon_m > 1$$

$$1 + \epsilon = 1 \quad \text{with } |\epsilon| < \epsilon_m$$

let's use  $\epsilon = \frac{\epsilon_m}{4}$  based on the description of the problem, then ....

$$1 + \frac{\epsilon_m}{4} = 1 \Rightarrow \frac{1}{\epsilon_m} + \frac{1}{4} = \frac{1}{\epsilon_m}$$

notice that  $\frac{1}{\epsilon_m} \gg \frac{1}{4}$  or any constant  $k > 2$

↳ recall

$$\epsilon < \frac{\epsilon_m}{2}$$

$$\therefore 1 - \frac{1}{\epsilon} \rightarrow 1 - \frac{k}{\epsilon_m}$$

has this term.  
which is larger  
than 1 and  
not negligible  
making

$$1 - \frac{1}{\epsilon} \quad \text{with } |\epsilon| < \frac{\epsilon_m}{2}$$

a negative number  
of the order of  $10^6$  or larger.

and essentially  
we could approximate

$$1 - \frac{1}{\epsilon} \approx -\frac{1}{\epsilon}$$



b)

$$A = \begin{bmatrix} \epsilon & 1 \\ 1 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 \\ 1/\epsilon & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} \epsilon & 1 \\ 0 & 1 - 1/\epsilon \end{bmatrix}}_U$$

$$A = \begin{bmatrix} \epsilon & 1 \\ 1 & 1 \end{bmatrix} \rightarrow R_2 - \frac{1}{\epsilon} R_1 \begin{bmatrix} \epsilon & 1 \\ 0 & 1 - \frac{1}{\epsilon} \end{bmatrix}$$

c) Compute  $W$  for the  $L$  and  $U$  matrices found in the previous part.

$$\begin{bmatrix} 1 & 0 \\ 1/\epsilon & 1 \end{bmatrix} \begin{bmatrix} \epsilon & 1 \\ 0 & 1 - 1/\epsilon \end{bmatrix} = \begin{bmatrix} \epsilon + 0 & 1 + 0(1 - 1/\epsilon) \\ 1 + 0 & \frac{1}{\epsilon} + 1 - \frac{1}{\epsilon} \end{bmatrix} = \begin{bmatrix} \epsilon & 1 \\ 1 & 1 \end{bmatrix} = A$$

d) Permute the rows of  $A$ , compute the LU factorization of the resulting matrix in floating-point arithmetic, and confirm the product  $LU$  is correct.

$$LU = PA$$

$$\rightarrow P = I$$



5. Consider a symmetric positive definite matrix

$$E = \begin{bmatrix} A & \alpha \\ \alpha^T & c \end{bmatrix}$$

where  $c$  is a scalar,  $\alpha$  is a  $n \times 1$  vector, and  $A$  is an  $n \times n$  matrix.

a) prove that  $c$  is positive and  $A$  is positive definite

If  $A$  is positive it follows that

$$x^T A x > 0 \text{ for all } x \in \mathbb{R}^n$$

$$[x_1, x_2, \dots, x_n] \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$[x_1, x_2, \dots, x_n] \begin{bmatrix} x_1 a_{11} + x_2 a_{12} + \dots + x_n a_{1n} \\ \vdots \\ x_1 a_{n1} + \dots + x_n a_{nn} \end{bmatrix}$$

$$x_1(x_1 a_{11} + x_2 a_{12} + \dots + x_n a_{1n}) + x_2(x_1 a_{21} + \dots + x_n a_{2n}) + \dots + x_n(x_1 a_{n1} + \dots + x_n a_{nn})$$

If  $A$  is non-zero and nonsingular then the condition that follows is

$$A = L D L^T$$

where  $x = L^{-T} e_i$  and  $e_i$  is the  $i$ -th element of  $I$

$$\therefore x^T A x = d_i > 0$$



b) by the above, the cholesky factorization  $A = LL^T$  exists. Assuming  $(L^{-1}\alpha)^T(L^{-1}\alpha) < c$ , and the cholesky factorization of  $E$  in terms of  $L, \alpha, c$

$$E = LDL^T = \begin{bmatrix} A & \alpha \\ \alpha^T & c \end{bmatrix}$$

$$L = \begin{bmatrix} I & 0 \\ \alpha^T A^{-1} & I \end{bmatrix} \rightarrow L^T = \begin{bmatrix} I & A^{-1}\alpha \\ 0 & I \end{bmatrix}$$

$$D = \begin{bmatrix} A & 0 \\ 0 & c - \alpha^T A^{-1} \alpha \end{bmatrix}$$

$$E = \begin{bmatrix} I & 0 \\ \alpha^T A^{-1} & I \end{bmatrix} \begin{bmatrix} A & 0 \\ 0 & c - \alpha^T A^{-1} \alpha \end{bmatrix} \begin{bmatrix} I & A^{-1}\alpha \\ 0 & I \end{bmatrix}$$