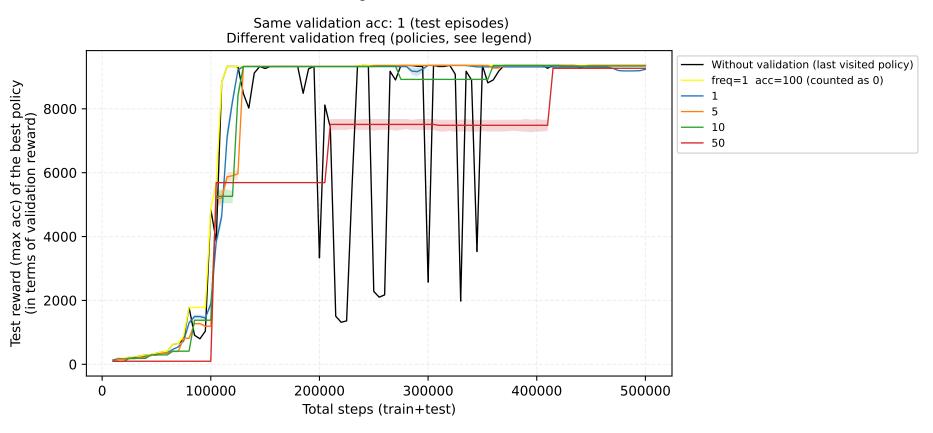
## Learning-curves with



(2048 train steps = training 1 policy = 1 trajectory)