

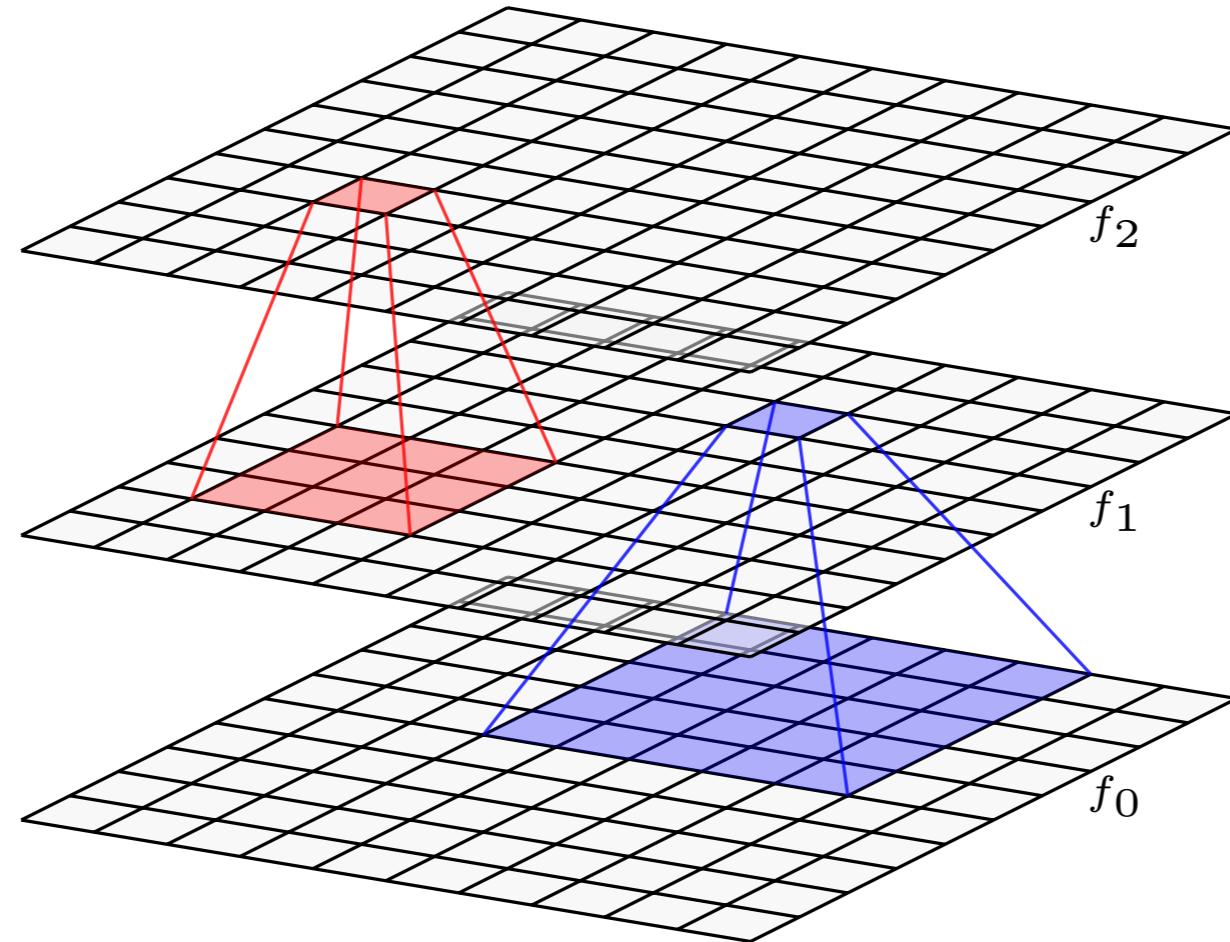
On the Generalization of Convolution to the Action of Compact Groups

Risi Kondor
The University of Chicago

Shubhendu Trivedi
Toyota Technological Institute, Chicago

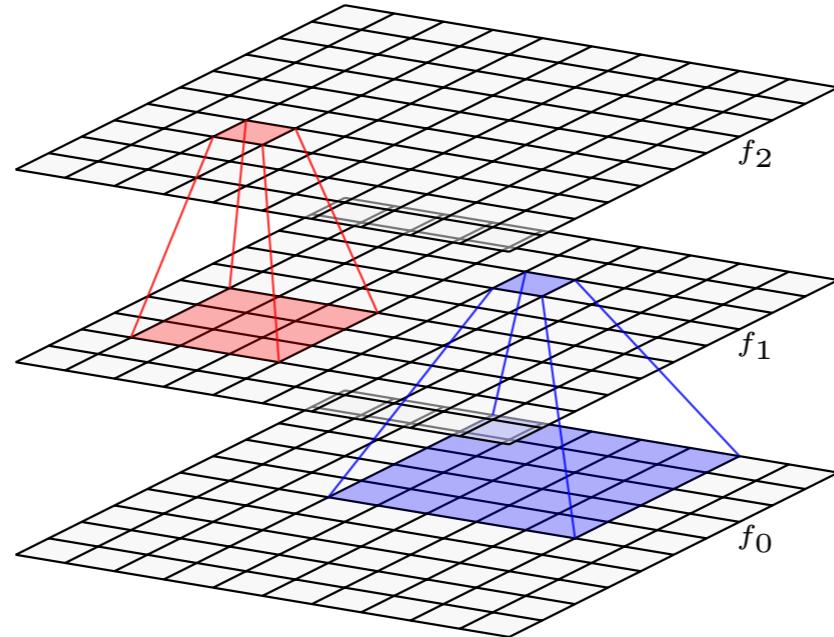


Convolutional Neural Networks



$$f_0 \longmapsto \phi_1(f_0) \xrightarrow{\sigma} f_1 \longmapsto \phi_2(f_1) \xrightarrow{\sigma} f_2 \longmapsto \dots \longmapsto \phi_L(f_{L-1}) \longmapsto f_L$$

Convolutional Neural Networks



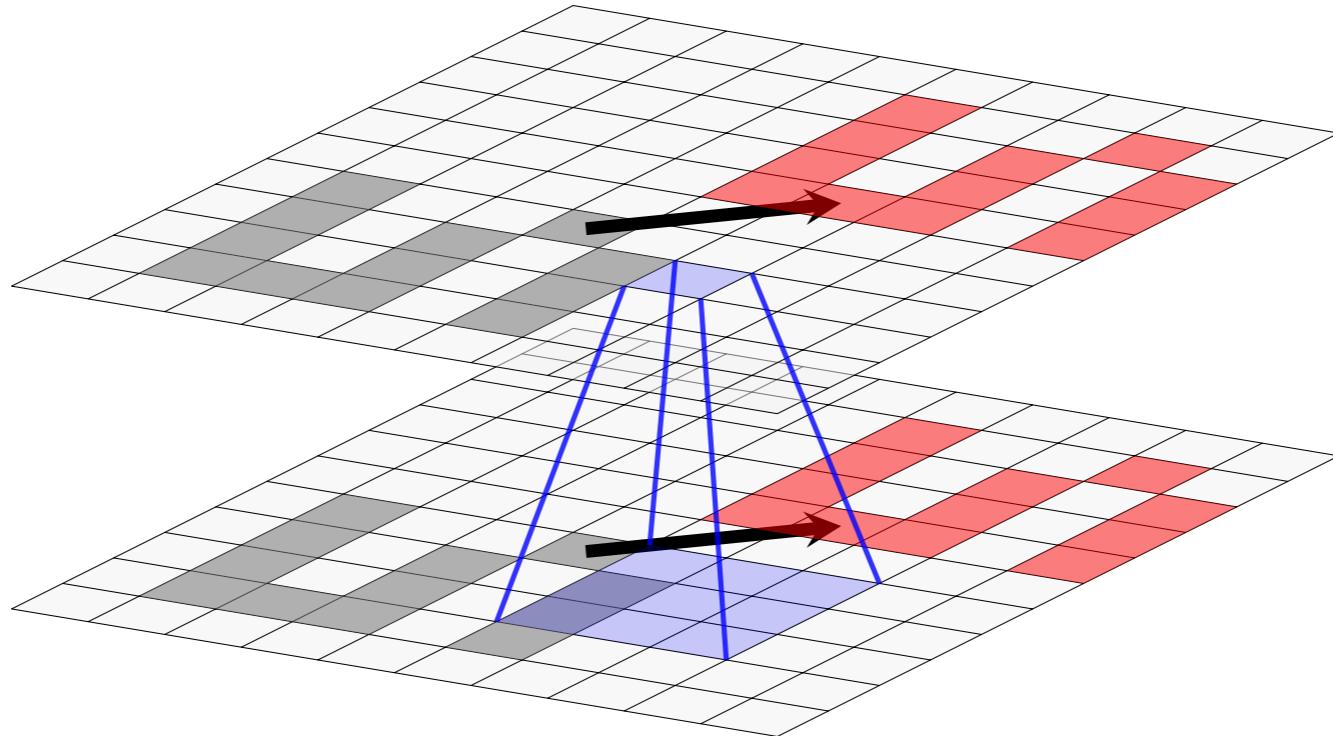
$$\phi_\ell(f_{\ell-1}) = (f_{\ell-1} * g_\ell)(x) = \sum_{y \in \mathbb{Z}^2} f_{\ell-1}(x - y) g_\ell(y)$$

Filter at layer ℓ

Equivariance

f_ℓ

$f_{\ell-1}$



$$f'_{\ell-1}(\mathbf{x}) = f_{\ell-1}(\mathbf{x} - \mathbf{t}) \quad \implies \quad f'_\ell(\mathbf{x}) = f_\ell(\mathbf{x} - \mathbf{t})$$

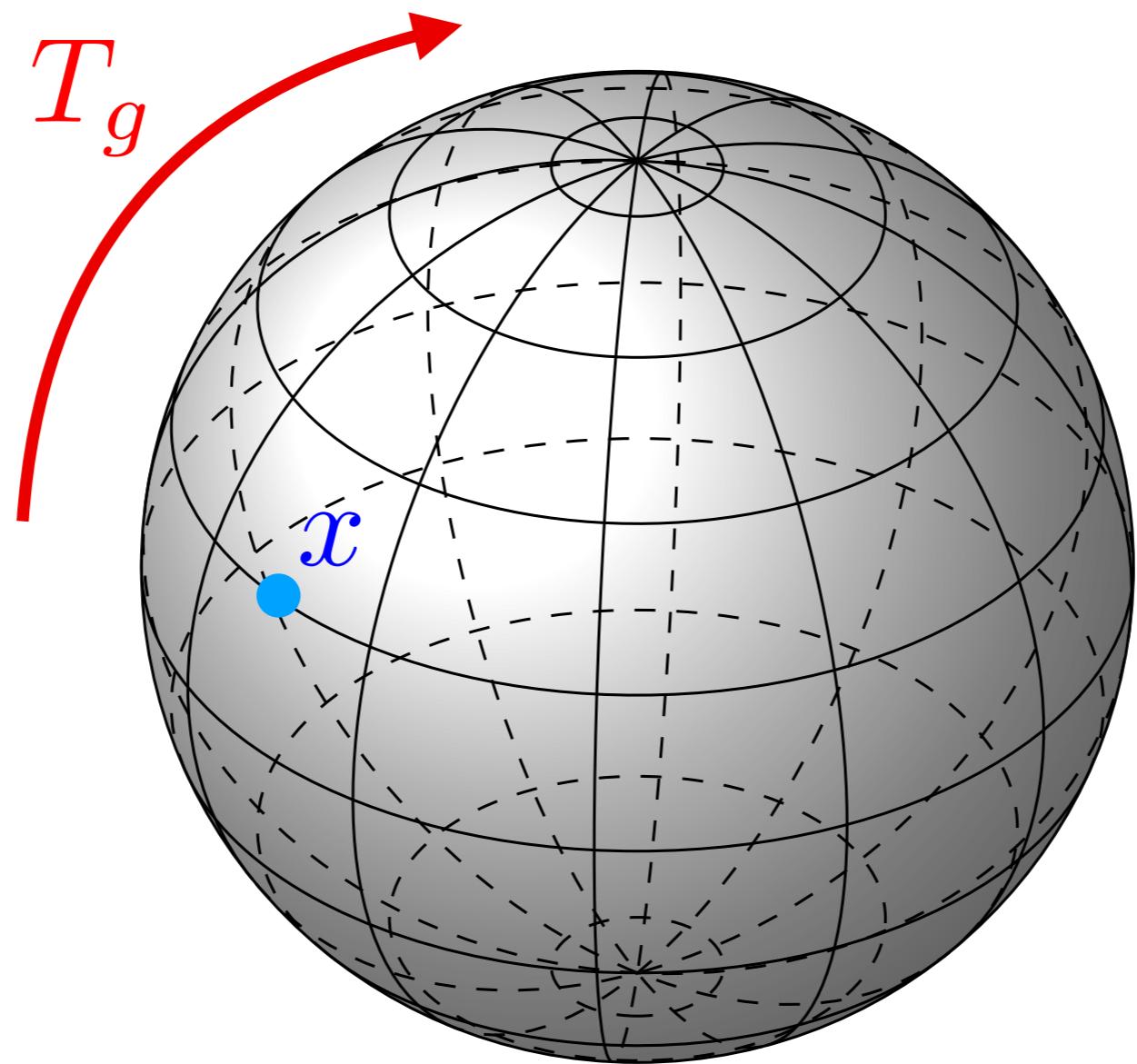
1. Parameter sharing
2. Same filters applied to every part of the image
3. Invariance, if followed by final invariant layer.

[Cohen & Welling, 2016]

[Cohen & Welling, 2017]

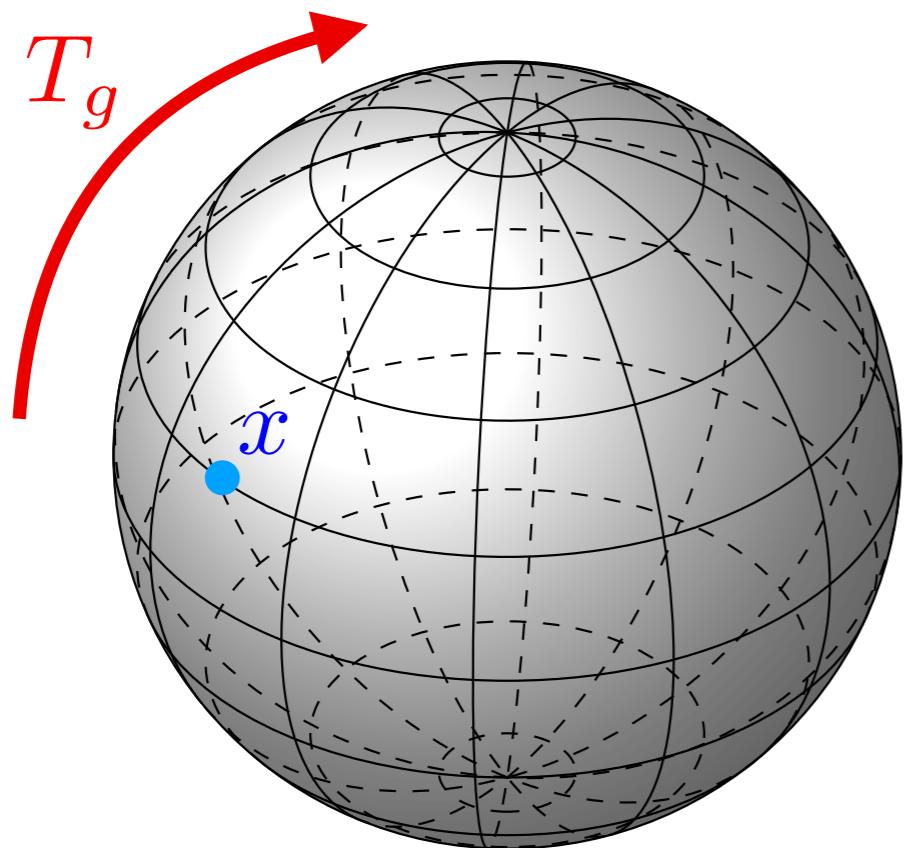
[Ravanbakhsh, Schneider & Poczos, 2017]

How do we generalize this to other
transformation groups?



[Cohen, Geiger, Köhler & Welling, 2018]

Group actions



1. Our function lives on a space \mathcal{X}
$$f: \mathcal{X} \rightarrow \mathbb{C}$$
2. We have a group G acting on \mathcal{X}
$$x \mapsto T_g(x)$$
3. This induces an action on functions

$$f \xrightarrow{T_g} f' \quad f'(x) = f(T_g^{-1}(x))$$

Equivariance



Equivariance

1. We have two different spaces \mathcal{X}_1 and \mathcal{X}_2 on which G acts by

$$T_g^{(1)}: \mathcal{X}_1 \rightarrow \mathcal{X}_1$$

$$T_g^{(2)}: \mathcal{X}_2 \rightarrow \mathcal{X}_2$$

2. We have corresponding actions on functions

$$f \mapsto \mathbb{T}_g^{(1)}(f)$$

$$\mathbb{T}_g^{(1)}(f)(x) = f((T_g^{(1)})^{-1}(x))$$

$$f \mapsto \mathbb{T}_g^{(2)}(f)$$

$$\mathbb{T}_g^{(2)}(f)(x) = f((T_g^{(2)})^{-1}(x))$$

3. A map $\phi: L(\mathcal{X}_1) \rightarrow L(\mathcal{X}_2)$ is **equivariant** to these actions if

$$\phi(\mathbb{T}_g^{(1)}(f)) = \mathbb{T}_g^{(2)}(\phi(f))$$

for all $f \in L(\mathcal{X}_1)$.

$$\begin{array}{ccc} L(\mathcal{X}_1) & \xrightarrow{\mathbb{T}_g^{(1)}} & L(\mathcal{X}_1) \\ \downarrow \phi & & \downarrow \phi \\ L(\mathcal{X}_2) & \xrightarrow{\mathbb{T}_g^{(2)}} & L(\mathcal{X}_2) \end{array}$$

$$(f*g)(u)=\int_G f(uv^{-1})\,g(v)\,d\mu(v)$$

$$(f*g)(u)=\int_G f{\restriction} G(uv^{-1})\,g{\restriction} G(v)\,d\mu(v)$$

Main theorem

A feed-forward neural network is equivariant to the action of a compact group G if and only if the linear operation in each layer is of the form

$$\phi_\ell(f_{\ell-1}) = f_{\ell-1} * g_\ell.$$

$$\rho_0 \qquad \rho_1 \qquad \rho_2 \qquad \rho_p$$

A diagram illustrating the decomposition of a space $L(\mathcal{X})$ into a direct sum of subspaces V_i . The top row contains labels $\rho_0, \rho_1, \rho_2, \dots, \rho_p$. Below this, the equation $L(\mathcal{X}) = V_0 \oplus V_1 \oplus V_2 \oplus \dots \oplus V_p$ is written. Four arrows originate from the labels $\rho_0, \rho_1, \rho_2, \rho_p$ and point downwards towards the corresponding subspaces V_0, V_1, V_2, V_p in the equation below.

$$L(\mathcal{X}) = V_0 \oplus V_1 \oplus V_2 \oplus \dots \oplus V_p$$

$$V_i=W_i^1\oplus W_i^2\oplus\ldots\oplus W_i^{m_i}$$

Consequences

$$\widehat{f}(\rho_i) = \int_G f(u) \rho_i(u) d\mu(u) \quad i = 0, 1, 2, \dots$$

$$\widehat{f * g}(\rho_i) = \widehat{f}(\rho_i) \cdot \widehat{g}(\rho_i)$$



matrix multiplication

Case 1: $f_{\ell-1}: G/H \rightarrow \mathbb{C}$ $f_\ell: G \rightarrow \mathbb{C}$

$$\left(\begin{array}{c} \text{[Gray rectangle]} \end{array} \right) = \left(\begin{array}{c} \text{[White rectangle with vertical gray bars]} \end{array} \right) \times \left(\begin{array}{c} \text{[White rectangle with horizontal gray bars]} \end{array} \right)$$

$$\widehat{f * g}(\rho)$$

$$\widehat{f \uparrow G}(\rho)$$

$$\widehat{g \uparrow G}(\rho)$$

Case 2: $f_{\ell-1}: G/H \rightarrow \mathbb{C}$ $f_\ell: G/K \rightarrow \mathbb{C}$

$$\left(\begin{array}{c|c|c|c|c} \hline & & & & \\ \hline \end{array} \right) = \left(\begin{array}{c|c|c|c} \hline & & & \\ \hline \end{array} \right) \times \left(\begin{array}{ccc} \textcolor{gray}{\square} & \textcolor{gray}{\square} & \textcolor{gray}{\square} \\ \vdots & \vdots & \vdots \\ \textcolor{gray}{\square} & \textcolor{gray}{\square} & \textcolor{gray}{\square} \end{array} \right)$$
$$\widehat{f * g}(\rho) \qquad \widehat{f \uparrow G}(\rho) \qquad \widehat{g \uparrow G}(\rho)$$

Fourier space neural networks

1. Spherical CNNs

[Cohen, Geiger, Köhler & Welling, 2018]

[K., Lin and Trivedi, 2018]

2. Steerability and conv-nets for manifolds

[Marcos, Volpi et al., 2017]

[Masci, Boscaini et al., 2015]

[Worral, Garbin et al., 2017]

3. Neural nets for graphs

[Duvenaud at al., 2015]

[Gilmer et al., 2017]

[Son, Trivedi et al. 2018]

4. Neural nets for physical systems

[...]

Also see:

[Cohen, Geiger & Weiler, 2018]

Conclusions

1. There is a clear prescription for how to generalize CNNs to architectures that are equivariant to the action of any compact group.
2. When dealing with groups, the Fourier picture is much more compelling because it reduces all the fancy algebra to just matrix multiplication.

Poster: 154

