Project2 Introduction

1 Components

I create two threads in main function: <u>ProcessSche</u> and <u>PageRep</u>. These two threads work simultaneously so that they can simulate how CPU and memory work. After I read project2 problem statement file, the first idea of the project is that thread programming can achieve these requirements. But after I finished this project I exchanged my idea with some classmates and I found out that they did not use any thread. I reviewed my program and I found out that actually a single thread was absolutely able to achieve these requirements. But the time is not enough because I have to change lots of code to convert two threads to a single thread. So this is the final version. I will introduce these two threads in Section 3. All include files are as follows.

- Include files:
- Struct.h: includes all structures used in this project. Structure <u>PSarg</u> is used to transmit parameters to thread <u>ProcessSche</u>. Structure <u>PRarg</u> is used to transmit parameters to thread <u>PageRep</u>. Structure <u>process</u> includes all sufficient variables to describe a process, such as <u>name</u>, <u>startTime</u>, <u>CPUTime</u> and so on. Structure <u>page</u> is used to describe how page behaves in page replacement algorithms, which has three variables: <u>refBit</u>, which is reference bit <u>,addr</u>, which is the address of the page that result in page fault, and <u>pid</u>, which the process id of the page, for example, the pid of P1 is 0, the pid of P2 is 1, the pid of P3 is 2 and so on.
- Queue.h: includes two classes: <u>Queue</u> and <u>circularQueue</u>. <u>Queue</u> is similar to STL class queue; <u>circularQueue</u> describes a circular queue. I add some functions in them in order to make them convenient to use.
- priorityQueue.h: includes a class <u>priorityQueue</u>, which is similar to STL class priority_queue. It is based on a array, and is used for <u>arrivalQueue</u> in thread <u>processSche</u>, because the element of <u>arrivalQueue</u> is sorted by the order of time.
- Mem.h: includes a class <u>Mem</u>, it simulates how memory deals with page fault.
 This class has a <u>Queue</u> named <u>memory</u> to store page address, and is used by fifo and lru algorithm; it also has a <u>priorityQueue</u> named <u>pageQueue</u>, and is only used by second-chance algorithm.
- 2 Poilicy decisions
 - 2.1 The program first read the scheduling trace file, and push() all the processes to <u>arrivalQueue</u>, which is a priority queue. Then thread <u>ProcessSche</u> and <u>PageRep</u> starts to work.
 - 2.2 There is a increasing counter in <u>ProcessSche</u> named <u>currentCycle</u>. If it equals to the <u>startTime</u> of the first process of <u>arrivalQueue</u>, then pop() <u>arrivalQueue</u>, and push() it to the end of <u>readyQueue</u>.
 - 2.3 If a instruction results in a page fault, then the process will be removed from the scheduler, pushed to the end of <u>blockQueue</u>, and let the next process in <u>readyQueue</u> to execute. At the same time, thread <u>PageRep</u> will deal with the new process in <u>blockQueue</u> by different methods according to the replacement policy you enter.
 - 2.4 In thread <u>PageRep</u>, the <u>startTime</u> of the process will be updated, and pushed to the end of <u>arrivalQueue</u>. So the next time this process starts up, a page faullt probably may happen again.
- 3 Introduction of threads and their synchronization

3.1 ProcessSche

This thread simulates how scheduler works. In each loop, a increasing counter <u>currentCycle</u> is increased by 1 to record the current cycle. If <u>currentCycle</u> equals to the first of <u>arrivalQueue</u>, it means a new process arrives, so push it to the end of <u>readyQueue</u>. Then follow these steps:

- 1. check whether <u>status</u> is <u>CONTEXTSWITCH</u>, if so, continue to the next loop; else go to step 2
- 2. if there is no <u>runningProcess</u>, go to step 3; else go to step 6
- 3. if <u>readyQueue</u> is empty, go to step 4; if not, go to step 5
- 4. increase <u>noExecTime</u> by 1, go to step 5
- 5. pop() the first process of <u>readyQueue</u>, and let it be <u>runningProcess</u>, go to step 6
- 6. read the current instruction from the memory traces, and check if it is in memory, if so, increase <a href="mailto:execution-execut
- 7. increase <u>currentCycle</u> by 1, go to step 1. The thread will follow those steps until the number of finished process equals to the total number of processes.

3.2 PageRep

This thread simulate how memory deals with page fault. In each loop, follow these steps: 1. if <u>blockQueue</u> is not empty, then pop() <u>blockQueue</u>, and do page replacement according to the policy you enter, update the <u>startTimeCycle</u> of this process, push() it to <u>arrivalQueue</u>, and continue to the next loop

2. if <u>blockQueue</u> is empty, continue to the next loop.

The thread will follow those steps until the number of finished process equals to the total number of processes.

3.3 Synchronization

There are two threads running simultaneously in this program, so it is significant to synchronize them perfectly, otherwise error is likely to happen, such as deadlock, or wrong result may happen.

- 3.3.1 Because thread <u>ProcessSche</u> and <u>PageRep</u> work at the same time, and move page from disk to memory costs 1000 cycles, so in the 1000 cycles to come, the process must be pushed back to <u>arrivalQueue</u> again, or <u>ProcessSche</u> has to wait for it, otherwise the time will exceed 1000 plus the time when it blocked, and those processes which are supposed to be later than this process will be earlier than it. To implement this function, every time <u>PageRep</u> move a page from disk to memory, it signal a semaphore <u>page_fault</u>. In <u>ProcessSche</u>, after 1000 plus the time a page fault happens it wait the semaphore <u>page_fault</u>.
- 3.3.2 <u>arrivalQueue blockQueue</u> and <u>validPage</u> are shared by these two threads, so there are three mutex <u>arrivalQueue mutex blockQueue mutex</u> and <u>validPage mutex</u>.

4 Experiment result presentation

4.1 page replacement algorithm

| Memory size: 500, quntum: 50000, sche_traces_big.txt | | | | | | | |
|--|--------------------------|-----------------------|-------------------|----------------------------|--|--|--|
| page replacement algorithm | total elapsed time/cycle | total idle time/cycle | total page faults | average elapsed time/cycle | | | |
| fifo | 7490260966 | 7477408972 | 7489479 | 4998531490 | | | |
| lru | 6724043865 | 6711191871 | 6723185 | 4565145542 | | | |
| 2ch-alg | 6731502348 | 6718650354 | 6730612 | 4571226048 | | | |

It is clear that lru performs better than the other two algorithms, while fifo is the worst. Yet second-chance algorithm is not that bad. FIFO is easy to implement but does not perform well. LRU algorithm needs more hardware and software support so that it performs better. And 2ch-alg is a compromise, because it is not complicated as LRU algorithm, but is more efficient than FIFO.

4.2 Time quntum

| page replacement algorithm: 2ch-alg, memory size: 500, sche_traces_big.txt | | | | | | | |
|--|---------------------------|------------------------|-------------------|-----------------------------|--|--|--|
| quntum/cycles | total elapsed time/cycles | total idle time/cycles | total page faults | average elapsed time/cycles | | | |
| 10000 | 6569195336 | 6556343342 | 6568447 | 4403496691 | | | |
| 50000 | 6731502348 | 6718650354 | 6730612 | 4571226048 | | | |
| 200000 | 6723008906 | 6710156912 | 6722138 | 4565657313 | | | |

We can find out that larger time quntum results in worse performance. It is because if the time quntum is too large, round robin policy degenerates to FCFS policy, which is not efficient as RR policy.

4.3 Memory size

| page replacement algorithm: 2ch-alg, quntum: 50000, sche_traces_big.txt | | | | | | | |
|---|---------------------------|------------------------|-------------------|-----------------------------|--|--|--|
| memory size | total elapsed time/cycles | total idle time/cycles | total page faults | average elapsed time/cycles | | | |
| 150 | 11907315051 | 11894463057 | 11906770 | 8118111147 | | | |
| 500 | 6731502348 | 6718650354 | 6730612 | 4571226048 | | | |
| 5000 | 19346479 | 6494485 | 9973 | 3878692 | | | |

I fail to run this program if the memory size is only 50. It is probably because the process that has page fault will fault again for the same page. 150 is much smaller than 500, I think it can take the place of 50 in this experiment, and is also able to represent a small memory in a computer.

From these data, it is clear that the bigger the memory size is, the better the program performs. It is because more memory size means less page fault. In extreme condition, if memory size is the same as disk, there will be only one page fault for each page.