

# MBS Benchmark A02: N Four-Bar Mechanism

## Benchmark Objective

The NMS benchmark problem **A02** is a common example of a mechanism which undergoes singular configuration [1].

## Benchmark Description

N four-bar mechanism (Fig. 1) is a common example of a mechanism which undergoes singular configuration. The system has N four-bar windows composed of  $2N+1$  links. It is an extension of the two four-bar mechanism proposed in [2]. When the mechanism reaches the horizontal position, the number of the degrees of freedom instantaneously increase from 1 to  $N+1$ . Gravity is on the negative  $y$  direction.

Tab. 1 reports the system properties.

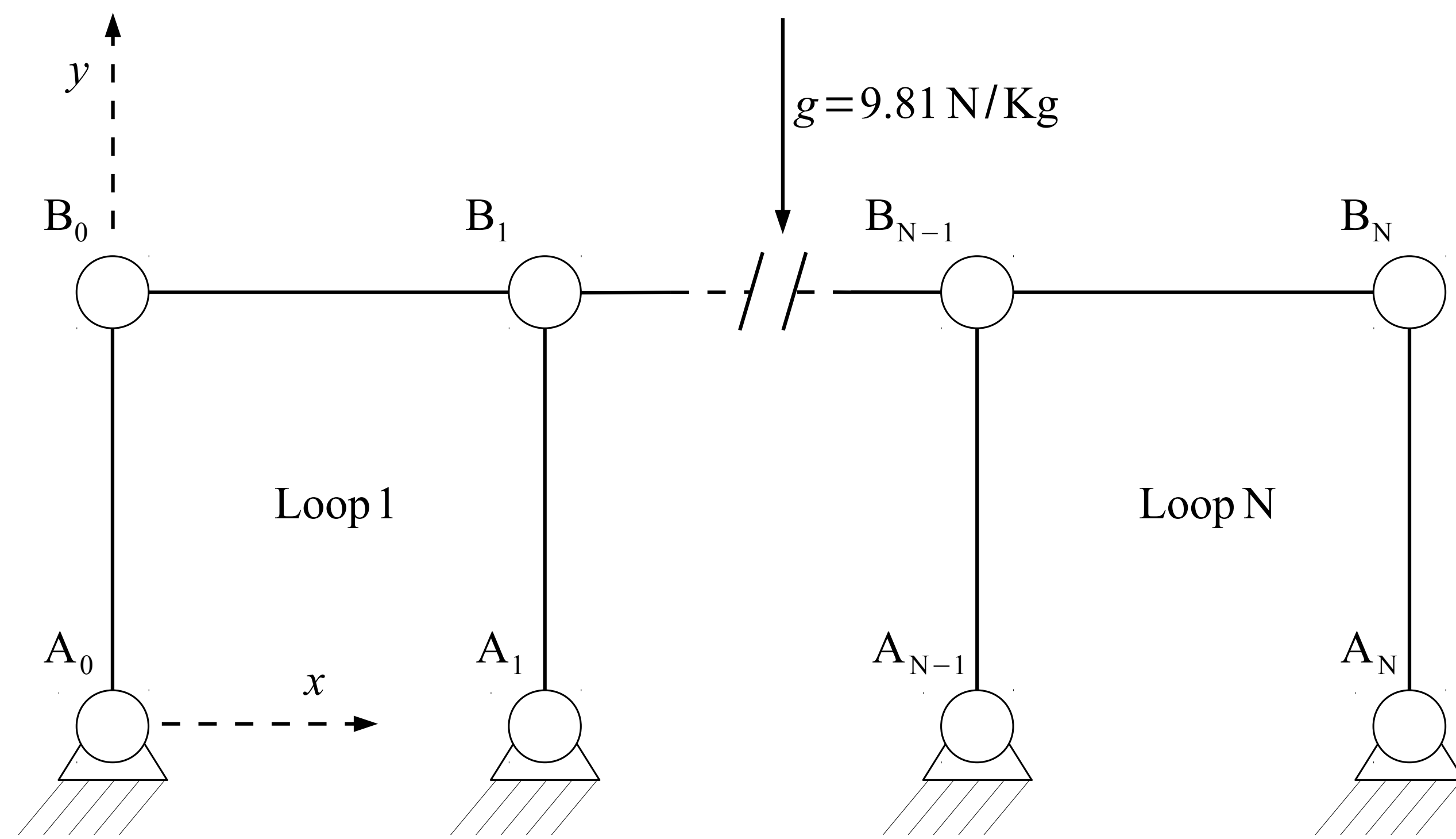


Figure 1: N four-bar mechanism sketch.

$N$	40
Link mass	1.0 kg
Link length	1.0 m
$\dot{B}_0 x(0)$	1.0 m/s

Table 1: System Properties and Configuration

## Results

The dynamic simulation of the **A02** benchmark was executed for 20s. The starting position of the simulation is shown in Fig. 1 with an initial speed for the point  $B_0$  in the positive  $x$ -direction of  $1 \text{ m s}^{-1}$ . The objective of the simulation is to measure the displacement of  $B_0$ , and compare the results with the reference solution [1]. The simulation with OpenSim perfectly matches the reference values. Fig. 2 shows a 10s simulation.

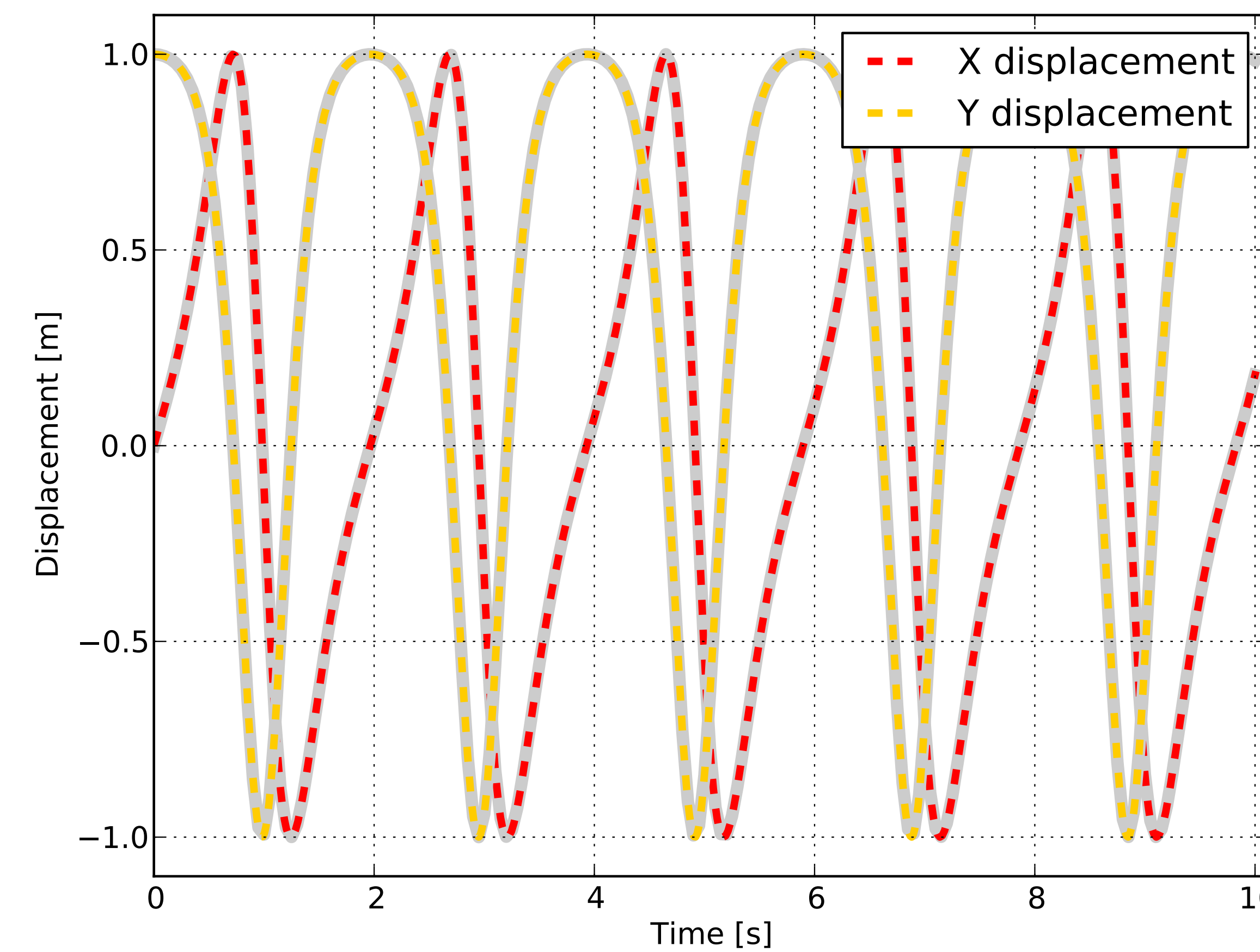


Figure 2:  $B_0$  displacement in OpenSim simulation (dashed lines) and MBS benchmark reference values (gray lines).

## Download

- MBS Benchmark available at: <http://goo.gl/ySQ5me>
- OpenSim implementation available at: <http://goo.gl/R9t13z>
- Videos of OpenSim simulation available at: <http://goo.gl/q4G2FZ>

## References

- [1] M. González, D. Dopico, U. Lúgrís, J. Cuadrado, “A benchmarking system for MBS simulation software: Problem standardization and performance measurement,” in *Multibody System Dyn.*, vol. 6, no.2, 2006, pp. 179–190.
- [2] E. Bayo and A. Avello, “Singularity-Free Augmented Lagrangian Algorithms for Constrained Multibody Dynamics,” *Nonlinear Dyn.*, vol. 5, no. 2, 1994, pp. 209–231.

## Contact Information

Rehabilitation Engineering Group  
Department of Management and Engineering  
University of Padua

- Web: <http://reg.gest.unipd.it>
- Email: [reg.info@gest.unipd.it](mailto:reg.info@gest.unipd.it)