



Práctica 1: Diseño de controladores

Departamento de Ingeniería Eléctrica y Electrónica, Ingeniería Biomédica

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Información general



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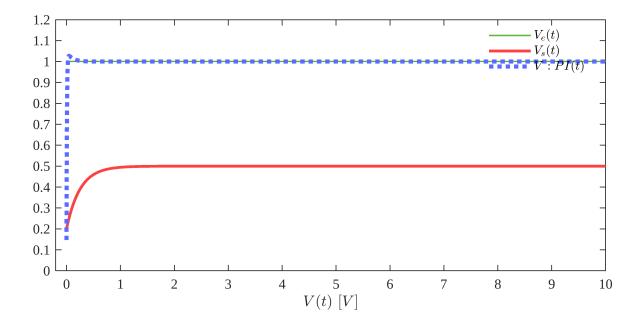
Asignatura: Modelado de Sistemas Fisiológicos

Datos de la simulación

```
clc; clear; close all; warning('off','all')
tend = "10";
file= "P1";
open_system(file);
parameters.StopTime = tend;
parameters.Solver= "ode45";
parameters.MaxStep="1E-3";
Controlador="PI";
```

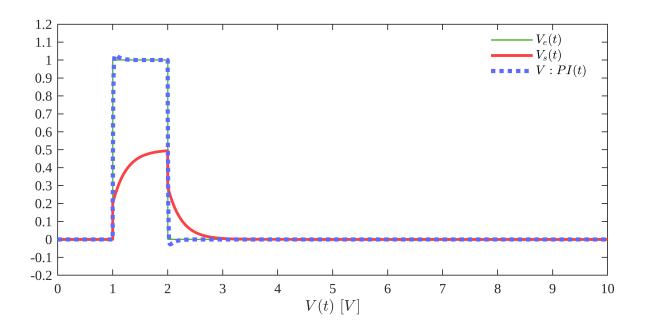
Respuesta al escalón

```
Signal="Escalon";
set_param("P1/S1","sw","1")
set_param("P1/Ve(t)","sw","1")
x1=sim(file,parameters);
plotsignals(x1.t,x1.Ve,x1.Vs,x1.VPID,Controlador,Signal)
```



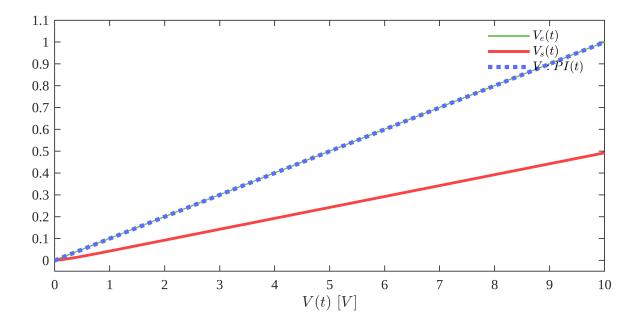
Respuesta al impulso

```
Signal="Impulso";
set_param("P1/S1","sw","0")
set_param("P1/Ve(t)","sw","1")
x2=sim(file,parameters);
plotsignals(x2.t,x2.Ve,x2.Vs,x2.VPID,Controlador,Signal)
```



Respuesta a la rampa

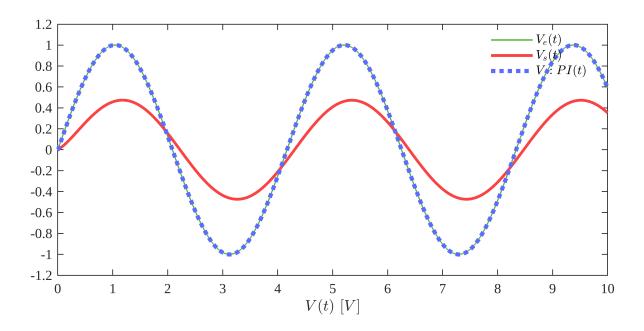
```
Signal="Rampa";
set_param("P1/S2","sw","1")
set_param("P1/Ve(t)","sw","0")
x3=sim(file,parameters);
plotsignals(x3.t,x3.Ve,x3.Vs,x3.VPID,Controlador,Signal)
```



Respuesta a la función sinusoidal

```
Signal="Sinusoidal";
set_param("P1/S2","sw","0")
set_param("P1/Ve(t)","sw","0")
```

```
x4=sim(file,parameters);
plotsignals(x4.t,x4.Ve,x4.Vs,x4.VPID,Controlador, Signal)
```



Función: Respuesta a las señales

```
function plotsignals(t, Ve, Vs, VPID, Controlador, Signal)
    set(figure(), "Color", "w")
    set(gcf, "units", "Centimeters", "Position", [1,1,18,8])
    set(gca, "FontName", "Times New Roman")
    fontsize(10, "points")
    c1 = [92/255, 179/255, 56/255];
    c2 = [251/255,65/255,65/255];
    c3 = [92/255, 107/255, 255/255];
    hold on; grid off; box on
    plot(t, Ve, "LineWidth", 1, "Color", c1)
    plot(t, Vs, "LineWidth", 2, "Color", c2)
    plot(t, VPID, ":", "LineWidth", 3, "Color", c3)
    xlabel("$t$ $[s]$","Interpreter","Latex")
    xlabel("$V(t)$ $[V]$","Interpreter","Latex")
    L= legend("V_{e}(t),","V_{s}(t),","V:\{PI\}(t),");
    set(L, "Interpreter", "Latex", "Location", "Best", "Box", "Off")
    if Signal== "Escalon"
        xlim([-0.2,10]); xticks(0:1:10)
        ylim([0,1.2]); yticks(0:0.1:1.2)
        elseif Signal=="Impulso"
```

```
xlim([0,10]); xticks(0:1:10)
ylim([-0.2,1.2]); yticks(-0.2:0.1:1.2)
elseif Signal=="Rampa"
```