

# COMPSCI 220: Introduction to Graph Algorithms

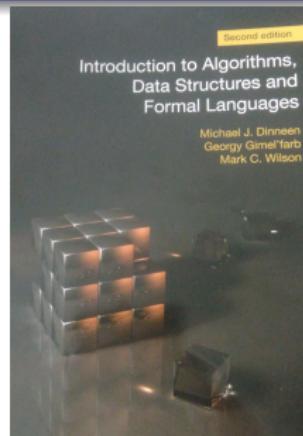
Lecturer: **Michael J. Dinneen**<sup>1</sup>

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Semester 2, 2023



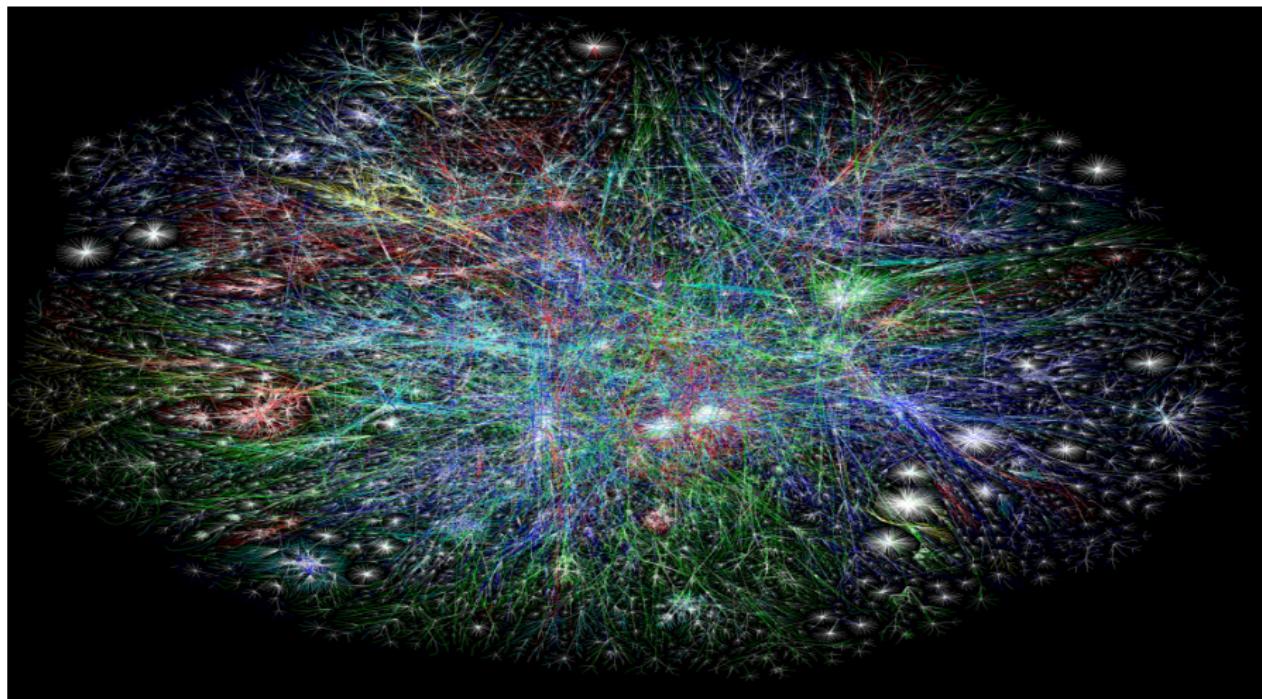
- 1 The Graph Abstract Data Type
- 2 Basic Definitions
- 3 Graph Representation and Data Structures
- 4 Python Graph Implementation

# Graphs in Life: World Air Routes



<http://milenomics.com/2014/05/partners-alliances-partner-awards/>

# Graphs in Life: Global Internet Connections



<http://www.opte.org/maps/>

# Graphs in Life: Social Networks (Facebook)



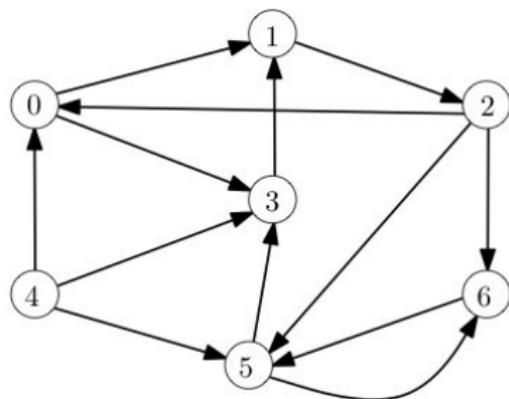
<http://robotmonkeys.net/wp-content/uploads/2010/12/social-nets-then-and-now-fb-cities-airlines-data>

# Directed Graph, or Digraph: Definition

A **digraph**  $G = (V, E)$  is a finite nonempty set  $V$  of **nodes** together with a (possibly empty) set  $E$  of ordered pairs of nodes<sup>o</sup> of  $G$  called **arcs**.

$$V = \{ 0, 1, 2, 3, 4, 5, 6 \}$$

$$\begin{aligned} E = & \{ (0, 1), (0, 3), \\ & (1, 2), \\ & (2, 0), (2, 5), (2, 6), \\ & (3, 1), \\ & (4, 0), (4, 3), (4, 5), \\ & (5, 3), (5, 6), \\ & (6, 5) \} \end{aligned}$$

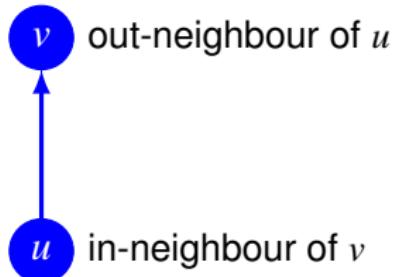


<sup>o</sup>) Set  $E$  is a neighbourhood, or adjacency relation on  $V$ .

# Digraph: Relations of Nodes

If  $(u, v) \in E$ ,

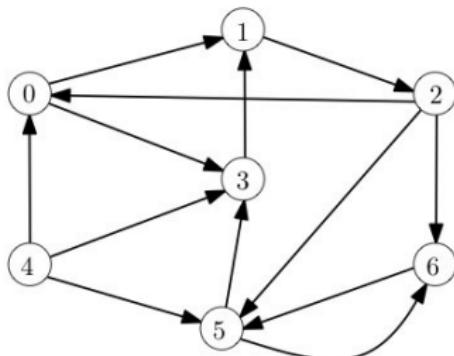
- $v$  is **adjacent** to  $u$ ;
- $v$  is an **out-neighbour** of  $u$ , and
- $u$  is an **in-neighbour** of  $v$ .



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Examples:

- Nodes (points) 1 and 3 are adjacent to 0.
- 1 and 3 are out-neighbours of 0.
- 0 is an in-neighbour of 1 and 3.
- Node 1 is adjacent to 3.
- 1 is an out-neighbour of 3.
- 3 is an in-neighbour of 1. ...
- 5 is an out-neighbour of 2, 4, and 6.

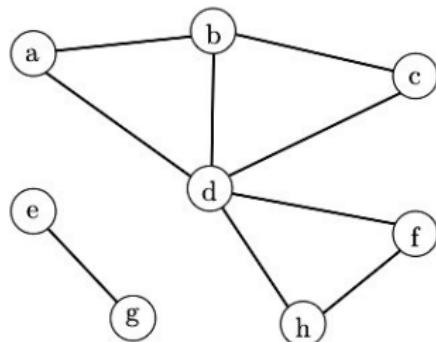


# (Undirected) Graph: Definition

A **graph**  $\circ$   $G = (V, E)$  is a finite nonempty set  $V$  of **vertices** together with a (possibly empty) set  $E$  of unordered pairs of vertices of  $G$  called **edges**.

$$V = \{a, b, c, d, e, f, g, h\}$$

$$E = \{\{a, b\}, \{a, d\}, \{b, d\}, \{b, c\}, \\ \{c, d\}, \{d, f\}, \{d, h\}, \{f, h\}, \\ \{e, g\}\}$$



- 
- The symmetric digraph: each arc  $(u, v)$  has the opposite arc  $(v, u)$ .  
Such a pair is reduced into a single undirected edge that can be traversed in either direction.

# Order, Size, and In- / Out-degree

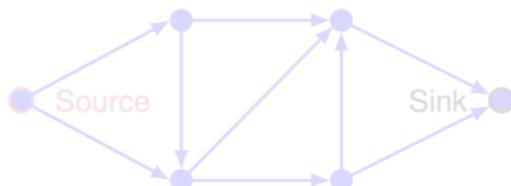
The **order** of a digraph  $G = (V, E)$  is the number of nodes,  $n = |V|$ .

The **size** of a digraph  $G = (V, E)$  is the number of arcs,  $m = |E|$ .

For a given  $n$ ,  $m = 0$  Sparse digraphs:  $|E| \in O(n)$  Dense digraphs:  $|E| \in \Theta(n^2)$   $n(n - 1)$

The **in-degree** or **out-degree** of a node  $v$  is the number of arcs entering or leaving  $v$ , respectively.

- A node of in-degree 0 – a **source**.
- A node of out-degree 0 – a **sink**.
- This example: the order  $|V| = 6$  and the size  $|E| = 9$ .



# Order, Size, and In- / Out-degree

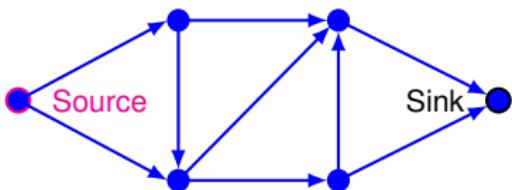
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A **walk** in a digraph  $G = (V, E)$ :

a sequence of nodes  $v_0 v_1 \dots v_n$ , such that  $(v_i, v_{i+1})$  is an arc in  $G$ , i.e.,  $(v_i, v_{i+1}) \in E$ , for each  $i; 0 \leq i < n$ .

- The **length** of the walk  $v_0 v_1 \dots v_n$  is the number  $n$  of arcs involved.
  - A **path** is a walk, in which no node is repeated.
  - A **cycle** is a walk, in which  $v_0 = v_n$  and no other nodes are repeated.
- 
- By convention, a cycle in a graph is of length at least 3.
  - It is easily shown that if there is a walk from  $u$  to  $v$ , then there is at least one path from  $u$  to  $v$ .

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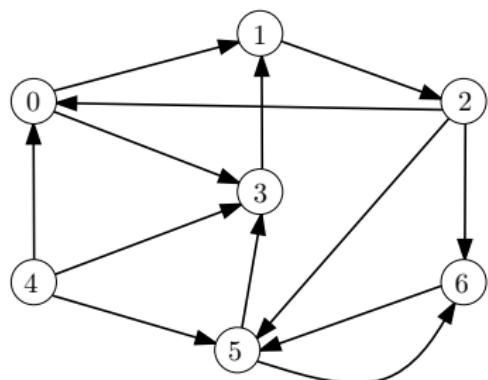
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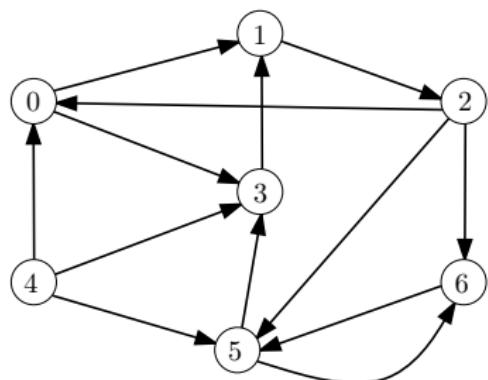
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# Walks, Paths, and Cycles in a Digraph: an Example



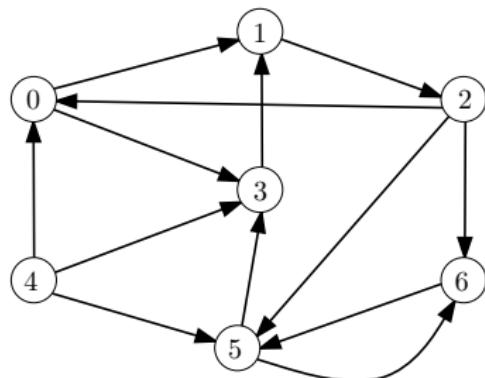
Sequence	Walk?	Path?	Cycle?
0 2 3	no	no	no
3 1 2	yes	yes	no
1 2 6 5 3 1	yes	no	yes
4 5 6 5	yes	no	no
4 3 5	no	no	no

# Walks, Paths, and Cycles in a Digraph: an Example



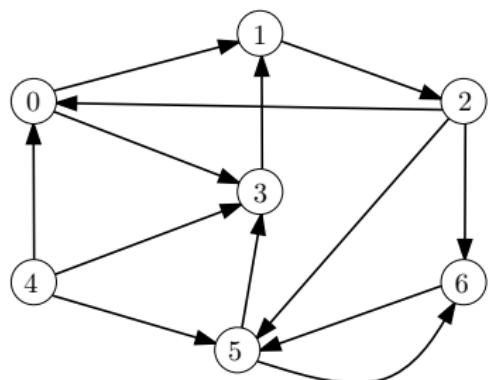
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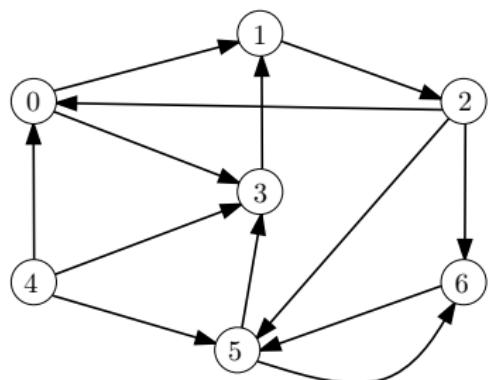
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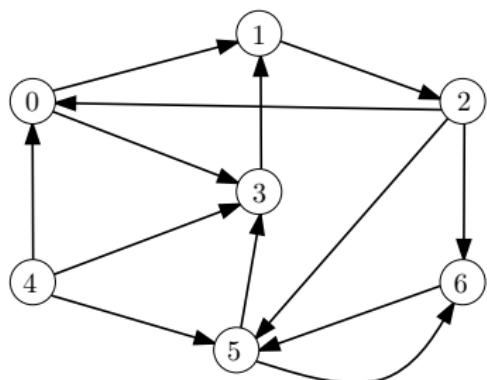
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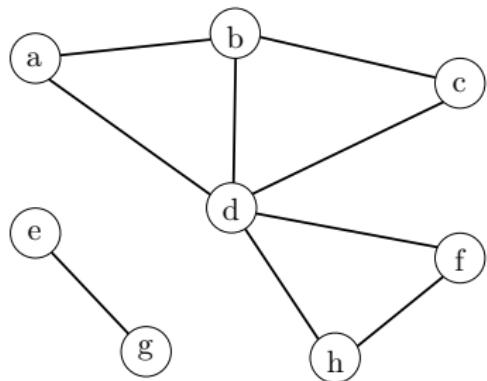
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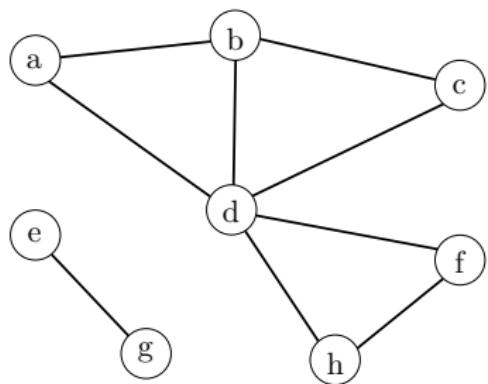
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3 1 2	yes	yes	no
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# Walks, Paths, and Cycles in a Graph: an Example



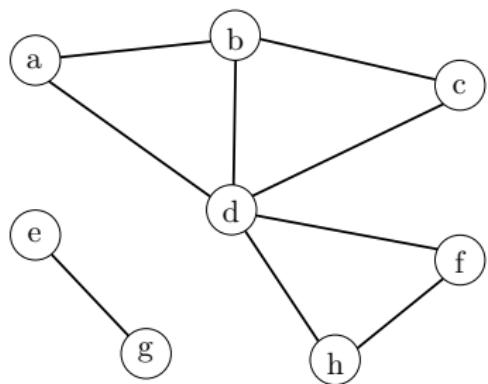
Sequence	Walk?	Path?	Cycle?
$a b c$	yes	yes	no
$e g e$	yes	no	no
$d b c d$	yes	no	yes
$d a d f$	yes	no	no
$a b d f h$	yes	yes	no

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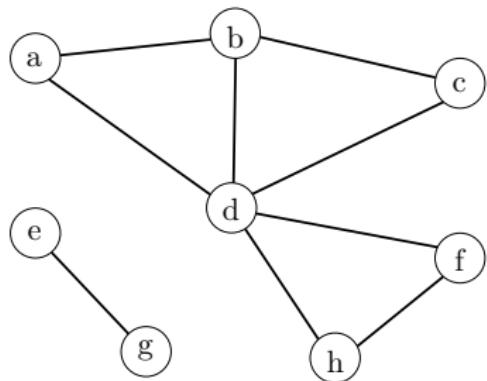
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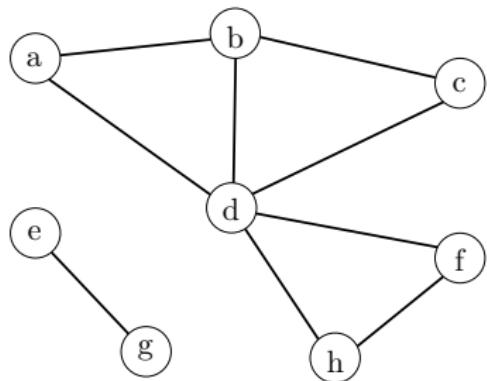
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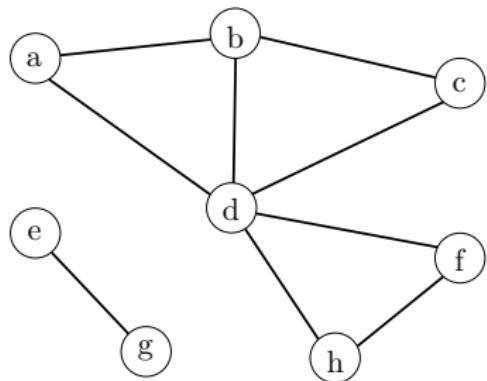
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# Digraph $G = (V, E)$ : Distances and Diameter

The **distance**,  $d(u, v)$ , from a node  $u$  to a node  $v$  in  $G$  is the *minimum* length of a path from  $u$  to  $v$ .

- If no path exists, the distance is undefined or  $+\infty$ .
- For graphs,  $d(u, v) = d(v, u)$  for all vertices  $u$  and  $v$ .

The **diameter** of  $G$  is the *maximum* distance  $\max_{u,v \in V} [d(u, v)]$  between any two vertices.

The **radius** of  $G$  is  $\min_{u \in V} \max_{v \in V} [d(u, v)]$ .

A graph is **connected** if it has finite radius and diameter.

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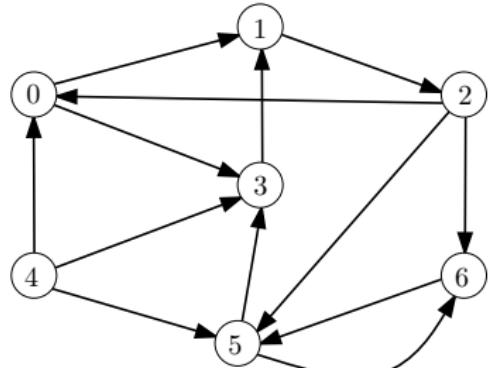
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# Path Distances in Digraphs: Examples

$$\begin{aligned}d(0, 3) &= \min\{\text{length}_{0,3}; \text{length}_{0,1,2,6,5,3}; \text{length}_{0,1,2,5,3}\} \\&= \min\{1; 5; 4\} = 1\end{aligned}$$



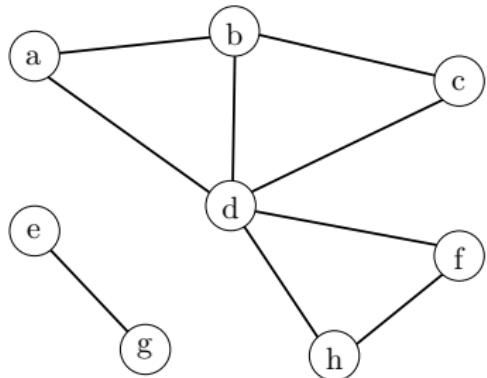
	v						
u=0	0	1	2	3	4	5	6
u=1	2	-	1	3	$\infty$	2	2
u=2	1	3	-	2	$\infty$	1	1
u=3	3	1	2	-	$\infty$	3	3
u=4	1	2	3	1	-	1	2
u=5	4	2	3	1	$\infty$	-	1
u=6	5	3	4	2	$\infty$	1	-

$$\begin{aligned}d(0, 1) &= 1, d(0, 2) = 2, d(0, 5) = 3, d(0, 4) = \infty, d(5, 5) = 0, d(5, 2) = 3, \\d(5, 0) &= 4, d(4, 6) = 2, d(4, 1) = 2, d(4, 2) = 3\end{aligned}$$

**Diameter:**  $\max\{1, 2, 1, \infty, 3, \dots, 4, \dots, 5, \dots, 1\} = \infty$

**Radius:**  $\min\{\infty, \infty, \dots, 3, \infty, \infty\} = 3$

# Path Distances in Graphs: Examples



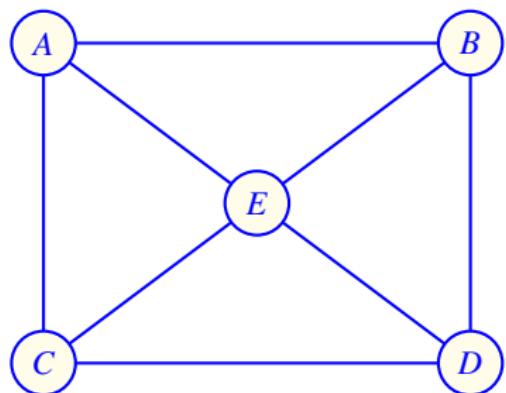
	v							
u=a	a	b	c	d	e	f	g	h
u=b	0	1	2	1	$\infty$	2	$\infty$	2
u=c	1	0	1	1	$\infty$	2	$\infty$	2
u=d	2	1	0	1	$\infty$	2	$\infty$	2
u=e	1	1	1	0	$\infty$	1	$\infty$	1
u=f	$\infty$	$\infty$	$\infty$	$\infty$	0	$\infty$	1	$\infty$
u=g	2	2	2	1	$\infty$	0	$\infty$	1
u=h	$\infty$	$\infty$	$\infty$	$\infty$	1	$\infty$	0	$\infty$
	2	2	2	1	$\infty$	1	$\infty$	0

$$\begin{aligned}d(a, b) &= d(b, a) = 1, \quad d(a, c) = d(c, a) = 2, \quad d(a, f) = d(f, a) = 2, \\d(a, e) &= d(e, a) = \infty, \quad d(e, e) = 0, \quad d(e, g) = d(g, e) = 1, \quad d(h, f) = d(f, h) = 1, \\d(d, h) &= d(h, d) = 1\end{aligned}$$

**Diameter:**  $\max\{0, 1, 2, 1, \infty, 2, \dots, 2, \dots, 0\} = \infty$

**Radius:**  $\min\{\infty, \dots, \infty\} = \infty$

# Diameter / Radius of an Unweighted Graph



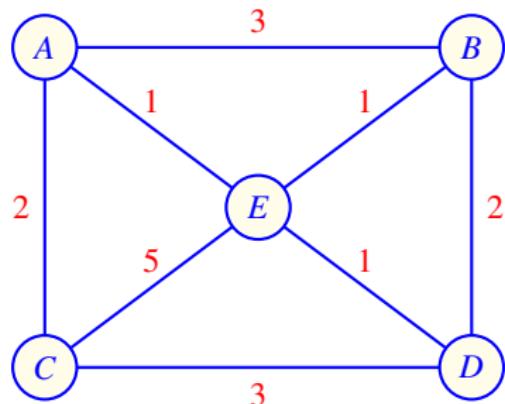
	A	B	C	D	E	$\max_v d(u,v)$
A	0	1	1	2	1	2
B	1	0	2	1	1	2
C	1	2	0	1	1	2
D	2	1	1	0	1	2
E	1	1	1	1	0	1

$$d(C, E) = d(E, C) = 1$$

$$d(B, C) = d(C, B) = 2$$

Radius = 1; diameter = 2.

# Diameter / Radius of a Weighted Graph



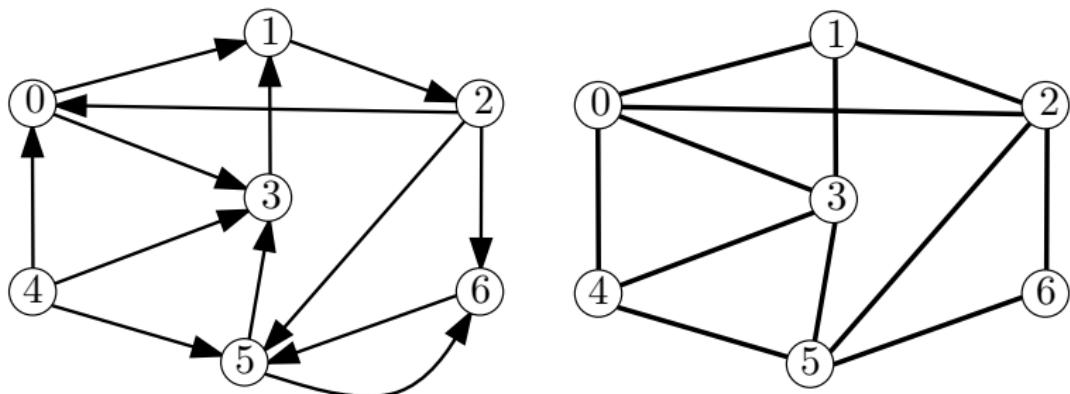
	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>	$\max_v d(u,v)$
<i>A</i>	0	2	2	2	1	2
<i>B</i>	2	0	4	2	1	4
<i>C</i>	2	4	0	3	3	4
<i>D</i>	2	2	3	0	1	3
<i>E</i>	1	1	3	1	0	3

$$\begin{aligned}d(C, E) &= d(E, C) \\&= \min\{5, 2 + 1, 3 + 1, 2 + 3 + 1, 3 + 2 + 1\} = 3 \\d(B, C) &= d(C, B) \\&= \min\{3 + 2, 1 + 1 + 2, 1 + 5, 1 + 1 + 3, 2 + 3, 2 + 1 + 5\} = 4\end{aligned}$$

Radius = 2; diameter = 4.

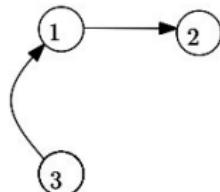
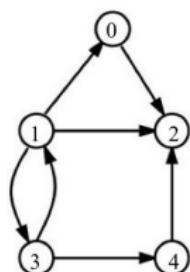
# Underlying Graph of a Digraph

The **underlying graph** of a digraph  $G = (V, E)$  is the graph  $G' = (V, E')$  where  $E' = \{\{u, v\} \mid (u, v) \in E\}$ .



# Sub(di)graphs

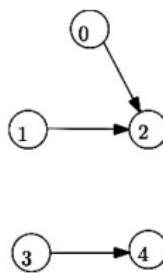
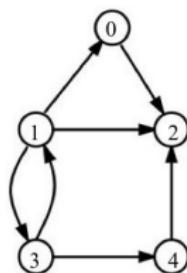
A **subdigraph** of a digraph  $G = (V, E)$  is a digraph  $G' = (V', E')$  where  $V' \subseteq V$  and  $E' \subseteq E$ .



$$G = \left( \begin{array}{l} V = \{0, 1, 2, 3, 4\}, \\ E = \left\{ \begin{array}{l} (0, 2), (1, 0), (1, 2), \\ (1, 3), (3, 1), (4, 2), \\ (3, 4) \end{array} \right\} \end{array} \right) \quad G' = \left( \begin{array}{l} V' = \{1, 2, 3\}, \\ E' = \{(1, 2), (3, 1)\} \end{array} \right)$$

# Spanning Sub(di)graphs

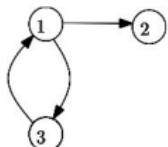
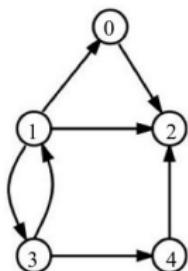
A **spanning** subdigraph contains all nodes, that is,  $V' = V$ .



$$G = \left( \begin{array}{l} V = \{0, 1, 2, 3, 4\}, \\ E = \left\{ (0, 2), (1, 0), (1, 2), (1, 3), (3, 1), (4, 2), (3, 4) \right\} \end{array} \right) \quad G' = \left( \begin{array}{l} V' = \{0, 1, 2, 3, 4\}, \\ E' = \left\{ (0, 2), (1, 2), (3, 4) \right\} \end{array} \right)$$

# Induced Sub(di)graphs

The subdigraph **induced** by a subset  $V'$  of  $V$  is the digraph  $G' = (V', E')$  where  $E' = \{(u, v) \in E \mid u \in V' \text{ and } v \in V'\}$ .



$$G = \left( \begin{array}{l} V = \{0, 1, 2, 3, 4\}, \\ E = \left\{ (0, 2), (1, 0), (1, 2), (1, 3), (3, 1), (4, 2), (3, 4) \right\} \end{array} \right) \quad G' = \left( \begin{array}{l} V' = \{1, 2, 3\}, \\ E' = \left\{ (1, 2), (1, 3), (3, 1) \right\} \end{array} \right)$$

# Digraphs: Computer Representation

For a digraph  $G$  of order  $n$  with the vertices,  $V$ , labelled  $0, 1, \dots, n - 1$ :

The **adjacency matrix** of  $G$ :

The  $n \times n$  boolean matrix (often encoded with 0's and 1's) such that its entry  $(i, j)$  is true if and only if there is an arc  $(i, j)$  from the node  $i$  to node  $j$ .

An **adjacency list** of  $G$ :

A sequence of  $n$  sequences,  $L_0, \dots, L_{n-1}$ , such that the sequence  $L_i$  contains all nodes of  $G$  that are adjacent to the node  $i$ .

Each sequence  $L_i$  may not be sorted! But we often sort them.

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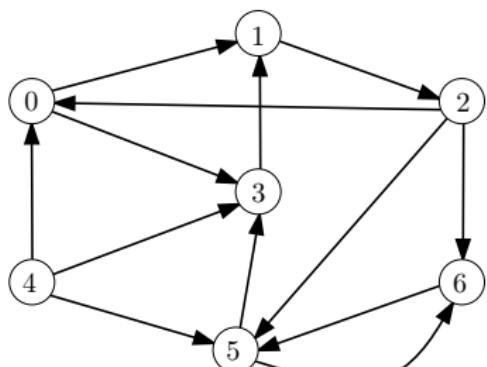
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# Adjacency Matrix of a Digraph



Digraph  $G = (V, E)$

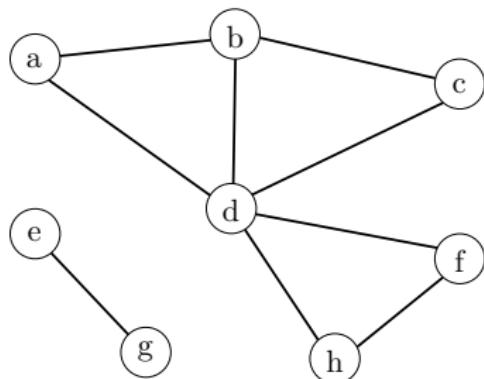
	0	1	2	3	4	5	6
0	0	1	0	1	0	0	0
1	0	0	1	0	0	0	0
2	1	0	0	0	0	1	1
3	0	1	0	0	0	0	0
4	1	0	0	1	0	1	0
5	0	0	0	1	0	0	1
6	0	0	0	0	0	1	0

Adjacency matrix of  $G$ :

- 0 – a non-adjacent pair of vertices:  
 $(i, j) \notin E$
- 1 – an adjacent pair of vertices:  
 $(i, j) \in E$

The number of 1's in a row (column) is the out-(in-) degree of the related node.

# Adjacency Lists of a Graph



Graph  $G = (V, E)$

## symbolic

- 0 = a: b d
- 1 = b: a c d
- 2 = c: b d
- 3 = d: a b c f h
- 4 = e: g
- 5 = f: d h
- 6 = g: e
- 7 = h: d f

## numeric

- 8
- 1 3
- 0 2 3
- 1 3
- 0 1 2 5 7
- 6
- 3 7
- 4
- 3 5

Here the first line of the **numeric** representation is the graph's order  $n$ . Vertices are usually indexed from 0 to  $n - 1$ .

# Digraph Operations w.r.t. Data Structures

Operation	Adjacency Matrix	Adjacency Lists
arc $(i,j)$ exists?	is entry $(i,j)$ 0 or 1	find $j$ in list $i$
out-degree of $i$	scan row and sum 1's	size of list $i$
in-degree of $i$	scan column and sum 1's	for $j \neq i$ , find $i$ in list $j$
add arc $(i,j)$	change entry $(i,j)$	insert $j$ in list $i$
delete arc $(i,j)$	change entry $(i,j)$	delete $j$ from list $i$
add node	create new row/column	add new list at end
delete node $i$	delete row/column $i$ and shuffle other entries	delete list $i$ and for $j \neq i$ , delete $i$ from list $j$

# Adjacency Lists / Matrices: Comparative Performance

$$G = (V, E) \quad \xrightarrow{\hspace{1cm}} \quad n = |V|; \quad m = |E|$$

Operation	adj. matrix	adj. lists
arc $(i, j)$ exists?	$\Theta(1)$	$\Theta(\alpha)$
out-degree of $i$	$\Theta(n)$	$\Theta(1)$
in-degree of $i$	$\Theta(n)$	$\Theta(n + m)$
add arc $(i, j)$	$\Theta(1)$	$\Theta(1)$
delete arc $(i, j)$	$\Theta(1)$	$\Theta(\alpha)$
add node	$\Theta(n)$	$\Theta(1)$
delete node $i$	$\Theta(n^2)$	$\Theta(n + m)$

Here,  $\alpha$  denotes size of the adjacency list for vertex  $i$ .

Special cases can be stored more efficiently or convenient for algorithms:

- A complete binary tree or a heap: in an array.
- A general rooted tree: in an array  $\text{pred}$  of size  $n$ ;  
 $\text{pred}[i]$  – a pointer to the parent of node  $i$ .
- Mathematical: Set of vertices and set of edges  
(pairs/tuples).
- Lists of dictionaries (of neighbours).
- Edge incidence matrix (see COMPSCI 320).
- Sparse graphs of bounded pathwidth, treewidth or  
branchwidth (see COMPSCI 720).

# Graph Adjacency Matrix in Python

```
n = 3 # order of graph
M = [[0]*n for _ in range(n)] # can use False/True
M[0][2],M[1][2] = 1,1 # add two arcs (directed edges)
print("M1:", M)
M[1][0],M[1][2],M[2][1] = 1,0,1 # add two, remove one
print("M2:", M)
M.append([0]*n) # add new node/vertex (row)
n += 1
for i in range(n): M[i].append(0) # extend all rows
print("M3:", M)
```

Output should be:

M1: [[0, 0, 1], [0, 0, 1], [0, 0, 0]]

M2: [[0, 0, 1], [1, 0, 0], [0, 1, 0]]

M3: [[0, 0, 1, 0], [1, 0, 0, 0], [0, 1, 0, 0], [0, 0, 0, 0]]

# Graph Adjacency Lists in Python

```
n = 3 # order of graph
M = [] for _ in range(n)           # n empty lists
M[0].append(2); M[1].append(2)    # add two arcs
print("M1:", M)
M[1].append(0); M[2].append(1)    # add two more arcs
M[1].remove(2)                  # and remove one
print("M2:", M)
n += 1                         # add new node/vertex (list)
M.append([])
print("M3:", M)
```

Output should be:

```
M1: [[2], [2], []]
M2: [[2], [0], [1]]
M3: [[2], [0], [1], []]
```

# Simple Graph ADT in Python

```
class AdjacencyLists:  
    """  
        AdjacencyLists stores the state of vertices and arcs  
        as a list of lists. The arc (i,j) is represented by  
        the list at element i containing the value j.  
    """  
  
    def __init__(self):  
        self._adj = [] # Creates an internal empty array  
  
    def empty(self): self._adj = []  
  
    def order(self):  
        return len(self._adj)  
  
    def size(self):  
        return reduce(  
            lambda x, y : x + y, # Add up the lengths of  
            map(len, self._adj), # every row's list  
            0 ) # Initial value 0
```

```
def addVertices(self, n):
    if not 0 <= n:
        raise ValueError('Argument is negative!')

    for i in range(n): self._adj.append([])

def removeVertex(self, i):
    if not 0 <= i < self.order():
        raise ValueError('Arguments out of bounds')

    del self._adj[i] # Delete this vertex's list

    for otherVertex in range(self.order()):
        current = self._adj[otherVertex]
        try:
            current.remove(i) # Try to remove node i
        except ValueError:
            pass # It didn't appear

    for j in range(len(current)): # Relabel
        if current[j] > i: current[j] -= 1
```

```
def addArc(self, i, j):
    if not (0 <= i < self.order() and \
            0 <= j < self.order()):
        raise ValueError('Arguments out of bounds')

    if not self.isArc(i, j):      # Avoid multi-edges
        self._adj[i].append(j)

def removeArc(self, i, j):
    if not (0 <= i < self.order() and \
            0 <= j < self.order()):
        raise ValueError('Arguments out of bounds')
    try:
        self._adj[i].remove(j)
    except ValueError:
        pass # Not found

def addEdge(self, i, j):
    self.addArc(i,j); self.addArc(j,i)
def removeEdge(self, i, j):
    self.removeArc(i,j); self.removeArc(j,i)
```

```
def isArc(self, i, j):
    if not (0 <= i < self.order() and \
            0 <= j < self.order()):
        raise ValueError('Arguments out of bounds')
    return j in self._adj[i]

def isEdge(self, i, j):
    return self.isArc(i,j) and self.isArc(j,i)

def degree(self, i):
    if not 0 <= i < self.order():
        raise ValueError('Argument out of bounds')
    return len(self._adj[i])

def inDegree(self, i):
    if not 0 <= i < self.order():
        raise ValueError('Argument out of bounds')
    retval = 0
    for j in range(self.order()):
        if self.isArc(j, i): retval += 1
    return retval
```

```
def neighbors(self, i):
    if not 0 <= i < self.order():
        raise ValueError('Argument out of bounds')

    # Returning a copy that is safe for modification
    return sorted(self._adj[i])

neighbours = neighbors # Permit the Old English /
                      British spelling

def read(self, stream): # CompSci 220 format
    self.empty()
    order = int(stream.readline().strip())
    self.addVertices(order)
    for i in range(order):
        for neighbor in map(int, \
                           stream.readline().strip().split()):
            self.addArc(i, neighbor)
```