```
Configuration: Default
  Coordinate system: -- default --
Density = 0.001000 grams per cubic millimeter
Mass = 1.162527 grams
Volume = 162.526576 cubic millimeters
Surface area = 1919.374849 square millimeters
Center of mass: ( millimeters )
         X = 0.000000
         Y = 0.000000
         Z = 0.000000
Principal axes of inertia and principal moments of inertia: ( grams * square millimeters )
Tken at the center of mass.
          Ix = (0.000000, 1.000000, 0.000000)
                                                   Px = 44.880466
          ly = ( 0.000000, 0.000000, 1.000000)
                                                   Py = 44.880466
          Iz = (1.000000, 0.000000, 0.000000)
                                                   Pz = 84.846534
Moments of inertia: ( grams * square millimeters )
aken at the center of mass and aligned with the output coordinate system. (Using positive tensor notation.)
         Lxx = 84.846534
                              Lxy = 0.000000
                                                   Lxz = 0.000000
         Lyx = 0.000000
                                                   Lyz = 0.000000
                              Lyy = 44.880466
         Lzx = 0.000000
                              Lzy = 0.000000
                                                   Lzz = 44.880466
Moments of inertia: ( grams * square millimeters )
Aken at the output coordinate system. (Using positive tensor notation.)
                              Ixy = 0.000000
         Ixx = 84.846534
                                                   Ixz = 0.000000
```

lyz = 0.000000

Izz = 44.880466

lyy = 44.880466

Izy = 0.000000

Mass properties of challenge

Iyx = 0.000000

Izx = 0.000000