Constrained Bayesian Optimisation with Knowledge Gradient

Juan Ungredda

University of Warwick



Constrained KG

Non-constrained KG:

$$KG(x) = \mathbb{E}[\max_{x'} \{\mu^{n+1}(x')\} | x^{n+1} = x]$$

Constrained KG with Probability of Feasibility (pf):

$$c - KG(x) = \mathbb{E}[\max_{x'} \{pf^{n+1}(x')\mu^{n+1}(x')\} | x^{n+1} = x]$$

Constrained KG corrected*:

$$c - \mathit{KG}(x) = \mathbb{E}[\max_{x'} \{\mathit{pf}^{n+1}(x')\mu^{n+1}(x') + (1-\mathit{pf}^{n+1}(x'))M\} | x^{n+1} = x]$$

where $M \in \mathbb{R}$ is the penalisation for sampling points in an infeasible region. It's commonly assumed to be zero.

Constrained KG

Benefits

- Takes into account that constraints change for each possible x^{n+1} considered.
- Assuming M = 0 may give "benefit" to infeasible regions. A more general approach avoids that problem.

Limitations

- Computationally expensive compared to constrained Expected Improvement. However, it's possible to make an efficient implementation by using gradients.
- M may be need to chosen by the decision maker.

Results

benchmark Method:

Constrained Expected Improvement. i.e. Expected Improvement times Probability of feasibility.

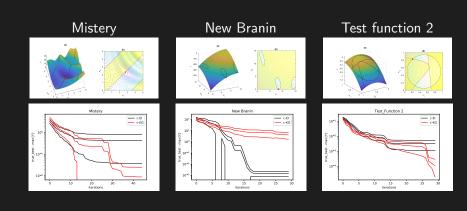
Test Functions:

New Branin, test function 2, and Mistery function. Non-noisy and constrained test functions.

Important Remark:

In the last evaluation of our approach, the function is sampled according to Expected Improvement times the probability of feasibility.

Plots



Gradient Information

Numerical methods to optimise KG rely on ∇KG. Quantity can be obtained either by Finite Difference or Analytically.

$$\nabla c \mathcal{K} G(x) = \nabla \mathbb{E}[\max_{x'} \{ p f^{n+1}(x') \mu^{n+1}(x') \} | x^{n+1} = x]$$

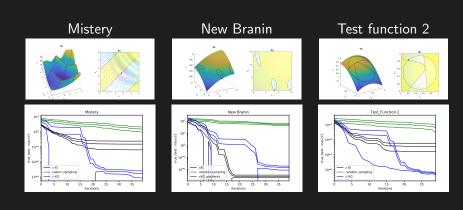
Once solved, the inner optimisation problem,

$$\nabla c KG(x) = \mathbb{E}[\nabla \{pf^{n+1}(x^*; x^{n+1})\mu^{n+1}(x^*; x^{n+1})\} | x^{n+1} = x]$$

Potential issue with Finite Differences:

Since the expectations is calculated only over a few values slight deviations of x^* affect greatly the outer gradient estimation.

Results with Analytical Gradients



Multi-Objective Constrained Optimisation

▶ Multi-Objective formulation using linear scalarisation.

$$KG(x';\theta) = \mathbb{E}_{y}[\max_{x'} \theta \mu^{n+1}(x') | x^{n+1} = x', \theta]$$

where the policy is,

$$maKG(x') = \mathbb{E}_{\theta}[KG(x';\theta)]$$

Multi-Objective constrained formulation

$$KG(x';\theta) = \mathbb{E}_{y}[\max_{x'}\theta\mu^{n+1}(x')pf^{n+1}(x')|x^{n+1} = x',\theta]$$

where the policy is,

$$maKG(x') = \mathbb{E}_{\theta}[KG(x'; \theta)]$$

Work to do

Main line of work

Constrained Multi-Objective problem

Secondary line of work

- Include noisy test functions.
- Set dynamically the M penalization.