

A Maple implementation of a modular algorithm for computing the common zeros of a polynomial and a regular chain

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Agenda

- 1 Introduction
- 2 Preliminaries
- 3 The Non-Modular Method and its Genericity Assumptions
 - The goal
 - Genericity assumptions
- 4 The Modular Method
- 5 Experimentation
- 6 Conclusion

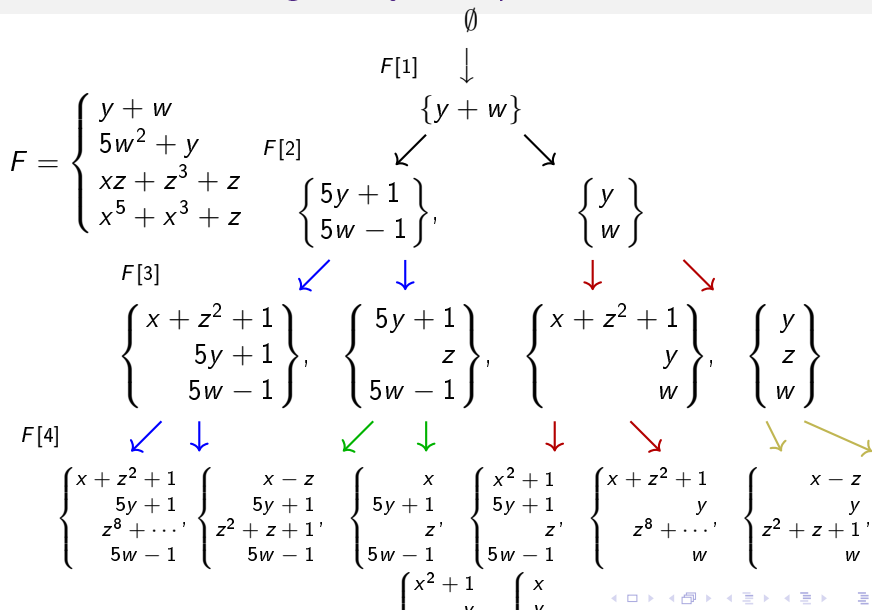
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Solving polynomial systems incrementally

- Most algorithms for solving polynomial systems symbolically proceed
 - *incrementally*, that is, solving one equation after another, against the solutions of the previously solved equations, or
 - by *projection and lifting*, that is, by successively eliminating one variable after another, and then proceeding by back-substitution as in linear system solving.
- The algorithm `Triangularize` of the Maple's `RegularChains` library belongs to the category of incremental solving.
- Without entering technical details, we illustrate this algorithm in the following slides.

Incremental solving: a toy example



Incremental solving: a real-life example

- As illustrated below, the algorithm Triangularize proceeds by repeated calls to a procedure called Intersect.
- This procedure computes the common zeros of a polynomial and a solution set (termed *regular chain* in polynomial system theory).

```

> R := PolynomialRing([x,y,z,t,u]);
                                     R := polynomial_ring
-
> F := [2*x + 2*y + 2*z + 2*t + u - 1, 2*x^2 + 2*y^2 + 2*z^2 + 2*t^2 + u^2 - u, 2*x*y + 2*y*z + 2*z*t + 2*t*u - t, 2*x*z +
2*y*t + t^2 + 2*z*u - z, 2*x*t + 2*z*t + 2*y*u - y]; rc := Empty(R); lrc := [rc];
F = [2 x + 2 y + 2 z + 2 t + u - 1, 2 x^2 + 2 y^2 + 2 z^2 + 2 t^2 + u^2 - u, 2 x y + 2 y z + 2 z t + 2 t u - t, 2 x z + 2 y t + 2 z u + t^2 - z, 2 x t + 2 y u + 2 z t
-y]
                                     rc := regular_chain
                                     lrc := [rc]
-
> ## solving F[1] against lrc
> a := time(): lrc := [ seq ( op(Intersect(F[1], ts, R)), ts=lrc ) ]; map(Dimension, lrc, R); time() - a;
                                     lrc := [regular_chain]
                                     [4]
                                     0.003
-
> ## solving F[2] against lrc
> a := time() ; lrc := [ seq ( op(Intersect(F[2], ts, R)), ts=lrc ) ]; map(Dimension, lrc, R); time() - a;
                                     a := 19.378
                                     lrc := [regular_chain]
                                     [3]
                                     0.006
-
> ## solving F[3] against lrc
-
> a := time(): lrc := [ seq ( op(Intersect(F[3], ts, R)), ts=lrc ) ]; map(Dimension, lrc, R); time() - a;
                                     lrc := [regular_chain, regular_chain]
                                     [2, 1]

```

```

> ## solving F[4] against lrc
> a:= time(): lrc := [ seq ( op(Intersect(F[4], ts, R)), ts=lrc ) ]; map(Dimension, lrc, R); time() - a;
      lrc := [regular_chain, regular_chain, regular_chain, regular_chain, regular_chain, regular_chain, regular_chain, regular_chain]
              [1, 0, 0, 0, 0, 0, 0, 0]
              0.270
> ## solving F[5] against the first regular chain in lrc
> a := time() : Intersect(F[5], lrc[1], R); time() -a ;
              [regular_chain, regular_chain]
              1.639
> ## solving F[5] against the other chains in lrc
> a:= time() ; [ seq ( op(Intersect(F[5], ts, R)), ts=lrc[2..-1] )]; time() - a;
              a := 21.316
              [regular_chain, regular_chain]
              0.145

```

- The above example shows that most of the time is spent in computing the common zeroes of a polynomial and a regular chain of dimension 1 (that is, a space curve).
- This motivates the work presented here, where we propose a new algorithm for computing such intersections.
- Our new algorithm is based on *curve fitting techniques*.

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Regular chains

Let \mathbf{k} be a perfect field, and $\mathbf{k}[X]$ have ordered vars. $X = X_1 < \dots < X_n$

A triangular set $T \subset \mathbf{k}[X]$ is a regular chain if either T is empty, or T_v^- is a regular chain and h is regular modulo $\text{sat}(T_v^-)$

$$T = \left\{ \begin{array}{l} T_v = h v^d + \text{tail}(T_v) \\ T_v^- = \left\{ \begin{array}{c} \text{---} \\ \diagdown \\ \text{---} \end{array} \right\} \end{array} \right\}$$

$$T = \left\{ \begin{array}{l} (2y + ba)x - by + a^2 \\ 2y^2 - by - a^2 \\ a + b \end{array} \right\} \\ \subset \mathbb{Q}[b < a < y < x]$$

Saturated ideal of a regular chain:

- $\text{sat}(T) = (\text{sat}(T_v^-) + T_v) : h^\infty$
- $\text{sat}(\emptyset) = \langle 0 \rangle$

Quasi-component of a regular chain:

- $W(T) := V(T) \setminus V(h_T)$,
 $h_T := \prod_{p \in T} h_p$
- $\overline{W(T)}^{p \in T} = V(\text{sat}(T))$

The algorithms Intersect and Triangularize

Intersect

Let $p \in \mathbf{k}[X]$ and let $T \subseteq \mathbf{k}[X]$ be a regular chain. The function call $\text{Intersect}(p, T)$ computes regular chains $T_1, \dots, T_e \subseteq \mathbf{k}[X]$ such that:

$$V(p) \cap W(T) \subseteq W(T_1) \cup \dots \cup W(T_e) \subseteq V(p) \cap \overline{W(T)}. \quad (1)$$

Triangularize

Given a finite set $F = \{f_0, f_1, f_2, \dots\} \dots, \subseteq \mathbf{k}[X]$, $\text{Triangularize}(F)$ compute regular chains $T_1, \dots, T_e \subseteq \mathbf{k}[X]$ encoding the solutions of $V(F)$:

$$V(F) = W(T_1) \cup \dots \cup W(T_e). \quad (2)$$

This is achieved by successively applying Intersect to f_0, f_1, f_2, \dots on the previously obtained regular chains.

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- Let \mathbf{k} be a field of characteristic zero or a prime field of *sufficiently large* characteristic.
- Let $f, t, b \in \mathbf{k}[x, y, z]$ be non-constant polynomials in the ordered variables $x > y > z$.

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$$\text{mvar}(t) = x \text{ and } \text{mvar}(b) = y.$$

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- **Our goal:** compute the *intersection* $V(f) \cap W(T)$ in the sense of the function call `Intersect(f, T)`, i.e., we want to compute regular chains $T_1, \dots, T_e \subseteq \mathbf{k}[x, y, z]$ such that:

$$V(f) \cap W(T) \subseteq W(T_1) \cup \dots \cup W(T_e) \subseteq V(f) \cap \overline{W(T)}. \quad (3)$$

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Hypothesis 1

- Let $S(t, f, x)$ be the **subresultant chain** of t and f (resp. f and t) regarded as polynomials in $(\mathbf{k}[y, z])[x]$ if $\text{mdeg}(t) \geq \text{mdeg}(f)$ (resp. $\text{mdeg}(t) < \text{mdeg}(f)$).

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Hypothesis

$$r \notin \mathbf{k} \text{ and } \text{mvar}(r) = y. \quad (5)$$

Hypothesis 2

- Let $S(r, b, y)$ be the **subresultant chain** of r and b (resp. b and r) regarded as polynomials in $\mathbf{k}[y, z]$ if $\text{mdeg}(r) \geq \text{mdeg}(b)$ (resp. $\text{mdeg}(r) < \text{mdeg}(b)$).

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*The polynomial set $C := \{\bar{s}, g, \ell\}$ is a **regular chain**.*

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- The initial h_g is **invertible** mod \bar{s} and the initial h_ℓ is **invertible** modulo the ideal $\langle \bar{s}, g \rangle$.
- $V(\bar{s}, r, b) = V(\bar{s}, g)$.

Hypothesis 3

Our last genericity assumption is the following

Hypothesis

*The initial of the polynomial t is **invertible** modulo the ideal*

$$\text{sat}(\{\bar{s}, g\}) = \langle \bar{s}, g \rangle.$$

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- As a consequence we have:

$$V(f) \cap V(\{\bar{s}, g, t\}) = V(\{\bar{s}, g, \ell\}).$$

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- Putting all hypotheses together yield the following theorem:

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- Putting all hypotheses together yield the following theorem:

$$V(f, t, b) = V(\{\bar{s}, g, \ell\}).$$

- Therefore, under our hypothesis, we have:

$$\text{Intersect}(f, \{t, b\}) = V(\{\bar{s}, g, \ell\}).$$

Example

$R := \text{PolynomialRing}([x, y, z]) :$

$f := (y + z) * x^2 + x + 1;$

$t := z * x^2 + y * x + 1;$

$b := (z + 1) * y^2 + y + 2;$

$$f := (y + z) x^2 + x + 1$$

$$t := z x^2 + y x + 1$$

$$b := (z + 1) y^2 + y + 2 \quad (1)$$

$\text{src1} := \text{SubresultantChain}(f, t, x, R) :$

$l := \text{SubresultantOfIndex}(1, \text{src1}, R); r := \text{SubresultantOfIndex}(0, \text{src1}, R);$

$$l := x y^2 + x y z - x z + y$$

$$r := y^3 + y^2 z - 2 y z + z \quad (2)$$

$\text{src2} := \text{SubresultantChain}(r, b, y, R) :$

$g := \text{SubresultantOfIndex}(1, \text{src2}, R); s := \text{SubresultantOfIndex}(0, \text{src2}, R);$

$$g := -2 y z^3 - 5 y z^2 + z^3 - 5 y z - y - z + 2$$

$$s := z^5 + 9 z^4 + 24 z^3 + 38 z^2 + 13 z + 8 \quad (3)$$

$$\text{sol} := \text{Chain}([s], \text{Empty}(R), R) : \text{IsRegular}(\text{Initial}(g, R), \text{sol}, R);$$

true (4)

$$\text{sol2} := \text{Chain}([g], \text{sol}, R) : \text{IsRegular}(\text{Initial}(l, R), \text{sol2}, R);$$

true (5)

$$\text{IsRegular}(\text{Initial}(t, R), \text{sol2}, R);$$

true (6)

$$\text{sol3} := \text{Chain}([l], \text{sol2}, R) : \text{Display}(\text{sol3}, R);$$

$$\left\{ \begin{array}{l} (y^2 + yz - z)x + y = 0 \\ (-2z^3 - 5z^2 - 5z - 1)y + z^3 - z + 2 = 0 \\ z^5 + 9z^4 + 24z^3 + 38z^2 + 13z + 8 = 0 \\ y^2 + yz - z \neq 0 \\ -2z^3 - 5z^2 - 5z - 1 \neq 0 \end{array} \right. \quad (7)$$

$$\text{dec3} := \text{Triangularize}([f, t, b], R) : \text{Display}(\text{dec3}[1], R);$$

$$\left\{ \begin{array}{l} (y^2 + yz - z)x + y = 0 \\ (2z^3 + 5z^2 + 5z + 1)y - z^3 + z - 2 = 0 \\ z^5 + 9z^4 + 24z^3 + 38z^2 + 13z + 8 = 0 \\ y^2 + yz - z \neq 0 \\ 2z^3 + 5z^2 + 5z + 1 \neq 0 \end{array} \right. \quad (8)$$

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The Modular Method

The key ideas of that method are

- Computing the **subresultants** $r = S_0(t, f, x)$, $\ell = S_1(t, f, x)$,
 $s = S_0(r, b, y)$, $g = S_1(r, b, y)$ by **evaluation and interpolation**.

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- Verify the **genericity assumptions** as we recover ℓ, s, g from the evaluation and interpolation process, returning an **error** if one of those assumptions is not met.

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- Use the **Bézout bound** of the (zero-dimensional) variety $V(f, t, b)$ for this evaluation and interpolation process.
- Verify the **genericity assumptions** as we recover ℓ, s, g from the evaluation and interpolation process, returning an **error** if one of those assumptions is not met.
- Use only **basic** well optimized functions of maple. In particular the **modp1** library.

The implementation

while $i \leq bnd := 2 * BezoutBdn + 1$ **do**

Select a point v and specialize f, t, b at $z = v$.

if f, t, b does not specialize well **then**

Next

end if

Normalize T to $T_v = \{t_v, b_v\}$.

Compute $r_v = S_0(t_v, f_v, x)$, $\ell_v = S_1(t_v, f_v, x)$.

Check assumptions about r .

Compute $s_v = S_0(r_v, b_v, y)$, $g_v = S_1(r_v, b_v, y)$.

end while

Interpolate s_v, g_v, ℓ_v into s, g, ℓ .

Apply Rational Function Reconstruction to s, g, ℓ .

Get the numerator of s, g, ℓ .

Compute the squarefree part of s , \bar{s} .

Check that $C = \{\bar{s}, g, \ell\}$ is a regular chain and the initial of t .

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- $s = z^5 + 9z^4 + 2 * z^3 + 38z^2 + 13z + 8.$
- $g = z^3 + 469762048z + 2 + (469762047z^3 + 469762044z^2 + 469762044z + 469762048)y.$

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- $\ell = z^3 + 469762048z + 2 + (469762047z^3 + 469762044z^2 + 469762044z + 469762048)y.$

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- $t = 4x^9 - 40x^5y^2z + 6x^3y^3z + 27xy^6 + 68xy^3z^2 - 11z^5,$
- $b = -33y^8z + 8y^5z^2 - 69y^4z^2 - 34z^6 - 58y^5 - 53yz^2,$
- $f = -7x^3y^2z^4 - 50y^4z^5 - 70x^3y^5 + 19xy^5 - 5y^3z + 48x.$

A second example

- Prime characteristic 469762049.
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- $\deg(s) = 573, \deg(g) = 504, \deg(\ell) = 64.$

Benchmark

Prime characteristic 469762049.

N	$\deg(t)$	$\deg(b)$	$\deg(f)$	Intersect	Intersect by Specialization
1	3	2	3	0.123s	0.476s
2	5	4	4	0.312s	1.020s
3	5	4	5	0.412s	1.406s
4	7	6	7	14.652s	12.576s
5	7	7	7	1.509s	9.755s
6	8	7	8	37.540s	35.174s
7	8	8	8	33.720s	21.716s
8	9	6	9	28.545s	13.705s

Benchmark

Prime characteristic 469762049.

N	$\deg(t)$	$\deg(b)$	$\deg(f)$	Intersect	Intersect by Specialization
9	8	7	8	37.540s	35.174s
10	8	8	8	33.720s	21.716s
11	8	8	8	31.280s	19.766s
12	8	8	8	21.285s	15.244s
13	8	8	8	24.387s	13.059s
14	8	8	8	45.607s	16.406s
15	8	8	8	46.862s	18.717s
16	8	8	8	46.862s	18.717s
17	8	8	9	68.167s	23.177s
18	9	9	8	34.497s	29.235s
19	9	6	9	28.545s	13.705s

Outline

- 1 Introduction
- 2 Preliminaries
- 3 The Non-Modular Method and its Genericity Assumptions
 - The goal
 - Genericity assumptions
- 4 The Modular Method
- 5 Experimentation
- 6 Conclusion

Concluding remarks

Theoretical aspects

- We have presented a modular algorithm for solving a trivariate polynomial system:

$$f = t = b = 0$$

under genericity assumptions.

- To be more precise, this is a modular method for the call $\text{Intersect}(f, \{t, b\})$.
- The article to-be-submitted to the Maple conference proceedings will explain how to relax the genericity assumptions
- A follow-up article will extend this modular method to solve square systems with an arbitrary number of variables.

Concluding remarks

Practical aspects

- The preliminary implementation and experimentation in Maple bring promising results for this modular method.
- To be more precise, for generic input systems of sufficiently large Bézout bound, the modular method outperforms the non-modular implementation of the command `Intersect`.
- There is large room for improvement: indeed, this modular method opens the door to using **speculative algorithms** for computing subresultants. Those are asymptotically fast algorithms that:

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 - compute the **subresultants** of index 0 and 1 without computing the other subresultants,

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- There is large room for improvement: indeed, this modular method opens the door to using **speculative algorithms** for computing subresultants. Those are asymptotically fast algorithms that:
 - compute the **subresultants** of index 0 and 1 without computing the other subresultants,
 - while being able to **resume** the computations for obtaining the subresultants of higher index, if needed.